# YET ANOTHER SINGLE LAW FOR GROUPS 

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To the memory of my old friend Bill Boone

## 1. Introduction

Groups can be axiomatised in many ways. Of special interest are definitions of groups in terms of operations and laws, because such a definition has as an immediate consequence the fact that the class of groups forms a variety.

One binary operation suffices, if it is right division,

$$
x y \rho=x \cdot y^{-1}
$$

(or left division, or the transpose of right division $x y \rho^{T}=y^{-1} \cdot x$, or the transpose of left division); and in terms of right division (or left division or their transposes), a single, albeit complicated, law suffices: see [1]. If multiplication

$$
x y \mu=x \cdot y
$$

(or its transpose) is chosen as the binary operation, it does not suffice for a definition of groups by laws; nor even if the nullary operation

$$
\varepsilon=e
$$

is added. (Greek letters stand for operations and are written as right-hand operators; the nullary $\varepsilon$, operating on the empty sequence on the left-hand side, produces the constant element $e$, which is to become the neutral element of multiplication, that is the unit element of the group.) If instead the unary inversion

$$
x \iota=x^{-1}
$$

is added to the binary multiplication, then groups can again be defined by laws, and indeed by a single law: see [2]. In terms of multiplication, inversion, and the nullary unit element, groups can, of course, be defined by laws, but not by a single law: see [2].

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Recently at the University of Manitoba Dr Padmanabhan asked me whether a single law suffices to define groups in terms of the binary "multiplication of inverses",

$$
x y \nu=x^{-1} \cdot y^{-1}
$$

and the nullary unit element-that it can be done by laws in these two operations is easy to see. I came away with the impression that Dr Padmanabhan had grounds for thinking that it could not be done; and I soon came to the same conclusion-until I demolished this conclusion by constructing a single law that will do the trick.

As a trick, it is of no real interest, except for a small methodological point in universal algebra: the presence of a nullary operation ensures that all carriers (i.e., sets of elements) of groups are non-empty. We like to forget about the empty set as the carrier of an algebra, but then need to modify the proposition "The intersection of (carriers of) subsemigroups of a semigroup is (the carrier of) a subsemigroup" (usually formulated without my pedanticisms in the parentheses) by the insertion of "if non-empty" before "is" to render it valid. A small price to pay for the convenience of forgetting about the empty set? Perhaps; but the price is not all that small if, for example, we want to turn the power set of the carrier of a semigroup into the carrier of another lattice-ordered semigroup in the obvious way.

This is not a good reason for wanting to axiomatise groups in terms of $\nu$ and $\varepsilon$ by a single law. However, the gauntlet having been thrown down, somebody had to pick it up.

The notational conventions are as in the earlier papers [1], [2]. Lower case Greek letters stand for algebraic operations; $x, y, z, t$ are variables ranging over the carrier of the algebra under consideration; $e, f$ are constant elements of that carrier; capital letters stand for mappings of the carrier into itself, and $I$ in particular is the identity mapping of the carrier.

Some simple facts that will be used without explicit reference are that if the mapping $P$ of the carrier into itself has both a left inverse and a right inverse, that is if there are mappings $Q, Q^{\prime}$ with

$$
Q P=P Q^{\prime}=I
$$

then $Q=Q^{\prime}$ is the unique inverse of $P$, written $Q=P^{-1}$, and $P$ is a permutation of the carrier. Moreover if

$$
A B C D=P
$$

where $A, D, P$ are permutations, then $B$ has a right inverse and $C$ has a left inverse. I write mappings as right-hand operators, and read products from left to right; thus a mapping with a right inverse is one-to-one, and a mapping with a left inverse is onto the whole carrier.

## 2. The law

Theorem 1. The law

$$
\begin{equation*}
z \varepsilon y \nu \varepsilon t \nu t \nu x \nu \nu \varepsilon z \nu \nu y \nu \nu \nu=x \tag{1}
\end{equation*}
$$

defines the variety of groups with the interpretation

$$
\begin{align*}
x y \nu & =x^{-1} \cdot y^{-1}  \tag{2}\\
\varepsilon & =e, \text { the unit element } . \tag{3}
\end{align*}
$$

The proof follows the pattern of those in [1] and [2]: first I show that with respect to $\nu$ the algebra is a quasigroup; next the properties of the element $e$ are investigated; then the associative law for the group multiplication, expressed in terms of $\nu$ and $\varepsilon$, is proved; and finally the interpretations (2), (3) of $\nu$ and $\varepsilon$ are verified. The details follow.

I introduce mappings $S_{y}$ and $T_{x}$ of the carrier of the algebra into itself by

$$
x y \nu=x S_{y}=y T_{x}
$$

they are right and left " $\nu$-multiplication". With this notation the law (1) becomes

$$
\begin{equation*}
T_{e t \nu t \nu} T_{e y \nu} S_{e z \nu y \nu} T_{z}=I \tag{4}
\end{equation*}
$$

This shows that all left $\nu$-multiplications $T_{z}$ have left inverses, and those of the form $T_{\text {etvt }}$ also have right inverses, thus are permutations; then also all $T_{\text {eyv }}$ have right inverses, hence are permutations. Now $e y \nu=y T_{e}$ ranges with $y$ over the whole carrier, as $T_{e}$ has a left inverse: this implies that all left $\nu$-multiplications are permutations. Then also all $S_{e z \nu y \nu}$ are permutations; and as $e z \nu y \nu=$ $y T_{e z \nu}$ ranges, even for fixed $z$, over the whole carrier, all right $\nu$-multiplications $S_{z}$ are permutations. It follows that with respect to $\nu$ the algebra is a quasigroup.

Next it is seen that the mapping $T_{\text {etvtv }}\left(=T_{z}^{-1} S_{e z v y \nu}^{-1} T_{\text {eyv }}^{-1}\right)$ does not depend on $t$, hence is constant; and thus also the element etvtv is constant. To compute this constant, I introduce the element

$$
f=e T_{e}^{-1}
$$

so that ef $\nu=e$. Then the constant element is

$$
\begin{equation*}
e t \nu t \nu=e f \nu f \nu=e f \nu=e \tag{5}
\end{equation*}
$$

The law (4) thus implies the simpler law

$$
\begin{equation*}
T_{e} T_{e y v} S_{e z v y v} T_{z}=I \tag{6}
\end{equation*}
$$

Next notice that $T_{e y \nu} S_{e z \nu y \nu}\left(=T_{e}^{-1} T_{z}^{-1}\right)$ is independent of $y$. With $z=f$ this gives that $T_{e y \nu} S_{e y \nu}$ is a constant permutation, and putting eyv=t and noting that $t=y T_{e}^{-1}$ ranges with $y$ over the whole carrier, one has the result that $T_{t} S_{t}$ is a constant permutation, say $T_{t} S_{t}=K$. With $z=f$ then (6) gives

$$
T_{e} K T_{f}=I
$$

Put $t=e$ in (5) to get

$$
\begin{equation*}
e e \nu e \nu=e T_{e} S_{e}=e K=e \tag{7}
\end{equation*}
$$

and, still using (5),

$$
e t \nu t \nu=e=e K=e T_{t} S_{t}=t e \nu t \nu
$$

Hence et $\nu=t e \nu$, or $t T_{e}=t S_{e}$ : thus

$$
\begin{equation*}
T_{e}=S_{e} \tag{8}
\end{equation*}
$$

Now from (7), $e=e K^{-1}=e T_{f} T_{e}$, that is

$$
e e \nu e \nu=e=e f e \nu \nu=f e \nu e \nu
$$

Hence $f e \nu=e e \nu$ and $f=e$; and, moreover, eev $=e$. Now (8) shows that $K=T_{e} S_{e}=T_{e}^{2}$, and $T_{e}^{4}=I$. This is not quite good enough: what is needed is $K=T_{e}^{2}=I$. To show this, put $y=z$ in (6), notice that $e z \nu z \nu=e$ and use (8) again:

$$
\begin{equation*}
T_{e} T_{e y \nu} T_{e} T_{y}=I \tag{9}
\end{equation*}
$$

Multiply on the right by $S_{y} T_{e}$ and use $T_{e} T_{y} S_{y} T_{e}=T_{e} K T_{e}=I$, to get

$$
\begin{equation*}
T_{e} T_{e y \nu}=S_{y} T_{e} \tag{10}
\end{equation*}
$$

Replace $y$ in (9) by eyv; then

$$
T_{e e y \nu \nu}=T_{e}^{-1} T_{e y \nu}^{-1} T_{e}^{-1}=T_{y}
$$

Hence eeyv $\nu=y$, that is $y T_{e}^{2}=y$, and

$$
\begin{equation*}
T_{e}^{2}=I \tag{11}
\end{equation*}
$$

as required. This implies $K=I$, and

$$
\begin{equation*}
S_{t}=T_{t}^{-1} \tag{12}
\end{equation*}
$$

for all $t$.

Now define a new operation $\mu$ by

$$
x y \mu=y x \nu \varepsilon \nu .
$$

With the notation

$$
x y \mu=x R_{y}=y L_{x},
$$

it is seen that

$$
R_{y}=T_{y} S_{e}, \quad L_{x}=S_{x} S_{e}
$$

so $R_{y}, L_{x}$ are permutations, and the algebra is a quasigroup with respect to $\mu$. Next,

$$
\begin{equation*}
x y z \mu \mu=z y \nu \varepsilon \nu x \nu \varepsilon \nu=x T_{z y \nu e \nu} S_{e} \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
x y \mu z \mu=z y x \nu \varepsilon \nu \nu \varepsilon \nu=x T_{y} S_{e} T_{z} S_{e} ; \tag{14}
\end{equation*}
$$

now

$$
z y \nu \varepsilon \nu=z S_{y} S_{e}=z S_{y} T_{e}=z T_{e} T_{e y \nu}=e y \nu e z \nu \nu
$$

by (10), and

$$
\begin{aligned}
T_{e y \nu e z \nu v} & =S_{e y v e z \nu \nu}^{-1}=T_{y} T_{e} T_{e e z \nu \nu} \\
& =T_{y} T_{e} T_{z}=T_{y} S_{e} T_{z},
\end{aligned}
$$

using (12), (6), (11), (8). It follows that the right-hand sides of (13) and (14) are equal, verifying the associative law for $\mu$. Next,

$$
x e \mu=e x \nu e \nu=x T_{e} S_{e}=x T_{e}^{2}=x
$$

and

$$
\text { ex } \mu=x e \nu e \nu=x S_{e}^{2}=x T_{e}^{2}=x,
$$

showing that $e$ is the (right and left) neutral element with respect to $\mu$. Also

$$
\operatorname{xex\nu } \mu=\operatorname{exv} \nu \nu e \nu=e e \nu=e,
$$

by (5), so exv is the (right, hence also left) inverse of $x$ with respect to $\mu$ and $e$. This shows the group property of the algebra with respect to $\mu$ as multiplication, with $e$ as unit element and exv as inverse of $x$. Finally, to verify the interpretations (2) and (3) of $\nu$ and $\varepsilon$ : that of $\varepsilon$ has just been verified, and it remains to show that

$$
\text { eyvexvvev }=x y \nu .
$$

Here the left-hand side is $x T_{e} T_{e y \nu} S_{e}=x S_{y}$, by (10) and (12), giving the desired interpretation, and so completing the proof of the theorem.

## 3. Final remarks

The law (1) has a word of length 19 as its left-hand side-counting, as one has to in the presence of nullary or unary operations, both Latin and Greek letters. Is 19 the least possible length? I do not know the answer. The number of variables involved in (1) is 4 ; can this be reduced to 3 ? I do not know the answer. Can one, as in the single group laws of [1] and [2], build a further law into (1), so as to define a subvariety of the variety of all groups, for example the variety of all abelian groups, by a single law in $\nu$ and $\varepsilon$ ? I have not tried, but guess that this should be quite feasible. Can one define the variety of groups by a single law in $\nu$ and $\iota$, where $\iota$ is inversion, $x \iota=x^{-1}$ ? This question can be answered in the affirmative:

## Theorem 2. The law

$$
t z y \nu z x \iota y \iota \nu \nu \iota \nu \nu t \nu \iota=x
$$

defines the variety of groups with the interpretation

$$
x y \nu=x^{-1} \cdot y^{-1}, \quad x \iota=x^{-1}
$$

The proof follows lines similar to that of Theorem 1, and is omitted. The same questions can be asked about the law in Theorem 2 as about the law in Theorem 1; I know no more answers. Finally one may wish to define groups by a single law in right division, $x y \rho=x \cdot y^{-1}$, and either $\varepsilon$ or $\iota$; this should be quite feasible, but I have not tried.

## References

1. Graham Higman and B.H. Neumann, Groups as groupoids with one law. Publ. Math. Debrecen, vol. 2 (1952), pp. 215-221.
2. B.H. Neumann, Another single law for groups, Bull. Austral. Math. Soc., vol. 23 (1981), pp. 81-102.

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