

EXTRINSIC SPHERES IN IRREDUCIBLE HERMITIAN SYMMETRIC SPACES

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1. INTRODUCTION

Let M be an irreducible Hermitian symmetric space. Then \tilde{M} is simply connected and its canonical Hermitian structure is Kählerian. Let $2m$ be the real dimension of \tilde{M} . An n -dimensional submanifold N of \tilde{M} is called an extrinsic sphere if it is umbilical and has parallel, nonzero mean curvature vector. In Remark 2 of [2], Chen indicated that if the rank of \tilde{M} is ℓ , then \tilde{M} admits extrinsic spheres of dimensions $\leq \ell - 1$ with flat normal connections; namely, extrinsic spheres of maximal flat totally geodesic submanifolds of \tilde{M} . In this paper we investigate extrinsic spheres with flat normal connections in irreducible Hermitian symmetric spaces and shall prove the following.

THEOREM. *If N is an n -dimensional ($n \geq 2$) complete, simply connected extrinsic sphere with flat normal connection in an irreducible Hermitian symmetric space \tilde{M} , then $n \leq \text{rank } \tilde{M}$ and N is isometric to a standard n -sphere.*

2. PRELIMINARIES

\tilde{M} is always assumed to be an irreducible Hermitian symmetric space of real dimension $2m$ ($m > 1$). Let J and g be the complex structure and Kähler metric of \tilde{M} , let N be an n -dimensional submanifold of \tilde{M} , and let $\tilde{\nabla}$ and ∇ be the covariant differentiations on \tilde{M} and N , respectively. The second fundamental form h of N in \tilde{M} is defined by $h(X, Y) = \tilde{\nabla}_X Y - \nabla_X Y$, where X, Y are vector fields tangent to N . Then h is symmetric, with values in the normal bundle. For a vector field ξ normal to N we write $\tilde{\nabla}_X \xi = -A_\xi X + D_X \xi$, where $-A_\xi X$ and $D_X \xi$ denote the tangential and normal components of $\tilde{\nabla}_X \xi$. If $D_X \xi = 0$, ξ is said to be *parallel*. If $h(X, Y) = g(X, Y)H$, where $H = (\text{trace } h)/n$ is the mean curvature vector of N in \tilde{M} , N is said to be *umbilical*. Let \tilde{R} , R , and R^\perp be the curvature tensors associated with $\tilde{\nabla}$, ∇ , and D , respectively. Let

$$(\overline{\nabla}_X h)(Y, Z) = D_X(h(Y, Z)) - h(\nabla_X Y, Z) - h(Y, \nabla_X Z)$$

for X, Y, Z tangent to N . Then the equations of Codazzi and Ricci are

$$(\tilde{R}(X, Y)Z)^\perp = (\overline{\nabla}_X h)(Y, Z) - (\overline{\nabla}_Y h)(X, Z);$$

$$\tilde{R}(X, Y; \xi, \eta) = R^\perp(X, Y, \xi, \eta) - g([A_\xi, A_\eta]X, Y),$$

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where X, Y, Z are tangent to N , ξ and η are normal to N , and $(\tilde{R}(X, Y)Z)^\perp$ denotes the normal component of $\tilde{R}(X, Y)Z$. N is said to have *flat normal connection* in \tilde{M} if $R^\perp(X, Y) = 0$. If N is simply connected and has flat normal connection, then there exist $2m - n$ mutually orthogonal parallel unit normal vector fields

$$\xi_1, \xi_2, \dots, \xi_{2m-n}$$

along N . Furthermore, if N has parallel mean curvature vector H , we may assume that $H = \alpha\xi_1$, where α is a nonzero constant. Hence if N is an extrinsic sphere with flat normal connection in \tilde{M} , then $h(X, Y) = \alpha g(X, Y)\xi_1$, $\bar{\nabla}_X h = 0$, $R^\perp(X, Y) = 0$. The Codazzi and Ricci equations on N become

(1)
$$(\tilde{R}(X, Y)Z)^\perp = 0;$$

(2)
$$\tilde{R}(X, Y; \xi, \eta) = -g([A_\xi, A_\eta]X, Y).$$

For a Hermitian symmetric space \tilde{M} there is a triple (G, H, σ) consisting of a connected Lie group G , a closed subgroup H of G , and an involutive automorphism σ of G such that $\tilde{M} = G/H$. Let \mathfrak{G} and \mathfrak{H} be the Lie algebras of G and H , and let σ be the automorphism of \mathfrak{G} which is induced by σ of G . \mathfrak{H} is the eigenspace of σ for the eigenvalue 1. Let \mathfrak{M} be the eigenspace of σ for the eigenvalue -1. Then we have the canonical decomposition $\mathfrak{G} = \mathfrak{H} + \mathfrak{M}$ of $(\mathfrak{G}, \mathfrak{H}, \sigma)$ so that $[\mathfrak{H}, \mathfrak{H}] \subset \mathfrak{H}$, $[\mathfrak{H}, \mathfrak{M}] \subset \mathfrak{M}$, $[\mathfrak{M}, \mathfrak{M}] \subset \mathfrak{H}$. We may identify the tangent space $T_0(\tilde{M})$ of \tilde{M} at the origin 0 of \tilde{M} with \mathfrak{M} . The curvature tensor \tilde{R} of \tilde{M} is then given by

(3)
$$\tilde{R}(\tilde{X}, \tilde{Y})\tilde{Z} = -[[\tilde{X}, \tilde{Y}], \tilde{Z}], \quad \tilde{X}, \tilde{Y}, \tilde{Z} \in T_0(\tilde{M}).$$

For the Kähler structure J on \tilde{M} , we have $\tilde{R}(J\tilde{X}, J\tilde{Y}) = \tilde{R}(\tilde{X}, \tilde{Y})$. Hence we may use the relation $[J\tilde{X}, J\tilde{Y}] = [\tilde{X}, \tilde{Y}]$ for $\tilde{X}, \tilde{Y} \in T_0(\tilde{M})$.

3. PROOF OF THE THEOREM

Let \tilde{M} be an irreducible Hermitian symmetric space of real dimension $2m$ ($m > 1$). It is clear that \tilde{M} is either of compact or of noncompact type. Let N be a complete, simply connected extrinsic sphere with flat normal connection in \tilde{M} . The dimension of N is n and we assume that $n \geq 2$.

Let $\tilde{H}(\tilde{X})$ be the holomorphic sectional curvature of \tilde{M} determined by the vector \tilde{X} . Then the holomorphic pinching of \tilde{H} can be found in [2]. We shall utilize the results in [2] in the following form.

LEMMA 1. *If \tilde{M} is of compact type, then $\tilde{H} > 0$. If \tilde{M} is of noncompact type, then $\tilde{H} < 0$.*

We shall prove several other lemmas.

LEMMA 2. *Let N be a complete simply connected extrinsic sphere with flat normal connection in \tilde{M} . Then either N is isometric to a standard sphere and $\tilde{R}(X, Y) = 0$ for all X, Y tangent to N , or $J\xi_1$ is tangent to N , where ξ_1 is the direction of the mean curvature vector of N .*

Proof. If the dimension of N is even, Chen proved in [1] that N is isometric to a standard sphere of radius $1/\alpha$ and that $\tilde{R}(X, Y) = 0$ for all X, Y tangent to N .

Here α is the length of the mean curvature vector of N . Let the dimension of N be odd, say $2k + 1$. We may choose parallel orthonormal normal vectors $\xi_1, \xi_2, \dots, \xi_{2m-2k-1}$ so that $A_{\xi_1} = \alpha I$ and $A_{\xi_r} = 0$ for $r \geq 2$. We then have

$$(4) \quad \tilde{\nabla}_X \xi_r = -A_{\xi_r} X + D_X \xi_r = 0, \quad r \geq 2.$$

Define the functions ϕ_r on N by $\phi_r = g(J\xi_1, \xi_r)$, $r \geq 2$. As in the proof given in [1] for the even-dimensional case, ϕ_r satisfy the differential equations for all vectors X tangent to N :

$$(5) \quad \nabla_X d\phi_r = -\alpha^2 \phi_r X, \quad r \geq 2.$$

If there exists a nonconstant function ϕ_r defined on N satisfying (5), then by a result of Obata [5], N is isometric to the standard sphere of radius $1/\alpha$. We can also prove $\tilde{R}(X, Y) = 0$ for all X, Y tangent to N , as done in [1] for the case where N has even dimension.

Now suppose that all ϕ_r are constants. By (4) we have for all X tangent to N ,

$$0 = X\phi_r = g(J\tilde{\nabla}_X \xi_1, \xi_r) = -g(JA_{\xi_1} X, \xi_r) = \alpha g(X, J\xi_r), \quad r \geq 2.$$

Hence $\{\xi_2, \dots, \xi_{2m-2k-1}, J\xi_2, \dots, J\xi_{2m-2k-1}\}$ is a subspace of the normal space ν to N . $\dim \{\xi_r, J\xi_r: 2 \leq r \leq 2m - 2k - 1\}$ is even and greater than or equal to $2m - 2k - 2$, since it is invariant by J . $\dim \nu = 2m - 2k - 1$ implies that

$$\dim \{\xi_r, J\xi_r: 2 \leq r \leq 2m - 2k - 1\} = 2m - 2k - 2.$$

This implies that $J\xi_1$ is tangent to N .

LEMMA 3. *If N is isometric to a sphere with $\tilde{R}(X, Y) = 0$ for all X, Y tangent to N , then $\dim N \leq \text{rank } \tilde{M}$.*

Proof. Since \tilde{M} is symmetric, every point x in \tilde{M} can be regarded as the origin 0. Let T_0N denote the tangent space of N at 0. $\tilde{R}(X, Y) = 0$ implies that T_0N is contained in a maximal abelian subspace of $T_0\tilde{M}$ which is identified with \mathfrak{M} . This gives $\dim N \leq \text{rank } \tilde{M}$.

Now assume that N is not isometric to a sphere. Then $J\xi_1 \in T_0(N)$. We shall prove two more lemmas and then arrive at a contradiction. In the proof of Lemma 2 we have shown for this case that the dimension of N is odd, say $2k + 1$, and that $\nu_0(N) = \{\xi_1, \xi_2, \dots, \xi_{m-k}, J\xi_2, \dots, J\xi_{m-k}\}$. We may choose $e_1, \dots, e_k \in T_0(N)$, so that $T_0(N) = \{e_1, \dots, e_k, Je_1, \dots, Je_k, J\xi_1\}$, $k \geq 1$, since we have assumed $\dim N \geq 2$.

Let

$$\mathfrak{M}_1 = T_0(N) \cap JT_0(N) = \{e_1, \dots, e_k, Je_1, \dots, Je_k\};$$

$$\mathfrak{M}_2 = \nu_0 \oplus J\nu_0 = \{\xi_1, \xi_2, \dots, \xi_{m-k}, J\xi_1, \dots, J\xi_{m-k}\}.$$

It is clear that $\mathfrak{M} = \mathfrak{M}_1 \oplus \mathfrak{M}_2$ (direct sum) and that both \mathfrak{M}_1 and \mathfrak{M}_2 are J -invariant.

LEMMA 4. $[\mathfrak{M}_1, \mathfrak{M}_2] = 0$.

Proof. Let $X \in \mathfrak{M}_1$; then $JX \in \mathfrak{M}_1$. By (1) we have $\langle \tilde{R}(X, JX)J\xi_1, \xi_1 \rangle = 0$. This and the Bianchi identity imply that

$$\langle \tilde{R}(X, J\xi_1)\xi_1, JX \rangle + \langle \tilde{R}(X, \xi_1)JX, J\xi_1 \rangle = 0.$$

In a Hermitian space \tilde{M} for $\tilde{X}, \tilde{Y}, \tilde{Z} \in T(\tilde{M})$ we have $\tilde{R}(\tilde{X}, \tilde{Y})\tilde{Z} = -[[\tilde{X}, \tilde{Y}], \tilde{Z}]$. Thus we have

$$\langle [X, J\xi_1], [\xi_1, JX] \rangle + \langle [X, \xi_1], [JX, J\xi_1] \rangle = 0.$$

Using $[J\tilde{X}, J\tilde{Y}] = [\tilde{X}, \tilde{Y}]$, we obtain for all $X \in \mathfrak{M}_1$

$$(6) \quad [X, \xi_1] = 0, \quad [X, J\xi_1] = 0.$$

By use of (2) and the fact that $A_{\xi_r} = A_{J\xi_r} = 0$ for $r \geq 2$, we have

$$\langle \tilde{R}(X, JX)\xi_r, J\xi_r \rangle = 0.$$

Using the Bianchi identity and the fact that $\tilde{R}(X, JX)J\xi_r = J\tilde{R}(X, JX)\xi_r$, we find

$$0 = \langle \tilde{R}(X, JX)\xi_r, J\xi_r \rangle = \langle \tilde{R}(X, \xi_r)X, \xi_r \rangle + \langle \tilde{R}(X, J\xi_r)X, J\xi_r \rangle.$$

We thus have $\langle [X, \xi_r], [X, \xi_r] \rangle + \langle [X, J\xi_r], [X, J\xi_r] \rangle = 0$, and hence

$$(7) \quad [X, \xi_r] = 0, \quad [X, J\xi_r] = 0, \quad r \geq 2.$$

By (6) and (7) we have proven that $[\mathfrak{M}_1, \mathfrak{M}_2] = 0$.

LEMMA 5. $[[\mathfrak{M}_1, \mathfrak{M}_1], \mathfrak{M}_1] \subset \mathfrak{M}_1$, $[[\mathfrak{M}_2, \mathfrak{M}_2], \mathfrak{M}_2] \subset \mathfrak{M}_2$.

Proof. Let $X_1, Y_1, Z_1 \in \mathfrak{M}_1$. By (1), $\tilde{R}(X_1, Y_1)Z_1 \in T_0(N)$. There is $W_1 \in T_0(N)$ so that $Z_1 = JW_1$. $\tilde{R}(X_1, Y_1)Z_1 = J\tilde{R}(X_1, Y_1)W_1 \in JT_0(N)$. Hence we have that $\tilde{R}(X_1, Y_1)Z_1 \in \mathfrak{M}_1$. This proves that $[[\mathfrak{M}_1, \mathfrak{M}_1], \mathfrak{M}_1] \subset \mathfrak{M}_1$.

Let $X_2, Y_2, Z_2 \in \mathfrak{M}_2$ and $[[X_2, Y_2], Z_2] = W_1 + W_2$, where $W_1 \in \mathfrak{M}_1$, $W_2 \in \mathfrak{M}_2$. By Lemma 4 and the Jacobi identity, if $X_1 \in \mathfrak{M}_1$,

$$[[X_2, Y_2], X_1] = -[[Y_2, X_1], X_2] - [[X_1, X_2], Y_2] = 0.$$

Since \mathfrak{M}_1 is J-invariant,

$$\begin{aligned} [W_1, JW_1] &= [[[X_2, Y_2], Z_2], JW_1] \\ &= -[[Z_2, JW_1], [X_2, Y_2]] - [[JW_1, [X_2, Y_2]], Z_2] = 0. \end{aligned}$$

If $W_1 \neq 0$, then $\langle \tilde{R}(W_1, JW_1)JW_1, W_1 \rangle = -[[[W_1, JW_1], JW_1], W_1] = 0$. Hence the holomorphic sectional curvature $\tilde{H}(W_1) = 0$. This contradicts Lemma 1. Thus we have $W_1 = 0$ and hence $[[\mathfrak{M}_2, \mathfrak{M}_2], \mathfrak{M}_2] \subset \mathfrak{M}_2$.

Lemma 5 shows that each of \mathfrak{M}_1 and \mathfrak{M}_2 forms a Lie triple system. Then there are complete totally geodesic submanifolds M_1 and M_2 through the origin 0 such that $T_0(M_1) = \mathfrak{M}_1$, $T_0(M_2) = \mathfrak{M}_2$. For this situation, using the same argument as in [3], we can conclude that $\tilde{M} = M_1 \times M_2$. This contradicts the assumption that \tilde{M} is irreducible. Hence the theorem is proved.

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