

ALGEBRAS OF DIFFERENTIABLE FUNCTIONS

BY K. DE LEEUW¹ AND H. MIRKIL²

Communicated by Walter Rudin, March 18, 1962

1. Classification of certain spaces of continuously differentiable functions of two variables. Denote by C_0 the space of all complex-valued continuous functions on the plane that are zero at infinity. Write $\|\cdot\|_\infty$ for the supremum norm on C_0 . Denote by D the dense subspace of C_0 consisting of infinitely differentiable functions with compact support.

Throughout we shall be concerned with differential operators of the form

$$(1.1) \quad \sum a_{m,n} \frac{\partial^{m+n}}{\partial x^m \partial y^n};$$

the $a_{m,n}$ are complex constants. For each set \mathcal{A} of such operators, we define $C_0(\mathcal{A})$ to be the space of all f in C_0 having Af in C_0 (in the sense of Laurent Schwartz) for all A in \mathcal{A} . Equivalently, $C_0(\mathcal{A})$ is the completion of D under the seminorms

$$f \rightarrow \|f\|_\infty \quad \text{and} \quad f \rightarrow \|Af\|_\infty, \quad A \text{ in } \mathcal{A}.$$

Each $C_0(\mathcal{A})$ so defined is a translation-invariant space of functions; those that are furthermore invariant under rotations of the plane will be called *rotating spaces of differentiable functions*.

Certain of these spaces are familiar, namely the spaces C_0^N consisting of those functions in C_0 that have all derivatives of order $\leq N$ in C_0 , and the space C_0^∞ , which is $\bigcap_N C_0^N$. A rotating space of differentiable functions will be called *proper* if it is not one of the C_0^N and not C_0^∞ . Here is the classification of such spaces.

We use the notation

$$\frac{\partial}{\partial z} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) \quad \text{and} \quad \frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right).$$

THEOREM 1.1. *If \mathcal{A} is a proper subset of*

$$(1.2) \quad \left\{ \partial^{m+n} / \partial z^m \partial \bar{z}^n : m + n = N \right\},$$

¹ This research is supported in part by the United States Air Force Office of Scientific Research under contract AF 49(638)-294.

² This research is supported in part by N.S.F. Grant G14242 and by the United States Air Force Office of Scientific Research under contract AF 49(638)-812.

for N a positive integer, then $C_0(\mathfrak{A})$ is a proper rotating space of differentiable functions between C_0^N and C_0^{N-1} . If \mathfrak{A}_1 and \mathfrak{A}_2 are distinct subsets of (1.2) then $C_0(\mathfrak{A}_1)$ and $C_0(\mathfrak{A}_2)$ are distinct. Each proper rotating space of differentiable functions is a $C_0(\mathfrak{A})$, where \mathfrak{A} is a proper subset of (1.2) for some N .

COROLLARY 1.2. *Every proper rotating space of differentiable functions is a Banach algebra under pointwise multiplication.*

For instance, the six distinct proper rotating spaces of differentiable functions between C_0^1 and C_0^2 are

$$\begin{aligned} C_0(\partial^2/\partial z^2), \\ C_0(\partial^2/\partial \bar{z}^2), \\ C_0(\partial^2/\partial z\partial \bar{z}) = C_0(\partial^2/\partial x^2 + \partial^2/\partial y^2), \\ C_0(\partial^2/\partial z^2, \partial^2/\partial \bar{z}^2) = C_0(\partial^2/\partial x^2 - \partial^2/\partial y^2, \partial^2/\partial x\partial y), \\ C_0(\partial^2/\partial z^2, \partial^2/\partial z\partial \bar{z}), \\ C_0(\partial^2/\partial \bar{z}^2, \partial^2/\partial z\partial \bar{z}). \end{aligned}$$

REMARK 1.3. *Suppose instead of the supremum norm we take as basic norm $\|f\|_p = \{\int |f|^p\}^{1/p}$, $1 < p < \infty$. Then there are no proper rotating spaces*

$$L_p(\mathfrak{A}) = \{f: f \in L_p, Af \in L_p \text{ for all } A \in \mathfrak{A}\}.$$

Indeed the only rotating spaces are the Sobolev spaces

$$L_p^N = \{f: f \in L_p, (\partial^{m+n}/\partial x^m \partial y^n)f \in L_p, m+n \leq N\},$$

analogous of the C_0^N ; and L_p^∞ , which is identical with C_0^∞ .

In a sense, rotating spaces are the ones that have geometrical significance. From this point of view the correct definition in norm $\|\cdot\|_\infty$ of "Sobolev space" would include not only the C_0^N but also the proper rotating spaces.

2. Spaces of continuously differentiable functions on Riemann surfaces. It is possible to define algebras of functions on Riemann surfaces corresponding to those described in Theorem 1.1 and to show that these algebras determine the conformal structure.

Let U be an open subset of the plane, $C(U)$ the space of all complex-valued continuous functions on U . For \mathfrak{A} a set of differential operators of the form (1.1), we denote by $C(U, \mathfrak{A})$ the subspace of $C(U)$ consisting of those f in $C(U)$ with Af in $C(U)$ (in the sense of Laurent Schwartz) for each A in \mathfrak{A} .

For a general set \mathfrak{A} of differential operators, the spaces $C(U, \mathfrak{A})$

have no interesting invariance properties. However we have

LEMMA 2.1. *If \mathfrak{A} is a subset of (1.2), the spaces $C(U, \mathfrak{A})$ are invariant under conformal transformations.*

This result allows the extension of the definition of the $C(U, \mathfrak{A})$ to Riemann surfaces. If R is a Riemann surface and \mathfrak{A} a subset of (1.2), $C(R, \mathfrak{A})$ is defined to be the space of those functions on R such that if $U = \{z: |z| < 1\}$ and $\phi: U \rightarrow R$ is a coordinate disk, the composite function $f \circ \phi$ is in $C(U, \mathfrak{A})$.

Each $C(R, \mathfrak{A})$ is an algebra of functions on R , with multiplicative linear functionals corresponding to points of R , and with a natural complete locally convex topology. In this topology $C(R, \mathfrak{A})$ is a Banach algebra if and only if R is compact.

In three instances $C(R, \mathfrak{A})$ can be described in terms of exterior differential operators defined globally on R .

$$\begin{aligned} C(R, \partial/\partial z) &= \{f: f \text{ and } \partial f \text{ continuous on } R\}, \\ C(R, \partial/\partial \bar{z}) &= \{f: f \text{ and } \bar{\partial} f \text{ continuous on } R\}, \\ C(R, \partial^2/\partial z \partial \bar{z}) &= \{f: f \text{ and } \Delta f \text{ continuous on } R\}, \end{aligned}$$

where the operators ∂ , $\bar{\partial}$ and Δ , taking functions into differential forms, are defined in terms of any coordinate system by

$$\partial f = \frac{\partial f}{\partial z} dz, \quad \bar{\partial} f = \frac{\partial f}{\partial \bar{z}} d\bar{z}, \quad \Delta f = \frac{1}{4} \frac{\partial^2 f}{\partial z \partial \bar{z}} dz d\bar{z}.$$

The following result states the extent to which the algebras $C(R, \mathfrak{A})$ determine the conformal structure of R .

THEOREM 2.2. *Let R_1 and R_2 be connected Riemann surfaces and \mathfrak{A} be a proper subset of (1.2). Each conformal equivalence of R_1 with R_2 induces an algebra isomorphism of $C(R_1, \mathfrak{A})$ with $C(R_2, \mathfrak{A})$. If \mathfrak{A} is symmetric (i.e., $\partial^{m+n}/\partial z^m \partial \bar{z}^n$ in \mathfrak{A} if $\partial^{m+n}/\partial z^n \partial \bar{z}^m$ in \mathfrak{A}), an anticonformal equivalence of R_1 with R_2 also induces an algebra isomorphism of $C(R_1, \mathfrak{A})$ with $C(R_2, \mathfrak{A})$. No other algebra isomorphisms of $C(R_1, \mathfrak{A})$ with $C(R_2, \mathfrak{A})$ are possible.*

A similar result identifies all algebra homomorphisms of the $C(R, \mathfrak{A})$.

3. Sup norm estimates. The work of the preceding sections is based on the existence and nonexistence of certain sup norm estimates for constant-coefficient differential operators. In this section we state

these results, which may be of some independent interest. All these results remain valid for n variables.

If P is a polynomial,

$$P(x, y) = \sum a_{m,n} x^m y^n,$$

we denote by P^N its homogeneous part of degree N ,

$$P^N(x, y) = \sum_{m+n=N} a_{m,n} x^m y^n,$$

and by \hat{P} its Fourier transform, the differential operator

$$\sum (-i)^{m+n} a_{m,n} \frac{\partial^{m+n}}{\partial x^m \partial y^n}.$$

An operator \hat{P} of order N is called *elliptic* if $P^N(x, y) \neq 0$ for $(x, y) \neq (0, 0)$.

THEOREM 3.1. *Let Q, P_1, \dots, P_r be polynomials of degree N or less. Then the following are equivalent:*

(1) *There is a constant K so that*

$$\|\hat{Q}f\|_\infty \leq K(\|\hat{P}_1 f\|_\infty + \dots + \|\hat{P}_r f\|_\infty)$$

for all f in D .

(2) *There are finite measures μ_1, \dots, μ_r in the plane whose Fourier-Stieltjes transforms $\hat{\mu}_1, \dots, \hat{\mu}_r$ satisfy*

$$Q = P_1 \hat{\mu}_1 + \dots + P_r \hat{\mu}_r.$$

If (1) and (2) hold, it is possible to find constants c_1, \dots, c_r so that

$$Q^N = c_1 P_1^N + \dots + c_r P_r^N.$$

THEOREM 3.2. *Let \hat{P} be elliptic and of order $N \geq 2$. Then for each \hat{Q} of order strictly less than N there is a constant K so that*

$$\|\hat{Q}f\|_\infty \leq K(\|\hat{P}f\|_\infty + \|f\|_\infty)$$

for all f in D .

COROLLARY 3.3. *$\partial^{m+n}/\partial x^m \partial \bar{z}^n$ is elliptic. Hence, if $p+q < m+n$, there is a constant K so that*

$$\|(\partial^{p+q}/\partial x^p \partial y^q)f\|_\infty \leq K(\|(\partial^{m+n}/\partial x^m \partial \bar{z}^n)f\|_\infty + \|f\|_\infty)$$

for all f in D .

REMARK 3.4. The situation for estimates in $\|\cdot\|_p$, $1 < p < \infty$, is quite different, which is the reason for the phenomenon mentioned in Re-

mark 1.3. To be precise, if \hat{P} is elliptic of order N , \hat{Q} arbitrary of order $\leq N$, it is known that there is an estimate of the form

$$\|\hat{Q}f\|_p \leq K(\|\hat{P}f\|_p + \|f\|_p) \quad f \in D,$$

and the existence of these estimates is characteristic of ellipticity. It is natural to ask whether the existence of sup norm estimates like those in Theorem 3.2 (where \hat{Q} has strictly lower order) also characterizes ellipticity. In the plane the answer is no, but in higher dimensions yes.

STANFORD UNIVERSITY AND
DARTMOUTH COLLEGE