

## SURFACES IN CONSTANT CURVATURE MANIFOLDS WITH PARALLEL MEAN CURVATURE VECTOR FIELD

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**I. Statement of results.** For an  $(n)$ -dimensional Riemannian manifold  $M^n$ , isometrically immersed in an  $(n+k)$ -dimensional Riemannian manifold  $M_{(c)}^{(n+k)}$  of constant sectional curvature  $c$ , let  $H$  denote the mean curvature vector field of  $M^n$ .  $H$  is a section of the normal bundle  $NM^n$  of the immersion. When  $n = 2$ ,  $k = 1$ , and  $c = 0$  (a surface immersed in  $E^3$ ), the requirement  $|H| = \text{constant}$  is classical constant mean curvature. If  $k > 1$ , however, the condition  $|H| = \text{constant}$  is usually too weak to prove reasonable generalizations of the classical theorems for surfaces of constant mean curvature in  $E^3$ . We investigate a stronger requirement on  $H$ ; namely, that  $H$  be parallel with respect to the induced connection in the normal bundle (for definitions, see II). Then using an analytic construction first employed by H. Hopf [2], we obtain

**THEOREM 1.** *A compact surface  $M^2$  of genus 0 immersed in  $M^4(c)$ ,  $c \geq 0$ , upon which  $H$  is parallel in the normal bundle, is a sphere of radius  $1/|H|$ .*

This generalizes a theorem of Hopf, who proved that the only immersed surfaces in  $E^3$  of genus 0 with constant mean curvature are spheres [2, Chapter 7, §4]. For complete surfaces in  $E^4$ , we prove

**THEOREM 2.** *A complete surface  $M^2$ , immersed in  $E^4$ , whose Gauss curvature does not change sign, and for which  $H$  is parallel in the normal bundle  $NM^2$ , is a minimal surface ( $H \equiv 0$ ), a sphere, a right circular cylinder, or a product of circles  $S^1(r) \times S^1(\rho)$ , where  $|H| = \frac{1}{2}(1/r^2 + 1/\rho^2)^{1/2}$ .*

This extends a theorem of Klotz and Osserman for complete surfaces of constant scalar mean curvature in  $E^3$  [5]. It can also be generalized to immersions into  $\bar{M}_{(c)}^4$ ,  $c \geq 0$ . Theorem 2 is proved in two steps. First we prove

**THEOREM 3.** *A piece of immersed surface  $M^2$  in  $E^4$ , satisfying the conditions of Theorem 2 with  $H \neq 0$ , is either a sphere or it is flat ( $K = 0$ ).*

Then we establish the following characterization of flat surfaces in  $E^4$  with parallel mean curvature vector fields:

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**THEOREM 4.** *A piece of immersed surface  $M^2$  in  $E^4$  with parallel mean curvature vector  $H \neq 0$  and  $K \equiv 0$  is a piece of  $S^1(r) \times S^1(\rho)$ : the product of two circles of radius  $r$  and  $\rho$  with the standard flat immersion. ( $\rho$  may be infinite, in which case we have a right circular cylinder.)*

Theorem 2 generalizes to immersions in  $S^4(c)$ .

Surfaces in  $E^n$  which lie minimally in hyperspheres of radius  $r$  have the same mean curvature vectors as the hypersphere, and consequently have parallel mean curvature vector fields. Such surfaces are pseudo-umbilic ( $\varphi_3 \equiv 0$  in the lemma in II). In this case, Itoh [3] has proven a special case of Theorem 2 for immersions in  $E^4$  (see also Chen, [1]). For minimal surfaces in  $S^4$ , Ruh [8] has proven a case of Theorem 1, using methods similar to the basic lemma in II. For a wide variety of examples of complete minimal surfaces in  $S^3$ , see Lawson [6].

It is possible to show the existence of surfaces in  $E^n$  and  $S^n(c)$  with parallel  $H$  and  $\varphi_3 \neq 0$  (i.e. they do not lie minimally in hyperspheres). The method employed uses a theorem due to Szczarba [9] on existence of immersions in constant curvature manifolds with codimension  $k > 1$ .

**II. Definitions and Main Lemma.**  $\bar{\nabla}$  denotes covariant differentiation on  $\bar{M}_{(c)}^{n+k}$ , and  $\nabla$  denotes covariant differentiation on  $M^n \subset \bar{M}^{n+k}$ . For  $X, Y$ , sections of  $TM^n$ ,  $\nabla_X Y = [\bar{\nabla}_X Y]^T$  where  $[\ ]^T$  is projection onto  $TM^n$ .  $[\ ]^N$  is projection onto  $NM^n$ .

**DEFINITIONS.**  $B(X, Y) = [\bar{\nabla}_X Y]^N$ .  $B$  is the second fundamental form tensor of the immersion. Similarly for  $N$ , a section of  $NM^n$ ,  $D_X N = [\bar{\nabla}_X N]^N$ .  $D$  defines a connection on  $NM^n$ .  $A(X, N) = [\bar{\nabla}_X N]^T$ .  $A$  is a tensor:  $A_p: TM^n \times NM^n \rightarrow TM^n$  is bilinear.

For an orthonormal framing  $(e_1 \cdots e_n)$  of  $TM^n$ ,  $H = (1/n) \sum_{i=1}^n B(e_i, e_i)$ . This definition of  $H$  is independent of the framing. A normal vector field  $N$  is said to be parallel in the normal bundle  $NM^n$  if  $D_X N = 0$  for all  $X$  in  $TM^n$ . This condition implies  $|N| = \text{const}$ . Thus our assumption that  $H$  is parallel in  $NM^n$  includes constant mean curvature. ( $|H| = c$ .)

The Gauss and Codazzi equations, for  $X, Y, Z$  sections in  $TM^n$ , are

$$(1) \quad R(X, Y)Z = c\{\langle X, Z \rangle Y - \langle Y, Z \rangle X\} + A(X, B(Y, Z)) - A(Y, B(X, Z)),$$

$$(2) \quad (\nabla_X B)(Y, Z) = (\nabla_Y B)(X, Z),$$

where  $(\nabla_X B)(Y, Z) = D_X(B(Y, Z)) - B(\nabla_X Y, Z) - B(Y, \nabla_X Z)$  (for a reference for the above definitions and equations, see [4, Chapter 7]).

For  $X, Y$  in  $TM^n$ ,  $N$  in  $NM^n$ ,  $\tilde{R}(X, Y)N = D_X D_Y N - D_Y D_X N - D_{[X, Y]} N$  is the curvature tensor for  $D$ . For  $\tilde{R}$ , there is a Gauss-type equation

$$(3) \quad \tilde{R}(X, Y)N = B(X, A(N, Y)) - B(Y, A(N, X))$$

and an equation, analogous to (2),

$$(4) \quad (\nabla_X A)(Y, N) = (\nabla_Y A)(X, N).$$

For a unit normal vector  $e_\alpha$  at  $p \in M^n$ , the matrix  $(\lambda_{ij}^\alpha) = (B(e_i, e_j) \cdot e_\alpha)$  is the "second fundamental form matrix in the  $\alpha$  direction." We specify  $H/|H|$  as  $e_{n+1}$  when  $H \neq 0$ . Considering an immersed surface ( $n = 2$ ) given in conformal coordinates  $(u, v): ds^2 = E(du^2 + dv^2)$ , we associate to it a natural framing

$$(e_1, e_2) = \left( \frac{\partial}{\partial u} \Big/ \sqrt{E}, \frac{\partial}{\partial v} \Big/ \sqrt{E} \right)$$

of the tangent bundle,  $TM^2$ .

LEMMA. For an immersed surface,  $M^2 \subset \bar{M}_{(c)}^{n+k}$  in conformal coordinates, let  $H \neq 0$  and  $e_\alpha$  be a unit normal vector field with  $e_\alpha \cdot H = 0$ :

- (a) if  $H$  is parallel in  $NM^2$ , then  $\varphi_3 = E\{\frac{1}{2}(\lambda_{11}^3 - \lambda_{22}^3) - i\lambda_{12}^3\}$  is an analytic function of  $z = u + iv$ ;
- (b) if  $e_\alpha$  is parallel in  $NM^2$ , then  $\varphi_\alpha = E\{\lambda_{11}^\alpha - i\lambda_{12}^\alpha\}$  is an analytic function of  $z$ ;
- (c) if  $k = 2$  and  $H$  is parallel, then  $e_\alpha$  is parallel, and both  $\varphi_3$  and  $\varphi_\alpha$  are analytic;
- (d) under the conditions of (a) and (b), either  $\varphi_3 \equiv 0$  or  $\varphi_\alpha = \kappa\varphi_3$  where  $\kappa$  is a real constant.

SKETCH OF PROOF. (a) Using equation (4) with  $X = \partial/\partial u, Y = \partial/\partial v, N = H$ , and the assumption that  $H$  is parallel, the equations

$$(5) \quad (E\lambda_{11}^3)_v - (E\lambda_{12}^3)_u = \frac{1}{2}E_v(\lambda_{11}^3 + \lambda_{22}^3), \quad (E\lambda_{12}^3)_u - (E\lambda_{22}^3)_v = \frac{1}{2}E_u(\lambda_{11}^3 + \lambda_{22}^3)$$

are obtained. (5) is in the same form as the Codazzi equations in conformal coordinates for surfaces in  $E^3$ , only it is expressed for the distinguished normal  $e_3 = H/|H|$ . Since  $\lambda_{11}^3 + \lambda_{22}^3 = 2|H| = \text{constant}$ , (5) reduces to the Cauchy-Riemann equations for  $\varphi_3$ .

(b) Proof follows that of (a), using the fact that  $\lambda_{11}^\alpha + \lambda_{22}^\alpha = 0$ .

(c) Since  $NM^2$  is 2-dimensional, the assumption that  $H$  is parallel forces  $e_\alpha$  to be parallel. Then (a) and (b) imply analyticity.

(d) Using equation (3) with

$$X = \frac{\partial}{\partial u_1} \Big/ \sqrt{E}, \quad Y = \frac{\partial}{\partial u_2} \Big/ \sqrt{E}, \quad \text{and} \quad N = e_3,$$

we obtain, using the fact that  $e_3$  is parallel,

$$(6) \quad 0 = \left( \sum_{k=1}^2 \lambda_{k2}^3 \lambda_{k1}^\alpha - \lambda_{k1}^3 \lambda_{k2}^\alpha \right).$$

Note that (6) implies  $\text{Im}(\varphi_\alpha \cdot \bar{\varphi}_3) = 0$ . So if  $\varphi_3 \neq 0, \varphi_\alpha/\varphi_3 = \varphi_\alpha \cdot \bar{\varphi}_3/|\varphi_3|^2$  is real. By (a) and (b), it is also meromorphic, hence constant.

III. **Proof of Theorems (Sketch).** Theorem 1 is proved by constructing an analytic differential  $\theta_3$  out of the functions  $\varphi_3(z)$  of the lemma: in local coordinates,  $\theta_3 = \varphi_3 dz^2$ . Since  $M^2$  is of genus 0,  $\theta_3$  must be identically zero.

Hence  $\varphi_3(z) \equiv 0$ . This implies that  $M^2$  is pseudo-umbilic ( $\lambda_{11}^3 = \lambda_{22}^3$ ,  $\lambda_{12}^3 = 0$ ). The function  $\varphi_4$  associated with  $e_4$ ,  $e_4 \cdot H = 0$  is also zero by a similar argument. Hence  $M^2$  is totally umbilic. This implies that  $M^2$  is immersed as a sphere.

To prove Theorem 3, we can consider on  $M^2$  the quadratic analytic differentials  $\theta_3$  and  $\theta_4$  given locally by  $\varphi_3 dz^2$  and  $\varphi_4 dz^2$  (where  $\varphi_3, \varphi_4$ , and  $z$  are as in the lemma). If  $K \geq 0$ ,  $M^2$  is either compact or parabolic by a theorem of Huber (see [5, p. 316]). If it is compact, then either  $K \equiv 0$  or  $M^2$  is of genus 0. The genus 0 case is a sphere by Theorem 1.

If  $K \leq 0$ , then  $|H|^2 - K > |H|^2 > 0$ . In a neighborhood of each point, we introduce the new metric  $d\tilde{s}^2 = E(|H|^2 - K)^{1/2}(du^2 + dv^2)$ . Using the equality

$$|\varphi_3|^2 + |\varphi_4|^2 = E^2(|H|^2 - K)$$

and part (d) of the lemma to show that  $\Delta \log(|\varphi_3|^2 + |\varphi_4|^2) = 0$ , we establish that  $d\tilde{s}^2$  is a flat metric. Therefore, the universal covering surface  $\tilde{M}^2$  of  $M^2$  is conformally the plane. The function  $|H|^2 - K$  is easily seen to be superharmonic. Since it is bounded below, it must be constant. Hence  $K$  is constant, and must be zero.

Theorem 4 is proved by introducing conformal coordinates  $(u, v)$  such that  $E \equiv 1$ . The lemma is used to show that all  $\lambda_{ij}^z$  are constant. Then a rotation of coordinates puts the immersion into the form

$$(u, v) \rightarrow \left( r \cos \frac{u}{r}, r \sin \frac{u}{r}, \rho \cos \frac{v}{\rho}, \rho \sin \frac{v}{\rho} \right).$$

The constants  $r$  and  $\rho$  are determined from the  $\lambda_{ij}^z$  and  $|H|$ . This immersion is the standard flat immersion of the plane into  $E^4$  as a product of circles.

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