CANONICAL VARIABLES AS OPTIMAL PREDICTORS

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Let $\mathbf{X}=(X_1,\cdots,X_m)'$ and $\mathbf{Y}=(Y_1,\cdots,Y_n)'$ be two random vectors. Given any random vector \mathbf{Z} , let \mathbf{Y}_Z^* be the best linear predictor of \mathbf{Y} based on \mathbf{Z} . Let p be any natural number smaller than m. We consider the problem of finding the p-dimensional random vector $\mathbf{Z}=(Z_1,\cdots,Z_p)'$ where each component Z_i is a linear function of \mathbf{X} , which minimizes the determinant of $E(\mathbf{Y}-\mathbf{Y}_Z^*)(\mathbf{Y}-\mathbf{Y}_Z^*)'$. We show that Z_1,\cdots,Z_p coincide with the first p canonical variables (except for a nonsingular linear transformation). We also show that the square of the (p+1)th canonical correlation coefficient measures the relative improvement in the prediction of \mathbf{Y} when p+1 Z_i 's are used instead of p.

1. Introduction. Let $X = (X_1, \dots, X_m)'$ and $Y = (Y_1, \dots, Y_n)'$ be two random vectors and assume $m \le n$. Assume also that E(X) = E(Y) = 0 and let

$$egin{pmatrix} oldsymbol{\Sigma}_{11} & oldsymbol{\Sigma}_{12} \ oldsymbol{\Sigma}_{21} & oldsymbol{\Sigma}_{22} \end{pmatrix}$$

be the covariance matrix of (X', Y')', where Σ_{11} and Σ_{22} are nonsingular matrices. Classically, the problem of canonical correlation consists of finding vectors $\mathbf{b}_1, \dots, \mathbf{b}_m$ in R^m and $\mathbf{c}_1, \dots, \mathbf{c}_n$ in R^n such that if $V_i = \mathbf{b}_i' X$ and $W_i = \mathbf{c}_i' Y$ then

- (i) V_1 , W_1 are the two linear functions of X and Y respectively, with variance 1, which have correlation coefficient with maximum absolute value.
- (ii) for $i \le m$, V_i is the linear function of **X** with variance 1, uncorrelated with V_1, \dots, V_{i-1} , and W_i is the linear function of **Y** with variance 1, uncorrelated with W_1, \dots, W_{i-1} , such that the pair (V_i, W_i) has a correlation coefficient with maximum absolute value.
 - (iii) for i > m, W_i has variance 1 and is uncorrelated with W_1, \dots, W_{i-1} .

For $1 \le i \le m$ the pair of variables (V_i, W_i) is called the *i*th pair of canonical variables and the absolute value of its correlation coefficient ρ_i is called the *i*th canonical correlation. Clearly $\rho_1^2 \ge \rho_2^2 \ge \cdots \rho_m^2$ is satisfied.

It is well known [Rao (1973, Section 8f)] that to solve this problem it suffices to find a $m \times m$ matrix **B** and a $n \times n$ matrix **C** such that

$$\mathbf{B}' \mathbf{\Sigma}_{12} \mathbf{\Sigma}_{22}^{-1} \mathbf{\Sigma}_{21} \mathbf{B} = \mathbf{R}_{1}$$

$$\mathbf{B}'\mathbf{\Sigma}_{11}\mathbf{B} = \mathbf{I}_m$$

$$\mathbf{C}'\boldsymbol{\Sigma}_{21}\boldsymbol{\Sigma}_{11}^{-1}\boldsymbol{\Sigma}_{12}\mathbf{C} = \mathbf{R}_{2}$$

$$(1.4) C'\Sigma_{22}C = I_n$$

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where I_m is the $m \times m$ identity matrix and where R_1 and R_2 are two diagonal matrices with decreasing elements in their diagonals. Then the vectors $\mathbf{b}_i (1 \le i \le m)$ and $\mathbf{c}_i (1 \le i \le n)$ which solve the problem of canonical correlation are given by the columns of \mathbf{B} and \mathbf{C} respectively. The *i*th diagonal element of R_1 and R_2 is ρ_i^2 if $1 \le i \le m$ and if i > m the *i*th diagonal element of R_2 is 0. The treatment of the case where m > n is analogous.

The solution to the canonical correlation problem is unique (except for a change of sign in the b_i 's or the c_i 's) if and only if the numbers ρ_i^2 are all different.

In this approach to the canonical correlation problem, the vectors X and Y play symmetrical roles, but in many practical problems their roles differ. This happens for example when the components of X are observable variables correlated to the components of Y, while the components of Y are not observable or have high cost of observation. In this case the researcher may be interested in using X to predict Y. If M is very large it would be useful to summarize the information contained in X in a few variables Z_1, \dots, Z_p , linear functions of X:

$$Z_i = \mathbf{a}_i' \mathbf{X},$$

choosing \mathbf{a}_i , $1 \le i \le p$, such that the vector $\mathbf{Z} = (Z_1, \dots, Z_p)'$ be the best for linearly predicting the vector Y. This may be formalized as follows: Let \mathbf{Y}_Z^* be the least square predictor of Y based on Z. Then \mathbf{Y}_Z^* is given by [Rao (1973, Section 4g)]:

(1.5)
$$\mathbf{Y}_{\mathbf{Z}}^{*} = E(\mathbf{Y}\mathbf{Z}') E(\mathbf{Z}\mathbf{Z}')^{-1}\mathbf{Z}.$$

It is well known that Y_Z^* is the best linear predictor of Y based on Z using either of the following criteria:

- (i) it minimizes $E(||\mathbf{Y} \mathbf{Y}_{Z}^{*}||^{2})$, and
- (ii) it minimizes $|E(Y Y_Z^*)(Y Y_Z^*)'|$, among all predictors of the forms $Y_Z^* = DZ$, where **D** is any $n \times p$ matrix. (| | indicates the matrix determinant and || || the vector Euclidean norm).

Then we may define the best p-vector Z for predicting Y using two different criteria:

(a) the vector **Z** which minimizes

$$(1.6) E(\|\mathbf{Y} - \mathbf{Y}_{\mathbf{Z}}^*\|^2)$$

or

(b) the vector **Z** which minimizes

(1.7)
$$|E(Y - Y_z^*)(Y - Y_z^*)'|.$$

The problem of finding **Z** which minimizes (1.6) is treated in Rao (1973, Chapter 8, Problem 2). The variables Z_1, \dots, Z_p which solve this problem are in general different from the first p canonical variables, being the same in the particular case that Σ_{22} is of the form λ I_n where λ is a scalar.

On the other hand, if the criterium for choosing **Z** is to minimize (1.7), we will show that a solution is to choose $\mathbf{Z} = (V_1, \dots, V_p)'$ where V_1, \dots, V_p are the first canonical variables.

2. Proofs. We will prove the following theorem:

THEOREM. Consider the problem of choosing a $m \times p$ matrix A^* such that $Z^* = A^{*'}X$ minimizes (1.7), among all the p-dimensional vectors Z = A'X. Then

- (i) The $m \times p$ matrix A_0 given by the first p columns of the matrix B satisfying (1.1) and (1.2) is a solution to this problem.
- (ii) If $\rho_p^2 > \rho_{p+1}^2$ then every other solution A^* is of the form $A^* = A_0G$ where G is any nonsingular $p \times p$ matrix.

On the other hand with k equal eigenvalues $\rho_{q+1}^2 = \rho_{q+2}^2 = \cdots = \rho_{q+k}^2$ and q the <math>p - q last columns of A_0 can be chosen as any set of p - q orthogonal eigenvectors associated with the common eigenvalue, and in this framework every solution can be written in the form $A^* = A_0G$.

(iii) The minimum value of (1.7) is given by

$$|\mathbf{\Sigma}_{22}| \prod_{i=1}^{p} (1 - \rho_i^2).$$

PROOF. Replacing in (1.7) Y_Z^* by its expression (1.5), it turns out that (1.7) is equivalent to

$$(2.1) |E(\mathbf{YY}') - E(\mathbf{YZ}')E(\mathbf{ZZ}')^{-1}E(\mathbf{ZY}')|.$$

Let us note that the best linear predictor of Y based on Z is the same as the best linear predictor of Y based on DZ for any $p \times p$ nonsingular matrix D. D may be always chosen such that the covariance matrix of DZ be the identity. Then without loss of generality we may choose A^* among the matrices A such that:

(2.2)
$$E(\mathbf{Z}\mathbf{Z}') = \mathbf{A}'\mathbf{\Sigma}_{11}\mathbf{A} = \mathbf{I}_{p}.$$

Replacing Z by A'X in (2.1) and using (2.2) the expression (1.7) to be minimized may be written

$$|\Sigma_{22} - \Sigma_{21}AA'\Sigma_{12}|$$

and this is equal to [Press (1972, Formula 2.4.2)]:

(2.3)
$$|\Sigma_{22}| |I_p - A'\Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}A|$$
.

Since the first factor does not depend on A, the problem of minimizing (1.7) is reduced to finding a $m \times p$ matrix A such that

$$\left|\mathbf{I}_{p}-\mathbf{A}'\boldsymbol{\Sigma}_{12}\boldsymbol{\Sigma}_{22}^{-1}\boldsymbol{\Sigma}_{21}\mathbf{A}\right|$$

is minimized, subject to the restriction (2.2).

Let **B** be a matrix satisfying (1.1) and (1.2) and put $\mathbf{H} = \mathbf{B}^{-1}\mathbf{A}$. Then replacing $\mathbf{A} = \mathbf{B}\mathbf{H}$ and using (1.1), (2.4) is equivalent to

$$|\mathbf{I}_p - \mathbf{H}'\mathbf{R}_1\mathbf{H}|.$$

Moreover by (2.2) and (1.2) the matrix H satisfies

$$(2.6) H'H = I_p.$$

Given any $p \times p$ symmetric matrix **A** we denote by $\lambda_i(\mathbf{A})$ the *i*th largest eigenvalue of **A**. Then (2.5) is equivalent to

(2.7)
$$\prod_{i=1}^{p} (1 - \lambda_i(\mathbf{H}'\mathbf{R}_1\mathbf{H})).$$

According to Lemma 2.6 of Okamoto (1969) a $p \times m$ matrix H^* minimizes (2.7) if and only if

$$(2.8) H^* = SQ,$$

where Q is any nonsingular $p \times p$ matrix, in particular we may take

$$Q = I_p$$

and S is any $m \times p$ matrix whose columns are eigenvectors of \mathbf{R}_1 corresponding to the first p largest eigenvalues. Since \mathbf{R}_1 is diagonal with nondecreasing elements in its diagonal, the first p vectors of the canonical base on \mathbf{R}^P satisfy this property. Therefore \mathbf{H}^* may be taken equal to

$$\mathbf{H}_0 = \begin{pmatrix} \mathbf{I}_P \\ \mathbf{O} \end{pmatrix},$$

where **O** denotes the $(m - p) \times p$ matrix with all its elements 0. Then $A_0 = BH_0$ is a solution to the problem of minimizing (1.7), where the matrix A_0 is formed by the first p columns of **B**.

The proof of (iii) follows immediately replacing **A** by A_0 in (2.3) and using (1.1). To prove (ii) it is enough to observe that given any other matrix A^* such that $Z^* = A^{*'}X$ minimizes (1.7), we may obtain a nonsingular matrix **D** such that $\tilde{A} = A^*D'$ satisfies (2.2). Denote $H^* = B^{-1}\tilde{A}$. Then from (2.8) and the fact that $\rho_n^2 > \rho_{n+1}^2$ we have

$$\mathbf{H}^* = \begin{pmatrix} \mathbf{I}_p \\ \mathbf{O} \end{pmatrix} \mathbf{Q}$$

where Q is a $p \times p$ nonsingular matrix. Then

$$\mathbf{A}^* = \mathbf{B} \begin{pmatrix} \mathbf{I}_p \\ \mathbf{O} \end{pmatrix} \mathbf{Q} \mathbf{D}'^{-1} = \mathbf{A}_0 \mathbf{Q} \mathbf{D}'^{-1}$$

and denoting $G = QD'^{-1}$ we obtain (ii).

In the case where $\rho_{q+1}^2 = \rho_{q+2}^2 = \cdots = \rho_{q+k}^2$ and q the matrix of the <math>p-q last columns of A_0 can be replaced by

$$(\mathbf{b}_{q+1}, \mathbf{b}_{q+2}, \cdots, \mathbf{b}_{q+k})\mathbf{F}$$

where F is a $k \times (p-q)$ matrix such that $F'F = I_{p-q}$. After this change the solution $A^* = A_0G$ depends on both F and G, and every solution which minimizes (2.4) can be written in this way.

REMARK. Point (iii) of the theorem yields an interpretation of the square of the p+1-canonical correlation ρ_{p+1} : it measures the relative improvement in the prediction of Y when a (p+1)-dimensional vector Z is used instead of a p-dimensional one. In effect from point (iii) of the above theorem we have that the determinant of the covariance matrix of the residual vector $\mathbf{Y} - \mathbf{Y}_Z^*$ when an optimal p-dimensional vector Z is used is

$$|\mathbf{\Sigma}_{22}| \prod_{i=1}^{p} (1 - \rho_i^2).$$

If a (p + 1)-dimensional optimal vector **Z** is used the determinant will be reduced to

$$|\Sigma_{22}| \prod_{i=1}^{p+1} \left(1-\rho_i^2\right)$$

and then the relative reduction of the determinant is ρ_{p+1}^2 .

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