

## Elliptic differential inequalities with applications to harmonic maps

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### Introduction.

Harmonic maps  $\phi: (M, g) \rightarrow (N, h)$  between Riemannian manifolds are the smooth critical points of the *energy functional*

$$E(\phi) = \int_M e(\phi) dV_M,$$

where  $e(\phi) = (1/2)|d\phi|^2$  is the *energy density* of  $\phi$ . Or, equivalently, the  $C^2$  solutions of the elliptic system

$$(0.1) \quad \text{Trace}_g \nabla d\phi = 0.$$

The left-hand side of (0.1) is the *tension field* of  $\phi$ , denoted  $\tau(\phi)$ ; it is a vector field along  $\phi$ : we refer to the surveys [5], [6] for complete definitions and background.

Since the pioneering work of Eells and Sampson ([7] (1964)), harmonic maps have attracted the interest of both geometers and analysts: during the early stages of the theory, research was focused on maps between compact manifolds. Indeed, in a compact setting a harmonic map provides a strong candidate for a “best map” in a prescribed homotopy class; and a natural generalization of the concept of closed geodesic.

More recently, harmonic maps of non-compact domains have become object of growing interest: as a significant example, we quote the discovery of a new family of harmonic maps  $\phi: \mathbf{R}^2 \rightarrow \mathbf{H}^2$  of rank two almost everywhere; that was obtained by Choi and Treibergs [4], using a version of Ruh-Vilms’ Theorem for constant mean curvature hypersurfaces of Minkowski 3-space. It is natural to view the study of harmonic maps of non-compact domains as a generalization of the theory of harmonic functions  $f: M \rightarrow \mathbf{R}$  on complete Riemannian manifolds [18]; however, we point out two key differences:

- a) a single equation — i.e.,  $\Delta f = 0$  — is replaced by a system — i.e., (0.1).
- b) the curvature of the range plays a role, making system (0.1) non-linear.

Nevertheless, Liouville's type Theorems for harmonic maps have been obtained ([3], [16], [17]); more generally, one expects relations between the growth at  $\infty$  of solutions—or of their energy density—and the geometry of the manifolds.

In this paper we undertake this type of study under the hypothesis that the domain  $M$  is a complete,  $m$ -dimensional Riemannian manifold such that  $\text{Ricci}(M) \geq -AG(r)$ , where  $A$  is a positive constant and  $r$  denotes distance from a fixed point  $q \in M$  (the choice of  $q$  plays no role in what follows);  $G(r)$  is a positive, non-decreasing function such that  $G(0)=1$  and  $G(r) \rightarrow +\infty$  as  $r \rightarrow +\infty$ . In the sequel, we shall always abbreviate this by simply writing that  $M$  satisfies  $\text{Ricci}(M) \geq -AG(r)$ .

We prove our results by studying the relations between the growth of  $G$  at  $+\infty$  and the existence of  $C^2$  solutions on  $M$  of differential inequalities of the type

$$(0.2) \quad \Delta u \geq b(x)\varphi(u), \quad x \in M$$

(the sign convention is  $\Delta = \text{div}(\nabla u)$ ). Osserman [12] and Redheffer ([14], [15]) studied (0.2) in the case  $M = \mathbf{R}^m$ , while Calabi [1] analysed the case  $\text{Ricci}(M) \geq 0$ : their use of the maximum principle has inspired our work.

In Section 2 we obtain a priori estimates for the energy density of bounded harmonic maps  $\phi: M \rightarrow N$ , where  $N$  has non-positive sectional curvature ((2.12) below). As a by-pass product of our analysis we also obtain refinements (Theorem 2.17 and Corollary 2.24) of results of [2] and [9] on the image diameter of maps with bounded tension field; in the case of isometric immersions this also complements work of Karp [10].

In Section 3 we illustrate further applications and extensions to rotationally symmetric manifolds (i.e., models in the sense of [8]); in particular, we extend work of Tachikawa ([16], [17]), proving non-existence results for certain harmonic maps into Hadamard manifolds or models (see (3.26), (3.37–41) below).

Most of the technicalities of this paper rely on the analysis (Section 1) of an O.D.E. which arise from the study of rotationally symmetric solutions of (0.2): reading Sections 2 and 3 requires some familiarity with notation and facts of Section 1.

We also remark that the methods of this paper can be applied to study other elliptic equations of geometric interest; in particular, they yield some non-existence results for the non-compact Yamabe problem, as we shall illustrate in a forthcoming paper. Finally, we mention here that the works [10], [11], [13] deal — by different methods — with problems related to this paper.

# 1. Analysis of the O.D.E..

In this section we establish some qualitative properties of solutions of (1.1) below: the key technical result is Proposition 1.11.

$$(1.1) \quad \begin{aligned} \alpha''(t) + (m-1)[\tilde{g}'(t)/\tilde{g}(t)]\alpha'(t) &= f(\alpha(t)) \\ \alpha'(0) &= 0, \quad \alpha(0) = \alpha_0, \quad t \geq 0 \end{aligned}$$

where  $m \geq 2$ ,  $f \in \text{Lip}_{\text{loc}}(\mathbf{R})$ ,  $f$  is non-decreasing and nonnegative;  $\tilde{g} \in C^1([0, +\infty))$ ,  $\tilde{g} > 0$  on  $(0, +\infty)$ ,  $\tilde{g}(0) = 0$  and  $\tilde{g}'(0) > 0$ . Unless otherwise specified, in the sequel we shall tacitly assume that the above assumptions on  $f$ ,  $\tilde{g}$  and  $m$  hold (but we note that the assumption  $f$  non-decreasing is unnecessary in Lemma 1.2 below).

LEMMA 1.2. *The Cauchy problem (1.1) has a unique solution  $\alpha$  which is defined on a maximal interval  $[0, T)$ . Moreover, if  $f(\alpha_0) > 0$ , then  $\alpha' > 0$  on  $(0, T)$ ; and if  $T < +\infty$ , then  $\alpha(t) \rightarrow +\infty$  as  $t \rightarrow T^-$ .*

PROOF. First we write (1.1) in integral form

$$(1.3) \quad \alpha(t) = \alpha_0 + \int_0^t [\tilde{g}(s)]^{1-m} \left\{ \int_0^s [\tilde{g}(u)]^{m-1} f(\alpha(u)) du \right\} ds.$$

Existence and uniqueness for small  $t$  is standard: it can be obtained by applying the Picard iteration procedure. To see that  $\alpha'(t) > 0$  for  $t > 0$ , we write (1.1) as

$$(\tilde{g}^{m-1} \alpha')' = \tilde{g}^{m-1} f(\alpha).$$

Integrating over  $[0, t]$  and using  $\alpha'(0) = 0$  we find

$$[\tilde{g}(t)]^{m-1} \alpha'(t) = \int_0^t [\tilde{g}(s)]^{m-1} f(\alpha(s)) ds$$

from which the assertion follows immediately. Finally, let  $T < +\infty$  and suppose that  $\alpha(t) \rightarrow c < +\infty$  as  $t \rightarrow T^-$ . Then  $[\tilde{g}(s)]^{m-1} f(\alpha(s)) \in L^1([0, T])$ ; therefore differentiating (1.3) we find that  $\alpha'(t)$  converges to a finite limit as  $t \rightarrow T^-$ , a fact which contradicts the maximality of  $[0, T)$ . //

LEMMA 1.4. *Let  $\alpha$  be a solution of (1.1) on  $[0, +\infty)$  such that  $\alpha(t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ . Suppose that  $\tilde{g}' \geq 0$  and*

$$(1.5) \quad ([f(t)]^\eta/t) \longrightarrow +\infty \quad \text{as } t \rightarrow +\infty, \quad \text{for some } \eta > 0.$$

*Then for any  $c > 0$  there exists  $\tau_0 \in (0, +\infty)$  such that*

$$(1.6) \quad \{1 - (m-1)(2/c)^{1/2} [\tilde{g}'(t)/\tilde{g}(t)] [f(\alpha(t))]^{(\eta-1)/2}\} f(\alpha(t)) < \alpha''(t)$$

for all  $t \geq \tau_0$ .

PROOF. Because  $\alpha' \geq 0$  and  $\tilde{g}' \geq 0$ , (1.1) implies  $f(\alpha)\alpha' \geq \alpha''\alpha'$ . Integrating this inequality over  $[0, t]$  and using  $\alpha'(0)=0$ ,  $\alpha' > 0$  on  $(0, +\infty)$  we obtain

$$(1.7) \quad 2 \int_{\alpha_0}^{\alpha(t)} f(s) ds \geq [\alpha'(t)]^2.$$

Given  $c > 0$ , (1.5) guarantees the existence of  $t_0$  such that

$$[f(t)]^\eta > c(t - \alpha_0) \quad \text{for all } t \geq t_0.$$

We choose  $\tau_0 \geq t_0$  in such a way that  $\alpha(t) \geq t_0$  for all  $t \geq \tau_0$ ; it follows that

$$(1.8) \quad [f(\alpha(t))]^\eta > c[\alpha(t) - \alpha_0] \quad \text{for all } t \geq \tau_0.$$

From now on let  $t \geq \tau_0$ . From (1.7) and  $f$  non-decreasing we get

$$[\alpha'(t)]^2 \leq 2f(\alpha(t))[\alpha(t) - \alpha_0].$$

Thus, applying (1.8) and elevating to  $1/2$ , we obtain

$$(1.9) \quad \alpha'(t) < (2/c)^{1/2} [f(\alpha(t))]^{(\eta+1)/2}.$$

Now multiplying (1.9) by  $(m-1)[\tilde{g}'/\tilde{g}]$  and using (1.1) gives (1.6). //

(1.10) In order to measure the rate of growth of  $[\tilde{g}'(t)/\tilde{g}(t)]$  as  $t \rightarrow +\infty$  it is convenient to introduce two classes  $\mathcal{F}$ ,  $\mathcal{G}$  of  $C^1$  functions  $F$  defined in a neighbourhood of  $+\infty$ : namely, we say that  $F \in \mathcal{G}$  if  $[F]^{-1} \notin L^1(+\infty)$ ,  $F'(t) \geq 0$  ( $t$  large) and  $F(t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ . And  $F \in \mathcal{F}$  if  $F \in \mathcal{G}$  and furthermore

$$\lim_{t \rightarrow +\infty} F'(t)[F'(t)]^{-\varepsilon} \in \mathbf{R} \quad \text{for any } \varepsilon > 0.$$

Examples of  $F(t) \in \mathcal{F}$  are:  $t$ ,  $t \log t$ ,  $t[\log t][\log(\log t)]$ ,  $\dots$ .

NOTATION.  $[\tilde{g}'/\tilde{g}] = \mathcal{O}(k)$  means that  $[\tilde{g}'(t)/\tilde{g}(t)]/k(t) \rightarrow 0$  as  $t \rightarrow +\infty$ .

PROPOSITION 1.11. Let  $\alpha$  be a solution of (1.1) such that  $f(\alpha_0) > 0$ . Assume that

- i)  $([f(t)]^\eta/t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ , for some  $0 < \eta < 1$ ;
- ii) there exists  $0 < \gamma < (1-\eta)/(1+\eta)$  and a nonnegative function  $D(t)$  such that

$$[\tilde{g}'(t)/\tilde{g}(t)] \leq D(t); \text{ and } D(t) = \mathcal{O}(F^\gamma) \quad \text{for some } F \in \mathcal{F} \text{ as in (1.10).}$$

Then  $\alpha$  is defined on a maximal interval  $[0, T)$  with  $T < +\infty$ .

PROOF. For technical reasons (the application of Lemma 1.4) we begin with proving the Proposition under the additional hypothesis that  $\tilde{g}' \geq 0$ . We define

$$h(t) = [\tilde{g}(t)]^{1-m} \int_0^t [\tilde{g}(s)]^{m-1} ds, \quad k(t) = [\tilde{g}'(t)/\tilde{g}(t)] \left\{ \int_0^t h(s) ds \right\}^{-\delta/\eta}$$

where  $\delta = (1-\eta)/2$ ; for a moment, let us suppose that

$$\text{iii) } h(t) \notin L^1(+\infty); \text{ iv) } k(t) \in L^\infty(+\infty) \text{ and v) } \left\{ \int_0^t f(s) ds \right\}^{-1/2} \in L^1(+\infty).$$

We show that iii), iv) and v) together imply the Proposition: by contradiction, let  $T = +\infty$ ;  $\alpha' \geq 0$  and  $f$  non-decreasing force  $f(\alpha(t)) \geq f(\alpha_0)$  for all  $t \geq 0$ . Therefore from (1.3) we have

$$(1.12) \quad \alpha(t) \geq \alpha_0 + f(\alpha_0) \int_0^t h(s) ds.$$

Now (1.12) together with iii) imply that  $\alpha(t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ , so that the hypotheses of Lemma 1.4 are satisfied. Moreover, for  $t$  large,  $f(\alpha(t)) \geq [\alpha(t)]^{1/\eta}$  by i). It follows that

$$[\tilde{g}'/\tilde{g}][f(\alpha)]^{-\delta} \leq [\tilde{g}'/\tilde{g}][\alpha]^{-\delta/\eta} \leq c_1 k$$

for some  $c_1 > 0$ . Applying iv) and (1.6) with a sufficiently large  $c > 0$  we obtain the existence of  $B > 0$  such that

$$(1.13) \quad Bf(\alpha) < \alpha'' \quad \text{for all } t \geq \tau_0, \tau_0 \text{ large.}$$

Multiplying both members of (1.13) by  $\alpha'$  and integrating over  $[\tau_0, t]$  gives

$$(1.14) \quad (2B) \int_{\alpha(\tau_0)}^{\alpha(t)} f(s) ds + [\alpha'(\tau_0)]^2 < [\alpha'(t)]^2.$$

Because  $\alpha' > 0$  on  $[\tau_0, t]$ , (1.14) gives

$$(1.15) \quad \alpha'(t) \left\{ (2B) \int_{\alpha(\tau_0)}^{\alpha(t)} f(s) ds + [\alpha'(\tau_0)]^2 \right\}^{-1/2} > 1.$$

Integrating (1.15) over  $[\tau_0, \tau]$  we obtain

$$(1.16) \quad \int_{\alpha(\tau_0)}^{\alpha(\tau)} \left\{ (2B) \int_{\alpha(\tau_0)}^u f(s) ds + [\alpha'(\tau_0)]^2 \right\}^{-1/2} du > \tau - \tau_0.$$

Letting  $\tau \rightarrow +\infty$  we see that (1.16) contradicts v): so (if  $\tilde{g}' \geq 0$ ) the proof is complete provided that we show that iii), iv) and v) hold.

**Proof of iii).** If  $\tilde{g}(t)$  is bounded the conclusion is obvious. So we assume that  $\tilde{g}(t)$  tends to  $+\infty$  as  $t$  goes to  $+\infty$ : since  $[F]^{-1} \notin L^1(+\infty)$ , also  $[F]^{-r} \notin L^1(+\infty)$  for  $r$  as in (1.11) ii): therefore it is enough to show that

$$(1.17) \quad [F]^r h(t) \longrightarrow +\infty \quad \text{as } t \rightarrow +\infty$$

Now, using the explicit expression of  $h(t)$ , (1.17) follows easily from de l'Hôpital's rule, (1.10) and (1.11) ii).

Proof of iv). Using (1.17) we deduce that

$$k(t) \leq c_2 + [\tilde{g}'(t)/\tilde{g}(t)] \left\{ \int_0^t [F(s)]^{-r} ds \right\}^{-\delta/\eta} \quad \text{for some } c_2 > 0.$$

Because of (1.11) ii) it suffices to show that  $[F(t)]^{\eta r/\delta} / \left\{ \int_0^t [F(s)]^{-r} ds \right\}$  converges to a finite limit as  $t \rightarrow +\infty$ : but this follows easily from de l'Hôpital's rule and the fact that  $F'F^{-\varepsilon}$  converges for all  $\varepsilon > 0$  because  $F \in \mathcal{F}$ .

Proof of v). Clearly  $\int_0^t f(s) ds \rightarrow +\infty$  as  $t \rightarrow +\infty$ , because  $f(\alpha_0) > 0$  and  $f$  is non-decreasing. Since  $0 < \eta < 1$  we can choose  $\sigma > 0$  such that  $[2\sigma + 1 - (1/\eta)] < 0$ . Now we apply de l'Hôpital's rule and (1.11) i) to obtain

$$\lim_{t \rightarrow +\infty} \left\{ t^{2\sigma+2} / \int_0^t f(s) ds \right\} = \lim_{t \rightarrow +\infty} (2\sigma+2) \{ t^{1/\eta} / f(t) \} t^{2\sigma+1-(1/\eta)} = 0$$

from which v) follows.

Finally, we show that the assumption  $\tilde{g}' \geq 0$  is unnecessary. Indeed, we can consider

$$\alpha''(t) + (m-1)D(t)\alpha'(t) = f(\alpha(t))$$

$$\alpha'(0) = 0, \quad \alpha(0) = \alpha_0, \quad f(\alpha_0) > 0$$

where  $D(t)$  is a suitable function as in (1.11) ii). The previous argument (with  $\exp \left[ \int_1^t D(s) ds \right]$  in place of  $\tilde{g}(t)$ ) tells us that the unique solution of this Cauchy problem is defined on a maximal interval  $[0, T_1)$  with  $T_1 < +\infty$ . Now standard comparison arguments (using  $[\tilde{g}'(t)/\tilde{g}(t)] \leq D(t)$ ) imply that the solution of the original problem (1.1) blows up in finite time  $T \leq T_1$ . //

A modification of the arguments of Proposition 1.11 gives

LEMMA 1.18. *Let  $\alpha$  be a solution of (1.1) which is defined on  $[0, +\infty)$ , with  $f(\alpha_0) > 0$ . Suppose that there exists a nonnegative function  $D(t)$  such that  $[\tilde{g}'(t)/\tilde{g}(t)] \leq D(t)$ ; and  $D(t) = \mathcal{O}(F)$  for some  $F \in \mathcal{G}$  as in (1.10). Then  $\alpha(t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ .*

REMARKS 1.19. a) Hypothesis (1.1) ii) is quite sharp, as the following example shows:

$$\alpha''(t) + \{[(t^2+3)^\delta - 2]/2t\} \alpha'(t) = [\alpha(t)]^\delta, \quad \delta > 1$$

$$\alpha'(0) = 0, \quad \alpha(0) = 3$$

admits the global solution  $\alpha(t) = t^2 + 3$  (here  $\tilde{g}(t) = \exp \left( \int_1^t \{[(s^2+3)^\delta - 2]/2s\} ds \right)$ ).

b) If  $\tilde{g}'(t) \geq 0$ , then the natural choice for the function  $D(t)$  is  $D(t) =$

$[\tilde{g}'(t)/\tilde{g}(t)]$ ; in general, the function  $D(t)$  serves a technical purpose of comparison, based on the fact that  $\tilde{g}'(t) < 0$  — and, all the more reason,  $\tilde{g}'(t) \rightarrow -\infty$  as  $t \rightarrow +\infty$  — is a condition which contributes to a faster growth of solutions and so to their blowing up in finite time.

The following is a standard fact:

LEMMA 1.20. *Suppose that the function  $f$  in (1.1) satisfies*

$$(1.21) \quad f(s) \leq a_1 s + a_2 \quad \text{for some } a_1, a_2 > 0.$$

*Then any solution  $\alpha(t)$  of (1.1) is defined for all  $t \geq 0$ .*

(1.22) For our purposes it will be useful to consider a variant of (1.1): namely, let  $a \in C^1([0, +\infty))$  be a positive function such that  $a^{1/2} \notin L^1(+\infty)$ . We consider

$$(1.23) \quad \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) = a(r)f(\beta(r))$$

and set

$$(1.24) \quad h(r) = \int_0^r [a(s)]^{1/2} ds.$$

Then the change of variable  $h(r) = t$ ,  $t \in [0, +\infty)$ , defines a bijection between solutions of

$$(1.25) \quad \alpha''(t) + (m-1)[\tilde{g}'(t)/\tilde{g}(t)]\alpha'(t) = f(\alpha(t))$$

where

$$(1.26) \quad \alpha(t) = \beta(h^{-1}(t)), \quad \tilde{g}(t) = g(r)[a(r)]^{1/(2m-2)} \quad \text{and}$$

$$(1.27) \quad [\tilde{g}'(t)/\tilde{g}(t)] = [a(r)]^{-1/2} \{ [g'(r)/g(r)] + [1/2(m-1)][a'(r)/a(r)] \}.$$

The proof of these facts is a straightforward computation and therefore we omit it. We observe that (1.25) is of type (1.1); thus we can apply (modulo the change of variable  $t = h(r)$ ) the results of this section to (1.23).

REMARK 1.28. The methods of this section apply to the more general Cauchy problem

$$(1.29) \quad |\alpha'(t)|^{-p} \{ \alpha''(t) + (m-1)[\tilde{g}'(t)/\tilde{g}(t)]\alpha'(t) \} = f(\alpha(t))$$

$$\alpha'(0) = 0, \quad \alpha(0) = \alpha_0, \quad t \geq 0.$$

In particular, Proposition 1.11 holds in this case provided that  $p < 1$ ,  $0 < \eta < 1/(1-p)$ ,  $0 < \gamma < [1 - (1-p)\eta]/[1 + (1-p)^2\eta]$  and  $[\tilde{g}'/\tilde{g}] = \mathcal{O}(Fr^{(1-p)})$ .

Equation (1.29) would permit us to study inequalities of the type

$$(1.30) \quad \Delta u \geq b(x)\varphi(u)|\nabla u|^p, \quad x \in M$$

which arise in the study of the operator  $\operatorname{div}(|\nabla u|^{-p}\nabla u)$ . However, we shall not pursue this generalization in this paper, because the case  $p=0$  suffices for the geometric applications of the next sections.

## 2. Estimates for harmonic maps.

Differential equations of type (1.1) arise in geometry from problems involving  $\Delta r$ , where  $r$  is the distance function from a fixed point  $q \in M$ . We will use the following estimate which can be derived from [8]: suppose that  $\operatorname{Ricci}(M) \geq -AG(r)$ , as in the introduction; then, at each  $x \notin C_q$  (the cut locus of  $q$ ), we have

$$(2.1) \quad \Delta r \leq (m-1)[g'(r)/g(r)]$$

where  $m = \dim M$  and, setting  $\Omega = (A/(m-1))^{1/2}$ ,

$$g(r) = [\sinh(\Omega r)] \exp \int_0^r \Omega \coth(\Omega s) \{ [1 + (G(s)-1) \tanh^2(\Omega s)]^{1/2} - 1 \} ds.$$

We observe that

$$(2.2) \quad [g'(r)/g(r)] \approx \Omega [G(r)]^{1/2} \quad \text{as } r \rightarrow +\infty; \text{ and}$$

also recall that if  $\operatorname{Ricci}(M) \geq 0$ , then (2.1) holds with  $g(r) = r$ ; and if  $\operatorname{Ricci}(M) \geq -A$ ,  $A > 0$ , we can take  $g(r) = \sinh(\Omega r)$ .

LEMMA 2.3. [15] *Let  $M$  be a complete Riemannian manifold and  $u$  a  $C^2$  solution on  $M$  of the differential inequality*

$$(2.4) \quad \Delta u \geq b(x)\varphi(u), \quad x \in M,$$

where  $b(x) \geq 0$ ,  $b \not\equiv 0$  and  $\varphi \geq 0$ . Fix  $q \in M$  and let  $r$  be the distance from  $q$ : If there exists a  $C^2$  function  $v$  such that, for some  $R > 0$ ,

$$(2.5) \quad \Delta v < b \quad \text{on } M/B_R(q) \text{ and}$$

$$(2.6) \quad v(x) \longrightarrow +\infty \quad \text{as } r(x) \rightarrow +\infty,$$

then either  $\sup_M \{u\} = +\infty$  or  $\sup_M \{u\} \in Z(\varphi) = \{t \in \mathbf{R} : \varphi(t) = 0\}$ .

PROOF. This was proved by Redheffer in case  $M = \mathbf{R}^m$  ([15], Theorem 1): in this general case the proof is essentially the same and therefore omitted. //

In the notation of the introduction and Section 1, we have

LEMMA 2.7. *Assume  $\operatorname{Ricci}(M) \geq -AG(r)$ . Let  $a(r)$  be a function as in (1.22) and suppose that*



$$(2.8) \quad [\tilde{g}'(t)/\tilde{g}(t)] = \mathcal{O}(F(t)),$$

where  $t=h(r)$ , as in (1.24);  $[\tilde{g}'/\tilde{g}]$  is defined by (1.27) with  $g$  as in (2.1); and  $F \in \mathcal{G}$  as in (1.10). Consider inequality (2.4) and furthermore suppose that  $b(x) \geq a(r(x))$  on  $M/B_R(q)$ , for some  $R > 0$ . If  $u$  is a  $C^2$  solution of (2.4) then either  $\sup_M \{u\} = +\infty$  or  $\sup_M \{u\} \in Z(\varphi) = \{t \in \mathbf{R}; \varphi(t) = 0\}$ . Moreover, in the special case  $a \equiv 1 \equiv b$ , the conclusion holds with (2.8) replaced by

$$(2.9) \quad [G(t)]^{1/2} = \mathcal{O}(F(t)).$$

PROOF. We proceed to the construction of a function  $v$  as in Lemma 2.3. Let  $\beta$  be the unique solution of

$$(2.10) \quad \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) = (1/2)a(r)$$

determined by  $\beta(0)=0$ ,  $\beta'(0)=0$ . Equation (2.10) is of type (1.23), with  $f \equiv 1/2$ : so we can transform it into (1.25) (via (1.24)) and apply Lemma 1.20 to conclude that  $\beta$  is defined for all  $r \geq 0$ . Moreover, (2.8) enables us to apply Lemma 1.18 and deduce that  $\beta(r) \rightarrow +\infty$  as  $r \rightarrow +\infty$ . Next, set  $v(x) = \beta(r(x))$ ; we compute using Gauss Lemma, (2.1) and (2.10) to get

$$\Delta v = \beta''(r) + \beta'(r)\Delta r \leq \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) = (1/2)a(r) < a(r) \leq b$$

outside some  $B_R(q)$ . Thus we can apply Lemma 2.3 to conclude. If furthermore  $a(r) \equiv 1$ , then  $t=h(r)=r$ ; so  $\tilde{g}=g$  and (2.2) tells us that in this case (2.9) is equivalent to (2.8). //

(2.11) Let  $N$  be a complete Riemannian manifold such that  $\text{Riem } N \leq K$ , for some nonpositive constant  $K$ . We study harmonic maps  $\phi: M \rightarrow N$  under the assumption  $\text{Ricci}(M) \geq -AG(r)$ . We say that any such  $\phi$  is bounded if its image is relatively compact in  $N$ . We have

THEOREM 2.12. Let  $\phi: M \rightarrow N$  be a harmonic map between manifolds as in (2.11). Suppose that

$$e(\phi)(x) \geq [\varepsilon + r(x)]^{-2d} \quad \text{outside } B_R(q),$$

for some  $R, \varepsilon > 0$  and  $d \leq (1/2)$ . If

$$(2.13) \quad [t]^{d/(1-d)}[G(t^{1/(1-d)})]^{1/2} = \mathcal{O}(F(t))$$

for some  $F \in \mathcal{G}$  as in (1.10), then  $\phi$  is unbounded.

PROOF. Let  $\rho$  be the distance in  $N$  from  $\phi(q)$ . We prove the theorem for  $K < 0$  (the case  $K=0$  is similar). Without loss of generality we can assume  $K=-1$ : setting  $h=(\cosh \rho)/2$  and  $u=h \circ \phi$ , we compute (see [5])

$$(2.14) \quad \Delta u = \sum_i \text{Hess}(h)(\phi_* e_i, \phi_* e_i) + dh(\tau(\phi))$$

where  $\{e_i\}$ ,  $1 \leq i \leq m$ , is a local orthonormal frame in  $TM$ . But  $\tau(\phi)=0$ , because  $\phi$  is harmonic: thus, applying the Hessian comparison theorem [8] to (2.14), we obtain

$$(2.15) \quad \Delta u \geq (\cosh \rho) e(\phi) \geq e(\phi).$$

Now we show that we can apply Lemma 2.7 with  $\varphi \equiv 1$ ,  $b=e(\phi)$  and  $a(r)=[\varepsilon+r]^{-2d}$ : indeed, (1.24) is explicitly integrable and gives

$$t = h(r) = (1/(1-d))[(\varepsilon+r)^{1-d} - \varepsilon^{1-d}];$$

from this, together with (1.27) and (2.2) it is not difficult to see that there exists  $c_1 > 0$  such that

$$(2.16) \quad 0 \leq [\tilde{g}'(t)/\tilde{g}(t)] \leq c_1 [t]^{d/(1-d)} [G(t^{1/(1-d)})]^{1/2} \quad \text{for } t \text{ large};$$

this latter is  $\mathcal{O}(F(t))$  by hypothesis (2.13); thus (2.8) holds and we can apply Lemma 2.7 (with  $\varphi \equiv 1$ ) to conclude that  $u -$  and so  $\phi -$  is unbounded. //

**THEOREM 2.17.** Assume  $\text{Ricci}(M) \geq -AG(r)$ , with  $[G(r)]^{1/2} = \mathcal{O}(F(r))$ , for some  $F \in \mathcal{G}$  as in (1.10). Let  $N$  be a Riemannian manifold such that  $\text{Riem } N \leq K$ ,  $K \in \mathbb{R}$ ; and let  $B_R(\tilde{q})$  be a geodesic ball centered at  $\tilde{q} \in N$  and inside the cut locus of  $\tilde{q}$  ( $R < \pi/2(K)^{1/2}$  if  $K > 0$ ). If  $\phi: M \rightarrow N$  is a smooth map with  $|\tau(\phi)| \leq \tau_0$ ,  $\tau_0 \in [0, +\infty)$ , and  $\phi(M) \subset B_R(\tilde{q})$ , then setting  $\chi = \inf_M \{e(\phi)\}$

$$(2.18) \quad R \geq (K)^{-1/2} \tan^{-1} \{2(K)^{1/2} \chi / \tau_0\} \quad \text{when } K > 0;$$

$$(2.19) \quad R \geq 2\chi / \tau_0 \quad \text{when } K = 0;$$

$$(2.20) \quad R \geq (-K)^{-1/2} \tanh^{-1} \{2(-K)^{1/2} \chi / \tau_0\} \quad \text{when } K < 0.$$

**PROOF.** Again, we only prove the theorem in the case  $K = -1$  (the other cases are similar). Proceeding as in the proof of (2.12) we obtain (2.14) and deduce that

$$(2.21) \quad \Delta u \geq u \{2e(\phi) + \tanh(\rho \circ \phi) \langle \nabla \rho, \tau(\phi) \rangle\}$$

Since  $u \geq (1/2)$  and  $-\tanh(R)\tau_0 \leq \tanh(\rho \circ \phi) \langle \nabla \rho, \tau(\phi) \rangle$  (using  $|\nabla \rho| = 1$ ), we have

$$(2.22) \quad \Delta u \geq \chi - (1/2) \tanh(R)\tau_0.$$

Now, suppose that  $\chi - (1/2) \tanh(R)\tau_0 = C > 0$ : then we apply Lemma 2.7 with  $a \equiv 1 \equiv b$  and  $\varphi \equiv C$  to conclude that  $u$  is unbounded — contradiction. Thus

$$\chi - (1/2) \tanh(R)\tau_0 \leq 0$$

and (2.20) follows readily. //

**REMARK 2.23.** Theorem 2.17 was proved — with different methods — in [2]

in the special case  $G(r)=[1+\{r \log (r+2)\}^2]$  (compare with (1.10)). Similarly, Corollary 3.2, 3.5 and Theorems 3.3, 3.4 of [2] still hold if assumption  $\text{Ricci}(M) \geq -A[1+\{r \log (r+2)\}^2]$  is replaced by  $\text{Ricci}(M) \geq -AG(r)$  as in our Theorem 2.17. If  $\phi$  is an isometric immersion, then  $\tau(\phi)=mH$ , where  $m=\dim M$  and  $H$  is the mean curvature vector; the boundedness of  $|H|$ , together with Gauss equations, ensure that in this case the assumption  $\text{Ricci}(M) \geq -AG(r)$  can be substituted by the corresponding assumption on the scalar curvature: in particular (compare with Theorem 3.3 of [2]), we obtain

**COROLLARY 2.24.** *Let  $M$  be a complete, non-compact immersed submanifold of  $\mathbf{R}^n$  with parallel mean curvature  $H$  and scalar curvature bounded below by  $-AG(r)$ , with  $[G(r)]^{1/2}=\mathcal{O}(F(r))$ , for some  $F \in \mathcal{G}$  as in (1.10). If the image of the Gauss map  $\gamma: M \rightarrow G_m(\mathbf{R}^n)$  lies in a geodesic ball  $B_R(\bar{q})$  with  $R < \pi/(2\sqrt{B})$  (where  $B=1$  if  $n-m=1$  and  $B=2$  otherwise), then  $M$  is minimal.*

**REMARK 2.25.** Let  $M$  be the 2-dimensional plane with metric  $dr^2+k^2(r)d\theta^2$  and assume that  $k(r)=\exp[r^2(\log r)]$  for  $r \gg 1$ . Since  $\text{Ricci}(M)=-k''/k$ , we see that  $\text{Ricci}(M) \geq -Ar^2(\log r)^2$  for  $r \gg 1$  and some  $A>0$ . So we can apply Theorem 2.17 with  $F(r)=r(\log r)(\log \log r)$ ; on the other hand,  $M$  has no sub-quadratic exponential growth. Indeed

$$\lim_{r \rightarrow +\infty} \{\log(\text{Vol } B_r)\}/r^2 = \lim_{r \rightarrow +\infty} \log r = +\infty.$$

Thus Theorem 2.17 extends Theorem 3.1 (and related Corollaries) of [10].

### 3. Applications to models and Hadamard manifolds.

(3.1) We begin with some differential geometric preliminaries: a *model* (see [8]) is a complete Riemannian manifold

$$(3.2) \quad M^m(g) = (S^{m-1} \times [0, +\infty), g^2(r)d\theta^2 + dr^2), \quad m \geq 2,$$

where  $d\theta^2$  is the standard metric of  $S^{m-1}$  and  $g(r)$  is a smooth function, odd at the origin and such that

$$(3.3) \quad g(0) = 0, \quad g'(0) = 1 \quad \text{and} \quad g(r) > 0 \quad \text{for all } r > 0.$$

The point of  $M^m(g)$  corresponding to  $r=0$  is called pole and denoted by  $p$ . If  $g(r)=r, \sinh r, \sin r$  ( $r \in [0, \pi/2)$ ), we have  $M^m(g)=\mathbf{R}^m, \mathbf{H}^m, S_+^m$  respectively. (Of course,  $S_+^m$  is not a model.)

(3.4) Let  $(N, ds^2)$  be a complete,  $n$ -dimensional Riemannian manifold; and let  $B_R(q)$  be a geodesic ball inside the cut locus of  $q \in N$ : following [8] we say that  $B_R(q)$  *dominates* an  $n$ -dimensional model  $M^n(\tilde{k})$  if  $z \in B_R(q)$ ,  $y \in M^n(\tilde{k})$  and  $\rho(z)=\tilde{\rho}(y)$  ( $\rho, \tilde{\rho}$  distances from  $q$  and the pole of  $M^n(\tilde{k})$  respectively) imply

$$(3.5) \quad K_{\text{rad}}(z) \leq K_{\text{rad}}(y),$$

where  $K_{\text{rad}}$  is the radial curvature. Under these hypotheses, the hessian comparison theorem and Proposition 2.20 of [8] give

$$(3.6) \quad \text{Hess}(\rho)_z > \text{Hess}(\tilde{\rho})_y = \tilde{k}'(\tilde{\rho}(y))\tilde{k}(\tilde{\rho}(y))d\theta^2$$

where  $d\theta^2$  is the standard metric of  $S^{n-1}$  and the symbol  $>$  is explained in [8], p. 19.

LEMMA 3.7. *Let  $M, N$  be Riemannian manifolds,  $p \in M, q \in N, \dim N = n$ , and let  $ds^2$  be the metric on  $N$ . Let  $\rho$  be the distance function from  $q$  and  $B_R(q)$  a ball which dominates  $M^n(\tilde{k})$  as in (3.4). Let  $\lambda^2(z)$  be the minimum eigenvalue of  $ds^2 - d\rho^2$  at  $z \in B_R(q)$  and  $\phi: M \rightarrow N$  a smooth map such that  $\phi(p) = q$ . Define  $u = \rho \circ \phi$ ,  $U = \{x \in M : u(x) \neq 0\}$ , and  $\xi = \pi \circ \phi$  on  $U$ , where  $\pi: B_R(q) = [0, R] \times S^{n-1} \rightarrow S^{n-1}$  denotes projection on the second factor. Then on  $U \cap \phi^{-1}(B_R(q))$*

$$(3.8) \quad \langle \nabla \rho, \tau(\phi) \rangle \leq \Delta u - 2\tilde{k}'(u)\tilde{k}(u)e(\xi)[(\lambda^2 \circ \phi)/(\tilde{k}(u))^2].$$

PROOF. A standard computation (see [5]) gives

$$(3.9) \quad \langle \nabla \rho, \tau(\phi) \rangle = \Delta u - \sum_i \text{Hess}(\rho)_\phi(d\phi(e_i), d\phi(e_i))$$

where  $\{e_i\}$  is a local orthonormal frame on  $M$ . Now we apply (3.6) to (3.9) to get

$$(3.10) \quad \langle \nabla \rho, \tau(\phi) \rangle \leq \Delta u - \tilde{k}'(u)\tilde{k}(u)\sum_i d\theta^2(d\tilde{\phi}(e_i), d\tilde{\phi}(e_i))$$

where  $d\tilde{\phi}(e_i)$  are defined as follows: Let  $\theta^A, A=1, \dots, n-1$ , be a local orthonormal coframe for  $S^{n-1}$ ; using polar coordinates  $(\rho, \theta)$  we can express  $ds^2$  on  $B_R(q)$  in the form

$$(3.11) \quad ds^2 = d\rho^2 + [h_{AB}^2(\rho, \theta)]\theta^A\theta^B$$

(the sum over repeated indexes is understood). Because we perform the computations at a point  $z = \phi(x) \neq q$ , we can assume that we have diagonalized (3.11) by means of an orthogonal transformation of the  $\theta^A$ 's, so that at  $z$

$$ds^2 = d\rho^2 + [h_A^2(\rho, \theta)][\theta^A]^2.$$

Let  $\{E_A\}$  be the frame field dual to  $\{\theta^A\}$ . Then

$$d\phi(e_i) = B_i^0[\partial/\partial\rho] + B_i^A[h_A(\rho, \theta)]^{-1}E_A$$

with  $|d\phi(e_i)|^2 = (B_i^0)^2 + \sum_A (B_i^A)^2$ . It follows that we can define, at  $y$ ,

$$d\tilde{\phi}(e_i) = B_i^0[\partial/\partial\tilde{\rho}] + B_i^A[\tilde{k}(\tilde{\rho}(y))]^{-1}E_A.$$

From this we deduce that

$$(3.12) \quad \sum_i d\theta^2(d\tilde{\phi}(e_i), d\tilde{\phi}(e_i)) = \{\sum_{A,i}(B_i^A)^2\}/\tilde{k}^2(u).$$

Now we observe that, on  $U$ ,  $2e(\xi) = \sum_{A,i}\{B_i^A/h_A\}^2$  and therefore

$$(3.13) \quad 2e(\xi) \leq \{\sum_{A,i}(B_i^A)^2\}/\lambda^2.$$

Now (3.8) follows from (3.10), (3.12) and (3.13). //

REMARK 3.14. In many instances  $[\lambda^2/\tilde{k}^2] \geq 1$  and so (3.8) yields the more manageable inequality

$$(3.15) \quad \langle \nabla \rho, \tau(\phi) \rangle \leq \Delta u - 2\tilde{k}'(u)\tilde{k}(u)e(\xi).$$

For instance, a model  $N$  dominates itself with  $[\lambda^2/\tilde{k}^2] \equiv 1$ . Or else, let the sectional curvature on  $B_R(q)$  be bounded above by  $K \in \mathbf{R}$ . We have the three cases  $K < 0$ ,  $K = 0$  and  $K > 0$  or, to simplify notation,  $K = -1$ ,  $K = 0$  and  $K = 1$ . Using Rauch comparison theorem we obtain  $\lambda^2 \geq \sinh^2 \rho$ ,  $\lambda^2 \geq \rho^2$  and  $\lambda^2 \geq \sin^2 \rho$  respectively. Thus, choosing  $\mathbf{H}^n$ ,  $\mathbf{R}^n$  and  $S_+^n$  respectively as dominated "models", we find  $[\lambda^2/\tilde{k}^2] \geq 1$ . Lemma 3.7 provides a key ingredient in the proof of the next results and can be applied to manifolds  $M, N$  in considerable generality: however, in order to limit technical assumptions on the cut locus of points, we shall only state and prove the next theorems for especially interesting choices of  $M$  and  $N$ , leaving to the interested reader the details of further possible extensions to the other cases covered by Lemma 3.7 (see also (3.40), as an example).

(3.16) Recall that a Hadamard manifold  $N$  is a complete, simply connected Riemannian manifold with non-positive sectional curvature; in particular, the cut locus of any point is empty. In case the sectional curvature is bounded above by  $-B^2$ ,  $B > 0$ , then  $N$  dominates  $M_k^n$  with  $\tilde{k}(r) = \sinh(Br)$ .

THEOREM 3.17. Let  $N$  be a Hadamard manifold. Suppose that  $M^m(g)$  is a model such that

$$(3.18) \quad [g(r)]^{-1} \notin L^1(+\infty) \quad \text{and} \quad g'(r) = \mathcal{O}(F(h(r)))$$

for some  $F \in \mathcal{G}$  as in (1.10) and  $h(r) = \int_0^r [1+g(s)]^{-1} ds$ . Then there are no bounded harmonic maps  $\phi: M^m(g) \rightarrow N$  such that  $e(\xi) > 0$  on  $U = \{x \in M^m(g): \phi(x) \neq \phi(p)\}$  and

$$(3.19) \quad e(\xi) \geq [c/g^2] \quad \text{on } U \cap \{M^m(g) \setminus B_{R_0}(p)\} \quad \text{for some } c, R_0 > 0$$

( $\xi$  is defined as in Lemma 3.7).

PROOF. By contradiction, suppose that there exists a harmonic map  $\phi: M^m(g) \rightarrow N$  whose image is contained in  $B_R(q)$ , for  $q = \phi(p)$  and some  $R > 0$ .

By Remark (3.14) and (3.16)  $B_R(q)$  dominates a model  $M^n(\tilde{k})$  that, without loss of generality, we can assume to be either  $H^n$  or  $R^n$ : in particular, we have

$$(3.20) \quad \tilde{k}'(\rho) > 0.$$

Let  $u = \rho \circ \phi$ ; because  $\phi$  is harmonic,  $\tau(\phi) = 0$ . Thus, using Lemma 3.7 in the form (3.15), we obtain

$$(3.21) \quad \Delta u \geq 2\tilde{k}'(u)\tilde{k}(u)e(\xi)$$

on the open, dense set  $U$ . By a version of Lemma 2.3 (with  $\varphi(u) = 2\tilde{k}'(u)\tilde{k}(u)$ ,  $b(x) = e(\xi)(x)$ ) it suffices to construct a  $C^2$  function  $v$  such that

$$(3.22) \quad \Delta v < e(\xi) \quad \text{on } U \cap \{M^m(g) \setminus B_{R_0}(p)\}; \text{ and}$$

$$(3.23) \quad v(x) \longrightarrow +\infty \quad \text{as } r(x) \rightarrow +\infty.$$

For this purpose we consider

$$(3.24) \quad \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) = c/[1+g(r)]^2$$

$$\beta(0) = 0, \quad \beta'(0) = 0.$$

This is of type (1.23) with  $f \equiv 1$  and  $a(r) = c/[1+g(r)]^2$ ; using (1.24) we transform (3.24) in an equation of type (1.25): then, using (1.27), (3.18) and computing it is not difficult to deduce that  $[\tilde{g}'(t)/\tilde{g}(t)] \leq D(t)$ , for some function  $D(t)$  which satisfies the hypotheses of Lemma 1.18. Thus Lemmas 1.2, 1.18 and 1.20 (with  $f \equiv 1$ ) enable us to conclude that (3.24) has a solution  $\beta$  which is defined for all  $r > 0$  and tends to  $+\infty$  as  $r \rightarrow +\infty$ . We set  $v = \beta \circ r$ : clearly (3.23) holds. Moreover, on  $U \cap \{M^m(g) \setminus B_{R_0}(p)\}$ ,

$$(3.25) \quad \Delta v = \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) = c/[1+g(r)]^2 < c/[g(r)]^2 \leq e(\xi)$$

as required by (3.22).

**THEOREM 3.26.** *Let  $N$  be a Hadamard manifold with sectional curvature bounded above by a negative constant. Let  $M^m(g)$  be a model such that*

$$(3.27) \quad [g(r)]^{-1} \notin L^1(+\infty) \quad \text{and} \quad g'(r) = \mathcal{O}(F^\gamma(h(r)))$$

*for some  $F \in \mathcal{F}$  as in (2.10),  $0 < \gamma < 1$  and  $h(r) = \int_0^r [1+g(s)]^{-1} ds$ . Then there are no harmonic maps  $\phi: M^m(g) \rightarrow N$  such that, on  $U = \{x \in M^m(g) : \phi(x) \neq \phi(p)\}$ ,*

$$(3.28) \quad e(\xi) \geq [c/g^2] \quad \text{for some } c > 0.$$

( $\xi$  is defined as in Lemma 3.7).

**PROOF.** We consider

$$(3.29) \quad \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) = \{c/[1+g(r)]^2\}\tilde{k}'(\beta)\tilde{k}(\beta).$$

with  $\tilde{k}$  as in (3.16). As usual, we transform (3.29) into an equation of type (1.25): applying Proposition 1.11 (with  $\eta$  so small as to have  $\gamma < (1-\eta)/(1+\eta)$ ) we obtain a solution  $\beta$  of (3.29) corresponding to initial conditions

$$(3.30) \quad \beta(0) = \beta_0 > 0, \quad \beta'(0) = 0.$$

Such a  $\beta$  is defined on a maximal finite interval  $[0, R)$  and satisfies

$$(3.31) \quad \beta(r) \longrightarrow +\infty \quad \text{as } r \rightarrow R^-.$$

Moreover, given arbitrary  $\varepsilon, \delta > 0$ , we can assume that  $R > \delta$  and

$$(3.32) \quad \beta(r) < \varepsilon \quad \text{for all } r \in [0, \delta]$$

provided that  $\beta_0$  is sufficiently small; indeed,  $\tilde{k}'\tilde{k}$  is locally Lipschitz on  $[0, +\infty)$  and so, if  $\beta_0$  is small, the solution determined by (3.30) approximates the trivial solution  $\beta \equiv 0$  on compact sets.

Next, for  $x \in M^m(g)$  we define  $v(x) = \beta(r(x))$ ; so, using (3.29), we have

$$(3.33) \quad \begin{aligned} \Delta v &= \beta''(r) + (m-1)[g'(r)/g(r)]\beta'(r) \\ &= \{c/[1+g(r)]^2\}\tilde{k}'(v)\tilde{k}(v) < \{c/[g(r)]^2\}\tilde{k}'(v)\tilde{k}(v). \end{aligned}$$

Moreover,

$$(3.34) \quad v(x) < \varepsilon \quad \text{on } B_\delta(p); \quad \text{and} \quad v(x) \longrightarrow +\infty \quad \text{as } x \rightarrow \partial B_R(p)$$

by (3.31) and (3.32). Now we assume that there exists a nonconstant  $\phi: M^m(g) \rightarrow N$  as in the statement of the theorem. Let  $\rho$  be the distance in  $N$  from  $q = \phi(p)$  and set  $u = \rho \circ \phi$ . Since  $\phi$  is nonconstant, there exist  $\delta, \varepsilon > 0$  and  $y \in B_\delta(p)$  such that  $u(y) > \varepsilon$ . Let  $v$  be constructed as above with respect to this latter choice of  $\varepsilon, \delta$ . Since  $\phi$  is nonconstant,  $U$  is dense in  $M^m(g)$ ; thus the open set  $U \cap B_R(p)$  is not empty. On it we consider the function  $w = u - v$ : if  $z \in \partial\{U \cap B_R(p)\}$ , then either  $r(z) = R$  or  $\phi(z) = q$ ; hence  $w$  is nonpositive near  $\partial\{U \cap B_R(p)\}$ . On the other hand at  $y$  we have  $w(y) = u(y) - v(y) > \varepsilon - \varepsilon = 0$ . It follows that  $w$  attains a positive maximum at some interior point  $\tilde{y} \in U \cap B_R(p)$ . Using Lemma 3.7 and (3.33), at  $\tilde{y}$  we have

$$0 \geq \Delta w \geq \tilde{k}'(u)\tilde{k}(u)e(\xi) - \tilde{k}'(v)\tilde{k}(v)c/g^2 \geq [c/g^2]\{\tilde{k}'(u)\tilde{k}(u) - \tilde{k}'(v)\tilde{k}(v)\}.$$

Now  $u(\tilde{y}) > v(\tilde{y})$  together with  $\tilde{k}'\tilde{k}$  increasing give the desired contradiction. //

APPLICATION 3.36. In the case of rotationally symmetric maps between models  $e(\xi) = (m-1)/g^2$  (see [13]). We also observe that the condition  $g'(r) = \mathcal{O}(F(h(r)))$  in (3.27) (and similarly in (3.18)) can be relaxed: indeed, in order to be able to apply Proposition 1.11, as required in the proof of Theorem 3.26, it

suffices that  $g'(r_i) = \mathcal{O}(F'(h(r_i)))$  as  $i \rightarrow +\infty$ , for each sequence  $r_i$  such that  $g'(r_i) \rightarrow +\infty$  as  $i \rightarrow +\infty$  (see also Remark 1.19 b)). As a special case, blowing up of solutions occurs if  $g'(r)$  is bounded from above; these facts together lead us to

**COROLLARY 3.37.** *Let  $M^m(g)$  be a model such that  $[g]^{-1} \notin L^1(+\infty)$  and  $g'$  is bounded above by some positive constant. Then any rotationally symmetric harmonic map  $\phi: M^m(g) \rightarrow \mathbf{H}^m$  is constant.*

Similarly,

**COROLLARY 3.38.** *Let  $N$  be a Hadamard manifold with sectional curvature bounded above by a negative constant and  $M^m(g)$  a model such that  $[g]^{-1} \notin L^1(+\infty)$  and  $g'$  is bounded above by some positive constant. Then there are no nonconstant harmonic maps  $\phi: M^m(g) \rightarrow N$  such that, on  $U = \{x \in M^m(g) : \phi(x) \neq \phi(p)\}$ ,*

$$(3.39) \quad e(\xi) \geq [c/g^2] \quad \text{for some } c > 0.$$

( $\xi$  is defined as in Lemma 3.7).

**APPLICATION 3.40.** Instead of a Hadamard manifold  $N$  we can take a model, say  $N = N^n(k)$ , and consider maps  $\phi: M^m(g) \rightarrow N^n(k)$  which send pole into pole: then Theorem 3.17 (resp., Theorem 3.26 and its Corollaries 3.37 and 3.38) holds true — with the same proofs — if  $k' > 0$  (resp.,  $k' > 0$ ,  $(kk')' > 0$  and  $kk'$  verifies (1.11) i)), the remaining assumptions being unchanged. That is of interest because the sectional curvature of these models  $N^n(k)$  is not necessarily nonpositive.

**REMARK 3.41.** Assumption (3.19) (or, equivalently, (3.28) or (3.39)) gives an extension of condition (0.2) in Theorem 0.1 (resp., Theorem 1) of [16] (resp., [17]). In particular, Theorem 3.26, Corollaries 3.37, 3.38 and (3.40) extend the main theorems of [16], [17].

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