# The wave equation for the $p$-Laplacian 

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#### Abstract

We consider generalized wave equations for the $p$-Laplacian and prove the local in time existence of solutions to the Cauchy problem. We give an estimate of the lifespan of the solution, and show by a generic counter-example that global in time solutions can not be expected.


Key words: local in time Sobolev solutions, blow-up in finite time, weakly hyperbolic equations.

## 1. Introduction

This paper is devoted to strong solutions to the hyperbolic Cauchy problem

$$
\begin{align*}
& w_{t t}(t, x)-\left(\left|w_{x}(t, x)\right|^{p-2} w_{x}(t, x)\right)_{x}=0,  \tag{1.1}\\
& w(0, x)=\Phi(x), \quad w_{t}(0, x)=\Psi(x)
\end{align*}
$$

where $p$ is a positive real number, not necessarily an even integer. More generally, we shall study

$$
\begin{align*}
& w_{t t}(t, x)-a\left(w_{x}(t, x)\right) w_{x x}(t, x)=0,  \tag{1.2}\\
& w(0, x)=\Phi(x), \quad w_{t}(0, x)=\Psi(x),
\end{align*}
$$

where $a=a(s):[-M, M] \rightarrow \mathbb{R}$ is a function with the following properties.
Condition 1 For all $s \in[-M, M]=\overline{B_{M}}$, the following holds:

$$
\begin{align*}
& a(s) \geq 0, \quad a(s)=0 \Longleftrightarrow s=0  \tag{1.3}\\
& a(s)=s^{2} a_{0}(s), \quad a_{0}(s) \leq C_{a}  \tag{1.4}\\
& 0 \leq s a_{0}^{\prime}(s) \leq C_{a} a_{0}(s), \quad 0 \leq s a^{\prime}(s) \leq C_{a} a(s) \tag{1.5}
\end{align*}
$$

Additionally, $a_{0}$ is even and $a_{0}, a_{1} \in C^{P}\left(\overline{B_{M}}\right)$, where $a_{1}(s)=a^{\prime}(s) / s$, and $P \in \mathbb{N}$.

[^0]Remark 1.1 The choice $a(s)=(p-1)|s|^{p-2}$ leads to (1.1) with $p>P+4$, or $p \in 2 \mathbb{N}, p \geq 4$, and $P \in \mathbb{N}$ is arbitrary.

The first of our main results is the following.
Theorem 1.2 Assume that the function $a=a(s)$ satisfies Condition 1, and suppose that the initial data $\Phi, \Psi \in C_{0}^{k+2}(\mathbb{R})$ with $4 \leq k \leq P+1$, $P, k \in \mathbb{N}$, are compatible to $a(s)$, i.e., they are real-valued and $\left\|\Phi_{x}\right\|_{L^{\infty}}<$ $M$.

Then the Cauchy problem (1.2) has a real-valued local solution $w$ with

$$
w \in L^{\infty}\left(\left[0, T_{0}\right], H^{k}(\mathbb{R})\right), \quad \partial_{t}^{2} w \in L^{\infty}\left(\left[0, T_{0}\right], H^{k-2}(\mathbb{R})\right)
$$

This solution vanishes outside $\left[0, T_{0}\right] \times \operatorname{supp}(\Phi, \Psi)$. The estimate $T_{0}$ of the life span only depends on $M, \operatorname{supp}(\Phi, \Psi)$, and the norms $\|(\Phi, \Psi)\|_{C^{6}(\mathbb{R})}$, $\left\|\left(a_{0}, a_{1}\right)\right\|_{C^{3}\left(B_{M}\right)}$. The solution is unique in the space of all functions $w$ with $w \in L^{\infty}\left(\left[0, T_{0}\right], H^{4}(\mathbb{R})\right), \partial_{t}^{2} w \in L^{\infty}\left(\left[0, T_{0}\right], H^{2}(\mathbb{R})\right)$.

Remark 1.3 By the same arguments, we can study the more general equation

$$
w_{t t}-a\left(w_{x}\right) w_{x x}-b\left(w_{x}\right)-c w=0
$$

where $a(s)$ is as above, $b(s)$ is sufficiently smooth with $b(0)=0$ and $\left|b^{\prime}(s)\right|^{2} \leq$ $C a(s)$, and $c$ is a real constant. It is even possible to allow an additional dependence on time of $a, b, c$. However, for simplicity, we stick to (1.2).

Remark 1.4 If the function $a(s)$ is analytic, we can drop Condition 1 and follow a modified version of the proof given in [17], where equations $u_{t t}-a(u) \Delta u=0$ with analytic function $a$ were studied.

In the proof, we shall replace the nonsmooth coefficient $a(s)$ by a smooth approximation, preserving the other conditions.

Condition 2 The coefficient $a=a(s)$ satisfies Condition 1, and $a_{0} \in$ $C^{\infty}\left(\overline{B_{M}}\right)$.

Theorem 1.5 Let the assumptions of Theorem 1.2 be satisfied. Additionally, suppose that $a=a(s)$ satisfies Condition 2 , and $\Phi, \Psi \in C_{0}^{\infty}(\mathbb{R})$.

Then the solution $w$ to the Cauchy problem (1.2) belongs to $C_{b}^{\infty}\left(\left[0, T_{0}\right] \times\right.$ $\mathbb{R}$ ).

The life span of the solution tends to infinity for initial data approaching
zero, in the following sense. Fix some $0<\lambda \ll 1$, and consider the Cauchy problem

$$
\begin{align*}
& w_{t t}(t, x)-a\left(w_{x}(t, x)\right) w_{x x}(t, x)=0  \tag{1.6}\\
& w(0, x)=\lambda \Phi(x), \quad w_{t}(0, x)=\lambda \Psi(x)
\end{align*}
$$

Theorem 1.6 Let the assumptions of Theorem 1.2 be satisfied. Then the lower estimate of the life span $T_{0}=T_{0}(\lambda)$ goes to infinity for $\lambda \rightarrow 0$. More precisely,

$$
T_{0}(\lambda) \geq C|\ln \lambda|^{1 / 3}, \quad 0<\lambda \ll 1
$$

It is known (see [7]) that (1.2) admits a unique local solution in Sobolev spaces in the strictly hyperbolic case, $(a(s) \geq \alpha>0)$. However, this solution is never a global classical solution, except in trivial cases. In [13], the Cauchy problem

$$
\begin{aligned}
& w_{t t}(t, x)-a\left(w_{x}(t, x)\right)^{2} w_{x x}(t, x)=0 \\
& w(0, x)=\Phi(x), \quad w_{t}(0, x)=\Psi(x)
\end{aligned}
$$

has been considered, where $a\left(w_{x}\right)>0, a^{\prime}\left(w_{x}\right) \neq 0$, and the data $\Phi, \Psi$ have compact support. It was shown that the only global solution $w \in C^{2}\left(\mathbb{R}_{t} \times\right.$ $\mathbb{R}_{x}$ ) is $w \equiv 0$. In other words, every nontrivial solution develops a singularity in finite time, it is the second derivatives of $w$ that become infinite. This result can not be applied to (1.2) since (1.2) is neither strictly hyperbolic nor everywhere genuinely nonlinear. However, by a different method, we show in Section 9 that global solutions to (1.1) can not exist in case of $p=4$ provided that the initial data satisfy appropriate sign conditions.

At first glance, it seems natural to attack (1.2) by a linearisation argument, leading to a family of Cauchy problems

$$
\begin{aligned}
& w_{t t}^{(n+1)}(t, x)-a\left(w_{x}^{(n)}(t, x)\right) w_{x x}^{(n+1)}(t, x)=0 \\
& w^{(n+1)}(0, x)=\Phi(x), \quad w_{t}^{(n+1)}(0, x)=\Psi(x)
\end{aligned}
$$

and then one hopes to be able to show convergence $w^{(n)} \rightarrow w^{*}$ at least for small times. In general, this direct approach will not work in the weakly hyperbolic case. In fact, a Cauchy problem

$$
\begin{aligned}
& w_{t t}(t, x)-a(t) w_{x x}(t, x)=0, \quad a \geq 0, \quad a \in C^{\infty} \\
& w(0, x)=\Phi(x), \quad w_{t}(0, x)=\Psi(x), \quad \Phi, \Psi \in C^{\infty}
\end{aligned}
$$

without solution was constructed in [3]. On the other hand, (1.2) is wellposed in Gevrey spaces with Gevrey index between 1 and 2 if $a=a(s)$ is analytic. This is a special case of much more general results in [14], [15]. If one allows damping terms of the form $(-\Delta)^{\alpha} \partial_{t} w$ in (1.2), $0<\alpha \leq 1$, then the global existence and the energy decay of weak solutions can be proved, see for instance [1], [2], [9], [11].

In [8], the Cauchy problem

$$
\begin{aligned}
& w_{t t}-\nabla\left(|\nabla w|^{p-2} \nabla w\right)-|w|^{q-1} w=0, \quad p, q>1, q \geq p-1, \\
& w(0, x)=\Phi_{0}(x), \quad w_{t}(0, x)=\Psi_{0}(x),
\end{aligned}
$$

has been studied. Assuming that $\Phi_{0}$ and $\Psi_{0}$ are real-valued and that $\left\|\Psi_{0}\right\|_{L^{2}}^{2} / 2+\left\|\nabla \Phi_{0}\right\|_{L^{p}}^{p} / p \leq\left\|\Phi_{0}\right\|_{L^{q+1}}^{q+1} /(q+1)$, it was shown that $\|w(t, \cdot)\|_{L^{2}}$ blows up in finite time if $\int \Phi_{0}(x) \Psi_{0}(x) d x>0$, and that $\|w(t, \cdot)\|_{L^{2}}$ decays (for $t \rightarrow \infty$ ) if $\int \Phi_{0}(x) \Psi_{0}(x) d x<0$.

The life span of periodic analytic solutions to the nonlinear Cauchy problem

$$
w_{t t}=F\left(x, w, D w, D^{2} w\right), \quad w(0, x)=\lambda \Phi(x), \quad w_{t}(0, x)=\lambda \Psi(x)
$$

has been studied in [5]. Assuming that this equation is weakly hyperbolic at $(x, 0,0,0)$, the estimate $T_{0}(\lambda) \geq C \log |\log \lambda|$ was proved.

Our approach relies on two key ingredients. The first is a careful investigation of a so-called separating curve, a method which is represented in [6]. The second is a certain decomposition of the solution and the reduction to a hyperbolic $2 \times 2$ system of second order. This technique has been developed in [4] and [17], where certain semilinear and quasilinear cases were studied. This method consists of several steps, which are performed in the Sections 2 to 8. A more detailed description can be found at the end of Section 2. The blow-up of solutions for a variant of (1.1) is shown in Section 9.

We employ the standard notations $\partial_{x}=\partial / \partial x, \partial_{t}=\partial / \partial t ; H^{k}(X)=$ $W_{2}^{k}(X)$ are the usual Sobolev spaces on an open set $X$, and $C_{b}^{\infty}(X)$ denotes the linear space of all functions that are bounded and continuous together with all their derivatives.

## 2. Transformation into a system

In order to be able to derive a priori estimates for (1.2), we shall transform this Cauchy problem into a second order system. The main advantage
is that we will have more information about the principal part available.
Set $u(t, x)=\partial_{x} w(t, x), \phi(x)=\partial_{x} \Phi(x), \psi(x)=\partial_{x} \Psi(x)$. Assuming that $w$ is a solution to (1.2), we find that $u$ solves

$$
\begin{align*}
& u_{t t}(t, x)-\partial_{x}\left(a(u(t, x)) \partial_{x} u(t, x)\right)=0  \tag{2.1}\\
& u(0, x)=\phi(x), \quad u_{t}(0, x)=\psi(x)
\end{align*}
$$

If $\phi\left(x_{0}\right)=\psi\left(x_{0}\right)=0$, then $\left(\partial_{t}^{k} u\right)\left(0, x_{0}\right)=0$ for all $k \in \mathbb{N}$. This suggests the educated guess

$$
\begin{aligned}
& u(t, x)=\phi(x) g(t, x)+\psi(x) h(t, x) \\
& g(0, x)=1, \quad h(0, x)=0, \quad g_{t}(0, x)=0, \quad h_{t}(0, x)=1
\end{aligned}
$$

A direct calculation gives us $u_{t t}=\phi g_{t t}+\psi h_{t t}$ and

$$
\begin{aligned}
& \partial_{x}\left(a(u) u_{x}\right)=a(u)\left(\phi g_{x x}+\psi h_{x x}\right) \\
& \quad+a^{\prime}(u) u_{x}\left(\phi g_{x}+\psi h_{x}\right)+2 a_{0}(u)(\phi g+\psi h)^{2}\left(\phi_{x} g_{x}+\psi_{x} h_{x}\right) \\
& \quad+(\phi g+\psi h)\left(a_{0}(u) u\left(\phi_{x x} g+\psi_{x x} h\right)+a_{1}(u)\left(\phi_{x} g+\psi_{x} h\right)^{2}\right)
\end{aligned}
$$

which leads us to

$$
\begin{aligned}
& \phi\left(g_{t t}-\partial_{x}\left(a(u) g_{x}\right)-2 a_{0}(u) u g\left(\phi_{x} g_{x}+\psi_{x} h_{x}\right)-c g\right) \\
& \quad+\psi\left(h_{t t}-\partial_{x}\left(a(u) h_{x}\right)-2 a_{0}(u) u h\left(\phi_{x} g_{x}+\psi_{x} h_{x}\right)-c h\right)=0
\end{aligned}
$$

where we have introduced

$$
c=c(x, g, h)=a_{0}(u) u\left(\phi_{x x} g+\psi_{x x} h\right)+a_{1}(u)\left(\phi_{x} g+\psi_{x} h\right)^{2}
$$

Now we define the vector $U=(g, h)^{T}$ of unknowns and

$$
\begin{align*}
& A(x, U)=\left(\begin{array}{cc}
a(\phi(x) g+\psi(x) h) & 0 \\
0 & a(\phi(x) g+\psi(x) h)
\end{array}\right)  \tag{2.2}\\
& B(x, U)=2 a_{0}(\phi(x) g+\psi(x) h) \\
& \times(\phi(x) g+\psi(x) h)\left(\begin{array}{ll}
\phi_{x}(x) g & \psi_{x}(x) g \\
\phi_{x}(x) h & \psi_{x}(x) h
\end{array}\right)  \tag{2.3}\\
& C(x, U)=\left(\begin{array}{cc}
c(x, U) & 0 \\
0 & c(x, U)
\end{array}\right) \tag{2.4}
\end{align*}
$$

Clearly, if we are able to find a solution $U=U(t, x)$ to the Cauchy problem

$$
\begin{equation*}
\partial_{t}^{2} U-\partial_{x}\left(A(x, U) \partial_{x} U\right)-B(x, U) \partial_{x} U-C(x, U) U=0 \tag{2.5}
\end{equation*}
$$

$$
U(0, x)=(1,0)^{T}, \quad U_{t}(0, x)=(0,1)^{T}
$$

then the function $u(t, x)=\phi(x) g(t, x)+\psi(x) h(t, x)$ solves (2.1).
In case of (1.6), we obtain the Cauchy problem

$$
\begin{align*}
& \partial_{t}^{2} U-\partial_{x}\left(A_{\lambda}(x, U) \partial_{x} U\right)-B_{\lambda}(x, U) \partial_{x} U-C_{\lambda}(x, U) U=0  \tag{2.6}\\
& U(0, x)=(1,0)^{T}, \quad U_{t}(0, x)=(0,1)^{T}
\end{align*}
$$

where $A_{\lambda}, B_{\lambda}, C_{\lambda}$ are defined as in (2.2)-(2.4), with $(\phi, \psi)$ replaced by $(\lambda \phi, \lambda \psi)$.

We will consider a linearised version of (2.5),

$$
\begin{equation*}
\partial_{t}^{2} V-\partial_{x}\left(A(x, U) \partial_{x} V\right)-B(x, U) \partial_{x} V-C(x, U) V=F(t, x) \tag{2.7}
\end{equation*}
$$

with one of the following initial conditions:

$$
\begin{align*}
& V(0, x)=V_{0}(x), \quad V_{t}(0, x)=V_{1}(x)  \tag{2.8}\\
& V\left(t_{0}, x\right)=V_{0}(x), \quad V_{t}\left(t_{0}, x\right)=V_{1}(x), \quad 0<t_{0}<T \tag{2.9}
\end{align*}
$$

where $U=U(t, x)$ is some vector valued function with

$$
\begin{equation*}
\left\|U(t, \cdot)-\binom{1}{t}\right\|_{C_{b}^{1}\left([0, T] \times B_{R}\right)}<\varepsilon \ll 1 \tag{2.10}
\end{equation*}
$$

The paper is organised as follows. In Section 3, we study the behaviour of $A=A(x, U(t, x))$ under the condition $(2.10)_{T}$. Using results from [17], we shall derive a priori estimates in Sobolev spaces for a solution $V$ to (2.7) in Section 4. Then, a regularisation argument will enable us to prove the existence of a unique $C^{\infty}$ solution $V$ to (2.7) in Section 5. By means of Nash-Moser-Hamilton theory, the existence of a local $C^{\infty}$ solution $U$ to (2.5) will be shown in Section 6. The life span of this solution is studied in Section 7, leading to a proof of Theorem 1.5. Finally, Theorem 1.2 is proved in Section 8. The proof of Theorem 1.6 relies on a careful analysis of the dependence of all constants on $\lambda$.

## 3. The separating curve

Assume that $U=(g, h)^{T}$ is defined on $[0, T] \times B_{R}$ and fulfils $(2.10)_{T}$. Setting $U(t, x)+U(-t, x):=2 U(0, x)$, we extend $U$ as a $C^{1}$ function to $[-T, T] \times B_{R}$, and have $\left\|U(t, \cdot)-(1, t)^{T}\right\|_{C^{1}\left([-T, T] \times B_{R}\right)}<\varepsilon$, allowing
some modification in $\varepsilon$. The next proposition describes the behaviour of the function $a_{*}(t, x)=a(\phi(x) g(t, x)+\psi(x) h(t, x))$ in a neighbourhood of the line $\{0\} \times B_{R}$.
Proposition 3.1 Let $a=a(s)$ satisfy Condition 1, and assume that $\phi, \psi$ $\in C_{0}^{1}(\mathbb{R})$ are compatible data, i.e., $\|\phi\|_{L^{\infty}}<M$. Introduce the notation

$$
\Omega_{\phi \psi}=\{x:|\phi(x)|+|\psi(x)|>0\} .
$$

Then there are constants $\varepsilon, \alpha, \tau>0$ such that for every $U=(g, h)^{T}$ with $(2.10)_{\tau}$ there is a $\gamma \in C^{1}\left(\Omega_{\phi \psi}\right)$ such that $a_{*}(t, x)=a(\phi(x) g(t, x)+$ $\psi(x) h(t, x))$ satisfies

$$
\begin{array}{lll}
\alpha a_{*}(t, x)-\partial_{t} a_{*}(t, x) \geq 0 & : t<\gamma(x), & (t, x) \in[-\tau, \tau] \times \Omega_{\phi \psi},  \tag{3.1}\\
\alpha a_{*}(t, x)+\partial_{t} a_{*}(t, x) \geq 0 & : t>\gamma(x), \quad(t, x) \in[-\tau, \tau] \times \Omega_{\phi \psi}, \\
a_{*}(\gamma(x), x)\left(\gamma^{\prime}(x)\right)^{2} \leq \frac{1}{4} & : x \in \Omega_{\phi \psi} .
\end{array}
$$

Moreover, the function $\gamma$ has the same regularity as $\phi, \psi$, and $U$; and the constants $\varepsilon, \tau, \alpha$ depend only on $M, C_{a},\|(\phi, \psi)\|_{C^{1}}$.

Remark 3.2 The curve $\{t=\gamma(x)\}$ separates the $(t, x)$ space into two parts. In the following section, different methods will be employed in both parts in order to derive a priori estimates of the solution $V$ of (2.7).

Remark 3.3 Condition (3.3) means that the curve $\{t=\gamma(x)\}$ is noncharacteristic.

Proof. This proof is based on ideas from [17].
Set $M^{\prime}=\|\phi\|_{L^{\infty}}<M$. If $\tau \leq\left(M-M^{\prime}\right) /\left(2\|\psi\|_{L^{\infty}}\right)$ and $|t| \leq \tau$, then $\|\phi+t \psi\|_{L^{\infty}} \leq\left(M+M^{\prime}\right) / 2$. If $0<\varepsilon \leq \varepsilon_{0}\left(M, M^{\prime},\|\psi\|_{L^{\infty}}\right)$, then $\|\phi g+\psi h\|_{L^{\infty}} \leq M$ for $|t| \leq \tau$ and $U=(g, h)^{T}$ satisfying $(2.10)_{\tau}$; and the mapping $t \mapsto \chi(t ; x)=h(t, x) / g(t, x)$ is invertible for every $|x| \leq R,|t| \leq \tau$. Assuming $\varepsilon \tau \leq 1 / 6$, we get

$$
\begin{equation*}
|\chi(t ; x)-t| \leq 2 \varepsilon+\frac{|t|}{2}, \quad|\chi(t ; x)| \leq 2(\varepsilon+|t|), \tag{3.4}
\end{equation*}
$$

since $\left|\chi_{t}(t ; x)-1\right| \leq 1 / 2$. Then the inverse function $\chi^{-1}(s ; x)$ of the mapping
$t \mapsto \chi(t ; x)$ satisfies $\left|\chi^{-1}(s ; x)\right| \leq 2(\varepsilon+|s|)$. For every $r>0$, we set

$$
\Omega_{\phi \psi}^{r}=\left\{x \in \Omega_{\phi \psi}:|\phi(x)| \leq r|\psi(x)|\right\}
$$

Clearly, if $x \in \Omega_{\phi \psi}^{r}$, then $\psi(x) \neq 0$. Assuming $x \in \Omega_{\phi \psi} \backslash \Omega_{\phi \psi}^{r}$, we have

$$
\begin{align*}
& |\phi(x) g(t, x)+\psi(x) h(t, x)| \geq|\phi(x)| g(t, x)\left(1-\frac{|\chi(t ; x)|}{r}\right) \\
& \left|\partial_{t} a_{*}(t, x)\right| \leq C_{a} a_{*}(t, x) \frac{\left|\phi(x) g_{t}(t, x)+\psi(x) h_{t}(t, x)\right|}{|\phi(x) g(t, x)+\psi(x) h(t, x)|}  \tag{3.5}\\
& \quad \leq C_{a} a_{*}(t, x) \frac{\left|\phi(x) g_{t}(t, x)\right|+\left|\psi(x) h_{t}(t, x)\right|}{|\phi(x)| g(t, x)}\left(1-\frac{|\chi(t ; x)|}{r}\right)^{-1} \\
& \quad \leq C_{a} a_{*}(t, x) \frac{\varepsilon r+1+\varepsilon}{1-\varepsilon} \frac{1}{r-|\chi(t ; x)|} \\
& \quad \leq \frac{(2+r) C_{a}}{r-|\chi(t ; x)|} a_{*}(t, x)
\end{align*}
$$

if $|\chi(t ; x)|<r$, due to (1.5). Trivially, if $x \in \Omega_{\phi \psi}^{2 r}$, then

$$
\begin{equation*}
\left|\partial_{x} \frac{\phi(x)}{\psi(x)}\right| \leq \frac{\left\|\phi^{\prime}\right\|_{L^{\infty}}+2 r\left\|\psi^{\prime}\right\|_{L^{\infty}}}{|\psi(x)|} \tag{3.6}
\end{equation*}
$$

Now choose some odd function $\beta=\beta(s) \in C_{0}^{\infty}(\mathbb{R})$ with $\operatorname{supp} \beta \subset(-2,2)$ and $\|\beta\|_{L^{\infty}} \leq 2,\left\|\beta^{\prime}\right\|_{L^{\infty}} \leq 2$, satisfying $s \beta(s) \leq 0$ and $\beta(s)=-s,-1 \leq$ $s \leq 1$. Then we define the separating curve by

$$
\gamma(x)=\chi^{-1}\left(r \beta\left(\frac{\phi(x)}{r \psi(x)}\right) ; x\right), \quad 0<r \ll 1
$$

We see that $|\gamma(x)| \leq 4(\varepsilon+r)$. Now we check that this function $\gamma=$ $\gamma(x)$ satisfies (3.1)-(3.3) for small $r$. If $x \in \Omega_{\phi \psi}^{r}$, then $-\phi(x) / \psi(x)=$ $h(\gamma(x), x) / g(\gamma(x), x)$. In case $t<\gamma(x)$ we have $-\phi(x) / \psi(x)>h(t, x) / g(t, x)$. Assuming

$$
\begin{equation*}
\varepsilon(1+r)<1 \tag{3.7}
\end{equation*}
$$

we then obtain

$$
\frac{\phi(x) g_{t}(t, x)+\psi(x) h_{t}(t, x)}{\phi(x) g(t, x)+\psi(x) h(t, x)}<0
$$

which implies

$$
\begin{aligned}
& \alpha a_{*}(t, x)-\partial_{t} a_{*}(t, x)=\alpha a_{*}(t, x) \\
& \quad-a^{\prime}(\phi(x) g(t, x)+\psi(x) h(t, x))(\phi(x) g(t, x)+\psi(x) h(t, x)) \\
& \quad \times \frac{\phi(x) g_{t}(t, x)+\psi(x) h_{t}(t, x)}{\phi(x) g(t, x)+\psi(x) h(t, x)} \geq 0
\end{aligned}
$$

for any $\alpha \geq 0$, see Condition 1 . The case $t>\gamma(x)$ can be considered similarly.

Now assume that $x \in \Omega_{\phi \psi} \backslash \Omega_{\phi \psi}^{r},|\chi(t ; x)| \leq r / 2$. According to (3.5),

$$
\left|\partial_{t} a_{*}(t, x)\right| \leq \frac{(2+r) C_{a}}{r-|\chi(t ; x)|} a_{*}(t, x) \leq \frac{(4+2 r) C_{a}}{r} a_{*}(t, x)
$$

which proves (3.1) and (3.2) with

$$
\begin{equation*}
2 \varepsilon \leq \frac{r}{4}, \quad 2 \tau \leq \frac{r}{4}, \quad \alpha=\frac{(4+2 r) C_{a}}{r} \tag{3.8}
\end{equation*}
$$

see (3.4). It remains to check (3.3). This holds true for $x \in \Omega_{\phi \psi}^{r}$, since then the left-hand side vanishes. Now let $x \in \Omega_{\phi \psi} \backslash \Omega_{\phi \psi}^{r}$, but $x \in \Omega_{\phi \psi}^{2 r}$, which implies $r|\psi(x)|<|\phi(x)| \leq 2 r|\psi(x)|$. By elementary computation,

$$
\begin{aligned}
& \gamma^{\prime}(x)=\left.\frac{\beta^{\prime}(\phi(x) /(r \psi(x))) \partial_{x}(\phi(x) / \psi(x))}{\partial_{t}(h(t, x) / g(t, x))}\right|_{t=\gamma(x)} \\
&-\left.\frac{\partial_{x}(h(t, x) / g(t, x))}{\partial_{t}(h(t, x) / g(t, x))}\right|_{t=\gamma(x)}
\end{aligned}
$$

From $(2.10)_{\tau}$ we obtain $\left\|\partial_{x}(h / g)\right\|_{L^{\infty}} \leq(2+r) \varepsilon \leq 2$ and $\left|\partial_{t}(h / g)\right|=\left|\chi_{t}\right| \geq$ $1 / 2$. Consequently, according to (3.6) and (1.4),

$$
\begin{align*}
\left|\gamma^{\prime}(x)\right| \leq 4 \frac{\left\|\phi^{\prime}\right\|_{L^{\infty}}+2 r\left\|\psi^{\prime}\right\|_{L^{\infty}}}{|\psi(x)|}+4 \\
\begin{aligned}
a_{*}(\gamma(x), x)\left(\gamma^{\prime}(x)\right)^{2}
\end{aligned}  \tag{3.9}\\
\begin{aligned}
\leq 32 C_{a}(\phi(x) g(\gamma(x), x) & +\psi(x) h(\gamma(x), x))^{2} \\
\leq & \times\left(\frac{\left(\left\|\phi^{\prime}\right\|_{L^{\infty}}+2 r\left\|\psi^{\prime}\right\|_{L^{\infty}}\right)^{2}}{|\psi(x)|^{2}}+1\right) \\
\leq 32 C_{a} r^{2}(2 g(\gamma(x), x) & \left.+\frac{5(\varepsilon+r)}{r}\right)^{2} \\
& \times\left(\left(\left\|\phi^{\prime}\right\|_{L^{\infty}}+2 r\left\|\psi^{\prime}\right\|_{L^{\infty}}\right)^{2}+\|\psi\|_{L^{\infty}}^{2}\right)
\end{aligned} \\
\quad
\end{align*}
$$

if $r$ is sufficiently small, compare (3.8). It remains to consider $x \in \Omega_{\phi \psi} \backslash$ $\Omega_{\phi \psi}^{2 r}$. Then $\gamma(x)=\chi^{-1}(0 ; x)$; hence $\left|\gamma^{\prime}(x)\right| \leq 4 \varepsilon$. Then we need

$$
\begin{equation*}
a_{*}(\gamma(x), x)\left(\gamma^{\prime}(x)\right)^{2} \leq 32 C_{a}\left(\|\phi\|_{L^{\infty}}+\tau\|\psi\|_{L^{\infty}}\right)^{2} \varepsilon^{2} \leq \frac{1}{4} \tag{3.10}
\end{equation*}
$$

We choose $r$ according to (3.9), and then $\varepsilon, \tau, \alpha$ as in (3.7), (3.8) and (3.10).

Remark 3.4 In the case of (2.6), $\varepsilon, \tau, \alpha$ will depend on $\lambda$. Careful checking of the proof shows $r=\mathscr{O}\left(\lambda^{-1 / 2}\right), \tau=\mathscr{O}\left(\lambda^{-1 / 2}\right), \alpha=\mathscr{O}(1), \varepsilon=\mathscr{O}\left(\lambda^{1 / 2}\right)$.
Remark 3.5 Consider (2.6) and choose $\varepsilon, \tau$ as given in Remark 3.4. Suppose that $U=(g, h)^{T}$ satisfies (2.10) with that $\tau$ and that $\varepsilon$. Then we have, for all $\lambda$,

$$
\begin{aligned}
& \sum_{|\alpha|+|\beta| \leq k}\left|\partial_{x}^{\alpha} \partial_{U}^{\beta} A_{\lambda}(x, U)\right|+\left|\partial_{x}^{\alpha} \partial_{U}^{\beta} B_{\lambda}(x, U)\right| \\
&+\left|\partial_{x}^{\alpha} \partial_{U}^{\beta} C_{\lambda}(x, U)\right| \leq C_{k} \lambda
\end{aligned}
$$

From Lemma 10.1, we conclude that

$$
\begin{aligned}
& \left\|A_{\lambda}(\cdot, U(t, \cdot))\right\|_{H^{k}\left(B_{R}\right)}+\left\|B_{\lambda}(\cdot, U(t, \cdot))\right\|_{H^{k}\left(B_{R}\right)} \\
& +\left\|C_{\lambda}(\cdot, U(t, \cdot))\right\|_{H^{k}\left(B_{R}\right)} \\
& \quad \leq C_{k} \lambda\left(1+\|U(t, \cdot)\|_{L^{\infty}}^{k}\right)\left(1+\|U(t, \cdot)\|_{H^{k}\left(B_{R}\right)}\right)
\end{aligned}
$$

for $k \geq 1$. By computation,

$$
\left\|\partial_{x}^{2} a_{*, \lambda}(t, \cdot)\right\|_{L^{\infty}} \leq C \lambda\left(1+\left\|\partial_{x}^{2} U(t, \cdot)\right\|_{L^{\infty}}\right)
$$

## 4. A priori estimates for (2.7)

The system (2.7) can be written in the form

$$
\begin{align*}
& \partial_{t}^{2} V-a_{*}(t, x) \partial_{x}^{2} V-\tilde{B}(t, x) \partial_{x} V-\tilde{C}(t, x) V=F(t, x) \\
& V(0, x)=V_{0}(x), \quad V_{t}(0, x)=V_{1}(x) \tag{4.1}
\end{align*}
$$

where $\tilde{B}(t, x)=B(x, U(t, x))+\partial_{x} a_{*}(t, x) I, \tilde{C}(t, x)=C(x, U(t, x))$. More generally, we consider the Cauchy problem

$$
\begin{align*}
& \partial_{t}^{2} V-a_{*}(t, x) \partial_{x}^{2} V-B_{*}(t, x) \partial_{x} V-C_{*}(t, x) V=F(t, x)  \tag{4.2}\\
& V\left(t_{0}, x\right)=V_{0}(x), \quad V_{t}\left(t_{0}, x\right)=V_{1}(x) \tag{4.3}
\end{align*}
$$

where $a_{*}, B_{*}, C_{*}$ are functions satisfying the following hypothesis.

## Hypothesis 1

(a) $\quad a_{*}(t, x)=a(\phi(x) g(t, x)+\psi(x) h(t, x))$, and $a=a(s)$ satisfies Condition 1,
(b) $\left|B_{*}(t, x)\right|^{2} \leq L a_{*}(t, x)$ for some $L \geq 0$ (Levi Condition),
(c) $\phi, \psi \in C_{0}^{2}(\mathbb{R})$ with $\operatorname{supp}(\phi, \psi) \subset B_{R}=\{|x|<R\}$, and $\|\phi\|_{L^{\infty}}<M$,
(d) the coefficient $a_{*}$ admits a separating curve in the sense of Proposition 3.1,
(e) the numbers $\varepsilon$ and $\tau$ from $(2.10)_{\tau},(3.1),(3.2)$ are chosen as in Proposition 3.1.

For the proof of (b) we only recall Condition 1 and Glaeser's inequality [10],

$$
\left|e^{\prime}(x)\right|^{2} \leq 2\|e\|_{C^{2}(\mathbb{R})} e(x)
$$

for every function $e=e(x) \in C^{2}(\mathbb{R})$ with $e(x) \geq 0$ for all $x$.
Now we give estimates of $|V(t, x)|$ separately in the both zones $\{x: \gamma(x)>t\}$ and $\{x: \gamma(x)<t\}$. Our approach is based on a work of Manfrin, we only list the results and refer the reader to [17] for the proofs. See also [18].

We introduce the sets

$$
\begin{aligned}
& D(t)=\left\{\left(t^{\prime}, x\right): x \in \Omega_{\phi \psi}, 0<t^{\prime}<\min \{\gamma(x), t\}\right\} \\
& G(t)=\left\{\left(t^{\prime}, x\right): x \in \Omega_{\phi \psi}, \max \{\gamma(x), 0\}<t^{\prime}<t\right\}
\end{aligned}
$$

and define the energies

$$
\begin{aligned}
& \mathscr{E}(t, x)=\left|V_{t}(t, x)\right|^{2}+a_{*}(t, x)\left|V_{x}(t, x)\right|^{2}+|V(t, x)|^{2} \\
& E_{1}(t)=\int_{\{x: \gamma(x)>t\}} e^{\theta_{1} t \mathscr{E}(t, x) d x} \\
& E_{2}(t)=e^{-\beta_{2} t} \iint_{G(t)} e^{\theta_{2} t^{\prime}}\left|V\left(t^{\prime}, x\right)\right|^{2} d x d t^{\prime}
\end{aligned}
$$

The following results have been proved in [17], Lemmas 5.1 and 5.2.
Lemma 4.1 Let $V(t, x)$ be a solution of (4.1), (4.2) and assume Hypothesis 1. Then there is a $\theta_{1,0} \in \mathbb{R}$,

$$
\begin{equation*}
\theta_{1,0}=- \text { const. }\left(1+\alpha+L+\sup _{[0, \tau]}\left\|\partial_{x}^{2} a_{*}(t, \cdot)\right\|_{L^{\infty}}+\left\|C_{*}(t, \cdot)\right\|_{L^{\infty}\left(B_{R}\right)}\right), \tag{4.4}
\end{equation*}
$$

such that if we define $E_{1}(t)$ with $\theta_{1} \leq \theta_{1,0}$, the following estimate holds:

$$
\begin{align*}
& E_{1}(t)+\frac{1}{2} \int_{\{x: 0<\gamma(x) \leq t\}} e^{\theta_{1} \gamma(x)} \mathscr{E}(\gamma(x), x) d x  \tag{4.5}\\
& \quad \leq E_{1}(0)+\iint_{D(t)} e^{\theta_{1} t^{\prime}}\left|F\left(t^{\prime}, x\right)\right|^{2} d x d t^{\prime}, \quad 0 \leq t \leq \tau .
\end{align*}
$$

Lemma 4.2 Let $V(t, x)$ be a solution of (4.1), (4.2) and assume Hypothesis 1. Then there is a $\theta_{2,0}$,

$$
\begin{equation*}
\theta_{2,0}=\text { const. }\left(\alpha+L+\sup _{[0, \tau]}\left\|\partial_{x}^{2} a_{*}(t, \cdot)\right\|_{L^{\infty}}\right), \tag{4.6}
\end{equation*}
$$

such that if we define $E_{2}(t)$ with $\theta_{2} \geq \theta_{2,0}$, there is a $\beta_{2,0}>0$,

$$
\begin{align*}
\beta_{2,0}= & \operatorname{const} .\left(1+\tau^{2}\right)  \tag{4.7}\\
& \times \sup _{[0, \tau]}\left(1+\theta_{2}^{2}+L+\left\|\partial_{x}^{2} a_{*}(t, \cdot)\right\|_{L^{\infty}}\right. \\
& \left.+\left\|B_{*}(t, \cdot)\right\|_{C^{1}}+\left\|C_{*}(t, \cdot)\right\|_{L^{\infty}\left(B_{R}\right)}\right),
\end{align*}
$$

such that for $\beta_{2} \geq \beta_{2,0}$ and $t \in[0, \tau]$ we have

$$
\begin{aligned}
E_{2}(t) \leq & \int_{0}^{t} e^{-\beta_{2} s} \int_{\{x: 0<\gamma(x)<s\}} e^{\theta_{2} \gamma(x)} \mathscr{E}(\gamma(x), x) d x d s \\
& +\int_{0}^{t} e^{-\beta_{2} s} \iint_{G(s)} e^{\theta_{2} t^{\prime}}\left|F\left(t^{\prime}, x\right)\right|^{2} d x d t^{\prime} d s \\
& +\frac{1-e^{-\beta_{2} t}}{\beta_{2}} \int_{\{x: \gamma(x) \leq 0\}}|V(0, x)|^{2}+\left|V_{t}(0, x)\right|^{2} d x .
\end{aligned}
$$

Moreover, almost everywhere in $[0, \tau]$ we have

$$
\begin{align*}
& \int_{\{x: \gamma(x)<t\}} e^{\theta_{2} t}|V(t, x)|^{2} d x \leq \beta_{2} e^{\beta_{2} t} E_{2}(t)  \tag{4.8}\\
& \quad+\int_{\{x: 0<\gamma(x)<t\}} e^{\theta_{2} \gamma(x)} \mathscr{E}(\gamma(x), x) d x \\
& \quad+\int_{\{x: \gamma(x) \leq 0\}}|V(0, x)|^{2}+\left|V_{t}(0, x)\right|^{2} d x
\end{align*}
$$

$$
+\iint_{G(t)} e^{\theta_{2} t^{\prime}}\left|F\left(t^{\prime}, x\right)\right|^{2} d x d t^{\prime}
$$

Remark 4.3 The above two estimates have been proved in [17] in case of

$$
a_{*}(t, x)=a_{0}(t, x)(\phi(x) g(t, x)+\psi(x) h(t, x))^{2 q}, \quad q \in \mathbb{N}_{+}
$$

where $a_{0} \geq \delta>0$ is some $C^{2}$ function. However, in the proofs of Lemmas 5.1 and 5.2 in [17] this special form of the coefficient $a_{*}$ was never used. Actually, it suffices to assume that $a_{*}$ admits a separating curve in the sense of Proposition 3.1.

Now we are in a position to estimate the $L^{2}\left(B_{R}\right)$ norm of $V(t, x)$.
Proposition 4.4 Let $V=V(t, x)$ with $\partial_{t}^{j} V \in L^{\infty}\left(\left[t_{0}, \tau\right], H^{2-j}\left(B_{R}\right)\right)$, $j=0,1,2$, be a solution of (4.2), (4.3) and assume that Hypothesis 1 holds. Then there is a constant $C_{0}$ such that for all $t \in\left[t_{0}, \tau\right]$ we have

$$
\begin{align*}
& \|V(t, \cdot)\|_{L^{2}\left(B_{R}\right)}^{2}  \tag{4.9}\\
& \leq C_{0}\left(\left\|V_{0}(\cdot)\right\|_{H^{1}\left(B_{R}\right)}^{2}+\left\|V_{1}(\cdot)\right\|_{L^{2}\left(B_{R}\right)}^{2}+\int_{t_{0}}^{t}\|F(s, \cdot)\|_{L^{2}\left(B_{R}\right)}^{2} d s\right) .
\end{align*}
$$

The constant $C_{0}$ depends only on $\tau, \alpha, L$, and the norms $\sup _{[0, \tau]}\left\|a_{*}(t, \cdot)\right\|_{C^{2}\left(B_{R}\right)}, \sup _{[0, \tau]}\left\|B_{*}(t, \cdot)\right\|_{C^{1}\left(B_{R}\right)},\left\|C_{*}(\cdot, \cdot)\right\|_{L^{\infty}\left([0, \tau] \times B_{R}\right)}$.
Proof. Assume for a moment that $t_{0}=0$. If $x \in B_{R} \backslash \Omega_{\phi \psi}$, the Cauchy problem (4.2) degenerates into

$$
\partial_{t}^{2} V-C_{*}(t, x) V=F(t, x),
$$

which directly leads to an estimate of $\|V\|_{L^{2}\left(B_{R} \backslash \Omega_{\phi \psi}\right)}$ in terms of $\left\|V_{0}\right\|_{L^{2}\left(B_{R} \backslash \Omega_{\phi \psi}\right)},\left\|V_{1}\right\|_{L^{2}\left(B_{R} \backslash \Omega_{\phi \psi}\right)}$, and $\|F(s, \cdot)\|_{L^{2}\left(B_{R} \backslash \Omega_{\phi \psi}\right)}$. Therefore we may restrict ourselves to the case $x \in \Omega_{\phi \psi}$. Then we can apply the Lemmas 4.1 and 4.2. We set $\theta_{1}=\theta_{1,0}, \theta_{2}=\theta_{2,0}$, and $\beta_{2}=\beta_{2,0}\left(\theta_{2}\right)$. Let $t \in[0, \tau]$ be a number such that (4.8) holds. By Sard's Lemma, the set of all $t$ with

$$
\operatorname{meas}\left\{x \in \Omega_{\phi \psi}: \gamma(x)=t\right\}>0
$$

has Lebesgue measure 0 . Assume that $t$ is not from that set. Then we have

$$
\int_{\Omega_{\phi \psi}}|V(t, x)|^{2} d x
$$

$$
\begin{aligned}
= & \int_{\{x: \gamma(x)>t\}}|V(t, x)|^{2} d x+\int_{\{x: \gamma(x)<t\}}|V(t, x)|^{2} d x \\
\leq & e^{-\theta_{1} t} E_{1}(t)+\beta_{2} e^{\left(\beta_{2}-\theta_{2}\right) t} E_{2}(t) \\
& +e^{-\theta_{2} t} \int_{\{x: 0<\gamma(x)<t\}} e^{\theta_{2} \gamma(x)} \mathscr{E}(\gamma(x), x) d x \\
& +e^{-\theta_{2} t}\left(\left\|V_{0}(\cdot)\right\|_{L^{2}\left(\Omega_{\phi \psi}\right)}^{2}+\left\|V_{1}(\cdot)\right\|_{L^{2}\left(\Omega_{\phi \psi}\right)}^{2}\right) \\
& +e^{-\theta_{2} t} \iint_{G(t)} e^{\theta_{2} t^{\prime}}\left|F\left(t^{\prime}, x\right)\right|^{2} d x d t^{\prime},
\end{aligned}
$$

due to Lemmas 4.1 and 4.2. Applying these lemmas once more, we get

$$
\begin{aligned}
& \|V(t, \cdot)\|_{L^{2}\left(\Omega_{\phi \psi}\right)}^{2} \\
& \leq C_{0}\left(\left\|V_{0}(\cdot)\right\|_{H^{1}\left(\Omega_{\phi \psi}\right)}^{2}+\left\|V_{1}(\cdot)\right\|_{L^{2}\left(\Omega_{\phi \psi}\right)}^{2}+\int_{0}^{t}\|F(s, \cdot)\|_{L^{2}\left(\Omega_{\phi \psi}\right)}^{2} d s\right) .
\end{aligned}
$$

This gives us the desired estimate for a.e. $t \in[0, \tau]$. Since $\partial_{t} V$ belongs to the space $L^{\infty}\left([0, \tau], H^{1}\left(B_{R}\right)\right)$, we have shown (4.9) for all values of $t$.

Now let $t_{0}>0$. We set $\tilde{V}(t, x)=V\left(t+t_{0}, x\right)$. Since Hypothesis 1 is invariant under the translation $t \mapsto t+t_{0}$, we get from (4.9) an estimate for $\tilde{V}(t, x)$.
Remark 4.5 Consider (2.6) and suppose $\left\|\partial_{x}^{2} U(t, \cdot)\right\|_{L^{\infty}} \leq C$, uniformly in $\lambda$. Then $C_{0}=C_{0}(\lambda) \leq \exp \left(C\left(1+\tau(\lambda)^{3}\right)\right)$, for all $\lambda$, see Remark 3.5 and (4.4), (4.6), (4.7).

By standard arguments, we can estimate derivatives $\partial_{x}^{k} V(t, x)$.
Proposition 4.6 Let $\varepsilon, \tau$ be determined as in Proposition 3.1, and suppose that $U$ satisfies $(2.10)_{\tau}$. Let $k \in \mathbb{N}$, and $V$ with $\partial_{t}^{j} V \in L^{\infty}\left(\left[t_{0}, \tau\right]\right.$, $\left.H^{k+2-j}\left(B_{R}\right)\right), j=0,1,2$, be a solution to (2.7), (2.9). Then the estimate

$$
\begin{align*}
& \|V(t, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2} \leq C_{k}\left(1+\sup _{\left[t_{0}, t\right]}\|U(s, \cdot)\|_{H^{k+2}\left(B_{R}\right)}^{2}\right)  \tag{4.10}\\
& \times\left(\left\|V_{0}(\cdot)\right\|_{H^{k+1}\left(B_{R}\right)}^{2}+\left\|V_{1}(\cdot)\right\|_{H^{k}\left(B_{R}\right)}^{2}+\int_{t_{0}}^{t}\|F(s, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2} d s\right)
\end{align*}
$$

holds for $0 \leq t_{0} \leq t \leq \tau$, where $C_{k}$ depends only on $\tau, \alpha$, $L$, and the norms

$$
\begin{aligned}
& \sup _{[0, \tau]}\|U(t, \cdot)\|_{H^{3}\left(B_{R}\right)}, \quad\|A(\cdot, \cdot)\|_{C^{k+2}\left(B_{R} \times[1-\varepsilon, 1+\varepsilon] \times[\tau-\varepsilon, \tau+\varepsilon]\right)}, \\
& \|B(\cdot, \cdot)\|_{C^{k}\left(B_{R} \times[1-\varepsilon, 1+\varepsilon] \times[\tau-\varepsilon, \tau+\varepsilon]\right)},
\end{aligned}
$$

$$
\|C(\cdot, \cdot)\|_{C^{k}\left(B_{R} \times[1-\varepsilon, 1+\varepsilon] \times[\tau-\varepsilon, \tau+\varepsilon)\right.} .
$$

Proof. The estimate (4.10) holds for $k=0$, see Proposition 4.4. Assume that (4.10) is true for $k$ replaced by $k-1$. We set $V^{k}(t, x)=\partial_{x}^{k} V(t, x)$ and obtain

$$
\begin{aligned}
& \partial_{t}^{2} V^{k}-A(x, U) \partial_{x}^{2} V^{k}-\left((k+1)\left(\partial_{x} A(x, U(t, x))\right)+B(x, U)\right) \partial_{x} V^{k} \\
&-\left(\frac{k(k+1)}{2}\left(\partial_{x}^{2} A(x, U(t, x))\right)+k\left(\partial_{x} B(x, U(t, x))\right)+C(x, U)\right) V^{k} \\
&= F^{k}=\partial_{x}^{k} F+I_{1}+I_{2}+I_{3}+I_{4} \\
&= \partial_{x}^{k} F+\sum_{l=3}^{k}\binom{k}{l}\left(\partial_{x}^{l} A(x, U(t, x))\right) V^{k+2-l} \\
&+\sum_{l=2}^{k}\binom{k}{l}\left(\partial_{x}^{l+1} A(x, U(t, x))\right) V^{k+1-l} \\
&+\sum_{l=2}^{k}\binom{k}{l}\left(\partial_{x}^{l} B(x, U(t, x))\right) V^{k+1-l} \\
&+\sum_{l=1}^{k}\binom{k}{l}\left(\partial_{x}^{l} C(x, U(t, x))\right) V^{k-l} .
\end{aligned}
$$

By Proposition 4.4, we deduce that

$$
\begin{aligned}
& \left\|V^{k}(t, \cdot)\right\|_{L^{2}}^{2} \\
& \leq C_{0}\left(\left\|V_{0}(\cdot)\right\|_{H^{k+1}}^{2}+\left\|V_{1}(\cdot)\right\|_{H^{k}}^{2}+\int_{t_{0}}^{t}\left\|F^{k}(s, \cdot)\right\|_{L^{2}}^{2} d s\right) .
\end{aligned}
$$

For the estimate of $I_{1}$ and $I_{2}$, we have to consider terms of the form $\left(\partial_{x}^{m} A\right) V^{k+2-m}$ with $m=3, \ldots, k+1$. From Lemma 10.1 and Sobolev's embedding theorem,

$$
\begin{aligned}
& \left\|\left(\partial_{x}^{m} A(\cdot, U(t, \cdot))\right) V^{k+2-m}(t, \cdot)\right\|_{L^{2}} \\
& \leq\left\|\partial_{x}^{m} A(\cdot, U(t, \cdot))\right\|_{L^{\infty}}\left\|V^{k+2-m}(t, \cdot)\right\|_{L^{2}} \\
& \leq C\left(\|U(t, \cdot)\|_{L^{\infty}}\right)\left(1+\|U(t, \cdot)\|_{H^{m+1}}\right)\|V(t, \cdot)\|_{H^{k+2-m}},
\end{aligned}
$$

Similarly, we get

$$
I_{3}+I_{4} \leq C\left(\|U(t, \cdot)\|_{C^{2}}\right)\|V(t, \cdot)\|_{H^{k-1}}
$$

$$
+C\left(\|U(t, \cdot)\|_{L^{\infty}}\right) \sum_{m=3}^{k}\left(1+\|U(t, \cdot)\|_{H^{m+1}}\right)\|V(t, \cdot)\|_{H^{k+1-m}}
$$

Then it follows that

$$
\begin{aligned}
& \|V(t, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2} \leq C_{0}\left(\left\|V_{0}(\cdot)\right\|_{H^{k+1}}^{2}+\left\|V_{1}(\cdot)\right\|_{H^{k}}^{2}\right) \\
& \quad+C_{0} \int_{t_{0}}^{t}\|F(s, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2}+\|V(s, \cdot)\|_{H^{k-1}\left(B_{R}\right)}^{2} d s \\
& \quad+C\left(\sup _{\left[t_{0}, t\right]}\|U(s, \cdot)\|_{C^{2}\left(B_{R}\right)}\right) \\
& \quad \times \sum_{m=3}^{k+1} \sup _{\left[t_{0}, t\right]}\left(1+\|U(s, \cdot)\|_{H^{m+1}\left(B_{R}\right)}^{2}\right) \int_{t_{0}}^{t}\|V(s, \cdot)\|_{H^{k+2-m}\left(B_{R}\right)}^{2} d s
\end{aligned}
$$

From the induction assumption,

$$
\begin{aligned}
& \sup _{\left[t_{0}, t\right]}\|U(s, \cdot)\|_{H^{m+1}\left(B_{R}\right)}^{2} \int_{t_{0}}^{t}\|V(s, \cdot)\|_{H^{k+2-m}\left(B_{R}\right)}^{2} d s \\
& \leq C_{k} \sup _{\left[t_{0}, t\right]}\|U(s, \cdot)\|_{H^{m+1}\left(B_{R}\right)}^{2}\left(1+\sup _{\left[t_{0}, t\right]}\|U(s, \cdot)\|_{H^{k+4-m}\left(B_{R}\right)}^{2}\right) \\
& \times\left(\left\|V_{0}(\cdot)\right\|_{H^{k}\left(B_{R}\right)}^{2}+\left\|V_{1}(\cdot)\right\|_{H^{k-1}\left(B_{R}\right)}^{2}+\int_{t_{0}}^{t}\|F(s, \cdot)\|_{H^{k-1}\left(B_{R}\right)}^{2} d s\right) .
\end{aligned}
$$

By Nirenberg-Gagliardo interpolation,

$$
\begin{aligned}
& \|U(s, \cdot)\|_{H^{m+1}\left(B_{R}\right)} \\
& \quad \leq C\|U(s, \cdot)\|_{H^{k+2}\left(B_{R}\right)}^{(m-2) /(k-1)}\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}^{1-(m-2) /(k-1)}, \\
& \|U(s, \cdot)\|_{H^{k+4-m}\left(B_{R}\right)} \\
& \quad \leq C\|U(s, \cdot)\|_{H^{k+2}\left(B_{R}\right)}^{(k+1-m) /(k-1)}\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}^{1-(k+1-m) /(k-1)},
\end{aligned}
$$

for $k \geq 2$. This completes the proof.

## 5. Existence of solutions to (2.7)

Proposition 5.1 Let $a=a(s)$ satisfy Condition 2, and let $\phi, \psi \in C_{0}^{\infty}(\mathbb{R})$ be to a(s) compatible data, i.e., $\|\phi\|_{L^{\infty}}<M$. Assume $\operatorname{supp}(\phi, \psi) \subset B_{R}=$ $\{|x|<R\}$. Choose $\varepsilon, \tau$ as in Proposition 3.1, and suppose that $U \in$ $C^{2}\left([0, \tau], C_{b}^{\infty}\left(B_{R}\right)\right)$ satisfies $(2.10)_{\tau}$. Finally, assume that
$F \in C\left(\left[t_{0}, \tau\right], C_{b}^{\infty}\left(B_{R}\right)\right), V_{0}, V_{1} \in C_{b}^{\infty}\left(B_{R}\right)$. Then the problem (2.7), (2.9) has a unique solution $V \in C^{2}\left(\left[t_{0}, \tau\right], C_{b}^{\infty}\left(B_{R}\right)\right)$.

Remark 5.2 Fix $0<R^{\prime}<R$ with $\operatorname{supp}(\phi, \psi) \subset B_{R^{\prime}}$. Then the functions $A(x, U), B(x, U), C(x, U)$ vanish for $R^{\prime} \leq|x| \leq R$; and the existence of a solution $V \in C^{2}\left(\left[t_{0}, \tau\right], C_{b}^{\infty}\left(\left\{R^{\prime} \leq|x| \leq R\right\}\right)\right)$ is clear. Hence, we assume in the sequel $|x| \leq R^{\prime}$.

The proof of Proposition 5.1 is based on an approximation argument.
Definition 5.3 Let $\varrho=\varrho(s)$ be an even function from the Gevrey space $G_{0}^{d}(\mathbb{R})$,

$$
\left|\partial_{s}^{k} \varrho(s)\right| \leq C^{k+1} k!^{d}, \quad k \in \mathbb{N}, \quad s \in \mathbb{R}, \quad 1<d<2
$$

and $\operatorname{supp} \varrho \subset(-1,1)$. Additionally, suppose that $s \varrho^{\prime}(s) \leq 0 \leq \varrho(s)$, $\int_{-\infty}^{\infty} \varrho(s) d s=1$, and write $\varrho_{m}(s)=m \varrho(m s)$ for $1 \ll m \in \mathbb{R}$. Then we define for large $m$

$$
\begin{aligned}
& a_{0, m}(s)=\left(a_{0} * \varrho_{m}\right)(s), \quad a_{m}(s)=s^{2} a_{0, m}(s), \quad a_{1, m}(s)=a_{m}^{\prime}(s) / s, \\
& \phi_{m}(x)=\left(\phi * \varrho_{m}\right)(x), \quad \psi_{m}(x)=\left(\psi * \varrho_{m}\right)(x) \\
& U_{m}(t, x)=\left(U * \varrho_{m}\right)(t, x), \quad F_{m}(t, x)=\left(F * \varrho_{m}\right)(t, x) \\
& V_{0, m}(x)=\left(V_{0} * \varrho_{m}\right)(x), \quad V_{1, m}(x)=\left(V_{1} * \varrho_{m}\right)(x)
\end{aligned}
$$

where $*$ denotes the usual convolution.
Lemma 5.4 Replace the interval $\overline{B_{M}}=[-M, M]$ of Condition 1 by some shrinked interval $\left[-M^{\prime}, M^{\prime}\right], 0<M^{\prime}<M$. If $m$ is large enough, then the coefficient $a_{m}(s)$ satisfies Condition 1 with $C_{a}$ replaced by $C_{a}+3$.

Proof. Suppose that $m$ is so large that $a_{m}(s)$ is well defined on $\left[-M^{\prime}, M^{\prime}\right]$. The properties of the convolution imply $0<a_{0, m}(s) \leq C_{a}$ for all $|s| \leq M^{\prime}$. We have

$$
0 \leq s \int a_{0}^{\prime}(s-r) m \varrho(m r) d r=s \partial_{s} a_{0, m}(s)
$$

since $a_{0}$ and $\varrho$ are even functions. From $r \varrho^{\prime}(m r) \leq 0$ we deduce that

$$
\begin{aligned}
& s \partial_{s} a_{0, m}(s)=s \int a_{0}^{\prime}(s-r) m \varrho(m r) d r \\
& =s \int a_{0}(s-r) m^{2} \varrho^{\prime}(m r) d r \leq \int(s-r) a_{0}(s-r) m^{2} \varrho^{\prime}(m r) d r
\end{aligned}
$$

$$
=\int\left(a_{0}(s-r)+(s-r) a_{0}^{\prime}(s-r)\right) m \varrho(m r) d r \leq\left(C_{a}+1\right) a_{0, m}(s)
$$

Clearly, $0 \leq s a_{m}^{\prime}(s) \leq\left(C_{a}+3\right) a_{m}(s)$. This completes the proof.
Proof of Proposition 5.1. We consider the linear system

$$
\begin{align*}
& \partial_{t}^{2} V_{m}-\partial_{x}\left(A_{m}\left(x, U_{m}\right) \partial_{x} V_{m}\right)-B_{m}\left(x, U_{m}\right) \partial_{x} V_{m}  \tag{5.1}\\
&-C_{m}\left(x, U_{m}\right) V_{m}=F_{m}(t, x) \\
& V_{m}(0, x)=V_{0, m}(x), \quad \partial_{t} V_{m}(0, x)=V_{1, m}(x)
\end{align*}
$$

where $A_{m}, B_{m}, C_{m}$ are defined as in (2.2)-(2.4) with $a(s)$ replaced by $a_{m}(s)$. According to [16], the problem (5.1) has a unique solution $V_{m} \in$ $C^{2}\left(\left[t_{0}, \tau\right], G^{d}\left(B_{R^{\prime}}\right)\right)$. Similarly to Section 4, we set

$$
\begin{aligned}
& a_{*, m}(t, x)=a_{m}\left(\phi_{m}(x) g_{m}(t, x)+\psi_{m}(x) h_{m}(t, x)\right), \\
& B_{*, m}(t, x)=B_{m}\left(x, U_{m}(t, x)\right)+\partial_{x} a_{*, m}(t, x) I \\
& C_{*, m}(t, x)=C_{m}\left(x, U_{m}(t, x)\right)
\end{aligned}
$$

Obviously, $a_{*, m} \rightarrow a_{*}, B_{*, m} \rightarrow B_{*}, C_{*, m} \rightarrow C_{*}$ in the topology of the space $C\left(\left[t_{0}, \tau\right], C_{b}^{\infty}\left(B_{R^{\prime}}\right)\right)$. Due to Proposition 4.6, we have uniform estimates

$$
\sup _{\left[t_{0}, \tau\right]}\left\|V_{m}(t, \cdot)\right\|_{H^{k}\left(B_{R^{\prime}}\right)} \leq C_{k}, \quad m \geq m_{0}, \quad k \in \mathbb{N}
$$

Then (5.1) yields $\left\|V_{m}(\cdot, \cdot)\right\|_{C^{2}\left(\left[t_{0}, \tau\right], H^{k}\left(B_{R^{\prime}}\right)\right)} \leq C_{k}$. By the Arzela-Ascoli theorem, there is a subsequence $\left\{V_{m^{\prime}}\right\}$ converging in $C^{1}\left(\left[t_{0}, \tau\right], H^{k-1}\left(B_{R^{\prime}}\right)\right)$ to some limit $V^{(k)}$ which solves (2.7). By Proposition 4.4, solutions to (2.7) are unique. Therefore, $V^{(k)}=V^{(l)}$ for all $k, l$; hence we have a solution $V \in C^{2}\left(\left[t_{0}, \tau\right], C_{b}^{\infty}\left(B_{R^{\prime}}\right)\right)$.

## 6. Existence of solutions to (2.5)

Now we prove the existence of $C^{\infty}$ solutions $U$ to (2.5) for small times. In the next section, more attention will be paid to a better description of the life span of this solution. We shall show that, under suitable assumptions, a solution $U$ to (2.5) can be extended to some longer interval. Therefore, we now discuss the equation (2.5) with slightly more general initial conditions.

Define $A, B, C$ as in (2.2)-(2.4), and consider the Cauchy problem

$$
\begin{align*}
& \partial_{t}^{2} U-\partial_{x}\left(A(x, U) \partial_{x} U\right)-B(x, U) \partial_{x} U-C(x, U) U=0  \tag{6.1}\\
& U\left(t_{0}, x\right)=U_{0}(x), \quad U_{t}\left(t_{0}, x\right)=U_{1}(x)
\end{align*}
$$

$$
\begin{equation*}
\left\|U_{0}(\cdot)-\left(1, t_{0}\right)^{T}\right\|_{C^{1}\left(B_{R}\right)}<\varepsilon_{0}, \quad\left\|U_{1}(\cdot)-(0,1)^{T}\right\|_{L^{\infty}\left(B_{R}\right)}<\varepsilon_{0}, \tag{6.2}
\end{equation*}
$$

Proposition 6.1 Let $a=a(s)$ satisfy Condition 2, and let $(\phi, \psi) \in$ $C_{0}^{\infty}(\mathbb{R})$ with $\operatorname{supp}(\phi, \psi) \subset B_{R}$ be to a(s) compatible data, i.e., $\|\phi\|_{L^{\infty}}<$ $M$.

Then there is an $\varepsilon_{0}$, depending only on $M, C_{a},\|\phi\|_{C^{1}\left(B_{R}\right)},\|\psi\|_{C^{1}\left(B_{R}\right)}$, such that:

For every $U_{0}, U_{1} \in C_{b}^{\infty}\left(B_{R}\right)$ with (6.2) there is some $T_{1}>t_{0}$ and a unique local solution $U \in C_{b}^{\infty}\left(\left[t_{0}, T_{1}\right] \times B_{R}\right)$ to the Cauchy problem (6.1).

The proof bases on the Nash-Moser-Hamilton theory. We recall the main results of that theory and refer the reader to [12] for the details.

## Definition 6.2

(a) A graded (Fréchet) space $E$ is a Fréchet space whose topology is induced by a grading, that is a sequence of seminorms $\left\{\|\cdot\|_{n}: n \in \mathbb{N}\right\}$ such that $\|e\|_{n} \leq\|e\|_{n+1}$ for all $e \in E$ and all $n \in \mathbb{N}$.
(b) A tame linear map is a linear map $L \in L\left(E_{1}, E_{2}\right)$ between two graded spaces $E_{1}, E_{2}$ such that constants $r, b \in \mathbb{N}$ exist with

$$
\|L e\|_{E_{2}, n} \leq C_{n}\|e\|_{E_{1}, n+r}, \quad e \in E_{1}, \quad n \geq b
$$

where the $C_{n}$ do not depend on $e \in E_{1}$.
(c) For a Banach space $B$, we define the graded space $\sum(B)$ of exponentially decreasing sequences by

$$
\sum(B)=\left\{\left\{v_{k}\right\}_{k=0}^{\infty}: v_{k} \in B,\left\|\left\{v_{k}\right\}\right\|_{n}=\sum_{k=0}^{\infty} e^{n k}\left\|v_{k}\right\|_{B}<\infty, n \in \mathbb{N}\right\} .
$$

(d) The graded space $E$ is a tame space if some Banach space $B$ and linear tame maps $L_{1} \in L\left(E, \sum(B)\right), L_{2} \in L\left(\sum(B), E\right)$ exist with the property that $L_{2} L_{1}$ is the identity on $E$.

Example 6.3 Spaces of $C_{b}^{\infty}$ functions on smooth compact manifolds $X$ (with or without boundary) are tame (see [12], pp. 135-138), when we define the seminorms $\|v\|_{n}=\|v(\cdot)\|_{W_{p}^{n}(X)}, 1 \leq p \leq \infty$.
Definition 6.4 Let $P: \mathscr{M} \subset E_{1} \rightarrow E_{2}$ be a (nonlinear) mapping between the graded spaces $E_{1}, E_{2}$, and be defined on the open set $\mathscr{M}$. The map $P$ is called tame if for each point $e^{*} \in \mathscr{M}$ there is a neighbourhood $e^{*} \in \Omega \subset \mathscr{M}$
and constants $r, b \in \mathbb{N}$ such that

$$
\|P(e)\|_{E_{2}, n} \leq C_{n}\left(1+\|e\|_{E_{1}, n+r}\right), \quad e \in \Omega, \quad n \geq b
$$

Remark 6.5 A map is a tame linear map if and only if it is linear and tame.

Definition 6.6 Let $P: \mathscr{M} \subset E_{1} \rightarrow E_{2}$ be a tame map. Then, $P$ is called smooth tame if it is $C^{\infty}$ and $D^{n} P$ is tame for all $n \in \mathbb{N}$.

Example 6.7 Nonlinear partial differential operators acting on the tame space $C_{b}^{\infty}(X)$ are smooth tame. Sums and compositions of smooth tame maps are smooth tame (see [12], p. 146).

The following implicit function theorem is the crucial tool in the following.

Theorem 6.8 (Nash-Moser-Hamilton) Let $E_{1}, E_{2}$ be tame spaces, $\mathscr{M} \subset E_{1}$ be an open set, and $P: \mathscr{M} \subset E_{1} \rightarrow E_{2}$ be a smooth tame map. Suppose that the derivative $D P(u) \in L\left(E_{1}, E_{2}\right)$ has a right inverse $V P(u) \in L\left(E_{2}, E_{1}\right)$ for each $u \in \mathscr{M}$, which is smooth tame as a mapping $V P(u): \mathscr{M} \times E_{2} \rightarrow E_{1}$. Then $P$ is in $\mathscr{M}$ locally invertible, and each inverse is smooth tame.

Proof of Proposition 6.1. We show $U \in C^{2}\left(\left[t_{0}, T_{1}\right], C_{b}^{\infty}\left(B_{R}\right)\right)$. The smoothness in time then follows from (2.5). We fix the tame spaces

$$
\begin{aligned}
& E_{1}=\left(C^{2}\left(\left[t_{0}, T\right], C_{b}^{\infty}\left(B_{R}\right)\right)\right)^{2}, \\
& E_{2}=\left(C\left(\left[t_{0}, T\right], C_{b}^{\infty}\left(B_{R}\right)\right)\right)^{2} \times\left(C_{b}^{\infty}\left(B_{R}\right)\right)^{2} \times\left(C_{b}^{\infty}\left(B_{R}\right)\right)^{2}, \\
& \|e\|_{E_{1}, n} \\
& =\sup _{\left[t_{0}, T\right]}\left(\|e(t, \cdot)\|_{H^{n}\left(B_{R}\right)}+\left\|e_{t}(t, \cdot)\right\|_{H^{n}\left(B_{R}\right)}+\left\|e_{t t}(t, \cdot)\right\|_{H^{n}\left(B_{R}\right)}\right), \\
& \left\|\left(e_{I}, e_{I I}, e_{I I I}\right)\right\|_{E_{2}, n} \\
& =\sup _{\left[t_{0}, T\right]}\left\|e_{I}(t, \cdot)\right\|_{H^{n}\left(B_{R}\right)}+\left\|e_{I I}(\cdot)\right\|_{H^{n}\left(B_{R}\right)}+\left\|e_{I I I}(\cdot)\right\|_{H^{n}\left(B_{R}\right)},
\end{aligned}
$$

where $T$ with $0<T-t_{0} \ll 1$ will be chosen later. The map $P: E_{1} \rightarrow E_{2}$ is

$$
\begin{array}{r}
P(U)=\left(\partial_{t}^{2} U-\partial_{x}\left(A(x, U) \partial_{x} U\right)-B(x, U) \partial_{x} U-C(x, U) U,\right. \\
\left.U\left(t_{0}, x\right)-U_{0}(x), U_{t}\left(t_{0}, x\right)-U_{1}(x)\right),
\end{array}
$$

which is a smooth tame map. To fix the open set $\mathscr{M}$, we introduce

$$
\begin{aligned}
& U_{*}(t, x)=U_{0}(x)+\left(t-t_{0}\right) U_{1}(x)+\frac{1}{2}\left(t-t_{0}\right)^{2} \partial_{x}\left(A\left(x, U_{0}(x)\right) U_{0, x}(x)\right) \\
& \quad+\frac{1}{2}\left(t-t_{0}\right)^{2} B\left(x, U_{0}(x)\right) U_{0, x}(x)+\frac{1}{2}\left(t-t_{0}\right)^{2} C\left(x, U_{0}(x)\right) U_{0}(x),
\end{aligned}
$$

and define

$$
\mathscr{M}=\left\{U \in E_{1}:\left\|U-U_{*}\right\|_{C^{1}\left(\left[t_{0}, T\right] \times B_{R}\right)}<\varepsilon_{0},\right.
$$

with some constant $C>0$. If we fix $\varepsilon_{0}=\varepsilon / 10$ and choose $T=T(\varepsilon)$ with $0<$ $T-t_{0} \ll 1$ appropriately, then each element of $\mathscr{M}$ can be extended to $[0, T] \times$ $B_{R}$ in such a way that $(2.10)_{T}$ holds, with $\varepsilon$ chosen as in Proposition 3.1. Obviously,

$$
P\left(U_{*}\right)(t, x)=\left(\left(t-t_{0}\right) Z(t, x), 0,0\right)
$$

with some $Z \in C\left(\left[t_{0}, T\right], C_{b}^{\infty}\left(B_{R}\right)\right)$. Choose some function $\chi \in C^{\infty}(\mathbb{R})$ with $\chi(t)=0$ for $t \leq 1$ and $\chi(t)=1$ for $t \geq 2$. Then $\left(\left(t-t_{0}\right) \chi(m(t-\right.$ $\left.\left.\left.t_{0}\right)\right) Z(t, x), 0,0\right)$ converges to $\left(\left(t-t_{0}\right) Z(t, x), 0,0\right)$ in the topology of $E_{2}$ if $m$ tends to infinity. Therefore, every neighbourhood of $P\left(U_{*}\right)$ contains elements of the form $(\tilde{Z}(t, x), 0,0)$ where $\tilde{Z}(t, x)=0$ for $t_{0} \leq t \leq T_{1}$; and $T_{1}-t_{0}>0$ is small. If we are able to show that the image $P(\mathscr{M})$ contains a neighbourhood of $P\left(U_{*}\right)$ in $E_{2}$, then we have proved the existence of a solution $U$ to (2.5) in $\left[t_{0}, T_{1}\right] \times B_{R}$. More precisely, we show that $P$ is locally invertible in the neighbourhood $\mathscr{M}$.

The Fréchet derivative $D P(U)$ is a linear map $V \mapsto\left(F, V_{0}, V_{1}\right)$ with

$$
\begin{aligned}
& F= \partial_{t}^{2} V-\partial_{x}\left(A(x, U) \partial_{x} V\right)-\partial_{x}\left(\left(A_{U}(x, U) V\right) \partial_{x} U\right) \\
& \quad-B(x, U) \partial_{x} V-B_{U}(x, U) V \partial_{x} U-C(x, U) V-C_{U}(x, U) V U \\
& V_{0}(x)=V\left(t_{0}, x\right), \quad V_{1}(x)=V_{t}\left(t_{0}, x\right) .
\end{aligned}
$$

Here we have introduced the notation

$$
A_{U}(x, U) V=a^{\prime}(\phi g+\psi h)(\phi, \psi) V I, \quad U=(g, h)^{T}, \quad V=\left(v_{1}, v_{2}\right)^{T},
$$

where $(\phi, \psi) V=\phi v_{1}+\psi v_{2}$ is the usual $\mathbb{R}^{2}$ scalar product. This Cauchy problem is of the form (2.7); and Hypothesis 1 is satisfied if $U \in \mathscr{M}$. We
note that the Levi condition (b) follows from $\left|a^{\prime}(s)\right|^{2} \leq C_{a}^{3} a(s)$, see (1.5). Then the Propositions 4.6 and 5.1 imply the existence of an inverse map

$$
V P:\left(U, F, V_{0}, V_{1}\right) \mapsto V, \quad \mathscr{M} \times E_{2} \rightarrow E_{1}
$$

which satisfies

$$
\sup _{\left[t_{0}, T\right]}\|V(t, \cdot)\|_{H^{k}\left(B_{R}\right)} \leq C_{k}\left(1+\|U\|_{E_{1}, k+2}\right)\left\|\left(F, V_{0}, V_{1}\right)\right\|_{E_{2}, k}
$$

From the equation (6.3),

$$
\|V\|_{E_{1}, k} \leq C_{k}\left(1+\|U\|_{E_{1}, k+4}\right)\left\|\left(F, V_{0}, V_{1}\right)\right\|_{E_{2}, k+2}
$$

Hence $V P: \mathscr{M} \times E_{2} \rightarrow E_{1}$ is tame, see [12]. The proof is complete if we show that $V P$ is smooth tame. We proceed by induction and only show that $D^{1} V P$ is tame; the higher derivatives $D^{k} V P$ can be considered in the same way. We find that

$$
V^{(1)}=D^{1} V P\left(U, F, V_{0}, V_{1}\right)\left\{\delta U, \delta F, \delta V_{0}, \delta V_{1}\right\}
$$

where $V^{(1)} \in E_{1}$ depends linearly on $\left(\delta U, \delta F, \delta V_{0}, \delta V_{1}\right) \in E_{1} \times E_{2}$ and nonlinearly on $\left(U, F, V_{0}, V_{1}\right) \in \mathscr{M} \times E_{2}$. More precisely,

$$
\begin{aligned}
& \partial_{t}^{2} V^{(1)}-\partial_{x}\left(A(x, U) \partial_{x} V^{(1)}\right)-\partial_{x}\left(\left(A_{U}(x, U) V^{(1)}\right) \partial_{x} U\right) \\
& -B(x, U) \partial_{x} V^{(1)}-B_{U}(x, U) V^{(1)} \partial_{x} U \\
& -C(x, U) V^{(1)}-C_{U}(x, U) V^{(1)} U \\
& =\delta F+R \delta U, \\
& V^{(1)}\left(t_{0}, x\right)=\delta V_{0}(x), \quad V_{t}^{(1)}\left(t_{0}, x\right)=\delta V_{1}(x),
\end{aligned}
$$

where $R$ is a linear differential operator depending on $U$ and $V=$ $V P\left(U, F, V_{0}, V_{1}\right)$. By Proposition 4.6, $D^{1} V P$ is tame. This completes the proof.

## 7. A life span criterion

In this section, we describe the life span of the $C^{\infty}$ solution $U$ to (2.5) mentioned in Proposition 6.1.

Proposition 7.1 Let the assumptions of Proposition 6.1 be satisfied. Then there is a constant $T_{0}>0$ depending only on $M, R,\left\|\left(a_{0}, a_{1}\right)\right\|_{C^{3}\left(B_{M}\right)}$,
$\|(\phi, \psi)\|_{C^{5}\left(B_{R}\right)}$; and there is a unique solution $U \in C_{b}^{\infty}\left(\left[0, T_{0}\right] \times B_{R}\right)$ to (2.5).

The proof is split into the Lemmas 7.2 and 7.5.
Lemma 7.2 Let the assumptions of Proposition 6.1 be satisfied, and let $\varepsilon, \tau$ be the numbers determined in Proposition 3.1. Finally, let $U \in C^{2}\left([0, T), C_{b}^{\infty}\left(B_{R}\right)\right), 0<T<\tau$, be a solution to (2.5) which satisfies (2.10). Then the estimates

$$
\begin{align*}
& \|U(t, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2}  \tag{7.1}\\
& \leq C_{R}\left(1+t^{2}\right) C_{k} \int_{0}^{t} \varrho_{k}\left(\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}\right)\left(1+\|U(s, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2}\right) d s \\
& \sup _{[0, t]}\left\|U(s, \cdot)-(1, s)^{T}\right\|_{H^{3}\left(B_{R}\right)}^{2} \leq t C_{3} \tilde{\varrho}_{3}\left(\sup _{[0, t]}\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}^{2}\right) \tag{7.2}
\end{align*}
$$

hold for $0 \leq t<T$, where $\varrho_{k}, \tilde{\varrho}_{k}: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$are certain continuous and increasing functions, and $C_{k}$ depend on $\left\|\left(a_{0}, a_{1}\right)\right\|_{C^{k}\left(B_{M}\right)},\|(\phi, \psi)\|_{C^{k+2}\left(B_{R}\right)}$, and $R$.

The proof is based on an a priori estimate similar to that of Proposition 4.6 for the Cauchy problem (2.7), but now we take advantage from the fact $U \equiv V$.

Lemma 7.3 Let $m, n \in \mathbb{N}$ with $m \geq 2$, $n \geq 3$, and $X \subset \mathbb{R}$ be a bounded domain. Then

$$
\begin{aligned}
&\|w\|_{C^{m}(X)}\|w\|_{H^{n}(X)} \leq C\|w\|_{H^{3}(X)}\|w\|_{H^{m+n-2}(X)} \\
& w \in H^{m+n-2}(X)
\end{aligned}
$$

Proof. By Sobolev's embedding theorem,

$$
\begin{aligned}
\|w\|_{C^{m}(X)}\|w\|_{H^{n}(X)} & \leq C\|w\|_{H^{m+1}(X)}\|w\|_{H^{n}(X)} \\
& \leq C\|w\|_{H^{3}(X)}\|w\|_{H^{m+n-2}(X)}
\end{aligned}
$$

where we have used the complex interpolation method,

$$
\begin{aligned}
& H^{m+1}(X)=\left[H^{3}(X), H^{m+n-2}(X)\right]_{\theta_{1}} \\
& H^{n}(X)=\left[H^{3}(X), H^{m+n-2}(X)\right]_{\theta_{2}}
\end{aligned}
$$

with $\theta_{1}+\theta_{2}=1$.

Proof of Lemma 7.2. We write (2.5) in the form

$$
\begin{aligned}
& \partial_{t}^{2} U-A(x, U) \partial_{x}^{2} U \\
& \quad-A_{x}(x, U) U_{x}-A_{U}(x, U) U_{x} U_{x}-B(x, U) U_{x}-C(x, U) U=0,
\end{aligned}
$$

where $A_{x}(x, U)=a^{\prime}(\phi g+\psi h)\left(\phi_{x}, \psi_{x}\right) U I$, and $\left(\phi_{x}, \psi_{x}\right) U$ is the $\mathbb{R}^{2}$ scalar product $\phi_{x} g+\psi_{x} h$. Similarly, $A_{U}(x, U) U_{x}=a^{\prime}(\phi g+\psi h)(\phi, \psi) U_{x} I$. We apply $\partial_{x}^{k}$, set $U^{k}=\partial_{x}^{k} U$, and obtain

$$
\begin{aligned}
& \partial_{t}^{2} U^{k}-A(x, U) \partial_{x}^{2} U^{k}-(k+1)\left(\partial_{x} A(x, U)\right) \partial_{x} U^{k} \\
& \quad-A_{U}(x, U)\left(\partial_{x} U^{k}\right) U_{x}-B(x, U) \partial_{x} U^{k} \\
& =F^{k}=I_{1}+I_{2}+I_{3}+I_{4} \\
& =\sum_{l=2}^{k}\binom{k}{l}\left(\partial_{x}^{l} A(x, U)\right) U^{k+2-l} \\
& \quad+\sum_{l=1}^{k}\binom{k}{l}\left(\partial_{x}^{l} A_{x}(x, U)+\partial_{x}^{l} B(x, U)\right) U^{k+1-l} \\
& \quad+\sum_{l+m=0}^{k-1} \frac{k!}{l!m!(k-l-m)!}\left(\partial_{x}^{k-l-m} A_{U}(x, U)\right) U^{l+1} U^{m+1} \\
& \quad+\partial_{x}^{k}(C(x, U) U) .
\end{aligned}
$$

From $U^{k}(0, \cdot)=\left(\partial_{t} U^{k}\right)(0, \cdot)=0$ for $k \geq 1$ and Proposition 4.4,

$$
\left\|U^{k}(t, \cdot)\right\|_{L^{2}\left(B_{R}\right)}^{2} \leq C_{0} \int_{0}^{t}\left\|F^{k}(s, \cdot)\right\|_{L^{2}\left(B_{R}\right)}^{2} d s
$$

We recall that Hypothesis 1 is satisfied because of $\left|a^{\prime}(s)\right|^{2} \leq C_{a}^{3} a(s)$, see (1.5). Employing Lemmas 7.3 and 10.1, we estimate $I_{1}, \ldots, I_{4}$. For $l=2$ in $I_{1}$, we find

$$
\left\|\left(\partial_{x}^{2} A(x, U)\right) U^{k}\right\|_{L^{2}}^{2} \leq C\left(\|a\|_{C^{2}},\|(\phi, \psi)\|_{C^{2}}\right)\left(1+\|U\|_{C^{2}}^{4}\right)\left\|U^{k}\right\|_{L^{2}}^{2} .
$$

For $3 \leq l \leq k$, we have

$$
\begin{aligned}
& \left\|\left(\partial_{x}^{l} A(x, U)\right) U^{k+2-l}\right\|_{L^{2}}^{2} \\
& \leq C\left(\|a\|_{C^{l}},\|U\|_{L^{\infty}},\|(\phi, \psi)\|_{C^{l}}\right)\left(1+\|U\|_{H^{l}}^{2}\right)\|U\|_{C^{k+2-l}}^{2} \\
& \leq C\left(\|a\|_{C^{l}},\|U\|_{L^{\infty}},\|(\phi, \psi)\|_{C^{l}}\right)\left(1+\|U\|_{H^{3}}^{2}\right)\|U\|_{H^{k}}^{2} .
\end{aligned}
$$

The term $I_{2}$ can be discussed similarly. Concerning $I_{3}$, it is enough to
discuss the case $m \leq l$. Suppose $k-1 \geq l+m \geq k-2$ and $l \geq 2(l \leq 1$ is trivial). Then

$$
\begin{aligned}
& \left\|\left(\partial_{x}^{k-l-m} A_{U}(x, U)\right) U^{l+1} U^{m+1}\right\|_{L^{2}}^{2} \\
& \leq C\left(\|a\|_{C^{3}},\|(\phi, \psi)\|_{C^{2}}\right)\left(1+\|U\|_{C^{2}}^{4}\right)\left\|U^{l+1}\right\|_{L^{2}}^{2}\left\|U^{m+1}\right\|_{L^{\infty}}^{2} \\
& \leq C\left(\|a\|_{C^{3}},\|(\phi, \psi)\|_{C^{2}}\right)\left(1+\|U\|_{C^{2}}^{4}\right)\|U\|_{H^{3}}^{2}\|U\|_{H^{k}}^{2}
\end{aligned}
$$

Now let $1 \leq l+m \leq k-3$. Then we have

$$
\begin{aligned}
& \left\|\left(\partial_{x}^{k-l-m} A_{U}(x, U)\right) U^{l+1} U^{m+1}\right\|_{L^{2}}^{2} \\
& \leq C\left(\|a\|_{C^{k}},\|U\|_{L^{\infty}},\|(\phi, \psi)\|_{C^{k}}\right) \\
& \quad \times\left(1+\|U\|_{H^{k-l-m}}^{2}\right)\left\|U^{l+1}\right\|_{L^{\infty}}^{2}\left\|U^{m+1}\right\|_{L^{\infty}}^{2}
\end{aligned}
$$

By Lemma 7.3,

$$
\begin{aligned}
& \|U\|_{H^{k-l-m}}^{2}\left\|U^{l+1}\right\|_{L^{\infty}}^{2}\left\|U^{m+1}\right\|_{L^{\infty}}^{2} \leq C\|U\|_{H^{3}}^{2}\|U\|_{H^{k-m-1}}^{2}\|U\|_{C^{m+1}}^{2} \\
& \leq C\|U\|_{H^{3}}^{4}\|U\|_{H^{k-1}}^{2}
\end{aligned}
$$

In case $l=m=0$ we apply Lemma 10.1 and find

$$
\begin{aligned}
& \left\|\left(\partial_{x}^{k} A_{U}(x, U)\right) U^{1} U^{1}\right\|_{L^{2}}^{2} \\
& \leq C\left(\|a\|_{C^{k+1}},\|U\|_{L^{\infty}},\|(\phi, \psi)\|_{C^{k}}\right)\left(1+\|U\|_{H^{k}}^{2}\right)\|U\|_{C^{1}}^{4}
\end{aligned}
$$

The term $I_{4}$ is left to the reader, see Lemma 10.1. From $a^{\prime}(s)=s a_{1}(s)$ we derive $\|a\|_{C^{k+1}} \leq C\left\|a_{1}\right\|_{C^{k}}$. Then we obtain the estimate

$$
\begin{aligned}
\| \partial_{x}^{k} U(t, \cdot) & \|_{L^{2}\left(B_{R}\right)}^{2} \\
& \leq C_{k} \int_{0}^{t} \varrho_{k}\left(\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}\right)\left(1+\|U(s, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2}\right) d s
\end{aligned}
$$

for $k \geq 1$. Since $\operatorname{supp}(\phi, \psi) \subset B_{R}$, there is some $0<R^{\prime}<R$ such that $\phi(x)=\psi(x)=0$ for $R^{\prime} \leq|x| \leq R$. For such $x$, the Cauchy problem (2.5) degenerates to $\partial_{t}^{2} U=0$; hence $U(t, x)=(1, t)^{T}$. Then Poincaré's inequality implies

$$
\left\|U(t, \cdot)-(1, t)^{T}\right\|_{L^{2}\left(B_{R}\right)}^{2} \leq C_{R}\left\|\partial_{x} U(t, \cdot)\right\|_{L^{2}\left(B_{R}\right)}^{2}
$$

The desired estimates (7.1), (7.2) are then obtained easily.

Remark 7.4 Consider (2.6). Remarks 3.5, 4.5 and Lemma 10.1 give the refinement

$$
\begin{aligned}
& \left\|\partial_{x}^{k} U(t, \cdot)\right\|_{L^{2}\left(B_{R}\right)}^{2} \\
& \qquad \begin{array}{l}
\leq C_{k} e^{C\left(1+\tau^{3}\right)} \\
\quad \int_{0}^{t} \lambda^{2}\left(1+\tau^{k}\right) \\
\quad \times\left(1+\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}^{4}\right)\left(1+\|U(s, \cdot)\|_{H^{k}\left(B_{R}\right)}^{2}\right) d s
\end{array}
\end{aligned}
$$

for $k \geq 1$. From this we conclude that

$$
\begin{align*}
& \sup _{[0, t]}\left\|U(s, \cdot)-(1, s)^{T}\right\|_{H^{3}\left(B_{R}\right)}^{2} \\
& \leq \lambda^{2} t C_{3} e^{C^{\prime}\left(1+\tau^{3}\right)}\left(1+\sup _{[0, t]}\|U(s, \cdot)\|_{H^{3}\left(B_{R}\right)}^{6}\right) \tag{7.3}
\end{align*}
$$

for all $\lambda$ and all $0 \leq t<T$. Obviously,

$$
\begin{aligned}
& \left\|U_{t t}(t, \cdot)\right\|_{L^{\infty}} \\
& \leq\left\|A_{\lambda}(x, U) U_{x}\right\|_{C^{1}}+\left\|B_{\lambda}(x, U) U_{x}\right\|_{L^{\infty}}+\left\|C_{\lambda}(x, U) U\right\|_{L^{\infty}} \\
& \leq C\left\|A_{\lambda}(x, U)\right\|_{H^{2}\left(B_{R}\right)}\left\|\left(U(t, \cdot)-(1, t)^{T}\right)_{x}\right\|_{H^{2}\left(B_{R}\right)} \\
& \quad+\left\|B_{\lambda}(x, U)\right\|_{L^{\infty}}\left\|\left(U(t, \cdot)-(1, t)^{T}\right)_{x}\right\|_{L^{\infty}}+\left\|C_{\lambda}(x, U) U\right\|_{L^{\infty}} \\
& \leq C \lambda\left(1+\|U(t, \cdot)\|_{H^{2}\left(B_{R}\right)}^{3}\right)\left\|U(t, \cdot)-(1, t)^{T}\right\|_{H^{3}\left(B_{R}\right)}+C \lambda(1+\tau)
\end{aligned}
$$

Supposing that the right-hand side of (7.3) were less than 1, we find

$$
\begin{equation*}
\left\|U_{t}(t, \cdot)-(0,1)^{T}\right\|_{L^{\infty}\left(B_{R}\right)} \leq C^{\prime} \lambda \tau\left(1+\tau^{3}\right) \tag{7.4}
\end{equation*}
$$

Lemma 7.5 Let the assumptions of Proposition 6.1 be satisfied. Assume that $U \in C^{2}\left([0, T), C_{b}^{\infty}\left(B_{R}\right)\right), 0<T<\tau$, is a solution to (2.5) which fulfils

$$
\begin{align*}
& \left\|U(t, \cdot)-(1, t)^{T}\right\|_{C_{b}^{1}\left([0, T) \times B_{R}\right)}<\varepsilon_{0}  \tag{7.5}\\
& \sup _{[0, T)}\|U(t, \cdot)\|_{H^{3}\left(B_{R}\right)}<\infty \tag{7.6}
\end{align*}
$$

where $\varepsilon_{0}$ is from Proposition 6.1. Then $U$ can be extended to some function $\tilde{U} \in C^{2}\left(\left[0, T^{\prime}\right], C_{b}^{\infty}\left(B_{R}\right)\right), T<T^{\prime}<\tau$, which solves $(2.5)$ for $(t, x) \in$ $\left[0, T^{\prime}\right] \times B_{R}$.

Proof. According to Lemma 7.2, $\|U(t, \cdot)\|_{H^{k}\left(B_{R}\right)} \leq C_{k}$ for $0 \leq t<T$ and all $k \in \mathbb{N}$. The equation (2.5) then gives $\left\|\partial_{t}^{2} U(t, \cdot)\right\|_{H^{k}\left(B_{R}\right)} \leq C_{k}$ for $0 \leq$
$t<T$ and all $k$. Therefore, $U$ can be smoothly extended in a unique way up to $t=T$. Now we consider the Cauchy problem

$$
\begin{aligned}
& \partial_{t}^{2} W-\partial_{x}\left(A(x, W) \partial_{x} W\right)-B(x, W) \partial_{x} W-C(x, W) W=0 \\
& W(t, x)=U(t, x), \quad W_{t}(t, x)=U_{t}(t, x)
\end{aligned}
$$

By Proposition 6.1, this problem has a solution $W \in C^{2}\left(\left[T, T_{1}\right], C_{b}^{\infty}\left(B_{R}\right)\right)$. We set

$$
\tilde{U}(t, x)=\left\{\begin{array}{l}
U(t, x): 0 \leq t<T \\
W(t, x): T \leq t \leq T_{1}=T^{\prime}
\end{array}\right.
$$

and the proof is complete.
Proof of Proposition 7.1. From Proposition 6.1 we conclude that there is a local solution $U \in C_{b}^{\infty}\left(\left[0, T_{1}\right] \times B_{R}\right)$ to (2.5) which satisfies (7.2). By Lemma 7.5 , this solution can be extended as long as (7.5) and (7.6) are satisfied. A lower estimate $T_{0}>0$ of the life span of $U$ can then be derived from (7.2).

Proof of Theorem 1.5. The problem (1.2) can be transformed into the system (2.5) by means of the reduction presented in Section 2. According to Proposition 7.1, this system has a unique local solution $U \in C_{b}^{\infty}\left(\left[0, T_{0}\right] \times\right.$ $\left.B_{R}\right)$. For $x \notin \operatorname{supp}(\phi, \psi)$, the system $(2.5)$ degenerates into $\partial_{t}^{2} U(t, x)=0$, hence $u(t, x)=0$. Therefore, we have found a solution $u \in C_{b}^{\infty}\left(\left[0, T_{0}\right] \times \mathbb{R}\right)$ to $(2.1)$, which vanishes outside $\left[0, T_{0}\right] \times \operatorname{supp}(\phi, \psi)$. Then the solution $w$ to (1.2) is given by

$$
w(t, x)=\int_{-R}^{x} u(t, y) d y
$$

and it is easy to show that $w$ vanishes outside $\left[0, T_{0}\right] \times \operatorname{supp}(\Phi, \Psi)$.
Proof of Theorem 1.6. For $0<\lambda \ll 1$, choose $\varepsilon(\lambda)=\mathscr{O}\left(\lambda^{1 / 2}\right)$ as in Remark 3.4, and set $\varepsilon_{0}=\varepsilon / 10$, see the proof of Proposition 6.1. Now choose $\tau=\tau(\lambda)$ with

$$
\begin{aligned}
\lambda^{2} \tau C_{3} e^{C^{\prime}\left(1+\tau^{3}\right)}\left(1+\left(\varepsilon_{0}+\|(1, \tau)\right.\right. & \left.\left.\|_{H^{3}\left(B_{R}\right)}\right)^{6}\right) \\
& <C_{\mathrm{sob}}^{-2} \varepsilon_{0}^{2}, \quad C^{\prime} \lambda \tau\left(1+\tau^{3}\right)<\varepsilon_{0}
\end{aligned}
$$

see (7.3), (7.4). Here $C_{\text {sob }}$ is the norm of the embedding $H^{3}\left(B_{R}\right) \subset C^{1}\left(B_{R}\right)$.

Due to Remark 7.4, we then have

$$
\left\|U(t, \cdot)-(1, t)^{T}\right\|_{C^{1}\left(B_{R}\right)}<\varepsilon_{0}, \quad\left\|U_{t}(t, \cdot)-(0,1)^{T}\right\|_{L^{\infty}\left(B_{R}\right)}<\varepsilon_{0}
$$

provided that $t<\tau$. According to Lemma 7.5, the solution $U$ persists in the interval $[0, \tau)$. Finally, $\tau(\lambda)>C|\ln \lambda|^{1 / 3}$.

## 8. The case of non smooth $a(s)$

Proof of Theorem 1.2. We transform (1.2) into the system (2.5), where $A$, $B, C$ are given by $(2.2)-(2.4)$, and $(\phi, \psi)=\left(\Phi_{x}, \Psi_{x}\right) \in C_{0}^{k+1}(\mathbb{R})$. We approximate $a_{0}(s), \phi(x), \psi(x)$ by $a_{0, m}, \phi_{m}, \psi_{m}$ as in Definition 5.3, and obtain uniform estimates

$$
\left\|\left(\phi_{m}, \psi_{m}\right)\right\|_{C^{k+1}}, \quad\left\|a_{0, m}\right\|_{C^{P}\left(B_{M^{\prime}}\right)} \leq C, \quad m \geq m_{0}\left(M^{\prime}\right), \quad M^{\prime}<M
$$

We set $a_{m}(s)=s^{2} a_{0, m}(s), a_{1, m}(s)=a_{m}^{\prime}(s) / s=2 a_{0, m}(s)+s a_{0, m}^{\prime}(s)$. Clearly,

$$
\begin{aligned}
& s a_{0, m}^{\prime}(s)=s \int a_{0}^{\prime}(s-r) m \varrho(m r) d r=\int(s-r) a_{0}^{\prime}(s-r) m \varrho(r m) d r \\
& \quad+\int a_{0}(s-r) m \varrho(r m) d r+\int a_{0}(s-r) r m^{2} \varrho^{\prime}(r m) d r \\
& =I_{1, m}(s)+I_{2, m}(s)+I_{3, m}(s)
\end{aligned}
$$

We see that $\left\|I_{1, m}\right\|_{C^{P}}+\left\|I_{2, m}\right\|_{C^{P}} \leq C\left(\left\|a_{0}\right\|_{C^{P}}+\left\|a_{1}\right\|_{C^{P}}\right)$, since $s a_{0}^{\prime}(s)=$ $a_{1}(s)-2 a_{0}(s)$. Due to $|m r| \leq 1$ on $\operatorname{supp} \varrho^{\prime}(m r)$,

$$
\left|\partial_{s}^{P} I_{3, m}(s)\right| \leq\left\|a_{0}\right\|_{C^{P}} \int\left|m \varrho^{\prime}(m r)\right| d r \leq C\left\|a_{0}\right\|_{C^{P}}
$$

As a consequence, $\left\|a_{1, m}\right\|_{C^{P}} \leq C$ for all $m$.
Now we consider the Cauchy problem

$$
\begin{aligned}
& \partial_{t}^{2} U_{m}-\partial_{x}\left(A_{m}\left(x, U_{m}\right) \partial_{x} U_{m}\right) \\
& \quad-B_{m}\left(x, U_{m}\right) \partial_{x} U_{m}-C_{m}\left(x, U_{m}\right) U_{m}=0 \\
& U_{m}(0, x)=(1,0)^{T}, \quad U_{m, t}(0, x)=(0,1)^{T}
\end{aligned}
$$

where $A_{m}, B_{m}, C_{m}$ are defined as in (2.2)-(2.4), but with $a_{0}, a_{1}, a, \phi, \psi$ replaced by $a_{0, m}, a_{1, m}, a_{m}, \phi_{m}, \psi_{m}$. According to Proposition 7.1, there is a unique local solution $U_{m} \in C_{b}^{\infty}\left(\left[0, T_{0}\right] \times B_{R}\right)$ for large $m$, where $T_{0}$ only depends on $\left\|\left(a_{0, m}, a_{1, m}\right)\right\|_{C^{3}},\left\|\left(\phi_{m}, \psi_{m}\right)\right\|_{C^{5}}$. These norms are uniformly in
$m$ bounded. Taking into account that $k \geq 4$, we apply Lemma 7.2 with $k$ replaced by $k-1$. Then we find

$$
\sup _{\left[0, T_{0}\right]}\left\|U_{m}(t, \cdot)\right\|_{H^{k-1}\left(B_{R}\right)} \leq C<\infty
$$

for all $m \geq m_{0}$. By the differential equation, it can be deduced that $\left\{U_{m}\right\}$ is a bounded sequence in $C\left(\left[0, T_{0}\right], H^{k-1}\left(B_{R}\right)\right) \cap C^{2}\left(\left[0, T_{0}\right], H^{k-3}\left(B_{R}\right)\right)$. The Arzela-Ascoli theorem gives us a subsequence $\left\{U_{m^{\prime}}\right\}$ converging in $C^{1}\left(\left[0, T_{0}\right], H^{k-4}\left(B_{R}\right)\right)$ to some limit $U^{*}$. Interpolating between the spaces $C\left(\left[0, T_{0}\right], H^{k-4}\left(B_{R}\right)\right)$ and $C\left(\left[0, T_{0}\right], H^{k-1}\left(B_{R}\right)\right)$ shows $U_{m^{\prime}} \rightarrow U^{*}$ in $C\left(\left[0, T_{0}\right], H^{k-1-\varepsilon}\left(B_{R}\right)\right)$. Especially, we have convergence in $C\left(\left[0, T_{0}\right], C^{2}\left(B_{R}\right)\right)$, since $k \geq 4$. Then the limit $U^{*}$ is a solution to (2.5). From the weak precompactness of bounded sets in $H^{k-1}$ we deduce that $U_{m^{\prime}} \rightarrow U^{*}$ in $L^{\infty}\left(\left[0, T_{0}\right], H^{k-1}\left(B_{R}\right)\right)$. The differential equation then yields

$$
\partial_{t}^{2} U^{*} \in L^{\infty}\left(\left[0, T_{0}\right], H^{k-3}\left(B_{R}\right)\right)
$$

The uniqueness of $U^{*}$ can be shown by standard arguments, Proposition 4.4 and Gronwall's lemma.

Then we find a solution $u \in L^{\infty}\left(\left[0, T_{0}\right], H^{k-1}\left(B_{R}\right)\right)$ to (2.1), which satisfies $\partial_{t}^{2} u \in L^{\infty}\left(\left[0, T_{0}\right], H^{k-3}\left(B_{R}\right)\right)$. A solution $w$ to (1.2) then is given by $w(t, x)=\int_{-R}^{x} u(t, y) d y$, compare the proof of Theorem 1.5.

Finally, we discuss the uniqueness of this solution $w$. It suffices to consider the reduced problem (2.1). Let $v=v(t, x)$ be a second solution to (2.1) with

$$
\partial_{t}^{j} v \in L^{\infty}\left(\left[0, T_{0}\right], H^{3-j}(\mathbb{R})\right), \quad j=0,2
$$

Then the difference $z(t, x)=u(t, x)-v(t, x)$ solves

$$
\partial_{t}^{2} z-\partial_{x}\left(a_{*}(t, x) \partial_{x} z\right)-b(t, x) \partial_{x} z-c(t, x) z=0
$$

with the coefficients $a_{*}(t, x)=a(u(t, x)), b(t, x)=a^{\prime}(u(t, x)) \partial_{x} v(t, x)$, and $c(t, x)$ is given implicitly by $c(t, x) z=(a(u)-a(v)) \partial_{x}^{2} v+\left(a^{\prime}(u)-\right.$ $\left.a^{\prime}(v)\right)\left(\partial_{x} v\right)^{2}$. We see that $c(t, x)$ is bounded; and by Condition $1,|b(t, x)|^{2} \leq$ $L a_{*}(t, x)$. From Proposition 4.4 we get $\|z(t, \cdot)\|_{L^{2}\left(B_{R}\right)}=0$. On the other hand, $u(t, x) \equiv 0$ for $x \notin B_{R}$, which implies $\partial_{t}^{2} z-c(t, x) z=0$. Consequently, $z(t, x)$ vanishes everywhere.

## 9. A blow-up result

We consider the Cauchy problem 1.2 and describe a class of coefficients $a=a(s)$, and initial data $\Phi, \Psi$ for which the solution blows up in finite time.

Proposition 9.1 Suppose Condition 2 with $a_{0}(0)>0$. We assume that $\Phi, \Psi \in C_{0}^{\infty}(\mathbb{R})$ are even functions, and

$$
\Phi^{\prime \prime}(0)>0, \quad \Psi^{\prime \prime}(0)>0 \quad \text { or } \quad \Phi^{\prime \prime}(0)<0, \quad \Psi^{\prime \prime}(0)<0
$$

Then the Cauchy problem (1.2) has no global $C^{\infty}$ solution $w$.
Proof. According to Theorem 1.5, there is a unique solution $w \in C_{b}^{\infty}\left(\left[0, T_{0}\right] \times \mathbb{R}\right)$, for some $T_{0}>0$. Now we show that $T_{0}$ is bounded from above.

Since $a, \Phi, \Psi$ are even functions, the solution $w=w(t, x)$ is also even, hence $w_{x}(t, 0)=0$ for $0 \leq t \leq T_{0}$, which implies $w(t, 0)=\Phi(0)+t \Psi(0)$. For $0 \leq t \leq T_{0},-\varepsilon<x<\varepsilon$, we have the Taylor expansion

$$
\begin{aligned}
& \begin{aligned}
w(t, x) & =\sum_{k=0}^{2} \frac{1}{k!}\left(\partial_{x}^{k} w\right)(t, 0)+\mathscr{O}\left(|x|^{3}\right) \\
& =(\Phi(0)+t \Psi(0))+\xi(t) x^{2}+\mathscr{O}\left(|x|^{3}\right)
\end{aligned} \\
& \xi(0)=\frac{1}{2} \Phi^{\prime \prime}(0), \quad \xi^{\prime}(0)=\frac{1}{2} \Psi^{\prime \prime}(0)
\end{aligned}
$$

Plugging this into (1.2) and collecting the terms with $x^{2}$ gives

$$
\begin{aligned}
& \xi_{t t}(t) x^{2}-a(2 \xi(t) x) \cdot 2 \xi(t)+\mathscr{O}\left(|x|^{3}\right)=0 \\
& \xi_{t t}(t)-(2 \xi(t))^{3} a_{0}(0)=0, \quad 0 \leq t \leq T_{0}
\end{aligned}
$$

Since $\xi(0)$ and $\xi^{\prime}(0)$ have the same sign, and $a_{0}(0)>0$, this ODE has no global solution, as can be seen from the equivalent formulation

$$
\left(\left(\xi_{t}\right)^{2}\right)_{t}=4 a_{0}(0)\left(\xi^{4}\right)_{t}, \quad 0 \leq t \leq T_{0}
$$

## 10. Appendix

The following technical lemma is proved by Nirenberg-Gagliardo interpolation.

Lemma 10.1 Let $f=f(x, u): \Omega \times \mathscr{M} \rightarrow \mathbb{R}$ be some $C^{k}$ function, where $\Omega \subset \mathbb{R}^{n}, \mathscr{M} \subset \mathbb{R}^{N}$ are domains with smooth boundary, and $\Omega$ is bounded. Assume $k>n / 2$. Then there is some continuous function $\varrho_{k}: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$ depending on $\|f(\cdot, \cdot)\|_{C^{k}(\Omega \times \mathscr{M})}$ such that

$$
\|f(x, u(x))\|_{H^{k}(\Omega)} \leq \varrho_{k}\left(\|u(\cdot)\|_{L^{\infty}(\Omega)}\right)\left(1+\|u(\cdot)\|_{H^{k}(\Omega)}\right)
$$

for all functions $u \in H^{k}(\Omega)$ taking values in $\mathscr{M}$. The function $\varrho_{k}$ satisfies

$$
\varrho_{k}(s) \leq C_{k} \sup _{x \in \Omega,|u| \leq s} \sum_{|\alpha|+|\beta| \leq k}\left|\partial_{x}^{\alpha} \partial_{u}^{\beta} f(x, u)\right|\left(1+s^{k}\right) .
$$

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