# Global hypoelliptic estimates for Landau-type operators with external potential 

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#### Abstract

In this paper we study a Landau-type operator with an external force. It is a linear model of the Landau equation near Maxwellian distributions. Making use of multiplier method, we get the global hypoelliptic estimate under suitable assumptions on the external potential.


## 1. Introduction and main results

In this article we are interested in the study of the regularity of solutions of some kinetic equations. In the linear or linearized equations, the corresponding collision operator may behave in some cases like a Laplacian - or at least a fractional power of a Laplacian - and we may hope for some improved smoothness at positive time. This type of question concerns Fokker-Planck equations, Landau equations, or Boltzmann equations without angular cut-off.

In the linear homogeneous case these equations have then a parabolic behavior, and the study of the local smoothing properties in the velocity variable is rather direct. In the nonhomogeneous case, the regularization in space variable is not so easy, but occurs anyway thanks to the so-called hypoelliptic structure of the equation. This type of behavior is a subject of intensive recent research in kinetic theory, coming back to the first results of Hörmander [13] concerning the Kolmogorov equation, and it is also in the core of averaging lemmas (see e.g., [2]). In this article we are interested in global estimates of the following Landau-type operator:

$$
\begin{align*}
P= & i\left(y \cdot D_{x}-\partial_{x} V(x) \cdot D_{y}\right)+D_{y} \cdot \nu(y) D_{y} \\
& +\left(y \wedge D_{y}\right) \cdot \mu(y)\left(y \wedge D_{y}\right)+F(y), \tag{1}
\end{align*}
$$

where $D_{x}=-i \partial_{x}, D_{y}=-i \partial_{y}$ and $x \in \mathbb{R}^{3}$ is the space variable and $y \in \mathbb{R}^{3}$ is the velocity variable, and $X \cdot Y$ stands for the standard dot product on $\mathbb{R}^{3}$. The real-valued function $V(x)$ of space variable $x$ denotes the potential of the

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macroscopic external force, and the functions $\nu(y), \mu(y)$, and $F(y)$ of the variable $y$ in the diffusion are smooth and real-valued with the properties subsequently listed below.
(i) There exists a constant $c>0$ such that
(2) $\quad \forall y \in \mathbb{R}^{3}, \quad \nu(y) \geq c\langle y\rangle^{\gamma}, \quad \mu(y) \geq c\langle y\rangle^{\gamma}, \quad$ and $\quad F(y) \geq c\langle y\rangle^{2+\gamma}$,
with $\gamma \in[0,1]$ and $\langle y\rangle=\left(1+|y|^{2}\right)^{1 / 2}$.
(ii) For any $\alpha \in \mathbb{Z}_{+}^{3}$, there exists a constant $C_{\alpha}$ such that

$$
\begin{align*}
\forall y \in \mathbb{R}^{3}, \quad & \left|\partial^{\alpha} \nu(y)\right|+\left|\partial^{\alpha} \mu(y)\right| \leq C_{\alpha}\langle y\rangle^{\gamma-|\alpha|}, \quad \text { and } \\
& \left|\partial^{\alpha} F(y)\right| \leq C_{\alpha}\langle y\rangle^{2+\gamma-|\alpha|} . \tag{3}
\end{align*}
$$

It is sometimes convenient to rewrite the operator as the form

$$
P=i\left(y \cdot D_{x}-\partial_{x} V(x) \cdot D_{y}\right)+\left(B(y) D_{y}\right)^{*} \cdot B(y) D_{y}+F(y),
$$

where the matrix $B(y)$ is given by

$$
B(y)=\left(B_{j k}(y)\right)_{1 \leq j, k \leq 3}=\left(\begin{array}{ccc}
\sqrt{\nu(y)} & -y_{3} \sqrt{\mu(y)} & y_{2} \sqrt{\mu(y)}  \tag{4}\\
-y_{3} \sqrt{\mu(y)} & \sqrt{\nu(y)} & -y_{1} \sqrt{\mu(y)} \\
-y_{2} \sqrt{\mu(y)} & y_{1} \sqrt{\mu(y)} & \sqrt{\nu(y)}
\end{array}\right)
$$

and $\left(B(y) D_{y}\right)^{*}=D_{y} B(y)^{T}$, with $B^{T}$ the transpose of $B$, is the formal adjoint of $B(y) D_{y}$. By (2) and (3) one has, for any $y, \eta \in \mathbb{R}^{3}$ and any $\alpha \in \mathbb{Z}_{+}^{3}$,

$$
\begin{equation*}
\left|\partial^{\alpha} B_{j k}(y)\right| \leq C_{\alpha}\langle y\rangle^{1-|\alpha|+\gamma / 2} \tag{5}
\end{equation*}
$$

and

$$
\begin{align*}
|B(y) \eta|^{2} & =\nu(y)|\eta|^{2}+\mu(y)|y \wedge \eta|^{2}  \tag{6}\\
& \geq c|y|^{\gamma}\left(|\eta|^{2}+|y \wedge \eta|^{2}\right) .
\end{align*}
$$

As a result, observing that $i\left(y \cdot D_{x}-\partial_{x} V(x) \cdot D_{y}\right)$ is skew-adjoint, we have

$$
\begin{align*}
& \left\|\langle y\rangle^{1+\gamma / 2} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2}\left(y \wedge D_{y}\right) u\right\|_{L^{2}}^{2} \\
& \leq c^{-1}\left\|B(y) D_{y} u\right\|_{L^{2}}^{2}+(F u, u)_{L^{2}} \leq c^{-1} \operatorname{Re}(P u, u)_{L^{2}} \tag{7}
\end{align*}
$$

where $(\cdot, \cdot)_{L^{2}}$ and $\|\cdot\|_{L^{2}}$ stand for the inner product and norm in $L^{2}\left(\mathbb{R}_{x, y}^{6}\right)$.
Denoting by $(\xi, \eta)$ the dual variables of $(x, y)$, we notice that the diffusion only occurs in the variables $(y, \eta)$ but not in the other directions, and that the cross-product term $y \wedge D_{y}$ improves this diffusion in specific directions of the phase space where the variables $y$ and $\eta$ are orthogonal. In this work, we aim to prove that linear Landau-type operators are actually hypoelliptic despite this lack of diffusion in the spatial derivative $D_{x}$. More specifically, we shall be concerned with proving global hypoelliptic estimates with weights in both spatial and velocity derivatives whose structure is exactly related to the anisotropy of the diffusion. Our main results can be stated as follows.

THEOREM 1.1
Let $V \in C^{2}\left(\mathbb{R}^{3} ; \mathbb{R}\right)$ satisfy that

$$
\begin{equation*}
\forall|\alpha|=2, \exists C_{\alpha}>0 \text { such that } \forall x \in \mathbb{R}^{3}, \quad\left|\partial_{x}^{\alpha} V(x)\right| \leq C_{\alpha}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} \tag{8}
\end{equation*}
$$

Then there exists a constant $C$ such that for any $u \in C_{0}^{\infty}\left(\mathbb{R}^{6}\right)$ one has

$$
\begin{align*}
& \left\|\langle y\rangle^{\gamma / 6}\left|\partial_{x} V(x)\right|^{2 / 3} u\right\|_{L^{2}}+\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}} \\
& \quad+\left\|\left|D_{x}\right|^{2 / 3} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}}  \tag{9}\\
& \quad \leq \\
& \quad C\left(\|P u\|_{L^{2}}+\|u\|_{L^{2}}\right)
\end{align*}
$$

Moreover if $V$ satisfies the condition that

$$
\begin{align*}
C_{0}^{-1}\langle x\rangle^{M} & \leq\left\langle\partial_{x} V(x)\right\rangle \leq C_{0}\langle x\rangle^{M}, \quad \text { and } \\
\forall|\alpha| \geq 2, \quad\left|\partial_{x}^{\alpha} V(x)\right| & \left.\leq C_{\alpha}<\partial_{x} V(x)\right\rangle^{1 / 3}, \tag{10}
\end{align*}
$$

with $M, C_{0}$ two positive numbers and $C_{\alpha}$ a constant depending only on $\alpha$, we have additionally

$$
\begin{align*}
& \left\|\left(\left\langle\partial_{x} V \wedge \eta+y \wedge \xi\right\rangle^{2 / 3}\right)^{w} u\right\|_{L^{2}}+\left\|\left(\left\langle\partial_{x} V \wedge \xi\right\rangle^{2 / 5}\right)^{w} u\right\|_{L^{2}}  \tag{11}\\
& \quad \leq C\left(\|P u\|_{L^{2}}+\|u\|_{L^{2}}\right)
\end{align*}
$$

where $p^{w}$ stands for the Weyl quantization of the symbol $p$.

There is a large class of potentials satisfying (8) and (10), for example the quadratic functions of the form $V\left(x_{1}, x_{2}, x_{3}\right)=\sum_{1 \leq j \leq 3} a_{j} x_{j}^{2}$ with $a_{j}$ 's real coefficients. More generally the potential $V$ appearing in this work is related to an external force $F=-\nabla V(x)$ acting on the system of particles whose distribution we want to study. We refer to, for example, the introduction of [11] for a short presentation of the linearized Landau model (there without external force, see also [8] or [23]). We mention here following [11] that for operator $P$ defined in (1), the Cauchy problem

$$
\partial_{t} u+P u=0,\left.\quad u\right|_{t=0}=u_{0}
$$

is a linearization of the full inhomogeneous nonlinear Landau equation

$$
\begin{equation*}
\partial_{t} f+y \cdot \nabla_{x} f-\nabla_{x} V(x) \cdot \nabla_{y} f=Q_{L}(f, f),\left.\quad f\right|_{t=0}=f_{0} \tag{12}
\end{equation*}
$$

where the unknown $f(t, x, y)$ is the density of probability of the presence at time $t$ in $(x, y)$ of the system of particles, and $Q_{L}$ is the Landau collision kernel (see $[11,(8)])$. The linearization procedure is $f=\mathcal{M}+\mathcal{M}^{1 / 2} u$, where $\mathcal{M}(x, y)=$ $e^{-\left(|y|^{2} / 2+V(x)\right)}$ is the so-called Maxwellian (which is a stationary solution of (12)). Here we are interested in the control of the regularity of $u$ by that of $P u$.

Estimates of the type given in Theorem 1.1 can be analyzed through different view points. At first they give at least local regularity estimates in the velocity direction, according to the term $\left|D_{y}\right|^{2}$ appearing in (9). Now one of the goals of this article is to give global estimates to identify the good functional spaces associated to the problems: here we are able to prove that in the elliptic direction we have an estimate of type

$$
\begin{aligned}
& \left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}} \\
& \quad \leq C\left\{\|P u\|_{L^{2}}+\|u\|_{L^{2}}\right\} .
\end{aligned}
$$

A priori it does not seem to be optimal, and indeed when $V=0$ a similar inequality was proven in [11] with an exponent $\gamma$ there instead of $5 \gamma / 6$ and $\gamma / 2$ here, but the study with $V \neq 0$ is harder. Similar to [11], we recover here in (9) some intrinsic global anisotropy via a term of type $y \wedge D_{y}$ already appearing in the definition of the original operator.

The second main feature of this result is to reflect the regularizing effect in the space variable $x$, thanks to the hypoelliptic structure, which leads to terms involving, for example, $\left|D_{x}\right|^{2 / 3}$. Recall that the exponent $2 / 3$ here is optimal, according to local estimates coming back to [13] (see also [1]). In this direction (i.e., concerning local optimal subelliptic estimates for kinetic models), we mention also the works [20], [21], and [18] on the Boltzmann operator without cut-off and the series of works on Gevrey regularity (see [5], [4], [3]).

Now similar to the case of elliptic directions, it may be interesting to get global weighted estimates in the space direction. In [10] and [9] the authors studied the Fokker-Planck case, in particular with a potential, following original ideas from [7] (see also [6]). In this direction the work [11] also gave a first subelliptic global (optimal) estimate, concerning the Landau-type operator in the case when there is no potential; the main feature of that work was to show that subellipticity in space direction occurred with anisotropic weights of type $\langle y\rangle^{\gamma} y \wedge D_{x}$. In the present article we recover the same type of behavior, with additional terms-also involving wedges-linked with the potential $V$.

To prove the result, we use the same multiplier method as in [11], which allows us to obtain a global hypoellipticity result with optimal loss of $4 / 3$ derivatives. This method was first introduced in [12] for the Fokker-Planck equation. It was then extended to more general doubly characteristic quadratic differential operators by Pravda-Starov [22] to get optimal hypoelliptic estimates. The present work is a natural continuation of [11], and as was done there, we will make strong use of pseudodifferential and Wick calculus, following the presentation by Lerner [17].

The plan of this article is the following. In the second section we introduce some notations and facts about the symbolic calculus. In the third section we prove some weighted estimates in space and velocity, without derivatives, needed later to complete the proof. In Section 4, we essentially work on the velocity side after a change of operator through a partial Wick quantization in $(x, \xi)$. This allows us to treat the space variable (and its dual) as parameters and to get optimal velocity estimates with parameters. In the last two sections we go back to the original operator and complete the proof.

## 2. Notations and some basic facts on symbolic calculus

We first list some notations used throughout the paper. Denote by $(\cdot, \cdot)_{L^{2}}$ and
$\|\cdot\|$ the inner product and the norm in $L^{2}\left(\mathbb{R}^{n}\right)$, respectively. For a vector-valued function $U=\left(u_{1}, \ldots, u_{n}\right)$ the norm $\|U\|_{L^{2}}$ stands for $\left(\sum_{j}\left\|u_{j}\right\|_{L^{2}}^{2}\right)^{1 / 2}$.

To simplify the notation, by $A \lesssim B$ we mean there exists a positive constant $C$ such that $A \leq C B$, and similarly for $A \gtrsim B$. While the notation $A \approx B$ means both $A \lesssim B$ and $B \lesssim A$ hold.

Now we introduce some notation of phase space analysis and recall some basic properties of symbolic calculus (see [14], [17] for detailed discussions). Throughout the paper let $g$ be the admissible metric $|d z|^{2}+|d \zeta|^{2}$, and let $m$ be an admissible weight for $g$ (see, e.g., [14], [17] for the definitions of admissible metric and weight). Given a symbol $p(z, \zeta)$, we say $p \in S(m, g)$ if

$$
\forall \alpha, \beta \in \mathbb{Z}_{+}^{n}, \forall(z, \zeta) \in \mathbb{R}^{2 n}, \quad\left|\partial_{z}^{\alpha} \partial_{\zeta}^{\beta} p(z, \zeta)\right| \leq C_{\alpha, \beta} m(z, \zeta),
$$

with $C_{\alpha, \beta}$ a constant depending only on $\alpha, \beta$. For such a symbol $p$ we may define its Weyl quantization $p^{w}$ by

$$
\forall u \in \mathcal{S}\left(\mathbb{R}^{n}\right), \quad p^{w} u(z)=\int e^{2 i \pi(z-v) \cdot \zeta} p\left(\frac{z+v}{2}, \zeta\right) u(v) d v d \zeta .
$$

The $L^{2}$-continuity theorem in the class $S(1, g)$, which will be used frequently, says that if $p \in S(1, g)$, then

$$
\forall u \in L^{2}, \quad\left\|p^{w} u\right\|_{L^{2}} \lesssim\|u\|_{L^{2}} .
$$

We shall denote by $\operatorname{Op}(S(m, g))$ the set of operators whose symbols are in the class $S(m, g)$. Finally let us recall some basic properties of the Wick quantization and refer the reader to the works of Lerner [15]-[17] for thorough and extensive presentations of this quantization and some of its applications. Using the notation $Z=(z, \zeta) \in \mathbb{R}^{2 n}$, the wave-packets transform of a function $u \in \mathcal{S}\left(\mathbb{R}^{n}\right)$ is defined by

$$
W u(Z)=\left(u, \varphi_{Z}\right)_{L^{2}\left(\mathbb{R}^{n}\right)}=2^{n / 4} \int_{\mathbb{R}^{n}} u(v) e^{-\pi|v-z|^{2}} e^{2 i \pi(v-z / 2) \cdot \zeta} d v,
$$

with

$$
\varphi_{Z}(v)=2^{n / 4} e^{-\pi|v-z|^{2}} e^{2 i \pi(v-z / 2) \cdot \eta}, \quad v \in \mathbb{R}^{n} .
$$

Then one can verify that $W$ is an isometric mapping from $L^{2}\left(\mathbb{R}^{n}\right)$ to $L^{2}\left(\mathbb{R}^{2 n}\right)$ :

$$
\begin{equation*}
\|W u\|_{L^{2}\left(\mathbb{R}^{2 n}\right)}=\|u\|_{L^{2}\left(\mathbb{R}^{n}\right)} . \tag{13}
\end{equation*}
$$

Moreover the operator

$$
\pi_{\mathcal{H}}=W W^{*},
$$

with $W^{*}$ the adjoint of $W$, is an orthogonal projection on a closed space in $L^{2}$, whose kernel is given by

$$
\begin{equation*}
K(Z, \tilde{Z})=e^{-\pi / 2\left(|z-\tilde{z}|^{2}+|\zeta-\tilde{\zeta}|^{2}\right)} e^{i \pi(z-\tilde{z}) \cdot(\zeta+\tilde{\zeta})}, \quad Z=(z, \zeta), \tilde{Z}=(\tilde{z}, \tilde{\zeta}) \tag{14}
\end{equation*}
$$

We define the Wick quantization of any $L^{\infty}$-symbol $p$ as

$$
p^{\text {Wick }}=W^{*} p W \text {. }
$$

The main property of the Wick quantization is its positivity; that is,

$$
\begin{equation*}
p(Z) \geq 0 \quad \text { for all } Z \in \mathbb{R}^{2 n} \text { implies } p^{\text {Wick }} \geq 0 \tag{15}
\end{equation*}
$$

According to [17, Proposition 2.4.3], the Wick and Weyl quantizations of a symbol $p$ are linked by the following identities

$$
\begin{equation*}
p^{\text {Wick }}=p^{w}+r^{w} \tag{16}
\end{equation*}
$$

with

$$
r(Z)=\int_{0}^{1} \int_{\mathbb{R}^{2 n}}(1-\theta) p^{\prime \prime}(Z+\theta Y) Y^{2} e^{-2 \pi|Y|^{2}} 2^{n} d Y d \theta
$$

We also recall the following composition formula obtained in the proof of [15, Proposition 3.4]

$$
p^{\text {Wick }} q^{\text {Wick }}=\left[p q-\frac{1}{4 \pi} p^{\prime} \cdot q^{\prime}+\frac{1}{4 i \pi}\{p, q\}\right]^{\text {Wick }}+T,
$$

with $T$ a bounded operator in $L^{2}\left(\mathbb{R}^{2 n}\right)$, when $p \in L^{\infty}\left(\mathbb{R}^{2 n}\right)$ and $q$ is a smooth symbol whose derivatives of order at least 2 are bounded on $\mathbb{R}^{2 n}$. The notation $\{p, q\}$ denotes the Poisson bracket defined by

$$
\begin{equation*}
\{p, q\}=\frac{\partial p}{\partial \zeta} \cdot \frac{\partial q}{\partial z}-\frac{\partial p}{\partial z} \cdot \frac{\partial q}{\partial \zeta} \tag{17}
\end{equation*}
$$

## 3. First part of the proof of Theorem 1.1: Weighted estimates

In this section we are mainly concerned with the estimate in weighted $L^{2}$-norms, that is, Proposition 3.1.

PROPOSITION 3.1
Let $V(x) \in C^{2}\left(\mathbb{R}^{3} ; \mathbb{R}\right)$ satisfy the condition (8). Then

$$
\begin{gather*}
\forall u \in C_{0}^{\infty}\left(\mathbb{R}^{6}\right), \quad\left\|\langle y\rangle^{\gamma / 6}\left|\partial_{x} V(x)\right|^{2 / 3} u\right\|_{L^{2}}+\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}  \tag{18}\\
\lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}} .
\end{gather*}
$$

To prove this proposition, we begin with the following lemma.

LEMMA 3.2 ([11, LEMMA 3.7])
Let $p \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ and $B(y)$ be the matrix given in (4). We have

$$
\begin{gather*}
\forall u \in C_{0}^{\infty}\left(\mathbb{R}^{6}\right), \quad\left|\left(F(y), p^{w} u\right)_{L^{2}}\right|+\left|\left(\left(B(y) D_{y}\right)^{*} B(y) D_{y} u, p^{w} u\right)_{L^{2}}\right| \\
\lesssim\left|(P u, u)_{L^{2}}\right| . \tag{19}
\end{gather*}
$$

LEMMA 3.3
For all $u \in C_{0}^{\infty}\left(\mathbb{R}^{3}\right)$ we have

$$
\begin{align*}
& \left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}+\left\|\langle y\rangle^{1+5 \gamma / 6} D_{y} u\right\|_{L^{2}}+\left\|\langle y\rangle^{1+5 \gamma / 6}\left(y \wedge D_{y}\right) u\right\|_{L^{2}}  \tag{20}\\
& \quad \lesssim\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V\right\rangle^{2 / 3} u\right\|_{L^{2}}+\|P u\|_{L^{2}} .
\end{align*}
$$

## Proof

In the proof we let $u \in C_{0}^{\infty}\left(\mathbb{R}^{2 n}\right)$. The conclusion will follow if one can prove

$$
\begin{align*}
& \left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{1+\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}^{2} \\
& \quad \lesssim\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}, \tag{21}
\end{align*}
$$

since by (6), one has

$$
\langle y\rangle^{1+\gamma / 3}\left|B(y) D_{y} u\right| \geq\langle y\rangle^{1+5 \gamma / 6}\left|D_{y} u\right|+\langle y\rangle^{1+5 \gamma / 6}\left|\left(y \wedge D_{y}\right) u\right| .
$$

As a preliminary step, let us first show that for any $\varepsilon>0$ there exists a constant $C_{\varepsilon}>0$ such that

$$
\begin{align*}
& \left|\left(P\langle y\rangle^{1+\gamma / 3} u,\langle y\rangle^{1+\gamma / 3} u\right)_{L^{2}}\right| \\
& \quad \lesssim \varepsilon\left(\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{1+\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}^{2}\right)  \tag{22}\\
& \quad+C_{\varepsilon}\left\{\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right\} .
\end{align*}
$$

In fact, the estimate

$$
\left\langle\partial_{x} V(x)\right\rangle\langle y\rangle^{1+2 \gamma / 3} \leq \varepsilon\langle y\rangle^{4+5 \gamma / 3}+C_{\varepsilon}\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{4 / 3}
$$

yields

$$
\begin{align*}
\left(\langle y\rangle^{1+2 \gamma / 3}\left\langle\partial_{x} V(x)\right\rangle u, u\right)_{L^{2}} \leq & \varepsilon\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2} \\
& +C_{\varepsilon}\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2} . \tag{23}
\end{align*}
$$

Consequently, using (3) we compute

$$
\left|\left[P,\langle y\rangle^{1+\gamma / 3}\right] u\right| \lesssim\left|\partial_{x} V(x)\right|\langle y\rangle^{\gamma / 3}|u|+\langle y\rangle^{1+5 \gamma / 6}\left|B(y) D_{y} u\right|,
$$

and thus

$$
\begin{aligned}
& \left|\left(\left[P,\langle y\rangle^{1+\gamma / 3}\right] u,\langle y\rangle^{1+\gamma / 3} u\right)_{L^{2}}\right| \\
& \quad \lesssim\left(\left|\partial_{x} V(x)\right|\langle y\rangle^{1+2 \gamma / 3} u, u\right)_{L^{2}}+\left(\left\langle y \gamma^{\gamma / 3}\right| B(y) D_{y} u\left|,\langle y\rangle^{2+5 \gamma / 6}\right| u \mid\right)_{L^{2}} \\
& \quad \lesssim \varepsilon\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\langle y\rangle^{\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}^{2} \\
& \quad \lesssim \varepsilon\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+\varepsilon\left\|\langle y\rangle^{1+\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}^{2} \\
& \quad+C_{\varepsilon}\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}+C_{\varepsilon, \gamma}\left\|\langle y\rangle^{-1} B(y) D_{y} u\right\|_{L^{2}}^{2} \\
& \quad \lesssim \varepsilon\left(\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{1+\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}^{2}\right) \\
& \quad+C_{\varepsilon}\left(\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right),
\end{aligned}
$$

where the second inequality follows from (23), the third inequality holds because $\forall \tilde{\varepsilon}>0, \quad\left\|\langle y\rangle^{\gamma / 3} B(y) D_{y} u\right\|_{L^{2}} \leq \tilde{\varepsilon}\left\|\langle y\rangle^{1+\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}+C_{\tilde{\varepsilon}}\left\|\langle y\rangle^{-1} B(y) D_{y} u\right\|_{L^{2}}$, and the last inequality follows from (7) since by (5),

$$
\left\|\langle y\rangle^{-1} B(y) D_{y} u\right\|_{L^{2}} \leq\left\|\langle y\rangle^{\gamma / 2} D_{y} u\right\|_{L^{2}} .
$$

As a result, observing

$$
\begin{aligned}
& \left|\left(P\langle y\rangle^{1+\gamma / 3} u,\langle y\rangle^{1+\gamma / 3} u\right)_{L^{2}}\right| \\
& \quad \leq\left|\left(P u,\langle y\rangle^{2+2 \gamma / 3} u\right)_{L^{2}}\right|+\left|\left(\left[P,\langle y\rangle^{1+\gamma / 3}\right] u,\langle y\rangle^{1+\gamma / 3} u\right)_{L^{2}}\right|
\end{aligned}
$$

and

$$
\left|\left(P u,\langle y\rangle^{2+2 \gamma / 3} u\right)_{L^{2}}\right| \leq \varepsilon\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\|P u\|_{L^{2}}^{2}
$$

due to the fact that $2 \gamma / 3 \leq 5 \gamma / 6$ for $\gamma \geq 0$, we obtain the inequality (22).
Now we prove (21). Let us first write

$$
\begin{aligned}
& \left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{1+\gamma / 3} B(y) D_{y} u\right\|_{L^{2}}^{2} \\
& \quad \lesssim\left\|\langle y\rangle^{1+\gamma / 2}\langle y\rangle^{1+\gamma / 3} u\right\|_{L^{2}}^{2}+\left\|B(y) D_{y}\langle y\rangle^{1+\gamma / 3} u\right\|_{L^{2}}^{2} \\
& \quad+\left\|B(y)\left[D_{y},\langle y\rangle^{1+\gamma / 3}\right] u\right\|_{L^{2}}^{2} \\
& \quad \lesssim\left|\left(P\langle y\rangle^{1+\gamma / 3} u,\langle y\rangle^{1+\gamma / 3} u\right)_{L^{2}}\right|+\left\|B(y)\left[D_{y},\langle y\rangle^{1+\gamma / 3}\right] u\right\|_{L^{2}}^{2},
\end{aligned}
$$

the last inequality using (7). For the last term, we have

$$
\left\|B(y)\left[D_{y},\langle y\rangle^{1+\gamma / 3}\right] u\right\|_{L^{2}}^{2} \lesssim\left\|\langle y\rangle^{1+5 \gamma / 6} u\right\|_{L^{2}}^{2} \leq \varepsilon\left\|\langle y\rangle^{2+5 \gamma / 6} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\|u\|_{L^{2}}^{2} .
$$

Then the desired estimate (21) follows from the above inequalities and (22), completing the proof of Lemma 3.3.

Proof of Proposition 3.1
Let $\rho \in C^{1}\left(\mathbb{R}^{2 n}\right)$ be a real-valued function given by

$$
\rho=\rho(x, y)=\frac{2\langle y\rangle^{\gamma / 3} \partial_{x} V(x) \cdot y}{\left\langle\partial_{x} V(x)\right\rangle^{4 / 3}} \phi(x, y),
$$

with

$$
\phi=\chi\left(\frac{\langle y\rangle^{2+2 \gamma / 3}}{\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}}\right),
$$

where $\chi \in C_{0}^{\infty}(\mathbb{R} ;[0,1])$ such that $\chi=1$ in $[-1,1]$ and supp $\chi \subset[-2,2]$. We have, using the notation $Q=y \cdot D_{x}-\partial_{x} V(x) \cdot D_{y}$,
$\operatorname{Re}(P u, \rho u)_{L^{2}}=\operatorname{Re}(i Q u, \rho u)_{L^{2}}+\left(\left(B(y) D_{y}\right)^{*} \cdot B(y) D_{y} u, \rho u\right)_{L^{2}}+(F(y) u, \rho u)_{L^{2}}$, which along with (19) yields

$$
\operatorname{Re}(i Q u, \rho u)_{L^{2}} \lesssim\left|(P u, u)_{L^{2}}\right|+\left|(P u, \rho u)_{L^{2}}\right| .
$$

Next we want to give a lower bound for the term on the left side. Direct computation shows that

$$
\begin{equation*}
\operatorname{Re}(i Q u, \rho u)_{L^{2}}=\frac{i}{2}([\rho, Q] u, u)_{L^{2}}=\sum_{j=1}^{3}\left(\mathcal{A}_{j} u, u\right)_{L^{2}}, \tag{24}
\end{equation*}
$$

with $\mathcal{A}_{j}$ given by

$$
\begin{aligned}
& \mathcal{A}_{1}=\frac{\langle y\rangle^{\gamma / 3}\left|\partial_{x} V(x)\right|^{2}}{\left\langle\partial_{x} V(x)\right\rangle^{4 / 3}} \phi, \\
& \mathcal{A}_{2}=\left\langle\partial_{x} V(x)\right\rangle^{-4 / 3}\left(\partial_{x} V(x) \cdot y\right) \partial_{x} V(x) \cdot \partial_{y}\left[\langle y\rangle^{\gamma / 3} \phi(x, y)\right], \\
& \mathcal{A}_{3}=-\langle y\rangle^{\gamma / 3} y \cdot \partial_{x}\left(\left\langle\partial_{x} V(x)\right\rangle^{-4 / 3}\left(\partial_{x} V(x) \cdot y \phi(x, y)\right)\right) .
\end{aligned}
$$

We will proceed to treat the above three terms. First one has

$$
\begin{aligned}
\mathcal{A}_{1} & =\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} \phi(x, y)-\frac{\langle y\rangle^{\gamma / 3}}{\left\langle\partial_{x} V(x)\right\rangle^{4 / 3}} \phi(x, y) \\
& =\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}-\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}(1-\phi(x, y))-\frac{\langle y\rangle^{\gamma / 3}}{\left\langle\partial_{x} V(x)\right\rangle^{4 / 3}} \phi(x, y),
\end{aligned}
$$

from which it follows that

$$
\begin{equation*}
\left(\mathcal{A}_{1} u, u\right)_{L^{2}} \geq\left(\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u, u\right)_{L^{2}}-\left\|\langle y\rangle^{1+\gamma / 2} u\right\|_{L^{2}}^{2} . \tag{25}
\end{equation*}
$$

Here we used the facts that

$$
\frac{\langle y\rangle^{\gamma / 3}}{\left\langle\partial_{x} V(x)\right\rangle^{4 / 3}} \leq 1
$$

on the support of $\phi$, and $\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} \leq\langle y\rangle^{2+2 \gamma / 3}$ on the support of $1-\phi$. As for the term $\mathcal{A}_{2}$ we make use of the relation

$$
\forall \sigma \in \mathbb{R}, \quad \partial_{x} V(x) \partial_{y}\left(\langle y\rangle^{\sigma}\right)=\sigma\langle y\rangle^{\sigma-2} \partial_{x} V(x) \cdot y,
$$

to compute

$$
\begin{aligned}
\mathcal{A}_{2} & =\left\langle\partial_{x} V(x)\right\rangle^{-4 / 3}\left|\partial_{x} V(x) \cdot y\right|^{2}\left[\frac{\gamma}{3}\langle y\rangle^{\gamma / 3-2} \phi+\frac{(2+\gamma)\langle y\rangle^{\gamma}}{\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}} \chi^{\prime}\left(\frac{\langle y\rangle^{2+2 \gamma / 3}}{\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}}\right)\right] \\
& \gtrsim-\left\langle\partial_{x} V(x)\right\rangle^{-4 / 3}\left|\partial_{x} V(x) \cdot y\right|^{2}\left\langle\partial_{x} V(x)\right\rangle^{-2 / 3}\langle y\rangle^{\gamma} \\
& \gtrsim-\langle y\rangle^{2+\gamma},
\end{aligned}
$$

the first inequality using the fact that $\gamma \geq 0$, and hence the term $\frac{\gamma}{3}\langle y\rangle^{\gamma / 3-2} \phi$ is nonnegative. As a result we conclude:

$$
\begin{equation*}
\left(\mathcal{A}_{2} u, u\right)_{L^{2}} \gtrsim-\left(\langle y\rangle^{2+\gamma} u, u\right)_{L^{2}} . \tag{26}
\end{equation*}
$$

For the term $\mathcal{A}_{3}$, using (8) gives

$$
\mathcal{A}_{3} \gtrsim-\langle y\rangle^{2+\gamma / 3} \gtrsim-\langle y\rangle^{2+\gamma},
$$

and thus

$$
\left(\mathcal{A}_{3} u, u\right)_{L^{2}} \gtrsim-\left(\langle y\rangle^{2+\gamma} u, u\right)_{L^{2}} .
$$

This along with (24), (25), and (26) shows that

$$
\begin{aligned}
\left(\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u, u\right)_{L^{2}} & \lesssim\left\|\langle y\rangle^{1+\gamma / 2} u\right\|_{L^{2}}^{2}+\left|(P u, u)_{L^{2}}\right|+\left|(P u, \rho u)_{L^{2}}\right| \\
& \lesssim\left|(P u, u)_{L^{2}}\right|+\left|(P u, \rho u)_{L^{2}}\right| .
\end{aligned}
$$

Now for any $u \in C_{0}^{\infty}\left(\mathbb{R}^{2 n}\right)$, we use the above estimate to the function $\left\langle\partial_{x} V(x)\right\rangle^{1 / 3} u$; this gives

$$
\begin{aligned}
& \left(\langle y\rangle^{\gamma / 3}\left\langle\partial_{x} V(x)\right\rangle^{4 / 3} u, u\right)_{L^{2}} \\
& \quad \lesssim\left\|\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3} P\left\langle\partial_{x} V(x)\right\rangle^{1 / 3} u\right\|_{L^{2}}\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}},
\end{aligned}
$$

which, together with the fact that $\gamma \geq 0$, implies

$$
\begin{aligned}
\left\|\langle y\rangle^{\gamma / 6}\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}} & \lesssim\left\|\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3} P\left\langle\partial_{x} V(x)\right\rangle^{1 / 3} u\right\|_{L^{2}} \\
& \lesssim\|P u\|_{L^{2}}+\left\|\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3}\left[P,\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}\right] u\right\|_{L^{2}} .
\end{aligned}
$$

Moreover in view of (8) we have

$$
\left\|\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3}\left[P,\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}\right] u\right\|_{L^{2}} \lesssim\|\langle y\rangle u\|_{L^{2}} \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}}
$$

Then the desired inequality (18) follows, completing the proof of Proposition 3.1.

## 4. Hypoelliptic estimates for the operator with parameters

In this section we always consider $X=(x, \xi) \in \mathbb{R}^{6}$ as parameters, and we study the operator acting on the velocity variable $y$ :

$$
\begin{equation*}
P_{X}=i Q_{X}+\left(B(y) D_{y}\right)^{*} \cdot B(y) D_{y}+F(y), \tag{27}
\end{equation*}
$$

where $Q_{X}=y \cdot \xi-\partial_{x} V(x) \cdot D_{y}$ and $B(y)$ is the matrix given in (4).

## NOTATIONS

Throughout this section, we will use $\|\cdot\|_{L^{2}}$ and $(\cdot, \cdot)_{L^{2}}$ to denote, respectively, the norm and inner product in the space $L^{2}\left(\mathbb{R}_{y}^{3}\right)$. Given a symbol $p$, we use $p^{\text {Wick }}$ and $p^{w}$ to denote the Wick and Weyl quantization of $p$ in the variables $(y, \eta)$.

The main result of this section is the following proposition.

## PROPOSITION 4.1

Let $\lambda$ be defined by

$$
\begin{align*}
\lambda= & \left(1+\left|\partial_{x} V \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}\right. \\
& \left.+|y|^{6}+|\eta|^{6}+\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{6 / 5}\right)^{1 / 2} . \tag{28}
\end{align*}
$$

Then the following estimate

$$
\begin{align*}
& \left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3}\right)\|u\|_{L^{2}} \\
& \quad \quad+\left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}  \tag{29}\\
& \quad \lesssim\left\|P_{X} u\right\|_{L^{2}}+\|u\|_{L^{2}}
\end{align*}
$$

holds for all $u \in \mathcal{S}\left(\mathbb{R}_{y}^{3}\right)$ uniformly with respect to $X$.

We will make use of the multiplier method introduced in [11] to show the above proposition through the following subsections.

### 4.1. Lemmas

Before the proof of Proposition 4.1, we list some lemmas.

## LEMMA 4.2

Let $\lambda$ be defined in (28). Then

$$
\begin{equation*}
\forall \sigma \in \mathbb{R}, \quad \lambda^{\sigma} \in S\left(\lambda^{\sigma},|d y|^{2}+|d \eta|^{2}\right) \tag{30}
\end{equation*}
$$

uniformly with respect to $X$. Moreover if $\sigma \leq 1$, then the inequality

$$
\begin{equation*}
\forall|\alpha|+|\beta| \geq 1, \quad\left|\partial_{y}^{\alpha} \partial_{\eta}^{\beta}\left(\lambda^{\sigma}\right)\right| \lesssim\left\langle\partial_{x} V(x)\right\rangle^{\sigma}+\langle\xi\rangle^{\sigma} \tag{31}
\end{equation*}
$$

holds uniformly with respect to $X$, and thus

$$
\begin{equation*}
\left(\lambda^{\sigma}\right)^{\text {Wick }}=\left(\lambda^{\sigma}\right)^{w}+\left(\left\langle\partial_{x} V(x)\right\rangle^{\sigma}+\langle\xi\rangle^{\sigma}\right) r^{w} \tag{32}
\end{equation*}
$$

with $r \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$.
Proof
By direct verification we see that for all $(y, \eta) \in \mathbb{R}^{6}$ and all $\alpha, \beta \in \mathbb{Z}_{+}^{3}$ one has

$$
\left|\partial_{y}^{\alpha} \partial_{\eta}^{\beta}\left(\lambda(y, \eta)^{2}\right)\right| \leq \lambda(y, \eta)^{2},
$$

which implies (30). Moreover note that

$$
\forall|\alpha|+|\beta| \geq 1, \quad\left|\partial_{y}^{\alpha} \partial_{\eta}^{\beta}\left(\lambda(y, \eta)^{2}\right)\right| \leq\left(\left\langle\partial_{x} V(x)\right\rangle+\langle\xi\rangle\right) \lambda(y, \eta),
$$

and thus

$$
\forall \sigma \in \mathbb{R}, \quad\left|\partial_{y}^{\alpha} \partial_{\eta}^{\beta}\left(\lambda(y, \eta)^{\sigma}\right)\right| \lesssim|\sigma| \lambda^{\sigma-1}\left(\left\langle\partial_{x} V(x)\right\rangle+\langle\xi\rangle\right) .
$$

Then we get (31) if $\sigma \leq 1$, and thus (32) in view of (16); we complete the proof of Lemma 4.2.

## LEMMA 4.3

Let $\lambda$ be given in (28). Then for all $u \in \mathcal{S}\left(\mathbb{R}^{3}\right)$ one has

$$
\begin{align*}
& \left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}} \\
& \quad \lesssim\left\|P_{X} u\right\|_{L^{2}}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}+\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}, \tag{33}
\end{align*}
$$

where $\Phi$ is defined by

$$
\begin{equation*}
\Phi=\Phi(X)=\left(1+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}\right)^{1 / 2} \tag{34}
\end{equation*}
$$

Proof
Similar to (7), we have, for any $u \in \mathcal{S}\left(\mathbb{R}_{y}^{3}\right)$,

$$
\begin{equation*}
\left\|\langle y\rangle^{1+\gamma / 2} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2}\left(y \wedge D_{y}\right) u\right\|_{L^{2}}^{2} \lesssim \operatorname{Re}\left(P_{X} u, u\right)_{L^{2}} . \tag{35}
\end{equation*}
$$

Using the above inequality for $D_{y_{j}} u$ gives

$$
\begin{aligned}
\sum_{j, k=1}^{n}\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} \cdot D_{y_{j}} u\right\|_{L^{2}}^{2} & \lesssim \sum_{j=1}^{n}\left|\left(P_{X} D_{y_{j}} u, D_{y_{j}} u\right)_{L^{2}}\right| \\
& \lesssim\left|\left(P_{X} u, D_{y} \cdot D_{y} u\right)_{L^{2}}\right|+\sum_{j=1}^{n}\left|\left(\left[P_{X}, D_{y_{j}}\right] u, D_{y_{j}} u\right)_{L^{2}}\right|
\end{aligned}
$$

which, with the fact that $\gamma \geq 0$, implies

$$
\begin{equation*}
\sum_{j, k=1}^{n}\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} \cdot D_{y_{j}} u\right\|_{L^{2}}^{2} \lesssim\left\|P_{X} u\right\|_{L^{2}}^{2}+\sum_{j=1}^{n}\left|\left(\left[P_{X}, D_{y_{j}}\right] u, D_{y_{j}} u\right)_{L^{2}}\right| . \tag{36}
\end{equation*}
$$

So we only need to handle the last term in the above inequality. Direct verification shows that

$$
\begin{aligned}
{\left[P_{X}, D_{y_{j}}\right]=} & \xi_{j}+\left(\left(D_{y_{j}} B(y)\right) D_{y}\right)^{*} \cdot B(y) D_{y} \\
& +\left(B(y) D_{y}\right)^{*} \cdot\left(D_{y_{j}} B(y)\right) D_{y}+\left(D_{y_{j}} F(y)\right)
\end{aligned}
$$

This gives

$$
\begin{equation*}
\sum_{j=1}^{n}\left|\left(\left[P, D_{y_{j}}\right] u, D_{y_{j}} u\right)_{L^{2}}\right| \leq \mathcal{B}_{1}+\mathcal{B}_{2}+\mathcal{B}_{3}, \tag{37}
\end{equation*}
$$

with

$$
\begin{aligned}
\mathcal{B}_{1} & =\sum_{j=1}^{n}\left|\left(\xi_{j} u, D_{y_{j}} u\right)_{L^{2}}\right|, \\
\mathcal{B}_{2} & =\sum_{j=1}^{n}\left(\left|\left(B(y) D_{y} u,\left(D_{y_{j}} B\right) D_{y} D_{y_{j}} u\right)_{L^{2}}\right|+\left|\left(\left(D_{y_{j}} B\right) D_{y} u, B(y) D_{y} D_{y_{j}} u\right)_{L^{2}}\right|\right), \\
\mathcal{B}_{3} & =\sum_{j=1}^{n}\left|\left(\left(D_{y_{j}} F(y)\right) u, D_{y_{j}} u\right)_{L^{2}}\right| .
\end{aligned}
$$

By Parseval's theorem, we may write, denoting by $\hat{u}$ the Fourier transform with respect to $y$,

$$
\left|\left(\xi_{j} u, D_{y_{j}} u\right)_{L^{2}}\right|=\left|\left(\xi_{j} \hat{u}, \eta_{j} \hat{u}\right)_{L^{2}\left(\mathbb{R}_{\eta}^{6}\right)}\right|,
$$

and hence

$$
\mathcal{B}_{1} \leq \varepsilon\left\|D_{y} \cdot D_{y} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\langle\xi\rangle^{2 / 3} u\right\|_{L^{2}}^{2},
$$

due to the inequality

$$
\left|\xi_{j} \eta_{j}\right| \leq \varepsilon|\eta|^{4}+C_{\varepsilon}\langle\xi\rangle^{4 / 3} .
$$

From (5) and (3) it follows that

$$
\mathcal{B}_{2}+\mathcal{B}_{3} \leq \varepsilon \sum_{j, k=1}^{3}\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} D_{y_{j}} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\langle y\rangle^{1+\gamma / 2} D_{y} u\right\|_{L^{2}}^{2} .
$$

Moreover repeating the arguments used in the proof of (21), with $P$ replaced by $P_{X}$, gives

$$
\left\|\langle y\rangle^{1+\gamma / 2} D_{y} u\right\|_{L^{2}}^{2} \lesssim\left\|\langle y\rangle B(y) D_{y} u\right\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2} \lesssim\left\|\left\langle\partial_{x} V\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2} .
$$

Combining these inequalities, we have

$$
\mathcal{B}_{2}+\mathcal{B}_{3} \lesssim \varepsilon \sum_{j, k=1}^{3}\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} D_{y_{j}} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2}\right) .
$$

Due to the arbitrariness of the number $\varepsilon$, the above inequalities along with (36) and (37) give the desired upper bound for the first term on the left-hand side of (33).

It remains to treat the second term. In the following discussion we use the notation

$$
T=\left(T_{1}, T_{2}, T_{3}\right)=y \wedge D_{y}, \quad A=\left(A_{1}, A_{2}, A_{3}\right)=y \wedge \xi+\partial_{x} V(x) \wedge D_{y} .
$$

From (35) it follows that

$$
\begin{aligned}
\sum_{j, k=1}^{3} & \left(\left\|\langle y\rangle^{\gamma / 2} T_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right) \\
& \leq \sum_{j=1}^{3}\left|\left(P_{X} T_{j} u, T_{j} u\right)_{L^{2}}\right| \leq\left|\left(P_{X} u, T \cdot T u\right)_{L^{2}}\right|+\left|\left(\left[P_{X}, T\right] u, T u\right)_{L^{2}}\right|,
\end{aligned}
$$

which, with the fact that $\gamma \geq 0$, implies

$$
\begin{align*}
\sum_{j, k=1}^{3} & \left(\left\|\langle y\rangle^{\gamma / 2} T_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right) \\
& \lesssim\left\|P_{X} u\right\|_{L^{2}}^{2}+\left|\left(\left[P_{X}, T\right] u, T u\right)_{L^{2}}\right| . \tag{38}
\end{align*}
$$

To handle the last term in the above inequality, we write

$$
\begin{aligned}
{\left[P_{X}, T_{j}\right]=} & -A_{j}+\left[D_{y}, T_{j}\right] \cdot \nu(y) D_{y}+D_{y} \cdot \nu(y)\left[D_{y}, T_{j}\right]+D_{y} \cdot\left(T_{j} \nu(y)\right) D_{y} \\
& +\left[T, T_{j}\right] \cdot \mu(y) T+T \cdot\left(T_{j} \mu(y)\right) T+T \cdot \mu(y)\left[T, T_{j}\right]+\left(T_{j} F(y)\right) .
\end{aligned}
$$

This gives

$$
\begin{equation*}
\left|([P, T] u, T u)_{L^{2}}\right| \leq \mathcal{N}_{1}+\mathcal{N}_{2}+\mathcal{N}_{3}+\mathcal{N}_{4}, \tag{39}
\end{equation*}
$$

with

$$
\begin{aligned}
& \mathcal{N}_{1}=\left|(A u, T u)_{L^{2}}\right|, \\
& \mathcal{N}_{2}=\sum_{j=1}^{3}\left|\left(\left[D_{y}, T_{j}\right] \cdot \nu(y) D_{y} u+D_{y} \cdot \nu(y)\left[D_{y}, T_{j}\right] u+D_{y} \cdot\left(T_{j} \nu(y)\right) D_{y} u, T_{j} u\right)_{L^{2}}\right|, \\
& \mathcal{N}_{3}=\sum_{j=1}^{3}\left|\left(\left[T, T_{j}\right] \cdot \mu(y) T u+T \cdot\left(T_{j} \mu(y)\right) T u+T \cdot \mu(y)\left[T, T_{j}\right] u, T_{j} u\right)_{L^{2}}\right|,
\end{aligned}
$$

$\mathcal{N}_{4}=\sum_{j=1}^{3}\left|\left(\left(\partial_{y_{j}} F(y)\right) u, D_{y_{j}} u\right)_{L^{2}}\right|$.
Next we treat the above four terms. For the term $\mathcal{N}_{1}$ one has, with $\lambda$ defined in (28),

$$
\begin{aligned}
(A u, T u)_{L^{2}} & \leq \varepsilon\left\|\left(\lambda^{1 / 3}\right)^{w} T u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\left(\lambda^{-1 / 3}\right)^{w} A u\right\|_{L^{2}}^{2} \\
& \leq \varepsilon\left\|\left(\lambda^{1 / 3}\right)^{w} T u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2},
\end{aligned}
$$

the last inequality holding because

$$
\left(\lambda^{-1 / 3}\right)^{w} A\left(\lambda^{-2 / 3}\right)^{w} \in \operatorname{Op}\left(S\left(1,|d y|^{2}+|d \eta|^{2}\right)\right)
$$

On the other hand,

$$
\begin{aligned}
\left\|\left(\lambda^{1 / 3}\right)^{w} T u\right\|_{L^{2}}^{2} & \lesssim\left|\left(\left(\lambda^{2 / 3}\right)^{w} T u, T u\right)_{L^{2}}\right| \\
& \lesssim\left|\left(\left(\lambda^{2 / 3}\right)^{w} u, T \cdot T u\right)_{L^{2}}\right|+\left|\left(\left[\left(\lambda^{2 / 3}\right)^{w}, T\right] u, T u\right)_{L^{2}}\right| \\
& \lesssim \varepsilon\|T \cdot T u\|_{L^{2}}+C_{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}+\left|\left(\left[\left(\lambda^{2 / 3}\right)^{w}, T\right] u, T u\right)_{L^{2}}\right|
\end{aligned}
$$

Observing (30), symbolic calculus gives

$$
\left[\left(\lambda^{2 / 3}\right)^{w}, T\right]=\left[\left(\lambda^{2 / 3}\right)^{w}, y \wedge D_{y}\right]=D_{y} b_{1}^{w}+y b_{2}^{w}+b_{3}^{w},
$$

with $b_{j}, 1 \leq j \leq 3$ belonging to $S\left(\lambda^{2 / 3},|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$. This shows that
$\left|\left(\left[\left(\lambda^{2 / 3}\right)^{w}, T\right] u, T u\right)_{L^{2}}\right| \lesssim \varepsilon \sum_{j, k=1}^{3}\left(\left\|D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right)+C_{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}$.
Combining the above inequalities, we have
$\mathcal{N}_{1} \lesssim \varepsilon \sum_{j, k=1}^{3}\left(\left\|\langle y\rangle^{\gamma / 2} T_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right)+C_{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}$.
Direct verification shows that

$$
\left[T_{j}, D_{y_{k}}\right]=\sum_{\ell} a_{j, k}^{\ell} D_{y_{\ell}}, \quad\left[T_{1}, T_{2}\right]=i T_{3}, \quad\left[T_{3}, T_{1}\right]=i T_{2}, \quad\left[T_{2}, T_{3}\right]=i T_{1}
$$

with $a_{j, k}^{\ell} \in\{0,-1,+1\}$, and thus

$$
\begin{aligned}
\mathcal{N}_{2}+\mathcal{N}_{3} \lesssim & \varepsilon \sum_{j, k=1}^{3}\left(\left\|\langle y\rangle^{\gamma / 2} T_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right) \\
& +C_{\varepsilon}\left(\left\|\langle y\rangle^{\gamma / 2} T u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} y u\right\|_{L^{2}}^{2}\right) \\
\lesssim & \varepsilon \sum_{j, k=1}^{3}\left(\left\|\langle y\rangle^{\gamma / 2} T_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right) \\
& +C_{\varepsilon}\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right),
\end{aligned}
$$

the last inequality using (7). It remains to treat $\mathcal{N}_{4}$, and by (2) and (7) we have

$$
\mathcal{N}_{4} \lesssim\left\|\langle y\rangle^{1+\gamma / 2} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y} u\right\|_{L^{2}}^{2} \lesssim\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right) .
$$

Combining the above estimates, we conclude that

$$
\begin{aligned}
\mathcal{N}_{1}+ & \mathcal{N}_{2}+\mathcal{N}_{4}+\mathcal{N}_{4} \\
\lesssim & \varepsilon \sum_{j, k=1}^{3}\left(\left\|\langle y\rangle^{\gamma / 2} T_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} D_{y_{k}} \cdot T_{j} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2} y_{k} \cdot T_{j} u\right\|_{L^{2}}^{2}\right) \\
& +C_{\varepsilon}\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right) .
\end{aligned}
$$

This along with (38) and (39) yields the desired upper bound for $\|\langle y\rangle^{\gamma / 2} \mid y \wedge$ $\left.D_{y}\right|^{2} \|_{L^{2}}$, with $\varepsilon$ small enough. The proof of Lemma 4.3 is thus complete.

## LEMMA 4.4

Let $p \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$, and let $\lambda$ be defined in (28). Then for any $\varepsilon>0$ there exists a constant $C_{\varepsilon}$, such that

$$
\begin{aligned}
& \left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u, p^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim \varepsilon\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\{\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}+\left\|\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} u\right\|_{L^{2}}^{2}\right\},
\end{aligned}
$$

where $\Phi$ is given in (34).

## Proof

As a preliminary step we first show that for any $\varepsilon, \tilde{\varepsilon}>0$ there exists a constant $C_{\varepsilon, \tilde{\varepsilon}}$ such that

$$
\begin{align*}
& \operatorname{Re}\left(\left[P_{X},\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim \varepsilon\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}  \tag{41}\\
& \quad+\tilde{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+C_{\varepsilon . \tilde{\varepsilon}}\left\{\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}+\left\|\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} u\right\|_{L^{2}}^{2}\right\}
\end{align*}
$$

where $a$ is an arbitrary symbol belonging to $S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$. Observing (3) and (31), symbolic calculus (see, e.g., [17, Theorem 2.3.8]) shows that the symbols of the commutators

$$
\left[\nu(y),\left(\lambda^{1 / 3}\right)^{w}\right] \quad \text { and } \quad\left[\mu(y),\left(\lambda^{1 / 3}\right)^{w}\right]
$$

belong to $S\left(\Phi^{1 / 3},|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$. As a result, using the notation

$$
\begin{aligned}
& \mathcal{Z}_{1}=\left(D_{y} \cdot\left[\nu(y),\left(\lambda^{1 / 3}\right)^{w}\right] D_{y} u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \mathcal{Z}_{2}=\left(\left(y \wedge D_{y}\right) \cdot\left[\mu(y),\left(\lambda^{1 / 3}\right)^{w}\right]\left(y \wedge D_{y}\right) u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}},
\end{aligned}
$$

we have

$$
\begin{aligned}
& \mathcal{Z}_{1}+\mathcal{Z}_{2} \leq \varepsilon\left\|\left\langle D_{y}\right\rangle a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+\varepsilon\left\|\left(y \wedge D_{y}\right) a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \\
&+C_{\varepsilon}\left\|\left\langle D_{y}\right\rangle \Phi^{1 / 3} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\left(y \wedge D_{y}\right) \Phi^{1 / 3} u\right\|_{L^{2}}^{2}
\end{aligned}
$$

$$
\begin{aligned}
\leq & \varepsilon\left\|\left(\left\langle D_{y}\right\rangle+\langle y\rangle\right)\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+\varepsilon\left\|\left(y \wedge D_{y}\right)\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \\
& +C_{\varepsilon} \Phi^{2 / 3}\left\|\left\langle D_{y}\right\rangle u\right\|_{L^{2}}^{2}+C_{\varepsilon} \Phi^{2 / 3}\left\|\left(y \wedge D_{y}\right) u\right\|_{L^{2}}^{2},
\end{aligned}
$$

the last inequality holding because

$$
\left[D_{y}, a^{w}\right], \quad\left[y \wedge D_{y}, a^{w}\right]\left((1+\langle y\rangle+\langle\eta\rangle)^{-1}\right)^{w} \in \mathrm{Op}\left(S\left(1,|d y|^{2}+|d \eta|^{2}\right)\right)
$$

since $a \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$. Moreover using (35) gives

$$
\begin{equation*}
\mathcal{Z}_{1}+\mathcal{Z}_{2} \leq \varepsilon\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+C_{\varepsilon}\left\{\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}\right\} . \tag{42}
\end{equation*}
$$

Denote that

$$
\begin{aligned}
\mathcal{Z}_{3}= & \left(\left[D_{y},\left(\lambda^{1 / 3}\right)^{w}\right] \cdot \nu(y) D_{y} u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& +\left(D_{y} \cdot \nu(y)\left[D_{y},\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
\mathcal{Z}_{4}= & \left(\left[y \wedge D_{y},\left(\lambda^{1 / 3}\right)^{w}\right] \cdot \mu(y)\left(y \wedge D_{y}\right) u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& +\left(\left(y \wedge D_{y}\right) \cdot \mu(y)\left[y \wedge D_{y},\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} .
\end{aligned}
$$

Observing (31), symbolic calculus gives

$$
\left[D_{y},\left(\lambda^{1 / 3}\right)^{w}\right]=a_{1}^{w}, \quad\left[\left(y \wedge D_{y}\right),\left(\lambda^{1 / 3}\right)^{w}\right]=a_{2}^{w} D_{y}+a_{3}^{w} y+a_{4}^{w},
$$

with $a_{j}, 1 \leq j \leq 4$ belonging to $S\left(\Phi^{1 / 3},|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$. It then follows that

$$
\begin{aligned}
\mathcal{Z}_{3}+\mathcal{Z}_{4} \leq & \varepsilon\left\|\left\langle D_{y}\right\rangle a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+\varepsilon\left\|\langle y\rangle^{1+\gamma / 2} a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \\
& +\varepsilon\left\|\langle y\rangle^{\gamma / 2}\left\langle D_{y}\right\rangle a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+\varepsilon\left\|\langle y\rangle^{\gamma / 2}\left\langle y \wedge D_{y}\right\rangle a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \\
& +C_{\varepsilon}\left\|\langle y\rangle^{\gamma / 2}\left(\langle y\rangle+\left\langle D_{y}\right\rangle\right) \Phi^{1 / 3} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left\|\langle y\rangle^{\gamma / 2}\left(y \wedge D_{y}\right) \Phi^{1 / 3} u\right\|_{L^{2}}^{2} .
\end{aligned}
$$

Using similar arguments as the treatment of $\mathcal{Z}_{1}$ and $\mathcal{Z}_{2}$, we conclude that

$$
\mathcal{Z}_{3}+\mathcal{Z}_{4} \leq \varepsilon\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+C_{\varepsilon}\left\{\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}\right\} .
$$

This along with (42) gives

$$
\begin{align*}
& \left(\left[\left(B(y) D_{y}\right)^{*} B(y) D_{y},\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim \varepsilon\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+C_{\varepsilon}\left\{\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}\right\} \tag{43}
\end{align*}
$$

since

$$
\left(\left[\left(B(y) D_{y}\right)^{*} B(y) D_{y},\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}=\sum_{1 \leq j \leq 4} \mathcal{Z}_{j} .
$$

Moreover we have

$$
\begin{align*}
& \left(\left[F(y),\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}  \tag{44}\\
& \quad \lesssim \varepsilon\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+C_{\varepsilon}\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}\right),
\end{align*}
$$

which can be deduced similarly as above, since by (3),

$$
\left[F(y),\left(\lambda^{1 / 3}\right)^{w}\right] \in \operatorname{Op}\left(S\left(\langle y\rangle^{1+\gamma} \Phi^{1 / 3},|d y|^{2}+|d \eta|^{2}\right)\right)
$$

uniformly with respect to $X$. Next we treat the commutator $\left[i Q_{X},\left(\lambda^{1 / 3}\right)^{w}\right]$, whose symbol is

$$
-\frac{\lambda^{1 / 3-2}}{6}\left[2\left(\partial_{x} V(x) \wedge \eta+y \wedge \xi\right) \cdot\left(\partial_{x} V(x) \wedge \xi\right)+3|y|^{4} \partial_{x} V(x) \cdot y+3|\eta|^{4} \xi \cdot \eta\right] .
$$

In view of (30) and (28), one can verify that the above symbol belongs to

$$
S\left(\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} \lambda^{1 / 3}+\Phi^{2 / 3} \lambda^{1 / 3},|d y|^{2}+|d \eta|^{2}\right)
$$

uniformly with respect to $X$. As a result, observing that $\lambda^{1 / 3} \in S\left(\lambda^{1 / 3},|d y|^{2}+\right.$ $|d \eta|^{2}$ ) uniformly with respect to $X$, we have

$$
\left(\lambda^{-1 / 3}\right)^{w} a^{w}\left[i Q_{X},\left(\lambda^{1 / 3}\right)^{w}\right] \in \operatorname{Op}\left(S\left(\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}+\Phi^{2 / 3},|d y|^{2}+|d \eta|^{2}\right)\right)
$$

uniformly with respect to $X$, which implies, with $\tilde{\varepsilon}$ arbitrarily small that

$$
\begin{aligned}
& \left(\left[i Q_{X},\left(\lambda^{1 / 3}\right)^{w}\right] u, a^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim \tilde{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w}\right\|_{L^{2}}^{2}+C_{\tilde{\varepsilon}}\left(\left\|\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}\right)
\end{aligned}
$$

This along with (43) and (44) gives (41), since

$$
\left[P_{X},\left(\lambda^{1 / 3}\right)^{w}\right]=\left[i Q_{X},\left(\lambda^{1 / 3}\right)^{w}\right]+\left[\left(B(y) D_{y}\right)^{*} B(y) D_{y}+F(y),\left(\lambda^{1 / 3}\right)^{w}\right]
$$

Next we prove (40). The relation

$$
\begin{aligned}
& \operatorname{Re}\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+\operatorname{Re}\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u, p^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& =\operatorname{Re}\left(P_{X} u,\left(\lambda^{1 / 3}\right)^{w}\left(\operatorname{Id}+p^{w}\right)\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad+\operatorname{Re}\left(\left[P_{X},\left(\lambda^{1 / 3}\right)^{w}\right] u,\left(\operatorname{Id}+p^{w}\right)\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}
\end{aligned}
$$

gives, with $\tilde{\varepsilon}>0$ arbitrary,

$$
\begin{aligned}
& \operatorname{Re}\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+\operatorname{Re}\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u, p^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim \tilde{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w}\right\|_{L^{2}}^{2}+C_{\tilde{\varepsilon}}\left\|P_{X} u\right\|_{L^{2}}^{2}+\operatorname{Re}\left(\left[P_{X},\left(\lambda^{1 / 3}\right)^{w}\right] u,\left(\operatorname{Id}+p^{w}\right)\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} .
\end{aligned}
$$

We can apply (41) with $a=1+p$ to control the last term in the above inequality; this gives, with $\varepsilon, \tilde{\varepsilon}>0$ arbitrarily small,

$$
\begin{aligned}
& \operatorname{Re}\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+\operatorname{Re}\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u, p^{w}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim \varepsilon\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}+\tilde{\varepsilon}\left\|\left(\lambda^{2 / 3}\right)^{w}\right\|_{L^{2}}^{2} \\
& \quad+C_{\varepsilon, \tilde{\varepsilon}}\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}+\left\|\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} u\right\|_{L^{2}}^{2}\right) .
\end{aligned}
$$

Taking $\varepsilon$ small enough yields the desired estimate (40). The proof is thus complete.

### 4.2. Proof of Proposition 4.1

In what follows, let $h_{N}$, with $N$ a large integer, be a symbol defined by

$$
\begin{equation*}
h_{N}=h_{N}(y, \eta)=\frac{\partial_{x} V(x) \cdot y+\xi \cdot \eta+\left(\partial_{x} V \wedge \eta+y \wedge \xi\right) \cdot(y \wedge \eta)}{\lambda_{N}^{4 / 3}} \psi_{N}(y, \eta), \tag{45}
\end{equation*}
$$

where

$$
\begin{equation*}
\lambda_{N}=\left(1+\left|\partial_{x} V \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}+N^{-1}\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{6 / 5}\right)^{1 / 2} \tag{46}
\end{equation*}
$$

and

$$
\begin{equation*}
\psi_{N}(y, \eta)=\chi\left(\frac{\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) N^{2}}{\lambda_{N}^{2 / 3}}\right) \tag{47}
\end{equation*}
$$

with $\chi \in C_{0}^{\infty}(\mathbb{R} ;[0,1])$ such that $\chi=1$ in $[-1,1]$ and supp $\chi \subset[-2,2]$.

## LEMMA 4.5

Let $\lambda_{N}$ be given in (46). Then

$$
\begin{equation*}
\forall \sigma \in \mathbb{R}, \quad \lambda_{N}^{\sigma} \in S\left(\lambda_{N}^{\sigma},|d y|^{2}+|d \eta|^{2}\right) \tag{48}
\end{equation*}
$$

uniformly with respect to $X$. Moreover if $\sigma \leq 1$, then

$$
\begin{equation*}
\forall|\alpha|+|\beta| \geq 1, \quad\left|\partial_{y}^{\alpha} \partial_{\eta}^{\beta}\left(\lambda_{N}^{\sigma}\right)\right| \lesssim\left\langle\partial_{x} V(x)\right\rangle^{\sigma}+\langle\xi\rangle^{\sigma} . \tag{49}
\end{equation*}
$$

Proof
The proof is the same as that of Lemma 4.2.

## LEMMA 4.6

The symbol $h_{N}$ given in (45) belongs to $S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$.

Proof
It is just a straightforward verification by (48).

LEMMA 4.7
Let $\lambda_{N}$ and $\psi_{N}$ be given in (46) and (47). Then for any $\sigma \in \mathbb{R}$ the following two inequalities

$$
\begin{equation*}
\left|\left(\xi \cdot \partial_{\eta}+\partial_{x} V(x) \cdot \partial_{y}\right) \lambda_{N}^{\sigma}\right| \lesssim N \lambda_{N}^{\sigma+2 / 3} \tag{50}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\left(\xi \cdot \partial_{\eta}+\partial_{x} V(x) \cdot \partial_{y}\right) \psi_{N}\right| \lesssim N^{3}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) \tag{51}
\end{equation*}
$$

hold uniformly with respect to $(x, \xi)$.
Proof
Using the inequality $\left\langle\partial_{x} V \wedge \xi\right\rangle \leq N^{5 / 6} \lambda_{N}^{5 / 3}$ due to (46), we can verify that

$$
\left|\xi \cdot \partial_{\eta}\left(\lambda_{N}^{2}\right)\right|+\left|\partial_{x} V(x) \cdot \partial_{y}\left(\lambda_{N}^{2}\right)\right| \lesssim \lambda_{N}\left\langle\partial_{x} V \wedge \xi\right\rangle \lesssim N \lambda_{N}^{2+2 / 3}
$$

Then for any $\sigma \in \mathbb{R}$ one has

$$
\left|\xi \cdot \partial_{\eta}\left(\lambda_{N}^{\sigma}\right)\right|+\left|\partial_{x} V(x) \cdot \partial_{y}\left(\lambda_{N}^{\sigma}\right)\right| \lesssim N \lambda_{N}^{\sigma} \lambda_{N}^{2 / 3} .
$$

Thus (50) follows. To show (51), we write

$$
\left|\left(\xi \cdot \partial_{\eta}+\partial_{x} V(x) \cdot \partial_{y}\right) \psi_{N}\right| \leq\left(\mathcal{K}_{1}+\mathcal{K}_{2}\right),
$$

with

$$
\begin{aligned}
\mathcal{K}_{1}= & N^{2} \mid \lambda_{N}^{-2 / 3}\left(\xi \cdot \partial_{\eta}+\partial_{x} V(x) \cdot \partial_{y}\right)\left[|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right] \\
& \times \chi^{\prime}\left(\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) N^{2} \lambda_{N}^{-2 / 3}\right) \mid, \\
\mathcal{K}_{2}= & N^{2} \mid\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V(x) \cdot \partial_{y}\right) \lambda_{N}^{-2 / 3}\right] \\
& \times \chi^{\prime}\left(\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) N^{2} \lambda_{N}^{-2 / 3}\right) \mid .
\end{aligned}
$$

Using (50) shows that

$$
\mathcal{K}_{2} \lesssim N^{3}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)
$$

Moreover direct computation gives

$$
\begin{aligned}
\mathcal{K}_{1} & \lesssim N^{2} \lambda_{N}^{1 / 3}(|y \wedge \eta|+|y|+|\eta|) \chi^{\prime}\left(\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) N^{2} \lambda_{N}^{-2 / 3}\right) \\
& \lesssim N^{3}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right),
\end{aligned}
$$

the last inequality following from the fact that $\lambda_{N}^{2 / 3} \lesssim\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) N^{2}$ on the support of the function

$$
\chi^{\prime}\left(\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) N^{2} \lambda_{N}^{-2 / 3}\right) .
$$

Then the above inequalities yield the desired inequality (51). The proof of Lemma 4.7 is thus complete.

## Proof of Proposition 4.1

This will occupy the rest of this section. Since the proof is quite long, we divide it into three steps.

Step 1. Let $N$ be a large integer to be determined later, and let $H=h_{N}^{\text {Wick }}$ be the Wick quantization of the symbol $h_{N}$ given in (45). To simplify the notation we will use $C_{N}$ to denote different suitable constants which depend only on $N$. In the following discussion, let $u \in \mathcal{S}\left(\mathbb{R}_{y}^{3}\right)$. By (16) and Lemma 4.6 we can find a symbol $\tilde{h}_{N}$ such that $H=\tilde{h}_{N}^{w}$ with $\tilde{h}_{N} \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$. Then using (19) gives

$$
\left|\left(\left(B(y) D_{y}\right)^{*} B(y) D_{y} u, H u\right)_{L^{2}}+(F u, H u)_{L^{2}}\right| \lesssim\left|\left(P_{X} u, u\right)_{L^{2}}\right| .
$$

This together with the relation

$$
\begin{aligned}
\operatorname{Re}\left(i Q_{X} u, H u\right)_{L^{2}}= & \operatorname{Re}\left(P_{X} u, H u\right)_{L^{2}}-\operatorname{Re}\left(\left(B(y) D_{y}\right)^{*} B(y) D_{y} u, H u\right)_{L^{2}} \\
& -\operatorname{Re}(F u, H u)_{L^{2}}
\end{aligned}
$$

yields

$$
\begin{equation*}
\operatorname{Re}\left(i Q_{X} u, H u\right)_{L^{2}} \lesssim\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, H u\right)_{L^{2}}\right| . \tag{52}
\end{equation*}
$$

Next we give a lower bound for the term on the left-hand side. Observe that the symbol of $Q_{X}$ is a first-order polynomial in $y, \eta$. Then

$$
i Q_{X}=i\left(y \cdot \xi-\partial_{x} V(x) \cdot \eta\right)^{\text {Wick }}
$$

and hence

$$
\begin{equation*}
\operatorname{Re}\left(i Q_{X} u, H u\right)_{L^{2}}=\frac{1}{4 \pi}\left(\left\{h, y \cdot \xi-\partial_{x} V(x) \cdot \eta\right\}^{\text {Wick }} u, u\right)_{L^{2}}, \tag{53}
\end{equation*}
$$

where $\{\cdot, \cdot\}$ is the Poisson bracket defined in (17). Direct calculus shows that

$$
\begin{aligned}
\{h, y \cdot & \left.\xi-\partial_{x} V(x) \cdot \eta\right\} \\
= & \frac{\left|\partial_{x} V(x) \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}+2\left(\partial_{x} V \wedge \xi\right) \cdot(y \wedge \eta)}{\lambda_{N}^{4 / 3}} \psi_{N} \\
& +\left(\partial_{x} V \wedge \eta+y \wedge \xi\right) \cdot(y \wedge \eta)\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V \cdot \partial_{y}\right)\left(\lambda_{N}^{-4 / 3} \psi_{N}\right)\right] \\
= & \lambda_{N}^{2 / 3} \psi_{N}-\frac{1+N^{-1}\left\langle\partial_{x} V(x) \wedge y\right\rangle^{6 / 5}}{\lambda_{N}^{4 / 3}} \psi_{N}+\frac{2\left(\partial_{x} V \wedge \xi\right) \cdot(y \wedge \eta)}{\lambda_{N}^{4 / 3}} \psi_{N} \\
& +\left(\partial_{x} V \wedge \eta+y \wedge \xi\right) \cdot(y \wedge \eta)\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V \cdot \partial_{y}\right)\left(\lambda_{N}^{-4 / 3} \psi_{N}\right)\right] \\
\geq & \lambda_{N}^{2 / 3}-\lambda_{N}^{2 / 3}\left(1-\psi_{N}\right)-\frac{1+N^{-1}\left\langle\partial_{x} V \wedge \xi\right\rangle^{6 / 5}}{\lambda_{N}^{4 / 3}-\frac{2\left|\left(\partial_{x} V \wedge \xi\right) \cdot(y \wedge \eta)\right|}{\lambda_{N}^{4 / 3}} \psi_{N}} \\
& -\left|\left(\partial_{x} V \wedge \eta+y \wedge \xi\right) \cdot(y \wedge \eta)\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V \cdot \partial_{y}\right)\left(\lambda_{N}^{-4 / 3} \psi_{N}\right)\right]\right| \\
\geq & \lambda_{N}^{2 / 3}-N^{2}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)-\frac{1+N^{-1}\left\langle\partial_{x} V \wedge \xi\right\rangle^{6 / 5}}{\lambda_{N}^{4 / 3}} \\
& -\frac{2\left|\left(\partial_{x} V \wedge \xi\right) \cdot(y \wedge \eta)\right|}{\lambda_{N}^{4 / 3}} \psi_{N} \\
& -\left|\left(\partial_{x} V \wedge \eta+y \wedge \xi\right) \cdot(y \wedge \eta)\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V \cdot \partial_{y}\right)\left(\lambda_{N}^{-4 / 3} \psi_{N}\right)\right]\right|
\end{aligned}
$$

the last inequality holding because $\lambda_{N}^{2 / 3} \leq N^{2}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)$ on the support of $1-\psi_{N}$. Due to the positivity of the Wick quantization, the above inequalities, along with (52), (53), and the estimate

$$
\begin{equation*}
\left(\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)^{\text {Wick }} u, u\right)_{L^{2}} \lesssim\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2} \tag{54}
\end{equation*}
$$

due to (35), yield

$$
\begin{align*}
\left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{\left.L^{2} R_{y}^{3}\right)} \lesssim & \sum_{j=1}^{3}\left(R_{j}^{\text {Wick }} u, u\right)_{L^{2}}+\left|\left(P_{X} u, u\right)_{L^{2}}\right| \\
& +\left|\left(P_{X} u, H u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2}, \tag{55}
\end{align*}
$$

where $R_{j}$ are given by

$$
\begin{aligned}
& R_{1}=\frac{1+N^{-1}\left\langle\partial_{x} V \wedge \xi\right\rangle^{6 / 5}}{\lambda_{N}^{4 / 3}} \\
& R_{2}=\frac{2\left|\left(\partial_{x} V \wedge \xi\right) \cdot(y \wedge \eta)\right|}{\lambda_{N}^{4 / 3}} \psi_{N}, \\
& R_{3}=\left|\left(\partial_{x} V \wedge \eta+y \wedge \xi\right) \cdot(y \wedge \eta)\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V \cdot \partial_{y}\right)\left(\lambda_{N}^{-4 / 3} \psi_{N}\right)\right]\right| .
\end{aligned}
$$

Step 2. In this step we treat the above terms $R_{j}$, and we show that there exists a symbol $q$, belonging to $S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$, such that

$$
\begin{align*}
\sum_{j=1}^{3}\left(R_{j}^{\text {Wick }} u, u\right)_{L^{2}} \leq & N^{-1 / 3}\left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}}  \tag{56}\\
& +C_{N}\left\{\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, q^{\text {Wick }} u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2}\right\} .
\end{align*}
$$

For this purpose we define $q$ by

$$
q(y, \eta)=q_{X}(y, \eta)=\frac{\left(\partial_{x} V(x) \wedge \xi\right) \cdot\left(\partial_{x} V(x) \wedge \eta+y \wedge \xi\right)}{\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{8 / 5}} \varphi(y, \eta)
$$

with

$$
\varphi(y, \eta)=\chi\left(\frac{\left|\partial_{x} V(x) \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}}{\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{6 / 5}}\right)
$$

Then one can verify that $q \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $(x, \xi)$. Thus similar to (52) we conclude that

$$
\begin{equation*}
\operatorname{Re}\left(i Q_{X} u, q^{\text {Wick }} u\right)_{L^{2}} \lesssim\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, q^{\text {Wick }} u\right)_{L^{2}}\right| . \tag{57}
\end{equation*}
$$

On the other hand, it is just a direct computation of the Poisson bracket to see that

$$
\begin{align*}
\operatorname{Re}\left(i Q_{X} u, q^{\text {Wick }} u\right)_{L^{2}} & =\frac{1}{4 \pi}\left(\left\{q(y, \eta), y \cdot \xi-\partial_{x} V(x) \cdot \eta\right\}^{\text {Wick }} u, u\right)_{L^{2}} \\
& =\frac{1}{4 \pi}\left(R_{1,1}^{\text {Wick }} u, u\right)_{L^{2}}+\frac{1}{4 \pi}\left(R_{1,2}^{\text {Wick }} u, u\right)_{L^{2}}, \tag{58}
\end{align*}
$$

with

$$
\begin{aligned}
R_{1,1} & =\frac{2\left|\partial_{x} V(x) \wedge \xi\right|^{2}}{\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{8 / 5}} \varphi \\
R_{1,2} & =\frac{\left(\partial_{x} V(x) \wedge \xi\right) \cdot\left(\partial_{x} V(x) \wedge \eta+y \wedge \xi\right)}{\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{8 / 5}}\left[\left(\xi \cdot \partial_{\eta}+\partial_{x} V(x) \cdot \partial_{y}\right) \varphi(y, \eta)\right]
\end{aligned}
$$

Moreover we have

$$
\left|R_{1,2}\right| \lesssim\left(\left|\partial_{x} V(x) \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}\right)^{1 / 3} \lesssim \lambda_{N}^{2 / 3}
$$

due to the fact that

$$
\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} \approx\left(\left|\partial_{x} V(x) \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}\right)^{1 / 3}
$$

on the support of $\varphi^{\prime}$, and

$$
\begin{aligned}
\frac{1}{2} R_{1,1}= & \left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}-\frac{1}{\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{8 / 5}} \varphi-\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}(1-\varphi) \\
\geq & \left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}-\frac{1}{\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{8 / 5}} \\
& -\left(\left|\partial_{x} V(x) \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}\right)^{1 / 3}
\end{aligned}
$$

where the inequality holds because

$$
\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} \leq\left(\left|\partial_{x} V(x) \wedge \eta+y \wedge \xi\right|^{2}+\left|\partial_{x} V(x)\right|^{2}+|\xi|^{2}\right)^{1 / 3}
$$

on the support of $1-\varphi$. These inequalities, combining (58) and (57), yield

$$
\begin{aligned}
\left(\left(\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}\right)^{\text {Wick }} u, u\right)_{L^{2}} \lesssim & \left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}} \\
& +\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, q^{\text {Wick }} u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2} .
\end{aligned}
$$

Consequently, observing that

$$
R_{1}=\frac{1+N^{-1}\left\langle\partial_{x} V \wedge \xi\right\rangle^{6 / 5}}{\lambda_{N}^{4 / 3}} \leq N^{-1 / 3}\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}+1,
$$

and

$$
\begin{aligned}
R_{2} & =\frac{\left|\left(\partial_{x} V \wedge \xi\right) \cdot(y \wedge \eta)\right|}{\lambda_{N}^{4 / 3}} \psi_{N} \lesssim \frac{N^{-1}\left\langle\partial_{x} V \wedge \xi\right\rangle}{\lambda} \frac{N|y \wedge \eta|}{\lambda_{N}^{1 / 3}} \psi_{N} \\
& \leq N^{-1 / 2}\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5},
\end{aligned}
$$

we get the desired upper bound for the terms $R_{1}$ and $R_{2}$.
It remains to handle $R_{3}$. By virtue of (50) and (51), we compute
$R_{3} \lesssim N \lambda_{N}^{1 / 3}|y \wedge \eta|+N^{2}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right) \leq N^{-1} \lambda_{N}^{2 / 3}+C_{N}\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)$.
As a result, the positivity of Wick quantization gives

$$
\begin{aligned}
\left(R_{3}^{\text {Wick }} u, u\right)_{L^{2}} & \leq N^{-1}\left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}}+C_{N}\left(\left(|y \wedge \eta|^{2}+|y|^{2}+|\eta|^{2}\right)^{\text {Wick }} u, u\right)_{L^{2}} \\
& \leq N^{-1}\left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}}+C_{N}\left\{\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2}\right\},
\end{aligned}
$$

the last inequality using (54). Thus the desired estimate (56) follows.
Step 3. Now we proceed to the proof of Proposition 4.1. From (55) and (56), it follows that there exists a symbol $p \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$ such that

$$
\begin{aligned}
\left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}} \leq & N^{-1 / 3}\left(\left(\lambda_{N}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}} \\
& +C_{N}\left\{\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, p^{\text {Wick }} u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2}\right\},
\end{aligned}
$$

which allows us to choose an integer $N_{0}$ large enough such that

$$
\left(\left(\lambda_{N_{0}}^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}} \lesssim C_{N_{0}}\left\{\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, p^{\text {Wick }} u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2}\right\} .
$$

Consequently, observing that

$$
\lambda^{2 / 3} \lesssim \lambda_{N_{0}}^{2 / 3}+|y|^{2}+|\eta|^{2}
$$

with $\lambda$ defined in (28), we get, combining (54),

$$
\begin{equation*}
\left(\left(\lambda^{2 / 3}\right)^{\text {Wick }} u, u\right)_{L^{2}} \lesssim\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, p^{\text {Wick }} u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2} . \tag{59}
\end{equation*}
$$

Note that $\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3} \leq \lambda^{2 / 3}$; then the above inequality yields

$$
\left(\left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3}\right) u, u\right)_{L^{2}} \lesssim\left|\left(P_{X} u, u\right)_{L^{2}}\right|+\left|\left(P_{X} u, p^{\text {Wick }} u\right)_{L^{2}}\right|+\|u\|_{L^{2}}^{2} .
$$

Since $p \in S\left(1,|d y|^{2}+|d \eta|^{2}\right)$ uniformly with respect to $X$, applying the above inequality to the function

$$
\left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3}\right)^{1 / 2} u
$$

implies

$$
\begin{equation*}
\left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3}\right)\|u\|_{L^{2}} \lesssim\left\|P_{X} u\right\|_{L^{2}}+\|u\|_{L^{2}} . \tag{60}
\end{equation*}
$$

Similarly, since $\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} \leq \lambda^{2 / 3}$, by virtue of (59) we have, repeating the above arguments,

$$
\begin{equation*}
\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5}\|u\|_{L^{2}} \lesssim\left\|P_{X} u\right\|_{L^{2}}+\|u\|_{L^{2}} . \tag{61}
\end{equation*}
$$

Now we apply (59) to the function $\left(\lambda^{1 / 3}\right)^{w} u$ to get

$$
\begin{aligned}
& \left(\left(\lambda^{2 / 3}\right)^{\text {Wick }}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \\
& \quad \lesssim\left|\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}\right|+\left|\left(P_{X}\left(\lambda^{1 / 3}\right)^{w} u, p^{\text {Wick }}\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}}\right| \\
& \quad+\left\|\left(\lambda^{1 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \\
& \quad \leq \varepsilon\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left(\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}+\left\|\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} u\right\|_{L^{2}}^{2}+\left\|P_{X} u\right\|_{L^{2}}^{2}\right),
\end{aligned}
$$

where the last inequality follows from (40). Furthermore, using (32) implies

$$
\left(\left(\lambda^{2 / 3}\right)^{\text {Wick }}\left(\lambda^{1 / 3}\right)^{w} u,\left(\lambda^{1 / 3}\right)^{w} u\right)_{L^{2}} \gtrsim\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}-\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2} .
$$

Combining the above inequalities, we have

$$
\begin{aligned}
\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \lesssim & \varepsilon\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2} \\
& +C_{\varepsilon}\left(\left\|\Phi^{2 / 3} u\right\|_{L^{2}}^{2}+\left\|\left\langle\partial_{x} V(x) \wedge \xi\right\rangle^{2 / 5} u\right\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right) \\
\lesssim & \varepsilon\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}}^{2}+C_{\varepsilon}\left(\left\|P_{X} u\right\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}\right),
\end{aligned}
$$

the last inequality following from (60) and (61). Taking the number $\varepsilon$ small enough yields

$$
\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}} \lesssim\left\|P_{X} u\right\|_{L^{2}}+\|u\|_{L^{2}} .
$$

This, along with (33) and (60), gives the desired estimate (29), completing the proof of Proposition 4.1.

## 5. Proof of Theorem 1.1: Regularity estimates in all variables

In this section we show the hypoelliptic estimates in spatial and velocity variables for the original operator $P$. Throughout this section $\|\cdot\|_{L^{2}}$ stands for the norm in $L^{2}\left(\mathbb{R}_{x, y}^{6}\right)$.

## PROPOSITION 5.1

Let $V(x)$ be a $C^{2}$-function satisfying the assumption (8). Then for any $u \in$ $C_{0}^{\infty}\left(\mathbb{R}^{2 n}\right)$ one has

$$
\begin{align*}
& \left\|\left|D_{x}\right|^{2 / 3} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}} \\
& \quad \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}} . \tag{62}
\end{align*}
$$

Proof
The proof is quite similar to that of [19, Proposition 4.1]. So we only give a sketch here and refer to [19] for more detailed discussions. To each fixed $x_{\mu} \in \mathbb{R}^{3}$ we associate an operator

$$
P_{x_{\mu}}=i\left(y \cdot D_{x}-\partial_{x} V\left(x_{\mu}\right) \cdot D_{y}\right)+\left(B(y) D_{y}\right)^{*} \cdot B(y) D_{y}+F(y) .
$$

Let $P_{X_{\mu}}$, with $X_{\mu}=\left(x_{\mu}, \xi\right)$, be the operator defined in (27); that is,

$$
P_{X_{\mu}}=i\left(y \cdot \xi-\partial_{x} V\left(x_{\mu}\right) \cdot D_{y}\right)+\left(B(y) D_{y}\right)^{*} \cdot B(y) D_{y}+F(y) .
$$

Observe that

$$
\mathcal{F}_{x} P_{x_{\mu}}=P_{X_{\mu}},
$$

where $\mathcal{F}_{x}$ stands for the partial Fourier transform in the $x$ variable. Suppose $V$ satisfies the condition (8). Then performing the Fourier transform with respect to $x$, it follows from (29) that for all $u \in C_{0}^{\infty}\left(\mathbb{R}^{6}\right)$,

$$
\begin{align*}
& \left\|\left\langle D_{x}\right\rangle^{2 / 3} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}} \\
& \quad \lesssim\left\|P_{x_{\mu}} u\right\|_{L^{2}}+\|u\|_{L^{2}} . \tag{63}
\end{align*}
$$

Li [19, Lemma 4.2] showed that the metric

$$
g_{x}=\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}|d x|^{2}, \quad x \in \mathbb{R}^{3}
$$

is slowly varying; that is, we can find two constants $C_{*}, r_{0}>0$ such that if $g_{x}(x-$ $y) \leq r_{0}^{2}$, then

$$
C_{*}^{-1} \leq \frac{g_{x}}{g_{y}} \leq C_{*} .
$$

The main feature of a slowly varying metric is that it allows us to introduce some partitions of unity related to the metric (see, e.g., [14, Lemma 18.4.4]). Precisely, we could find a constant $r>0$ and a sequence $x_{\mu} \in \mathbb{R}^{n}, \mu \geq 1$ such that the union of the balls

$$
\Omega_{\mu, r}=\left\{x \in \mathbb{R}^{n} ; g_{x_{\mu}}\left(x-x_{\mu}\right)<r^{2}\right\}
$$

covers the whole space $\mathbb{R}^{n}$. Moreover there exists a positive integer $N_{r}$, depending only on $r$, such that the intersection of more than $N_{r}$ balls is always empty. One can choose a family of nonnegative functions $\left\{\varphi_{\mu}\right\}_{\mu \geq 1}$ in $S\left(1, g_{x}\right)$ such that

$$
\operatorname{supp} \varphi_{\mu} \subset \Omega_{\mu, r}, \quad \sum_{\mu \geq 1} \varphi_{\mu}^{2}=1, \quad \text { and } \quad \sup _{\mu \geq 1}\left|\partial_{x} \varphi_{\mu}(x)\right| \lesssim\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}
$$

By [19, Lemma 4.6] we see

$$
\begin{equation*}
\left\|\left\langle D_{x}\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2} \lesssim \sum_{\mu \geq 1}\left\|\left\langle D_{x}\right\rangle^{2 / 3} \varphi_{\mu} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2} . \tag{64}
\end{equation*}
$$

Using the notation

$$
R_{\mu}=-y \cdot \partial_{x} \varphi_{\mu}(x)-\varphi_{\mu}\left(\partial_{x} V(x)-\partial_{x} V\left(x_{\mu}\right)\right) \cdot \partial_{y},
$$

we write

$$
\varphi_{\mu} P u=P_{x_{\mu}} \varphi_{\mu} u+R_{\mu} u .
$$

Then

$$
\sum_{\mu \geq 1}\left\|P_{x_{\mu}} \varphi_{\mu} u\right\|_{L^{2}}^{2} \leq 2 \sum_{\mu \geq 1}\left(\left\|\varphi_{\mu} P u\right\|_{L^{2}}^{2}+\left\|R_{\mu} u\right\|_{L^{2}}^{2}\right) \leq 2\|P u\|_{L^{2}}^{2}+2 \sum_{\mu \geq 1}\left\|R_{\mu} u\right\|_{L^{2}}^{2}
$$

On the other hand, by [19, Lemma 4.9] we have

$$
\sum_{\mu \geq 1}\left\|R_{\mu} u\right\|_{L^{2}}^{2} \lesssim\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}
$$

The above two inequalities yield

$$
\forall u \in C_{0}^{\infty}\left(\mathbb{R}^{2 n}\right), \quad \sum_{\mu \geq 1}\left\|P_{x_{\mu}} \varphi_{\mu} u\right\|_{L^{2}}^{2} \lesssim\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2}
$$

Using (64) and (63), we have

$$
\begin{aligned}
\left\|\left\langle D_{x}\right\rangle^{2 / 3} u\right\|_{L^{2}}^{2} & \lesssim \sum_{\mu \geq 1}\left\|\left\langle D_{x}\right\rangle^{2 / 3} \varphi_{\mu} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2}+C\|u\|_{L^{2}}^{2} \\
& \lesssim \sum_{\mu \geq 1}\left\|P_{x_{\mu}} \varphi_{\mu} u\right\|_{L^{2}}^{2}+\|P u\|_{L^{2}}^{2}+\|u\|_{L^{2}}^{2},
\end{aligned}
$$

and

$$
\begin{aligned}
& \left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} u\right\|_{L^{2}}^{2}+\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} u\right\|_{L^{2}}^{2} \\
& \quad=\sum_{\mu \geq 1}\left\|\langle y\rangle^{\gamma / 2}\left|D_{y}\right|^{2} \varphi_{\mu} u\right\|_{L^{2}}^{2}+\sum_{\mu \geq 1}\left\|\langle y\rangle^{\gamma / 2}\left|y \wedge D_{y}\right|^{2} \varphi_{\mu} u\right\|_{L^{2}}^{2} \\
& \quad \lesssim \sum_{\mu \geq 1}\left\|P_{x_{\mu}} \varphi_{\mu} u\right\|_{L^{2}}^{2}+\sum_{\mu \geq 1}\left\|\varphi_{\mu} u\right\|_{L^{2}}^{2} .
\end{aligned}
$$

As a result, combining these inequalities gives (62). The proof is then complete.

## 6. End of the proof of Theorem 1.1: Anisotropic estimates

In this section we prove the anisotropic estimate (11) in Theorem 1.1 under the condition (10). Starting from the estimates for operators with parameters given in Section 4, we first establish an estimate in Wick quantization, and then we come back to the Weyl quantization from the Wick quantization.

## NOTATIONS

Throughout this section, $\|\cdot\|_{L^{2}}$ stands for the norm in $L^{2}\left(\mathbb{R}_{x, y}^{6}\right)$. Given a symbol $p$, we use $p^{\text {Wick }}$ to denote the Wick quantization of $p$ in all variables $(x, y, \xi, \eta)$; we use $p^{\text {Wick }(x)}$ and $p^{\text {Wick( } y)}$ to denote the Wick quantization of $p$ in $(x, \xi)$ and in
$(y, \eta)$, respectively; similarly we use it for the Weyl quantization $p^{w}, p^{w(x)}$, and $p^{w(y)}$, and for the wave-packets transform $W, W_{x}$, and $W_{y}$.

## PROPOSITION 6.1 (ESTIMATES IN WICK QUANTIZATION)

Let $V$ satisfy the condition (10). Then

$$
\begin{equation*}
\forall u \in \mathcal{S}\left(\mathbb{R}_{x, y}^{6}\right), \quad\left\|\left(\lambda^{2 / 3}\right)^{\text {Wick }} u\right\|_{L^{2}} \leq\|\tilde{P} u\|_{L^{2}}+\|P u\|_{L^{2}}+\|u\|_{L^{2}}, \tag{65}
\end{equation*}
$$

where $\lambda$ is given in (28) and $\tilde{P}$ is defined by

$$
\begin{equation*}
\tilde{P}=i\left(y \cdot \xi-\partial_{x} V(x) \cdot D_{y}\right)^{\operatorname{Wick}(x)}+\left(B(y) D_{y}\right)^{*} \cdot B(y) D_{y}+F(y) . \tag{66}
\end{equation*}
$$

## Proof

We prove this proposition in three steps. In what follows let $u \in \mathcal{S}\left(\mathbb{R}_{x, y}^{6}\right)$, and use the notation $X=(x, \xi)$.

Step 1. Let $\lambda$ be given in (28). Then for any $f \in \mathcal{S}\left(\mathbb{R}_{x, \xi, y}^{9}\right)$, we have, by (32),

$$
\begin{aligned}
& \left\|\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(\mathrm{y})} f(X, \cdot)\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)} \\
& \quad \lesssim\left\|\left(\lambda^{2 / 3}\right)^{w(y)} f(X, \cdot)\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)}+\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} f(X, \cdot)\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)} \\
& \quad+\left\|\langle\xi\rangle^{2 / 3} f(X, \cdot)\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)} .
\end{aligned}
$$

This along with (29) gives for all $f \in \mathcal{S}\left(\mathbb{R}_{x, \xi, y}^{9}\right)$,

$$
\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} f\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)}+\left\|\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} f\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)} \lesssim\left\|P_{X} f\right\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)}+\|f\|_{L^{2}\left(\mathbb{R}_{y}^{3}\right)},
$$

which holds uniformly with respect to $(x, \xi)$. Integrating both sides of the above estimate over $\mathbb{R}_{x, \xi}^{6}$ yields, for all $f \in \mathcal{S}\left(\mathbb{R}_{x, \xi, y}^{9}\right)$,

$$
\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} f\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} f\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \lesssim\left\|P_{X} f\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\|f\|_{L^{2}\left(\mathbb{R}^{9}\right)}
$$

In particular, for any $u \in \mathcal{S}\left(\mathbb{R}_{x, y}^{6}\right)$, applying the above inequality to the function $W_{x} u$, with $W_{x}$ the wave-packets transform only in the $(x, \xi)$ variables, we have

$$
\begin{aligned}
& \left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \\
& \quad \lesssim\left\|P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} .
\end{aligned}
$$

Note that the operator $\pi_{\mathcal{H}}=W_{x} W_{x}^{*}$ is an orthogonal projection on a closed space in $L^{2}$; then from the above inequality it follows that

$$
\begin{aligned}
\left\|W_{x} W_{x}^{*}\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} & \lesssim\left\|\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \\
& \leq\left\|P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} .
\end{aligned}
$$

On the other hand, by (13) we see

$$
\begin{aligned}
\left\|W_{x} W_{x}^{*}\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} & =\left\|W_{x}^{*}\left(\lambda^{2 / 3}\right)^{\operatorname{Wick}(y)} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{6}\right)} \\
& =\left\|\left(\lambda^{2 / 3}\right)^{\text {Wick }} u\right\|_{L^{2}\left(\mathbb{R}^{6}\right)},
\end{aligned}
$$

where the last equality follows from the relation

$$
W_{x}^{*} W_{y}^{*} \lambda^{2 / 3} W_{y} W_{x}=W^{*} \lambda^{2 / 3} W .
$$

Then the above inequalities yield

$$
\begin{align*}
& \left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|\left(\lambda^{2 / 3}\right)^{\text {Wick }} u\right\|_{L^{2}\left(\mathbb{R}^{6}\right)} \\
& \quad \lesssim\left\|P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}  \tag{67}\\
& \quad \lesssim\left\|\pi_{\mathcal{H}} P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|\left(1-\pi_{\mathcal{H}}\right) P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\|u\|_{L^{2}\left(\mathbb{R}^{6}\right)} .
\end{align*}
$$

Using (13) again, we have

$$
\begin{aligned}
\left\|\pi_{\mathcal{H}} P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}= & \left\|W_{x} W_{x}^{*} P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}=\left\|W_{x}^{*} P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{6}\right)} \\
= & \|\left[W_{x}^{*}\left(i y \cdot \xi-i \partial_{x} V(x) \cdot D_{y}\right) W_{x}\right. \\
& \left.+W_{x}^{*}\left(\left(B(y) D_{y}\right)^{*} B(y) D_{y}+F(y)\right) W_{x}\right] u \|_{L^{2}\left(\mathbb{R}^{6}\right)},
\end{aligned}
$$

and thus, with $\tilde{P}$ given in (66),

$$
\begin{equation*}
\left\|\pi_{\mathcal{H}} P_{X} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}=\|\tilde{P} u\|_{L^{2}\left(\mathbb{R}^{6}\right)} \tag{68}
\end{equation*}
$$

due to the relation

$$
W_{x}^{*}\left(\left(B(y) D_{y}\right)^{*} B(y) D_{y}+F(y)\right) W_{x}=\left(B(y) D_{y}\right)^{*} B(y) D_{y}+F(y),
$$

since $W_{x}^{*} W_{x}=\operatorname{Id}$ and $\left(B(y) D_{y}\right)^{*} B(y) D_{y}+F(y)$ commutes with $W_{x}$. Moreover observe

$$
\left(1-\pi_{\mathcal{H}}\right)\left(\left(B(y) D_{y}\right)^{*} B(y) D_{y}+F(y)\right) W_{x}=0,
$$

since $\left(1-\pi_{\mathcal{H}}\right) W_{x}=W_{x}\left(\operatorname{Id}-W_{x}^{*} W_{x}\right)=0$. Thus

$$
\begin{aligned}
\left(1-\pi_{\mathcal{H}}\right) P_{X} W_{x} & =\left(i y \cdot \xi-i \partial_{x} V(x) \cdot D_{y}\right) W_{x}-W_{x} W_{x}^{*}\left(i y \cdot \xi-i \partial_{x} V(x) \cdot D_{y}\right) W_{x} \\
& =-\left[W_{x} W_{x}^{*}, i y \cdot \xi-i \partial_{x} V(x) \cdot D_{y}\right] W_{x} .
\end{aligned}
$$

This along with (67) and (68) gives

$$
\begin{align*}
& \left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}+\left\|\left(\lambda^{2 / 3}\right)^{\text {Wick }} u\right\|_{L^{2}\left(\mathbb{R}^{6}\right)} \\
& \quad \lesssim\|\tilde{P} u\|_{L^{2}\left(\mathbb{R}^{6}\right)}+\|u\|_{L^{2}\left(\mathbb{R}^{6}\right)}+\left\|\left[\pi_{H}, y \cdot \xi-\partial_{x} V(x) \cdot D_{y}\right] W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} . \tag{69}
\end{align*}
$$

Step 2. In this step we deal with the last term in (69), and we show that for $\varepsilon>0$ there exists a constant $C_{\varepsilon}$ such that

$$
\begin{equation*}
\left\|\left[\pi_{\mathcal{H}}, y \cdot \xi\right] W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \lesssim\|P u\|_{L^{2}\left(\mathbb{R}^{6}\right)}+\|u\|_{L^{2}\left(\mathbb{R}^{6}\right)} \tag{70}
\end{equation*}
$$

and

$$
\begin{align*}
\left\|\left[\pi_{\mathcal{H}}, \partial_{x} V(x) \cdot D_{y}\right] W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \leq & \varepsilon\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}  \tag{71}\\
& +C_{\varepsilon}\left(\|P u\|_{L^{2}\left(\mathbb{R}^{6}\right)}+\|u\|_{L^{2}\left(\mathbb{R}^{6}\right)}\right) . \tag{72}
\end{align*}
$$

Let us first prove (70). In view of (14) we see that the kernel of the commutator $\left[\pi_{\mathcal{H}}, y \cdot \xi\right]$ is given by

$$
K_{1}(X, \tilde{X})=K_{1}((x, \xi),(\tilde{x}, \tilde{\xi}))=e^{-\pi / 2\left(|x-\tilde{x}|^{2}+|\xi-\tilde{\xi}|^{2}\right)} e^{i \pi(x-\tilde{x}) \cdot(\xi+\tilde{\xi})}(y \cdot \tilde{\xi}-y \cdot \xi) .
$$

Then

$$
\left|K_{1}(X, \tilde{X})\right| \leq e^{-\pi / 2\left(|x-\tilde{x}|^{2}+|\xi-\tilde{\xi}|^{2}\right)}|\xi-\tilde{\xi}||y|,
$$

and thus

$$
\sup _{X \in \mathbb{R}^{6}} \int_{\mathbb{R}^{6}}\left|K_{1}(X, \tilde{X})\right| d \tilde{X}+\sup _{\tilde{X} \in \mathbb{R}^{6}} \int_{\mathbb{R}^{6}}\left|K_{1}(X, \tilde{X})\right| d X \lesssim|y| .
$$

Consequently using the Schur criterion we have

$$
\left\|\left[\pi_{\mathcal{H}}, y \cdot \xi\right] W_{x} u(\cdot, y)\right\|_{L^{2}\left(\mathbb{R}_{x, \xi}^{6}\right)} \lesssim|y|\left\|W_{x} u(\cdot, y)\right\|_{L^{2}\left(\mathbb{R}_{x, \xi}^{6}\right)}=|y|\|u(\cdot, y)\|_{L^{2}\left(\mathbb{R}_{x}^{3}\right)}
$$

the last equality following from (13). Integrating both sides with respect to $y$ gives

$$
\left\|\left[\pi_{\mathcal{H}}, y \cdot \xi\right] W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \lesssim\|\langle y\rangle u\|_{L^{2}\left(\mathbb{R}^{6}\right)}
$$

which along with (7) gives the desired estimate (70).
It remains to show (71). In view of (14) we see that the kernel of the commutator $\left[\pi_{\mathcal{H}}, \partial_{x} V(x) \cdot D_{y}\right]$ is given by

$$
K_{2}(X, \tilde{X})=\sum_{1 \leq j \leq 3} \tilde{K}_{2, j} \cdot D_{y_{j}},
$$

with

$$
\tilde{K}_{2, j}(X, \tilde{X})=e^{-\pi / 2\left(|x-\tilde{x}|^{2}+|\xi-\tilde{\xi}|^{2}\right)} e^{i \pi(x-\tilde{x}) \cdot(\xi+\tilde{\xi})}\left(\partial_{x_{j}} V(\tilde{x})-\partial_{x_{j}} V(x)\right) .
$$

Direct computation shows that

$$
\begin{aligned}
& \sup _{X \in \mathbb{R}^{6}} \int_{\mathbb{R}^{6}}\left|\tilde{K}_{2, j}(X, \tilde{X})\right|\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3} d \tilde{X} \\
& \quad+\sup _{\tilde{X} \in \mathbb{R}^{6}} \int_{\mathbb{R}^{6}}\left|\tilde{K}_{2, j}(X, \tilde{X})\right|\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3} d X \lesssim C,
\end{aligned}
$$

since

$$
\begin{aligned}
\left|\partial_{x} V(\tilde{x})-\partial_{x} V(x)\right| & \lesssim|x-\tilde{x}| \sum_{j, k} \int_{0}^{1}\left|\partial_{x_{j} x_{k}} V(x+\theta(\tilde{x}-x))\right| d \theta \\
& \lesssim|x-\tilde{x}| \int_{0}^{1}\langle x+\theta(\tilde{x}-x)\rangle^{M / 3} d \theta \\
& \lesssim C_{M}\langle x-\tilde{x}\rangle^{1+M / 3}\langle x\rangle^{M / 3} \\
& \lesssim C_{M}\langle x-\tilde{x}\rangle^{1+M / 3}\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}
\end{aligned}
$$

the second and the last inequalities using (10), and the third inequality holding because

$$
\langle x+\theta(\tilde{x}-x)\rangle^{M / 3} \leq C_{M}\langle\theta(\tilde{x}-x)\rangle^{M / 3}\langle x\rangle^{M / 3}
$$

with $C_{M}$ a constant depending only on $M$. Using again the Schur criterion for the kernel

$$
\tilde{K}_{2, j}(X, \tilde{X})\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3}
$$

implies

$$
\begin{aligned}
\left\|\left[\pi_{\mathcal{H}}, \partial_{x} V(x) \cdot D_{y}\right] W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} & \lesssim \sum_{j=1}^{3}\left\|\tilde{K}_{2, j} D_{y_{j}} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \\
& \lesssim\left\|\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}\left\langle D_{y}\right\rangle W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} .
\end{aligned}
$$

On the other hand, for any $\varepsilon>0$, we have

$$
\begin{aligned}
\left\|\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}\left\langle D_{y}\right\rangle W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \leq & \varepsilon\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)} \\
& +C_{\varepsilon}\left\|\left\langle D_{y}\right\rangle^{2} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}
\end{aligned}
$$

and moreover by (13) and (62),

$$
\left\|\left\langle D_{y}\right\rangle^{2} W_{x} u\right\|_{L^{2}\left(\mathbb{R}^{9}\right)}=\left\|\left\langle D_{y}\right\rangle^{2} u\right\|_{L^{2}\left(\mathbb{R}^{6}\right)} \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}} .
$$

Then (71) follows from the above inequalities.
Step 3. By virtue of (69), (70), and (71), the desired estimate (65) follows if we let the number $\varepsilon$ in (71) be small enough. The proof of Proposition 6.1 is thus complete.

End of the proof of Theorem 1.1
Now we are ready to prove the anisotropic estimate (11) in Theorem 1.1. This will occupy the rest of the section.

Step a. Using the inequality

$$
\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}} \lesssim\left\|\left(\lambda^{2 / 3}\right)^{\text {Wick }} u\right\|_{L^{2}}+\left\|\left(\left(\lambda^{2 / 3}\right)^{w}-\left(\lambda^{2 / 3}\right)^{\text {Wick }}\right) u\right\|_{L^{2}}
$$

we have, by (65),

$$
\begin{align*}
\left\|\left(\lambda^{2 / 3}\right)^{w} u\right\|_{L^{2}} & \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}}+\mathcal{R}_{1}+\|(P-\tilde{P}) u\|_{L^{2}}  \tag{73}\\
& \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}}+\mathcal{R}_{1}+\mathcal{R}_{2},
\end{align*}
$$

with

$$
\begin{aligned}
& \mathcal{R}_{1}=\left\|\left(\left(\lambda^{2 / 3}\right)^{w}-\left(\lambda^{2 / 3}\right)^{\text {Wick }}\right) u\right\|_{L^{2}}, \\
& \mathcal{R}_{2}=\left\|\left(\partial_{x} V(x)-\left(\partial_{x} V(x)\right)^{\text {Wick }(x)}\right) \cdot D_{y} u\right\|_{L^{2}} .
\end{aligned}
$$

Here we used the fact that

$$
\begin{aligned}
P-\tilde{P} & =i\left(y \cdot D_{x}-\partial_{x} V(x) \cdot D_{y}\right)-i\left(y \cdot \xi-\partial_{x} V(x) \cdot D_{y}\right)^{\operatorname{Wick}(x)} \\
& =-i \partial_{x} V(x) \cdot D_{y}+i\left(\partial_{x} V(x) \cdot D_{y}\right)^{\operatorname{Wick}(x)}
\end{aligned}
$$

the last equality holding because $y \cdot D_{x}-(y \cdot \xi)^{\text {Wick }(x)}=0$ due to (16) since the symbol $y \cdot \xi$ is a first-order polynomial in $(x, \xi)$.

Step b. In this step we show that

$$
\begin{equation*}
\left\|\left(\left(\lambda^{2 / 3}\right)^{w}-\left(\lambda^{2 / 3}\right)^{\text {Wick }}\right) u\right\|_{L^{2}} \leq\|P u\|_{L^{2}}+\|u\|_{L^{2}} . \tag{74}
\end{equation*}
$$

By (16),

$$
\left(\lambda^{2 / 3}\right)^{\text {Wick }}-\left(\lambda^{2 / 3}\right)^{w}=r^{w}
$$

with

$$
r(x, y, \xi, \eta)=r(Z)=\int_{0}^{1} \int_{\mathbb{R}^{12}}(1-\theta)\left(\lambda^{2 / 3}\right)^{\prime \prime}(Z+\theta \tilde{Z}) \tilde{Z}^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} d \theta
$$

Direct computation shows that if $|\alpha|+|\beta|+|\tilde{\alpha}|+|\tilde{\beta}| \geq 1$, then

$$
\left|\partial_{x}^{\alpha} \partial_{\xi}^{\beta} \partial_{y}^{\tilde{\alpha}} \partial_{\eta}^{\tilde{\beta}}\left(\lambda^{2 / 3}\right)\right| \leq C_{\alpha, \beta, \tilde{\alpha}, \tilde{\beta}}\left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3}+\langle y\rangle+\langle\eta\rangle\right)
$$

As a result we have, with $Z=(x, y, \xi, \eta)$ and $\tilde{Z}=(\tilde{x}, \tilde{y}, \tilde{\xi}, \tilde{\eta})$,

$$
\begin{equation*}
\left|\partial_{x}^{\alpha} \partial_{\xi}^{\beta} \partial_{y}^{\tilde{\alpha}} \partial_{\eta}^{\tilde{\beta}} r(Z)\right| \leq C_{\alpha, \beta, \tilde{\alpha}, \tilde{\beta}}\left(\mathcal{L}_{1}+\mathcal{L}_{2}+\mathcal{L}_{3}+\mathcal{L}_{4}\right) \tag{75}
\end{equation*}
$$

where the $\mathcal{L}_{j}$ 's are given by

$$
\begin{aligned}
& \mathcal{L}_{1}=\int_{0}^{1} \int_{\mathbb{R}^{12}}\left\langle\partial_{x} V(x+\theta \tilde{x})\right\rangle^{2 / 3}|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} d \theta \\
& \mathcal{L}_{2}=\int_{0}^{1} \int_{\mathbb{R}^{12}}\langle\xi+\theta \tilde{\xi}\rangle^{2 / 3}|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} d \theta \\
& \mathcal{L}_{3}=\int_{0}^{1} \int_{\mathbb{R}^{12}}\langle y+\theta \tilde{y}\rangle|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} d \theta \\
& \mathcal{L}_{4}=\int_{0}^{1} \int_{\mathbb{R}^{12}}\langle\eta+\theta \tilde{\eta}\rangle|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} d \theta
\end{aligned}
$$

As for the term $\mathcal{L}_{1}$, we use the condition (10) to compute

$$
\begin{aligned}
\mathcal{L}_{1} & \lesssim \int_{0}^{1} \int_{\mathbb{R}^{12}}\langle x+\theta \tilde{x}\rangle^{2 M / 3}|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} d \theta \\
& \lesssim \int_{\mathbb{R}^{12}}\langle x\rangle^{2 M / 3}\langle\tilde{x}\rangle^{2 M / 3}|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} \\
& \lesssim\langle x\rangle^{2 M / 3} \lesssim\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} .
\end{aligned}
$$

Using the inequality

$$
\langle\xi+\theta \tilde{\xi}\rangle^{2 / 3} \lesssim\langle\xi\rangle^{2 / 3}\langle\tilde{\xi}\rangle^{2 / 3},
$$

we have

$$
\mathcal{L}_{2} \lesssim\langle\xi\rangle^{2 / 3} \int_{\mathbb{R}^{12}}\langle\tilde{\xi}\rangle^{2 / 3}|\tilde{Z}|^{2} e^{-2 \pi|\tilde{Z}|^{2}} 2^{6} d \tilde{Z} \lesssim\langle\xi\rangle^{2 / 3}
$$

Similarly,

$$
\mathcal{L}_{3}+\mathcal{L}_{4} \lesssim\langle y\rangle+\langle\eta\rangle .
$$

It follows from (75) and the above estimates that
$r^{w}\left(\left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}+\langle\xi\rangle^{2 / 3}+\langle y\rangle+\langle\eta\rangle\right)^{-1}\right)^{w} \in \operatorname{Op}\left(S\left(1,|d x|^{2}+|d y|^{2}+|d \xi|^{2}+|d \eta|^{2}\right)\right)$,
and thus

$$
\begin{aligned}
\left\|r^{w} u\right\|_{L^{2}} \lesssim & \left\|\left(\left\langle\partial_{x} V(x)\right\rangle^{2 / 3}\right)^{w} u\right\|_{L^{2}}+\left\|\left(\langle\xi\rangle^{2 / 3}\right)^{w} u\right\|_{L^{2}} \\
& +\left\|\langle y\rangle^{w} u\right\|_{L^{2}}+\left\|\langle\eta\rangle^{w} u\right\|_{L^{2}}
\end{aligned}
$$

$$
\begin{aligned}
& \lesssim\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}+\left\|\left\langle D_{x}\right\rangle^{2 / 3} u\right\|_{L^{2}}+\|\langle y\rangle u\|_{L^{2}}+\left\|\left\langle D_{y}\right\rangle u\right\|_{L^{2}} \\
& \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}},
\end{aligned}
$$

the last inequality using (18), (62), and (7).
Step c. Supposing $V$ satisfies the assumption (10), we show

$$
\begin{equation*}
\left\|\left(\partial_{x} V(x)-\left(\partial_{x} V(x)\right)^{\operatorname{Wick}(x)}\right) \cdot D_{y} u\right\|_{L^{2}} \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}} . \tag{76}
\end{equation*}
$$

In fact, for each $1 \leq j \leq 3$, one has, by (16),

$$
\begin{array}{rl}
\partial_{x_{j}} V & V(x)-\left(\partial_{x_{j}} V(x)\right)^{\mathrm{Wick}(x)} \\
& =\left(\left(\partial_{x_{j}} V(x)\right)^{w(x)}-\left(\partial_{x_{j}} V(x)\right)^{\operatorname{Wick}(x)}\right)+\left(\partial_{x_{j}} V(x)-\left(\partial_{x_{j}} V(x)\right)^{w(x)}\right) \\
& =r_{j}^{w}+\tilde{r}_{j}^{w}
\end{array}
$$

with $\tilde{r}_{j} \in S\left(\left\langle\partial_{x} V(x)\right\rangle^{1 / 3},|d x|^{2}+|d \xi|^{2}\right)$ due to [17, Theorem 2.3.18], and

$$
r_{j}(x, \xi)=r(X)=\int_{0}^{1} \int_{\mathbb{R}^{6}}(1-\theta)\left(\partial_{x_{j}} V\right)^{\prime \prime}(x+\theta \tilde{x}) \tilde{x}^{2} e^{-2 \pi|\tilde{X}|^{2}} 2^{3} d \tilde{X} d \theta
$$

Applying (10) we have, for any $\alpha, \beta \in \mathbb{Z}_{+}^{3}$,

$$
\begin{aligned}
\left|\partial_{x}^{\alpha} \partial_{\xi}^{\beta} r_{j}(x, \xi)\right| & \lesssim \int_{0}^{1} \int_{\mathbb{R}^{6}}\langle x+\theta \tilde{x}\rangle^{M / 3}|\tilde{x}|^{2} e^{-2 \pi|\tilde{X}|^{2}} 2^{3} d \tilde{X} d \theta \\
& \lesssim\langle x\rangle^{M / 3} \int_{\mathbb{R}^{6}}\langle\tilde{x}\rangle^{M / 3}|\tilde{x}|^{2} e^{-2 \pi|\tilde{X}|^{2}} 2^{3} d \tilde{X} \\
& \lesssim\left\langle\partial_{x} V(x)\right\rangle^{1 / 3} .
\end{aligned}
$$

It then follows that

$$
\tilde{r}_{j}^{w}\left(\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3}\right)^{w}, r_{j}^{w}\left(\left\langle\partial_{x} V(x)\right\rangle^{-1 / 3}\right)^{w} \in \mathrm{Op}\left(S\left(1,|d x|^{2}+|d \xi|^{2}\right)\right),
$$

and thus

$$
\begin{aligned}
\left\|r_{j}^{w} D_{y_{j}} u\right\|_{L^{2}}+\left\|\tilde{r}_{j}^{w} D_{y_{j}} u\right\|_{L^{2}} & \lesssim\left\|\left\langle\partial_{x} V(x)\right\rangle^{1 / 3}\left\langle D_{y}\right\rangle u\right\|_{L^{2}} \\
& \lesssim\left\|\left\langle\partial_{x} V(x)\right\rangle^{2 / 3} u\right\|_{L^{2}}+\left\|\left\langle D_{x}\right\rangle^{2} u\right\|_{L^{2}} \\
& \lesssim\|P u\|_{L^{2}}+\|u\|_{L^{2}},
\end{aligned}
$$

the last inequality using (18). The estimate (76) follows.
Step d. Combining (73), (74), and (76), we get the desired estimate (11), completing the proof of Theorem 1.1.

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