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Upper bounds for the dimension of tori acting on GKM manifolds

By Shintarô Kuroki

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Abstract. The aim of this paper is to give an upper bound for the dimension of a torus T which acts on a GKM manifold M effectively. In order to do that, we introduce a free abelian group of finite rank, denoted by $\mathcal{A}(\Gamma, \alpha, \nabla)$, from an (abstract) (m, n)-type GKM graph (Γ, α, ∇) . Here, an (m, n)-type GKM graph is the GKM graph induced from a 2m-dimensional GKM manifold M^{2m} with an effective n-dimensional torus T^n -action which preserves the almost complex structure, say (M^{2m}, T^n) . Then it is shown that $\mathcal{A}(\Gamma, \alpha, \nabla)$ has rank $\ell(> n)$ if and only if there exists an (m, ℓ) -type GKM graph $(\Gamma, \tilde{\alpha}, \nabla)$ which is an extension of (Γ, α, ∇) . Using this combinatorial necessary and sufficient condition, we prove that the rank of $\mathcal{A}(\Gamma_M, \alpha_M, \nabla_M)$ for the GKM graph $(\Gamma_M, \alpha_M, \nabla_M)$ induced from (M^{2m}, T^n) gives an upper bound for the dimension of a torus which can act on M^{2m} effectively. As one of the applications of this result, we compute the rank associated to $\mathcal{A}(\Gamma, \alpha, \nabla)$ of the complex Grassmannian of 2-planes $G_2(\mathbb{C}^{n+2})$ with the natural effective torus action which preserves the standard complex structure.

1. Introduction.

GKM manifolds (or more general spaces) are "roughly" spaces with torus action whose 0- and 1-dimensional orbits have the structure of a graph. This class of spaces first appeared in the work of Goresky–Kottwitz–MacPherson [8] as a class of algebraic varieties (GKM stands for their initials). Motivated by their work, Guillemin–Zara [11] introduce a combinatorial counterpart of the GKM manifold, called a(n) (abstract) GKM graph, and give some relationships between the (symplectic) geometry (and topology) of GKM manifolds and the combinatorics of GKM graphs. This leads to the study of geometric and topological properties of the GKM manifolds using combinatorial properties of GKM graphs (see e.g. [6], [7], [9], [10], [15], [17], [19], [20] etc.). In this paper, we introduce a new invariant of GKM graphs and provide a partial answer to the extension problem of torus actions on GKM manifolds.

To state our main results more precisely, we briefly recall the setting of this paper and background of the extension problem of torus actions. Let T^n be the *n*-dimensional torus and M^{2m} be a 2*m*-dimensional, compact, connected, almost complex manifold with effective T^n -action, which preserves the almost complex structure. We denote such a manifold by (M^{2m}, T^n) , or M^{2m} , M, (M, T) (if its torus action or dimensions of the

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manifold and torus are obviously known from the context). We call (M^{2m}, T^n) a *GKM* manifold if it satisfies the following properties (see Section 4 for details):

- 1. the set of fixed points is not empty and isolated, i.e., M^T is 0-dimensional;
- 2. the closure of each connected component of 1-dimensional orbits is equivariantly diffeomorphic to the 2-dimensional sphere, called an *invariant 2-sphere*.

By regarding fixed points as vertices and invariant 2-spheres as edges, this condition is equivalent to the one-skeleton of (M^{2m}, T^n) having the structure of a graph, where the one-skeleton of (M^{2m}, T^n) is the orbit space of the set of 0- and 1-dimensional orbits. Note that there are several definitions of GKM manifolds (see e.g. [9], [11] etc.). This is because the spaces with such torus actions have been studied from several different points of view (homotopically, topologically, algebraically and geometrically). In this paper, we study the GKM manifolds defined by Guillemin–Zara in their original paper [11]. In particular, equivariant formality is often assumed for the cohomology of GKM spaces. However, in this paper, we do not need to use this assumption; therefore, our definition of a GKM manifold is more general than the equivariantly formal GKM manifolds (see Section 4).

For example, in our setting, the following manifolds are GKM manifolds: nonsingular complete toric varieties (also called toric manifolds) and homogeneous manifolds G/H (where G is a compact connected Lie group and H is its closed subgroup with the same maximal torus) with torus invariant almost complex structures such as $S^6 = G_2/SU(3)$, flag manifolds and complex Grassmannians, etc.

Since GKM manifolds are even-dimensional and their effective torus actions have isolated fixed points, the differentiable slice theorem tells us that the following inequality holds for every GKM manifold (M, T):

$$\dim T \le \frac{1}{2} \dim M.$$

If the equality dim $T = (1/2) \dim M$ holds, such a GKM manifold is also known as a torus manifold (with invariant almost complex structure); famous examples are toric manifolds. Namely, by definition, the torus action on a torus manifold is maximal, i.e., the torus action can not be extended to a bigger torus action. In this case, the author, Masuda and Wiemeler [13], [14], [16], [22] have studied the extended *G*-actions of *T*-actions on torus manifolds, where *G* is a non-abelian, compact, simply connected Lie group with maximal torus *T*. On the other hand, for general GKM manifolds, the given torus action might not be maximal. In fact, a restricted T^{m-1} -action of a 2*m*-dimensional toric manifold (M^{2m}, T^m) is often a GKM manifold (M^{2m}, T^{m-1}), in other words, this GKM manifold (M^{2m}, T^{m-1}) extends to a toric manifold (M^{2m}, T^m). Thus the following problem naturally arises in the GKM manifolds (also see Proposition 4.3):

PROBLEM 1.1. When does a GKM manifold (M^{2m}, T^n) extend to a GKM manifold (M^{2m}, T^{ℓ}) ? Here, $T^n \subset T^{\ell}$ and $n < \ell \leq m$.

As not every GKM manifold can be endowed with a torus T^{ℓ} -action, that extends the given action and makes it a torus manifold, in this paper we give a combinatorial method to determine an upper bound for ℓ . Namely we first introduce a free abelian group with finite rank $\mathcal{A}(\Gamma, \alpha, \nabla)$, called a group of axial functions, for the GKM graph (Γ, α, ∇) in Section 2. Here, a *GKM graph* is "roughly" the following triple (see Section 2 for details): an *m*-valent graph Γ ; a function $\alpha : E(\Gamma) \to H^2(BT^n) \simeq \mathbb{Z}^n$, called an *axial* function; and a collection ∇ of some bijective maps between out-going edges on adjacent vertices, called a *connection*. We call such a GKM graph an (m, n)-type GKM graph in this paper. The main theorem of this paper can be stated as follows (see Sections 2 and 3 for details):

THEOREM 1.2. Let (Γ, α, ∇) be an abstract (m, n)-type GKM graph. Then, the following two statements are equivalent:

- 1. rk $\mathcal{A}(\Gamma, \alpha, \nabla) \geq \ell$ for some $n \leq \ell \leq m$;
- 2. there is an (m, ℓ) -type GKM graph $(\Gamma, \tilde{\alpha}, \nabla)$ which is an extension of (Γ, α, ∇) .

As a GKM manifold (M^{2m}, T^n) defines an (m, n)-type GKM graph (see Section 4), Theorem 1.2 implies that the maximal dimension of a torus which can act on a GKM manifold M is bounded from above by the rank of the group of axial functions of the GKM graph induced from M. Namely, we obtain the main result of this paper as follows (see Section 4 for details):

COROLLARY 1.3. Let (M^{2m}, T^n) be a GKM manifold and $(\Gamma_M, \alpha_M, \nabla_M)$ be its (m, n)-type GKM graph. Assume that $\operatorname{rk} \mathcal{A}(\Gamma_M, \alpha_M, \nabla_M) = \ell$. Then, the T^n -action on M^{2m} does not extend to any $T^{\ell+1}$ -action preserving the given almost complex structure.

In particular, if $\operatorname{rk} \mathcal{A}(\Gamma_M, \alpha_M, \nabla_M) = n$, then the T^n -action on M^{2m} is maximal among torus actions which preserve the given almost complex structure.

REMARK 1.4. Shunji Takuma also obtains a partial answer to Problem 1.1 by introducing an obstruction class for the extension of an (m, n)-type GKM graph to an (m, n + 1)-type GKM graph in his note [19]. Theorem 1.2 may be regarded as the generalization of his result.

Problem 1.1 is reminiscent of the computation of the *torus degree of symmetry* of a manifold X (see [12]), i.e., the maximal dimension of a torus which can act on X effectively. A torus degree of symmetry has been studied for many classes of manifolds, in particular from differential geometry (see e.g. [4], [12], [21], [23]). Corollary 1.3 may be regarded as giving an upper bound of the *torus degree of symmetry of an invariant almost complex structure* of a GKM manifold. As an application of Corollary 1.3, in the final section (Section 5), we compute the torus degree of such symmetry for the complex Grassmannian of 2-planes, denoted as

$$G_2(\mathbb{C}^{n+2}) \simeq GL(n+2,\mathbb{C})/GL(2,\mathbb{C}) \times GL(n,\mathbb{C}) \simeq U(n+2)/U(2) \times U(n).$$

Namely, we compute rk $\mathcal{A}(\Gamma_M, \alpha_M, \nabla_M)$ for $M = G_2(\mathbb{C}^{n+2})$ with the natural effective T^{n+1} -action and prove the following fact:

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PROPOSITION 1.5. The standard effective T^{n+1} -action on $G_2(\mathbb{C}^{n+2})$ is maximal among the effective torus actions which preserve the almost complex structure.

Note that there is the natural T^{n+2} -action on $G_2(\mathbb{C}^{n+2})$ which is induced from the maximal torus subgroup in U(n+2). However, this action is not effective.

The organization of this paper is as follows. In Section 2, we recall an abstract GKM graph (Γ, α, ∇) , and introduce its group of axial functions $\mathcal{A}(\Gamma, \alpha, \nabla)$. In Section 3, the main theorem (Theorem 1.2) is proved. In Section 4, in order to apply our results to geometry, we recall the definition of a GKM graph induced from a GKM manifold, and prove Corollary 1.3. We also prove the T^2 -action on $S^6 = G_2/SU(3)$ is maximal. In Section 5, we obtain the GKM graph obtained from the effective T^{n+1} -action on $G_2(\mathbb{C}^{n+2})$, and compute its group of axial functions. This proves Proposition 1.5.

2. GKM graph and its group of axial functions.

In this section, we first recall the basic facts about GKM graphs (Γ, α, ∇) (see [11]) and introduce the extension of axial functions of GKM graphs precisely. Then a finite rank free abelian group $\mathcal{A}(\Gamma, \alpha, \nabla)$, called a *group of axial functions*, is defined.

2.1. GKM graph and its extension.

We first prepare some notation to define a GKM graph. Let $\Gamma = (V(\Gamma), E(\Gamma))$ be an *abstract graph* comprising of a set $V(\Gamma)$ of vertices and a set $E(\Gamma)$ of oriented edges. For a given orientation on $e \in E(\Gamma)$, we denote its initial vertex by i(e) and its terminal vertex by t(e). In this paper, we assume that there are no loops in $E(\Gamma)$, i.e., $i(e) \neq t(e)$ for any $e \in E(\Gamma)$, and Γ is connected. The symbol $\overline{e} \in E(\Gamma)$ represents the edge e with its orientation reversed, i.e., $i(e) = t(\overline{e})$ and $t(e) = i(\overline{e})$. The subset $E_p(\Gamma) \subset E(\Gamma)$ is the set of out-going edges from $p \in V(\Gamma)$; more precisely,

$$E_p(\Gamma) = \{ e \in E(\Gamma) \mid i(e) = p \}.$$

A finite connected graph Γ is called an *m*-valent graph if $|E_p(\Gamma)| = m$ for all $p \in V(\Gamma)$, where the symbol |X| represents the cardinality of a finite set X.

Let Γ be an *m*-valent graph. We next define a label $\alpha : E(\Gamma) \to H^2(BT)$ on Γ . Recall that BT^n (often denoted by BT) is a classifying space of an *n*-dimensional torus T, and its cohomology ring (over \mathbb{Z} -coefficients) is isomorphic to the polynomial ring

$$H^*(BT) \simeq \mathbb{Z}[a_1, \ldots, a_n],$$

where a_i is a variable with deg $a_i = 2$ for i = 1, ..., n. So its degree 2 part $H^2(BT)$ is isomorphic to \mathbb{Z}^n . We put a label on edges of Γ by using a function $\alpha : E(\Gamma) \to H^2(BT)$ on edges of Γ . Set

$$\alpha_{(p)} = \{ \alpha(e) \mid e \in E_p(\Gamma) \} \subset H^2(BT).$$

An axial function on Γ is the function $\alpha : E(\Gamma) \to H^2(BT^n)$ for $n \leq m$ which satisfies the following three conditions:

(1) $\alpha(e) = -\alpha(\overline{e});$

- (2) for each $p \in V(\Gamma)$, the set $\alpha_{(p)}$ is pairwise linearly independent, i.e., each pair of elements in $\alpha_{(p)}$ are linearly independent in $H^2(BT)$;
- (3) for all $e \in E(\Gamma)$, there exists a bijective map $\nabla_e : E_{i(e)}(\Gamma) \to E_{t(e)}(\Gamma)$ such that
 - 1. $\nabla_{\overline{e}} = \nabla_e^{-1}$,
 - 2. $\nabla_e(e) = \overline{e}$, and
 - 3. for each $e' \in E_{i(e)}(\Gamma)$, there exists an integer $c_e(e')$ such that

$$\alpha(\nabla_e(e')) - \alpha(e') = c_e(e')\alpha(e) \in H^2(BT).$$
(2.1)

The collection $\nabla = \{\nabla_e \mid e \in E(\Gamma)\}$ is called a *connection* on the labelled graph (Γ, α) ; we denote the labelled graph with connection as (Γ, α, ∇) , and equation (2.1) is called a *congruence relation*. We call the integer $c_e(e')$ in the congruence relation a *congruence coefficient of* e' on e. Here, geometrically, $c_e(e')$ is nothing but the Chern numbers of the line bundles over the sphere corresponding to e, (see Section 4). The conditions above are called *the axiom of an axial function*. In addition, in this paper, we also assume the followings:

(4) for each $p \in V(\Gamma)$, the set $\alpha_{(p)}$ spans $H^2(BT)$.

The axial function which satisfies (4) is called an *effective* axial function.

DEFINITION 2.1 (GKM graph [11]). If an *m*-valent graph Γ is labeled by an axial function $\alpha : E(\Gamma) \to H^2(BT^n)$ for some $n \leq m$, then such a labeled graph is said to be an (abstract) *GKM graph*, and denoted by (Γ, α, ∇) (or (Γ, α) if the connection ∇ is obviously determined).

DEFINITION 2.2 ((m, n)-type GKM graph). Let (Γ, α, ∇) be an abstract GKM graph. If the axial function α is effective, (Γ, α, ∇) is said to be an (m, n)-type GKM graph.

In this paper, we only consider (m, n)-type GKM graphs $(n \le m)$ unless otherwise stated.

Figure 1 shows examples of GKM graphs. Note that we often omit the axial functions of the opposite directions of edges (see the 3rd figure) because it is automatically determined by axiom (1) of a GKM graph.

We note the following lemma proved in [11, Proposition 2.1.3].

LEMMA 2.3. Let (Γ, α, ∇) be a GKM graph. If $\alpha_{(p)}$ is three-independent for every $p \in V(\Gamma)$, the connection ∇ is uniquely determined.

Here, in Lemma 2.3, the set of vectors $\alpha_{(p)}$ in $H^2(BT)$ is called *three-independent* if every triple $\{\alpha(e_i), \alpha(e_j), \alpha(e_k)\} \subset \alpha_{(p)}$ is linearly independent (e.g., the right (3,3)-type GKM graph in Figure 1). So, in this case, we may denote (Γ, α, ∇) as (Γ, α) without the connection ∇ .

We also note the following lemma:

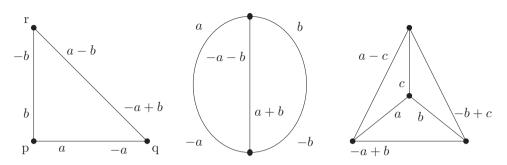


Figure 1. Examples of (2,2)-type, (3,2)-type and (3,3)-type GKM graphs from the left, where a, b (resp. c) are generators of $H^*(BT^2)$ (resp. $H^*(BT^3)$). For example, in the (2, 2)-type GKM graph, the axial function is defined by $\alpha(pq) = a, \alpha(qr) = -a + b$, etc. In the (3,3)-type GKM graph, we omit the axial functions of the opposite directions of edges. Note that in the figure we do not distinct two edges e and \overline{e} , and represent it by one undirected edge.

LEMMA 2.4. For all $e \in E(\Gamma)$, $c_e(e) = -2$.

PROOF. By the axiom (1), (3)-(2) and (3)-(3) of axial function, it is straightforward. $\hfill \Box$

REMARK 2.5. As we mentioned before, $c_e(e')$ represents the Chern number of the line bundle over the 2-sphere corresponding to e and e'. The sign of this number depends on the choice of the complex structure on the line bundle. The number $c_e(e)$ corresponds to the Chern number of the tangent bundle of the 2-sphere. In our convention, we take the orientation which gives its Chern number as -2.

We close this section by defining an extension. Let (Γ, α, ∇) be an (m, n)-type GKM graph. An (m, ℓ) -type GKM graph $(\widetilde{\Gamma}, \widetilde{\alpha}, \widetilde{\nabla})$ (for $n < \ell \leq m$) is said to be an *extension* of (Γ, α, ∇) if $\widetilde{\Gamma} = \Gamma$, $\nabla = \widetilde{\nabla}$ and there exists a projection $\pi : H^2(BT^{\ell}) \to H^2(BT^n)$ such that the following diagram commutes:

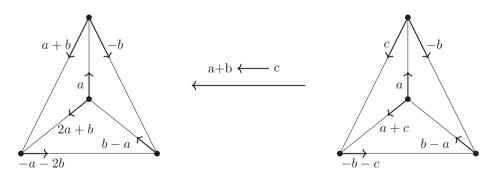


Figure 2. The left (3,2)-type GKM graph extends to the right (3,3)-type GKM graph. In this figure, we omit the axial function on the direction \overline{e} , because of the relation $\alpha(\overline{e}) = -\alpha(e)$.

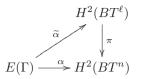


Figure 2 shows an example of an extension.

2.2. The invariant function.

Let (Γ, α, ∇) be an (m, n)-type GKM graph for $n \leq m$. We shall define an invariant function $c_{(\Gamma,\alpha,\nabla)} : E(\Gamma) \to \mathbb{Z}^m$ under extensions, called a *function invariant under extension* of (Γ, α, ∇) . To define it, we first fix an order of out-going edges on each vertex p, i.e., set

$$E_p(\Gamma) = \{e_{1,p}, \dots, e_{m,p}\}.$$

Then we can define the free \mathbb{Z} -module with rank m on each p, say $\mathbb{Z}E_p(\Gamma)$, by regarding $\{e_{1,p},\ldots,e_{m,p}\}$ as the formal generator of $\mathbb{Z}E_p(\Gamma)$. Namely,

$$\mathbb{Z}E_p(\Gamma) := \mathbb{Z}e_{1,p} \oplus \cdots \oplus \mathbb{Z}e_{m,p} \simeq \mathbb{Z}^m.$$

As an order on each $E_p(\Gamma)$ is fixed, the connection $\nabla_e : E_{i(e)}(\Gamma) \to E_{t(e)}(\Gamma)$ induces a permutation on $\{1, \ldots, m\}$. So, there is a permutation $\sigma : \{1, \ldots, m\} \to \{1, \ldots, m\}$ such that

$$\nabla_e(e_{j,i(e)}) = e_{\sigma(j),t(e)}.$$

Then, the connection ∇_e defines the isomorphism

$$N_e: \mathbb{Z}E_{i(e)}(\Gamma) \to \mathbb{Z}E_{t(e)}(\Gamma) \in GL(m; \mathbb{Z})$$
(2.2)

by the inverse (or equivalently the transpose) of the permutation $(m \times m)$ -square matrix. More precisely, the square matrix N_e is defined as follows. If we put $\mathbb{Z}E_{i(e)}(\Gamma) = \mathbb{Z}e_{1,p} \oplus \cdots \oplus \mathbb{Z}e_{m,p}$ (p = i(e)) and $\mathbb{Z}E_{t(e)}(\Gamma) = \mathbb{Z}e_{1,q} \oplus \cdots \oplus \mathbb{Z}e_{m,q}$ (q = t(e)), then ∇_e induces the following isomorphism:

$$k_1 e_{1,p} \oplus \dots \oplus k_m e_{m,p}$$

$$\mapsto k_1 e_{\sigma(1),q} \oplus \dots \oplus k_m e_{\sigma(m),q} = k_{\sigma^{-1}(1)} e_{1,q} \oplus \dots \oplus k_{\sigma^{-1}(m)} e_{m,q}.$$

Thus $N_e : \mathbb{Z}E_{i(e)}(\Gamma) \to \mathbb{Z}E_{t(e)}(\Gamma)$ is defined by the square matrix which induces the following isomorphism

$$N_e: \begin{pmatrix} k_1\\ \vdots\\ k_m \end{pmatrix} \mapsto \begin{pmatrix} k_{\sigma^{-1}(1)}\\ \vdots\\ k_{\sigma^{-1}(m)} \end{pmatrix}$$
(2.3)

where σ is the permutation induced from ∇_e . Take an edge $e \in E(\Gamma)$. Recall that the congruence coefficient $c_e(e')$ which is defined by (2.1) is an integer attached on every

edge $e' \in E_{i(e)}(\Gamma)$ for the fixed edge $e \in E(\Gamma)$. Therefore, the *m*-tuple of congruence coefficients on *e* defines the element in $\mathbb{Z}E_{i(e)}(\Gamma)$ by

$$c_e = (c_e(e_{1,i(e)}), \dots, c_e(e_{m,i(e)})) \in \mathbb{Z}e_{1,i(e)} \oplus \dots \oplus \mathbb{Z}e_{m,i(e)}.$$

Thus we may define the function

$$c_{(\Gamma,\alpha,\nabla)}: E(\Gamma) \to \mathbb{Z}^m$$
 by $c_{(\Gamma,\alpha,\nabla)}(e) = c_e$.

Due to the following proposition (see also [19]), we call this function $c_{(\Gamma,\alpha,\nabla)}$ a function invariant under extension of (Γ, α, ∇) :

PROPOSITION 2.6. For any extension $(\Gamma, \tilde{\alpha}, \nabla)$ of (Γ, α, ∇) , the equation $c_{(\Gamma, \alpha, \nabla)} = c_{(\Gamma, \tilde{\alpha}, \nabla)}$ holds.

PROOF. Let $(\Gamma, \tilde{\alpha}, \nabla)$ be an (m, ℓ) -type GKM graph for some $\ell > n$, and $\tilde{c}_e(e')$ be its congruence coefficient of e' on e. Fix an order of out-going edges on each vertex p. By the definition of the function $c_{(\Gamma,\alpha,\nabla)}$, it is enough to prove the equation $c_e(e') = \tilde{c}_e(e')$ for all $e \in E(\Gamma)$ and $e' \in E_{i(e)}(\Gamma)$.

By definition, there is a projection $\pi : H^2(BT^{\ell}) \to H^2(BT^n)$ such that $\pi \circ \tilde{\alpha} = \alpha$. Together with the congruence relations (2.1), we have

$$\pi(\widetilde{\alpha}(\nabla_e(e'))) = \alpha(\nabla_e(e')) = \alpha(e') + c_e(e')\alpha(e)$$

and

$$\pi(\widetilde{\alpha}(\nabla_e(e'))) = \pi(\widetilde{\alpha}(e') + \widetilde{c}_e(e')\widetilde{\alpha}(e))$$
$$= \pi(\widetilde{\alpha}(e')) + \widetilde{c}_e(e')\pi(\widetilde{\alpha}(e))$$
$$= \alpha(e') + \widetilde{c}_e(e')\alpha(e).$$

Comparing these equations, we establish the statement.

The following lemma tells us that $c_{(\Gamma,\alpha,\nabla)}(\overline{e})$ is automatically determined by $c_{(\Gamma,\alpha,\nabla)}(e)$ and N_e defined in (2.2).

LEMMA 2.7. For any $e \in E(\Gamma)$, the equation $N_e(c_{(\Gamma,\alpha,\nabla)}(e)) = c_{(\Gamma,\alpha,\nabla)}(\overline{e})$ holds.

PROOF. Let σ be the permutation on $\{1, \ldots, m\}$ induced from ∇_e . Then, $\nabla_e(e_{j,i(e)}) = e_{\sigma(j),i(\overline{e})}$ (and $\nabla_{\overline{e}}(e_{\sigma(j),i(\overline{e})}) = e_{j,i(e)}$). Therefore, by definitions of N_e and $c_{(\Gamma,\alpha,\nabla)}$, it is enough to show the following equality: $c_e(e_{\sigma^{-1}(j),i(e)}) = c_{\overline{e}}(e_{j,i(\overline{e})})$, i.e.,

$$c_e(e_{j,i(e)}) = c_{\overline{e}}(e_{\sigma(j),i(\overline{e})})$$

for all j = 1, ..., m. Due to the congruence relations (2.1) on e and \overline{e} , we have

$$\alpha(\nabla_e(e_{j,i(e)})) - \alpha(e_{j,i(e)}) = c_e(e_{j,i(e)})\alpha(e)$$
$$= \alpha(e_{\sigma(j),i(\overline{e})}) - \alpha(e_{j,i(e)})$$

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and

$$\begin{aligned} \alpha(\nabla_{\overline{e}}(e_{\sigma(j),i(\overline{e})})) - \alpha(e_{\sigma(j),i(\overline{e})}) &= c_{\overline{e}}(e_{\sigma(j),i(\overline{e})})\alpha(\overline{e}) \\ &= \alpha(e_{j,i(e)}) - \alpha(e_{\sigma(j),i(\overline{e})}) \end{aligned}$$

By these equations and $\alpha(e) = -\alpha(\overline{e})$, we establish the statement.

EXAMPLE 2.8. Figure 3 shows an example of the invariant function $c_{(\Gamma,\alpha,\nabla)}$ induced from a (3,2)-GKM graph (Γ,α) . In this case, we put the order of $E_p(\Gamma)$ as in Figure 3 by

$$e_{1,p} = e_1, \quad e_{2,p} = e_2, \quad e_{3,p} = e_3,$$

and the order of $E_q(\Gamma)$ similarly by

$$e_{1,q} = \overline{e_1}, \quad e_{2,q} = \overline{e_2}, \quad e_{3,q} = \overline{e_3}.$$

Then by using the congruence relation for the axial function defined in Figure 3, the connection ∇_{e_i} for i = 1, 2, 3 is determined uniquely by $e_i \mapsto \overline{e}_i$ and $e_j \mapsto \overline{e}_k$, where $\{i, j, k\} = \{1, 2, 3\}$ in Figure 3. For example, for the edge e_1 , by definition of $c_{(\Gamma, \alpha, \nabla)}$ and Lemma 2.4, we have

$$c_{(\Gamma,\alpha,\nabla)}(e_1) = (-2,1,1).$$

With the similar computation (and using Lemma 2.7), we obtain $c_{(\Gamma,\alpha,\nabla)}$ as the righthand graph in Figure 3.

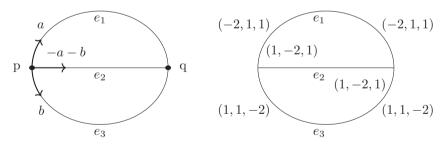


Figure 3. The left one is the (3,2)-GKM graph (Γ, α) in Figure 1 and the right one is its invariant function $c_{(\Gamma,\alpha,\nabla)}: E(\Gamma) \to \mathbb{Z}^3$.

2.3. A group of axial functions $\mathcal{A}(\Gamma, \alpha, \nabla)$ of (Γ, α, ∇) .

Let (Γ, α, ∇) be an (m, n)-type GKM graph. In this subsection, we introduce a finitely generated free abelian group $\mathcal{A}(\Gamma, \alpha, \nabla)$, called a group of axial functions. Before defining $\mathcal{A}(\Gamma, \alpha, \nabla)$, we prepare some notation. Let $f \in \mathbb{Z}E_p(\Gamma)$. The symbol $f_e(\in \mathbb{Z})$ represents the integer of the coefficient in f corresponding to the edge $e \in E_p(\Gamma)$. For example, if we put the order $E_p(\Gamma) = \{e_1, \ldots, e_m\}$ and $f = (x_1, \ldots, x_m) \in \mathbb{Z}^m \simeq \mathbb{Z}E_p(\Gamma)$ with respect to this order, then we put $f_{e_j} = x_j$.

 \Box

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DEFINITION 2.9 (Group of axial functions). A \mathbb{Z} -module $\mathcal{A}(\Gamma, \alpha, \nabla)$ is defined by the submodule of

$$\{f: V(\Gamma) \to \mathbb{Z}^m\} = \bigoplus_{p \in V(\Gamma)} \mathbb{Z}E_p(\Gamma) \simeq \bigoplus_{p \in V(\Gamma)} \mathbb{Z}^m$$

which satisfies the following relations for all $e \in E(\Gamma)$:

$$N_e(f(p)) - f(q) = f(q)_{\overline{e}} c_{(\Gamma,\alpha,\nabla)}(\overline{e})$$
(2.4)

where i(e) = p, t(e) = q, $N_e : \mathbb{Z}E_p(\Gamma) \to \mathbb{Z}E_q(\Gamma)$ is the square matrix defined in (2.3) and $f(q)_{\overline{e}} \in \mathbb{Z}$ is the integer defined just before. This module $\mathcal{A}(\Gamma, \alpha, \nabla)$ is said to be a group of axial functions of (Γ, α, ∇) (also see Remark 3.5).

REMARK 2.10. As the set $\{f : V(\Gamma) \to \mathbb{Z}^m\}$ is a finitely generated free \mathbb{Z} -module with rank $m|V(\Gamma)|$ i.e., a free abelian group with finite rank, its submodule $\mathcal{A}(\Gamma, \alpha, \nabla)$ is so too. It is also easy to check that two groups of axial functions with different orders for $E_p(\Gamma)$ (for any $p \in V(\Gamma)$) are isomorphic.

REMARK 2.11. The geometric idea behind the definition of the group of axial functions is as follows: one essentially needs to define the set of all possible weights of a generic circle action (the circle being a subcircle of the maximal torus action which can act on a GKM manifold) making sure that the Chern number of the line bundles, in which the tangent bundle splits over each invariant sphere, stay the same.

The following corollary follows immediately from Definition 2.9 and Proposition 2.6:

COROLLARY 2.12. Let (Γ, α, ∇) be a GKM graph and $(\Gamma, \tilde{\alpha}, \nabla)$ be its extension. Then the two groups of axial functions are isomorphic, i.e., $\mathcal{A}(\Gamma, \alpha, \nabla) \simeq \mathcal{A}(\Gamma, \tilde{\alpha}, \nabla)$.

We note the following property of equation (2.4) which will be useful to compute $\mathcal{A}(\Gamma, \alpha, \nabla)$.

LEMMA 2.13. Let $f: V(\Gamma) \to \mathbb{Z}^m$ be any function. If equation (2.4) holds for some edge $e \in E(\Gamma)$, then $f(p)_e = -f(q)_{\overline{e}}$ and equation (2.4) also holds for the edge \overline{e} , where p = i(e) and q = t(e).

PROOF. Let $e = e_{j,p}$ and $\overline{e} = e_{\sigma(j),q}$, where σ is the permutation induced from ∇_e . Put

$$f(p) = \begin{pmatrix} k_{1,p} \\ \vdots \\ k_{m,p} \end{pmatrix}.$$

Then $f(p)_e = k_{j,p}$ and

$$N_e(f(p)) = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} = \begin{pmatrix} k_{\sigma^{-1}(1),p} \\ \vdots \\ k_{\sigma^{-1}(m),p} \end{pmatrix}.$$

This shows that $N_e(f(p))_{\overline{e}} = x_{\sigma(j)} = k_{j,p} = f(p)_e$. Therefore, together with Lemma 2.4, we have

$$N_e(f(p))_{\overline{e}} - f(q)_{\overline{e}} = f(p)_e - f(q)_{\overline{e}} = -2f(q)_{\overline{e}}$$

So $f(p)_e = -f(q)_{\overline{e}}$. Note that $N_{\overline{e}} = N_e^{-1}$ because $\nabla_{\overline{e}} = \nabla_e^{-1}$. Thus, evaluating equation (2.4) by $N_{\overline{e}}$ and using Lemma 2.7, we have

$$f(p) - N_{\overline{e}}(f(q)) = -f(p)_e N_{\overline{e}}(c_{(\Gamma,\alpha,\nabla)}(\overline{e})) = -f(p)_e c_{(\Gamma,\alpha,\nabla)}(e).$$

This establishes the statement.

EXAMPLE 2.14. Before proving the main theorem, let us compute $\mathcal{A}(\Gamma, \alpha, \nabla)$ of (Γ, α, ∇) in Example 2.8. By the definition of $\mathcal{A}(\Gamma, \alpha, \nabla)$, we first have

$$\mathcal{A}(\Gamma, \alpha, \nabla) = \{ f : \{ p, q \} \to \mathbb{Z}^3 \mid N_{e_i}(f(p)) - f(q) = f(q)_{\overline{e}_i} c_{(\Gamma, \alpha, \nabla)}(\overline{e}_i) \}.$$

Put $f(p) = (x, y, z) \in \mathbb{Z}E_p(\Gamma)$ and $f(q) = (x', y', z') \in \mathbb{Z}E_q(\Gamma)$. Then by Lemma 2.13 x' = -x, y' = -y and z' = -z. Therefore, for example for the case when i = 1, the relation of $\mathcal{A}(\Gamma, \alpha, \nabla)$ says that

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} -x \\ -y \\ -z \end{pmatrix} = -x \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}.$$

Hence, we also have the relation x + y + z = 0. Similarly, computing for the other edges e_2, e_3 (Lemma 3.2 proved later may also be useful), we get

$$\mathcal{A}(\Gamma, \alpha, \nabla) = \{ (f(p), f(q)) = ((x, y, z), (-x, -y, -z)) \mid x + y + z = 0 \} (\simeq \mathbb{Z}^2).$$

3. Main theorem.

In this section, we prove the following main theorem.

THEOREM 3.1. Let (Γ, α, ∇) be an (m, n)-type GKM graph. Then the following two statements are equivalent:

- 1. there is an (m, ℓ) -type GKM graph which is an extension of (Γ, α, ∇) for some $\ell \ge n$;
- 2. $\ell \leq \operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla) (\leq m).$

In particular, if $\operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla) = k$, then there is an extended (m, k)-type GKM graph $(\Gamma, \widetilde{\alpha}, \nabla)$ which is the maximal among extensions.

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3.1. Proof of $(1) \Rightarrow (2)$.

We first prove $(1) \Rightarrow (2)$ in Theorem 3.1. The following lemma is the key lemma:

LEMMA 3.2. Let (Γ, α, ∇) be an (m, n)-type GKM graph. Then, the rank of $\mathcal{A}(\Gamma, \alpha, \nabla)$ satisfies the following inequality:

$$n \leq \operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla) \leq m.$$

PROOF. We first prove the inequality rk $\mathcal{A}(\Gamma, \alpha, \nabla) \leq m$. By definition, $f \in \mathcal{A}(\Gamma, \alpha, \nabla) \subset \bigoplus_{p \in V(\Gamma)} \mathbb{Z}E_p(\Gamma)$. Under the same notation as in equation (2.4), we put

$$f(p) = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix}, \quad f(q) = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix}, \quad c_{(\Gamma,\alpha,\nabla)}(e) = \begin{pmatrix} k_{1,p} \\ \vdots \\ k_{m,p} \end{pmatrix}$$

where x_j , y_j are variables and $k_{j,p} \in \mathbb{Z}$ for all j = 1, ..., m. Put $f(p)_e = x_j$. Then by equation (2.4) for \overline{e} , for all i = 1, ..., m the following equation holds:

$$y_{\sigma(i)} - x_i = x_j k_{i,p},$$

where σ is the permutation on $\{1, \ldots, m\}$ induced from ∇_e . This implies that once we choose the value $f(p) \in \mathbb{Z}^m$ for a vertex p which is connected to q by an edge, then the value $f(q) \in \mathbb{Z}^m$ is automatically and uniquely determined. Since Γ is a connected graph, iterating this argument on each edge, we can determine the value f(r) uniquely for all $r \in V(\Gamma)$ if we choose a value for f(p). This implies that the restriction map

$$\rho_p : \mathcal{A}(\Gamma, \alpha, \nabla) \to \mathbb{Z}^m \text{ such that } \rho_p(f) = f(p)$$
(3.1)

is the injective homomorphism for any vertex $p \in V(\Gamma)$, which proves $\operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla) \leq m$.

We next prove the next inequality $n \leq \operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla)$. As (Γ, α, ∇) is an (m, n)-type GKM graph, taking a linear basis of $H^2(BT^n)$ as $\{a_1, \ldots, a_n\}$, its axial function can be written as $\alpha : E(\Gamma) \to H^2(BT^n) = \mathbb{Z}a_1 \oplus \cdots \oplus \mathbb{Z}a_n \simeq \mathbb{Z}^n$. Let $\pi_i : H^2(BT^n) \to \mathbb{Z}a_i$ be the projection onto the *i*th coordinate of $H^2(BT^n)$ with respect to this basis. Define

$$\alpha_i: E(\Gamma) \xrightarrow{\alpha} H^2(BT^n) \xrightarrow{\pi_i} \mathbb{Z}a_i.$$

Recall that we chose an order on $E_p(\Gamma) = \{e_{1,p}, \ldots, e_{m,p}\}$ for each $p \in V(\Gamma)$. Let

$$\alpha_i(e_{j,p}) = k_{j,p}^{(i)} a_i$$

for some $k_{j,p}^{(i)} \in \mathbb{Z}$. Then the map $f_i : V(\Gamma) \to \mathbb{Z}^m$ is defined by

$$f_i(p) = \begin{pmatrix} k_{1,p}^{(i)} \\ \vdots \\ k_{m,p}^{(i)} \end{pmatrix} \in \mathbb{Z} E_p(\Gamma) \simeq \mathbb{Z}^m,$$

for each $p \in V(\Gamma)$. We claim that $f_i \in \mathcal{A}(\Gamma, \alpha, \nabla)$ and $\{f_1, \ldots, f_n\}$ spans the rank n submodule in $\mathcal{A}(\Gamma, \alpha, \nabla)$. Let $p = i(e), q = t(e) \in V(\Gamma)$ for some $e \in E(\Gamma)$. In order to prove $f_i \in \mathcal{A}(\Gamma, \alpha, \nabla)$, by definition, it is enough to show the equation

$$N_e(f_i(p)) - f_i(q) = f_i(q)_{\overline{e}} c_{(\Gamma,\alpha,\nabla)}(\overline{e}).$$
(3.2)

Now we have

$$\alpha(\nabla_e(e_{j,p})) = \alpha(e_{\sigma(j),q}) = \alpha(e_{j,p}) + c_e(e_{j,p})\alpha(e).$$

Taking π_i on these equations, we obtain

$$\alpha_i(\nabla_e(e_{j,p})) = k_{\sigma(j),q}^{(i)} a_i = k_{j,p}^{(i)} a_i + c_e(e_{j,p}) k_e^{(i)} a_i$$

for all j = 1, ..., m, where $k_e^{(i)} a_i = \alpha_i(e) = f_i(p)_e a_i$. Therefore, we have

$$\begin{pmatrix} k_{\sigma(1),q}^{(i)} \\ \vdots \\ k_{\sigma(m),q}^{(i)} \end{pmatrix} = \begin{pmatrix} k_{1,p}^{(i)} \\ \vdots \\ k_{m,p}^{(i)} \end{pmatrix} + k_e^{(i)} \begin{pmatrix} c_e(e_{1,p}) \\ \vdots \\ c_e(e_{m,p}) \end{pmatrix}.$$

As $N_{\overline{e}} = N_e^{-1}$ (where N_e is defined by ∇_e), we have the following from this equation:

$$N_{\overline{e}}(f_i(q)) = f_i(p) + f_i(p)_e c_{(\Gamma,\alpha,\nabla)}(e).$$

Thus, by multiplying N_e and using Lemma 2.7, we have that

$$N_e(f_i(p)) - f_i(q) = -f_i(p)_e c_{(\Gamma,\alpha,\nabla)}(\overline{e}).$$

Now, by the definition of α_i , we have that $f_i(p)_e = -f_i(q)_{\overline{e}}$. Hence, we obtain equation (3.2) and establish that $f_i \in \mathcal{A}(\Gamma, \alpha, \nabla)$ for all i = 1, ..., n. Now, by definition of the effective axial function, the collection $\{\alpha(e_{p,1}), \ldots, \alpha(e_{p,m})\}$ spans $H^2(BT^n) \simeq \mathbb{Z}^n$ for each $p \in V(\Gamma)$. This implies that for every $p \in V(\Gamma)$ there is a collection $\{f_1(p), \ldots, f_n(p)\}$ which spans some *n*-dimensional subspace in $\mathbb{Z}E_p(\Gamma)(\simeq \mathbb{Z}^m)$. Since the restriction map (3.1) is injective, this also implies that the set of functions $\{f_1, \ldots, f_n\}$ spans some *n*-dimensional submodule in $\mathcal{A}(\Gamma, \alpha, \nabla)(\subset \mathbb{Z}^m)$. This establishes that $n \leq \operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla)$.

Assume that there is an (m, ℓ) -type GKM graph $(\Gamma, \tilde{\alpha}, \nabla)$ which is an extension of (Γ, α, ∇) for some $n \leq \ell \leq m$. Then it easily follows from Corollary 2.12 and Lemma 3.2 that

$$\ell \leq \operatorname{rk} \mathcal{A}(\Gamma, \widetilde{\alpha}, \nabla) = \operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla) \leq m.$$

This establishes the statement $(1) \Rightarrow (2)$ in Theorem 3.1.

3.2. Proof of $(2) \Rightarrow (1)$.

We next prove (2) \Rightarrow (1) in Theorem 3.1 for an (m, n)-type GKM graph (Γ, α, ∇) . Assume that

$$\ell \leq \operatorname{rank} \mathcal{A}(\Gamma, \alpha, \nabla) (\leq m)$$

for some $\ell \geq n$. We shall prove that there exists an extension (m, ℓ) -type GKM graph $(\Gamma, \tilde{\alpha}, \nabla)$ of the (m, n)-type GKM graph (Γ, α, ∇) .

Let $f \in \mathcal{A}(\Gamma, \alpha, \nabla)$. Put the order of $E_p(\Gamma)$ as $\{e_{1,p}, \ldots, e_{m,p}\}$ for $p \in V(\Gamma)$ and

$$f(p) = \begin{pmatrix} k_{1,p} \\ \vdots \\ k_{m,p} \end{pmatrix}$$

with respect to this order. Then we may define $\alpha_f^a : E(\Gamma) \to \mathbb{Z}a$ for every $a \in H^2(BT^n)$ by

$$\alpha_f^a(e_{j,p}) = k_{j,p}a.$$

We call this label α_f^a on edges an *a*-labeling induced from $f \in \mathcal{A}(\Gamma, \alpha, \nabla)$. From the proof of Lemma 3.2, it is easy to see that $\alpha_i := \pi_i \circ \alpha = \alpha_{f_i}^{a_i}$ for $i = 1, \ldots, n$. Therefore, we obtain the following corollary from the proof of Lemma 3.2, which is the key fact to prove $(2) \Rightarrow (1)$ and tells us that the axial function α can be recovered from $\mathcal{A}(\Gamma, \alpha, \nabla)$ by using α_f^a .

COROLLARY 3.3. Let (Γ, α, ∇) be an (m, n)-type GKM graph. Then there exists $f_i \in \mathcal{A}(\Gamma, \alpha, \nabla)$ for i = 1, ..., n such that $\{f_1, ..., f_n\}$ spans an n-dimensional subspace of $\mathcal{A}(\Gamma, \alpha, \nabla)$ and for the fixed basis $a_1, ..., a_n$ of $H^2(BT^n)$ the axial function can be split into

$$\alpha_1 \oplus \dots \oplus \alpha_n = \alpha : E(\Gamma) \to H^2(BT^n) = \bigoplus_{i=1}^n \mathbb{Z}a_i$$

where $\alpha_i := \alpha_{f_i}^{a_i}$ is the a_i -labeling induced from f_i .

As $\ell \leq \operatorname{rk} \mathcal{A}(\Gamma, \alpha, \nabla)$, there are independent elements (as free \mathbb{Z} -module)

$$f_1,\ldots,f_\ell\in\mathcal{A}(\Gamma,\alpha,\nabla).$$

Moreover, because of $\ell \geq n$, we may choose the first part f_1, \ldots, f_n as the basis induced from (Γ, α, ∇) in Corollary 3.3 (also see the definitions of f_i 's in the proof of Lemma 3.2), and put

$$f_i(p) = \begin{pmatrix} k_{1,p}^{(i)} \\ \vdots \\ k_{m,p}^{(i)} \end{pmatrix} \in \mathbb{Z} E_p(\Gamma) \simeq \mathbb{Z}^m,$$
(3.3)

for $i = 1, ..., \ell$ and $p \in V(\Gamma)$. Fix the basis of $H^2(BT^\ell)$ as $a_1, ..., a_\ell$, where the first n elements $a_1, ..., a_n$ are the basis of $H^2(BT^n)$ (see Corollary 3.3), where $T^n \subset T^\ell$. Let α_i be the a_i -labeling induced from f_i , i.e., $\alpha_i = \alpha_{f_i}^{a_i}$, for $i = 1, ..., \ell$. Then, we can define the function as follows:

$$\widetilde{\alpha} := \bigoplus_{i=1}^{\ell} \alpha_i : E(\Gamma) \to H^2(BT^{\ell}).$$

The following lemma says that the triple $(\Gamma, \tilde{\alpha}, \nabla)$ is a GKM graph extending (Γ, α, ∇) .

LEMMA 3.4. The triple $(\Gamma, \tilde{\alpha}, \nabla)$ defined as above is an (m, ℓ) -type GKM graph which is an extension of an (m, n)-type GKM graph (Γ, α, ∇) .

PROOF. Since $\alpha = \bigoplus_{i=1}^{n} \alpha_i$ and $\tilde{\alpha} = \alpha \oplus (\bigoplus_{i=n+1}^{\ell} \alpha_i)$, it is enough to prove that $\tilde{\alpha}$ satisfies the axioms of a GKM graph under the same connection ∇ of (Γ, α, ∇) .

We first claim that axiom (1) of a GKM graph holds for $\tilde{\alpha}$, i.e., $\tilde{\alpha}(e) = -\tilde{\alpha}(\overline{e})$. To do this, by the definition of $\tilde{\alpha}$, it is enough to show that $\alpha_i(e) = -\alpha_i(\overline{e})$ for all $i = 1, \ldots, \ell$. Let $e = e_{j,p} \in E_p(\Gamma)$ and $\overline{e} = e_{\sigma(j),q} \in E_q(\Gamma)$ for $j = 1, \ldots, m$, where i(e) = p, t(e) = qand σ is the permutation on $\{1, \ldots, m\}$ induced from $\nabla_e : E_q(\Gamma) \to E_p(\Gamma)$. Then by the definition of α_i , we have that

$$\alpha_i(e) = \alpha_i(e_{j,p}) = k_{j,p}^{(i)}a_i$$

and

$$\alpha_i(\overline{e}) = \alpha_i(e_{\sigma(j),q}) = k_{\sigma(j),q}^{(i)} a_i$$

where $f_i(p)_e = k_{j,p}^{(i)}$ and $f_i(q)_{\overline{e}} = k_{\sigma(j),q}^{(i)} \in \mathbb{Z}$. As $f_i \in \mathcal{A}(\Gamma, \alpha, \nabla)$, it follows from Lemma 2.13 that $k_{j,p}^{(i)} = -k_{\sigma(j),q}^{(i)}$. This establishes axiom (1) of a GKM graph.

We next claim condition (4) regarding effectiveness, i.e., $\widetilde{\alpha}_{(p)} = \{\widetilde{\alpha}(e) \mid e \in E_p(\Gamma)\}$ spans $H^2(BT^{\ell})$ for all $p \in V(\Gamma)$. Recall that for $E_p(\Gamma) := \{e_{1,p}, \ldots, e_{m,p}\}$,

$$\widetilde{\alpha}(e_{j,p}) = \bigoplus_{i=1}^{\ell} \alpha_i(e_{j,p}) = \bigoplus_{i=1}^{\ell} k_{j,p}^{(i)} a_i,$$

where the integer $k_{j,p}^{(i)}$ is the *j*th coefficient of $f_i(p) \in \mathbb{Z}^m$ (see (3.3)). Now $\{f_1, \ldots, f_\ell\}$ spans an ℓ -dimensional subspace of $\mathcal{A}(\Gamma, \alpha, \nabla)$. As the restriction map defined in (3.1) is injective (by similar arguments as in the proof of Lemma 3.2), we have that the subset $\{f_1(p), \ldots, f_\ell(p)\} \subset \mathbb{Z}^m$ also spans a subgroup which is isomorphic to \mathbb{Z}^ℓ for all $p \in V(\Gamma)$. This shows that the $(m \times \ell)$ -matrix $(k_{j,p}^{(i)})_{i,j}$ has rank $\ell \leq m$ and some minor (of $(\ell \times \ell)$ smaller square matrix in $(k_{j,p}^{(i)})_{i,j}$) with determinant ± 1 , for all $p \in V(\Gamma)$. Therefore, there are ℓ elements in $\widetilde{\alpha}_{(p)} = \{\widetilde{\alpha}(e_{1,p}), \ldots, \widetilde{\alpha}(e_{m,p})\}$ which generate $H^2(BT^\ell)$. This establishes condition (4).

We also check axiom (2), i.e., $\tilde{\alpha}_{(p)}$ is pairwise linearly independent for all $p \in V(\Gamma)$. As α is an axial function, $\alpha_{(p)}$ is pairwise linearly independent for all $p \in V(\Gamma)$, i.e., $\alpha(e)$ S. KUROKI

and $\alpha(e')$ are linearly independent for all pairs $e, e' \in E_p(\Gamma)$. Moreover, we may write

$$\widetilde{\alpha}(e) = \bigoplus_{i=1}^{\ell} \alpha_i(e) = \bigoplus_{i=1}^{n} \alpha_i(e) \oplus \left(\bigoplus_{i=n+1}^{\ell} \alpha_i(e)\right) = \alpha(e) \oplus \left(\bigoplus_{i=n+1}^{\ell} \alpha_i(e)\right),$$

and

$$\widetilde{\alpha}(e') = \bigoplus_{i=1}^{\ell} \alpha_i(e') = \bigoplus_{i=1}^{n} \alpha_i(e') \oplus \left(\bigoplus_{i=n+1}^{\ell} \alpha_i(e')\right) = \alpha(e') \oplus \left(\bigoplus_{i=n+1}^{\ell} \alpha_i(e')\right).$$

Here, by definition of α_i , the element $\alpha_i(e)$ (resp. $\alpha_i(e')$), for $i = n + 1, \ldots, \ell$, is independent with respect to $\alpha(e)$ (resp. $\alpha(e')$). Hence, we have that $\tilde{\alpha}(e)$ and $\tilde{\alpha}(e')$ are also pairwise linearly independent. This establishes axiom (2).

Finally, we claim axiom (3), i.e., $\tilde{\alpha}$ satisfies the following congruence relation: for each $e' \in E_{i(e)}(\Gamma)$

$$\widetilde{\alpha}(\nabla_e(e')) = \widetilde{\alpha}(e') + c_e(e')\widetilde{\alpha}(e),$$

where $c_e(e')$ is the integer that satisfies

$$\alpha(\nabla_e(e')) = \alpha(e') + c_e(e')\alpha(e).$$

Since $\widetilde{\alpha} = \bigoplus_{i=1}^{\ell} \alpha_i$, it is enough to prove that α_i satisfies the congruence relation:

$$\alpha_i(\nabla_e(e')) = \alpha_i(e') + c_e(e')\alpha_i(e)$$

Set $e = e_{j,p}$ and $e' = e_{h,p}$ for some j, h = 1, ..., m, and $\nabla_e(e') = e_{\sigma(h),q}$. By definition, $\alpha_i(e_{j,p}) = k_{j,p}^{(i)} a_i$. Therefore, it is enough to check the following relation:

$$k_{\sigma(h),q}^{(i)} = k_{h,p}^{(i)} + c_e(e')k_{j,p}^{(i)}.$$
(3.4)

Using $f_i \in \mathcal{A}(\Gamma, \alpha, \nabla)$, (i.e., equation (2.4) holds), Lemma 2.7 and Lemma 2.13, we have

$$N_e(f_i(p)) - f_i(q) = -f_i(p)_e N_e(c_{(\Gamma,\alpha,\nabla)}(e))$$
(3.5)

for all $i = 1, ..., \ell$. Since $e = e_{j,p}$, we have $f_i(p)_e = k_{j,p}^{(i)}$ (see (3.3)). Therefore, equation (3.5) implies that

$$\begin{pmatrix} k_{\sigma^{-1}(1),p}^{(i)} \\ \vdots \\ k_{\sigma^{-1}(m),p}^{(i)} \end{pmatrix} - \begin{pmatrix} k_{1,q}^{(i)} \\ \vdots \\ k_{m,q}^{(i)} \end{pmatrix} = -k_{j,p}^{(i)} \begin{pmatrix} c_e(e_{\sigma^{-1}(1),p}) \\ \vdots \\ c_e(e_{\sigma^{-1}(m),p}) \end{pmatrix} .$$

This shows that

$$k_{h,p}^{(i)} - k_{\sigma(h),q}^{(i)} = -k_{j,p}^{(i)}c_e(e_{h,p}).$$

Since $e' = e_{h,p}$, this equation establishes equation (3.4).

Consequently, $\tilde{\alpha}$ is an extended axial function of α .

This establishes $(2) \Rightarrow (1)$ in Theorem 3.1. Together with Section 3.1, we obtain Theorem 3.1.

REMARK 3.5. Lemma 3.4 tells us that from an element of $\mathcal{A}(\Gamma, \alpha, \nabla)$ we can construct an extension of (Γ, α, ∇) . In fact, by similar arguments, we see that $\mathcal{A}(\Gamma, \alpha, \nabla)$ contains every extension of (Γ, α, ∇) , i.e., every extension of (Γ, α, ∇) corresponds to an element of $\mathcal{A}(\Gamma, \alpha, \nabla)$. Furthermore, it is not so difficult to show that every axial function on Γ whose connection is ∇ can be constructed by an element of $\mathcal{A}(\Gamma, \alpha, \nabla)$. This is the reason why we call $\mathcal{A}(\Gamma, \alpha, \nabla)$ a group of axial functions.

As a corollary, we have the following fact.

COROLLARY 3.6. Let (Γ, α, ∇) be an (m, n)-type GKM graph. If one of the following cases hold, then there are no extensions of (Γ, α, ∇) :

- 1. m = n;
- 2. rk $\mathcal{A}(\Gamma, \alpha, \nabla) = n$.

EXAMPLE 3.7. By Corollary 3.6 and the computation in Example 2.14, the GKM graphs in Figure 1 have no extensions, i.e., they are the maximal GKM graphs.

4. Applications to geometry.

Guillemin–Zara studied GKM graphs as a combinatorial counter part to *GKM manifolds*, and they built a bridge between the geometry (in particular, symplectic) of GKM manifolds and the combinatorics of GKM graphs. In this and the next sections, we give a new application of GKM graphs to study the geometry of GKM manifolds. More precisely, we apply our main result to study the maximal torus actions of GKM manifolds.

4.1. GKM manifold and its GKM graph.

We first briefly recall the relation between GKM manifolds and GKM graphs (see [11] for details). Let M be a 2m-dimensional, compact, connected smooth manifold with an effective n-dimensional torus T^n -action, where $1 \leq n \leq m$. We often denote such a manifold by (M,T) or (M,T,φ) if we emphasize the action $\varphi: T \times M \to M$. Denote by $M_1 \subset M$ the set of elements $x \in M$ such that the orbit $T(x) = \{x\}$ (a fixed point) or $T(x) \simeq S^1$, i.e.,

$$M_1 = \{ x \in M \mid \dim T(x) \le 1 \}.$$

The set M_1 is called the *one-skeleton* of (M, T).

A 2*m*-dimensional manifold with an *n*-dimensional torus action (M, T) is said to be a *GKM manifold* or an (m, n)-type *GKM manifold* if the following three conditions hold:

1. $M^T \neq \emptyset;$

 \square

- 2. the manifold M has a T-invariant almost complex structure;
- 3. the one-skeleton of M has the structure of an abstract (connected) graph Γ_M such that its vertices $V(\Gamma_M)$ are the fixed points and its edges $E(\Gamma_M)$ are embedded 2-spheres connecting two fixed points.

REMARK 4.1. The third condition implies that the orbit space of the one-skeleton is one-dimensional. Therefore, together with condition (1), the set of fixed points M^T is always isolated. Moreover, by definition of the (m, n)-type GKM manifold M, if $\dim T(=n) = 1$ then M is equivariantly diffeomorphic to $\mathbb{C}P^1$ with a non-trivial S^1 action. So, in this paper, we often assume $2 \le n \le m$ for an (m, n)-type GKM manifold. We also do not assume the equivariant formality because we do not use the equivariant cohomolgy of GKM manifolds.

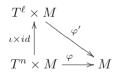
Due to [11], the GKM manifold M defines the GKM graph $(\Gamma_M, \alpha_M, \nabla_M)$ by using its one-skeleton and the tangential representations. In this paper, such a GKM graph (Γ_M, α_M) (or $(\Gamma_M, \alpha_M, \nabla_M)$) is called an *induced GKM graph* from M.

EXAMPLE 4.2. In Figure 1, the left GKM graph is the GKM graph induced from the standard T^2 -action on $\mathbb{C}P^2$ and the right one is that induced from T^3 -action on $\mathbb{C}P^3$. The middle GKM graph is induced from the T^2 -action on $S^6 = G_2/SU(3)$, where G_2 is the exceptional Lie group, see [9, Section 5.2].

4.2. Extensions of torus actions.

The definition of an extension of GKM graphs in Section 2.1 is motivated by an extension of a torus action on a GKM manifold. We explain it more precisely in this section.

Let (M, T^n, φ) be a manifold with an effective *n*-dimensional torus action $\varphi : T^n \times M \to M$ (not necessarily a GKM manifold). If there exists an effective ℓ -dimensional torus action (M, T^{ℓ}, φ') (for $n < \ell$) and an injective homomorphism $\iota : T^n \to T^{\ell}$ such that the following diagram commutes:



then (M, T^{ℓ}, φ') is called an *extension* of (M, T^n, φ) . We prove the following fact:

PROPOSITION 4.3. If (M^{2m}, T^{ℓ}) is an extension of an (m, n)-type GKM manifold (M^{2m}, T^n) (for $n < \ell \leq m$) and the T^{ℓ} -action preserves the almost complex structure of M, then (M^{2m}, T^{ℓ}) is an (m, ℓ) -type GKM manifold.

Furthermore, the induced (m, ℓ) -type GKM graph $(\widetilde{\Gamma}_M, \widetilde{\alpha}_M, \widetilde{\nabla}_M)$ from (M, T^{ℓ}) is an extension of the induced (m, n)-type GKM graph $(\Gamma_M, \alpha_M, \nabla_M)$ from (M, T^n) .

PROOF. Since the T^{ℓ} -action preserves the almost complex structure of M, it is enough to check that its one-skeleton has the structure of a graph. We note that for all

 $p \in M$ two orbits of p of these actions satisfy $T^n(p) \subset T^{\ell}(p)$, because the T^{ℓ} -action is an extension of T^n -action.

We first claim that $M^{T^n} = M^{T^{\ell}}$. Because $T^n(p) \subset T^{\ell}(p)$ for all $p \in M$, we have that $M^{T^n} \supset M^{T^{\ell}}$. Assume that there exists a fixed point $p \in M^{T^n}$ such that $T^{\ell}(p) \neq \{p\}$. As is well-known, there is a decomposition $T_pM = T_pT^{\ell}(p) \oplus N_pT^{\ell}(p)$, where $T_pT^{\ell}(p)(\neq \{0\})$ is the tangent space and $N_pT^{\ell}(p)$ is the normal space of $T^{\ell}(p)$ on p. By using the differentiable slice theorem, the isotropy subgroup T_p^{ℓ} (of the T^{ℓ} -action on p) acts on $T_pT^{\ell}(p)$ trivially. This shows that $T^n(\subset T_p^{\ell})$ also acts on $T_pT^{\ell}(p)$ trivially. However, by the definition of GKM manifolds, for the restricted action (T_pM, T^n) , there is another decomposition $T_pM = \bigoplus_{i=1}^m V(a_i)$ such that each representation $a_i : T^n \to S^1$ is non-trivial. This contradicts that T^n acts on $(\{0\} \neq)T_pT^{\ell}(p) \subset T_pM$ trivially. Hence, $M^{T^n} = M^{T^{\ell}}$.

Take $p \in M$ such that $T^n(p) \simeq S^1$. Since we assume that the one-skeleton of (M, T^n) has the structure of a connected graph, we have that p is an element in an invariant 2-sphere S^2 of (M, T^n) . As $M^{T^n} = M^{T^\ell}$, by considering the tangential representation around fixed points on this T^n -invariant $S^2(\ni p)$, there exists a representation $\rho: T^\ell \to S^1$ which may be regarded as the extension of the T^n -action on this S^2 . Therefore, every T^n -invariant S^2 is also a T^ℓ -invariant S^2 , i.e., if $T^n(p) \simeq S^1$ then $T^\ell(p) \simeq S^1$. Together with $T^n(p) \subset T^\ell(p)$ for all $p \in M$, this implies that the two one-skeletons of (M^{2m}, T^n) and (M^{2m}, T^ℓ) are the same.

We next prove the final statement. By arguments similar to the above, we have $\widetilde{\Gamma}_M = \Gamma_M$. Moreover, because the extended T^{ℓ} -action preserves the T^n -invariant almost complex structure, the splitting $\bigoplus_{i=1}^m \mathbb{L}_i$, of the restriction of the tangent bundle to such as S^2 , by the T^n -action is also preserved by the extended T^{ℓ} -action. This implies that the two connections on the induced GKM graphs ∇_M from the T^n -action and $\widetilde{\nabla}_M$ from the extended T^{ℓ} -action are the same. Finally, put the induced homomorphism from the inclusion $\iota: T^n \to T^{\ell}$ as $\pi: H^2(BT^{\ell}) \to H^2(BT^n)$. Then by considering the tangential representations (of both T^n and T^{ℓ} -actions) around fixed points, it is easy to check that there is the following commutative diagram:

 $\begin{array}{c|c} & H^2(BT^\ell) \\ & & & & \\ & & & & \\ & & & & \\ E(\Gamma_M) \xrightarrow{\alpha_M} H^2(BT^n) \ . \end{array}$

This establishes the final statement.

Therefore, by using Theorem 3.1 (or Theorem 1.2) and Proposition 4.3, we have Corollary 1.3.

4.3. Maximal torus action on $S^6 = G_2/SU(3)$.

As we mentioned in Example 4.2, the (3, 2)-type GKM graph in Figure 1 is the induced GKM graph of the GKM manifold $(G_2/SU(3), T^2)$, where T^2 acts on G_2 as its

maximal torus subgroup (e.g. see [9]). We also note that $G_2/SU(3) \simeq S^6$ (diffeomorphic). Therefore, by using Corollary 1.3 and Example 2.14, the following well-known fact can be proved (see also [3]):

COROLLARY 4.4. The T^2 -action on $G_2/SU(3) \simeq S^6$ is the maximal torus action. In other words, there are no extended T^3 -actions on S^6 of this T^2 -action, which preserves the almost complex structure induced from the homogeneous space $G_2/SU(3)$.

REMARK 4.5. Note that there is the T^3 -action on $S^6 \subset \mathbb{C}^3 \oplus \mathbb{R}$ defined by the standard T^3 -action on \mathbb{C}^3 (see e.g. [15]). However, from Corollary 4.4, this action is not the extended action of the T^2 -action on $S^6 = G_2/SU(3)$.

In the next section, we shall apply our results for more complicated GKM manifolds.

5. Maximal torus action on the complex Grassmannian $G_2(\mathbb{C}^{n+2})$.

The (complex) Grassmannian (of 2-planes in \mathbb{C}^{n+2}), denoted by $G_2(\mathbb{C}^{n+2})$, is defined by the set of all complex 2-dimensional vector spaces in \mathbb{C}^{n+2} . Namely,

$$G_2(\mathbb{C}^{n+2}) := \{ V \subset \mathbb{C}^{n+2} \mid \dim_{\mathbb{C}} V = 2 \}.$$
 (5.1)

The Grassmannian $G_2(\mathbb{C}^{n+2})$ has the natural transitive SU(n+2)-action which is induced from the standard SU(n+2)-action on \mathbb{C}^{n+2} . Since its isotropy group is $S(U(2) \times U(n))$, $G_2(\mathbb{C}^{n+2})$ is diffeomorphic to the homogeneous space $SU(n+2)/S(U(2) \times U(n))$ (also see [13]). In particular, this shows that

$$\dim G_2(\mathbb{C}^{n+2}) = \dim SU(n+2)/S(U(2) \times U(n)) = 4n.$$

Since a maximal torus of SU(n + 2) is isomorphic to T^{n+1} , there is a restricted T^{n+1} -action on $G_2(\mathbb{C}^{n+2})$ and its one-skeleton has the structure of a graph (see [9]). We denote this action by $(SU(n + 2)/S(U(2) \times U(n)), T^{n+1})$. Note that the action $(SU(n + 2)/S(U(2) \times U(n)), T^{n+1})$ is not effective because there is the non-trivial center in SU(n + 2) (isomorphic to $\mathbb{Z}/(n + 2)\mathbb{Z}$); therefore, the GKM graph obtained from this action does not satisfy condition (4) in Section 2, i.e., the axial function is not an effective axial function. So, in this paper, we define the T^{n+1} -action on $G_2(\mathbb{C}^{n+2})$ by the induced action from the standard T^{n+1} -action on the first (n+1)-coordinates in \mathbb{C}^{n+2} (see (5.1)). We denote this action as $(G_2(\mathbb{C}^{n+2}), T^{n+1})$. It is easy to check that $(G_2(\mathbb{C}^{n+2}), T^{n+1})$ is effective and preserves the complex structure of $G_2(\mathbb{C}^{n+2})$ induced from that of \mathbb{C}^{n+2} . For example, when n = 1, $(G_2(\mathbb{C}^3), T^2)$ is equivariantly diffeomorphic to the complex projective space $\mathbb{C}P^2$ with the standard T^2 -action, i.e., the toric manifold. Note that, for $n \geq 2$, $(G_2(\mathbb{C}^{n+2}), T^{n+1})$ is not a toric manifold.

REMARK 5.1. GKM graphs obtained from the non-effective torus actions for flag manifolds are studied by Tymoczko in [20] Fukukawa–Ishida–Masuda in [6] etc.

In the next subsection, we compute the GKM graph of $(G_2(\mathbb{C}^{n+2}), T^{n+1})$. For simplicity, we put

$$M_n = G_2(\mathbb{C}^{n+2})$$

from the next subsection.

REMARK 5.2. The following computation of the GKM graph of $(G_2(\mathbb{C}^{n+2}), T^{n+1})$ is not new. In [9], the computation of GKM graphs of more general homogeneous spaces are treated. However, for convenience, we give a precise computation here.

5.1. The GKM graph of $(G_2(\mathbb{C}^{n+2}), T^{n+1})$.

Let $(\Gamma_n, \alpha_n, \nabla_n)$ be the induced GKM graph from (M_n, T^{n+1}) . Note that $\Gamma_n = (V(\Gamma_n), E(\Gamma_n))$ is a 2*n*-valent graph, because the real dimension of M_n is 4n, where $n \ge 1$.

We first consider the fixed points of (M_n, T^{n+1}) . By definition, the Grassmannian M_n may be identified with the following set:

 $\{[v_1, v_2] \mid v_1, v_2 \text{ are linearly independent in } \mathbb{C}^{n+2}\},\$

where the symbol $[v_1, v_2]$ represents the equivalence class such that $[v_1, v_2]$ is identified with $[w_1, w_2]$ if two pairs of vectors $\{v_1, v_2\}$ and $\{w_1, w_2\}$ span the same 2-dimensional complex vector space in \mathbb{C}^{n+2} . Under this identification, the element $t \in T^{n+1}$ acts on $[v_1, v_2] \in M_n$ by

$$t \cdot [v_1, v_2] \mapsto [tv_1, tv_2],$$

where $t \in T^{n+1}$ acts on $v \in \mathbb{C}^{n+2}$ by the standard coordinatewise multiplication on the first (n+1)-coordinates. Then, the fixed points can be denoted by

$$M_n^T := \{ [e_i, e_j] \mid i \neq j, i, j = 1, \dots, n+2 \},\$$

where e_1, \ldots, e_{n+2} are the standard basis in \mathbb{C}^{n+2} . By identifying the element $[e_i, e_j] \in M_n^T$ as the subset $\{i, j\}$ in $[n+2] := \{1, 2, \ldots, n+2\}$, we may regard the set of vertices $V(\Gamma_n)$ as

$$V(\Gamma_n) = \{\{i, j\} \subset [n+2] \mid i \neq j\}.$$

We also have that

$$|V(\Gamma_n)| = \binom{n+2}{2} = \frac{(n+2)(n+1)}{2}$$

We next consider the invariant 2-spheres in (M_n, T^{n+1}) . Fix $\{i, j\} \subset [n+2]$. Now the following subsets are T^{n+1} -invariant sets in M_n which contain $[e_i, e_j]$:

$$S_{i,j}^{i,k} = \{ [e_i, v_{jk}] \in M_n \mid v_{jk} = a_j e_j + a_k e_k, \ (a_j, a_k) \in \mathbb{C}^2 \setminus \{0\} \};$$

$$S_{i,j}^{j,k} = \{ [v_{ik}, e_j] \in M_n \mid v_{ik} = a_i e_i + a_k e_k, \ (a_i, a_k) \in \mathbb{C}^2 \setminus \{0\} \},$$

for all $k \in [n+2] \setminus \{i, j\}$.

As $[e_i, v_{jk}]$ and $[e_i, \lambda v_{jk}]$ (for all $\lambda \in \mathbb{C}^*$) are the same element in M_n , we have that

 $S_{i,j}^{i,k}$ is diffeomorphic to $\mathbb{C}P^1$. Similarly, $S_{i,j}^{j,k}$ is also diffeomorphic to $\mathbb{C}P^1$. Moreover, $[e_i, e_j], [e_i, e_k] \in S_{i,j}^{i,k}$ and $[e_i, e_j], [e_k, e_j] \in S_{i,j}^{j,k}$. This shows that if $\{i, j\} \cap \{k, l\} \neq \emptyset$ then the fixed points $[e_i, e_j]$ and $[e_k, e_l]$ are on the same invariant 2-sphere. Namely, the pair of two distinct sets $\{i, j\}$ and $\{k, l\}$ such that $\{i, j\} \cap \{k, l\} \neq \emptyset$ may be regarded as an edge of the GKM graph, i.e., an element in $E(\Gamma_n)$. We call the edge corresponding to $S_{i,j}^{i,k}$ (resp. $S_{i,j}^{j,k}$) as $E_{i,j}^{i,k} \in E(\Gamma_n)$ (resp. $E_{i,j}^{j,k} \in E(\Gamma_n)$). Note that for all $k \in [n+2] \setminus \{i, j\}$, $E_{i,j}^{i,k}$ and $E_{i,j}^{j,k}$ are out-going edges from $\{i, j\}$. Since dim $M_n = 4n$, the number of out-going edges from $\{i, j\}$ is 2n. Hence, the set of all out-going edges from $\{i, j\}$ can be denoted by

$$E_{\{i,j\}}(\Gamma_n) = \{E_{i,j}^{i,k}, E_{i,j}^{j,k} \mid k \in [n+2] \setminus \{i,j\}\}.$$

Figure 4 shows the one-skeleton induced from $G_2(\mathbb{C}^4)$.

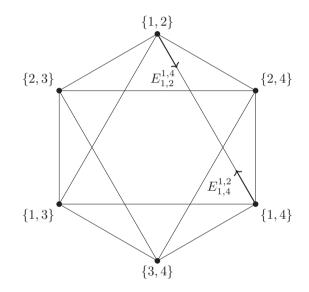


Figure 4. The vertices and edges of the one-skeleton of the Grassmannian $G_2(\mathbb{C}^4)$.

Next we consider the tangential representations around fixed points. To do that, we use the following notations:

- the symbol $E(\eta)$ represents the total space of the fibre bundle η over M_n ;
- the symbol η_p is the restriction of η onto $p \in M_n$;

Recall the structure of the tangent bundle τ of M_n . Let $\epsilon_{\mathbb{C}}^{n+2}$ be the trivial bundle $E(\epsilon_{\mathbb{C}}^{n+2}) = M_n \times \mathbb{C}^{n+2} \to M_n$. Then, the *tautological vector bundle* γ over M_n is defined as follows:

$$E(\gamma) = \{ (V, x) \in M_n \times \mathbb{C}^{n+2} \mid x \in V \} \to M_n,$$

where the projection of the bundle is just the projection onto the 1st factor. Note that γ is a complex 2-dimensional vector bundle over M_n and the diagonal T^{n+1} -action on $M_n \times \mathbb{C}^{n+2}$ induces the T^{n+1} -action on $E(\gamma)$; thus we may regard γ as the T^{n+1} equivariant vector bundle. Let γ^{\perp} be the normal bundle of γ in $\epsilon_{\mathbb{C}}^{n+2}$ (we define the inner product on \mathbb{C}^{n+2} as the standard Hermitian inner product). Since γ is a complex 2-dimensional vector bundle, γ^{\perp} is a complex *n*-dimensional vector bundle. Moreover, since the T^{n+1} -action on \mathbb{C}^{n+2} preserves the standard Hermitian inner product, the diagonal T^{n+1} -action on $M_n \times \mathbb{C}^{n+2}$ induces the T^{n+1} -action on γ^{\perp} .

Similar to the case of the real Grassmannian (see [18, Section 5 or proof of Theorem 14.10]), the tangent bundle τ of M_n is isomorphic to the complex 2*n*-dimensional vector bundle Hom (γ, γ^{\perp}) . Therefore, the tangent space around $[e_i, e_j] \in M_n^T$ may be regarded as

$$\tau_{[e_i,e_j]} \equiv \operatorname{Hom}(\gamma_{[e_i,e_j]},\gamma_{[e_i,e_j]}^{\perp}).$$

Since the total space of $\gamma_{[e_i,e_j]}$ is $V_{ij} := \{A_i e_i + A_j e_j \mid (A_i, A_j) \in \mathbb{C}^2\}$, its normal space in \mathbb{C}^{n+2} consists of

$$V_{ij}^{\perp} = \left\{ \sum_{k \in [n+2] \setminus \{i,j\}} B_k e_k \ \middle| \ B_k \in \mathbb{C} \right\}.$$

Therefore, $\varphi \in \operatorname{Hom}(V_{ij}, V_{ij}^{\perp})$ can be denoted by

$$\varphi(A_i e_i + A_j e_j) = \sum_{k \in [n+2] \setminus \{i,j\}} f_k(A_i, A_j) e_k$$

for some linear map $f_k : \mathbb{C}^2 \to \mathbb{C}$, i.e., $f_k(A_i, A_j) = A_i \ell_{ik} + A_j \ell_{jk}$ for some $(\ell_{ik}, \ell_{jk}) \in \mathbb{C}^2$ (we will identify f_k as (ℓ_{ik}, ℓ_{jk})). Then, we may regard $\varphi = (f_k)_{k \in [n+2] \setminus \{i,j\}} \in M(2, n; \mathbb{C})$ as the complex $(2 \times n)$ -matrix. Now the T^{n+1} -actions on γ and γ^{\perp} induce the T^{n+1} -action on $\operatorname{Hom}(\gamma, \gamma^{\perp})$ as follows: for $\varphi \in \operatorname{Hom}(\gamma_x, \gamma_x^{\perp})$ $(x \in M_n)$ and $t \in T^{n+1}$,

$$t \cdot \varphi = t \circ \varphi \circ t^{-1} : \gamma_{tx} \xrightarrow{t^{-1}} \gamma_x \xrightarrow{\varphi} \gamma_x^{\perp} \xrightarrow{t} \gamma_{tx}^{\perp}.$$

Therefore, on $x = [e_i, e_j]$, we have $t \cdot f_k = (t_i^{-1} t_k \ell_{ik} t_j^{-1} t_k \ell_{jk})$ for $f_k = (\ell_{ik} \ell_{jk}), \varphi = (f_k) \in M(2, n; \mathbb{C})$ and $t = (t_1, \ldots, t_{n+1}, 1) \in T^{n+2}$, i.e., $t_{n+2} = 1$. Hence, on the fixed point $[e_i, e_j] \in M_n^T$, we have the tangential representation as follows:

$$\operatorname{Hom}(\gamma_{[e_i,e_j]},\gamma_{[e_i,e_j]}^{\perp}) \simeq \bigoplus_{k \in [n+2] \setminus \{i,j\}} V(-a_i + a_k) \oplus V(-a_j + a_k),$$
(5.2)

where a_1, \ldots, a_{n+1} are the (dual) basis of the dual of Lie algebra \mathfrak{t}^* of T^{n+1} and we put $a_{n+2} = 0$. It is easy to check that the factor $V(-a_i + a_k)$ (resp. $V(-a_j + a_k)$) in (5.2) may be regarded as the tangent space on $[e_i, e_j]$ of the invariant 2-sphere $S_{i,j}^{j,k}$ (resp. $S_{i,j}^{i,k}$). Therefore, the axial function $\alpha_n : E(\Gamma_n) \to H^2(BT^{n+1}) \simeq \mathfrak{t}_{\mathbb{Z}}^*$ is defined as follows:

$$\alpha_n(E_{i,j}^{i,k}) = -a_j + a_k, \quad \alpha_n(E_{i,j}^{j,k}) = -a_i + a_k.$$
(5.3)

By the definition of edges, the reversed orientation edge satisfies $\overline{E_{i,j}^{i,k}} = E_{i,k}^{i,j}$ (resp. $\overline{E_{i,j}^{j,k}} = E_{j,k}^{i,j}$). Therefore, by the definition of the axial function the following equation holds:

$$\alpha_n(E_{i,k}^{i,j}) = -a_k + a_j = -\alpha_n(E_{i,j}^{i,k}) \quad (\text{resp. } \alpha_n(E_{j,k}^{i,j}) = -a_k + a_i = -\alpha_n(E_{i,j}^{j,k})).$$

We finally compute a connection on (Γ_n, α_n) . Put the connection on the edge $E_{i,j}^{i,k}$ as $(\nabla_n)_{E_{i,j}^{i,k}} = (\nabla_n)_{i,j}^{i,k}$. Namely,

$$(\nabla_n)_{i,j}^{i,k}: E_{\{i,j\}}(\Gamma_n) \to E_{\{i,k\}}(\Gamma_n),$$

where

$$E_{\{i,j\}}(\Gamma_n) := \{E_{i,j}^{i,l}, E_{i,j}^{j,l} \mid l \in [n+2] \setminus \{i,j\}\},\$$
$$E_{\{i,k\}}(\Gamma_n) := \{E_{i,k}^{i,l}, E_{i,k}^{k,l} \mid l \in [n+2] \setminus \{i,k\}\}.$$

Note that the set of the weights $\{-a_i + a_k, -a_j + a_k \mid k \in [n+2] \setminus \{i, j\}\}$ are 3independent for all $\{i, j\} \subset [n+2]$ (see (5.3)). Therefore, it follows from Lemma 2.3 that the connection ∇_n on (Γ_n, α_n) is unique. This implies that the bijection $(\nabla_n)_{i,j}^{i,k}$ which satisfies the congruence relation (2.1) is unique. Hence, by computing the congruence relation (2.1) of (Γ_n, α_n) , the connection must be defined as follows:

$$\begin{aligned} (\nabla_n)_{i,j}^{i,k}(E_{i,j}^{i,k}) &= \overline{E_{i,j}^{i,k}} = E_{i,k}^{i,j}, \\ (\nabla_n)_{i,j}^{i,k}(E_{i,j}^{i,l}) &= E_{i,k}^{i,l} \quad \text{for } l \in [n+2] \setminus \{i,j,k\}, \\ (\nabla_n)_{i,j}^{i,k}(E_{i,j}^{j,l}) &= E_{i,k}^{k,l} \quad \text{for } l \in [n+2] \setminus \{i,j,k\}, \\ (\nabla_n)_{i,j}^{i,k}(E_{i,j}^{j,k}) &= E_{i,k}^{j,k}. \end{aligned}$$

In addition, we also have that

$$\alpha_n(E_{i,k}^{i,l}) - \alpha_n(E_{i,j}^{i,l}) = c_{i,j}^{i,k}(E_{i,j}^{i,l})\alpha_n(E_{i,j}^{i,k}),$$

$$-a_k + a_l - (-a_j + a_l) = c_{i,j}^{i,k}(E_{i,j}^{i,l})(-a_j + a_k)$$

and

$$\alpha_n(E_{i,k}^{k,l}) - \alpha_n(E_{i,j}^{j,l}) = c_{i,j}^{i,k}(E_{i,j}^{j,l})\alpha_n(E_{i,j}^{i,k}),$$

$$-a_i + a_l - (-a_i + a_l) = c_{i,j}^{i,k}(E_{i,j}^{j,l})(-a_j + a_k),$$

for $l \in [n+2] \setminus \{i, j, k\}$ and

$$\alpha_n(E_{i,k}^{j,k}) - \alpha_n(E_{i,j}^{j,k}) = c_{i,j}^{i,k}(E_{i,j}^{j,k})\alpha_n(E_{i,j}^{i,k}),$$

$$-a_i + a_j - (-a_i + a_k) = c_{i,j}^{i,k}(E_{i,j}^{j,k})(-a_j + a_k),$$

for some integers (congruence coefficients) $c_{i,j}^{i,k}(E_{i,j}^{i,l}), c_{i,j}^{i,k}(E_{i,j}^{j,l})$. Therefore, together with

Lemma 2.4, the congruence coefficients are

$$c_{i,j}^{i,k}(E_{i,j}^{i,k}) = -2,$$

$$c_{i,j}^{i,k}(E_{i,j}^{i,l}) = -1 \quad \text{for } l \in [n+2] \setminus \{i, j, k\},$$

$$c_{i,j}^{i,k}(E_{i,j}^{j,l}) = 0 \quad \text{for } l \in [n+2] \setminus \{i, j, k\},$$

$$c_{i,j}^{i,k}(E_{i,j}^{j,k}) = -1.$$

In summary we have that

PROPOSITION 5.3. Let $\Gamma_n = (V(\Gamma_n), E(\Gamma_n))$ be the abstract graph defined by

- the set of vertices $V(\Gamma_n)$ consists of all $\{i, j\}$ in [n+2] for $i \neq j$;
- the set of edges E(Γ_n) consists of all pairs of distinct vertices {i, j}, {k, l} such that {i, j} ∩ {k, l} ≠ Ø.

Define its axial function as $\alpha_n : E(\Gamma_n) \to H^2(BT^{n+1})$ in (5.3). Then, the connection ∇_n is uniquely determined (as above) and the triple $(\Gamma_n, \alpha_n, \nabla_n)$ is the (2n, n+1)-type GKM graph.

REMARK 5.4. The graph in Proposition 5.3 is known as the Johnson graph J(n+2,2). The first GKM graph in Figure 1 shows the case when n = 1, i.e., the Johnson graph J(3,2), and the GKM graph in Figure 5 shows the case when n = 2, i.e.,

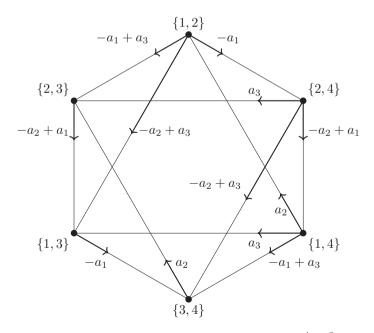


Figure 5. The GKM graph $(\Gamma_2, \alpha_2, \nabla_2)$ of $(G_2(\mathbb{C}^4), T^3)$.

the Johnson graph J(4, 2). It is known that the one-skeleton of the general Grassmannian $G_k(\mathbb{C}^{n+k})$ (for $k \ge 1$) is the Johnson graph J(n+k, k) (see [1]).

5.2. The second main result.

Since we fix the axial function α_n on Γ_n and its connection ∇_n is unique, we may write the GKM graph $(\Gamma_n, \alpha_n, \nabla_n)$ of (M_n, T^{n+1}) as Γ_n for simplicity; therefore, we denote the group of axial functions $\mathcal{A}(\Gamma_n, \alpha_n, \nabla_n)$ as $\mathcal{A}(\Gamma_n)$. This final section is devoted to the proof of the following theorem:

THEOREM 5.5. The group of axial functions $\mathcal{A}(\Gamma_n)$ is isomorphic to \mathbb{Z}^{n+1} .

When n = 1, the GKM graph Γ_1 is the (2, 2)-type GKM graph (which is the first GKM graph in Figure 1). Therefore, by Theorem 3.1, we have that $\mathcal{A}(\Gamma_1) \simeq \mathbb{Z}^2$. Hence, we may assume that $n \geq 2$.

To prove Theorem 5.5, we first choose an order on $E_{\{i,j\}}(\Gamma_n)$ for $i, j \in [n+2]$ as follows (see Figure 6 for n = 2):

- $E_{i,j}^{i,k} \prec E_{i,j}^{j,l}$ if i < j, where $k, l \in [n+2] \setminus \{i,j\};$
- $E_{i,j}^{i,k} \prec E_{i,j}^{i,l}$ if k < l, where $k, l \in [n+2] \setminus \{i, j\}$.

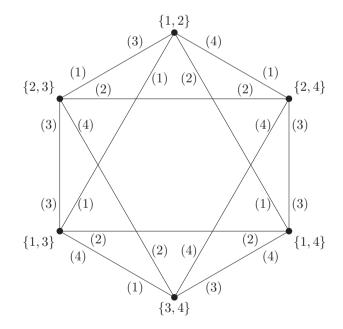


Figure 6. The order of out-going edges on each vertex of Γ_2 . For example, around the vertex $\{1,3\}$, Figure shows that $E_{1,3}^{1,2} \prec E_{1,3}^{1,4} \prec E_{1,3}^{2,3} \prec E_{1,3}^{3,4}$.

Take $f \in \mathcal{A}(\Gamma_n)$ and put

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$$f(\{n+1, n+2\}) = \begin{pmatrix} x_1 \\ \vdots \\ x_{2n} \end{pmatrix}$$

with respect to the order on $E_{\{n+1,n+2\}}(\Gamma_n)$ defined as before, i.e.,

$$E_{n+1,n+2}^{1,n+1} \prec \dots \prec E_{n+1,n+2}^{n,n+1} \prec E_{n+1,n+2}^{1,n+2} \prec \dots \prec E_{n+1,n+2}^{n,n+2}$$

More precisely, using the notation $f(p)_e$ defined in Section 2.3 for $p \in V(\Gamma_n)$ and $e \in E_p(\Gamma_n)$, we define the following correspondence between edges and integers (variables):

$$E_{n+1,n+2}^{1,n+1} \mapsto f(\{n+1,n+2\})_{E_{n+1,n+2}^{1,n+1}} = x_1;$$

$$\vdots$$

$$E_{n+1,n+2}^{n,n+1} \mapsto f(\{n+1,n+2\})_{E_{n+1,n+2}^{n,n+1}} = x_n;$$

$$E_{n+1,n+2}^{1,n+2} \mapsto f(\{n+1,n+2\})_{E_{n+1,n+2}^{1,n+2}} = x_{n+1};$$

$$\vdots$$

$$E_{n+1,n+2}^{n,n+2} \mapsto f(\{n+1,n+2\})_{E_{n+1,n+2}^{n,n+2}} = x_{2n}.$$

Then by the connectedness of Γ_n and the definition of $\mathcal{A}(\Gamma_n)$, the vector $f(\{i, j\})$ is denoted by the variables x_1, \ldots, x_{2n} for all $\{i, j\}$'s in $V(\Gamma_n)$. This shows that rk $\mathcal{A}(\Gamma_n) \leq 2n$ (this is also known from Theorem 3.1 and the fact that Γ_n is a (2n, n+1)-type GKM graph). By Theorem 3.1, we also have rk $\mathcal{A}(\Gamma_n) \geq n+1$. Therefore, in order to prove Theorem 5.5, it is enough to prove that the variables x_{n+2}, \ldots, x_{2n} can be denoted by the other variables x_1, \ldots, x_{n+1} . We shall prove that the following lemma holds.

LEMMA 5.6. For
$$j = 0, ..., n-2$$
 $(n \ge 2)$, the following equation holds:

$$x_{2n-j} = -x_1 + x_{n-j} + x_{n+1}.$$

PROOF. Recall the definition of the connection ∇_n in Section 5.1. There is the triangle GKM subgraph in Γ_n (i.e., a subgraph closed under the connection) which is spanned by the vertices $\{n+1, n+2\}$, $\{1, n+1\}$, $\{1, n+2\}$ (see Figure 7). We first show the variables corresponding to the edges in this triangle is as in Figure 7.

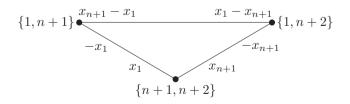


Figure 7. The triangle GKM subgraph with corresponding variables on edges.

We assumed $f(\{n+1, n+2\})_{E_{n+1,n+2}^{1,n+1}} = x_1$ (and $f(\{n+1, n+2\})_{E_{n+1,n+2}^{1,n+2}} = x_{n+1}$). So, by Lemma 2.13,

$$f(\{1, n+1\})_{E_{1,n+1}^{n+1,n+2}} = -x_1.$$

Moreover, the connection satisfies

$$(\nabla_n)_{n+1,n+2}^{1,n+1}(E_{n+1,n+2}^{1,n+2}) = E_{1,n+1}^{1,n+2}$$

and the congruence coefficient satisfies

$$c_{n+1,n+2}^{1,n+1}(E_{n+1,n+2}^{1,n+2}) = -1$$

Therefore, we have the following equation by the definition of $f \in \mathcal{A}(\Gamma_n)$:

$$x_{n+1} - f(\{1, n+1\})_{E_{1,n+1}^{1,n+2}} = (-1) \times (-x_1)$$

Hence, we have $f(\{1, n+1\})_{E_{1,n+1}^{1,n+2}} = x_{n+1} - x_1$, i.e., the correspondence $E_{1,n+1}^{1,n+2} \mapsto x_{n+1} - x_1$. Together with Lemma 2.13 we also have the correspondence

$$E_{1,n+2}^{1,n+1} \mapsto x_1 - x_{n+1}.$$

This establishes the variables in Figure 7.

We next consider the subgraph drawn in Figure 8 and compute the corresponding variables on edges in this subgraph as in Figure 8.

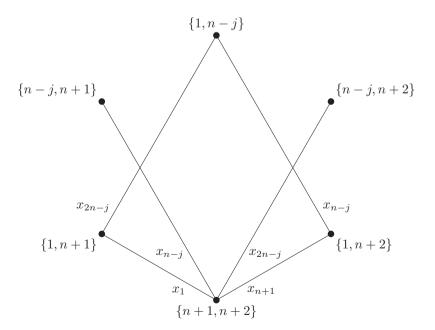


Figure 8. The subgraph with corresponding variables on edges.

We assumed $f(\{n+1, n+2\})_{E_{n+1,n+2}^{n-j,n+2}} = x_{2n-j} \text{ (and } f(\{n+1, n+2\})_{E_{n+1,n+2}^{n-j,n+1}} = x_{n-j})$ for $0 \le j \le n-2$. As $(\nabla_n)_{n+1,n+2}^{1,n+1} (E_{n+1,n+2}^{n-j,n+2}) = E_{1,n+1}^{1,n-j}$ and $c_{n+1,n+2}^{1,n+1} (E_{n+1,n+2}^{n-j,n+2}) = 0$, we have the correspondence

$$E_{1,n+1}^{1,n-j} \mapsto x_{2n-j}$$

Similarly, because $(\nabla_n)_{n+1,n+2}^{1,n+2}(E_{n+1,n+2}^{n-j,n+1}) = E_{1,n+2}^{1,n-j}$ and $c_{n+1,n+2}^{1,n+2}(E_{n+1,n+2}^{n-j,n+2}) = 0$, we have the correspondence

$$E_{1,n+2}^{1,n-j} \mapsto x_{n-j}.$$

This establishes the variables in Figure 8.

By Figure 7 and Figure 8, we have the triangle GKM subgraph with variables as in Figure 9.

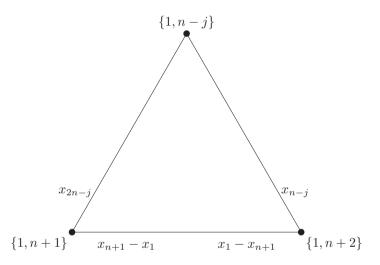


Figure 9. The triangle GKM subgraph with corresponding variables on edges.

In Figure 9, $(\nabla_n)_{1,n+1}^{1,n+2}(E_{1,n+1}^{1,n-j}) = E_{1,n+2}^{1,n-j}$ and $c_{1,n+1}^{1,n+2}(E_{1,n+1}^{1,n-j}) = -1$. Therefore, by definition of $f \in \mathcal{A}(\Gamma_n)$, we have the equation

$$x_{2n-j} - x_{n-j} = -1(x_1 - x_{n+1}).$$

This establishes that $x_{2n-j} = -x_1 + x_{n-j} + x_{n+1}$.

Consequently, this shows Theorem 5.5. Therefore, by Corollary 1.3, we have Proposition 1.5.

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Shintarô Kuroki

Department of Applied Mathematics Okayama University of Science 1-1 Ridai-cho Kita-ku Okayama-shi Okayama 700-0005, Japan E-mail: kuroki@xmath.ous.ac.jp