# Surface links with free abelian groups 

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#### Abstract

It is known that if a classical link group is a free abelian group, then its rank is at most two. It is also known that a $k$-component 2 -link group $(k>1)$ is not free abelian. In this paper, we give examples of $T^{2}$-links each of whose link groups is a free abelian group of rank three or four. Concerning the $T^{2}$-links of rank three, we determine the triple point numbers and we see that their link types are infinitely many.


## Introduction.

A classical link is the image of a smooth embedding of a disjoint union of circles into the Euclidean 3-space $\mathbb{R}^{3}$. The link group is the fundamental group of the link exterior. It is known [13, Theorem 6.3.1] that if a classical link group is a free abelian group, then its rank is at most two. A surface link is the image of a smooth embedding of a closed surface into the Euclidean 4 -space $\mathbb{R}^{4}$. A 2-link (resp. $T^{2}$-link) is a surface link whose components are homeomorphic to 2 -spheres (resp. tori). It is known [7, Chapter 3, Corollary 2] that a $k$-component 2 -link group for $k>1$ is not a free abelian group. The aim of this paper is to give concrete examples of $T^{2}$-links whose link groups are free abelian.

It is known (see Remark 2.1) that a $T^{2}$-link called a "Hopf 2 -link" [5] has a free abelian group of rank two. We give $T^{2}$-links with a free abelian group of rank three (Theorem 2.2). We also give a $T^{2}$-link with a free abelian group of rank four (Theorem 2.3). These $T^{2}$-links are "torus-covering $T^{2}$-links", which are $T^{2}$-links in the form of unbranched coverings over the standard torus.

Further we study the $T^{2}$-links given in Theorem 2.2 i.e. $T^{2}$-links each of whose link groups is a free abelian group of rank three. We determine the triple point number of each $T^{2}$-link (Theorem 3.1), by which we can see that their link types are infinitely many. The triple point number of each $T^{2}$-link is a multiple of four, and it is realized by a surface diagram in the form of a covering over the torus. For other examples of surface links (not necessarily orientable) which realize large triple point numbers, see $[\mathbf{6}],[\mathbf{9}]$, [12], [16], [17], [19].

The paper is organized as follows. In Section 1, we review the definition of a toruscovering $T^{2}$-link, and we review a formula how to calculate its link group. In Section 2, we show Theorems 2.2 and 2.3. In Section 3, we show Theorem 3.1.

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## 1. A torus-covering $\boldsymbol{T}^{2}$-link and its link group.

In this section, we give the definition of a torus-covering $T^{2}$-link $\mathcal{S}_{m}(a, b)$, which is determined from a pair of commuting $m$-braids $a$ and $b$ called basis braids. For the definition of a torus-covering link whose component might be of genus more than one, see $[\mathbf{1 5}]$. We can compute the link group of $\mathcal{S}_{m}(a, b)$ by using Artin's automorphism associated with $a$ or $b$ [15].

## 1.1.

Let $T$ be the standard torus in $\mathbb{R}^{4}$, i.e. the boundary of an unknotted solid torus in $\mathbb{R}^{3} \times\{0\} \subset \mathbb{R}^{4}$. Let $N(T)$ be a tubular neighborhood of $T$ in $\mathbb{R}^{4}$.

Definition 1.1. A torus-covering $T^{2}$-link is a surface link $F$ in $\mathbb{R}^{4}$ such that $F$ is embedded in $N(T)$ and $\left.p\right|_{F}: F \rightarrow T$ is an unbranched covering map, where $p: N(T) \rightarrow T$ is the natural projection.

Let us consider a torus-covering $T^{2}$-link $F$. Let us fix a point $x_{0}$ of $T$, and take a meridian $\boldsymbol{m}$ and a longitude $\mathbf{l}$ of $T$ with the base point $x_{0}$. A meridian is an oriented simple closed curve on $T$ which bounds a 2-disk in the solid torus whose boundary is $T$ and which is not null-homologous in $T$. A longitude is an oriented simple closed curve on $T$ which is null-homologous in the complement of the solid torus in the three space $\mathbb{R}^{3} \times\{0\}$ and which is not null-homologous in $T$. The intersections $F \cap p^{-1}(\boldsymbol{m})$ and $F \cap p^{-1}(\mathbf{l})$ are closures of classical braids. Cutting open the solid tori at the 2 -disk $p^{-1}\left(x_{0}\right)$, we obtain a pair of classical braids. We call them basis braids $[\mathbf{1 5}]$. The basis braids of a torus-covering $T^{2}$-link are commutative, and for any commutative braids $a$ and $b$, there exists a unique torus-covering $T^{2}$-link with basis braids $a$ and $b[\mathbf{1 5}$, Lemma 2.8]. For commutative $m$-braids $a$ and $b$, we denote by $\mathcal{S}_{m}(a, b)$ the torus-covering $T^{2}$-link with basis $m$-braids $a$ and $b$.

## 1.2.

We can compute the link group of a torus-covering $T^{2}-\operatorname{link} \mathcal{S}_{m}(a, b)[\mathbf{1 5}]$. As preliminaries, we will give the definition of Artin's automorphism (see [11]). Let $c$ be an $m$-braid in a cylinder $D^{2} \times[0,1]$, and let $Q_{m}$ be the starting point set of $c$. Let $\left\{h_{u}\right\}_{u \in[0,1]}$ be an isotopy of $D^{2}$ rel $\partial D^{2}$ such that $\cup_{u \in[0,1]} h_{u}\left(Q_{m}\right) \times\{u\}=c$. Let $\mathcal{A}^{c}:\left(D^{2}, Q_{m}\right) \rightarrow\left(D^{2}, Q_{m}\right)$ be the terminal map $h_{1}$, and consider the induced map $\mathcal{A}_{*}^{c}: \pi_{1}\left(D^{2}-Q_{m}\right) \rightarrow \pi_{1}\left(D^{2}-Q_{m}\right)$. It is known [1] that $\mathcal{A}_{*}^{c}$ is uniquely determined from $c$. We call $\mathcal{A}_{*}^{c}$ Artin's automorphism associated with $c$. Note that $\pi_{1}\left(D^{2}-Q_{m}\right)$ is naturally isomorphic to the free group $F_{m}$ generated by the standard generators $x_{1}, x_{2}, \ldots, x_{m}$ of $\pi_{1}\left(D^{2}-Q_{m}\right)$. By $\mathcal{A}_{*}^{c}$, the braid group $B_{m}$ acts on $\pi_{1}\left(D^{2}-Q_{m}\right)$. It is presented by

$$
\mathcal{A}_{*}^{\sigma_{i}}\left(x_{j}\right)= \begin{cases}x_{j} x_{j+1} x_{j}^{-1} & \text { if } j=i \\ x_{j-1} & \text { if } j=i+1 \\ x_{j} & \text { otherwise }\end{cases}
$$

and

$$
\mathcal{A}_{*}^{\sigma_{i}^{-1}}\left(x_{j}\right)= \begin{cases}x_{j+1} & \text { if } j=i \\ x_{j}^{-1} x_{j-1} x_{j} & \text { if } j=i+1 \\ x_{j} & \text { otherwise }\end{cases}
$$

where $i=1,2, \ldots, m-1$ and $j=1,2, \ldots, m$.
It is known [15, Proposition 3.1] that the link group of $\mathcal{S}_{m}(a, b)$ is presented by

$$
\left.\pi_{1}\left(\mathbb{R}^{4}-\mathcal{S}_{m}(a, b)\right)=\left\langle x_{1}, \ldots, x_{m}\right| x_{j}=\mathcal{A}_{*}^{a}\left(x_{j}\right)=\mathcal{A}_{*}^{b}\left(x_{j}\right), \text { for } j=1,2, \ldots, m\right\rangle
$$

## 2. $T^{2}$-links whose link groups are free abelian.

In this section we show Theorems 2.2 and 2.3: There are torus-covering $T^{2}$-links with a free abelian group of rank three (Theorem 2.2) or four (Theorem 2.3).

Remark 2.1. A Hopf 2 -link [5] is a $T^{2}$-link which is the product of a classical Hopf link in $B^{3}$ with $S^{1}$, embedded into $\mathbb{R}^{4}$ via an embedding of $B^{3} \times S^{1}$ into $\mathbb{R}^{4}$, where $B^{3}$ is a 3 -ball and $S^{1}$ is a circle. There are two link types according to the embedding of $B^{3} \times S^{1}$, called a standard Hopf 2-link and a twisted Hopf 2-link [5]. A standard (resp. twisted) Hopf 2 -link is the spun $T^{2}$-link (resp. the turned spun $T^{2}$-link) of a classical Hopf link [14], [2], [3]. It is known [14], [2], [3] that the link group of the spun $T^{2}$-link or the turned spun $T^{2}$-link of a classical link $L$ is isomorphic to the classical link group of $L$. Thus we can see that a Hopf 2 -link has a free abelian link group of rank two.

Let $\sigma_{1}, \sigma_{2}, \ldots, \sigma_{m-1}$ be the standard generators of $B_{m}$.
THEOREM 2.2. The link group of $\mathcal{S}_{3}\left(\sigma_{1}^{2} \sigma_{2}^{2 n}, \Delta\right)$ is a free abelian group of rank three, where $n$ is an integer and $\Delta$ is a full twist of a bundle of three parallel strings.

Proof. Put $S_{n}=\mathcal{S}_{3}\left(\sigma_{1}^{2} \sigma_{2}^{2 n}, \Delta\right)$. Let us compute the link group $G_{n}=\pi_{1}\left(\mathbb{R}^{4}-S_{n}\right)$ by applying [15, Proposition 3.1]. Let $x_{1}, x_{2}$ and $x_{3}$ be the generators. Then the relations concerning the basis braid $\sigma_{1}^{2} \sigma_{2}^{2 n}$ are

$$
\begin{align*}
x_{1} x_{2} & =x_{2} x_{1},  \tag{2.1}\\
\left(x_{2} x_{3}\right)^{|n|} & =\left(x_{3} x_{2}\right)^{|n|} . \tag{2.2}
\end{align*}
$$

The other relations concerning the other basis braid $\Delta$ are

$$
\begin{aligned}
& x_{1}=\left(x_{1} x_{2} x_{3}\right) x_{1}\left(x_{1} x_{2} x_{3}\right)^{-1}, \\
& x_{2}=\left(x_{1} x_{2} x_{3}\right) x_{2}\left(x_{1} x_{2} x_{3}\right)^{-1}, \\
& x_{3}=\left(x_{1} x_{2} x_{3}\right) x_{3}\left(x_{1} x_{2} x_{3}\right)^{-1}
\end{aligned}
$$

which are

$$
\begin{align*}
x_{1} x_{2} x_{3} & =x_{2} x_{3} x_{1}  \tag{2.3}\\
x_{2}\left(x_{1} x_{2} x_{3}\right) & =\left(x_{1} x_{2} x_{3}\right) x_{2}  \tag{2.4}\\
x_{3} x_{1} x_{2} & =x_{1} x_{2} x_{3} \tag{2.5}
\end{align*}
$$

By $(2.1),(2.3)$ is deformed to $x_{2} x_{1} x_{3}=x_{2} x_{3} x_{1}$; hence

$$
\begin{equation*}
x_{1} x_{3}=x_{3} x_{1} . \tag{2.6}
\end{equation*}
$$

Similarly, by (2.4) and (2.1),

$$
\begin{equation*}
x_{2} x_{3}=x_{3} x_{2} \tag{2.7}
\end{equation*}
$$

We can see that all the relations are generated by the three relations $(2.1),(2.6)$ and (2.7). Thus we have

$$
G_{n}=\left\langle x_{1}, x_{2}, x_{3} \mid x_{1} x_{2}=x_{2} x_{1}, x_{2} x_{3}=x_{3} x_{2}, x_{3} x_{1}=x_{1} x_{3}\right\rangle,
$$

which is a free abelian group of rank three.
THEOREM 2.3. The link group of $\mathcal{S}_{4}\left(\sigma_{1}^{2} \sigma_{2}^{2} \sigma_{3}^{2}, \Delta\right)$ is a free abelian group of rank four, where $\Delta$ is a full twist of a bundle of 4 parallel strings.

Proof. Similarly to the proof of Theorem 2.2, by [15, Proposition 3.1], for generators $x_{1}, x_{2}, x_{3}$ and $x_{4}$, we have the following relations:

$$
\begin{equation*}
x_{i} x_{i+1}=x_{i+1} x_{i} \tag{2.8}
\end{equation*}
$$

where $i=1,2,3$, and

$$
\begin{equation*}
x_{i}=\left(x_{1} x_{2} x_{3} x_{4}\right) x_{i}\left(x_{1} x_{2} x_{3} x_{4}\right)^{-1} \tag{2.9}
\end{equation*}
$$

where $i=1,2,3,4$. Using $x_{1} x_{2}=x_{2} x_{1}$ and $x_{3} x_{4}=x_{4} x_{3}$ of (2.8), the latter four relations (2.9) are deformed as follows:

$$
\begin{align*}
& x_{1} x_{3} x_{4}=x_{3} x_{4} x_{1},  \tag{2.10}\\
& x_{2} x_{3} x_{4}=x_{3} x_{4} x_{2},  \tag{2.11}\\
& x_{3} x_{1} x_{2}=x_{1} x_{2} x_{3},  \tag{2.12}\\
& x_{4} x_{1} x_{2}=x_{1} x_{2} x_{4} . \tag{2.13}
\end{align*}
$$

By $x_{2} x_{3}=x_{3} x_{2}$ of (2.8), (2.11) is deformed to $x_{3} x_{2} x_{4}=x_{3} x_{4} x_{2}$; hence

$$
\begin{equation*}
x_{2} x_{4}=x_{4} x_{2} \tag{2.14}
\end{equation*}
$$

Similarly, by $x_{2} x_{3}=x_{3} x_{2}$ of (2.8) and (2.12),

$$
\begin{equation*}
x_{3} x_{1}=x_{1} x_{3}, \tag{2.15}
\end{equation*}
$$

and by (2.14) and (2.13),

$$
\begin{equation*}
x_{4} x_{1}=x_{1} x_{4} . \tag{2.16}
\end{equation*}
$$

We can see that all the relations are generated by the relations (2.8), (2.14), (2.15) and (2.16). Thus the link group is a free abelian group of rank four.

## 3. The triple point numbers of the $T^{2}$-links with a free abelian group of rank three.

The triple point number of a surface link $F$ is the minimal number of triple points among all the surface diagrams of $F$. In this section we study the $T^{2}$-links given in Theorem 2.2 i.e. $T^{2}$-links each of whose link group is a free abelian group of rank three.

Theorem 3.1. The triple point number of $S_{n}=\mathcal{S}_{3}\left(\sigma_{1}^{2} \sigma_{2}^{2 n}, \Delta\right)$ given in Theorem 2.2 is $4 n$ for $n>0$ and $4(1-n)$ for $n \leq 0$. Further it is realized by a surface diagram in the form of a covering over $T$, in other words, by a 3-chart on $T$ which presents $S_{n}$. Thus $T^{2}$-links with a free abelian group of rank three are infinitely many.

Here, a 3-chart [11] is a finite graph with certain additional data, which we review in Section 3.1.

This section is organized as follows. In Section 3.1, we review a surface diagram and an $m$-chart on $T$ which presents a torus-covering $T^{2}$-link (see [15], [11]). In Section 3.2, we review the result of [16] which gives lower bounds of triple point numbers. In Section 3.3, we prove Theorem 3.1.

### 3.1. Surface diagrams and $m$-charts presenting torus-covering $T^{2}$-links.

The notion of an $m$-chart on a 2 -disk was introduced by Kamada [8] (see also [11]) to present a surface braid i.e. a 2 -dimensional braid in a bi-disk (see [18], [11]). An $m$-chart on a disk is obtained from the singularity set of a surface diagram of a surface braid. By a minor modification, we can define an $m$-chart on $T$ presenting a torus-covering link [15].

For a torus-covering $T^{2}$-link $F$, we consider a surface diagram in the form of a covering over the torus, as in Section 3.1.1.. Given $F$, we obtain such a surface diagram $D$, and from $D$ we obtain a graph called an $m$-chart on $T$ (without black vertices). Conversely, an $m$-chart on $T$ without black vertices presents such a surface diagram and hence a torus-covering $T^{2}$-link.

### 3.1.1. Surface diagrams.

We review a surface diagram of a surface link $F$ (see [4]). For a projection $\pi$ : $\mathbb{R}^{4} \rightarrow \mathbb{R}^{3}$, the closure of the self-intersection set of $\pi(F)$ is called the singularity set. Let $\pi$ be a generic projection, i.e. the singularity set of the image $\pi(F)$ consists of double

a double point curve

a triple point

a branch point

Figure 3.1. The singularity of a surface diagram.
points, isolated triple points, and isolated branch points; see Figure 3.1. The closure of the singularity set forms a union of immersed arcs and loops, which we call double point curves. Triple points (resp. branch points) form the intersection points (resp. the end points) of the double point curves. A surface diagram of $F$ is the image $\pi(F)$ equipped with over/under information along each double point curve with respect to the projection direction.

Throughout this paper, we consider the surface diagram of a torus-covering $T^{2}$-link $F$ by the projection which projects $N(T)=I \times I \times T$ to $I \times T$ for an interval $I$, where we identify $N(T)$ with $I \times I \times T$ in such a way as follows. Since $T$ is the boundary of the standard solid torus in $\mathbb{R}^{3} \times\{0\}$, the normal bundle of $T$ in $\mathbb{R}^{3} \times\{0\}$ is a trivial bundle. We identify it with $I \times T$. Then we identify $N(T)$ with $I \times I \times T$, where the second $I$ is an interval in the fourth axis of $\mathbb{R}^{4}$. Perturbing $F$ if necessary, we can assume that this projection is generic. We call this surface diagram the surface diagram of $F$ in the form of a covering over the torus.

### 3.1.2. From surface diagrams to $m$-charts on $T$.

Given a torus-covering $T^{2}$-link $F$, we obtain a graph on $T$ from the surface diagram in the form of a covering over the torus, as follows. Now we have $\operatorname{Sing}(\pi(F))$ in $I \times T$. By the definition of a torus-covering $T^{2}$-link, $\operatorname{Sing}(\pi(F))$ consists of double point curves and triple points, and no branch points. We can assume that the singular set of the image of $\operatorname{Sing}(\pi(F))$ by the projection to $T$ consists of a finite number of double points such that the preimages belong to double point curves of $\operatorname{Sing}(\pi(F))$. Thus the image of $\operatorname{Sing}(\pi(F))$ by the projection to $T$ forms a finite graph $\Gamma$ on $T$ such that the degree of its vertex is either 4 or 6 . An edge of $\Gamma$ corresponds to a double point curve, and a vertex of degree 6 corresponds to a triple point.

For such a graph $\Gamma$ obtained from the surface diagram, we give orientations and labels to the edges of $\Gamma$, as follows. Let us consider a path $l$ in $T$ such that $l \cap \Gamma$ is a point $P$ of an edge $e$ of $\Gamma$. Then $F \cap p^{-1}(l)$ is a classical $m$-braid with one crossing in $p^{-1}(l)$ such that $P$ corresponds to the crossing of the $m$-braid. Let $\sigma_{i}^{\epsilon}(i \in\{1,2, \ldots, m-1\}$, $\epsilon \in\{+1,-1\})$ be the presentation of $F \cap p^{-1}(l)$. Then label the edge $e$ by $i$, and moreover give $e$ an orientation such that the normal vector of $l$ corresponds (resp. does not correspond) to the orientation of $e$ if $\epsilon=+1$ (resp. -1). We call such an oriented and labeled graph an $m$-chart of $F$ (without black vertices).

In general, we define an $m$-chart on $T$ as follows.

Definition 3.2. Let $m$ be a positive integer, and let $\Gamma$ be a finite graph on $T$. Then $\Gamma$ is called an $m$-chart on $T$ if it satisfies the following conditions:
(i) Every edge is oriented and labeled by an element of $\{1,2, \ldots, m-1\}$.
(ii) Every vertex has degree 1, 4, or 6 .
(iii) The adjacent edges around each vertex are oriented and labeled as shown in Figure 3.2 , where we depict a vertex of degree 1 (resp. 6) by a black vertex (resp. white vertex).


Figure 3.2. Vertices in an $m$-chart.
A black vertex presents a branch point; see [11]. When an $m$-chart on $T$ without black vertices is given, we can reconstruct a torus-covering $T^{2}$-link [15] (see also [11]).

Two $m$-charts on $T$ are $C$-move equivalent [15] (see also $[\mathbf{8}],[\mathbf{1 0}],[\mathbf{1 1}]$ ) if they are related by a finite sequence of ambient isotopies of $T$ and CI, CII, CIII-moves. We show several examples of CI-moves in Figure 3.3; see [11] for the complete set of CI-moves and CII, CIII-moves. For two $m$-charts on $T$, their presenting torus-covering links are equivalent if the $m$-charts are C-move equivalent $[\mathbf{1 5}]$ (see also $[\mathbf{8}],[\mathbf{1 0}],[\mathbf{1 1}]$ ).


Figure 3.3. CI-moves. We give only several examples.

### 3.2. Triple point numbers.

For a surface link $F$, we denote by $t(F)$ the triple point number of $F$. It is shown [16] that for a pure $m$-braid $b(m \geq 3)$ and an integer $n$, a lower bound of $t\left(\mathcal{S}_{m}\left(b, \Delta^{n}\right)\right)$ is given by using the linking numbers of $\hat{b}$, and for a particular $b$, we can determine the triple point number. Here $\hat{b}$ denotes the closure of $b$.

For a pure 3 -braid $b$, it follows from [16] that we can give a lower bound of $t\left(\mathcal{S}_{3}(b, \Delta)\right)$ as follows. We define the $i$ th component of $\hat{b}$ by the component constructed by the $i$ th string of $\hat{b}(i=1,2,3)$. For positive integers $i$ and $j$ with $i \neq j$, the linking number of the $i$ th and $j$ th components of a classical link $L$, denoted by $\mathrm{Lk}_{i, j}(L)$, is the total number of positive crossings minus the total number of negative crossings
of a diagram of $L$ such that the under-arc (resp. over-arc) is from the $i$ th (resp. $j$ th) component. Put $\mu=\sum_{i<j}\left|\operatorname{Lk}_{i, j}(\hat{b})\right|$, and put $\nu=\nu_{1,2,3}+\nu_{2,3,1}+\nu_{3,1,2}$, where $\nu_{i, j, k}=\min _{i, j, k}\left\{\left|\operatorname{Lk}_{i, j}(\hat{b})\right|,\left|\operatorname{Lk}_{j, k}(\hat{b})\right|\right\}$ if $\operatorname{Lk}_{i, j}(\hat{b}) \operatorname{Lk}_{j, k}(\hat{b})>0$ and otherwise zero. Then, by [16],

$$
t\left(\mathcal{S}_{3}(b, \Delta)\right) \geq 4(\mu-\nu)
$$

In particular, let $b$ be a 3 -braid presented by a braid word which is an element of a monoid generated by $\sigma_{1}^{2}$ and $\sigma_{2}^{-2}$; note that $b$ is a pure braid. Then

$$
t\left(\mathcal{S}_{3}(b, \Delta)\right)=4 \mu
$$

and the triple point number is realized by a surface diagram in the form of a covering over the torus [16].

### 3.3. Proof of Theorem 3.1.

Put $b=\sigma_{1}^{2} \sigma_{2}^{2 n}$. We use the notations given in Section 3.2. Since $\operatorname{Lk}_{i, j}(\hat{b})=1$ (resp. $n$ ) if $\{i, j\}=\{1,2\}$ (resp. $\{2,3\}$ ) and otherwise zero, we can see that $\mu=1+|n|$.

Let us consider the case for $n \leq 0$. Since $b$ has the presentation which is an element of a monoid generated by $\sigma_{1}^{2}$ and $\sigma_{2}^{-2}, t\left(S_{n}\right)=4 \mu$ by [16]; thus $t\left(S_{n}\right)=4(1-n)(n \leq 0)$, and the triple point number is realized by a surface diagram in the form of a covering over the torus by $[\mathbf{1 6}]$.

Let us consider the case for $n>0$. Since $\operatorname{Lk}_{i, j}(\hat{b})=1$ (resp. $n$ ) if $\{i, j\}=\{1,2\}$ (resp. $\{2,3\}$ ) and otherwise zero, we can see that $\nu_{i, j, k}=1$ if $(i, j, k)=(1,2,3)$ and zero if $(i, j, k)=(2,3,1)$ or $(3,1,2)$; thus $\nu=1$, and hence $t\left(S_{n}\right) \geq 4(\mu-\nu)=4 n$ by [16].

It remains to show that there is a surface diagram of $S_{n}(n>0)$ with $4 n$ triple points. It suffices to draw a 3 -chart $\Gamma$ on $T$ which presents $S_{n}$ such that $\Gamma$ has exactly $4 n$ white vertices. We draw $\Gamma$ which presents $S_{n}$, and deform it to a 3 -chart with $4 n$ white vertices by C-moves, as follows. First we draw $\Gamma$ as a 3 -chart which consists of $2 n+2$ parts as follows, where we assume that a full twist $\Delta$ has the presentation $\Delta=\left(\sigma_{1} \sigma_{2} \sigma_{1}\right)^{2}$.
(i) The part of $\Gamma$ with basis braids $\sigma_{1}$ and $\Delta$. We have two copies.
(ii) The part of $\Gamma$ with basis braids $\sigma_{2}$ and $\Delta$. We have $2 n$ copies.

We draw the part (i) as in Figure 3.4 and we denote the white vertices by $t_{i 1}$ and $t_{i 2}$ as in Figure 3.4 for the $i$ th copy $(i=1,2)$. We draw the part (ii) as in Figure 3.5 and we denote the white vertices by $t_{i 1}$ and $t_{i 2}$ as in Figure 3.5 for the $(i-2)$ th copy


Figure 3.4. White vertices $t_{i 1}$ and $t_{i 2}(i=1,2)$.


Figure 3.5. White vertices $t_{i 1}$ and $t_{i 2}(i=3,4, \ldots, 2 n+2)$, for $n>0$.
$(i=3,4, \ldots, 2 n+2)$. There are $4 n+4$ white vertices in $\Gamma$. Let us apply a CI-move as in Figure 3.3 (3) to the pair $\left\{t_{21}, t_{31}\right\}$ of white vertices in $\Gamma$, and then to the pair $\left\{t_{(2 n+2) 2}, t_{12}\right\}$; then we can eliminate the four white vertices, and the resulting 3 -chart has $4 n$ white vertices. Hence $t\left(S_{n}\right)=4 n(n>0)$, and the triple point number is realized by this 3 -chart on $T$.

Remark 3.3. There is an oriented $T^{2}$-link as in Figure 3.6 with a free abelian group of rank three and with the triple point number zero. It is a ribbon $T^{2}$-link (see [4] for the definition of a ribbon surface link). We briefly show that the link group is free abelian, as follows. In the surface diagram, there are six broken sheets (see [4]), consisting of three pairs of a sheet attached with $x_{i}$ and a small disk $D_{i}$ such that each pair forms the $i$ th component of the $T^{2}$-link $(i=1,2,3)$. Let us attach $y_{i}$ to each $D_{i}$. The link group has the presentation with generators $x_{i}$ and $y_{i}(i=1,2,3)$ and the relations which are given around each double point curve (see [4], [11]). The singularity set consists of double point curves which form six circles. Around each circle in the $i$ th component which does not bound $D_{i}(i=1,2,3)$, there are three broken sheets such that one is an over-sheet with $x_{i}$ and the other two are under-sheets with the same generator $x_{i+1}$, where $x_{4}=x_{1}$; together with the orientation, the relation is $x_{i}=x_{i+1} x_{i} x_{i+1}^{-1}$, see [4], [11]. Around each circle $\partial D_{i}(i=1,2,3)$, there are three broken sheets such that one is an over-sheet with $x_{i+1}$ and the other two are under-sheets with $x_{i}$ and $y_{i}$ respectively, where $x_{4}=x_{1}$; together with the orientation, the relation is $y_{i}=x_{i+1} x_{i} x_{i+1}^{-1}$, see [4], [11]. Thus the link group is a free abelian group of rank three.

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Figure 3.6. A ribbon $T^{2}$-link with a free abelian group of rank three.

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