

### 3. Remarks on the Stability of Certain Periodic Solutions of the Heat Convection Equations

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§ 1. Introduction. Let  $\Omega(t)$  be a time-dependent bounded space domain in  $R^m$  ( $m=2$  or  $3$ ) whose boundary  $\partial\Omega(t)$  consists of two components, namely,  $\partial\Omega(t)=\Gamma_0\cup\Gamma(t)$ . Here  $\Gamma_0$  is the inner boundary and  $\Gamma(t)$  is the outer one. Moreover, these two boundaries do not intersect each other. We denote by  $K$  the compact set which is bounded by  $\Gamma_0$ . Let  $u=u(x, t)$ ,  $\theta=\theta(x, t)$  and  $p=p(x, t)$  be the velocity of the viscous fluid, the temperature and the pressure, respectively. We consider the heat convection equation (HC) of Boussinesq approximation in  $\hat{\Omega}=\bigcup_{0<t<T}\Omega(t)\times\{t\}$  with boundary conditions

$$(1) \quad u|_{\partial\Omega(t)}=\beta(x, t), \quad \theta|_{\Gamma_0}=T_0>0, \quad \theta|_{\Gamma(t)}=0 \text{ for any } t\in(0, T).$$

In our previous paper [4], we have proven the unique existence of the time-periodic strong solution of (HC) with (1), provided the domain  $\Omega(t)$  and the boundary data  $\beta(x, t)$  both vary periodically with period  $T$ . The purpose of this paper is to show the asymptotic stability of the periodic solution which is obtained in [4].

§ 2. Assumptions and results. We make some assumptions:

(A1) For any fixed  $t>0$ ,  $\Gamma(t)$  and  $\Gamma_0$  are both simple closed curves (or surfaces) and also they are of class  $C^3$ .

(A2)  $\Gamma(t)\times\{t\}$  ( $0<t<T$ ) changes smoothly (say, of class  $C^4$ ) with respect to  $t$ . (See, Assumptions II and III in [4].)

(A3)  $g(x)$  is a bounded and continuous vector function in  $R^m\setminus\text{int } K$ .

(A4)  $\beta(x, t)$  is sufficiently smooth in  $x$  and  $t$ . Moreover, it satisfies the following condition

$$\int_{\partial\Omega(t)}\beta\cdot n \, dS=0,$$

where  $n$  is the outer normal vector to  $\partial\Omega(t)$ .

(A5) The domain  $\Omega(t)$  and the function  $\beta(x, t)$  vary periodically in  $t$  with period  $T>0$ , i.e.,  $\Omega(t+T)=\Omega(t)$ ,  $\beta(\cdot, t+T)=\beta(\cdot, t)$  for each  $t>0$ .

Since  $\Omega(t)$  is bounded, there exists an open ball  $B_1$  with radius  $d$  such that  $\overline{\Omega(t)}\subset B_1$ . We put  $B=B_1\setminus K$ . We introduce a solenoidal periodic function  $b$  over  $B$  such that  $b(x, t)=\beta(x, t)$  on  $\partial\Omega(t)$  and an appropriate function  $\bar{\theta}$  on  $\Omega(t)$  with the same boundary values on  $\partial\Omega(t)$  as  $\theta$ .

We now set the periodicity condition

$$(2) \quad u(\cdot, 0)=u(\cdot, T) \quad \text{in } \Omega(0)=\Omega(T),$$

and consider the periodic problem for (HC) with (1) and (2).

Then we have in [4] the following theorem:

**Theorem A.** *In addition to assumptions (A1)–(A5), if the viscosity  $\nu$  is sufficiently large and the boundary data  $\beta$  and  $T_0$  are sufficiently small in some sense, then the periodic problem for (HC) has a unique strong solution with period  $T$ .*

**Remark 1.** The definition of strong solutions is to be given in § 3. Detailed conditions on  $\nu, \beta$  and  $T_0$  in the above theorem are contained in [4].

We have now the following stability theorem which is the main result in this paper. (Symbols  $W_2^p(\Omega), \dot{W}_2^p(\Omega)$  and  $H_0^1(\Omega)$  are used as usual.)

**Theorem B.** *Let  $W(t) = (w(t), \psi(t))$  be the periodic strong solution in Theorem A and let  $U_0 = (u_0, \theta_0) \in H_0^1(\Omega(0)) \times \dot{W}_2^1(\Omega(0))$ . Then there exist positive numbers  $\nu_*$  and  $\gamma_*$  independent of  $T \geq 1$  such that if  $\nu > \nu_*$ ,*

$$\begin{aligned} \sup_{0 \leq t \leq T} \|\nabla \bar{\theta}(t)\|_{L^2(\Omega(t))} < \gamma_*, \quad \sup_{0 \leq t \leq T-1} \left( \int_t^{t+1} \|b(s)\|_{W_2^2(B)}^2 ds \right)^{1/2} < \gamma_*, \\ \sup_{0 \leq t \leq T-1} \left( \int_t^{t+1} \|b_s(s)\|_{L^2(B)}^2 ds \right)^{1/2} < \gamma_*, \quad \sup_{0 \leq t \leq T} \|b(t)\|_{W_2^1(B)} < \gamma_* \\ \text{and } \|U_0\|_{\{W_2^1(\Omega(0))\}_{m+1}} < \gamma_*, \end{aligned}$$

then the followings hold:

(i) *The initial value problem for (HC) with (1) and*  
 (3)  $u(0) = w(0) + u_0, \quad \theta(0) = \psi(0) + \theta_0 \quad \text{in } \Omega(0)$   
*has a unique global strong solution.*

(ii) *Let us denote the global strong solution obtained in (i) by  $V(t) = (v(t), \theta(t))$ , then we have*

$$(4) \quad \|V(t) - W(t)\|_{\{L^2(\Omega(t))\}_{m+1}} \longrightarrow 0 \quad \text{as } t \rightarrow \infty.$$

**§ 3. Strong solutions of the heat convection equation.** We make a suitable change of variables and use the same letters after changing of variables, then (HC) and (1) are transformed to the followings:

$$(5) \quad \begin{cases} u_t + (u \cdot \nabla)u = -\nabla p - (u \cdot \nabla)b - (b \cdot \nabla)u - R\theta + \Delta u + f_1 & \text{in } \hat{\Omega}, \\ \operatorname{div} u = 0 & \text{in } \hat{\Omega}, \\ \theta_t + (u \cdot \nabla)\theta = \frac{1}{P}\Delta\theta - (u \cdot \nabla)\bar{\theta} - (b \cdot \nabla)\theta + f_2 & \text{in } \hat{\Omega}, \end{cases}$$

$$(6) \quad u|_{\partial\Omega(t)} = 0, \quad \theta|_{\partial\Omega(t)} = 0 \quad \text{for any } t \in (0, T),$$

where  $f_1 = -b_t - (b \cdot \nabla)b + \Delta b + d^3 g/\nu^2 - R(\bar{\theta} - 1/P), f_2 = -(b \cdot \nabla)\bar{\theta}, R = \alpha g T_0 d^3/\kappa\nu, P = \nu/\kappa; \nu, \kappa, \alpha, \rho$  are physical constants and  $g = g(x)$  is the gravitational vector.

Let us put  $U = (u, \theta)$  and we notice  $H_0(B) \times L^2(B) = (H_0(B) \times 0) + (0 \times L^2(B))$  (direct sum). Then we introduce a proper lower semicontinuous convex (p.l.s.c.) function as follows:

$$(7) \quad \varphi_B(U) = \begin{cases} \frac{1}{2} \int_B (|\nabla u|^2 + \frac{1}{P} |\nabla \theta|^2) dx & \text{if } U \in H_0^1(B) \times \dot{W}_2^1(B), \\ +\infty & \text{if } U \in (H_0(B) \times L^2(B)) \setminus (H_0^1(B) \times \dot{W}_2^1(B)). \end{cases}$$

Next we consider a closed convex set  $K(t)$  of  $H_0(B) \times L^2(B)$ :

$$(8) \quad K(t) = \{U \in H_0(B) \times L^2(B); U = 0 \text{ a.e. in } B \setminus \Omega(t)\}$$

for any  $t \in [0, T]$  and denote its indicator function by  $I_{K(t)}$ , namely,  $I_{K(t)}(U)$

$=0$  if  $U \in K(t)$  and  $I_{K(t)}(U) = +\infty$  if  $U \in (H_o(B) \times L^2(B)) \setminus K(t)$ . Then we define the following p.l.s.c. function

$$(9) \quad \varphi^t(U) = \varphi_B(U) + I_{K(t)}(U) \quad \text{for every } t \in [0, T].$$

Let  $\partial\varphi^t$  be the subdifferential operator of  $\varphi^t$ , then we see:

$$(i) \quad D(\partial\varphi^t) = \{U \in H_o(B) \times L^2(B); U|_{a(t)} \in (W_2^2(\Omega(t)) \cap H_o^1(\Omega(t))) \\ \times (W_2^2(\Omega(t)) \cap \mathring{W}_2^1(\Omega(t))), U|_{B \setminus a(t)} = 0\}$$

$$(ii) \quad \partial\varphi^t(U) = \{f \in H_o(B) \times L^2(B); P(\Omega(t))f|_{a(t)} = A(\Omega(t))U|_{a(t)}\},$$

where  $A(\Omega(t))$  is the Stokes operator,  $P(\Omega(t)) = {}^t(P_o(\Omega(t)), 1_{a(t)})$  and  $P_o(\Omega(t))$  is the orthogonal projection from  $L^2(\Omega(t))$  to  $H_o(\Omega(t))$ . Using the operator  $\partial\varphi^t$ , we reduce (5) and (6) to the following abstract heat convection equation (AHC) in  $H_o(B) \times L^2(B)$ .

$$(AHC) \quad \frac{dV}{dt} + \partial\varphi^t(V(t)) + F(t)V(t) + M(t)V(t) \ni P(B)\tilde{f}(t), \quad t \in [0, T],$$

where  $V = {}^t(v, \theta)$ ,  $F(t)V(t) = {}^t(P_o(B)(v \cdot \nabla)v, (v \cdot \nabla)\theta)$ ,  $M(t)V(t) = {}^t(P_o(B)((v \cdot \nabla)b + (b \cdot \nabla)v + R\theta), (v \cdot \nabla)\tilde{\theta} + (b \cdot \nabla)\theta)$ ,  $\tilde{f} = {}^t(\tilde{f}_1, \tilde{f}_2)$  and  $P(B) = {}^t(P_o(B), 1_B)$ ;  $\tilde{f}_i$  means the natural extension of  $f_i$ .

Now we define the strong solution of (AHC) as follows.

**Definition 1.** Let  $V: [0, S] \rightarrow H_o(B) \times L^2(B)$ ,  $S \in (0, T]$ . Then  $V$  is called a strong solution of (AHC) on  $[0, S]$  if it satisfies the following properties (i) and (ii).

$$(i) \quad V \in C([0, S]; H_o(B) \times L^2(B)) \text{ and } dV/dt \in L^2(0, S; H_o(B) \times L^2(B)).$$

(ii)  $V(t) \in D(\partial\varphi^t)$  for a.e.  $t \in [0, S]$  and there is a function  $G \in L^2(0, S; H_o(B) \times L^2(B))$  satisfying  $G(t) \in \partial\varphi^t(V(t))$  and  $(dV/dt) + G(t) + F(t)V(t) + M(t)V(t) = P(B)\tilde{f}(t)$  for a.e.  $t \in [0, S]$ .

**Definition 2.** A strong solution of (AHC) satisfying the following condition (10) (resp. (11)) is called a periodic strong solution (resp. a strong solution of the initial value problem):

$$(10) \quad V(0) = V(T) \quad \text{in } H_o(B) \times L^2(B),$$

$$(11) \quad V(0) = {}^t(\tilde{a}, \tilde{h}) \quad \text{in } H_o(B) \times L^2(B),$$

where  $a$  and  $h$  are certain prescribed initial data in  $H_o^1(\Omega(0)) \times \mathring{W}_2^1(\Omega(0))$ .

**§ 4. Proof of the theorem.** We prove Theorem B. Let us put  $U = {}^t(u, \theta) = {}^t(v - w, \theta - \psi) = V - W$ . Then the assertions (i) and (ii) of Theorem B can be reduced to the global existence of the strong solution and the decay problem of it for the next initial value problem in  $\hat{\Omega} = \bigcup_{0 < t < \infty} \Omega(t) \times \{t\}$ :

$$(12) \quad \begin{cases} u_t + (u \cdot \nabla)u = -\nabla p - (u \cdot \nabla)w - (w \cdot \nabla)u - (u \cdot \nabla)b - (b \cdot \nabla)u - R\theta + \Delta u \\ \text{div } u = 0 \\ \theta_t + (u \cdot \nabla)\theta = (1/P)\Delta\theta - (u \cdot \nabla)\psi - (w \cdot \nabla)\theta - (u \cdot \nabla)\tilde{\theta} - (b \cdot \nabla)\theta \end{cases}$$

$$(13) \quad u|_{\partial\Omega(t)} = 0, \quad \theta|_{\partial\Omega(t)} = 0 \quad \text{for any } t \in (0, \infty),$$

$$(14) \quad u|_{t=0} = u_0, \quad \theta|_{t=0} = \theta_0 \quad \text{in } \Omega(0).$$

Here let put

$$(15) \quad \|\tilde{f}\|_{2, \infty, T}^2 = \sup_{0 \leq t \leq T-1} \int_t^{t+1} \|\tilde{f}(s)\|_B^2 ds.$$

Then we note the following estimate given in [4]:

$$(16) \quad \varphi^t(W(t)) \leq \gamma_0,$$

where  $\gamma_0$  is a constant depending on  $\|\tilde{f}\|_{2,\infty,T}$ . Moreover, it holds also that  $\gamma_0 \rightarrow 0$  as  $\|\tilde{f}\|_{2,\infty,T} \rightarrow 0$ . Employing (16), the claim (i) can be proven by using the similar arguments to those in [4]. So we omit details.

To show (ii), multiplying both sides of (12) by  $U$  and integrating over  $\Omega(t)$ , we get by standard inequalities

$$(17) \quad \frac{1}{2} \frac{d}{dt} \|U(t)\|^2 + 2\varphi'(U(t)) \\ \leq C \|\nabla U(t)\|^2 \cdot (\|\nabla W(t)\| + \|\nabla b(t)\| + \|\nabla \bar{\theta}(t)\| + |R|).$$

Considering (16), if  $b$  and  $\bar{\theta}$  are sufficiently small and  $\nu$  is sufficiently large, there exists  $\delta > 0$  such that  $2 - \delta > 0$  and

$$(18) \quad \frac{1}{2} \frac{d}{dt} \|U(t)\|^2 + (2 - \delta)\varphi'(U(t)) \leq 0$$

hold. Hence we have proven (ii).

Q.E.D.

### References

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