

A Functional Calculus for a Scalar Perturbation of $\partial/\partial z$

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1. Introduction

In this paper, we determine when a functional calculus exists for the operator

$$L = a_1 \left(-i \frac{\partial}{\partial z} \right) + a_2 \left(-i \frac{\partial}{\partial \bar{z}} \right), \quad a_1 \text{ close to } 1, \quad a_2 \text{ close to } 0.$$

In other words, we consider when $\phi(L)$ can be defined as a bounded operator on $L^2(\mathbf{R}^2)$ for a certain class of functions ϕ . The operator L is not normal, thus the usual spectral theory cannot be applied. The spectrum of L is the whole complex plane, so resolvents need to be interpreted, and one cannot define functions of L by integrating on the boundary of the spectrum.

Extending the unpublished results of Coifman and Meyer ([CM2]; see also [CM1]), we construct a functional calculus for L and prove L^2 boundedness for a certain class of ϕ , and connect the study of the functional calculus to a certain surface in \mathbf{C}^2 . The assumption of the boundedness on L^2 of some natural functions of L is equivalent to certain quantitative conditions on the surface. We also show how L can be obtained by conjugation from the Coifman–Meyer case. This gives another geometric interpretation: a connection via a change of variables to a simpler surface considered by Coifman and Meyer.

In Section 2, we discuss some general facts about functional calculi which lead to the definition of a surface Σ in \mathbf{C}^2 and the definition of the conjugate operator \bar{L} . Section 3 examines restrictions on the coefficients a_1 and a_2 , and exhibits a class of functions satisfying these restrictions. In Section 4, we calculate \bar{L}/L and L/\bar{L} , while in Section 5 we use the expression

$$\phi(L) = \frac{1}{\pi} \int_{\mathbf{C}} \frac{\partial \phi}{\partial \bar{\xi}} \frac{1}{L - \xi} d\sigma(\xi)$$

to define $\phi(L)$ for $\phi \in C_0^\infty(\mathbf{C})$. In Section 6 we show that the product formula holds for the functional calculus, and in Section 7 we extend the class of ϕ

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to those functions which are bounded and holomorphic in a conical sector in \mathbb{C}^2 . Section 8 considers the quantitative restrictions on the surface implied by assuming that L/\bar{L} and \bar{L}/L are bounded on L^2 , and Section 9 exhibits the conjugation to the Coifman–Meyer case.

2. Definition of L and a Naturally Associated Surface

Let

$$\frac{\partial}{\partial z} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right), \quad \frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right) \quad \text{and} \quad \partial_z = -i \frac{\partial}{\partial z}, \quad \partial_{\bar{z}} = -i \frac{\partial}{\partial \bar{z}}.$$

Consider the operator

$$L = a_1 \partial_z + a_2 \partial_{\bar{z}}.$$

Here, $a_1 = 1/(1 + \alpha)$, and α and a_2 have small L^∞ norm and are C^1 . We will restrict them more later.

We would like to define $\phi(L)$ and to show that, for ϕ in a certain general class, $\phi(L)$ is a bounded operator on L^2 . As is usually done when defining a functional calculus, one at first assumes ϕ is in some special class, uses an integral representation formula for ϕ , and then attempts to define $\phi(L)$ at least on a formal level. Then one shows that the proposed expression for $\phi(L)$ makes sense, verifies that $\phi_1(L)\phi_2(L) = (\phi_1\phi_2)(L)$, and extends the obtained formula to more general ϕ .

The first problem is thus to choose some representation formula for ϕ . A common candidate is the Cauchy integral formula, in which the integration is over the boundary of the domain containing the spectrum of L . Since the spectrum of L is the whole complex plane, we follow [CM2] and instead try the well-known integral representation formula

$$(2.1) \quad \phi(z) = \frac{1}{\pi} \int_{\mathbb{C}} \frac{\partial \phi}{\partial \bar{\xi}} \frac{1}{z - \xi} d\sigma(\xi),$$

which is certainly valid for smooth ϕ which decrease sufficiently rapidly at infinity. Thus we will attempt to make sense of the formula

$$(2.2) \quad \phi(L) = \frac{1}{\pi} \int_{\mathbb{C}} \frac{\partial \phi}{\partial \bar{\xi}} \frac{1}{L - \xi} d\sigma(\xi).$$

Note that $1/(L - \xi)$ still needs to be interpreted since $(L - \xi)^{-1}$ does not exist. The intuitive reason for choosing (2.1) instead of the Cauchy integral is that the singularity in (2.1) is integrable in two dimensions.

Suppose that $\chi(z)$ has the property that $L\chi = \xi\chi$. Then we can interpret $(L - \xi)^{-1}$ as $\chi L^{-1} \chi^{-1}$, on a formal level. Setting aside for the time being the problem of defining L^{-1} , we focus our attention on χ . Note that choosing $\chi_0 = \exp(i(\xi z + \bar{\xi} \bar{z}))$, we see that $\partial_z \chi_0 = \xi \chi_0$. Since L is a perturbation of ∂_z , a reasonable candidate for χ is

$$(2.3) \quad \chi = \exp(i(\xi(h(z) - g(z)) + \bar{\xi}g(z))),$$

where $h(z) - g(z)$ should be close to z , and $g(z)$ should be close to \bar{z} in some sense. The reason for choosing the notation $h - g$ to play the role of z rather than a function unrelated to g is for convenience in later formulas. Solving the equation $L\chi = \xi\chi$ for this χ leads to the system

$$(2.4) \quad \begin{cases} a_1 \frac{\partial h}{\partial z} + a_2 \frac{\partial h}{\partial \bar{z}} = 1, \\ a_1 \frac{\partial g}{\partial z} + a_2 \frac{\partial g}{\partial \bar{z}} = 0. \end{cases}$$

These are variants of the Beltrami equation, which can be solved explicitly:

$$h = z + \bar{z} + \eta, \quad g = \bar{z} + m.$$

The functions η and m should be thought of as perturbations of z and \bar{z} (see the remarks at the end of this section).

The above discussion serves as motivation for examining the functions h and g which solve system (2.4), and thinking of $h - g$ as being similar to z and g similar to \bar{z} . We move away from interpreting formula (2.2) for the time being, until Section 5, and concentrate on h and g . We will use these functions to find an operator \bar{L} commuting with L . Since L is a perturbation of ∂_z , we are looking for \bar{L} to be a perturbation of $\partial_{\bar{z}}$. \bar{L} is a very useful operator to find explicitly because, if we are given $\phi(\xi)$ and set $\phi_1(\xi) = \phi(\bar{\xi})$, then $\phi_1(L) = \phi(\bar{L})$ if $\phi_1(L)$ can be defined. To understand how to use h and g , consider the unperturbed operators ∂_z and $\partial_{\bar{z}}$. We define the surface $\Sigma_0 = (z, \bar{z})$, $\Sigma_0 \subset \mathbb{C} \times \mathbb{C} = \{(z_1, z_2)\}$. For F holomorphic in a neighborhood of Σ_0 , define $(\Lambda_0 F)(z) = F(z, \bar{z})$. It follows immediately that

$$\partial_z(\Lambda_0 F) = \Lambda_0(\partial_{z_1} F).$$

So $\Lambda_0^{-1}\partial_z\Lambda_0 = \partial_{z_1}$, and similarly $\Lambda_0^{-1}\partial_{\bar{z}}\Lambda_0 = \partial_{z_2}$. Thus, on the surface Σ_0 , ∂_z and $\partial_{\bar{z}}$ become the (commuting) operators ∂_{z_1} and ∂_{z_2} . Hence, following the idea of Coifman and Meyer in [CM2], to find \bar{L} we consider the surface $\Sigma = ((h - g)(z), g(z))$ and define, for F holomorphic in a neighborhood of Σ ,

$$(\Lambda F)(z) = F((h - g)(z), g(z)).$$

Then

$$L(\Lambda F) = (a_1\partial_z + a_2\partial_{\bar{z}})F((h - g)(z), g(z)) = \Lambda(\partial_{z_1} F),$$

using (2.4). So $\Lambda^{-1}L\Lambda = \partial_{z_1}$, or $L = \Lambda\partial_{z_1}\Lambda^{-1}$. From the previous remarks, to find a vector field \bar{L} commuting with L , it is natural to set $\bar{L} = \Lambda\partial_{z_2}\Lambda^{-1}$. If $\bar{L} = \tilde{b}_1\partial_z + \tilde{b}_2\partial_{\bar{z}}$, then using a similar calculation to the one above, we will obtain the following system of equations for \tilde{b}_1, \tilde{b}_2 :

$$(2.5a) \quad \begin{cases} \tilde{b}_1 \frac{\partial(h-g)}{\partial z} + \tilde{b}_2 \frac{\partial(h-g)}{\partial \bar{z}} = 0, \\ \tilde{b}_1 \frac{\partial g}{\partial z} + \tilde{b}_2 \frac{\partial g}{\partial \bar{z}} = 1. \end{cases}$$

Using (2.4), and letting $\tilde{b}_1 = a_1 + b_1$ and $\tilde{b}_2 = a_2 + b_2$, it is equivalent to solve:

$$(2.5b) \quad \begin{cases} b_1 \frac{\partial h}{\partial z} + b_2 \frac{\partial h}{\partial \bar{z}} = 0, \\ b_1 \frac{\partial g}{\partial z} + b_2 \frac{\partial g}{\partial \bar{z}} = 1. \end{cases}$$

Defining

$$D \equiv \frac{\partial h}{\partial z} \frac{\partial g}{\partial \bar{z}} - \frac{\partial g}{\partial z} \frac{\partial h}{\partial \bar{z}} = \frac{\partial(h-g)}{\partial z} \frac{\partial g}{\partial \bar{z}} - \frac{\partial g}{\partial z} \frac{\partial(h-g)}{\partial \bar{z}},$$

(2.5b) has solutions

$$b_1 = -\frac{\partial h}{\partial \bar{z}} \frac{1}{D}, \quad b_2 = \frac{\partial h}{\partial z} \frac{1}{D}.$$

For the development of Sections 4 through 7, when discussing the operators L/\bar{L} and \bar{L}/L , when defining more general functions of L , and when considering L^2 boundedness of a certain class of functions of L , we will always assume that η and m have small Lipschitz norms. This assumption (together with the assumptions that a_2 is small relative to a_1 , as in (i) of Proposition 8.1) is sufficient to guarantee that $h - g$ is a quasiconformal, and g an (anti)quasiconformal, homeomorphism of the plane. Furthermore, all the required expressions (e.g., D) stay away from 0, L/\bar{L} and \bar{L}/L are bounded on L^2 , and the rest of the results, including Proposition 7.1, go through. In Proposition 8.1, we see that we can estimate the distance of D from 0, the L^∞ norms of the partials of η and m , and the L^∞ norms of certain other functions connected with the quasiconformal nature of $h - g$ and g , using only the L^2 norms of L/\bar{L} and \bar{L}/L as well as certain L^∞ norms involving a_1 and a_2 . However, Proposition 8.1 is not a complete converse to our (sufficient) assumption that η and m have small partials: we need to make assumptions about boundedness without estimates in Proposition 8.1, and then we obtain the estimates; we do not obtain that η and m have necessarily small Lipschitz norm, but merely bounded. In the next section, we solve (2.4) explicitly, and give examples which guarantee that η and m have small partials.

3. Beurling Transform; Restrictions on a_1 and a_2

We first make a small digression to discuss the Beurling transform. Let $B = \partial_z \partial_{\bar{z}}^{-1}$ be the Beurling transform, and $B^{-1} = \partial_{\bar{z}} \partial_z^{-1}$ be its inverse. B^{-1} is convolution with *p.v.* $-1/\pi \bar{z}^2$, has symbol $\xi/\bar{\xi}$, and is bounded from L^2 to L^2 .

Let f be a radial function, $f(r)$, defined on \mathbf{C} , and let $F(z) = e^{im\theta} f(r)$. Following Garcia-Cuerva's derivation of $B(f)$ in [GC], one can show that

$$(3.1) \quad (B^{-1}F)(re^{i\psi}) = \begin{cases} -e^{i(m+2)\psi} \{2(m+1)/r^{m+2} \int_0^r s^{m+1} f(s) ds - f(r)\}, & m \geq -1, \\ e^{i(m+2)\psi} \{2(m+1)/r^{m+2} \int_r^\infty s^{m+1} f(s) ds + f(r)\}, & m \leq -3, \\ -(2 \int_r^\infty f(s)/s ds + 2f(0) \ln r - f(r)), & m = -2. \end{cases}$$

Using (3.1), if $F = e^{im\theta}f(r)$ for any integral m , if $f(r)$ is supported in $[1/M, M]$ with M some fixed constant, and if $f \in C^\infty$, then

$$\|B^{-1}F\|_\infty \leq 5 \ln M \|f\|_\infty.$$

So, in particular, if $\|f\|_\infty \leq \delta/5 \ln M$ ($\delta < 1$), we have that the series

$$(3.2) \quad (1 - B^{-1}f)^{-1}(1) = 1 + B^{-1}(f) + B^{-1}(fB^{-1}(f)) + \dots$$

converges in L^∞ with norm bounded by $1/(1 - \delta)$.

In what follows, f will be either a_2 , αa_2 , or their linear combination (here $a_1 = 1/(1 + \alpha)$), so we must take f in L^∞ . This places restrictions on the functions involved since B^{-1} , a Calderon-Zygmund operator, will not usually map L^∞ to L^∞ .

Now we return to the system (2.4). We treat each equation separately. Each is similar to the Beltrami equation, except one has a nonzero right-hand term, and the roles of ∂_z and $\partial_{\bar{z}}$ are reversed. So we can solve them in the usual way (a minor modification to the solution in Ahlfors [A]) to obtain:

$$(3.3) \quad \begin{aligned} g &= \bar{z} + m, \\ m &= -\left(\frac{a_2}{a_1} \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} (1)\right) * \frac{1}{\pi \bar{z}}, \\ \frac{\partial m}{\partial z} &= -\frac{a_2}{a_1} \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} (1), \\ \frac{\partial m}{\partial \bar{z}} &= \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} (1) - 1. \end{aligned}$$

Here, a_2/a_1 denotes the corresponding multiplication operator. We also have:

$$(3.4) \quad \begin{aligned} h &= z + \bar{z} + \eta, \\ \eta &= \left\{ \alpha - \frac{a_2}{a_1} \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} \left(1 + B^{-1} \frac{1}{a_1}\right) \right\} * \frac{1}{\pi \bar{z}}, \\ \frac{\partial \eta}{\partial z} &= \alpha - \frac{a_2}{a_1} \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} \left(1 + B^{-1} \frac{1}{a_1}\right), \\ \frac{\partial \eta}{\partial \bar{z}} &= \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} \left(1 + B^{-1} \frac{1}{a_1}\right) - 1 \\ &= \left(1 + B^{-1} \frac{a_2}{a_1}\right)^{-1} \left(B^{-1} \left(\frac{1}{a_1} - \frac{a_2}{a_1}\right)\right) \end{aligned}$$

(here, $a_1 = 1/(1 + \alpha)$). Noting that $B^{-1}(1) = 0$, and using (3.2), we see that if we choose α and a_2 to be C^∞ , compactly supported on $1/M \leq r \leq M$ (M fixed), of the form $\sum_{j=1}^N e^{im_j\theta} f_j(r)$ (the sum finite), and such that each f_j is of sufficiently small L^∞ norm, then all the series defining m , η , and their derivatives will converge, and m, η will be Lipschitz of norm as small as we want.

These restrictions on the form of α and a_2 are probably unnecessarily severe. They merely serve to illustrate that there do exist many functions α and a_2 such that the operator series in (3.3) and (3.4) converge and the partials of m and η can be taken small.

We now return to (2.5b) to calculate $\tilde{b}_1 = a_1 + b_1$ and $\tilde{b}_2 = a_2 + b_2$. Note that $D = (1/a_1)(\partial g/\partial \bar{z})$, using (2.4). D is never 0 and is, in fact, bounded away from 0, given our choices of α and a_2 . Thus,

$$(3.5a) \quad \tilde{b}_1 = -\frac{a_1(1+B^{-1}(a_2/a_1))^{-1}(B^{-1}(1/a_1))}{(1+B^{-1}(a_2/a_1))^{-1}(1)}$$

and

$$(3.5b) \quad \tilde{b}_2 = \frac{1 - a_2(1+B^{-1}(a_2/a_1))^{-1}(B^{-1}(1/a_1))}{(1+B^{-1}(a_2/a_1))^{-1}(1)}.$$

So $\bar{L} = \tilde{b}_1 \partial_z + \tilde{b}_2 \partial_{\bar{z}}$, where \tilde{b}_1 and \tilde{b}_2 (given by the formulas above) are in L^∞ and \bar{L} is obtained by simply finding the conjugate vector field, corresponding to $\partial/\partial z_2$ on Σ , to the vector field L (which corresponds to $\partial/\partial z_1$). If we write out the partial differential equations obtained by considering $L\bar{L} = \bar{L}L$, we obtain:

$$(3.6) \quad \begin{cases} a_1 \frac{\partial \tilde{b}_1}{\partial z} + a_2 \frac{\partial \tilde{b}_1}{\partial \bar{z}} = \tilde{b}_1 \frac{\partial a_1}{\partial z} + \tilde{b}_2 \frac{\partial a_1}{\partial \bar{z}}, \\ a_1 \frac{\partial \tilde{b}_2}{\partial z} + a_2 \frac{\partial \tilde{b}_2}{\partial \bar{z}} = \tilde{b}_1 \frac{\partial a_2}{\partial z} + \tilde{b}_2 \frac{\partial a_2}{\partial \bar{z}}. \end{cases}$$

One can check, without too much difficulty, that (3.5a) and (3.5b) satisfy system (3.6). It would be hard to guess a solution to (3.6) (other than the trivial one, viz., a multiple of L) without using the surface Σ .

4. Calculation of L^{-1} , \bar{L}^{-1} , L/\bar{L} , \bar{L}/L

In this section, we calculate some particular operators which have already been mentioned and which will also be used in what follows. In all that follows, we suppose $f \in C_0^\infty(\mathbf{C})$. We first state a lemma of Coifman–Meyer, a proof of which appears in the appendix.

LEMMA 4.1. *If $\rho: \mathbf{C} \rightarrow \mathbf{C}$ is a quasi-conformal mapping, and $f \in C_0^\infty$, then*

$$\frac{\partial}{\partial z} \int_{\mathbf{C}} \frac{1}{\rho(z) - \rho(w)} f(w) d\sigma(w) = -p.v. \int_{\mathbf{C}} \frac{\partial \rho / \partial z}{(\rho(z) - \rho(w))^2} f(w) d\sigma(w)$$

while

$$\begin{aligned} \frac{\partial}{\partial \bar{z}} \int_{\mathbf{C}} \frac{1}{\rho(z) - \rho(w)} f(w) d\sigma(w) \\ = \pi \frac{f(z)}{\partial \rho / \partial z} - p.v. \int_{\mathbf{C}} \frac{\partial \rho / \partial \bar{z}}{(\rho(z) - \rho(w))^2} f(w) d\sigma(w). \end{aligned}$$

Now, let

$$T_1 f = \int_{\mathbb{C}} \frac{i}{\pi} \frac{1}{g(z) - g(w)} f(w) D(w) d\sigma(w).$$

Then, $LT_1 f = f(z)$: we apply Lemma 4.1, but since \bar{g} (not g) is q.c., we must interchange $\partial/\partial z$ and $\partial/\partial \bar{z}$ in that lemma. So,

$$\begin{aligned} LT_1 f &= a_1 \frac{f(z)}{\partial g/\partial \bar{z}} D(z) - p.v. \frac{i}{\pi} \int_{\mathbb{C}} \frac{a_1 (\partial g/\partial z) f(w) D(w)}{(g(z) - g(w))^2} d\sigma(w) \\ &\quad - p.v. \frac{i}{\pi} \int_{\mathbb{C}} \frac{a_2 (\partial g/\partial \bar{z}) f(w) D(w)}{(g(z) - g(w))^2} d\sigma(w) \\ &= f(z), \end{aligned}$$

using (3.1) and the equality $D(z) = (1/a_1)(\partial g/\partial \bar{z})$. One can also show, using (2.4) and a bit more manipulation, that $T_1 L f = f(z)$. So, $T_1 = 1/L$.

Similarly,

$$\frac{1}{\bar{L}} = \int_{\mathbb{C}} \frac{i}{\pi} \frac{1}{(h-g)(z) - (h-g)(w)} f(w) D(w) d\sigma(w).$$

Here we use (2.5) and the fact that also $D(z) = (\partial(h-g)/\partial z)/\tilde{b}_2$.

Using Lemma 4.1 and the expressions for L^{-1} and \bar{L}^{-1} ,

$$\begin{aligned} \frac{\bar{L}}{L} f &= (\tilde{b}_1 \partial_z + \tilde{b}_2 \partial_{\bar{z}}) \left\{ \int_{\mathbb{C}} \frac{i}{\pi (g(z) - g(w))} f(w) D(w) d\sigma(w) \right\} \\ &= -p.v. \int_{\mathbb{C}} \frac{1}{\pi (g(z) - g(w))^2} f(w) D(w) d\sigma(w) + \frac{\tilde{b}_1(z)}{a_1(z)} f(z). \end{aligned}$$

Similarly,

$$\begin{aligned} \frac{L}{\bar{L}} f &= (a_1 \partial_z + a_2 \partial_{\bar{z}}) \left\{ \int_{\mathbb{C}} \frac{i}{\pi ((h-g)(z) - (h-g)(w))} f(w) D(w) d\sigma(w) \right\} \\ &= -p.v. \int_{\mathbb{C}} \frac{1}{\pi ((h-g)(z) - (h-g)(w))^2} f(w) D(w) d\sigma(w) + \frac{a_2(z)}{\tilde{b}_2(z)} f(z). \end{aligned}$$

5. Functional Calculus

We now try to make sense of the formula (2.2) which was discussed in Section 2:

$$\phi(L) = \frac{1}{\pi} \int_{\mathbb{C}} \frac{\partial \phi}{\partial \bar{\xi}} \frac{1}{L - \xi} d\sigma(\xi).$$

The first part of this section follows closely the work of Coifman–Meyer. Let us first suppose that ϕ is decreasing more rapidly than a linear exponential. Now, we know what L^{-1} is. If we let $\chi = \exp(i(\xi(h(z) - g(z)) + \bar{\xi}g(z)))$, as before, then $L\chi = \xi\chi$ and so

$$(L - \xi)^{-1} = \chi L^{-1} \frac{1}{\chi}.$$

Since the kernel of L^{-1} is $(i/\pi(g(z) - g(w)))D(w)$,

$$\frac{\partial}{\partial \bar{\xi}}(L - \xi)^{-1} = \frac{i^2}{\pi} \int_{\mathbf{C}} \exp(i(\xi((h-g)(z) - (h-g)(w)) + \bar{\xi}(g(z) - g(w)))) f(w) D(w) d\sigma(w)$$

and

$$(5.1) \quad \phi(L)f = \frac{1}{\pi^2} \int_{\mathbf{C}} k((h-g)(z) - (h-g)(w), g(z) - g(w)) f(w) D(w) d\sigma(w),$$

where

$$k(u, v) = \int_{\mathbf{C}} \phi(\xi) \exp(i(u\xi + v\bar{\xi})) d\sigma(\xi).$$

We now attempt to define more general functions of L , and to tie in \bar{L} (which was obtained by geometric considerations) to the functional calculus. To this end, define $\phi(\xi) = \exp(-|\xi|^2)$ and $\phi_t(\xi) = \exp(-t^2|\xi|^2)$. Then

$$\int_{\mathbf{C}} \phi_t(\xi) \exp(i(z\xi + \bar{z}\bar{\xi})) d\sigma(\xi) = \frac{\pi}{t^2} \exp\left(-\frac{1}{t^2} \left(\frac{z+\bar{z}}{2}\right)^2 - \frac{1}{t^2} \left(\frac{z-\bar{z}}{2i}\right)^2\right).$$

We can extend this uniquely as an entire function in $(u, v) \in \mathbf{C} \times \mathbf{C}$, to obtain

$$\theta_t(u, v) \equiv \frac{\pi}{t^2} \exp\left(-\frac{1}{t^2} \left(\frac{u+v}{2}\right)^2 - \frac{1}{t^2} \left(\frac{u-v}{2i}\right)^2\right).$$

Let $u = (h-g)(z) - (h-g)(w)$ and $v = g(z) - g(w)$. Note that

$$|\theta_t(u, v)| \leq \frac{\pi}{t^2} \exp\left(-\frac{c}{t^2} \left(\frac{(z-w) + \overline{(z-w)}}{2}\right)^2 - \frac{c}{t^2} \left(\frac{(z-w) - \overline{(z-w)}}{2i}\right)^2\right).$$

We want to calculate $\lim_{t \rightarrow 0} \phi_t(L)f$, where $\phi_t(L)f$ is defined by (5.1). Now, making a change of variables $w \rightarrow z - u'$ and then $u' \rightarrow vt$, we obtain

$$\begin{aligned} & \phi_t(L)f(z) \\ &= \frac{1}{\pi} \int_{\mathbf{C}} \exp\left(-\left(\frac{h(z) - h(z - vt)}{2t}\right)^2 - \left(\frac{(h-2g)(z) - (h-2g)(z - vt)}{2it}\right)^2\right) \\ & \quad f(z - vt) D(z - vt) d\sigma(v). \end{aligned}$$

Taking the limit as $t \rightarrow 0$, we obtain (since we can take the limit inside):

$$\begin{aligned} & \lim_{t \rightarrow 0} \phi_t(L)f(z) \\ &= f(z) D(z) \\ & \quad \times \left\{ \frac{1}{\pi} \int_{\mathbf{C}} \exp\left(-\left(\left(\frac{\partial h}{\partial \bar{z}}(z)\bar{v} + \frac{\partial h}{\partial z}(z)v\right) / 2\right)^2 - \left(\left(\frac{\partial(h-2g)}{\partial \bar{z}}(z)\bar{v} + \frac{\partial(h-2g)}{\partial z}(z)v\right) / 2i\right)^2\right) d\sigma(v) \right\}. \end{aligned}$$

The expression inside { } is an unpleasant (but straightforward) Gaussian, which yields $1/D(z)$ after calculation. So,

$$(5.2) \quad \lim_{t \rightarrow 0} \phi_t(L)f(z) = f(z).$$

Hence we have an entire (and rapidly decreasing on Σ) approximation to the identity.

For ρ rapidly decreasing, we define $f_\rho \equiv \rho(L)f$.

PROPOSITION 5.1.

$$f_{\xi^n \phi_t} = L^n(f_{\phi_t}) = (L^n f)_{\phi_t}$$

and

$$f_{\bar{\xi}^n \phi_t} = \bar{L}^n(f_{\phi_t}) = (\bar{L}^n f)_{\phi_t}$$

for $n = 1, 2, 3, \dots$

This proposition connects \bar{L} , obtained geometrically, to the functional calculus. Equation (5.2) shows that $\lim_{t \rightarrow 0} (f_{\xi^n \phi_t}) = L^n f$, giving the expected result, and similarly for $\bar{L}^n f$. Before proving the proposition, we first note that, by a calculation using (2.5), we have the following lemma.

LEMMA 5.2.

$$\partial_z(a_1 D) + \partial_{\bar{z}}(a_2 D) = 0 \quad \text{and} \quad \partial_z(\tilde{b}_1 D) + \partial_{\bar{z}}(\tilde{b}_2 D) = 0.$$

Here, as before,

$$D = \frac{\partial h}{\partial z} \frac{\partial g}{\partial \bar{z}} - \frac{\partial g}{\partial z} \frac{\partial h}{\partial \bar{z}}.$$

Proof of Proposition 5.1. We will show that

$$f_{\xi^n \phi} = L^n(f_\phi) = (L^n f)_\phi \quad \text{and} \quad f_{\bar{\xi}^n \phi} = \bar{L}^n(f_\phi) = (\bar{L}^n f)_\phi$$

for any suitable ϕ . ϕ_t is certainly suitable. We define

$$u \equiv (h - g)(z) - (h - g)(w) \quad \text{and} \quad v \equiv g(z) - g(w).$$

Now,

$$L(\theta(u, v)) = \frac{\partial \theta}{\partial u} L(u) + \frac{\partial \theta}{\partial v} L(v), \quad L(u) = -i, \quad L(v) = 0.$$

Thus $L(\theta(u, v)) = -i(\partial \theta / \partial u)$. So

$$L(f_\phi) = \frac{1}{\pi^2} \int_{\mathbf{C}} (-i) \frac{\partial \theta(u, v)}{\partial u} f(w) D(w) d\sigma(w)$$

and

$$L^n(f_\phi) = \frac{1}{\pi^2} \int_{\mathbf{C}} (-i)^n \frac{\partial^n \theta(u, v)}{\partial u^n} f(w) D(w) d\sigma(w).$$

Now,

$$(L f)_\phi = \frac{1}{\pi^2} \int_{\mathbf{C}} \theta(u, v) (L f)(w) D(w) d\sigma(w).$$

But

$$\begin{aligned} & \frac{1}{\pi^2} \int_{\mathbf{C}} \theta(u, v) \left\{ \left(a_1 \left(-i \frac{\partial}{\partial w} \right) + a_2 \left(-i \frac{\partial}{\partial \bar{w}} \right) \right) f(w) \right\} D(w) d\sigma(w) \\ &= -\frac{1}{\pi^2} \int_{\mathbf{C}} \left\{ \left(a_1 \left(-i \frac{\partial}{\partial w} \right) + a_2 \left(-i \frac{\partial}{\partial \bar{w}} \right) \right) \theta(u, v) \right\} f(w) D(w) d\sigma(w), \end{aligned}$$

using integration by parts and Lemma 5.2.

But this last expression may be rewritten as

$$\frac{1}{\pi^2} \int_{\mathbf{C}} (-i) \frac{\partial \theta(u, v)}{\partial u} f(w) D(w) d\sigma(w).$$

(We have the extra minus sign since $L_w(u) = -L_z(u) = +i$.) So

$$(L^n f)_\phi = \frac{1}{\pi^2} \int_{\mathbf{C}} (-i)^n \frac{\partial^n \theta(u, v)}{\partial u^n} f(w) D(w) d\sigma(w).$$

Also, for $f_{\xi\phi}$,

$$\int_{\mathbf{C}} \xi \phi(\xi) \exp(i(\xi u + \bar{\xi} v)) d\sigma(\xi) = (-i) \frac{\partial}{\partial u} \theta(u, v),$$

and

$$f_{\xi^n \phi} = \frac{1}{\pi^2} \int_{\mathbf{C}} (-i)^n \frac{\partial^n \theta(u, v)}{\partial u^n} f(w) D(w) d\sigma(w).$$

Hence, the first part of the proposition holds. In an analogous way, one can obtain

$$(\bar{L}^n f)_\phi = \bar{L}^n(f_\phi) = f_{\bar{\xi}^n \phi} = \frac{1}{\pi^2} \int_{\mathbf{C}} (-i)^n \frac{\partial^n \theta(u, v)}{\partial v^n} f(w) D(w) d\sigma(w).$$

This concludes the proof of Proposition 5.1. \square

6. More Functional Calculus

Returning to formula (5.1), we would like to show that if $\phi_1, \phi_2 \in C_0^\infty(\mathbf{R}^2)$, or are of the form $x^j y^k \exp(-x^2 - y^2)$, then

$$(6.1) \quad \phi_1(L)\phi_2(L) = (\phi_1\phi_2)(L).$$

First we have the following proposition.

PROPOSITION 6.1. *If $F(z_1, z_2)$ is an entire function which decreases rapidly in a conic sector $|z_1 - \bar{z}_2| < M|z_1 + \bar{z}_2| + M'$ (if $((h-g)(z), g(z)) = (z_1, z_2)$, then Σ is contained in this sector), then*

$$\int_{\mathbf{C}} F((h-g)(z), g(z)) D(z) d\sigma(z) = \int_{\mathbf{C}} F(z, \bar{z}) d\sigma(z).$$

Proof. We first claim that if $\phi(w) = (h-g) \circ g^{-1}(\bar{w})$ then

$$(i) \quad \int_{\mathbf{C}} F(\phi(w), \bar{w}) \frac{\partial \phi}{\partial w} d\sigma(w) = \int_{\mathbf{C}} F((h-g)(z), g(z)) D(z) d\sigma(z).$$

Indeed,

$$\phi(w) = h \circ g^{-1}(\bar{w}) - \bar{w}, \quad \frac{\partial \phi}{\partial w} = \frac{\partial (h \circ g^{-1})(\bar{w})}{\partial \bar{w}}.$$

Let $\bar{w} = g(z)$, and substitute into the left-hand side of (i). We have $\phi(w) = (h-g)(z)$ and $d\sigma(w) = |-J_g(z)| d\sigma(z) = -J_g(z) d\sigma(z)$, since $|\partial_{\bar{z}} g|^2 - |\partial_z g|^2 > 0$. Also note that

$$\left. \frac{\partial (h \circ g^{-1})(\bar{w})}{\partial \bar{w}} \right|_{\bar{w}=g(z)} = \left. \frac{\partial (h \circ g^{-1})(w)}{\partial w} \right|_{w=g(z)}.$$

Using the chain rule, and letting

$$X = \left. \frac{\partial (h \circ g^{-1})}{\partial w} \right|_{w=g(z)}, \quad Y = \left. \frac{\partial (h \circ g^{-1})}{\partial \bar{w}} \right|_{w=g(z)},$$

we have the following system of equations:

$$\begin{cases} \frac{\partial h}{\partial z} = X \frac{\partial g}{\partial z} + Y \frac{\partial \bar{g}}{\partial z}, \\ \frac{\partial h}{\partial \bar{z}} = X \frac{\partial g}{\partial \bar{z}} + Y \frac{\partial \bar{g}}{\partial \bar{z}}, \end{cases}$$

which implies that $Y = -(D(z)/J_g(z))$. Substituting these expressions for Y , $\phi(w)$, and $d\sigma(w)$ into the left-hand side of (i), we obtain the right-hand side.

For the second part of the proof, we want to show that

$$\int_{\mathbf{C}} F(\phi(w), \bar{w}) \frac{\partial \phi}{\partial w} d\sigma(w) = \int_{\mathbf{C}} F(w, \bar{w}) d\sigma(w)$$

(this is done in Coifman–Meyer [CM2]). We write $\phi(w) = w + r(w)$ for some r with small Lipschitz norm. Let $\phi_t(w) = w + tr(w)$ ($0 \leq t \leq 1$), and let

$$J(t) = \int_{\mathbf{C}} F(\phi_t(w), \bar{w}) \frac{\partial \phi_t}{\partial w} d\sigma(w).$$

Then

$$\begin{aligned} \frac{d}{dt} J(t) &= \int_{\mathbf{C}} F_1(\phi_t(w), \bar{w}) r(w) \frac{\partial \phi_t}{\partial w} d\sigma(w) + \int_{\mathbf{C}} F(\phi_t(w), \bar{w}) \frac{\partial r}{\partial w} d\sigma(w) \\ &= \int_{\mathbf{C}} \frac{\partial}{\partial w} \{F(\phi_t(w), \bar{w}) r(w)\} d\sigma(w) \\ &= 0. \end{aligned}$$

So $J(0) = J(1)$, which is what we needed. (The first part of the proof seems to be the nonlinear part of the calculation, while the second part is the linear one.) □

Now, we would like to show (6.1). We need to show that

$$(6.2) \quad \begin{aligned} & \frac{1}{\pi^4} \int_{\mathbf{C}} k_1((h-g)(z) - (h-g)(w), g(z) - g(w)) D(w) \\ & \quad k_2((h-g)(w) - (h-g)(z'), g(w) - g(z')) d\sigma(w) \\ & = \frac{1}{\pi^2} k_3((h-g)(z) - (h-g)(z'), g(z) - g(z')). \end{aligned}$$

Here, for $i = 1, 2$,

$$k_i(u, v) = \int_{\mathbf{C}} \phi_i(\xi) \exp(i(u\xi + v\bar{\xi})) d\sigma(\xi),$$

and k_3 is associated in an analogous way to $\phi_1\phi_2$. The left-hand side of (6.2) is

$$\frac{1}{\pi^4} \int_{\mathbf{C}} k_1((h-g)(z) - w, g(z) - \bar{w}) k_2(w - (h-g)(z'), \bar{w} - g(z')) d\sigma(w),$$

by Proposition 6.1. Now: $k_1((h-g)(z) - w, g(z) - \bar{w}) = (\tilde{\phi}_1)^\wedge(2x, -2y)$; $u = x + iy$, where $\tilde{\phi}_1 = \phi_1(\xi) \exp(i(\xi(h-g)(z) + \bar{\xi}g(z)))$; and

$$k_2(w - (h-g)(z'), \bar{w} - g(z')) = (\tilde{\phi}_2)^\vee(2x, -2y)4\pi^2,$$

where $\tilde{\phi}_2 = \phi_2(\xi) \exp(-i(\xi(h-g)(z') + \bar{\xi}g(z')))$. Thus, the left-hand side of (6.2) is:

$$\begin{aligned} & \frac{4\pi^2}{4\pi^4} \int_{\mathbf{C}} (\tilde{\phi}_1)^\wedge(x, y) (\tilde{\phi}_2)^\vee(x, y) dx dy \\ & = \frac{1}{\pi^2} \int_{\mathbf{C}} \tilde{\phi}_1 \tilde{\phi}_2 dx dy \\ & = \frac{1}{\pi^2} \int_{\mathbf{C}} \phi_1(\xi) \phi_2(\xi) \exp(i(\xi((h-g)(z) - (h-g)(z')) \\ & \quad + \bar{\xi}(g(z) - g(z')))) d\sigma(z) \\ & = \frac{1}{\pi^2} k_3((h-g)(z) - (h-g)(z'), g(z) - g(z')). \end{aligned}$$

This finishes the demonstration of (6.1). □

7. L^2 Boundedness and Extension to More General ϕ

In this section we define $\phi(L)$ for more general ϕ , and extend the results in [CM2] about L^2 boundedness. We define Ω_M ($0 < M < 1$) to be the sector on \mathbf{C}^2 given by

$$(\operatorname{Im} \tilde{u})^2 + (\operatorname{Im} \tilde{v})^2 < M^2((\operatorname{Re} \tilde{u})^2 + (\operatorname{Re} \tilde{v})^2),$$

with $\tilde{u} = \xi + i\xi'$ and $\tilde{v} = \eta + i\eta'$.

PROPOSITION 7.1. *Let L be as before. Suppose a_1 and a_2 are as in Section 3, or (more generally) that η and m have small Lipschitz norms (see*

also Section 8). Then, for any $0 < M < 1$, if $\chi: \Omega_M \rightarrow \mathbf{C}$ is bounded and holomorphic then the operator $\chi(L)$ is bounded on $L^2(\mathbf{R}^2)$. $\chi(L)$ is defined in the following way: We let

$$\chi_\epsilon = \chi \exp(-\epsilon(\tilde{u}^2 + \tilde{v}^2)), \quad (\tilde{u}, \tilde{v}) \in \Omega_M,$$

and $\chi(L)(f) = \lim_{\epsilon \rightarrow 0} \chi_\epsilon(L)(f)$ in the weak sense.

Proof. We will show that $\|\chi_\epsilon(L)\|_{L^2, L^2} \leq c \|\chi\|_{H^\infty(\Omega_M)}$, c independent of ϵ . We use formula (5.1) for $\chi_\epsilon(L)$. Let $k_\epsilon(z, w)$ be the kernel of $\chi_\epsilon(L)$, and let $k_\epsilon^0(z, w)$ be such that $k_\epsilon(z, w) = (1/\pi^2)k_\epsilon^0(z, w)D(w)$. Let T_ϵ^0 be the operator defined by k_ϵ^0 . We have:

- (i) $|k_\epsilon^0(z, w)| \leq c_1/|z - w|^2$;
- (ii) $|(\partial/\partial z)k_\epsilon^0(z, w)| + |(\partial/\partial \bar{z})k_\epsilon^0(z, w)| \leq c_2/|z - w|^3$, and similarly for $|(\partial/\partial w)k_\epsilon^0| + |(\partial/\partial \bar{w})k_\epsilon^0|$;
- (iii) $T_\epsilon^0(D) = c\chi(0)$;
- (iv) $(T_\epsilon^0)'(D) = c\chi(0)$; and
- (v) $\chi_\epsilon(L)f(z) = \int A(z, w)(Lf)(w)D(w) d\sigma(w)$, where $|A(z, w)| \leq c_3/|z - w|$.

The constants c_1, c_2, c_3, c depend only on M (in particular, not on ϵ). Once we have (i) through (v) we are done. (v) shows weak boundedness of DT_ϵ^0D ; if f, g are supported in a cube $Q \subseteq \mathbf{C}$ then

$$|\langle D(z)\chi_\epsilon(L)f(z), g(z) \rangle| \leq c|Q|^{3/2}\|g\|_\infty\|\nabla f\|_\infty.$$

(i) and (ii) show that k_ϵ^0 is standard, and (iii) and (iv) complete the requirements of the $T(b)$ theorem [DJS] for T_ϵ^0 , since $\text{Re } D(z) \approx 1$ if m and η have small Lipschitz norms.

To show (i) and (ii), we repeat the argument in [CM2]:

$$\chi_\epsilon = \chi \exp(-\epsilon(\tilde{u}^2 + \tilde{v}^2)),$$

and let $\phi_\epsilon(\zeta) = \chi_\epsilon(\bar{\zeta}/2)$. Calculate the inverse Fourier-Laplace transform of $\phi_\epsilon(\xi, \eta)$:

$$\Phi_\epsilon(\tilde{u}, \tilde{v}) = \frac{1}{4\pi^2} \int_{\mathbf{R}^2} \exp(i(\tilde{u}\xi + \tilde{v}\eta))\phi_\epsilon(\xi, \eta) d\xi d\eta.$$

Then $\Phi_\epsilon(\tilde{u}, \tilde{v})$ is holomorphic in the sector $\Omega_{M'}$, $M' < M$, and we have

$$|\Phi_\epsilon(\tilde{u}, \tilde{v})| \leq c \|\chi\|_{H^\infty(\Omega_M)} (|\tilde{u}|^2 + |\tilde{v}|^2)^{-1}.$$

Also,

$$|\partial_{\tilde{u}}^\alpha \partial_{\tilde{v}}^\beta \Phi_\epsilon(\tilde{u}, \tilde{v})| \leq c_{\alpha, \beta} \|\chi\|_{H^\infty(\Omega_M)} (|\tilde{u}|^2 + |\tilde{v}|^2)^{-1-\alpha/2-\beta/2}.$$

This can be obtained in the usual way. We change the contour of integration to change \tilde{u} and \tilde{v} in $\exp(i(\tilde{u}\xi + \tilde{v}\eta))$ to be real. By the definition of χ_ϵ , we are permitted to do this in each variable separately. Once we have done this rotation, using Cauchy's theorem again, we see that the symbol σ associated with $\Phi_\epsilon(\tilde{u}, \tilde{v})$ satisfies

$$|\partial^\alpha \partial^\beta \sigma| \leq \frac{C_{\alpha, \beta}}{(|\xi|^2 + |\eta|^2)^{(\alpha + \beta)/2}}.$$

We then do the usual real variable argument. Now,

$$\begin{aligned} k_\epsilon^0(z, w) &= \Phi_\epsilon \left(\frac{h(z) - h(w)}{2}, \frac{(h - 2g)(z) - (h - 2g)(w)}{2i} \right) \\ &= \Phi_\epsilon \left(x - s + \frac{\eta(z) - \eta(w)}{2}, y - t + \frac{(\eta - 2m)(z) - (\eta - 2m)(w)}{2i} \right), \end{aligned}$$

where $z = x + iy$ and $w = s + it$. (From the first section on functional calculus, \tilde{u} corresponds to $(u + v)/2$ and \tilde{v} to $(u - v)/2$.) We obtain (i) and (ii) from the fact that η and m are Lipschitz with small norm.

(iii) and (iv) follow from Proposition 6.1.

Finally, (v) follows from considering the symbol $\chi_\epsilon(\zeta)/\zeta$ instead of $\chi_\epsilon(\zeta)$ and applying a similar argument from pseudodifferential operators to the one used to obtain (i) and (ii).

It remains to show that $\lim_{\epsilon \rightarrow 0} \chi_\epsilon(L)f$ exists in the weak sense, that is, given $f, p \in L^2(\mathbf{R}^2)$, $\lim_{\epsilon \rightarrow 0} \int \chi_\epsilon(L)fp$ exists. This is equivalent to showing that

$$\lim_{\epsilon \rightarrow 0} \int \chi_\epsilon(L)f(z)p(z)D(z) d\sigma(z)$$

exists. We will show that the above sequence is Cauchy, that is,

$$(*) \quad \int \chi_{\epsilon_1}(L)f(z)p(z)D(z) - \int \chi_{\epsilon_2}(L)f(z)p(z)D(z) \rightarrow 0$$

as $\epsilon_1, \epsilon_2 \rightarrow 0$. Since we know that $\|\chi_\epsilon(L)\|_{L^2, L^2}$ is uniformly bounded, to show (*) it suffices to take f, p in some dense class in L^2 .

In order to define an appropriate dense class, we digress a bit to define an operator τ :

$$\tau u(z) = \frac{1}{2\pi} \int_{\mathbf{R}^2} \exp\left(\frac{i}{2}((h - g)(z)\bar{\xi} + g(z)\xi)\right) u(\xi) d\sigma(\xi).$$

Note that τu is well defined if u has compact support. It is easy to show that the set of τu , where u has compact support, is dense in $L^2(\mathbf{R}^2)$.

We now return to (*). We set $f = \tau\phi$ and $p = \tau\psi$, where ϕ, ψ have compact support and are in L^2 . Then

$$(*) = \frac{1}{\pi^2} \iint k((h - g)(z) - (h - g)(w), g(z) - g(w)) (\tau\phi)(w)(\tau\psi)(z)D(z)D(w) d\sigma(z) d\sigma(w),$$

where

$$k(u, v) = \int_{\mathbf{C}} (\chi_{\epsilon_1} - \chi_{\epsilon_2})(\xi) \exp(i(u\xi + v\bar{\xi})) d\sigma(\xi).$$

By Proposition 6.1 (applied twice),

$$(*) = c \int_{\mathbb{C}} \int_{\mathbb{C}} \int_{\mathbb{C}} (\chi_{\epsilon_1} - \chi_{\epsilon_2})(\xi) \exp(i((z-w)\xi + \overline{(z-w)}\bar{\xi})) \hat{\phi}(w) \hat{\psi}(z) d\sigma(w) d\sigma(z) d(\xi).$$

So

$$\begin{aligned} (*) &\leq c \int_{\mathbb{C}} |(\chi_{\epsilon_1} - \chi_{\epsilon_2})(\xi)| |\phi(-2\bar{\xi})| |\psi(2\bar{\xi})| d\sigma(\xi) \\ &\leq c \left(\int_{\mathbb{C}} |(\chi_{\epsilon_1} - \chi_{\epsilon_2})(\xi)|^2 |\phi(-2\bar{\xi})|^2 \right)^{1/2} \|\psi\|_2 \rightarrow 0 \end{aligned}$$

as $\epsilon_1, \epsilon_2 \rightarrow 0$, by dominated convergence theorem. This concludes the proof of Proposition 7.1. \square

8. Restrictions Forced on m and η Assuming L/\bar{L} and \bar{L}/L Are Bounded on L^2

We have obtained a functional calculus for $L = a_1 \partial_z + a_2 \partial_{\bar{z}}$, assuming that the partials of m and η are small, and making implicitly the assumptions of (i) in Proposition 8.1 below. All of the above are satisfied if, for example, we place the restrictions on a_2 and a_1 described in Section 3. In this section, we wish to show that bounds on a_1, a_2 and L^2 norms of L/\bar{L} and \bar{L}/L are all that is needed to estimate the bi-Lipschitz norms of $h-g$, g , the Lipschitz norms of m and η , and the distance of D away from 0.

In Proposition 8.1 below, we assume there are constants $c_1 > 0$, $c_2 > 0$, $c_3 > 0$, and $1 > c_4 > 0$ such that

$$\|a_1\|_{\infty} < c_1, \quad \|a_2\|_{\infty} < c_2, \quad \left\| \frac{1}{a_1} \right\|_{\infty} < c_3, \quad \text{and} \quad \left\| \frac{a_2}{a_1} \right\|_{\infty} < 1 - c_4.$$

We define \tilde{b}_1 and \tilde{b}_2 using (3.5a) and (3.5b) (see Proposition 8.1 for more details), and assume that there exist $c_5 > 0$ and $c_6 > 0$ such that L/\bar{L} and \bar{L}/L have L^2 norms bounded by c_5 and c_6 (resp.). We use the following form for L/\bar{L} and \bar{L}/L :

$$\begin{aligned} \frac{L}{\bar{L}} &= (a_1(z)B + a_2(z)) \frac{1}{\tilde{b}_1(z)B + \tilde{b}_2(z)}, \\ \frac{\bar{L}}{L} &= (\tilde{b}_1(z)B + \tilde{b}_2(z)) \frac{1}{a_1(z)B + a_2(z)} \end{aligned}$$

(not the integral kernel form obtained in Section 4). Now, let's solve (2.4) and (2.5) to obtain:

$$\begin{aligned} \frac{\partial g}{\partial z} &= -\frac{a_2}{a_1} \frac{\partial g}{\partial \bar{z}}, \\ \frac{\partial(h-g)}{\partial \bar{z}} &= -\frac{\tilde{b}_1}{\tilde{b}_2} \frac{\partial(h-g)}{\partial z}, \\ \frac{\partial(h-g)}{\partial z} &= \frac{1}{a_1} \left(1 - \frac{a_2 \tilde{b}_1}{a_1 \tilde{b}_2} \right)^{-1}, \end{aligned}$$

$$\frac{\partial g}{\partial \bar{z}} = \frac{1}{\tilde{b}_1} \left(1 - \frac{\tilde{b}_1 a_2}{\tilde{b}_2 a_1} \right)^{-1}.$$

Thus

$$\left(\frac{\partial(h-g)}{\partial z} \pm \frac{\partial(h-g)}{\partial \bar{z}} \right)^{\pm 1} = \left[\frac{1}{a_1} \left(1 \mp \frac{\tilde{b}_1}{\tilde{b}_2} \right) \left(1 - \frac{a_2 \tilde{b}_1}{a_1 \tilde{b}_2} \right)^{-1} \right]^{\pm 1}$$

and

$$\left(\frac{\partial g}{\partial \bar{z}} \pm \frac{\partial g}{\partial z} \right)^{\pm 1} = \left[\frac{1}{\tilde{b}_2} \left(1 \mp \frac{a_2}{a_1} \right) \left(1 - \frac{a_2 \tilde{b}_1}{a_1 \tilde{b}_2} \right)^{-1} \right]^{\pm 1}.$$

A similar expression can be obtained for D . Proposition 8.1 proves that $\|1/\tilde{b}_2\|_\infty < d_3$ and $\|\tilde{b}_1/\tilde{b}_2\|_\infty < 1 - d_4$ ($0 < d_4 < 1$), where d_3 and d_4 depend only on the constants c_1, \dots, c_6 mentioned above. Hence, we conclude that $h - g$ and g are bi-Lipschitz, m and η are Lipschitz, and D stays away from 0, with all quantities estimated in terms of c_1, \dots, c_6 .

PROPOSITION 8.1.

- (i) Suppose there are constants (not all independent) $c_1 > 0, c_2 > 0, c_3 > 0$, and $1 > c_4 > 0$ such that $\|a_1\|_\infty < c_1, \|a_2\|_\infty < c_2, \|1/a_1\|_\infty < c_3$, and $\|a_2/a_1\|_\infty < 1 - c_4$.
- (ii) Consider the operator $Q = (1 + B^{-1}M(a_2/a_1))^{-1}$, where $M(a_2/a_1)$ denotes multiplication by a_2/a_1 . Assume that $Q(1)$ and $Q(B^{-1}(1/a_1))$ are in L^∞ , and that $\|Q(1)\|_\infty > 0$.
- (iii) Using assumption (ii), we can define \tilde{b}_1 and \tilde{b}_2 by (3.5a) and (3.5b), and \tilde{b}_1 and \tilde{b}_2 are in L^∞ . Assume that $\|\tilde{b}_1/\tilde{b}_2\|_\infty < 1$ and $\|1/\tilde{b}_2\|_\infty < \infty$.
- (iv) Let c_5 be the L^2 norm of the operator

$$\frac{L}{\bar{L}} = (a_1(z)B + a_2(z)) \frac{1}{\tilde{b}_1(z)B + \tilde{b}_2(z)}$$

and let c_6 be the L^2 norm of the operator

$$\frac{\bar{L}}{L} = (\tilde{b}_1(z)B + \tilde{b}_2(z)) \frac{1}{a_1(z)B + a_2(z)}.$$

Then there exist $d_1 > 0, d_2 > 0, d_3 > 0$, and $0 < d_4 < 1$, depending only on c_1, \dots, c_6 , such that $\|\tilde{b}_1\|_\infty < d_1, \|\tilde{b}_2\|_\infty < d_2, \|1/\tilde{b}_2\|_\infty < d_3$, and $\|\tilde{b}_1/\tilde{b}_2\|_\infty < 1 - d_4$.

Note that the point of this proposition is that the quantities d_1, \dots, d_4 , whose existence is assumed in the hypotheses (ii) and (iii), depend only on c_1, \dots, c_6 .

We first prove the following lemma.

LOCALIZATION LEMMA. Let $e_1(z), e_2(z), e_3(z), e_4(z)$ be bounded functions, and either $\|e_4/e_3\|_\infty < 1$ and $\|1/e_3\|_\infty < \infty$ or $\|e_3/e_4\|_\infty < 1$ and $\|1/e_4\|_\infty < \infty$. Define the operators $S = e_1(z)B + e_2(z), T = 1/(e_3(z)B + e_4(z))$ on L^2 . Then $\|ST\|_2 \geq \|S_{z_0}T_{z_0}\|_2$ for any fixed z_0 in \mathbb{C} at which e_1, \dots, e_4 are continuous, where $S_{z_0} = e_1(z_0)B + e_2(z_0)$ and $T_{z_0} = 1/(e_3(z_0)B + e_4(z_0))$.

Proof. Choose f in L^2 of norm 1 and define $f_k(z) = kf(k(z - z_0))$, where the factor k preserves the L^2 norm. Write

$$STf_k - S_{z_0}T_{z_0}f_k = STf_k - ST_{z_0}f_k + ST_{z_0}f_k - S_{z_0}T_{z_0}f_k.$$

However,

$$\|ST_{z_0}f_k - S_{z_0}T_{z_0}f_k\|_2 = \|(S - S_{z_0})(T_{z_0}f)_k\|_2 \rightarrow 0$$

as $k \rightarrow \infty$. We use the fact that B commutes with translation and dilation and hence so does T_{z_0} , for z_0 kept constant. The first part of $STf_k - S_{z_0}T_{z_0}f_k$ can be handled in a similar way, so we have

$$\|STf_k - S_{z_0}T_{z_0}f_k\|_2 \rightarrow 0$$

as $k \rightarrow \infty$, and the conclusion of the lemma follows. \square

The proof of Proposition 8.1 is now almost immediate. From (iv) and the localization lemma, we have:

$$(a) \quad \left| \frac{a_1(z_0)(\bar{\xi}/\xi) + a_2(z_0)}{\tilde{b}_1(z_0)(\bar{\xi}/\xi) + \tilde{b}_2(z_0)} \right| < c_5;$$

$$(b) \quad \left| \frac{\tilde{b}_1(z_0)(\bar{\xi}/\xi) + \tilde{b}_2(z_0)}{a_1(z_0)(\bar{\xi}/\xi) + a_2(z_0)} \right| < c_6.$$

Here we have used Plancherel's theorem. (a) and (b) hold for almost all z_0 and ξ in \mathbf{C} . From (b), we can find the desired d_1 and d_2 to control $\|\tilde{b}_1\|_\infty$ and $\|\tilde{b}_2\|_\infty$. From (a), we obtain $1/|\tilde{b}_1| - |\tilde{b}_2| < d_5$, and these constants depend only on c_1, \dots, c_6 . The rest of Proposition 8.1 follows easily. \square

9. Conjugation to the Coifman-Meyer Case

In this section, we see how the operator L arises by conjugation from the operator $a\partial_z$ considered by Coifman and Meyer in [CM1] and [CM2].

Let $Tf = U_{\bar{g}}a\partial_z U_{\bar{g}}^{-1}$, where $U_{\bar{g}}h \equiv h \circ \bar{g}$; g and a will be determined in a moment, so that $T = L$. Now

$$\partial_z U_{\bar{g}}^{-1}(f) = (-i) \left(\frac{\partial f}{\partial z} \circ \bar{g}^{-1} \frac{\partial \bar{g}^{-1}}{\partial z} + \frac{\partial f}{\partial \bar{z}} \circ \bar{g}^{-1} \frac{\partial \bar{g}^{-1}}{\partial \bar{z}} \right),$$

so

$$Tf = -ia \circ \bar{g} \times \left(\frac{\partial f}{\partial z} \frac{\partial \bar{g}^{-1}}{\partial z} \circ \bar{g} + \frac{\partial f}{\partial \bar{z}} \frac{\partial \bar{g}^{-1}}{\partial \bar{z}} \circ \bar{g} \right).$$

But

$$\frac{\partial \bar{g}^{-1}}{\partial z} \circ \bar{g} = \frac{1}{\rho} \frac{\partial g}{\partial \bar{z}} \quad \text{and} \quad \frac{\partial \bar{g}^{-1}}{\partial \bar{z}} \circ \bar{g} = -\frac{1}{\rho} \frac{\partial g}{\partial z}, \quad \text{where } \rho \equiv \left| \frac{\partial g}{\partial \bar{z}} \right|^2 - \left| \frac{\partial g}{\partial z} \right|^2.$$

Therefore

$$Tf = -ia \circ \bar{g} \times \left(\frac{1}{\rho} \frac{\partial g}{\partial \bar{z}} \frac{\partial}{\partial z} - \frac{1}{\rho} \frac{\partial g}{\partial z} \frac{\partial}{\partial \bar{z}} \right) f.$$

Hence, $Tf = Lf$ if and only if

$$\begin{cases} a_1 = \frac{1}{\rho} \frac{\partial g}{\partial \bar{z}} \times a \circ \bar{g}, \\ a_2 = -\frac{1}{\rho} \frac{\partial g}{\partial z} \times a \circ \bar{g}. \end{cases}$$

From the above system,

$$\frac{a_2}{a_1} = -\left(\frac{\partial g}{\partial z} \Big/ \frac{\partial g}{\partial \bar{z}}\right),$$

so

$$\frac{\partial g}{\partial z} = -\frac{a_2}{a_1} \frac{\partial g}{\partial \bar{z}},$$

which shows that this g is the same g we had before. Thus

$$a = \left(a_1 \rho \Big/ \frac{\partial g}{\partial \bar{z}}\right) \circ \bar{g}^{-1}$$

makes $T = L$.

To show that the formula (5.1) is obtained by conjugating the Coifman-Meyer formula, $U_{\bar{g}}(\phi(a\partial_z))U_{\bar{g}^{-1}}$, we do the following. Let

$$\frac{\partial q}{\partial \bar{z}} = \mu \frac{\partial q}{\partial z}, \quad \text{where } \mu = aB^{-1}\left(\frac{1}{a}\right).$$

Then

$$\phi(a\partial_z)f = \int_{\mathbb{C}} \int_{\mathbb{C}} \phi(\xi) \exp(i((q(z) - q(u))\xi + (\bar{z} - \bar{w})\bar{\xi})) d\sigma(\xi) \frac{\partial q}{\partial w} f(w) d\sigma(w).$$

Hence

$$\begin{aligned} & U_{\bar{g}}(\phi(a\partial_z))U_{\bar{g}^{-1}}f \\ &= \int_{\mathbb{C}} \int_{\mathbb{C}} \phi(\xi) \exp(i((q \circ \bar{g}(z) - q \circ \bar{g}(u))\xi \\ & \quad + (g(z) - g(u))\bar{\xi})) d\sigma(\xi) \left(\frac{\partial q}{\partial w}\right) \circ \bar{g}(u) \rho f d\sigma(u), \end{aligned}$$

using the change of variables $u = \bar{g}^{-1}(w)$. Now $\partial q / \partial w = 1/a$, so

$$\frac{\partial q}{\partial w} \circ \bar{g} = \frac{1}{a \circ \bar{g}} = \frac{1}{\rho a_1} \frac{\partial g}{\partial \bar{z}}.$$

Hence

$$\rho \times \left(\frac{\partial q}{\partial w}\right) \circ \bar{g} = \frac{1}{a_1} \frac{\partial g}{\partial \bar{z}}.$$

Now, remembering D ,

$$D \equiv \frac{\partial(h-g)}{\partial z} \frac{\partial g}{\partial \bar{z}} - \frac{\partial g}{\partial z} \frac{\partial(h-g)}{\partial \bar{z}} = \frac{1}{a_1} \frac{\partial g}{\partial \bar{z}},$$

so the weight factors in the expression for $U_{\bar{g}}\phi(a\partial_z)U_{\bar{g}^{-1}}$ and formula (5.1) match.

It remains to show that $q \circ \bar{g} = h - g$. It suffices to show that the other equation in system (2.4) is satisfied (here, $q \circ \bar{g} \approx z$, so we need $h - g$, not h itself). We need to show that

$$1 = a_1 \frac{\partial(q \circ \bar{g})}{\partial z} + a_2 \frac{\partial(q \circ \bar{g})}{\partial \bar{z}}.$$

The right-hand side is:

$$(!) \quad a_1 \left(\frac{\partial q}{\partial z} \circ \bar{g} \frac{\partial \bar{g}}{\partial z} + \frac{\partial q}{\partial \bar{z}} \circ \bar{g} \frac{\partial g}{\partial z} \right) + a_2 \left(\frac{\partial q}{\partial \bar{z}} \circ \bar{g} \frac{\partial g}{\partial \bar{z}} + \frac{\partial q}{\partial z} \circ \bar{g} \frac{\partial \bar{g}}{\partial \bar{z}} \right).$$

Now $(\partial q/\partial z) \circ \bar{g} = 1/(a \circ \bar{g})$, so

$$\begin{aligned} (!) &= a_1 \frac{\partial q}{\partial z} \circ \bar{g} \frac{\partial \bar{g}}{\partial z} + a_2 \frac{\partial q}{\partial z} \circ \bar{g} \frac{\partial \bar{g}}{\partial \bar{z}} + \mu \circ \bar{g} \left(a_1 \frac{\partial q}{\partial z} \circ \bar{g} \frac{\partial g}{\partial z} + a_2 \frac{\partial q}{\partial z} \circ \bar{g} \frac{\partial g}{\partial \bar{z}} \right) \\ &= \frac{1}{\rho} \frac{a \circ \bar{g} (\partial g/\partial \bar{z})}{a \circ \bar{g}} \frac{\partial \bar{g}}{\partial \bar{z}} + \frac{a \circ \bar{g} (-1/\rho)}{a \circ \bar{g}} \frac{\partial g}{\partial z} \frac{\partial \bar{g}}{\partial \bar{z}} + \mu \circ \bar{g} \left(\frac{a_1}{a \circ \bar{g}} \frac{\partial g}{\partial z} + \frac{a_2}{a \circ \bar{g}} \frac{\partial g}{\partial \bar{z}} \right) \end{aligned}$$

(using the equations connecting a , a_1 , and a_2), and hence

$$\begin{aligned} (!) &= \frac{1}{\rho} \left(\left| \frac{\partial g}{\partial \bar{z}} \right|^2 - \left| \frac{\partial g}{\partial z} \right|^2 \right) + \mu \circ \bar{g} \left(\frac{1}{\rho} \frac{\partial g}{\partial \bar{z}} \frac{\partial g}{\partial z} - \frac{1}{\rho} \frac{\partial g}{\partial z} \frac{\partial g}{\partial \bar{z}} \right) \\ &= \frac{1}{\rho} \rho = 1. \end{aligned}$$

10. Appendix

To prove Lemma 4.1, we first calculate the following. Let R_1 be a circle of radius $a > 0$, centered at the origin of \mathbf{R}^2 , and let R_2 be the circumscribed ellipse with major axis b and minor axis a , $b \geq a$. Then

$$\int_{R_2 \setminus R_1} z^{-2} d\sigma(z) = \int_{R_2 \setminus R_1} \bar{z}^{-2} d\sigma(z) = \pi \frac{b-a}{b+a}.$$

Now, suppose ρ is quasiconformal. Let

$$G(u) = \int_{\mathbf{C}} \frac{1}{u - \rho(w)} f(w) d(w).$$

Then

$$\frac{\partial G}{\partial \bar{u}} \Big|_{\rho(z)} = \frac{\pi f(z)}{|\partial_z \rho|^2 - |\partial_{\bar{z}} \rho|^2},$$

and

$$\begin{aligned} \frac{\partial G}{\partial u} \Big|_{\rho(z)} &= \frac{\partial}{\partial u} \int_{\mathbf{C}} \frac{1}{u - \rho(w)} f(w) d\sigma(w) \\ &= \frac{\partial}{\partial u} \int_{\mathbf{C}} \frac{1}{u - v} f(\rho^{-1}(v)) J_{\rho^{-1}}(v) d\sigma(v) \\ &= -\lim_{\epsilon \rightarrow 0} \int_{|u-v| \geq \epsilon} \frac{1}{(u-v)^2} f(\rho^{-1}(v)) J_{\rho^{-1}}(v) d\sigma(v) = \end{aligned}$$

$$\begin{aligned}
 &= -\lim_{\epsilon \rightarrow 0} \int_{\rho^{-1}(v) \notin \rho^{-1}\{B_\epsilon(u)\}} \frac{1}{(u-v)^2} f(\rho^{-1}(v)) J_{\rho^{-1}}(v) d\sigma(v) \\
 &+ \lim_{\epsilon \rightarrow 0} \int_{\rho^{-1}(v) \in B_{\bar{\epsilon}}(\rho^{-1}(u))} \frac{1}{(u-v)^2} f(\rho^{-1}(v)) J_{\rho^{-1}}(v) d\sigma(v) \quad (A)
 \end{aligned}$$

$$-\lim_{\epsilon \rightarrow 0} \int_{\rho^{-1}(v) \in B_{\bar{\epsilon}}(\rho^{-1}(u))} \frac{1}{(u-v)^2} f(\rho^{-1}(v)) J_{\rho^{-1}}(v) d\sigma(v). \quad (B)$$

Now

$$\begin{aligned}
 B &= -\lim_{\epsilon \rightarrow 0} \int_{w \in B_{\bar{\epsilon}}(z)} \frac{1}{(\rho(z) - \rho(w))^2} f(w) d\sigma(w) \\
 &= -p.v. \int_{\mathbb{C}} \frac{f(w)}{(\rho(z) - \rho(w))^2} d\sigma(w)
 \end{aligned}$$

and

$$A = \lim_{\epsilon \rightarrow 0} \int_{v \in B_\epsilon(u) - \rho\{B_{\bar{\epsilon}}(\rho^{-1}(u))\}} \frac{1}{(u-v)^2} f(\rho^{-1}(v)) J_{\rho^{-1}}(v) d\sigma(v).$$

In the above, B_ϵ and $B_{\bar{\epsilon}}$ refer to balls of appropriate radii. Now, if (in the expression for A) the circle and the ellipse were aligned along the x and y axes, then we could use our preliminary calculation to obtain:

$$A = \left| \frac{\partial \bar{\rho}}{\partial z} \middle/ \frac{\partial \rho}{\partial z} \right| \frac{\pi f(z)}{J_\rho(z)}.$$

But our picture is rotated, so we must let $\tilde{z} = e^{-i\theta} z$ to rotate to standard picture, where

$$\theta = \frac{1}{2} \arg \left(\frac{\partial \rho}{\partial \tilde{z}} \middle/ \frac{\partial \rho}{\partial z} \right)$$

(see [A]). Hence

$$A = - \left(\frac{\partial \bar{\rho}}{\partial z} \middle/ \frac{\partial \rho}{\partial z} \right) \frac{\pi f(z)}{J_\rho}.$$

Since

$$\frac{\partial}{\partial \tilde{z}} (G \circ \rho) = \frac{\partial G}{\partial u} \frac{\partial \rho}{\partial \tilde{z}} + \frac{\partial G}{\partial \bar{u}} \frac{\partial \bar{\rho}}{\partial \tilde{z}},$$

we have

$$\begin{aligned}
 \frac{\partial}{\partial \tilde{z}} \int_{\mathbb{C}} \frac{1}{\rho(z) - \rho(w)} f(w) d\sigma(w) &= -p.v. \int_{\mathbb{C}} \frac{f(w)}{(\rho(z) - \rho(w))^2} d\sigma(w) \\
 &+ \pi f(z) \left\{ \frac{\partial \rho / \partial z}{J_\rho} - \frac{\partial \bar{\rho} / \partial z}{\partial \rho / \partial z} \frac{\partial \rho / \partial \tilde{z}}{J_\rho} \right\},
 \end{aligned}$$

and the expression inside $\{ \}$ is $1/(\partial \rho / \partial z)$. The second part of Lemma 4.1 follows in the same way. □

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