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THE SECOND VARIATION OF THE DIRICHLET ENERGY ON CONTACT MANIFOLDS

BY SHANGRONG DENG

1. Introduction

S.S. Chern and R.S. Hamilton in a paper of 1985 [5] studied a kind of Dirichlet energy in terms of the torsion $\tau(\tau = \mathcal{L}_{\xi}g)$ of a 3-dimensional compact contact manifold and a problem analogous to the Yamabe problem. They raised the question of determining all 3-dimensional contact manifolds with $\tau=0$ (i.e. K-contact). In a long paper of 1989 [8] S. Tanno studied the Dirichlet energy and gauge transformations of contact manifolds. D.E. Blair [2] obtained the critical point condition of $I(g) = \int_{\mathcal{M}} Ric(\xi) dV_g$ over $\mathcal{M}(\eta)$ (the space of all the associated metrics), and proved that the regularity of the characteristic vector field ξ and the critical point condition force the metric to be K-contact. Since $Ric(\xi)=2n-1/4|\tau|^2$, the study of I(g) is the same as the study of the Dirichlet energy. In this paper we investigate the second variation and prove the following result.

THEOREM 2. Let M^{2n+1} be a compact contact manifold. If g is a critical metric of the Dirichlet energy $L(g) = \int_{M} |\tau|^2 dV_g$, i.e. $\nabla_{\xi} L_{\xi} g = 2(\mathcal{L}_{\xi} g) \phi$, then along any path $g_{ij}(t) = g_{ir} [\delta_j^r + tH_j^r + t^2 K_j^r + O(t^3)]$ in $\mathcal{M}(\eta)$

$$\frac{d^2L}{dt^2}(0)=2\int_{\mathcal{M}}|\mathcal{L}_{\xi}H_{j}^{i}|^2dV_{g}\geq 0,$$

and L(g) has minimum at each critical metric.

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2. Contact manifolds

A C^{∞} manifold M^{2n+1} is said to be a *contact manifold* if it carries a global 1-form η such that $\eta \wedge (d\eta)^n \neq 0$ everywhere. Given a contact form η it is well

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known that there exists a unique vector field ξ on M satisfying $d\eta(\xi, X)=0$ and $\eta(\xi)=1$; ξ is called the *characteristic vector field* of the contact structure. A Riemannian metric g is said to be an *associated metric* if there exists a tensor field ϕ of type (1, 1) such that $d\eta(X, Y)=g(X, \phi Y)$, $\phi^2=-I+\eta\otimes\xi$ and $\eta(X)=g(X,\xi)$. We call (ϕ, ξ, η, g) a *contact metric structure*. Such ϕ and g can be constructed by the polarization of $d\eta$ and they are not unique (see [4]). All associated metrics have the same volume element, namely $dV=(1/2^n n!)\eta \wedge d\eta^n$.

Let $\tau = \mathcal{L}_{\xi}g$ be the torsion and let $h = (1/2)\mathcal{L}_{\xi}\phi$. We have

$$\tau_{ij} = -2\phi_{ir}h_j^r$$
$$h_r^i\phi_j^r + \phi_r^ih_j^r = 0$$
$$\nabla_i\eta_j = \phi_{ij} - \phi_{ir}h_j^s$$

where $\phi_{ij} = g_{ir} \phi_j^r$, and

$$Ric(\xi) = 2n - |h|^2 = 2n - \frac{1}{4} |\tau|^2$$

We call the contact metric structure with $\tau = h = 0$ (or ξ is Killing) *K*-contact. For general reference see [1], [7] and [9].

3. The space of all associated metrics and the Dirichlet energy

The space of all Riemannian metrics of M^{2n+1} with fixed volume, denoted by \mathcal{M}_1 , is a symmetric Hilbert manifold; geodesics in \mathcal{M}_1 are of the form ge^{Ht} (here H is a type (1, 1) tensor field; see [6]). The space of all the associated metrics $\mathcal{M}(\eta)$ is a totally geodesic submanifold of \mathcal{M}_1 . See [4] for details about $\mathcal{M}(\eta)$. Let g(t) be any curve in $\mathcal{M}(\eta)$ with g(0)=g. Then the structure tensors $(\phi(t), \xi, \eta, g(t))$ corresponding to g(t) satisfy the following:

$$g_{ir}(t)\xi^{r} = \eta_{i}$$

$$2g_{ir}(t)\phi_{j}^{r}(t) = 2\phi_{ij} = \overline{\nu}_{i}\eta_{j} - \overline{\nu}_{j}\eta_{i}$$

$$\phi_{r}^{i}(t)\phi_{j}^{r}(t) = -\delta_{j}^{i} + \xi^{i}\eta_{j}.$$

Now we put

$$g_{ij}(t) = g_{ir} [\delta_j^r + tH_j^r + t^2 K_j^r + O(t^3)]$$

$$\phi_j^i(t) = \phi_j^i + tS_j^i + t^2 T_j^i + O(t^3).$$

Then from the above conditions we have

$$H_{ir}\xi^r = K_{ir}\xi^r = S_r^i\xi^r = T_r^i\xi^r = 0$$

$$H_{ij} + H_{rs}\phi_i^r\phi_j^s = 0, \quad hence \quad H_i^i = 0$$

$$S_j^i = \phi_r^iH_j^r, \quad S_r^iS_j^r = H_r^iH_j^r$$

$$T_j^i = \phi_r^iK_j^r$$

SHANGRONG DENG

$$K_{ij} + K_{rs}\phi_i^r\phi_j^s = H_{ir}H_j^r$$
$$2K_r^r = H^{rs}H_{rs}$$

where $H_{ij} = g_{ir}H_j^r$, etc., and the inverse of g(t) is given by ([8])

$$g^{ij}(t) = g^{ij} - tH^{ij} + t^2(H^i_r H^{rj} - K^{ij}) + O(t^3).$$

The critical point condition of the Dirichlet energy $L(g) = \int_{M} |\tau|^2 dV_g$ is given by the following theorem, see [2], [5] and [8] for proof.

THEOREM 1. Let M^{2n+1} be a compact contact manifold. An associated metric $g \in \mathcal{M}(\eta)$ is critical with respect to the Dirichlet energy if and only if

$$\nabla_{\varepsilon}\tau = 2\tau\phi$$
.

Remarks. Chern and Hamilton studied this over the set of all the CR-structures. Strongly pseudo-convex CR-manifolds are contact manifolds satisfying an integrability condition i.e. Q=0; in dimension 3 Q=0 trivially (see [8]).

4. Proof of Theorem 2

THEOREM 2. Let M^{2n+1} be a compact contact manifold. If g is a critical metric of the Dirichlet energy, i.e. $V_{\xi}\tau=2\tau\phi$, then along any path g(t) in $\mathcal{M}(\eta)$ with g(0)=g

$$\frac{d^{2}L}{dt^{2}}(0) = 2 \int_{M} |\mathcal{L}_{\xi}H_{j}^{i}|^{2} dV_{g} \ge 0,$$

and L(g) has minimum at each critical metric.

Proof. Let $g_{ij}(t) = g_{ij} + tH_{ij} + t^2K_{ij} + O(t^3)$ be any curve in $\mathcal{M}(\eta)$ with g(0) = g critical. Then for the curvature tensor we have

$$\begin{split} R_{ijk}{}^{h}(t) &= R_{ijk}{}^{h} + \frac{t}{2} (\vec{V}_{i} D_{jk}{}^{h} - \vec{V}_{j} D_{ik}{}^{h}) \\ &+ \frac{t^{2}}{2} \Big[\vec{V}_{i} (E_{jk}{}^{h} - H_{r}^{h} D_{jk}{}^{r}) - \vec{V}_{j} (E_{ik}{}^{h} - H_{r}^{h} D_{ik}{}^{r}) \\ &+ \frac{1}{2} (D_{ir}{}^{h} D_{jk}{}^{r} - D_{jr}{}^{h} D_{ik}{}^{r}) \Big] + O(t^{3}) \end{split}$$

where $D_{jk}{}^{i} = \overline{V}_{j}H_{k}^{i} + \overline{V}_{k}H_{j}^{i} - \overline{V}^{i}H_{jk}$, $E_{jk}{}^{i} = \overline{V}_{j}K_{k}^{i} + \overline{V}_{k}K_{j}^{i} - \overline{V}^{i}K_{jk}$. Therefore we have

$$\begin{split} R_{jk}(t) &= R_{jk} + \frac{t}{2} (\overline{\mathcal{V}}_r \overline{\mathcal{V}}_j H_k^r + \overline{\mathcal{V}}_r \overline{\mathcal{V}}_k H_j^r - \overline{\mathcal{V}}^r \overline{\mathcal{V}}_r H_{jk}) \\ &+ \frac{t^2}{4} [2 (\overline{\mathcal{V}}_r \overline{\mathcal{V}}_j K_k^r + \overline{\mathcal{V}}_r \overline{\mathcal{V}}_k K_j^r - \overline{\mathcal{V}}^r \overline{\mathcal{V}}_r K_{jk} - \overline{\mathcal{V}}_j \overline{\mathcal{V}}_k K_r^r) \end{split}$$

472

SECOND VARIATION OF THE DIRICHLET ENERGY

$$\begin{split} &-2H^{rs}(\nabla_{s}\nabla_{j}H_{rk}+\nabla_{s}\nabla_{k}H_{rj}-\nabla_{s}\nabla_{r}H_{jk}-\nabla_{j}\nabla_{k}H_{rs})\\ &-2\nabla_{s}H^{sr}(\nabla_{j}H_{rk}+\nabla_{k}H_{rj}-\nabla_{r}H_{jk})\\ &+\nabla_{j}H^{rs}\nabla_{k}H_{rs}-2\nabla_{r}H^{s}_{j}\nabla_{s}H^{r}_{k}+2\nabla_{r}H^{s}_{j}\nabla^{r}H_{sk}]+O(t^{s})\,. \end{split}$$

See [8] for some details. Let $I(g) = \int_{M} Ric(\xi) dV_g$. For any associated metric we have $Ric(\xi) = 2n - (1/4)|\tau|^2$, hence $I(g) = 2n \ vol(M) - (1/4)L(g)$. Now we assume

$$\begin{split} I_{1} = & \int_{\mathcal{M}} \xi^{j} \xi^{l} (\overline{\mathcal{V}}_{r} \overline{\mathcal{V}}_{l} K_{j}^{r} + \overline{\mathcal{V}}_{r} \overline{\mathcal{V}}_{j} K_{l}^{r} - \overline{\mathcal{V}}_{r} \overline{\mathcal{V}}_{r} K_{jl} - \overline{\mathcal{V}}_{l} \overline{\mathcal{V}}_{j} K_{r}^{r}) dV_{g} \\ I_{2} = & \int_{\mathcal{M}} \xi^{j} \xi^{l} \bigg[-H^{rs} (\overline{\mathcal{V}}_{r} \overline{\mathcal{V}}_{l} H_{sj} + \overline{\mathcal{V}}_{r} \overline{\mathcal{V}}_{j} H_{sl} - \overline{\mathcal{V}}_{r} \overline{\mathcal{V}}_{s} H_{jl} - \overline{\mathcal{V}}_{l} \overline{\mathcal{V}}_{j} H_{rs}) \\ & - \overline{\mathcal{V}}_{s} H^{sr} (\overline{\mathcal{V}}_{l} H_{rj} + \overline{\mathcal{V}}_{j} H_{rl} - \overline{\mathcal{V}}_{r} H_{jl}) + \frac{1}{2} \overline{\mathcal{V}}_{l} H^{rs} \overline{\mathcal{V}}_{j} H_{rs} \\ & + \overline{\mathcal{V}}_{r} H_{sj} \overline{\mathcal{V}}^{r} H_{l}^{s} - \overline{\mathcal{V}}_{r} H_{sj} \overline{\mathcal{V}}^{s} H_{l}^{r} \bigg] dV_{g} \,. \end{split}$$

Then for I(g) we have

$$\frac{d^2I}{dt^2}(0) = I_1 + I_2$$

Using Green's Theorem, the critical point condition and the facts that

$$\begin{aligned} H_r^i H_s^r h_i^s = & \overline{V}_{\xi} H_s^r H_s^i h_j^i \phi_j^r = 0 \\ \overline{V}^r \xi^i \overline{V}_i \xi^s = -g^{rs} + \xi^r \xi^s + h_j^r h^{js} \\ \overline{V}^i \xi^r \overline{V}_i \xi^s = g^{rs} - \xi^r \xi^s - 2h^{rs} + h_j^r h^{js} \end{aligned}$$

we compute as follows

$$\begin{split} &\int_{\mathcal{M}} \xi^{j} \xi^{l} \nabla_{\tau} \nabla_{l} K^{r}_{j} dV_{g} = \int_{\mathcal{M}} (\xi^{l} \nabla_{l} \nabla^{r} \xi^{s} + \nabla_{l} \xi^{s} \nabla^{\tau} \xi^{l}) K_{\tau s} dV_{g} \\ &\int_{\mathcal{M}} \xi^{j} \xi^{l} \nabla_{\tau} \nabla^{r} K_{jl} dV_{g} = 2 \int_{\mathcal{M}} \nabla_{\tau} \xi^{j} \nabla^{\tau} \xi^{l} K_{jl} dV_{g} \\ &\int_{\mathcal{M}} \xi^{j} \xi^{l} \nabla_{l} \nabla_{j} K^{r}_{\tau} dV_{g} = 0 \end{split}$$

and hence

$$\begin{split} I_1 &= 2 \int_{\mathcal{M}} (\xi^l \nabla_l \nabla^r \xi^s + \nabla_l \xi^s \nabla^r \xi^l - \nabla_i \xi^s \nabla^i \xi^r) K_{rs} dV_g \\ &= -4 \int_{\mathcal{M}} K_r^r dV_g \\ &= -2 \int_{\mathcal{M}} |H|^2 dV_g \,. \end{split}$$

Now consider I_2

$$\begin{split} \int_{M} \xi^{j} \xi^{i} H^{rs} \nabla_{r} \nabla_{l} H_{sj} dV_{g} &= \int_{M} \left[\nabla_{l} \nabla_{r} \xi^{j} \xi^{l} H^{rs} H_{sj} + \nabla_{r} \xi^{j} \xi^{l} \nabla_{l} H^{rs} H_{sj} \right. \\ &+ \nabla_{l} \xi^{j} \nabla_{r} \xi^{l} H^{rs} H_{sj} - \xi^{j} \xi^{l} \nabla_{r} H^{rs} \nabla_{l} H_{sj} \right] dV_{g} \\ \int_{M} \xi^{j} \xi^{l} H^{rs} \nabla_{r} \nabla_{s} H_{jl} dV_{g} &= \int_{M} \left[2 \nabla_{r} \xi^{j} \nabla_{s} \xi^{l} H^{rs} H_{jl} - \xi^{j} \xi^{l} \nabla_{r} H^{rs} \nabla_{s} H_{jl} \right] dV_{g} \\ \int_{M} \xi^{j} \xi^{l} H^{rs} \nabla_{l} \nabla_{j} H_{rs} dV_{g} &= - \int_{M} |\nabla_{\xi} H|^{2} dV_{g} \\ \int_{M} \xi^{j} \xi^{l} \nabla_{r} H_{sj} \nabla^{r} H_{l}^{s} dV_{g} &= \int_{M} \nabla_{r} \xi^{j} \nabla^{r} \xi^{l} H_{sj} H_{l}^{s} dV_{g} \\ \int_{M} \xi^{j} \xi^{l} \nabla_{r} H_{sj} \nabla^{s} H_{l}^{r} dV_{g} &= \int_{M} \nabla_{r} \xi^{j} \nabla^{s} \xi^{l} H_{sj} H_{l}^{s} dV_{g} . \end{split}$$

Therefore

$$\begin{split} I_{2} = & \int_{\mathcal{M}} \left[-2 \nabla_{l} \nabla_{r} \xi^{j} \xi^{l} H^{rs} H_{sj} - 2 \nabla_{r} \xi^{j} \xi^{l} \nabla_{l} H^{rs} H_{sj} \right. \\ & -2 \nabla_{l} \xi^{j} \nabla_{r} \xi^{l} H^{rs} H_{sj} + 2 \nabla_{r} \xi^{j} \nabla_{s} \xi^{l} H^{rs} H_{jl} \\ & + \nabla_{r} \xi^{j} \nabla^{r} \xi^{l} H_{js} H^{s}_{l} - \nabla_{r} \xi^{j} \nabla^{s} \xi^{l} H_{sj} H^{r}_{l} \\ & - \frac{1}{2} |\nabla_{\xi} H|^{2} \right] dV_{g} \end{split}$$

but

$$\begin{split} &\int_{M} \xi^{i} \nabla_{i} \nabla_{r} \xi^{j} H^{rs} H_{sj} dV_{g} = 0 \\ &\int_{M} \nabla_{i} \xi^{j} \nabla_{r} \xi^{i} H^{rs} H_{sj} dV_{g} = \int_{M} (-|H|^{2} + |hH|^{2}) dV_{g} \\ &\int_{M} \nabla_{r} \xi^{j} \nabla_{s} \xi^{i} H^{rs} H_{jl} dV_{g} = \int_{M} (-|H|^{2} - tr(hH)^{2}) dV_{g} \\ &\int_{M} \nabla_{r} \xi^{j} \nabla^{r} \xi^{i} H_{sj} H_{l}^{s} dV_{g} = \int_{M} (|H|^{2} + |hH|^{2}) dV_{g} \\ &\int_{M} \nabla_{r} \xi^{j} \nabla^{s} \xi^{l} H_{sj} H_{l}^{r} dV_{g} = \int_{M} (|H|^{2} - tr(hH)^{2}) dV_{g} \end{split}$$

and hence

$$I_{2} = \int_{M} \left[2(\phi_{r}^{j} + \phi_{ri}h^{ij})\nabla_{\xi}H_{s}^{r}H_{j}^{s} - tr(hH)^{2} - |hH|^{2} - \frac{1}{2}|\nabla_{\xi}H|^{2} \right] dV_{g}.$$

Since $\phi_{ri}h^{ij}\nabla_{\xi}H^{r}_{s}H^{s}_{j}=0$, we have

474

SECOND VARIATION OF THE DIRICHLET ENERGY

$$\begin{aligned} \frac{d^{2}I}{dt^{2}}(0) &= I_{1} + I_{2} \\ &= \int_{M} \left[-2 |H|^{2} + 2\phi_{r}^{j} \nabla_{\xi} H_{s}^{r} H_{s}^{s} - \frac{1}{2} |\nabla_{\xi} H|^{2} \\ &- tr(hH)^{2} - |hH|^{2} \right] dV_{g} \\ &= \int_{M} \left[-\frac{1}{2} |2H - \phi \nabla_{\xi} H|^{2} - tr(hH)^{2} - |hH|^{2} \right] dV_{g} \end{aligned}$$

Now note that

$$|\mathcal{L}_{\xi}H_{j}^{i}|^{2} = |\nabla_{\xi}H - 2H\phi|^{2} + |Hh + hH|^{2}$$
$$= |\nabla_{\xi}H - 2H\phi|^{2} + 2tr(hH)^{2} + 2|hH|^{2}$$

therefore

$$\frac{d^{2}L}{dt^{2}}(0) = (-4)\frac{d^{2}I}{dt^{2}}(0) = 2\int_{M} |\mathcal{L}_{\xi}H_{j}^{i}|^{2}dV_{g} \ge 0.$$

We show in the next proposition that $|\tau(t)|^2$ is constant along any geodesic $g(t)=ge^{Ht}$ with $\mathcal{L}_{\xi}H_j^i=0$, hence, L(g) is constant along all such geodesics. $\mathcal{M}(\eta)$ is geodesically complete [4], therefore L(g) has minimum at each critical metric. Q. E. D.

PROPOSITION. $\tau_j^i(t) = \tau_j^i(0)$ along any geodesic $g(t) = ge^{Ht}$ with $\mathcal{L}_{\xi}H_j^i = 0$. In particular, $|\tau(t)|^2$ is constant along such geodesics.

Proof. Let $D_{jk}^{(n)i} = \overline{V}_j(H^n)_k^i + \overline{V}_k(H^n)_j^i - \overline{V}^i(H^n)_{jk}$. If $\mathcal{L}_{\xi}H_j^i = 0$, we have $\overline{V}_{\xi}H = 2H\phi$ and hH = -Hh, and hence

$$D_{jk}^{(n)}{}^{i}\xi^{k} = \nabla_{\xi}(H^{n})_{j}^{i} + (H^{n})_{k}^{i}\phi_{j}^{i} + \phi_{k}^{i}(H^{n})_{j}^{k} - (H^{n})_{r}^{i}h_{k}^{r}\phi_{j}^{k} - \phi_{r}^{i}h_{k}^{r}(H^{n})_{j}^{k}$$
$$= 2(H^{n})_{r}^{i}\phi_{j}^{r}$$

for any *n*. Thus along ge^{Ht} with $\mathcal{L}_{\xi}H_{j}^{i}=0$,

$$\begin{split} \overline{V}_{j}^{(t)}\xi^{i} &= \overline{V}_{j}\xi^{i} + \frac{t}{2}D_{jk}{}^{i}\xi^{k} + \frac{t^{2}}{2}\Big(\frac{1}{2}D_{jk}^{(2)i}\xi^{k} - H_{r}^{i}D_{jk}{}^{i}\xi^{k}\Big) + \cdots \\ &+ \frac{t^{n}}{2}\Big[\frac{1}{n!}D_{jk}^{(n)i} + \frac{1}{(n-1)!}(-1)H_{r}^{i}D_{jk}^{(n-1)r} + \frac{1}{(n-2)!2!}(H^{2})_{r}^{i}D_{jk}^{(n-2)r} + \cdots \\ &+ \frac{1}{(n-l)!l!}(-1)^{l}(H^{l})_{r}^{i}D_{jk}^{(n-l)r} + \cdots + \frac{1}{(n-1)!}(-1)^{n-1}(H^{n-1})_{r}^{i}D_{jk}{}^{r}\Big]\xi^{k} \\ &+ \cdots \end{split}$$

and therefore

$$-\phi_{j}^{i}(t) + \frac{1}{2}\tau_{j}^{i}(t) = -\phi_{j}^{i} + \frac{1}{2}\tau_{j}^{i} - t\phi_{r}^{i}H_{j}^{r} - \cdots - \frac{t^{n}}{n!}\phi_{r}^{i}(H^{n})_{j}^{r} - \cdots .$$

Note that $\phi(t) = \phi e^{Ht}$; therefore we have

 $\tau_j^i(t) = \tau_j^i(0)$

along ge^{Ht} with $\mathcal{L}_{\xi}H_{j}^{i}=0$.

Example 1. Any K-contact manifold, since $\tau = 0$, L(g) has minimum trivially.

Q. E. D.

Example 2. The tangent sphere bundle of a compact Riemannian manifold of constant curvature (-1), i.e. $T_1M(-1)$ (see [3]). In this case the standard associated metric is a critical point of L(g), but τ is not 0. In fact, non-trivial examples must be irregular (see [2]). Theorem 2 says that L(g) has local minimum at the standard metric. It seems that it is also a global minimum, or in other words, one can not deform the metric to have $\tau=0$.

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MATHEMATICS SOUTHERN TECH. MARIETTA, GA 30060 U.S.A.

476