Algebraically independent generators of invariant differential operators on a bounded symmetric domain

Dedicated to Professor Nobuhiko Tatsuuma on his 60th birthday

By

Takaaki Nomura

Introduction

Let \mathscr{D} be a bounded symmetric domain in a finite dimensional complex vector space V. We denote by G the identity component of the Lie group of holomorphic automorphisms of \mathscr{D} . Then, G is semisimple and acts transitively on \mathscr{D} . Regarding \mathscr{D} as a Riemannian symmetric space, one knows that the algebra $D(\mathscr{D})^G$ of G-invariant differential operators on \mathscr{D} is isomorphic to a polynomial algebra of r indeterminates, where r is the real rank of G, cf. [1, p. 277].

On the other hand, it is now widely known that the category of (circled) bounded symmetric domains is equivalent to a certain category of Jordan triple systems, [2], [4], [7, p.85] and [10, §2]. An advantage of the shift from Lie theoretic methods to Jordan theoretic ones is a transparent and an elementary description of the structure of bounded symmetric domains. This motivates an investigation of $D(\mathcal{D})^G$ by making use of Jordan triple systems and the purpose of this paper is, in the same spirit as [6], to give explicitly a set of algebraically independent generators of $D(\mathcal{D})^G$ without using the classification of \mathcal{D} .

Let us explain the content of this paper. A Jordan triple system (JTS for short) over **R** is a real vector space V equipped with a trilinear mapping $\{\cdot,\cdot,\cdot\}$: $V \times V \times V \to V$ such that

$$\{u, v, w\} = \{w, v, u\},\$$

$$(0.2) \{a, b, \{u, v, w\}\} - \{u, v, \{a, b, w\}\} = \{\{a, b, u\}, v, w\} - \{u, \{b, a, v\}, w\}$$

hold for all $u, v, w, a, b \in V$. A real JTS V is said to be hermitian if

- (1) V is a complex vector space,
- (2) $\{u, v, w\}$ is C-linear in u, w and C-antilinear in v.

Let V be a hermitian JTS. We define C-linear operators $u \square v$ $(u, v \in V)$ and C-antilinear operators Q(z) $(z \in V)$ on V by

$$(0.3) (u \square v)w = \{u, v, w\},$$

(0.4)
$$Q(z)w = \{z, w, z\}.$$

We note here that (0.2) is rewritten as

$$(0.5) \qquad \qquad \lceil a \, \Box \, b, \, u \, \Box \, v \rceil = ((a \, \Box \, b)u) \, \Box \, v - u \, \Box \, ((b \, \Box \, a)v),$$

where [A, B] = AB - BA for two operators A, B. Now, V is said to be positive if $(u, v) := \operatorname{tr}(u \square v)$ defines a (positive definite) hermitian inner product on V. Let V be positive. We know that $z \square z$ ($z \in V$) is a positive semi-definite hermitian operator. Letting $(z \square z)^{1/2}$ be the positive semi-definite square root of $z \square z$, we set

Then, as the notation indicates, $\|\cdot\|_{\infty}$ becomes a norm on V (cf. [4, 3.17]), called the *spectral norm*. Let

$$\mathscr{D} := \{ z \in V; \|z\|_{\infty} < 1 \}.$$

Then, \mathcal{D} is a (circled) bounded symmetric domain and every bounded symmetric domain arises in this way. Let G be the identity component of the Lie group of holomorphic automorphisms of \mathcal{D} and we denote by K the stabilizer of G at 0.

Let B(z, w) $(z, w \in V)$ be the Bergman operator:

$$(0.7) B(z, w) := I - 2z \square w + Q(z)Q(w).$$

One knows that if $z \in \mathcal{D}$, then B(z, z) is a positive definite hermitian operator. Assume further that V is simple and of rank r. Let $\operatorname{Pol}(V^{\mathbf{R}})^K$ be the algebra of K-invariant polynomial functions on the underlying real vector space $V^{\mathbf{R}}$ of V and consider the polynomial functions f_i ($1 \le j \le r$) on $V^{\mathbf{R}}$ defined by

$$f_j(v) := \frac{2}{q}(v^{(2j-1)}, v),$$

where q is the genus of V defined by (1.7) and $v^{(2j-1)}$ are the odd powers of v defined by (3.2). These f_i are shown to be real valued. Then,

Theorem 1. The r polynomial functions f_1, \ldots, f_r are algebraically independent generators of $Pol(V^R)^K$.

Theorem 2. (1) For each j $(1 \le j \le r)$, there is a polynomial function p_j on $V^{\mathbf{R}} \times V^{\mathbf{R}}$ such that

$$f_i(B(z, z)^{1/2}v) = p_i(z, v) \quad (z \in \mathcal{D}, v \in V).$$

- (2) These p_j are G-invariant functions on the cotangent bundle $T^*(\mathcal{D}) \approx \mathcal{D} \times V^{\mathbf{R}}$.
- (3) The r differential operators $p_j(x, \partial/\partial x)$ form algebraically independent generators of $\mathbf{D}(\mathcal{D})^G$.

An explicit expression for p_j is also given (see Proposition 3.5). Let $Pol(V^{\mathbf{R}} \times V^{\mathbf{R}})^G$ be the algebra of polynomial functions on $V^{\mathbf{R}} \times V^{\mathbf{R}}$ whose

restrictions to $\mathscr{D} \times V^{\mathbb{R}} \approx T^*(\mathscr{D})$ are G-invariant. Then,

Theorem 3. The mapping $Pol(V^{\mathbf{R}})^{\mathbf{K}} \ni f \mapsto \Phi f$, where

$$\Phi f(z, w) := f(B(z, z)^{1/2} w) \quad (z \in \mathcal{D}, w \in V),$$

defines an algebra isomorphism of $Pol(V^R)^K$ onto $Pol(V^R \times V^R)^G$.

Notation. Let V be a finite dimensional complex vector space. Its underlying real vector space will be written as $V^{\mathbf{R}}$. We identify naturally the tangent spaces $T_v(V^{\mathbf{R}})$ at $v \in V$ with $V^{\mathbf{R}}$. Let W be another finite dimensional complex vector space. Let $\mathscr D$ be an open subset in V. If f is a W-valued C^{∞} -function defined on $\mathscr D$, then its tangent mapping $d_z f \colon V^{\mathbf{R}} \to W^{\mathbf{R}}$ at $z \in \mathscr D$ is defined by

$$d_z f(v) := \frac{d}{dt} f(z + tv)|_{t=0}.$$

We set

$$\partial_z f(v) := \frac{1}{2} \left[(d_z f)(v) - i(d_z f)(iv) \right],$$

$$\overline{\partial}_z f(v) := \frac{1}{2} \left[(d_z f)(v) + i (d_z f)(iv) \right].$$

Then, $d_z f = \partial_z f + \overline{\partial}_z f$ and it is clear that $v \mapsto \partial_z f(v)$ (resp. $v \mapsto \overline{\partial}_z f(v)$) is C-linear (resp. C-antilinear). Moreover, by Cauchy-Riemann equations, f is holomorphic if and only if $\overline{\partial}_z f = 0$ for all $z \in \mathcal{D}$, the latter being equivalent to saying that $v \mapsto d_z f(v)$ is C-linear.

§ 1. Preliminaries

We summarize here fundamental facts of JTS. Their proofs can be found in [4], [8], for example.

1.1. Let V be a simple positive hermitian JTS. Then,

$$(1.1) (u, v) := \operatorname{tr}(u \square v)$$

defines a hermitian inner product on V. For every linear operator T on V, we denote by T^* its adjoint operator: $(Tu, v) = (u, T^*v)$. Then, by (0.5) we have

$$(1.2) (z \square w)^* = w \square z (z, w \in V),$$

and this gives

$$(Q(z)u, v) = \overline{(u, Q(z)v)}.$$

Moreover, by [8, 18.2], we have

$$Q(v)(u \square v) = (v \square u)Q(v).$$

An element $c \in V$ is called a tripotent if $\{c, c, c\} = c$. Every tripotent c gives an orthogonal direct sum decomposition of V (the *Peirce decomposition* of V relative to c):

$$V = V_0(c) \oplus V_{1/2}(c) \oplus V_1(c),$$

$$V_j(c) := \{ v \in V; (c \square c)v = jv \} \quad (j = 0, 1/2, 1).$$

Two tripotents c_1 , c_2 are said to be orthogonal if $c \square c = 0$. Every element $v \in V$ has the spectral decomposition:

$$(1.5) v = \lambda_1 c_1 + \dots + \lambda_n c_n \quad (0 < \lambda_1 < \dots < \lambda_n),$$

with $\{c_1, \ldots, c_n\}$ a family of orthogonal tripotents. Let $\{c_1, \ldots, c_n\}$ be a family of orthogonal tripotents. By (0.1), (0.5) and (1.2), $\{c_i \square c_i; 1 \le i \le n\}$ is a commutative family of selfadjoint operators, so that we have a simultaneous eigenspace decomposition (called the *Peirce decomposition* relative to $\{c_1, \ldots, c_n\}$):

$$(1.6) V = \bigoplus_{0 \le i \le j \le n} V_{ij} (orthogonal direct sum),$$

where

$$V_{ij} := \left\{ v \in V; (c_k \square c_k) v = \frac{1}{2} (\delta_{ik} + \delta_{jk}) v \quad \text{for} \quad 1 \le k \le n \right\}.$$

A tripotent c is said to be primitive if c cannot be written as a sum of two non-zero orthogonal tripotents. A maximal orthogonal system of primitive tripotents is called a *frame*. Then, if $\{c_1, \ldots, c_r\}$ is a frame, r equals, by definition, the *rank* of V. We assume from now on that V is of rank r. Let $V = \bigoplus_{0 \le i \le j \le r} V_{ij}$ be the Peirce decomposition (1.6) relative to a frame $\{c_1, \ldots, c_r\}$. Then, $V_{00} = \{0\}$ and $V_{ii} = Cc_i$. Furthermore, V_{ij} ($1 \le i < j \le r$) all have the same dimension and we put

$$a := \dim V_{ii}$$
 $(1 \le i < j \le r)$.

Since dim V_{0i} $(1 \le i \le r)$ are also all equal, we set

$$b := \dim V_{0i} \quad (1 \le i \le r).$$

The number

$$q := 2 + a(r - 1) + b$$

is called the genus of V.

Let GL(V) be the complex Lie group of complex linear automorphisms of V, and we denote by Aut V the automorphism group of V:

Aut
$$V := \{g \in GL(V); g\{u, v, w\} = \{gu, gv, gw\} \text{ for all } u, v, w \in V\}.$$

Then, Aut $V \subset U(V)$, where U(V) is the unitary group of V relative to the inner

product (1.1). Thus Aut V is a compact Lie group.

1.2. Let \mathscr{D} be the open unit ball of V relative to the spectral norm $\|\cdot\|_{\infty}$ defined by (0.6). We remark here that the spectral norm is invariant under Aut V. The domain \mathscr{D} is a (circled) bounded symmetric domain in V and the symmetry at $0 \in \mathscr{D}$ is given by $z \mapsto -z$. Let B(z, w) be the Bergman operator defined by (0.7). Then, by (1.2) and (1.3), we have

$$(1.8) B(z, w)^* = B(w, z).$$

Let G be the identity component of the Lie group of holomorphic automorphisms of \mathcal{D} . Then, G is semisimple (and simple) and acts transitively on \mathcal{D} . We have

$$(1.9) B(gz, gw) = (d_zg)B(z, w)(d_wg)^* (g \in G, z, w \in \mathcal{D}).$$

We note also the following important identity (see [3, p. 21] or [8, 21.8]):

$$(1.10) Q(B(z, w)u) = B(z, w)Q(u)B(w, z) (z, w, u \in V).$$

Since B(z, z) is positive definite hermitian for $z \in \mathcal{D}$,

$$h_z(u, v) := (B(z, z)^{-1}u, v) \quad (z \in \mathcal{D}, u, v \in V)$$

defines a G-invariant hermitian structure on \mathcal{D} . Thus

(1.11)
$$b_z(u, v) := \text{Re } h_z(u, v)$$

defines a G-invariant Riemannian structure on \mathcal{D} .

1.3. Let $\mathfrak{X}_{hol}(\mathcal{D})$ denote the set of holomorphic vector fields on \mathcal{D} . Every orthonormal basis e_1, \ldots, e_n $(n = \dim V)$ of V relative to the inner product (1.1) gives rise to a coordinate system (z_1, \ldots, z_n) in V by $z = \sum z_i e_i$. Then, each $X \in \mathfrak{X}_{hol}(\mathcal{D})$ is written as

(1.12)
$$X = \sum_{i=1}^{n} h_i(z) \frac{\partial}{\partial z_i},$$

where h_i are holomorphic functions on \mathscr{D} . Let $\mathscr{O}(\mathscr{D}, V)$ be the space of V-valued holomorphic functions on \mathscr{D} . Putting $h(z) = \sum h_i(z)e_i$ in (1.12), we get $h \in \mathscr{O}(\mathscr{D}, V)$ and this h is independent of the choice of orthonormal basis of V. It is clear that the correspondence $\mathfrak{X}_{hol}(\mathscr{D}) \ni X \mapsto h \in \mathscr{O}(\mathscr{D}, V)$ is bijective. This being so, we write the vector field (1.12) as $X = h(z)\partial/\partial z$. Thus, if f is a holomorphic function on \mathscr{D} into another complex vector space W, we have

(1.13)
$$X f(z) = d_z f(h(z)).$$

The space $\mathfrak{X}_{hol}(\mathcal{D})$ is a Lie algebra by the Poisson bracket:

$$\left[h(z)\frac{\partial}{\partial z}, k(z)\frac{\partial}{\partial z}\right] := \left(d_z k(h(z)) - d_z h(k(z))\right)\frac{\partial}{\partial z}.$$

Let $\mathfrak{P}(V)$ be the algebra of holomorphic polynomial mappings of V into V. We denote by $\mathfrak{P}_{\nu}(V)$ the subspace of $\mathfrak{P}(V)$ of homogeneous polynomial mappings of degree ν . Then, $\mathfrak{P}(V)$ is an algebraic direct sum $\mathfrak{P}(V) = \bigoplus_{\nu=0}^{\infty} \mathfrak{P}_{\nu}(V)$. Clearly, we have $\mathfrak{P}(V) \subset \mathcal{O}(\mathcal{D}, V)$.

Now let g be the Lie algebra of G. Every $X \in \mathfrak{g}$ is considered as an element of $\mathfrak{X}_{hol}(\mathcal{D})$ by

$$X f(z) = \frac{d}{dt} f(\exp(-tX) \cdot z)|_{t=0},$$

where exp is the exponential mapping $\mathfrak{g} \to G$ and f a holomorphic function on \mathscr{D} . For every $v \in V$, we define $q_v \in \mathfrak{P}_2(V)$ and $\xi_v \in \mathfrak{P}_0(V) + \mathfrak{P}_2(V)$ by

$$(1.14) q_{v}(z) := Q(z)v,$$

(1.15)
$$\xi_{v}(z) := v - q_{v}(z).$$

Then the following proposition is known, [4, §4] or [10, §2].

Proposition 1.1. (1) If $X = h(z)\partial/\partial z \in \mathfrak{g}$, then $h \in \sum_{\nu=0}^{2} \mathfrak{P}_{\nu}(V)$.

- (2) Let K be the stabilizer of G at $0 \in \mathcal{D}$. Then, K is the identity component of Aut V.
 - (3) *Put*

$$f := \{ T(z)\partial/\partial z ; T \text{ is a derivation of } V \},$$

$$\mathfrak{p} := \{ \xi_v(z)\partial/\partial z ; v \in V \}.$$

Then, $\mathfrak{k} = \text{Lie } K$ and $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$ is a Cartan decomposition of \mathfrak{g} .

§ 2. Compactification of V

To realize the complexification $G_{\mathbf{c}}$ of G, we will introduce a compactification of V defined by Loos [4, § 7] (see also [5]). A pair (x, y) of elements of V is said to be *invertible* if the operator B(x, y) is invertible, that is, if det $B(x, y) \neq 0$. Note that (x, y) is invertible if and only if so is (y, x) by (1.8). If (x, y) is invertible, we set

$$(2.1) x^{y} := B(x, y)^{-1}(x - Q(x)y),$$

$$(2.2) (x, y)^{-1} := (x^{y}, -y).$$

We call x^y the quasi-inverse of (x, y). We have

(2.3)
$$B(x, y)^{-1} = B((x, y)^{-1}).$$

Lemma 2.1. If $z, w \in \mathcal{D}$, then (z, w) is invertible.

Proof. Note that since B(0, w) = I, (0, w) is invertible. Now, the transitivity of G on \mathcal{D} together with (1.9) proves the lemma.

We define a relation \sim in $V \times V$ by the following:

$$(x, y) \sim (x', y')$$
 if $(x, y - y')$ is invertible and $x' = x^{y-y'}$.

Then, \sim is an equivalence relation. Let X be the set of equivalence classes. The equivalence class of (x, y) will be denoted by (x: y). V is considered as a subset of X by the injective mapping $x \mapsto (x: 0)$. Then, $(x: y) \in V$ if and only if (x, y) is invertible. For each $v \in V$, let $U_v := \{(x: v); x \in V\}$. Then, by [4, 7.7], there is a unique structure of smooth algebraic variety on X such that U_v is an open affine subvariety, which is isomorphic to V under $(x: y) \mapsto x$. Moreover, X is a projective variety by [4, 7.10].

Considering X as a compact complex manifold, the complexification $G_{\mathbf{c}}$ of G is now realized as the (Zariski-) connected component of the identity of the group of holomorphic automorphisms of X. The Lie algebra $g_{\mathbf{c}}$ of $G_{\mathbf{c}}$ is the set of all holomorphic vector fields on X. By restriction, $g_{\mathbf{c}}$ may be considered as a Lie algebra of vector fields on V.

For every $v \in V$, let

(2.4)
$$\tilde{t}_{v}(x:a) := (x:a+v) \quad ((x:a) \in X).$$

Then, \tilde{t}_v is well defined and $\tilde{t}_v \in G_{\mathbb{C}}$. Clearly we have $\tilde{t}_{v_1} \tilde{t}_{v_2} = \tilde{t}_{v_1 + v_2}$. Let Str V denote the structure group of V:

Str
$$V := \{g \in GL(V); Q(gz) = gQ(z)g^* \text{ for all } z \in V\}.$$

We see easily that $g \in GL(V)$ belongs to Str V if and only if

$$q(z \square w)q^{-1} = (qz) \square (q^{*-1}w) \quad (z, w \in V).$$

This together with (1.2) shows that Str V is stable under $g \mapsto g^*$. Now, Str V acts on X by

$$h(x:a) := (hx:h^{*-1}a) \quad (h \in \text{Str } V, (x:a) \in X).$$

We denote by H the identity component of Str V. Thus H is considered as a subgroup of $G_{\mathbb{C}}$. It should be noted here that $K = H \cap U(V)$. Finally, for every $u \in V$, the translation $t_u \colon V \ni x \mapsto x + u \in V$ is uniquely extended to an element of $G_{\mathbb{C}}$. Let

$$U^+ := \{t_u; u \in V\}, \quad U^- := \{\tilde{t}_v; v \in V\}.$$

Then, U^{\pm} are abelian subgroups of $G_{\mathbf{c}}$, and a computation shows

$$ht_uh^{-1} = t_{hu}, \quad h\tilde{t}_vh^{-1} = \tilde{t}_{h^{*-1}v},$$

for all $h \in H$ and $u, v \in V$. We note here that if (x, y) is invertible, then (1.8) and (1.10) imply that $B(x, y) \in \text{Str } V$. Further, the identity (as elements of $G_{\mathbb{C}}$)

$$B(x, y) = \tilde{t}_{yx}t_{-x}\tilde{t}_{-y}t_{xy}$$
 (cf. [4, 8.11])

says that $B(x, y) \in H$.

The Lie algebras u^{\pm} of U^{\pm} are identified as

$$u^+ = \{\text{constant vector fields on } V\},\$$

$$\mathfrak{u}^- = \{q_v(z)\partial/\partial z \, ; \, v \in V\}.$$

Let \mathfrak{h} := Lie H. Then, we have a vector space direct sum of Lie subalgebras: $\mathfrak{g}_{\mathbf{c}} = \mathfrak{u}^+ + \mathfrak{h} + \mathfrak{u}^-$. Let

$$\mathcal{\Xi} := \{ g \in G_{\mathbf{C}}; g(0:0) \in V \}.$$

Then, $\Xi \approx U^+ \times H \times U^-$ and $G \subset \Xi$. For every $v \in V$, one has (cf. [4, 9.8])

(2.5)
$$\exp \left(\xi_{\nu}(z) \partial / \partial z \right) = t_{\tanh \nu} \cdot B(\tanh \nu, \tanh \nu)^{1/2} \cdot \tilde{t}_{-\tanh \nu},$$

with $B(\tanh v, \tanh v)^{1/2} \in H$, where if $v = \sum \lambda_i c_i$ is the spectral decomposition (1.4) of v, then $\tanh v := \sum (\tanh \lambda_i) c_i$. Thus, $\tanh v \in \mathcal{D}$ for any $v \in V$. The following proposition will be needed later.

Proposition 2.2. Put $g_v := \exp(\xi_v(z)\partial/\partial z) \in \exp \mathfrak{p}$ for each $v \in V$. Then,

- (1) $g_v \cdot 0 = \tanh v$,
- (2) $d_z g_v = B(\tanh v, \tanh v)^{1/2} B(z, -\tanh v)^{-1} \in H \text{ for every } z \in \mathcal{D}.$

Proof. Put $u = \tanh v \in \mathcal{D}$ for simplicity. Lemma 2.1 implies that if $z \in \mathcal{D}$, then (z, -u) is invertible. Hence

$$\tilde{t}_{-u}(z:0) = (z:-u) = (z^{-u}:0).$$

Thus, \tilde{t}_{-u} induces a holomorphic mapping $\mathcal{D} \ni z \mapsto z^{-u} \in V$.

- (1) Since $0^{-u} = 0$ by (2.1), the assertion follows from (2.5).
- (2) Let $z \in \mathcal{D}$, $x \in V$ and $s \in \mathbb{R}$. By [3, Theorem 3.7 (b)], we have

$$(z + sx)^{-u} = z^{-u} + B(z, -u)^{-1}(sx)^{(-u)^{z}},$$

provided |s| is sufficiently small. We put $y = (-u)^z$ for brevity. Since

$$(sx)^{y} = B(sx, y)^{-1}(sx - Q(sx)y) = sB(sx, y)^{-1}(x - sQ(x)y)$$
$$= s(I + sO(1))^{-1}(x - sQ(x)y) = s(x + sO(1)),$$

we get

$$(z + sx)^{-u} = z^{-u} + sB(z, -u)^{-1}(x + sO(1)).$$

Hence, $d_z \tilde{t}_{-u} = B(z, -u)^{-1}$. Now, the proposition follows from (2.5) and the chain rule.

§ 3. Invariant polynomial functions

We begin with the following two lemmas which are more or less known to JTS specialists.

Lemma 3.1. Let $\{c_1, ..., c_r\}$ be a frame and put $c := c_1 + \cdots + c_r$. Then, for every pair (j, l), there is $x \in V$ such that $T := B(x, c) \in H$ satisfies

$$T^2 = I$$
, $Tc_i = T^*c_i = c_l$, $Tc_m = T^*c_m = c_m$ for all $m \neq j$, l.

Proof. We put

$$\mathfrak{A}(c) := V_1(c) \cap \{x \in V; Q(c)x = x\}.$$

Then, by [4, 3.13 (c)], $\mathfrak{A}(c)$ is a formally real Jordan algebra with the product $xy := \{x, c, y\}$. Note that $c_m \in \mathfrak{A}(c)$ for all m. The proof of [3, 17.1] shows that for every pair (j, l), there is $x \in \mathfrak{A}(c)$ such that T := B(x, c) satisfies

$$T^2 = I$$
, $Tc_j = c_l$, $Tc_m = c_m$ for $m \neq j$, l .

Since $x \in \mathfrak{A}(c)$, we have $c \square x = x \square c$ by [4, 9.13]. Moreover, it holds that

$$Q(c)Q(x)c_m = Q(x)c_m = Q(x)Q(c)c_m$$
 for all m ,

where the first equality is the consequence of

$$Q(x)c_m = \{x, \{c, c_m, c\}, x\}$$

$$= -\{c_m, c, \{x, c, x\}\} + 2\{\{c_m, c, x\}, c, x\} \quad \text{(by (0.1), (0.2))}$$

$$= -c_m x^2 + 2(c_m x)x \in \mathfrak{A}(c).$$

The above observation yields

$$Tc_m = B(x, c)c_m = c_m - 2(x \square c)c_m + Q(x)Q(c)c_m$$

= $c_m - 2(c \square x)c_m + Q(c)Q(x)c_m = B(c, x)c_m = T^*c_m$

for all m. This proves the lemma.

Corollary 3.2. Let $\{c_1, \ldots, c_r\}$ be a frame. Then, for each permutation σ of r letters, there is $k \in K$ such that $kc_m = c_{\sigma(m)}$ for all m.

Proof. It suffices to show the corollary in the case where σ are transpositions. Let σ be the transposition of j, l and $T \in H$ be as in Lemma 3.1. Consider the polar decomposition T = U | T | of the operator T, where U is unitary and $|T| = (T^*T)^{1/2}$ positive definite selfadjoint. Since $T^* \in H$, we have $|T| = \exp(\frac{1}{2}\log T^*T) \in H$, so that $U \in H \cap U(V) = K$. Since $|T|c_m = c_m$ for all m, this U is a required one.

Lemma 3.3. Let $\{c_1, \ldots, c_r\}$, $\{d_1, \ldots, d_r\}$ be frames. Then, there is $k \in K$ such that $kc_m = d_m$ for all m.

Proof. The real subspaces

$$C := \sum_{m=1}^{r} \mathbf{R} c_m, \qquad D := \sum_{m=1}^{r} \mathbf{R} d_m$$

are maximal flat subspaces in the sense of [4, 3.10]. By [4, 5.3 (a)], there is $k_1 \in K$ such that $k_1(C) = D$. Since $k_1 \in Aut \ V$, $k_1 c_m$ are tripotents, so that the primitivity and the linear independence of c_m imply that there is a permutation σ of r letters such that $k_1 c_m = \pm d_{\sigma(m)}$ for all m. By Corollary 3.2, we get $k_2 \in K$ such that

$$(3.1) k_2 c_m = \pm d_m for all m.$$

On the other hand, (0.2) says that $i(c_j \Box c_j)$ are derivations of V. Put $k^{(j)} := \exp(\pi i (c_j \Box c_j)) \in K$. Then,

$$k^{(j)}c_{i} = -c_{i}, \quad k^{(j)}c_{m} = c_{m} \quad \text{for } m \neq j.$$

This together with (3.1) proves the lemma.

We will fix a frame $\{c_1, \ldots, c_r\}$ of V throughout the rest of this section. We define odd powers $v^{(2j-1)}$ $(j=1,2,\ldots)$ of an element $v \in V$ inductively by

(3.2)
$$v^{(1)} := v, \quad v^{(2j+1)} := Q(v)v^{(2j-1)} \quad (j = 1, 2, ...).$$

Clearly we have

(3.3)
$$v^{(2j+1)} = Q(v)^{j}v \quad (j = 1, 2, ...).$$

An easy induction argument using (1.4) and (3.3) shows

$$(3.4) v^{(2j+1)} = (v \square v)^j v \quad (j=1, 2, \ldots).$$

Letting q be the genus of V defined by (1.7), we normalize the inner product (1.1) as

$$(u, v)_0 := \frac{2}{q}(u, v).$$

Then, since

(3.5)
$$\operatorname{tr}(c_m \square c_m) = 1 + \frac{b}{2} + \frac{1}{2}a(r-1) = \frac{q}{2} \quad \text{for all } m,$$

the normalization of the inner product is made so that the norm of c_m is one for every m. We put

(3.6)
$$f_j(v) := (v^{(2j-1)}, v)_0 \quad (j = 1, 2, ...).$$

We note that by (3.4) and (1.2), each f_j is real valued. Since $Q(kv) = kQ(v)k^{-1}$ for all $k \in K$ and $v \in V$, it is clear from (3.3) that $f_j \in \operatorname{Pol}(V^{\mathbb{R}})^K$. We note also that if λ_m are all real, then

(3.7)
$$f_j(\sum_{m=1}^r \lambda_m c_m) = \frac{2}{q} \operatorname{tr} \sum_{m=1}^r \lambda_m^{2j} c_m \square c_m = \sum_{m=1}^r \lambda_m^{2j}$$
 (by (3.5)).

Theorem 3.4. The polynomial functions f_j $(1 \le j \le r)$ form algebraically independent generators of $\operatorname{Pol}(V^R)^K$.

Proof. Let $f \in Pol(V^{\mathbb{R}})^K$ and consider the polynomial

$$F(\lambda_1,\ldots,\lambda_r):=f(\sum_{m=1}^r \lambda_m c_m) \quad (\lambda_m \in \mathbb{R}).$$

Take the frames $\{\varepsilon_1 c_1, \dots, \varepsilon_r c_r\}$ with $\varepsilon_j \in \{-1, 1\}$. Then, since f is K-invariant, Lemma 3.3 implies that F is of the form

$$F(\lambda_1,\ldots,\lambda_r)=F_0(\lambda_1^2,\ldots,\lambda_r^2)$$

for some polynomial F_0 . Let σ be an arbitrary permutation of r letters. Then, Corollary 3.2 and the K-invariance of f say that the polynomial F_0 is invariant under σ . Hence, there is a polynomial P of r variables such that

(3.8)
$$f(\sum_{m=1}^{r} \lambda_m c_m) = P(\sum_{m=1}^{r} \lambda_m^2, \dots, \sum_{m=1}^{r} \lambda_m^{2j}, \dots, \sum_{m=1}^{r} \lambda_m^{2r}).$$

Now, consider the polynomial function

$$R(v) := f(v) - P(f_1(v), \dots, f_r(v)) \quad (v \in V^{\mathbf{R}}),$$

where f_j are defined by (3.6). We have $R \in \operatorname{Pol}(V^{\mathbf{R}})^K$. Let $v \in V$ be arbitrary and consider its spectral decomposition: $v = \sum_{j=1}^n \mu_j d_j$. If the tripotent $d := \sum_{j=1}^n d_j$ is not maximal, then choose a tripotent $d' \in V_0(d)$, the Peirce 0-space of d, so that $d^0 := d + d'$ is a maximal tripotent. Anyhow, the spectral decomposition is refined as $v = \sum_{m=1}^r \lambda_m d_m^0$ with a frame $\{d_1^0, \ldots, d_r^0\}$ and $0 \le \lambda_1 \le \cdots \le \lambda_r$. Then, by Lemma 3.3, there is $k \in K$ such that $k d_m^0 = c_m$ for all m. Hence $kv = \sum_{j=1}^r \lambda_j c_j$. This together with (3.7) and (3.8) yields R = 0. Since the polynomials $\sum_m \lambda_m^j$ ($1 \le j \le r$) are algebraically independent as is well known, so are f_1, \ldots, f_r by (3.7).

We now make G act on $\mathscr{D} \times V^{\mathbf{R}}$ by

$$(3.9) g \cdot (z, w) := (gz, (d_z g)^{*-1} w) \quad (z \in \mathcal{D}, w \in V).$$

Let $\operatorname{Pol}(V^{\mathbf{R}} \times V^{\mathbf{R}})^G$ be the algebra of polynomial functions on $V^{\mathbf{R}} \times V^{\mathbf{R}}$ whose restrictions to $\mathscr{D} \times V^{\mathbf{R}}$ are invariant under the action of G defined by (3.9). We will define an injective mapping of $\operatorname{Pol}(V^{\mathbf{R}})^K$ into $\operatorname{Pol}(V^{\mathbf{R}} \times V^{\mathbf{R}})^G$.

Let $f_j \in \text{Pol}(V^{\mathbb{R}})^K$ be as in (3.6) and recall that B(z, z) is positive definite hermitian for $z \in \mathcal{D}$.

Proposition 3.5. For each j $(1 \le j \le r)$, there is a unique polynomial function $p_j \in \operatorname{Pol}(V^{\mathbf{R}} \times V^{\mathbf{R}})^G$ such that

(3.10)
$$f_i(B(z, z)^{1/2}v) = p_i(z, v) \quad (z \in \mathcal{D}, v \in V).$$

Moreover, these p_i are given as

(3.11)
$$p_j(z, v) = ((Q(v)B(z, z))^{j-1}v, B(z, z)v)_0 \quad (j = 1, 2, ...).$$

Remark 3.6. It is interesting to show directly that the right hand side of (3.11) is real. By (1.3), this is clear if j is odd. To see the case j = 2m, we note

$$B(z, z)(Q(v)B(z, z))^{2m-1}v$$

$$= (Q(B(z, z)v)Q(v))^{m-1}Q(B(z, z)v)v$$
 (by (1.10))
$$= (Q(B(z, z)v)Q(v))^{m-1}((B(z, z)v)\Box v)B(z, z)v$$

$$= ((B(z, z)v)\Box v)(Q(B(z, z)v)Q(v))^{m-1}B(z, z)v$$
 (by (1.4)).

Hence, we get

$$((Q(v)B(z, z))^{2m-1}v, B(z, z)v)_{0}$$

$$= ((Q(B(z, z)v)Q(v))^{m-1}B(z, z)v, (v \square B(z, z)v)v)_{0}$$

$$= ((Q(B(z, z)v)Q(v))^{m-1}B(z, z)v, Q(v)B(z, z)v)_{0}$$

$$= \overline{((Q(v)B(z, z))^{2m-1}v, B(z, z)v)_{0}}$$
 (by (1.3), (1.10)).

Proof of Proposition 3.5. Since \mathcal{D} is open in V, the uniqueness is clear. Let $z \in \mathcal{D}$ and $v \in V$. Since $B(z, z)^{1/2} \in \operatorname{Str} V$, we have

$$Q(B(z, z)^{1/2}v) = B(z, z)^{1/2}Q(v)B(z, z)^{1/2}.$$

Then, by (3.6), (3.3) and (3.12), we get

$$\begin{split} f_j(B(z,\,z)^{1/2}v) &= (Q(B(z,\,z)^{1/2}v)^{j-1}B(z,\,z)^{1/2}v,\,\,B(z,\,z)^{1/2}v)_0 \\ &= (B(z,\,z)^{1/2}(Q(v)B(z,\,z))^{j-1}v,\,\,B(z,\,z)^{1/2}v)_0 \\ &= p_j(z,\,v). \end{split}$$

Hence, it remains to prove that p_j are G-invariant. For this, we need the following lemma.

Lemma 3.7. If $g \in G$, then $d_z g \in H$ for all $z \in \mathcal{D}$, where H is the identity component of Str V.

Proof. Let us write g as $g = kg_v$ with $k \in K$, $v \in V$ and g_v as in Proposition 2.2. By chain rule, it suffices to show Lemma 3.7 for g = k and g_v separately. Suppose $g = k \in K$. Then, k is C-linear, so that $d_z k = k$ for all $z \in \mathcal{D}$. Therefore, $d_z k \in K \subset H$. Let $g = g_v \in \exp \mathfrak{p}$. Then, Proposition 2.2 (2) says that $d_z g_v \in H$.

Let us return to the proof of Proposition 3.5. Let $g \in G$, $z \in \mathcal{D}$ and $v \in V$. Since H is stable under $T \mapsto T^*$, Lemma 3.7 yields

$$Q((d_zg)^{*-1}v) = (d_zg)^{*-1}Q(v)(d_zg)^{-1}.$$

This together with (1.9) completes the proof.

Proposition 3.8. The mapping $\operatorname{Pol}(V^{\mathbf{R}})^K \ni f \mapsto \Phi f$, where $\Phi f(z, v) := f(B(z, z)^{1/2} v) \quad (z \in \mathcal{D}, v \in V)$

defines an injection of $Pol(V^{\mathbf{R}})$ into $Pol(V^{\mathbf{R}} \times V^{\mathbf{R}})^{G}$.

Proof. The injectivity follows from $f(v) = \Phi f(0, v)$. If $f \in Pol(V^{\mathbb{R}})^K$, then write f as a polynomial of f_1, \ldots, f_r by Theorem 3.4. Then, Φf is a polynomial of p_1, \ldots, p_r in Propositin 3.5.

We establish the surjectivity of $f \mapsto \Phi f$ in the next section.

§ 4. G-invariant differential operators on \mathcal{D}

Let $T^*(\mathcal{D}) \approx \mathcal{D} \times V^{\mathbf{R}}$ be the cotangent bundle of \mathcal{D} with the natural G-action:

(4.1)
$$g \cdot (z, w) = (gz, (d_z g)^{*-1} w) \quad (g \in G, z \in \mathcal{D}, w \in V).$$

If $L \in C^{\infty}(\mathcal{D} \times V^{\mathbb{R}})$ and if $V^{\mathbb{R}} \ni w \mapsto L(z, w)$ is polynomial for each fixed $z \in \mathcal{D}$, then we associate a differential operator $L(x, \partial/\partial x)$ with the property that

(4.2)
$$L(x, \partial/\partial x)e^{\langle x,y\rangle} = L(x, y)e^{\langle x,y\rangle} \quad (x \in \mathcal{D}, y \in V^{\mathbf{R}}),$$

where $\langle x, y \rangle := \text{Re}(x, y)_0$. In this way, one obtains every differential operator on \mathcal{D} with coefficients in $C^{\infty}(\mathcal{D})$.

The differential operator $L(x, \partial/\partial x)$ on \mathcal{D} is said to be *G-invariant*, if it commutes with the *G*-action:

$$qL(x, \partial/\partial x)q^{-1} = L(x, \partial/\partial x)$$
 for all $g \in G$.

It is easy to see that the differential operator $L(x, \partial/\partial x)$ is G-invariant if and only if the corresponding function L is invariant under the G-action defined by (4.1):

$$(4.3) L(gz, (d_zg)^{*-1}w) = L(z, w) (z \in \mathcal{D}, w \in V^{\mathbf{R}}).$$

Proposition 4.1. Let L(z, w) be C^{∞} in $z \in \mathcal{D}$ and polynomial in $w \in V^{\mathbb{R}}$. If L satisfies (4.3), then there is a polynomial P of r variables such that

$$L(z, w) = P(p_1(z, w), \dots, p_r(z, w)) \quad (z \in \mathcal{D}, w \in V^{\mathbf{R}}),$$

where $p_i \in Pol(V^{\mathbb{R}} \times V^{\mathbb{R}})^G$ are as in Proposition 3.5.

Proof. Set l(w) := L(0, w). Since every element of K is a unitary operator, we have $(d_z k)^{*-1} = k$ for all $z \in \mathcal{D}$ and $k \in K$. Hence (4.3) implies $l \in \operatorname{Pol}(V^{\mathbb{R}})^K$. By Theorem 3.4, there is a polynomial P of r variables such that

$$l(w) = P(f_1(w), \dots, f_r(w)) \quad (w \in V^{\mathbf{R}}).$$

Now, let $z \in \mathcal{D}$. Considering the spectral decomposition (1.5) of z, we see that there is $v \in V$ such that $z = \tanh v$. Let g_v be as in Proposition 2.2. Then, $g_v \cdot 0 = \tanh v = z$ and

$$(4.4) d_0 q_v = B(z, z)^{1/2}.$$

By virtue of the G-invariance (4.3) of L, we get

$$L(z, w) = L(g_v \cdot 0, (d_0 g_v)^{*-1} (d_0 g_v)^* w)$$

$$= L(0, B(z, z)^{1/2} w) = l(B(z, z)^{1/2} w) \quad \text{(by (4.4))}$$

$$= P(f_1(B(z, z)^{1/2} w), \dots, f_r(B(z, z)^{1/2} w))$$

$$= P(p_1(z, w), \dots, p_r(z, w)). \quad \blacksquare$$

Since \mathcal{D} is symmetric, we know that the algebra $D(\mathcal{D})^G$ of G-invariant differential operators on \mathcal{D} is commutative. Put

$$D_i = p_i(x, \partial/\partial x) \quad (j = 1, 2, ..., r).$$

By Proposition 3.5, we have $p_i \in Pol(V^{\mathbb{R}} \times V^{\mathbb{R}})^G$. Hence

$$D_i \in D(\mathcal{D})^G$$
 $(j = 1, 2, \dots, r).$

Lemma 4.2. D_1, \ldots, D_r are algebraically independent.

Proof. For any polynomial $q(x_1, ..., x_r)$ of r variables $x_1, ..., x_r$, we call the degree of $q(x_1, x_2^2, ..., x_r^r)$ the weight of q. Let now q be a polynomial of r variables such that $q(D_1, ..., D_r) = 0$. Suppose the weight of q is m. We denote by q_μ the sum of the monomials in q of weight μ . Then, $q = \sum_{\mu=0}^m q_\mu$. Let $t \in \mathbb{R}$. Since $y \mapsto p_j(x, y)$ is homogeneous of degree 2j, (4.2) yields

$$D_j e^{\langle x, ty \rangle} = t^{2j} p_j(x, y) e^{\langle x, ty \rangle}.$$

Then, we get

$$q_{\mu}(D_1, \dots, D_r)e^{\langle x, ty \rangle}$$

$$= e^{\langle x, ty \rangle} [t^{2\mu}q_{\mu}(p_1(x, y), \dots, p_r(x, y)) + \text{lower order terms in } t].$$

Hence

$$q(D_1, ..., D_r)e^{\langle x, ty \rangle}$$

$$= e^{\langle x, ty \rangle} [t^{2m} q_m(p_1(x, y), ..., p_r(x, y)) + \text{lower order terms in } t].$$

so that $q(D_1, ..., D_r) = 0$ leads us to

$$q_m(p_1(x, y), \dots, p_r(x, y)) = \frac{1}{(2m)!} \frac{d^{2m}}{dt^{2m}} e^{-\langle x, ty \rangle} q(D_1, \dots, D_r) e^{\langle x, ty \rangle} = 0$$

for all x, y. Putting x = 0, we obtain

$$q_m(f_1(y), \dots, f_r(y)) = q_m(p_1(0, y), \dots, p_r(0, y)) = 0.$$

This implies $q_m = 0$ by Theorem 3.4, whence q = 0.

We now arrive at two main theorems by virtue of Propositions 4.1, 3.8 and Lemma 4.2.

Theorem 4.3. D_1, \ldots, D_r form algebraically independent generators of $D(\mathcal{D})^G$.

Theorem 4.4. For every $f \in \text{Pol}(V^{\mathbb{R}})^K$, put

$$\Phi f(x, y) := f(B(x, x)^{1/2}y) \quad (x \in \mathcal{D}, y \in V).$$

Then, Φ defines an algebra isomorphism of Pol($V^{\mathbf{R}}$) onto Pol($V^{\mathbf{R}} \times V^{\mathbf{R}}$)^G.

DEPARTMENT OF MATHEMATICS KYOTO UNIVERSITY

References

- [1] S. Helgason, Groups and geometric analysis, Academic press, New York, 1984.
- [2] M. Koecher, An elementary approach to bounded symmetric domains, Lecture Notes, Rice Univ., 1969.
- [3] O. Loos, Jordan pairs, Lecture Notes in Math., 460, Springer, Berlin, 1975.
- [4] O. Loos, Bounded symmetric domains and Jordan pairs, Lecture Notes, Univ. California at Irvine, 1977.
- [5] O. Loos, Homogeneous algebraic varieties defined by Jordan pairs, Monatsh. Math., 86 (1978), 107-129.
- [6] T. Nomura, Algebraically independent generators of invariant differential operators on a symmetric cone, J. Reine Angew. Math., 400 (1989), 122-133.
- [7] I. Satake, Algebraic structures of symmetric domains, Iwanami Shoten and Princeton Univ. Press, Tokyo and Princeton, 1980.
- [8] H. Upmeier, Symmetric Banach manifolds and Jordan C*-algebras, North-Holland, Amster-dam, 1985.
- [9] H. Upmeier, Jordan algebras and harmonic analysis on symmetric spaces, Amer. J. Math., 108 (1986), 1-25.
- [10] H. Upmeier, Jordan algebras in analysis, operator theory and quantum mechanics, Regional Conf. in Math., 67, Amer. Math. Soc., Rhode Island, 1987.