# REMOVABLE SINGULARITIES FOR BLOCH AND BMO FUNCTIONS 

BY<br>Joseph A. Cima ${ }^{1}$ and Ian Graham ${ }^{2}$

## Introduction

This paper is a continuation of a study of the following problem. Let $\Omega$ be a domain in $\mathbf{C}^{n}$ with $V$ a subvariety of $\Omega$. Assume $\mathscr{F}$ is a space of holomorphic functions (on $\Omega$ ) which satisfy a given property. If one is given a function $f$ holomorphic on $\Omega \backslash V$ what conditions on the growth of $f$ and what geometric properties of $V$ will permit us to extend $f$ to a function $\widetilde{f}$ holomorphic on $\Omega$ and such that $\tilde{f}$ is in $\mathscr{F}$. In [2] we solved this problem for the ball in $\mathbf{C}^{n}$ and the space $\mathscr{F}$ represented by the Hardy space. In this paper we pursue this line of investigation and prove the following theorem.

Theorem 1. Let $\Omega$ be a bounded domain in $\mathbf{C}^{n}$ and let $V$ be a subvariety of $\Omega$. Assume a function $f$ is holomorphic on $\Omega \backslash V$, with $f$ satisfying the area bounded mean oscillation (BMO) condition on $\Omega \backslash V$. Assume further that $V$ satisfies condition $A$ (see Section 4). Then $f$ extends to a function $\tilde{f}$ holomorphic on $\Omega$ and $\tilde{f}$ satisfies the area BMO condition.

Definitions will be given in detail in Section 2. If $\Omega$ is strictly pseudo convex then the BMO condition referred to in the theorem coincides with the Bloch condition. A special case of this theorem which motivates the geometric condition on $V$ is the following.

Theorem 2. Let $\mathbf{B}_{1}$ be the unit disc in $\mathbf{C}^{1}$ and let $V=\left\{\alpha_{j}\right\}_{1}^{\infty}$ be a discrete set satisfying the sparsity condition

$$
\begin{equation*}
\chi\left(\alpha_{j}, \alpha_{k}\right)=\left|\frac{\alpha_{j}-\alpha_{k}}{1-\bar{\alpha}_{j} \alpha_{k}}\right| \geqslant \delta>0, \quad j \neq k \tag{1}
\end{equation*}
$$

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Assume $f$ is holomorphic on $\mathbf{B}_{1} \backslash V$ and satisfies

$$
\begin{equation*}
\left|f^{\prime}(z)\right| \leqslant c\left[\min \left\{\rho(z, V), \rho\left(z, \partial \mathbf{B}_{1}\right)\right\}\right]^{-1} z \in \mathbf{B}_{1} \backslash V \tag{2}
\end{equation*}
$$

for $c$ and $\delta$ positive constants and $\rho$ the distance from $z$ to $V$ (in the Euclidean norm). Then $f$ extends holomorphically to a function $\widetilde{f}$, holomorphic on $\mathbf{B}_{1}$, and $\tilde{f}$ is a Bloch function, i.e. there exists $c_{1}>0$ such that

$$
\left|\widetilde{f}^{\prime}(z)\right| \leqslant c_{1}\left(\rho\left(z, \partial \mathbf{B}_{1}\right)\right)^{-1}, \quad z \in \mathbf{B}_{1}
$$

An example of $R$. Timoney shows that condition (2) alone is not sufficient to obtain the result of Theorem 2. More detailed comments concerning the one variable case will follow after the proofs of these theorems. Our condition A is in part a covering condition of Whitney type. We note that conditions on the Whitney decomposition of a domain $\Omega \subseteq \mathbf{R}^{n}$ have been used by Peter Jones [6] in his work on extending BMO functions from the domain $\Omega$ in $\mathbf{R}^{n}$ into all of $\mathbf{R}^{n}$. Some of the research in this paper was carried out while the second author was on sabbatical leave at the University of California, Berkeley.

## 2. Area BMO functions and Bloch functions

Let $\Omega$ be a bounded domain in $\mathbf{R}^{n}$ and let $f$ be in $L^{\prime}(\Omega)$. For $Q \in \Omega$ and $r>0, \mathscr{B}(a, r) \equiv\left\{x \in \mathbf{R}^{n}:\|x\|<r\right\}$ and let $\lambda_{n}=\lambda$ denote Lebesgue measure on $\mathbf{R}^{n}$. The function $f$ is said to have bounded mean oscillation if there is a number $M>0$ such that

$$
\begin{equation*}
\frac{1}{|\mathscr{B}(Q, r)|} \int_{\mathscr{B}(Q, r)}\left|f(x)-\left(\frac{1}{|\mathscr{B}(Q, r)|} \int_{\mathscr{B}(Q, r)} f(y) d \lambda(y)\right)\right| d \lambda(x) \leqslant M \tag{3}
\end{equation*}
$$

for all $Q \in \Omega$ and $r>0$ such that $\mathscr{B}(Q, r) \subseteq \Omega$ and where $\lambda(\mathscr{B}(Q, r))=$ $|\mathscr{B}(Q, r)|$.

A function $f$ holomorphic on $\mathbf{B}_{1}$ is said to be a Bloch function if there is a constant $M$ such that

$$
\left|f^{\prime}(z)\right| \leqslant M\left(1-|z|^{2}\right)^{-1}, \quad z \in \mathbf{B}_{1} .
$$

In general if $\Omega$ is a bounded symmetric domain in $\mathbf{C}^{n}$ and $f$ is holomorphic on $\mathbf{C}^{n}$ then $f$ is a Bloch function (on $\Omega$ ) if

$$
\begin{equation*}
\sup \left\{\frac{\langle\nabla f(z), x\rangle}{H_{z}(x, \bar{x})^{1 / 2}}: x \neq 0, x \in \mathbf{C}^{n}, z \in \Omega\right\}<+\infty \tag{4}
\end{equation*}
$$

where $H_{z}(x, \bar{x})$ denotes the Bergman metric on $\Omega$. If $\Omega$ is strictly pseudo convex this definition is equivalent to requiring that

$$
|\nabla f(z)| \leqslant M(\rho(z, \partial \Omega))^{-1}, \quad z \in \Omega
$$

For the unit disc, as well as strictly pseudo convex domains in $\mathbf{C}^{n}$ the set of holomorphic BMO functions on $\Omega$ coincides with the space of Bloch
functions on $\Omega$. This follows from the Basic Lemma proven below. For the $n=1$ case (and with a slightly different BMO condition) this correspondence is noted in the paper of Coiffman, Rochberg and Weiss [3, p. 47]. For $n>1$, the proof given here is based on written correspondence with R. Timoney.

Basic Lemma. Let $\Omega$ be a bounded domain in $\mathbf{R}^{n}$ and let $f$ be harmonic on $\Omega$. The function $f$ satisfies the BMO condition (3) if and only if there is a constant $M^{\prime}$ such that

$$
\begin{equation*}
|\nabla f(x)| \leqslant M^{\prime}(\rho(x, \partial \Omega))^{-1}, \quad x \in \Omega . \tag{5}
\end{equation*}
$$

Proof. Let us assume that $g$ is a function harmonic on the unit ball of $\mathbf{R}^{n}$ and that

$$
|\nabla g(x)| \leqslant c(1-|x|)^{-1}
$$

Then

$$
g(x)-g(0)=\int_{0}^{1}\left(\frac{d}{d t} g(t x)\right) d t=\int_{0}^{1} \nabla g(t x) \circ x d t
$$

It follows then that

$$
|g(x)-g(0)| \leqslant \int_{0}^{1} \frac{|x|}{1-t|x|} d t=c \ln (1-|x|)
$$

and

$$
\int_{|x| \leqslant 1}|g(x)-g(0)| d \lambda(x) \leqslant c \int_{|x| \leqslant 1} \log (1-|x|) d \lambda(x)=c^{\prime}
$$

Now assume $f$ is harmonic on $\Omega$ and satisfies (5). Let $a \in \Omega, r<\rho(a, \partial \Omega)$. Define $g(y)=f(a+r y)$ for $|y|<1$. Observe that

$$
r(1-|y|)=\rho(a+r y, \partial \mathscr{B}(a, r))
$$

hence

$$
|\nabla g(y)|(1-|y|)=r(1-|y|)|\nabla f(a+r y)| \leqslant M^{\prime}
$$

With this notation $(x=a+r y)$,

$$
\begin{aligned}
\left.\frac{1}{|\mathscr{B}(a, r)|} \int_{\mathscr{B}(a, r)} \right\rvert\, f(x) & \left.-\left(\frac{1}{|\mathscr{B}(a, r)|} \int_{\mathscr{B}(a, r)} f(t) d t\right) \right\rvert\, d \lambda(x) \\
& =\frac{1}{r^{n}} \int_{\mathscr{B}(a, r)}|f(x)-f(a)| d \lambda(x)=\int_{|y|<1}|g(y)-g(0)| d \lambda(y) .
\end{aligned}
$$

As we have shown above the right side of this inequality is uniformly bounded and this proves that $f$ is in $\operatorname{BMO}(\Omega)$.

Assume for the converse that $f$ is a harmonic function on $\Omega$ and satisfies
the BMO condition. Let $a \in \Omega, r=1 / 2 \rho(a, \partial \Omega)$ and for $|y|<1$ set $g(y)=$ $f(a+r y)$. There is a smooth kernel $K(y, \eta)$ such that, for $|y|<1 / 2$,

$$
g(y)-g(0)=\int_{1 / 2<|\eta|<3 / 4} K(y, \eta)(g(\eta)-g(0)) d \lambda(\eta)
$$

Hence, there is a constant $c$ such that

$$
\begin{aligned}
&|\nabla g(0)|=\left|\int_{1 / 2<|\eta|<3 / 4} \nabla y K(y, \eta)(g(\eta)-g(0)) d \lambda(\eta)\right| \\
& \leqslant c \int_{|\eta|<1}|g(\eta)-g(0)| d \lambda(\eta)
\end{aligned}
$$

By the earlier part of the proof,

$$
\rho(a, \partial \Omega)|\nabla f(a)|=2|\nabla g(0)| \leqslant c^{\prime} \int_{|\eta|<1}|g(\eta)-g(0)| d \lambda(\eta) \leqslant c^{\prime \prime}| | f \|_{\mathrm{BMO}}
$$

## 3. Proof of Theorem 2

Condition (1) on the pseudo-hyperbolic metric for the set $V=\left\{\alpha_{j}\right\}$ is called a sparsity condition (See Vinogradov and Khavin [10], Sarason [7, p. 22]). It is equivalent to the following, there is a $\delta^{\prime}>0$ such that

$$
\begin{equation*}
\left|\alpha_{j}-\alpha_{k}\right| \geqslant \delta^{\prime}\left(1-\left|\alpha_{k}\right|\right), \quad j \neq k \tag{6}
\end{equation*}
$$

For if $j \neq k$ and condition (6) is satisfied,

$$
\left(\frac{\left|\alpha_{j}-\alpha_{k}\right|}{1-\bar{\alpha}_{j} \alpha_{k} \mid}\right)^{2} \geqslant\left(\delta^{\prime}\right)^{2} \frac{\left(1-\left|\alpha_{j}\right|\right)\left(1-\left|\alpha_{k}\right|\right)}{\left|1-\bar{\alpha}_{j} \alpha_{k}\right|^{2}}
$$

The equality

$$
\left|\frac{a-b}{1-\bar{a} b}\right|^{2}=1-\frac{\left(1-|a|^{2}\right)\left(1-|b|^{2}\right)}{|1-\bar{a} b|^{2}}, \quad \bar{a} b \neq 1
$$

implies

$$
\left(\left|\frac{\alpha_{j}-\alpha_{k}}{1-\bar{\alpha}_{j} \alpha_{k}}\right|\right)^{2} \geqslant\left(\delta^{\prime}\right)^{2}\left(1-\left|\frac{\alpha_{j}-\alpha_{k}}{1-\bar{\alpha}_{j} \alpha_{k}}\right|^{2}\right)
$$

or

$$
\left|\frac{\alpha_{j}-\alpha_{k}}{1-\bar{\alpha}_{j} \alpha_{k}}\right|^{2}\left(1+\left(\delta^{\prime}\right)^{2}\right) \geqslant\left(\delta^{\prime}\right)^{2}
$$

The inequality

$$
\left|\frac{\alpha_{j}-\alpha_{k}}{1-\bar{\alpha}_{j} \alpha_{k}}\right| \leqslant \frac{\left|\alpha_{j}-\alpha_{k}\right|}{1-\left|\alpha_{k}\right|}
$$

yields the other half of the equivalence.

We proceed now to the proof of Theorem 2. Assume that $f$ and $V$ satisfy the hypothesis of Theorem 2. For $z$ near $\alpha_{j}$ our hypothesis implies that $f^{\prime}$ has an expansion of the form

$$
f^{\prime}(z)=\frac{A_{-1}}{\left(z-\alpha_{j}\right)}+A_{0}+A_{1}\left(z-\alpha_{j}\right)+\ldots
$$

for $z$ near $\alpha_{j}$. A standard argument shows that $f$ can be continued to a holomorphic function $\tilde{f}$ in a neighborhood of $\alpha_{j}$. Hence, $f$ extends to $\tilde{f}$ holomorphic on $\mathbf{B}_{1}$.

Lemma 1. Let $D_{j}$ denote the Euclidean disc, center $\alpha_{j}$ and radius

$$
c\left(1-\left|\alpha_{j}\right|\right)=r_{j}
$$

(where $c$ is a constant smaller than $\delta^{\prime} / 2$ ) and let $\Omega=\mathbf{B}_{1} / \cup_{1}^{\infty} D_{j}$. Then for $z \in \Omega, \rho\left(z, \partial \mathbf{B}_{1}\right) \leqslant c^{\prime}(\rho(z, V))$.

Proof. Assume not and that $z_{n} \in \mathbf{B}_{1} \backslash \cup D_{j}$ and $t_{n} \in V$ with

$$
\lim _{n \rightarrow \infty}\left(\frac{\left|z_{n}-t_{n}\right|}{1-\left|z_{n}\right|}\right)=0
$$

Under this assumption the inequalities

$$
\frac{1-\left|t_{n}\right|}{1-\left|z_{n}\right|} \leqslant 1+\frac{\left|t_{n}-z_{n}\right|}{1-\left|z_{n}\right|}
$$

and

$$
1-\frac{\left|t_{n}-z_{n}\right|}{1-\left|z_{n}\right|} \leqslant \frac{1-\left|t_{n}\right|}{1-\left|z_{n}\right|}
$$

imply that

$$
\lim _{n \rightarrow \infty}\left(\frac{\left|z_{n}-t_{n}\right|}{1-\left|t_{n}\right|}\right)=0
$$

This is inconsistent with our hypothesis and so the lemma is valid.
Lemma 1 shows there is a constant $d_{1}>0$ such that, for $z \in \Omega=$ $B_{1} \backslash \cup_{1}^{\infty} D_{j}$,

$$
\left|f^{\prime}(z)\right| \leqslant d_{1}\left(\rho\left(z, \partial \mathbf{B}_{1}\right)\right)^{-1}
$$

Also, for $j$ fixed and $z \in \bar{D}_{j}$,

$$
\left|\widetilde{f}^{\prime}(z)\right| \leqslant \max \left\{\left|\tilde{\mathrm{f}}^{\prime}(\zeta)\right|: \zeta \in \partial D_{j}\right\} \equiv M_{j} .
$$

Note that, for $\zeta \in \partial D_{j}$,

$$
\left|\tilde{f}^{\prime}(\zeta)\right| \leqslant d_{1}\left(\rho\left(\zeta, \partial B_{1}\right)\right)^{-1} \leqslant \frac{d_{1}}{r_{j}}
$$

and so $M_{j} \leqslant d_{1} / r_{j}$ for all $j=1,2,3, \ldots$.
Lemma 2. For $w_{1}, w_{2}$ in $D_{j}$ we have constants $c_{1}$ and $c_{2}$ which satisfy

$$
0<c_{1} \leqslant \frac{\rho\left(w_{1}, \partial \mathbf{B}_{1}\right)}{\rho\left(w_{2}, \partial \mathbf{B}_{1}\right)} \leqslant c_{2}
$$

where the constants are independent of $j$.
Proof. For $w_{1}, w_{2}$ in $\bar{D}_{j}$, we have

$$
\frac{1-\left|w_{1}\right|}{1-\left|w_{2}\right|} \leqslant \frac{\left(1-\left|\alpha_{j}\right|\right)+c\left(1-\left|\alpha_{j}\right|\right)}{\left(1-\left|\alpha_{j}\right|\right)-c\left(1-\left|\alpha_{j}\right|\right)} \leqslant \frac{1+c}{1-c}
$$

Similarly,

$$
\frac{1-c}{1+c} \leqslant \frac{1-\left|w_{1}\right|}{1-\left|w_{2}\right|}
$$

The proof of Theorem 2 is completed by observing that for $z \in \bar{D}_{j}$,

$$
\left|\tilde{f}^{\prime}(z)\right| \leqslant M_{j} \leqslant \frac{d_{1}}{r_{j}} \leqslant \frac{d_{1}}{c}\left(\frac{1+c}{1-c}\right) \frac{1}{1-|z|}
$$

The following example of R. Timoney [9] shows the condition (2) of Theorem 2 is not sufficient and so some geometric condition must be imposed on $V$ to obtain the result. Take $f(z)=(1-z)^{-1}$ which is not in the Bloch space. For $V$, choose the sequence

$$
V=\bigcup_{n=1}^{\infty}\left(\bigcup_{j=1}^{n^{2}} \alpha_{j, n}\right) \quad \text { where } \alpha_{j, n}=\left(1-\frac{1}{n}\right) \exp \left(\frac{-2 \pi j}{n^{2}}\right) i
$$

$V$ is the zero set of some function holomorphic on $\mathbf{B}_{1}$. The points $\alpha_{j, n}$ are evenly distributed on a system of circles centered at 0 . The distance between consecutive circles is approximately $(\sim) 1 / n^{2}$. There are $n^{2}$ points on the circle of radius $1-1 / n$ so the distance between adjacent points on the circle is also approximately $1 / n^{2}$. Hence for

$$
1-\frac{1}{n} \leqslant|z| \leqslant 1-\frac{1}{n+1}, \quad \rho(z, V) \sim 1 / n^{2}
$$

But, for

$$
1-\frac{1}{n} \leqslant|z| \leqslant 1-\frac{1}{n+1}
$$

we have

$$
\left|f^{\prime}(z)\right|=\left|\frac{1}{1-z}\right|^{2} \leqslant \frac{1}{(1-|z|)^{2}} \leqslant(n+1)^{2} \sim(\rho(z, V))^{-1}
$$

Hence, $\left|f^{\prime}(z)\right|$ satisfies the growth condition (2) but can not be (is not) extended to a Bloch function.

## 4. Generalization to domains in $\mathbf{C}^{\boldsymbol{n}}$

The purpose of this section is to generalize the ideas of the previous section. In particular, since the zeros (and poles) of holomorphic functions of several complex variables are not isolated the separation property of Theorem 2 must be replaced by a more refined covering argument in the $n(>1)$ dimensional case. In the following $\Omega$ is a bounded domain in $\mathbf{C}^{n}$ and $V$ is a subvariety of $\Omega$.

Definition. The subvariety $V$ satisfies the $A$ covering condition if the following conditions are satisifed.
(a) There are polydiscs $P_{\alpha}$ with centers $z_{\alpha}$ and polyradii $r_{\alpha}=\left(r_{1}(\alpha), \ldots\right.$, $r_{n}(\alpha)$ ) such that $\bar{P}_{\alpha} \subset \Omega$ and $V \subseteq \cup P_{\alpha}$.
(b) There are constants $d_{1}$ and $d_{2}$ such that

$$
d_{1} r_{j}(\alpha) \leqslant \rho\left(P_{\alpha}, \partial \Omega\right) \leqslant d_{2} r_{j}(\alpha), \quad j=1,2, \ldots, n .
$$

(3) There is a constant $d_{3}>0$ such that

$$
\rho\left(V, \partial_{0} P_{\alpha}\right) \geqslant d_{3} \rho\left(P_{\alpha}, \partial \Omega\right) \quad \text { for all } \alpha .
$$

The distinguished boundary of a polydisc $P_{\alpha}$ is written $\partial_{0} P_{\alpha}$.
(d) There is a constant $d_{4}>0$ such that for any $w \in V$ there exists $\alpha$ with $w \in P_{\alpha}$ and

$$
\rho\left(w, \partial P_{\alpha}\right) \geqslant d_{4} \rho\left(P_{\alpha}, \partial \Omega\right) .
$$

Examples of such varieties are given by subvarieties of bounded domains which extend across the boundary of $\Omega$ and are smooth near the boundary. More details will be given in the next section. In view of the Basic Lemma, Theorem 1 may be stated in the following form.

Theorem 1'. $\Omega$ is a bounded domain in $\mathbf{C}^{n}$ and $V$ is a subvariety of $\Omega$ satisfying the $A$ covering condition. Suppose $f$ is holomorphic on $\Omega / V$ and

$$
|\nabla f(z)| \leqslant c[\min (\rho(z, \partial \Omega), \rho(z, V))]^{-1}, \quad z \in \Omega \backslash V
$$

then $f$ has a holomorphic extension $\mathcal{f}$ to $\Omega$ and $\mathcal{f}$ satisfies

$$
|\nabla \hat{f}(z)| \leqslant c^{\prime}[\rho(z, \partial \Omega)]^{-1} .
$$

Hence, if $\Omega$ is strictly pseudo convex $\widetilde{f}$ is a Bloch function.
Proof of Theorem 1'. We use the Weierstrass Preparation Theorem to reduce the extension problem to the one variable argument given in the
last section (also, see [2, p. 25]). Henceforth, assume $\tilde{f}$ extends $f$ holomorphically to all of $\Omega$.

Lemma 2. If $w_{1}, w_{2}$ are in $P_{\alpha}$ there are constants $c_{1}$ and $c_{2}$ such that

$$
c_{1} \leqslant \frac{\rho\left(w_{1}, \partial \Omega\right)}{\rho\left(w_{2}, \partial \Omega\right)} \leqslant c_{2}
$$

where the $c_{i}$ are independent of $\alpha$.
Proof. The assumption on $V$ states that each $r_{j}(\alpha)$ is equivalent to $\rho\left(P_{\alpha}, \partial \Omega\right)$ (condition (b) of $\left.A\right)$. Hence

$$
\frac{\rho\left(w_{1}, \partial \Omega\right)}{\rho\left(w_{2}, \partial \Omega\right)} \leqslant \frac{\rho\left(w_{1}, w_{2}\right)+\rho\left(w_{2}, \partial \Omega\right)}{\rho\left(w_{2}, \partial \Omega\right)} \leqslant 1+\mathrm{c} \frac{\rho\left(P_{\alpha}, \partial \Omega\right.}{\rho\left(w_{2}, \partial \Omega\right)} \leqslant 1+c
$$

Similarly, it follows that

$$
\frac{\rho\left(w_{1}, \partial \Omega\right)}{\rho\left(w_{2}, \partial \Omega\right)} \geqslant \frac{1}{1+c} .
$$

Lemma 3. For $z \in \Omega^{\prime}=\Omega \backslash \cup P_{\alpha}$ there is a constant $k_{1}$ such that

$$
\rho(z, V) \geqslant k_{1} \rho(z, \partial \Omega)
$$

Proof. Suppose the conclusion is false and that there exists sequences $\left\{z_{j}\right\}$ in $\Omega^{\prime}$ and $\left\{W_{j}\right\}$ in $V$ such that

$$
\begin{equation*}
\lim _{j \rightarrow \infty} \frac{\rho\left(z_{j}, w_{j}\right)}{\rho\left(z_{j}, \partial \Omega\right)}=0 \tag{7}
\end{equation*}
$$

Let $P_{j}$ be a polycylinder associated to $w_{j}$ according to condition (d) of the A-covering property. We note that

$$
\begin{equation*}
\frac{\rho\left(z_{j}, \partial \Omega\right)}{\rho\left(z_{j}, w_{j}\right)+\rho\left(z_{j}, \partial \Omega\right)} \leqslant \frac{\rho\left(z_{j}, \partial \Omega\right)}{\rho\left(w_{j}, \partial \Omega\right)} \leqslant \frac{\rho\left(z_{j}, \partial \Omega\right)}{\rho\left(z_{j}, \partial \Omega\right)-\rho\left(z_{j}, w_{j}\right)} \tag{8}
\end{equation*}
$$

Inequality (8) and equality (7) imply that

$$
\begin{equation*}
\lim _{j \rightarrow \infty} \frac{\rho\left(z_{j}, \partial \Omega\right)}{\rho\left(w_{j}, \partial \Omega\right)}=1 \tag{9}
\end{equation*}
$$

Since $z_{j}$ is not in $P_{j}$ it follows from Lemma 2 and (9) that

$$
\lim _{j \rightarrow \infty} \frac{\rho\left(w_{j}, \partial P_{j}\right)}{\rho\left(P_{j}, \partial \Omega\right)}=0
$$

This contradicts condition (d) of the A-covering property.

From Lemma 3 it follows that $|\nabla f(z)| \leqslant k^{\prime}(\rho(z, \partial \Omega))^{-1}$ all $z$ in $\Omega^{\prime}$. It remains to estimate $|\nabla \tilde{f}|$ for $z$ in $P_{\alpha}$ (independent of $\alpha$ ). For any polydisc $P_{\alpha}$ with $z_{0}$ in the distinguished boundary $\left(\partial_{0} P_{\alpha}\right)$ we have

$$
\rho\left(z_{0}, V\right) \geqslant d_{3} \rho\left(P_{\alpha}, \partial \Omega\right)
$$

Also, from Lemma 2,

$$
\rho\left(z_{0}, \partial \Omega\right) \geqslant c_{1} \rho\left(P_{\alpha}, \partial \Omega\right)
$$

The assumption on $\nabla f$ implies

$$
|\nabla f(z)| \leqslant c^{\prime}\left[\rho\left(P_{\alpha}, \partial \Omega\right)\right]^{-1} z \in \partial_{0} P_{\alpha}
$$

By the maximum principle applied to $\partial f / \partial z_{j}(j=1,2, \ldots, n)$,

$$
|\nabla \widetilde{f}(z)| \leqslant c^{\prime \prime}\left[\rho\left(P_{\alpha}, \partial \Omega\right)\right]^{-1}, \quad z \in P_{\alpha}
$$

Using Lemma 3 again, $|\nabla \tilde{f}(z)| \leqslant c^{\prime \prime \prime}(\rho(z, \partial \Omega))^{-1}$. This completes the proof.
Recall the example of Timoney presented in Section 3. We can exploit it for an n -dimensional example. Let

$$
z=\left(z_{1}, z_{2}, \ldots, z_{n}\right) \in \mathbf{B}_{n} \quad \text { and } \quad f(z)=\left(1-z_{1}\right)^{-1}
$$

with

$$
S=\left\{z \in \mathbf{B}_{n}: z_{1} \in V\right\}
$$

$V$ is the sequence $\left\{\alpha_{j, n}\right\}$ defined in that example. As in $\mathbf{C}^{1}$ the function $f$ is not in the Bloch space of $\mathbf{B}_{n}$ yet

$$
\|\nabla f(z)\| \leqslant c\left\{\min \left[\rho(z, S), \rho\left(z, \partial \mathbf{B}_{n}\right)\right]\right\}^{-1}
$$

It suffices to prove the stronger inequality

$$
\left.\frac{1}{1-\left|z_{1}\right|^{2}} \leqslant c\left[\min (\rho(z, S)), \rho\left(z, \partial \mathbf{B}_{n}\right)\right)\right]^{-1}
$$

For

$$
1-\frac{1}{n} \leqslant|z| \leqslant 1-\frac{1}{n+1}
$$

we have

$$
\rho(z, S) \leqslant \rho\left(z, S \cap\left\{\left|z_{1}\right|=1-\frac{1}{n}\right\}\right) \leqslant c / n^{2}
$$

Hence,

$$
\min \left[\rho(z, S), \rho\left(z, \partial \mathbf{B}_{n}\right)\right] \leqslant \rho(z, V) \leqslant \frac{c}{n^{2}}
$$

and

$$
\min \left[\rho(z, S), \rho\left(z, \partial \mathbf{B}_{n}\right)\right]^{-1} \geqslant \frac{n^{2}}{c} \geqslant c^{\prime}\left(\frac{1}{1-\left|z_{1}\right|^{2}}\right)
$$

## 5. The A-covering property

In this section we shall consider the A-covering property in more detail. We shall show that if $V=V^{\prime} \cap \Omega$ where $V^{\prime}$ is a submanifold of a neighborhood of $\bar{\Omega}$ then $V$ has the A-covering property. An open question is whether a subvariety of the form $V=V^{\prime} \cap \Omega$, where $V^{\prime}$ is a subvariety of a neighborhood of $\bar{\Omega}$, has the A-covering property. We begin with the following pointwise result.

Proposition 1. Let $V=\{z \in U: h(z)=0\}$ be the zero set of $a$ holomorphic function $h$ on an open set $U \subset \mathbf{C}^{n}$. Let $z_{0}$ be in $V$. There exists $\varepsilon_{0}>0$ and there exist constants $\mathscr{C}_{1}, \mathscr{C}_{2}, \mathscr{C}_{3}$ such that the following is true: for all $\varepsilon \leqslant \varepsilon_{0}$ there is a polycylinder $P_{\varepsilon}\left(z_{0}\right)$ centered at $z_{0}$ such that
(1) $C_{1} \varepsilon \leqslant r_{j} \leqslant C_{2} \varepsilon, j=1,2, \ldots, n$,
(where $r_{j}$ is the $j$-th polyradius of $P_{\varepsilon}\left(z_{0}\right)$ ) and
(2) $\rho\left(V, \partial_{0} P_{\varepsilon}\left(z_{0}\right)\right) \geqslant C_{3} \varepsilon$.

Proof. Take the origin of coordinates at $z_{0}$ and choose the $z_{n}$ coordinate so that $h\left(0, \ldots, 0, z_{n}\right)$ vanishes to minimal order at $z_{0}$. Write $h=\phi q$ where $\phi$ is a unit and $q$ is a Weierstrass polynomial in $z_{n}$ :

$$
q(z)=z \frac{\alpha}{n}+\sum_{j=1}^{\alpha} q_{\alpha-j}\left(z^{\prime}\right) z_{n}^{\alpha-} j
$$

Here, $z^{\prime}=\left(z_{1}, \ldots, z_{n-1}\right)$ and this representation is valid for $\left|z^{\prime}\right|<\varepsilon_{1}$, $\left|z_{n}\right|<\varepsilon_{2}$. Because of the choice of the $z_{n}$ coordinate, the coefficient $q_{\alpha-j}\left(z^{\prime}\right)$ of $z_{n}^{\alpha-j}$ vanishes to order at least $j$ at 0 for $j=1,2, \ldots, \alpha$. Thus there exists $K>0$ such that

$$
\begin{equation*}
\left|g_{\alpha-j}\left(z^{\prime}\right)\right| \leqslant K\left|z^{\prime}\right|^{j} \quad \text { for } j=1,2, \ldots, \alpha, \text { and }\left|z^{\prime}\right|<\varepsilon_{1} \tag{11}
\end{equation*}
$$

Now for $z_{n} \neq 0$ we may write

$$
q(z)=z_{n}^{\alpha}\left(1+\sum_{j=1}^{\alpha} \frac{q_{\alpha-j}\left(z^{\prime}\right)}{z_{n}^{\alpha-j}}\right)
$$

Choose $c$ such that $K \Sigma_{j=1}^{\alpha} c^{-j}<1$; we may assume that $c \geqslant 1$. Choose $\varepsilon_{0}$ small enough that

$$
\varepsilon_{0}<\min \left(\frac{\varepsilon_{1}}{2}, \frac{\varepsilon_{2}}{2 c}\right)
$$

and also so that $\phi(z) \neq 0$ when $z$ lies in the polycyiinder

$$
P_{\varepsilon}\left(z_{0}\right)=\left\{z \in \mathbf{C}^{n}:\left|z_{j}\right|<2 \varepsilon_{0}, \quad j=1, \ldots, n-1, \text { and }\left|z_{n}\right|<2 c \varepsilon .\right\}
$$

Now if $\varepsilon<2 \varepsilon_{0}$ and $z^{\prime}$ is fixed so that $\left|z^{\prime}\right|<\varepsilon$ we claim that the $\alpha$ roots $\xi_{1}\left(z^{\prime}\right), \ldots, \xi_{\alpha}\left(z^{\prime}\right)$ of $q\left(z^{\prime}, z_{n}\right)=0$ satisfy $\left|\xi_{j}\left(z^{\prime}\right)\right|<c \cdot \varepsilon, j=1, \ldots, \alpha$. This is a consequence of Rouche's Theorem: using the estimates (11) and the choice of $c$ we see that for fixed $z^{\prime}$ the polynomials $q\left(z^{\prime}, z_{n}\right)$ and $z_{n}^{\alpha}$ have the same number of roots inside the circle $\left|z_{n}\right|=c \cdot \varepsilon$. Now if we restrict $\varepsilon$ so that $\varepsilon<\varepsilon_{0}$ we may be sure that for $\left|z^{\prime}\right|<\varepsilon$, the equation $h\left(z^{\prime}, z_{n}\right)=$ 0 has no roots $\xi$ which satisfy $c \varepsilon<|\xi|<2 c \varepsilon$.

It suffices therefore to set $c_{1}=1, c_{2}=3 / 2 c, c_{3}=1 / 2 c$ and

$$
P_{\varepsilon}\left(z_{0}\right)=\left\{z| | z_{j} \mid<\varepsilon, j=1,2, \ldots, n-1 \text { and }\left|z_{n}\right|<c_{2} \varepsilon\right\} .
$$

Properties 1 and 2 then hold for $P_{\varepsilon}\left(z_{0}\right), 0<\varepsilon<\varepsilon_{0}$.
In order to use Proposition 1 to show that a given subvariety of $\Omega$ satisfies the A-covering property, we need to know that the constants $\varepsilon_{0}, c_{1}, c_{2}$ and $c_{3}$ depend continuously on the point $z_{0}$. We can establish this only in special cases.

Lemma 4. Let $M$ be a complex submanifold of an open set $U$ of $\mathbf{C}^{n}$. Then in Proposition 1 we may take $c_{1}=c_{2}=1$ (i.e., each radius of $\mathscr{P}_{8}\left(z_{0}\right)$ is precisely $\varepsilon$ ), and the constants $\varepsilon_{0}$ and $c_{3}$ may be taken to the locally independent of $z_{0}$.

Proof. Suppose $\operatorname{dim}_{\mathbf{C}}(M)=n-k$. Let $z_{0} \in M$. Choose orthonormal coordinates at $z_{0}$ (using the standard inner product on $\mathbf{C}^{n}$ ) so that the $z_{n-k+1}$, $\ldots, z_{n}$ axes are tangential to $M$ at $z_{0}$. By considering local defining functions $h_{1}, h_{2} \ldots, h_{k}$ for $M$ near $z_{0}$ such that $h_{j}(z)=z_{j}+\phi_{j}(z)$ where $\phi_{j}(z)$ vanishes to order greater than one at $z_{0}, j=1,2, \ldots, k$, we see that there exists $\varepsilon_{0}>0$ such that for $0<\varepsilon \leqslant \varepsilon_{0}$ the polycylinder

$$
P_{\varepsilon}\left(z_{0}\right)=\left\{z:\left|z_{j}\right|<\varepsilon, j=1, \ldots, n\right\}
$$

satisfies $\rho\left(M, \partial_{0} P_{\varepsilon}\left(z_{0}\right)\right) \sim \varepsilon$. It is clear that this family of polycylinders may be translated to nearby points without destroying property (2) of Theorem 3.

Using this lemma we can show:
Proposition 2. Suppose $\Omega \subset \subset \mathbf{C}^{n}$ has smooth boundary. Suppose $V^{\prime}$ is an analytic subvariety of a neighborhood $\Omega^{\prime}$ of $\Omega$ such that $V^{\prime}$ is smooth in a neighborhood $U$ of $\partial \Omega$. Let $V=V^{\prime} \cap \Omega$. Then $V$ has the A-covering property.

Remark. $\quad V$ can have at worst point singularities in $\Omega$.
Proof. Let $M=V^{\prime} \cap U$. Lemma 4 applies to $M$. Let $W$ be a neighborhood of $\partial \Omega$ such that $\bar{W} \subseteq U$. Referring to the construction in Lemma 4, we set
$\eta=\inf \left\{\varepsilon_{0}>0, z_{0} \in M \cap W\right\}$. For each $z_{0} \in M \cap W$, the polycylinder $P_{\eta}\left(z_{0}\right)$ is defined by the construction in Lemma 4. All radii of this polycylinder are equal to $\eta$, but the direction of the axes depends on $z_{0}$. Let

$$
V_{1}=\left\{z \in V \cap W: P_{\eta}(z) \cap \partial \Omega \neq \emptyset\right\}, \quad V_{2}=\{z \in V \cap W: \rho(z, \partial \Omega) \geqslant \eta\}
$$

The set $V_{2}$ is compact. Hence it has a finite covering by polycylinders $P_{1}$, $P_{2}, \ldots, P_{m}$ such that $\bar{P}_{j} \subset \Omega$ and $\partial_{0} P_{j} \cap V=\phi$. (We make use of the construction in Proposition 1 at each point of $V_{2}$, and then use compactness to extract a finite subcovering.) Also it is not hard to see that part (d) of the $A$-covering property is satisfied for $z \in V_{2}$. At this point we just have to cover $V \backslash V_{2}$ in the desired way. It is not hard to see that if $z \in V \backslash V_{2}$ then $z \in V_{1}$. The polycylinder $P_{\varepsilon}(z)$ obtained from Lemma 4 with

$$
\varepsilon=\frac{1}{2 \sqrt{n}} \rho(z, \partial \Omega)
$$

has closure contained in $\Omega$. Clearly $\rho(z, \partial \Omega) \simeq \varepsilon$ and $\rho\left(\partial_{0} P_{\varepsilon}(z), V\right) \simeq \varepsilon$. Hence the covering of $V-V_{2}$ consists of one polycylinder centered at each point $z \in V-V_{2}$ with radii

$$
\frac{1}{2 \sqrt{n}} \rho(z, \partial \Omega)
$$

and suitably chosen axes. Part (d) of the $A$-covering property is satisfied since each point $z \in V-V_{2}$ is actually the center of one of the polycylinders. This completes the proof of Proposition 2.

It would be of interest to see whether Proposition 2 holds under the assumption that $V=V^{\prime} \cap \Omega$ where $V^{\prime}$ is an arbitrary subvariety of a neighborhood of $\bar{\Omega}$. This amounts to determining whether the constants in Proposition 1 are locally independent of $z_{0}$. We shall indicate how this may be proved if $U$ is a neighborhood of $0 \in \mathbf{C}^{2}$ and $V=\left\{z \in U: z_{1}^{2}-z_{2}^{3}=\right.$ $0\}$. This illustrates some of the considerations which will be relevant to the case of more general singularities. (It follows that Proposition 2 holds when $\Omega$ is any smoothly bounded domain in $\mathbf{C}^{2}$ such that $0 \in \partial \Omega$ and $V=$ $\left\{z \in \Omega \mid z_{1}^{2}-z_{2}^{3}=0\right\}$.)

For each value of $z_{2} \neq 0$ there are two values of $z_{1}$ such that $\left(z_{1}, z_{2}\right) \in$ $V$. In modulus they are given by $\left|z_{1}\right|=\left|z_{2}\right|^{3 / 2}$. For each $\varepsilon<\varepsilon_{0}$ where $\varepsilon_{0}$ is some number we want to construct a polycylinder $P_{\varepsilon}\left(z_{1}, z_{2}\right)$ centered at $\left(z_{1}, z_{2}\right)$ with sides equivalent to $(\simeq) \varepsilon$ and $\rho\left(V, \partial_{0} P_{\varepsilon}\left(z_{1}, z_{2}\right) \simeq \varepsilon\right.$. Now the distance from $\left(z_{1}, z_{2}\right)$ to the other sheet of the variety is equivalent to $\left|z_{1}\right|$. It is much less than $\left|z_{2}\right|$ if $\left(z_{1}, z_{2}\right)$ is near 0 . For $\varepsilon>k\left|z_{1}\right|$ where $k$ is some constant we choose the polycylinder $P_{8}\left(z_{1}, z_{2}\right)$ to have fixed proportions, axes parallel to the coordinate axes, and such that both sheets of the variety are contained in the polycylinder. For $\varepsilon<k\left|z_{1}\right|$ we change the proportions of the polycylinders, choosing a smaller multiple of $\varepsilon$ for the $z_{1}$ radius, so
that the polycylinder just includes one sheet of the variety. (Of course when $z=0$ each polycylinder $P_{\varepsilon}(0)$ contains both sheets of the variety).

What is involved here is that the local representation of the variety at a given point must be used to construct the family of polycylinders at nearby points.

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The University of North Carolina at Chapel Hill Chapel Hill, North Carolina


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