K-CONTACT LIE GROUPS OF DIMENSION FIVE OR GREATER

Brendan J. Foreman

Abstract

We prove that a *K*-contact Lie group of dimension five or greater is the central extension of a symplectic Lie group by complexifying the Lie algebra and applying a result from complex contact geometry, namely, that, if the adjoint action of the complex Reeb vector field on a complex contact Lie algebra is diagonalizable, then it is trivial.¹

1. Introduction

Recall that a *real contact structure* on a manifold M of dimension 2n+1 is a distribution \mathscr{H} of TM given as the kernel of a 1-form η satisfying $\eta \wedge d\eta^n \neq 0$ at all points of M. The *Reeb vector field* of a contact manifold (M, \mathscr{H}, η) is the vector field ξ transverse to \mathscr{H} defined by the equations

$$\eta(\xi) = 1, \quad \iota(\xi) \ d\eta = 0.$$

The tangent bundle of M splits by $TM = \mathcal{H} \oplus \langle \xi \rangle$, and we denote the projection $TM \to \mathcal{H}$ by \mathcal{H} , as well. If M is a Lie group such that η is left-invariant, then we call M a contact Lie group.

Note that all of the above definitions also make sense if we switch to the complex category. That is, we call G a *complex contact Lie group*, if G is a complex Lie group with a left-invariant holomorphic one-form η such that $\eta \wedge d\eta^n \neq 0$ for $\dim_{\mathbb{C}} G = 2n+1$. Similarly, the definitions of the complex contact distribution and Reeb vector field carry over analogously.

The main result of this paper, namely that a *K*-contact Lie group of dimension five or greater is the central extension of a sympletic Lie group is the result of this analogy. Namely, given the *K*-contact Lie group, we complexify the contact structure, use a result in complex contact geometry and then note the consequences on the original real contact Lie group. Interestingly, this is the same strategy for which twistor spaces were originally invented and utilized in [5]. See [1] for additional and more detailed information on both real and complex contact structures.

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2. Real contact metric structures

This section provides the preliminary definitions and results with the real contact geometry. A metric g on a contact manifold (M, η) is called *associated* if the following criteria are satisified

- 1. $\eta(X) = g(X, \xi)$ for all $X \in TM$ and
- 2. the endomorphism $\phi: TM \to TM$ defined for $X, Y \in TM$ by

$$g(X, \phi Y) = d\eta(X, Y)$$

satisfies

$$\phi^2 = -I + \eta \otimes \xi.$$

Much is known about the resulting Riemannian geometry of associated metrics on contact manifolds ([1]). For the purposes here, the following results are needed.

PROPOSITION 2.1. Let (M, \mathcal{H}, η) be a contact manifold of dimension 2n + 1 with associated metric g. Then the Levi-Civita connection ∇ satisfies

$$\nabla_X \xi = -\phi X - \phi h X$$
,

where ϕ is a skew-symmetric endomorphism of TM such that $\phi^2 = -Id + \eta \otimes \xi$ and h is symmetric with respect to g.

For symplectic manifolds, there is an analogous concept of associated metric, namely, a metric k is associated to the symplectic structure of a manifold S, if there is an almost complex structure J on S such that the symplectic form ω is given by $\omega(X,Y)=g(X,JY)$.

An associated metric g of a contact manifold (M,\mathcal{H},η) is called K-contact, if ξ is an infinitesimal automorphism of g, i.e., $\mathcal{L}_{\xi}g=0$. It is not difficult to see that this is equivalent to the nullity of the tangent bundle transformation h as given in the proposition above. Also, it is easy to see that, if there is a symplectic manifold (S,ω) such that $\pi:M\to S$ is a fibration of the leaves of the Reeb vector field with $\pi^*\omega=d\eta$, then an associated metric g on g is g-contact if and only if there is an associated metric g on g-such that g

PROPOSITION 2.2. Let G be a contact Lie group with left-invariant contact form η , Reeb vector field ξ and left-invariant associated metric g. Then g is K-contact if and only if the matrix form of $ad(\xi)$ on the Lie algebra $\mathfrak g$ of G is skew-symmetric with respect to any orthonormal basis $e = \{e_1, \ldots e_{2n}\}$ of the contact distribution $\mathscr{H} = \ker \eta$.

Proof. Let g be a left-invariant metric and X, Y, Z be left-invariant vector fields on G. Then

$$g(\nabla_X Z, Y) = -\frac{1}{2}(g([Z, Y], X) + g([X, Y], Z) + g([Z, X], Y))$$

so that

$$g(\nabla_X Z, Y) + g(\nabla_Y Z, X) = -g([Z, Y], X) - g([Z, X], Y).$$

If g is associated, then $\nabla_X \xi = -\phi X - \phi h X$ and g is K-contact if and only if h=0. But the transformation ϕh is the symmetric part of $X\mapsto \nabla_X \xi$. So, h=0 if and only if $0=-g([\xi,Y],X)-g([\xi,X],Y)$ for any left-invariant horizontal vector fields X and Y, i.e., $0=-g(ad(\xi)Y,X)-g(ad(\xi)X,Y)$ for any $X,Y\in\mathfrak{g}$. This proves the proposition.

It is well known that any real skew-symmetric $n \times n$ matrix B is diagonalizable in the space of complex matrices, $M_{n \times n}(\mathbb{C})$. More specifically, there is a $Q \in O(n)$ such that

for some $b_1,\ldots,b_k\in\mathbf{R}^*$. Thus, if the Jordan canonical form of $ad(\xi)$ with respect to any left-invariant basis of g contains a block matrix of the form $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, then there is no K-contact structure on g.

3. Complex contact structures

This section deals solely with complex contact Lie groups, i.e., complex Lie groups with a left-invariant holomorphic 1-form η such that $\eta \wedge d\eta^n \neq 0$, where the complex dimension of the Lie group is 2n+1. Within this section, we will use the same notation for the resulting structures and forms in the complex contact Lie theoretical category as we did in the real category. So, like the real case, we let $\mathscr H$ be left-invariant distribution given as the kernel of η (in the holomorphic tangent bundle) and ξ be the left-invariant vector field given by $\eta(\xi)=1$ and $d\eta(\xi,*)=0$. It is only in the next section, where we are using both real and complex contact structures simultaneously that we will use different notation for the different categories. This material has already been published across two papers, [2] and [3], but for completeness and coherence we provide here a unified and streamlined presentation of the relevant results.

Suppose (G, η) is a (2n+1)-dimensional complex contact Lie group such that the adjoint representation of the Reeb vector field ξ on the Lie algebra of

G, \mathfrak{g} is diagonalizable. Let $A \subset \mathbb{C}$ be the set of all eigenvalues of $ad(\xi)$ with nontrivial eigenvectors. We call A the roots of ξ . For each $\alpha \in \mathbb{C}$, set

$$g_{\alpha} = \{ X \in \mathfrak{g} : [\xi, X] = \alpha X \}$$

For $X \in \mathfrak{g}$, $X = c\xi + \mathscr{H}X$ for some $c \in \mathbb{C}$ so that $[\xi, X] = [\xi, c\xi + \mathscr{H}X] = [\xi, \mathscr{H}X]$. Thus, if $\alpha \in A - \{0\}$, then $\mathfrak{g}_{\alpha} \subset \mathscr{H}$.

PROPOSITION 3.1. Let (G, η) be a (2n+1)-dimensional complex contact Lie group such that the adjoint representation of the Reeb vector field ξ is diagonalizable with roots given by the set A. Then

- 1. If $X \in \mathfrak{g}_{\alpha}$ and $Y \in \mathfrak{g}_{\beta}$ for $\alpha, \beta \in A$, then $ad(\xi)[X, Y] = (\alpha + \beta)[X, Y]$ and either $\alpha + \beta = 0$ or $d\eta(X, Y) = 0$.
- 2. For any $\alpha \in A$ and $X \in \mathfrak{g}_{\alpha} (0)$, there is a $Y \in \mathfrak{g}_{-\alpha}$ such that $[X, Y] = \xi + Z$ for some $Z \in \mathfrak{g}_0 \cap \mathscr{H}$.

Proof. For Statement 1, the Jacobi identity gives us:

$$0 = [[\xi, X], Y] + [[X, Y], \xi] + [[Y, \xi], X]$$

= $\alpha[X, Y] + [[X, Y], \xi] - \beta[Y, X].$

So, $ad(\xi)[X,Y]=(\alpha+\beta)[X,Y]$. In particular, $\eta(ad(\xi)[X,Y])=(\alpha+\beta)\eta([X,Y])$. By definition of ξ , the left-hand side is zero. Furthermore, $\eta([X,Y])=-2\ d\eta(X,Y)$. This proves Statement 1.

Let $\alpha \in A$ and $X \in \mathfrak{g}_{\alpha} - (0)$. Since $d\eta^n \neq 0$ on \mathscr{H} , we know that there exists $Y \in \mathscr{H}$ such that $[X,Y] = \xi + Z$ for some $Z \in \mathscr{H}$. In fact, if we create a basis of \mathscr{H} such that each element of the basis is an eigenvector of $ad(\xi)$, we see that there is some $\beta \in A$ such that $Y \in \mathfrak{g}_{\beta}$ and $[X,Y] = \xi + Z$ for some $Z \in \mathscr{H}$. By Statement 1, $\beta = -\alpha$. Also, $0 = ad(\xi)([X,Y]) = ad(\xi)(Z)$. This proves Statement 2.

THEOREM 3.2. Let (G, η) be a (2n+1)-dimensional complex contact Lie group such that the adjoint representation of the Reeb vector field ξ is diagonalizable. If n > 1, then $ad(\xi) = 0$.

Proof. We prove this theorem by systematically reviewing the cases where $A \neq \{0\}$ and showing that each such possible case creates a contradiction. First, we consider the situation in which $ad(\xi)$ has no zero eigenvectors in $\mathscr H$ and two distinct nonzero eigenvalues, α and $\beta \neq -\alpha$. Second, we investigate the case in which $ad(\xi)$ has exactly two eigenvectors in $\mathscr H$, $\alpha \neq 0$ and $-\alpha$. Finally, we consider the situation in which both $\alpha \neq 0$ and 0 are eigenvalues of $ad(\xi)$ in $\mathscr H$. We will show that each of these cases lead to a contradiction.

Case 1. Assume that $ad(\xi)$ has no zero eigenvectors in $\mathscr H$ and two distinct nonzero eigenvalues, α and $\beta \neq -\alpha$. Without losing any generality, we can assume that $\alpha \pm \beta \notin A$. In particular, by Proposition 3.1, $-\alpha \in A$, and $[X_{\alpha}, \mathfrak{g}_{-\alpha}] = \langle \xi \rangle$ for any $X_{\alpha} \in \mathfrak{g}_{\alpha}$. Furthermore, $[\mathfrak{g}_{+\alpha}, \mathfrak{g}_{\beta}] = (0)$.

Let $X_{\alpha} \in \mathfrak{g}_{\alpha}$, $X_{\beta} \in \mathfrak{g}_{\beta}$, both non-zero. By the Jacobi identity,

$$\beta X_{\beta} = ad(\xi)X_{\beta}$$

$$= ad([X_{\alpha}, X_{-\alpha}])X_{\beta}$$

$$= (ad X_{\alpha})(ad X_{-\alpha})(X_{\beta}) - (ad X_{-\alpha})(ad X_{\alpha})(X_{\beta})$$

$$= (ad X_{\alpha})([X_{-\alpha}, X_{\beta}] - (ad X_{-\alpha})[X_{\alpha}, X_{\beta}]$$

$$= 0.$$

since $[g_{+\alpha}, g_{\beta}] = (0)$. Thus, $\beta = 0$, a contradiction.

Case 2. Assume that $ad(\xi)$ has exactly two eigenvectors in \mathcal{H} , $\alpha \neq 0$ and $-\alpha$. Let $\underline{E} = \{E_1, \dots, E_{2n}\}$ be a basis of \mathcal{H} such that

$$\mathfrak{g}_{-\alpha} = \langle E_{2j-1} : j = 1, \dots, n \rangle$$

 $\mathfrak{g}_{\alpha} = \langle E_{2j} : j = 1, \dots, n \rangle$,

that is, $ad(\xi)E_k = (-1)^k \alpha E_k$ for $k = 1, \ldots, 2n$. By Proposition 3.1, $ad(\xi)[E_k, E_l] = ((-1)^k + (-1)^l)\alpha[E_k, E_l]$. In particular, $ad(\xi)[E_{2j_1}, E_{2j_2-1}] = 0$ and $0 = [E_{2j_1}, E_{2j_2}] = [E_{2j_1-1}, E_{2j_2-1}]$ for $j_1, j_2 = 1, \ldots, n$ (since $\mathfrak{g}_{\pm 2\alpha} = (0)$ by assumption). Thus, since $\mathfrak{g}_0 = \langle \xi \rangle$ by assumption, for each $k, l = 1, \ldots, 2n$, $[E_k, E_l] = \beta_{kl}\xi$ for some $\beta_{kl} \in \mathbb{C}$ with $0 = \beta_{\text{even even}} = \beta_{\text{odd odd}}$. Furthermore, the fact that \mathscr{H} is a complex contact structure on G implies that for every $k = 1, \ldots, 2n$, there is a $k = 1, \ldots, 2n$ such that $\beta_{kk} \neq 0$. Without loss of generality, we can assume that $\beta_{2j_2j_1-1} \neq 0$ for $j = 1, \ldots, n$.

Then

$$0 = [[E_1, E_2], E_3] + [[E_2, E_3], E_1] + [[E_3, E_1], E_2]$$
$$= \beta_{12}[\xi, E_3] + \beta_{23}[\xi, E_1]$$
$$= -\alpha \beta_{12} E_3 - \alpha \beta_{23} E_1.$$

Thus, $\alpha = 0$, which contradicts the assumption that $\alpha \neq 0$.

Case 3. Assume that both $\alpha \neq 0$ and 0 are eigenvalues of $ad(\xi)$ in \mathscr{H} . Proposition 3.1 implies that $[g_0,g_0] \subset g_0$. Let X_1 be a nonzero element of $g_0 \cap \mathscr{H}$. Then, again by Proposition 3.1, there is an element $\tilde{X}_2 \in g_0 \cap \mathscr{H}$ such that $\eta([X_1,\tilde{X}_2]) \neq 0$. By considering the Jordan canonical form of $ad(X_1)$ restricted on g_0 , we see that there is an $X_2 \in g_0 \cap \mathscr{H}$ such that $[X_1,X_2] = \xi$. Furthermore, $ad(X_j)(g_\alpha) \subset g_\alpha$ for each j=1,2. The Jacobi identity implies that $[ad(X_1),ad(X_2)]=ad([X_1,X_2])=ad(\xi)$ so that, on g_α , $[ad(X_1),ad(X_2)]=\alpha I$. But, for any linear transformations S and T on a given vector space V, ST-TS is never a non-zero multiple of the identity. Thus, we have a contradiction. Having exhausted all possibilities in which $A \neq \{0\}$, we have proven the theorem.

4. Main theorem

We now prove the main result as an easy corollary of Theorem 3.2.

THEOREM 4.1. Any K-contact Lie group of dimension five or greater is the central extension of a symplectic Lie group.

Proof. Given a real contact Lie algebra (\mathfrak{g},η) , the complexification $\mathfrak{g}^{\mathbb{C}}$ is a complex contact Lie algebra with complex contact form given by $\eta^{\mathbb{C}}(X+iY)=\eta(X)+i\eta(Y)$ for $X,Y\in\mathfrak{g}$. The complex Reeb vector field $\xi^{\mathbb{C}}$ in $\mathfrak{g}^{\mathbb{C}}$ is defined by:

$$\eta^{\mathbf{C}}(\xi^{\mathbf{C}}), d\eta^{\mathbf{C}}(\xi^{\mathbf{C}}, *) = 0.$$

Since $\xi \in \mathfrak{g} \subset \mathfrak{g}^{\mathbb{C}}$ satisfies this condition, $\xi^{\mathbb{C}} = \xi$. Thus, the adjoint operator $ad(\xi^{\mathbb{C}})$ is simply the complex extension of $ad(\xi)$ on g acting on $\mathfrak{g}^{\mathbb{C}}$.

In addition, suppose that g is a left-invariant associated metric on g such that (g, η, ξ, g) is a K-contact Lie algebra. There is then an orthonormal basis \underline{e} of gwith respect to which the matrix representation of $ad(\xi)$ is skew-symmetric.

Then the operator $ad(\xi^{\mathbb{C}})$ is diagonalizable on $\mathfrak{g}^{\mathbb{C}}$ with purely imaginary eigenvalues. By Theorem 3.2, $ad(\xi^{\mathbb{C}}) = 0$, which implies that $ad(\xi) = 0$. And so $(\mathfrak{g}, \eta, \xi)$ is the central extension of a symplectic Lie algebra.

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Brendan J. Foreman DEPARTMENT OF MATHEMATICS JOHN CARROLL UNIVERSITY University of Heights Оню 4418 **USA**

E-mail: bforeman@mirapoint.jcu.edu