

is invertible although the eigenvalues of the polynomials coincide.

The main result of this article is concerned with a new definition of a resultant matrix $R^\otimes(a, b) \stackrel{\text{def}}{=} R(a \otimes I, I \otimes b)$, where \otimes is the sign of the right-hand tensor product.

Let $\lambda_1, \lambda_2, \dots, \lambda_r$ be all the common eigenvalues of $a(\lambda)$ and $b(\lambda)$. Let us denote by $k_{1p}(a) \geq k_{2p}(a) \geq \dots \geq k_{j_p p}(a)$ the powers of the elementary divisors of $a(\lambda)$ for the eigenvalue λ_p . Let

$$\mu(a, b, \lambda_p) = \sum_{l=1}^{j_p(a)} \sum_{j=1}^{j_p(b)} \min\{k_{lp}(a), k_{jp}(b)\}$$

and

$$\mu(a, b) = (\mu(a, b, \lambda_1) + \mu(a, b, \lambda_2) + \dots + \mu(a, b, \lambda_r)).$$

The main result is the following generalization of the classical resultant theorem.

THEOREM. *Let $a(\lambda)$ and $b(\lambda)$ be $d \times d$ matrix polynomials with invertible highest coefficients. Then $\dim \text{Ker } R^\otimes(a, b) = \mu(a, b)$. Particularly $a(\lambda)$ and $b(\lambda)$ have a common eigenvalue if and only if $\det R^\otimes(a, b) = 0$.*

We start sketching the proof by defining the *common multiplicity* of the eigenvalue λ_0 of polynomials $a(\lambda)$ and $b(\lambda)$. Let $\phi_0, \phi_1, \dots, \phi_r$ be a chain of the eigenvector ϕ_0 and the associated vectors ϕ_1, \dots, ϕ_r , which correspond to λ_0 :

$$\sum_{j=1}^k \frac{1}{j!} \left(\frac{d^j}{d\lambda^j} a \right) (\lambda_0) \phi_{k-j} = \sum_{j=1}^k \frac{1}{j!} \left(\frac{d^j}{d\lambda^j} b \right) (\lambda_0) \phi_{k-j} = 0 \quad (k = 0, 1, \dots, r)$$

The number $r + 1$ is called the *length* of the chain. We denote the maximal length of such chain with the fixed vector ϕ_0 by $\text{rank}(\lambda_0, \phi_0)$. It is easy to find a basis $\phi_{10}, \phi_{20}, \dots, \phi_{j_0 0}$ in the subspace $M = \text{Ker } a(\lambda_0) \cap \text{Ker } b(\lambda_0)$ such that $\text{rank}(\lambda_0, \phi_{10}) = \max \text{rank}(\lambda_0, \phi)$ ($\phi \in M$) and $\text{rank}(\lambda_0, \phi_{j_0}) = \max \text{rank}(\lambda_0, \phi)$ ($\phi \in M_j; j = 2, 3, \dots, r$) where M_j is the subspace with the basis $\phi_{j+1,0}, \phi_{j+2,0}, \dots, \phi_{r,0}$. It is easy to see that for every vector $\phi \in M$, the integer $\text{rank}(\lambda_0, \phi)$ is equal to one of the numbers $k_j = \text{rank}(\lambda_0, \phi_{j_0})$ ($j = 1, 2, \dots, j_0$). Therefore these numbers depend only on the polynomials $a(\lambda)$, $b(\lambda)$ and the eigenvalue λ_0 . The integer $\nu(a, b, \lambda_0) = k_1 + k_2 + \dots + k_{j_0}$ is called the *common multiplicity* of the eigenvalue λ_0 of the polynomials $a(\lambda)$ and $b(\lambda)$. If $M = \{0\}$, then we set $\nu(a, b, \lambda_0) = 0$.

The proof of the theorem involves two main steps. The first is to prove the equality $\mu(a, b, \lambda_0) = \nu(a \otimes I, I \otimes b, \lambda_0)$. The main theorem from [1] then implies that for large l , $\dim \text{Ker } R_l(a \otimes I, I \otimes b) = \mu(a, b)$, where

$$R_l(a, b) = \left(\begin{array}{cccc} a_0 & a_1 & \cdots & a_n \\ & a_0 & a_1 & \cdots & a_n \\ & & \cdot & \cdot & \cdot \\ & & & \cdot & \cdot & \cdot \\ & & & & a_0 & a_1 & \cdots & a_n \\ b_0 & b_1 & \cdots & b_m \\ & b_0 & b_1 & \cdots & b_m \\ & & \cdot & \cdot & \cdot \\ & & & \cdot & \cdot & \cdot \\ & & & & b_0 & b_1 & \cdots & b_m \end{array} \right) \left. \begin{array}{l} \\ \\ \\ \\ \\ \\ \\ \\ \\ \end{array} \right\} \begin{array}{l} n + l \\ \\ \\ \\ \\ \\ \\ \\ \\ m + l \end{array}$$

The second step consists of proving that the $\dim \text{Ker } R_l(a \otimes I, I \otimes b)$ does not depend on l and therefore

$$\dim \text{Ker } R_l(a \otimes I, I \otimes b) = \dim \text{Ker } R(a \otimes I, I \otimes b).$$

Let us mention that the main theorem is connected with the theory of the equation $a(\lambda) x(\lambda) + y(\lambda) b(\lambda) = f(\lambda)$, where $f(\lambda)$ is the given and $x(\lambda), y(\lambda)$ are the unknown matrix polynomials.

All the detailed proofs will appear elsewhere together with some analogous results for the continuous case.

REFERENCES

1. I. C. Gohberg and G. Heining, *Resultant matrix and its generalization. I: Resultant operator of matrix polynomials*, Acta Sci. Math. (Szeged) 37 (1975), Fasc. 1-2, pp. 41-61. (Russian)

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