The existence of Leray-Hopf weak solutions with linear strain

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Abstract. This paper deals with the global existence of weak solutions to the initial value problem for the Navier-Stokes equations in \mathbb{R}^n $(n \in \mathbb{Z}, n \geq 2)$. Concerning initial data of the form Ax + v(0), where $A \in M_n(\mathbb{R})$ and $v(0) \in L^2_{\sigma}(\mathbb{R}^n)$, the weak solutions are properly-defined with the aid of the alternativity of the trilinear from $(Ax \cdot \nabla)v \cdot \varphi$. Furthermore, we construct the Leray-Hopf weak solution which satisfies not only the Navier-Stokes equations but also the energy inequality via the Galerkin approximation. From the viewpoint of quadratic forms, the Gronwall-Bellman inequality admits the uniform boundedness of the approximate solution.

Key words: Navier-Stokes equations, Leray-Hopf weak solutions, Linear strain.

1. Introduction

Let $n \in \mathbb{Z}$, $n \geq 2$ and T > 0. Motion of incompressible viscous fluids with linear strain in \mathbb{R}^n is described by the initial value problem for the Navier-Stokes equations as follows:

$$\begin{cases} \operatorname{div} u = 0 & \text{in } \mathbb{R}^n \times (0, T), \\ \rho \{\partial_t + (u \cdot \nabla)\} u + \nabla p - \mu \Delta u = 0 & \text{in } \mathbb{R}^n \times (0, T), \\ u|_{t=0} = Ax + v(0) & \text{in } \mathbb{R}^n, \end{cases}$$
(1.1)

where $u = (u_1, \ldots, u_n)^T$ is the fluid velocity, p is the pressure, ρ is the density, μ is the coefficient of viscosity, $A \in M_n(\mathbb{R})$, i.e., A is a real square matrix of order n and \cdot^T is the transposition. These equations correspond to the laws of conservation of mass and momentum respectively. Moreover, it is required that ρ and μ are positive constants. See, for example, Lamb [5] and Serrin [10] on conservation laws of fluid motion and derivation of the above equations.

This paper is concerned with the fluid velocity perturbation v := u - Ax from linear strain Ax. Note that Ax is characterized as an exact solution to

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(1.1). Indeed,

$$u := Ax, \quad p := -\frac{\rho}{2}Ax \cdot A^Tx$$

is a stationary solution to (1.1) provided that $\operatorname{tr} A = 0$ and $A^2 \in S_n(\mathbb{R})$, i.e., A^2 is a real symmetric matrix of order n. See, for example, Majda and Bertozzi [7] and Okamoto [9] on exact solutions to the Navier-Stokes equations and their fluid mechanical properties. Substituting

$$v := u - Ax, \quad q := p + \frac{\rho}{2} Ax \cdot A^T x$$

into (1.1), we consider a solution (v,q) to the following initial value problem:

$$\begin{cases} \operatorname{div} v = 0 & \text{in } \mathbb{R}^n \times (0, T), \\ \rho \{ \partial_t v + (v \cdot \nabla)v + (Ax \cdot \nabla)v + Av \} + \nabla q - \mu \Delta v = 0 & \text{in } \mathbb{R}^n \times (0, T), \\ v|_{t=0} = v(0) & \text{in } \mathbb{R}^n. \end{cases}$$

$$(1.2)$$

In the case where A is a zero matrix, there are many results on the global existence and kinetic energy of weak solutions to (1.1) or equivalently, (1.2). For any $v(0) \in L^2_{\sigma}(\mathbb{R}^3)$ and T > 0, Leray [6] constructed a weak solution u to (1.1) such that the energy inequality

$$\frac{1}{2}||u(t)||^2 + \frac{\mu}{\rho} \int_0^t ||\nabla u(\tau)||^2 d\tau \le \frac{1}{2}||v(0)||^2$$
(1.3)

holds for any 0 < t < T via the heat kernel. Moreover, it follows from Hopf [4] that the Galerkin approximation works in domains rather than \mathbb{R}^3 . On the other hand, Masuda [8] proved the global existence of weak solutions to (1.1) which seem to have a somewhat stronger property than Leray-Hopf weak solutions to (1.1). If A is a non-zero matrix, Campiti, Galdi and Hieber [1] recently obtained the global existence and uniqueness of strong solutions to (1.2) in the case of n = 2. However, it is unknown except for n = 2 whether (1.2) admits the global existence of weak solutions or not. Concerning the local existence and uniqueness of mild solutions to (1.2), Hieber and Sawada [2] defined the operator A_p in $L_{\sigma}^p(\mathbb{R}^n)$ (1 < $p < \infty$) as

$$A_p = -\Delta + (Ax \cdot \nabla) - A$$

with its domain $D(A_p) := \{u \in (W^{2,p}(\mathbb{R}^n))^n \cap L^p_{\sigma}(\mathbb{R}^n); (Ax \cdot \nabla)u \in (L^p(\mathbb{R}^n))^n\}$, and proved that $-A_p$ generates a C_0 (but non-analytic)-semigroup $\{e^{-tA_p}\}_{t\geq 0}$ on $L^p_{\sigma}(\mathbb{R}^n)$. Applying L^p - L^q smoothing estimates for $\{e^{-tA_p}\}_{t\geq 0}$ to the successive approximation, the local existence and uniqueness result was given as follows: Let $n \leq p < \infty$, $p \leq q \leq \infty$ and $v(0) \in L^p_{\sigma}(\mathbb{R}^n)$. Then there exists $T_* > 0$ such that (1.2) uniquely has a mild solution v satisfying

$$t^{n/2(1/p-1/q)}v \in C([0,T_*); L^q_\sigma(\mathbb{R}^n)).$$

The aim of this paper is to establish the global existence of Leray-Hopf weak solutions to (1.2). More precisely, weak solutions to (1.2) are properly-defined with the aid of

$$\int_{\mathbb{R}^n} (Ax \cdot \nabla) v \cdot \varphi dx = -\int_{\mathbb{R}^n} v \cdot (Ax \cdot \nabla) \varphi dx$$

for any $v \in H^1_{\sigma}(\mathbb{R}^n)$ and $\varphi \in C^1_{0,\sigma}(\mathbb{R}^n)$. Furthermore, we construct a weak solution v to (1.2) such that the energy inequality

$$\frac{1}{2}\|v(t)\|^2 + \int_0^t (Av(\tau), v(\tau))d\tau + \frac{\mu}{\rho} \int_0^t \|\nabla v(\tau)\|^2 d\tau \le \frac{1}{2}\|v(0)\|^2$$
 (1.4)

holds for any 0 < t < T via the Galerkin approximation. The crucial point is that the quadratic inequality

$$Ax \cdot x \ge a|x|^2 \tag{1.5}$$

holds for any $x \in \mathbb{R}^n$, where $a := \min\{\lambda; \lambda \in \sigma(S)\}$ and $S := (1/2)(A + A^T)$. Note that $\operatorname{tr} A = 0$ implies $a \leq 0$. Then it follows from (1.4), (1.5) and the Gronwall-Bellman inequality that a priori estimate

$$\frac{1}{2}\|v(t)\|^2 + \frac{\mu}{\rho} \int_0^t \|\nabla v(\tau)\|^2 d\tau \le \frac{1}{2}\|v(0)\|^2 \exp(-2at)$$
 (1.6)

holds for any 0 < t < T. By virtue of the global existence result of Leray-Hopf weak solutions to (1.2), the fluid velocity perturbation v = u - Ax

is in the energy class $C_w([0,T]; L^2_{\sigma}(\mathbb{R}^n)) \cap L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$. Moreover, our main result includes the case of the Navier-Stokes equations with the Coriolis force, e.g., Hieber and Shibata [3].

This paper is organized as follows: In Subsection 2.1, we define basic notation used in this paper. Subsection 2.2 provides the notion of weak solutions and Leray-Hopf weak solutions to (1.2) and our main result. In Subsection 3.1, we state some auxiliary lemmas. Finally, the global existence of Leray-Hopf weak solutions to (1.2) is established in Subsection 3.2.

2. Preliminaries and a main result

2.1. Function spaces

Function spaces and basic notation which we use throughout this paper are introduced as follows: $M_n(\mathbb{R})$ is the set of all real square matrices of order n. In particular, $S_n(\mathbb{R})$ is the set of all real symmetric matrix of order n. For any $A \in M_n(\mathbb{R})$, the spectrum of A is denoted by $\sigma(A)$.

 $L^p(\mathbb{R}^n)$ $(1 \leq p \leq \infty)$ and $H^k(\mathbb{R}^n)$ $(k \in \mathbb{Z}, k \geq 0)$ are the Lebesgue and L^2 -Sobolev spaces respectively. Moreover, the scalar product and the norm in $L^2(\mathbb{R}^n)$ is denoted by (\cdot,\cdot) and $\|\cdot\|$ respectively. Let us introduce solenoidal function spaces. $C^k(\mathbb{R}^n)$ $(k \in \mathbb{Z}, k \geq 1)$ is the space of all functions in \mathbb{R}^n which are continuously differentiable up to order k in \mathbb{R}^n . In particular, we denote by $C_0^k(\mathbb{R}^n)$ the space of all C^k -functions in \mathbb{R}^n whose support are compact. Set $C_{0,\sigma}^k(\mathbb{R}^n)$:= $\{u \in (C_0^k(\mathbb{R}^n))^n; \operatorname{div} u = 0\}$. $L_{\sigma}^p(\mathbb{R}^n)$ $(1 and <math>H_{\sigma}^1(\mathbb{R}^n)$ are the completions of $C_{0,\sigma}^1(\mathbb{R}^n)$ in $(L^p(\mathbb{R}^n))^n$ and in $(H^1(\mathbb{R}^n))^n$ respectively.

Let I be a bounded open interval in \mathbb{R} , and X be a Banach space. $L^q(I;X)$ $(1 \leq q \leq \infty)$ and $H^k(I;X)$ $(k \in \mathbb{Z}, k \geq 0)$ are the Lebesgue and L^2 -Sobolev spaces of X-valued functions respectively.

Let I be a bounded closed interval in \mathbb{R} , and X be a Banach space. C(I;X) is the Banach space of all X-valued functions which are continuous in I. In particular, $C^k(I;X)$ ($k \in \mathbb{Z}, k \geq 1$) is the Banach space of all X-valued functions which are continuously differentiable up to order k in I.

Let I be a bounded closed interval in \mathbb{R} , and X be a Hilbert space with the scalar product $(\cdot, \cdot)_X$. As for the Banach space of weak continuous functions, we set $C_w(I; X) := \{u : I \to X; \forall \varphi \in X, (u, \varphi)_X \in C(I; \mathbb{R})\}.$

2.2. Leray-Hopf weak solutions to (1.2) and a main result

This subsection provides the notion of weak solutions and Leray-Hopf weak solutions to (1.2) and our main result. First, we define weak solutions to (1.2) which satisfy the weak formulation of (1.2).

Definition 2.1 Let $A \in M_n(\mathbb{R})$, $v(0) \in L^2_{\sigma}(\mathbb{R}^n)$ and T > 0. Then $v \in C_w([0,T];L^2_{\sigma}(\mathbb{R}^n)) \cap L^2((0,T);H^1_{\sigma}(\mathbb{R}^n))$ is called a weak solution to (1.2) if the functional equation

$$-\int_{s}^{t} (v(\tau), \partial_{\tau} \varphi(\tau)) d\tau + \int_{s}^{t} ((v(\tau) \cdot \nabla)v(\tau), \varphi(\tau)) d\tau$$

$$-\int_{s}^{t} (v(\tau), (Ax \cdot \nabla)\varphi(\tau)) d\tau + \int_{s}^{t} (Av(\tau), \varphi(\tau)) d\tau$$

$$+ \frac{\mu}{\rho} \int_{s}^{t} (\nabla v(\tau), \nabla \varphi(\tau)) d\tau = -(v(t), \varphi(t)) + (v(s), \varphi(s))$$
(2.1)

holds for any $\varphi \in H^1((s,t); C^1_{0,\sigma}(\mathbb{R}^n))$ and $0 \le s < t < T$.

Second, we introduce Leray-Hopf weak solutions to (1.2) which satisfy not only the weak formulation of (1.2) but also the energy inequality, i.e., (1.4).

Definition 2.2 Let $A \in M_n(\mathbb{R})$, $v(0) \in L^2_{\sigma}(\mathbb{R}^n)$ and T > 0. Then a weak solution $v \in C_w([0,T]; L^2_{\sigma}(\mathbb{R}^n)) \cap L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$ to (1.2) is called a Leray-Hopf weak solution to (1.2) if the energy inequality

$$\frac{1}{2}\|v(t)\|^2 + \int_0^t (Av(\tau), v(\tau))d\tau + \frac{\mu}{\rho} \int_0^t \|\nabla v(\tau)\|^2 d\tau \le \frac{1}{2}\|v(0)\|^2$$
 (2.2)

holds for any 0 < t < T.

Finally, we state our main result of this paper, i.e., the global existence result of Leray-Hopf weak solutions to (1.2) is established. The following theorem means that for any T > 0, a Leray-Hopf weak solution to (1.2) exists in $\mathbb{R}^n \times (0,T)$.

Theorem 2.1 Let $A \in M_n(\mathbb{R})$, $\operatorname{tr} A = 0$, $v(0) \in L^2_{\sigma}(\mathbb{R}^n)$ and T > 0. Then (1.2) has a Leray-Hopf weak solution $v \in C_w([0,T]; L^2_{\sigma}(\mathbb{R}^n)) \cap L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$ satisfying

$$\lim_{t \to +0} ||v(t) - v(0)|| = 0. \tag{2.3}$$

Remark 2.1 In the case where A is a zero matrix, Theorems 2.1 is [8, Theorem 1].

3. Proof of a main result

3.1. Auxiliary Lemmas

Some auxiliary lemmas are given in this subsection. First, we have the following lemma on the approximation of functions in $L^2((s,t);X)$ and in $H^1((s,t);X)$:

Lemma 3.1 Let X be a Banach space with the norm $\|\cdot\|_X$, Y be a dense subset of X and $0 \le s < t$, and set

$$F([s,t];Y):=\bigg\{\sum_{\text{finite}}a_k\psi_k;a_k\in C^1([s,t];\mathbb{R}),\ \psi_k\in Y\bigg\}.$$

Then

(1) For any $\varphi \in L^2((s,t);X)$, there exists a sequence $\{\varphi_m; m \in \mathbb{N}\}$ in F([s,t];Y) satisfying

$$\lim_{m \to \infty} \varphi_m = \varphi \text{ in } L^2((s,t);X).$$

(2) For any $\varphi \in H^1((s,t);X)$, there exists a sequence $\{\varphi_m; m \in \mathbb{N}\}$ in F([s,t];Y) satisfying

$$\lim_{m \to \infty} \varphi_m = \varphi \text{ in } H^1((s,t);X).$$

Proof. See [8, Lemma 2.2].

Second, we proceed to the alternativity of the trilinear form $((u \cdot \nabla)v, w)$. This property is established as follows:

Lemma 3.2 Let $u \in H^1_{\sigma}(\mathbb{R}^n) \cap L^n_{\sigma}(\mathbb{R}^n)$. Then

$$((u \cdot \nabla)v, w) = -((u \cdot \nabla)w, v) \tag{3.1}$$

holds for any $v, w \in H^1_{\sigma}(\mathbb{R}^n)$.

Proof. See [8, Lemma 2.3].

Finally, the Friedrichs inequality for the trilinear form $((u \cdot \nabla)v, w)$ is given. The following lemma is used for the equicontinuity.

Lemma 3.3 Let T > 0 and $w \in C([0,T]; L^n_{\sigma}(\mathbb{R}^n))$. Then for any $\varepsilon > 0$, there exists $C(T, w, \varepsilon) > 0$, $N(T, w, \varepsilon) \in \mathbb{N}$ and a sequence $\{\varphi_k; k \in \{1, \ldots, N(T, w, \varepsilon)\}\}$ in $L^2_{\sigma}(\mathbb{R}^n)$ depending only on n, T, w and ε such that

$$\int_{s}^{t} |((u(\tau) \cdot \nabla)v(\tau), w(\tau))| d\tau$$

$$\leq \varepsilon \int_{s}^{t} (\|\nabla u(\tau)\|^{2} + \|u(\tau)\| \|\nabla v(\tau)\| + \|\nabla v(\tau)\|^{2}) d\tau$$

$$+ C(T, w, \varepsilon) \sum_{k=1}^{N(T, w, \varepsilon)} \int_{s}^{t} |(u(\tau), \varphi_{k})|^{2} d\tau \tag{3.2}$$

holds for any $u, v \in L^2((s,t); H^1_\sigma(\mathbb{R}^n))$ and $0 \le s < t \le T$.

Proof. See [8, Lemma 2.5].
$$\Box$$

3.2. Proof of Theorem 2.1

In this subsection, we will prove Theorem 2.1. Since $H^1_{\sigma}(\mathbb{R}^n) \cap L^n_{\sigma}(\mathbb{R}^n)$ is a separable Banach space and $C^1_{0,\sigma}(\mathbb{R}^n)$ is dense in $H^1_{\sigma}(\mathbb{R}^n) \cap L^n_{\sigma}(\mathbb{R}^n)$, see [8, Proposition 1 and Lemma 3.1], there exists a linearly independent total sequence $\{\psi_k; k \in \mathbb{N}\}$ in $H^1_{\sigma}(\mathbb{R}^n) \cap L^n_{\sigma}(\mathbb{R}^n)$ which admits $\psi_k \in C^1_{0,\sigma}(\mathbb{R}^n)$ for any $k \in \mathbb{N}$. Note that $C^1_{0,\sigma}(\mathbb{R}^n) \subseteq H^1_{\sigma}(\mathbb{R}^n) \cap L^n_{\sigma}(\mathbb{R}^n) \subseteq L^2_{\sigma}(\mathbb{R}^n)$ and $C^1_{0,\sigma}(\mathbb{R}^n)$ is dense in $L^2_{\sigma}(\mathbb{R}^n)$. Without loss of generality, we may assume that $\{\psi_k; k \in \mathbb{N}\}$ is an orthonormal basis for $L^2_{\sigma}(\mathbb{R}^n)$. The approximate solution v_m to (1.2) of the form

$$v_m(x,t) := \sum_{k=1}^m b_k(t)\psi_k(x) \quad (x \in \mathbb{R}^n, \ 0 \le t \le T)$$

is constructed by the sequence $\{b_k; k \in \{1, ..., m\}\}$ in $C^1([0, T]; \mathbb{R})$ which is a solution to the following initial value problem for the system of m ordinary differential equations:

$$b'_{k}(t) + \sum_{(i,j)=(1,1)}^{(m,m)} ((\psi_{i} \cdot \nabla)\psi_{j}, \psi_{k})b_{i}(t)b_{j}(t) - \sum_{i=1}^{m} (\psi_{i}, (Ax \cdot \nabla)\psi_{k})b_{i}(t)$$

$$+ \sum_{i=1}^{m} (A\psi_{i}, \psi_{k})b_{i}(t) + \frac{\mu}{\rho} \sum_{i=1}^{m} (\nabla\psi_{i}, \nabla\psi_{k})b_{i}(t) = 0$$

$$(k \in \{1, \dots, m\}), \quad (3.3)$$

$$b_{k}(0) = (v(0), \psi_{k}) \quad (k \in \{1, \dots, m\}). \quad (3.4)$$

Note that (3.3), (3.4) uniquely has a solution $\{b_k; k \in \{1, ..., m\}\}$ in $C^1([0,T];\mathbb{R})$. Furthermore, (3.3) is rewritten to the system of m ordinary differential equations

$$(\partial_t v_m(t), \psi_k) + ((v_m(t) \cdot \nabla) v_m(t), \psi_k) - (v_m(t), (Ax \cdot \nabla) \psi_k) + (Av_m(t), \psi_k) + \frac{\mu}{\rho} (\nabla v_m(t), \nabla \psi_k) = 0 \quad (k \in \{1, \dots, m\}).$$
 (3.5)

First, for any $k \in \mathbb{N}$, the (uniform) boundedness of $\{(v_m, \psi_k); m \in \mathbb{N}\}$ in $C([0,T];\mathbb{R})$ is derived from the following lemma on the energy equality for v_m :

Lemma 3.4 The energy equality

$$\frac{1}{2}\|v_m(t)\|^2 + \int_s^t (Av_m(\tau), v_m(\tau))d\tau + \frac{\mu}{\rho} \int_s^t \|\nabla v_m(\tau)\|^2 d\tau = \frac{1}{2}\|v_m(s)\|^2$$
(3.6)

holds for any $0 \le s < t \le T$.

Proof. After multiplying (3.5) by b_k , we integrate it with respect to time over [s,t]. This integration yields the system of m integral equations

$$\int_{s}^{t} (\partial_{\tau} v_{m}(\tau), b_{k}(\tau)\psi_{k})d\tau + \int_{s}^{t} ((v_{m}(\tau) \cdot \nabla)v_{m}(\tau), b_{k}(\tau)\psi_{k})d\tau
- \int_{s}^{t} (v_{m}(\tau), (Ax \cdot \nabla)(b_{k}(\tau)\psi_{k}))d\tau + \int_{s}^{t} (Av_{m}(\tau), b_{k}(\tau)\psi_{k})d\tau
+ \frac{\mu}{\rho} \int_{s}^{t} (\nabla v_{m}(\tau), \nabla(b_{k}(\tau)\psi_{k}))d\tau = 0 \quad (k \in \{1, \dots, m\}).$$
(3.7)

Since $v_m \in C^1([0,T]; C^1_{0,\sigma}(\mathbb{R}^n)),$

$$((v_m \cdot \nabla)v_m, v_m) = 0 = (v_m, (Ax \cdot \nabla)v_m)$$

follows from Lemma 3.2. Consequently, the sum of (3.7) with respect to $k \in \{1, ..., m\}$ yields

$$\int_{s}^{t} (\partial_{\tau} v_m(\tau), v_m(\tau)) d\tau + \int_{s}^{t} (Av_m(\tau), v_m(\tau)) d\tau + \frac{\mu}{\rho} \int_{s}^{t} \|\nabla v_m(\tau)\|^2 d\tau = 0.$$
(3.8)

It is easy to see (3.6) from (3.8) and the fundamental theorem of calculus, which completes the proof of Lemma 3.4.

The following lemma yields not only the (uniform) boundedness of $\{(v_m, \psi_k); m \in \mathbb{N}\}$ in $C([0, T]; \mathbb{R})$ but also the energy inequality for weak solutions to (1.2).

Lemma 3.5 The energy inequality

$$\frac{1}{2}\|v_m(t)\|^2 + \int_0^t (Av_m(\tau), v_m(\tau))d\tau + \frac{\mu}{\rho} \int_0^t \|\nabla v_m(\tau)\|^2 d\tau \le \frac{1}{2}\|v(0)\|^2$$
(3.9)

holds for any $0 < t \le T$.

Proof. Substituting s = 0 into Lemma 3.4, we have

$$\frac{1}{2}\|v_m(t)\|^2 + \int_0^t (Av_m(\tau), v_m(\tau))d\tau + \frac{\mu}{\rho} \int_0^t \|\nabla v_m(\tau)\|^2 d\tau = \frac{1}{2}\|v_m(0)\|^2.$$

Moreover, $||v_m(0)|| \le ||v(0)||$ follows from the Bessel inequality. This completes the proof of Lemma 3.5.

By the quadratic inequality,

$$\int_{0}^{t} (Av_{m}(\tau), v_{m}(\tau)) d\tau \ge a \int_{0}^{t} \|v_{m}(\tau)\|^{2} d\tau$$
 (3.10)

holds for any $0 < t \le T$, where $a = \min\{\lambda; \lambda \in \sigma(S)\}$ and $S = (1/2)(A + A^T)$. Note that $\operatorname{tr} A = 0$ implies $a \le 0$. Then it follows from Lemma 3.5 and (3.10) that

$$\frac{1}{2}\|v_m(t)\|^2 + \frac{\mu}{\rho} \int_0^t \|\nabla v_m(\tau)\|^2 d\tau \le -a \int_0^t \|v_m(\tau)\|^2 d\tau + \frac{1}{2}\|v(0)\|^2 \quad (3.11)$$

holds for any $0 < t \le T$. Applying the Gronwall-Bellman inequality to (3.11),

$$\frac{1}{2}\|v_m(t)\|^2 + \frac{\mu}{\rho} \int_0^t \|\nabla v_m(\tau)\|^2 d\tau \le \frac{1}{2}\|v(0)\|^2 \exp(-2at)$$
 (3.12)

holds for any $0 < t \le T$. Therefore, for any $k \in \mathbb{N}$, the Schwarz inequality, (3.12) and $\|\psi_k\| = 1$ admit that $\{(v_m, \psi_k); m \in \mathbb{N}\}$ is (uniformly) bounded in $C([0, T]; \mathbb{R})$.

Second, for any $k \in \mathbb{N}$, we proceed to the equicontinuity of $\{(v_m, \psi_k); m \in \mathbb{N}\}$ on [0, T]. It is easy to see from (3.5) and the fundamental theorem of calculus that

$$(v_m(t), \psi_k) - (v_m(s), \psi_k) = \int_s^t (\partial_\tau v_m(\tau), \psi_k) d\tau$$

$$= -\int_s^t ((v_m(\tau) \cdot \nabla) v_m(\tau), \psi_k) d\tau$$

$$+ \int_s^t (v_m(\tau), (Ax \cdot \nabla) \psi_k) d\tau$$

$$- \int_s^t (Av_m(\tau), \psi_k) d\tau - \frac{\mu}{\rho} \int_s^t (\nabla v_m(\tau), \nabla \psi_k) d\tau$$

$$=: I_1(s, t) + I_2(s, t) + I_3(s, t) + I_4(s, t)$$
 (3.13)

holds for any $0 \le s < t \le T$. Concerning continuity properties of the above integrals in (3.13) with respect to time, the following two lemmas are established.

Lemma 3.6 Let $I_1(s,t)$ be taken as in (3.13). Then for any $\varepsilon > 0$, there exists $C(k,\varepsilon) > 0$ depending only on n, k and ε such that

$$|I_1(s,t)| \le \left\{ \frac{\rho}{4\mu} \varepsilon + C(k,\varepsilon)(t-s) \right\} ||v(0)||^2 \exp(-2aT)$$
 (3.14)

holds for any $0 \le s < t \le T$.

Proof. By Lemma 3.3 and the Schwarz inequality, for any $\varepsilon > 0$, there exists $C(k,\varepsilon) > 0$ depending only on n, k and ε such that

$$|I_1(s,t)| \le \frac{\varepsilon}{2} \int_s^t \|\nabla v_m(\tau)\|^2 d\tau + C(k,\varepsilon) \int_s^t \|v_m(\tau)\|^2 d\tau$$

holds for any $0 \le s < t \le T$. Consequently, (3.14) follows from (3.12). \square

Lemma 3.7 Let $I_2(s,t)$, $I_3(s,t)$ and $I_4(s,t)$ be taken as in (3.13). Then

$$|I_2(s,t)| \le (t-s) ||(Ax \cdot \nabla)\psi_k|| ||v(0)|| \exp(-aT)$$
 (3.15)

holds for any $0 \le s < t \le T$,

$$|I_3(s,t)| \le (t-s)|A| ||v(0)|| \exp(-aT)$$
(3.16)

holds for any $0 \le s < t \le T$, and

$$|I_4(s,t)| \le \left\{ \frac{\mu}{2\rho} (t-s) \right\}^{1/2} \|\nabla \psi_k\| \|v(0)\| \exp(-aT)$$
 (3.17)

holds for any $0 \le s < t \le T$.

Proof. Analogously to the proof of Lemma 3.6, (3.15), (3.16) and (3.17) are derived from the Schwarz inequality, (3.12) and $||\psi_k|| = 1$.

Combining (3.13) with Lemmas 3.6 and 3.7, for any $\varepsilon > 0$, there exists $\delta(T, k, \varepsilon) > 0$ depending only on n, ρ , μ , a, v(0), T, k and ε such that

$$|(v_m(t), \psi_k) - (v_m(s), \psi_k)| < \varepsilon$$

holds for any $m \in \mathbb{N}$ and $0 \le s, t \le T$ satisfying $|t-s| < \delta(T, k, \varepsilon)$. Therefore, for any $k \in \mathbb{N}$, $\{(v_m, \psi_k); m \in \mathbb{N}\}$ is equicontinuous on [0, T].

The proof of Theorem 2.1 is based on the following lemma on the convergence of the approximate solution v_m to (1.2). Hereafter, a subsequence of $\{v_m; m \in \mathbb{N}\}$ is denoted by $\{v_m; m \in \mathbb{N}\}$ itself for the sake of simplicity of the notation.

Lemma 3.8 There exists $v \in C_w([0,T]; L^2_{\sigma}(\mathbb{R}^n)) \cap L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$ satisfying

$$\lim_{m \to \infty} v_m = v \text{ weakly in } L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$$

and

$$\lim_{m \to \infty} v_m = v \text{ in } C_w([0,T]; L^2_\sigma(\mathbb{R}^n)).$$

Proof. Since $\{v_m; m \in \mathbb{N}\}$ is (uniformly) bounded in $C([0,T]; L^2_{\sigma}(\mathbb{R}^n))$ and in $L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$, which follows from (3.12), there exists $v \in L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$ satisfying

$$\lim_{m \to \infty} v_m = v \text{ weakly in } L^2((0,T); H^1_{\sigma}(\mathbb{R}^n)).$$

As is proved above, for any $k \in \mathbb{N}$, $\{(v_m, \psi_k); m \in \mathbb{N}\}$ is (uniformly) bounded in $C([0,T];\mathbb{R})$ and equicontinuous on [0,T]. Recall that $\{\psi_k; k \in \mathbb{N}\}$ is an orthonormal basis for $L^2_{\sigma}(\mathbb{R}^n)$. Then, by the Arzelà-Ascoli theorem and Cantor's diagonal argument, v is also in $C_w([0,T];L^2_{\sigma}(\mathbb{R}^n))$, and

$$\lim_{m \to \infty} v_m = v \text{ in } C_w([0, T]; L^2_{\sigma}(\mathbb{R}^n)).$$

This completes the proof of Lemma 3.8.

Finally, we will prove that v is a Leray-Hopf weak solution to (1.2). Let $0 \le s < t < T$, and set

$$F([s,t]; \operatorname{span}\{\psi_k; k \in \mathbb{N}\}) := \left\{ \sum_{\text{finite}} a_k \psi_k; a_k \in C^1([s,t]; \mathbb{R}) \right\}.$$

Then the same argument as in Lemma 3.4 shows that

$$-\int_{s}^{t} (v_{m}(\tau), \partial_{\tau}\varphi(\tau))d\tau + \int_{s}^{t} ((v_{m}(\tau) \cdot \nabla)v_{m}(\tau), \varphi(\tau))d\tau$$
$$-\int_{s}^{t} (v_{m}(\tau), (Ax \cdot \nabla)\varphi(\tau))d\tau + \int_{s}^{t} (Av_{m}(\tau), \varphi(\tau))d\tau$$
$$+\frac{\mu}{\rho} \int_{s}^{t} (\nabla v_{m}(\tau), \nabla \varphi(\tau))d\tau = -(v_{m}(t), \varphi(t)) + (v_{m}(s), \varphi(s)) \quad (3.18)$$

holds for any $\varphi \in F([s,t]; \operatorname{span}\{\psi_k; k \in \mathbb{N}\})$. For the purpose of the conclu-

sion, we have the following lemma on the convergence of the triliner form $((v_m(\tau) \cdot \nabla)v_m(\tau), \varphi(\tau))$:

Lemma 3.9 Let $v \in C_w([0,T]; L^2_{\sigma}(\mathbb{R}^n)) \cap L^2((0,T); H^1_{\sigma}(\mathbb{R}^n))$ be taken as in Lemma 3.8. Then

$$\lim_{m \to \infty} \int_{s}^{t} ((v_m(\tau) \cdot \nabla) v_m(\tau), \varphi(\tau)) d\tau = \int_{s}^{t} ((v(\tau) \cdot \nabla) v(\tau), \varphi(\tau)) d\tau \quad (3.19)$$

holds for any $\varphi \in F([s,t]; \operatorname{span}\{\psi_k; k \in \mathbb{N}\}).$

Proof. See
$$[8, (3.12)]$$
.

Let $m \to \infty$ in (3.18). Then, by Lemmas 3.8 and 3.9, we obtain

$$-\int_{s}^{t} (v(\tau), \partial_{\tau} \varphi(\tau)) d\tau + \int_{s}^{t} ((v(\tau) \cdot \nabla)v(\tau), \varphi(\tau)) d\tau$$
$$-\int_{s}^{t} (v(\tau), (Ax \cdot \nabla)\varphi(\tau)) d\tau + \int_{s}^{t} (Av(\tau), \varphi(\tau)) d\tau$$
$$+ \frac{\mu}{\rho} \int_{s}^{t} (\nabla v(\tau), \nabla \varphi(\tau)) d\tau = -(v(t), \varphi(t)) + (v(s), \varphi(s))$$
(3.20)

for any $\varphi \in F([s,t]; \operatorname{span}\{\psi_k; k \in \mathbb{N}\})$. Thus, it follows from (3.20) and Lemma 3.1 with $X = H^1_{\sigma}(\mathbb{R}^n) \cap L^n_{\sigma}(\mathbb{R}^n)$ and $Y = C^1_{0,\sigma}(\mathbb{R}^n)$ that v is a weak solution to (1.2). Moreover, Lemma 3.5 and 3.8 admit the energy inequality for v, so v is also a Leray-Hopf weak solution to (1.2). This completes the proof of Theorem 2.1.

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