# ON THE DETERMINANT OF THE SECOND DERIVATIVE OF A LAPLACE TRANSFORM 

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#### Abstract

If $\mu$ is a positive measure on $\mathbb{R}^{n}$ with Laplace transform $L_{\mu}$, we show that there exists a positive measure $\nu$ on $\mathbb{R}^{n}$ such that $\operatorname{det} L_{\mu}^{\prime \prime}=L_{\nu}$. We deduce various corollaries from this result and, in particular, we obtain the Rao-Blackwell estimator of the determinant of the variance of a natural exponential family on $\mathbb{R}^{n}$ based on $(n+1)$ observations. A new proof and extensions of Lindsay's results on the determinants of moment matrices are also given. Finally we give a characterization of the Gaussian law in $\mathbb{R}^{n}$.


1. Introduction. If $\mu$ is a finite non-negative measure on $\mathbb{R}$, with moment generating function $m(t)$ (assumed to be finite on an open interval containing zero), Lindsay (1989) has shown that the determinant of the Hankel matrix $M_{p}(t)=\left(m^{(i+j)}(t)\right)$, whose entries are derivatives of $m(t)$, is itself, as a function of $t$, a moment generating function of another finite non-negative measure $\nu$ on $\mathbb{R}$. Motivated by this result we consider a generalization to measures on $\mathbb{R}^{n}$.

Let $\mu$ be a positive measure on $\mathbb{R}^{n}$ with Laplace transform

$$
L_{\mu}(\boldsymbol{\theta})=\int_{\mathbb{R}^{n}} \exp \langle\boldsymbol{\theta}, \mathbf{X}\rangle \mu(d \mathbf{X})
$$

and cumulant transform $k_{\mu}(\boldsymbol{\theta})=\log L_{\mu}(\boldsymbol{\theta})$. We suppose that the set of $\boldsymbol{\theta}$ in $\mathbb{R}^{n}$ such that $L_{\mu}(\boldsymbol{\theta})$ exists has a non-empty interior $\Theta(\mu)$ and we denote by $\overline{\mathscr{M}}\left(\mathbb{R}^{n}\right)$ the set of such $\mu$ and by $\mathscr{M}\left(\mathbb{R}^{n}\right)$ the set of such $\mu$ which furthermore are not concentrated on an affine hyperplane of $\mathbb{R}^{n}$. Among the moment matrices of measures on $\mathbb{R}^{n}$, by far the most important is the determinant of

$$
L_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\left[\frac{\partial^{2} L_{\mu}(\boldsymbol{\theta})}{\partial \theta_{i} \partial \theta_{j}}\right]_{i, j=1, \ldots, n},
$$

the determinant of the matrix of second order moments. Our main result shows that this determinant is again a Laplace transform of a positive measure $\nu$ on $\mathbb{R}^{n}$. On applying this result to a suitable $\mu$, we obtain Lindsay's result as Corollary 2.1 and Theorem 2.2. Finally, we apply this to simple

[^0]quadratic natural exponential families in $\mathbb{R}^{n}$ developed by Casalis (1992, 1994) as a generalization of the Morris (1982) class. We also apply it to Wishart distributions on symmetric matrices. The next application deals with the Rao-Blackwell estimator of the generalized variance of a natural exponential family in $\mathbb{R}^{n}$ in the special case of $(n+1)$ observations. We conclude with a characterization of the Gaussian laws in $\mathbb{R}^{n}$.
2. Main results. In what follows we use the notation $\mathbf{X} \otimes \mathbf{Y}$ to denote the matrix $\left(x_{i} y_{j}\right)_{i, j=1, \ldots, n}$, where $\mathbf{X}=\left(x_{1}, \ldots, x_{n}\right)^{t}$ and $\mathbf{Y}=\left(y_{1}, \ldots, y_{n}\right)^{t}$. A prime stands for the first derivative, two primes for the second derivative, $\operatorname{det} \mathbf{A}$ for the determinant of the matrix $\mathbf{A}$ and $\mu^{* k}$ for the $k$-fold convolution of the measure $\mu \in \overline{\mathscr{M}}\left(\mathbb{R}^{n}\right)$.

Our main result is the following.
Theorem 2.1. Let $\mu \in \overline{\mathscr{M}}\left(\mathbb{R}^{n}\right), \mathbf{X}_{1}, \ldots, \mathbf{X}_{n} \in \mathbb{R}^{n}$ and $\nu$ be the image of

$$
\frac{1}{n!}\left(\operatorname{det}\left[\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right]\right)^{2} \mu\left(d \mathbf{X}_{1}\right) \cdots \mu\left(d \mathbf{X}_{n}\right)
$$

by the map

$$
S:\left(\mathbb{R}^{n}\right)^{n} \rightarrow \mathbb{R}^{n}, \quad\left(\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right) \mapsto \mathbf{X}_{1}+\cdots+\mathbf{X}_{n}
$$

Then
(i) $\quad \operatorname{det} L_{\mu}^{\prime \prime}(\boldsymbol{\theta})=L_{\nu}(\boldsymbol{\theta})$
and
(ii)

$$
\operatorname{det} L_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\left(L_{\mu}(\boldsymbol{\theta})\right)^{n} \operatorname{det}\left[k_{\mu}^{\prime \prime}(\boldsymbol{\theta})+k_{\mu}^{\prime}(\boldsymbol{\theta}) \otimes k_{\mu}^{\prime}(\boldsymbol{\theta})\right]
$$

As a corollary we obtain a theorem of Lindsay [(1989, Theorem 3A] on the moment matrices of measures on $\mathbb{R}$.

Corollary 2.1 (Lindsay). Let $\alpha \in \mathscr{M}(\mathbb{R})$ and let $\beta$ be the image measure of $(1 / n!) \Pi_{i<j}\left(x_{i}-x_{j}\right)^{2} \alpha\left(d x_{1}\right) \cdots \alpha\left(d x_{n}\right)$ by the map $s: \mathbb{R}^{n} \rightarrow \mathbb{R},\left(x_{1}, \ldots, x_{n}\right) \mapsto$ $x_{1}+\cdots+x_{n}$. Then for every $t \in \Theta(\alpha)$,

$$
\operatorname{det}\left[\left(\frac{d}{d t}\right)^{i+j-2} L_{\alpha}(t)\right]_{i, j=1, \ldots, n}=L_{\beta}(t) .
$$

The most important consequence of the above results is an extension of the so-called Lindsay transform [Kokonendji and Seshadri $(1992,1994)$ and Kokonendji (1993)] of the first order for measures on $\mathbb{R}^{n}$. Let us denote by

$$
\mathscr{L}_{\mu}(\boldsymbol{\theta})=\left[\begin{array}{cc}
L_{\mu}(\boldsymbol{\theta}) & \left(L_{\mu}^{\prime}(\boldsymbol{\theta})\right)^{t} \\
L_{\mu}^{\prime}(\boldsymbol{\theta}) & L_{\mu}^{\prime \prime}(\boldsymbol{\theta})
\end{array}\right]
$$

the symmetric $(n+1) \times(n+1)$ matrix for $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$. We then have the following theorem.

THEOREM 2.2. Let $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ and let $\nu_{0}$ be the image measure of

$$
\frac{1}{(n+1)!}\left(\operatorname{det}\left[\begin{array}{cccc}
1 & 1 & & 1 \\
\mathbf{X}_{0} & \mathbf{X}_{1} & \cdots & \mathbf{X}_{n}
\end{array}\right]\right)^{2} \mu\left(d \mathbf{X}_{0}\right) \cdots \mu\left(d \mathbf{X}_{n}\right)
$$

by the map

$$
S_{0}:\left(\mathbb{R}^{n}\right)^{n+1} \rightarrow \mathbb{R}^{n}, \quad\left(\mathbf{X}_{0}, \mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right) \mapsto \mathbf{X}_{0}+\mathbf{X}_{1}+\cdots+\mathbf{X}_{n}
$$

Then for each $\boldsymbol{\theta} \in \Theta(\mu)$,

$$
\begin{equation*}
\operatorname{det} \mathscr{L}_{\mu}(\boldsymbol{\theta})=L_{\nu_{0}}(\boldsymbol{\theta}) \tag{i}
\end{equation*}
$$

and
(ii)

$$
\operatorname{det} \mathscr{L}_{\mu}(\boldsymbol{\theta})=\left(L_{\mu}(\boldsymbol{\theta})\right)^{n+1} \operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta}) .
$$

The proofs of the theorems rely on the following proposition concerning the expectation of a determinant. This appears as a problem due to Pólya and Szegö (1972), Vol. I, Part II, Chapter 1, Problem 68, pages 61-62, 247]. It generalizes a result (Theorem 2A) mentioned by Lindsay.

Proposition 2.1. Let $\eta$ be a positive measure on $\mathbb{R}^{n} \times \mathbb{R}^{n}$ such that $M=\int_{\mathbb{R}^{n} \times \mathbb{R}^{n}} \mathbf{X} \otimes \mathbf{Y} \eta(d \mathbf{X}, d \mathbf{Y})$ exists. Then

$$
\begin{aligned}
\operatorname{det} M=\frac{1}{n!} \int_{\left(\mathbb{R}^{n} \times \mathbb{R}^{n}\right)^{n}} & \left(\operatorname{det}\left[\mathbf{X}_{1} \cdots \mathbf{X}_{n}\right]\right)\left(\operatorname{det}\left[\mathbf{Y}_{1} \cdots \mathbf{Y}_{n}\right]\right) \eta\left(d \mathbf{X}_{1}, d \mathbf{Y}_{1}\right) \cdots \\
& \times \eta\left(d \mathbf{X}_{n}, d \mathbf{Y}_{n}\right)
\end{aligned}
$$

Proof of Theorem 2.1. Let $\boldsymbol{\theta} \in \Theta(\mu)$. Apply Proposition 2.1 to

$$
\eta(d \mathbf{X}, d \mathbf{Y})=\exp \{\langle\boldsymbol{\theta}, \mathbf{X}\rangle\} \mu(d \mathbf{X}) \delta_{\mathbf{x}}(d \mathbf{Y})
$$

( $\delta_{\mathbf{x}}$ being Dirac measure at $\mathbf{X}$ ). Then we obtain on the one hand from the definition of $L_{\mu}^{\prime \prime}(\boldsymbol{\theta})$,

$$
M=\int_{\mathbb{R}^{n}} \mathbf{X} \otimes \mathbf{X} \exp \{\langle\boldsymbol{\theta}, \mathbf{X}\rangle\} \mu(d \mathbf{X})=L_{\mu}^{\prime \prime}(\boldsymbol{\theta})
$$

while on the other hand, from the definition of $\nu$,

$$
\begin{aligned}
& \frac{1}{n!} \int_{\left(\mathbb{R}^{n}\right)^{n}}\left(\operatorname{det}\left[\mathbf{X}_{1} \cdots \mathbf{X}_{n}\right]\right)^{2} \exp \left\{\left\langle\boldsymbol{\theta}, \mathbf{X}_{1}\right\rangle+\cdots+\left\langle\boldsymbol{\theta}, \mathbf{X}_{n}\right\rangle\right\} \mu\left(d \mathbf{X}_{1}\right) \cdots \mu\left(d \mathbf{X}_{n}\right) \\
& \quad=L_{\nu}(\boldsymbol{\theta})
\end{aligned}
$$

This establishes (i).
Since $L_{\mu}(\boldsymbol{\theta})=\exp \left(k_{\mu}(\boldsymbol{\theta})\right)$ we obtain

$$
L_{\mu}^{\prime \prime}(\boldsymbol{\theta})=L_{\mu}(\boldsymbol{\theta})\left[k_{\mu}^{\prime \prime}(\boldsymbol{\theta})+k_{\mu}^{\prime}(\boldsymbol{\theta}) \otimes k_{\mu}^{\prime}(\boldsymbol{\theta})\right]
$$

Hence

$$
\operatorname{det} L_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\left(L_{\mu}(\boldsymbol{\theta})\right)^{n} \operatorname{det}\left[k_{\mu}^{\prime \prime}(\boldsymbol{\theta})+k_{\mu}^{\prime}(\boldsymbol{\theta}) \otimes k_{\mu}^{\prime}(\boldsymbol{\theta})\right]
$$

The proof of Corollary 2.1 relies on the following lemma.

Lemma 2.1. Let $\left(\Omega_{1}, \mathscr{A}_{1}\right)$ and $\left(\Omega_{2}, \mathscr{A}_{2}\right)$ be two measurable spaces, let $g: \Omega_{1} \rightarrow \Omega_{2}$ and $f: \Omega_{2} \rightarrow[0, \infty)$ be two measurable maps and let $\lambda$ and $\lambda_{1}$ be two measures on $\Omega_{1}$ such that

$$
\lambda_{1}\left(d \omega_{1}\right)=f\left(g\left(\omega_{1}\right)\right) \lambda\left(d \omega_{1}\right) .
$$

Then

$$
g\left(\lambda_{1}\right)\left(d \omega_{2}\right)=f\left(\omega_{2}\right) g(\lambda)\left(d \omega_{2}\right) .
$$

Proof. Let $A_{2}$ be in $\mathscr{A}_{2}$. Then

$$
\begin{aligned}
g\left(\lambda_{1}\right)\left(A_{2}\right) & \stackrel{(1)}{=} \lambda_{1}\left(g^{-1}\left(A_{2}\right)\right) \stackrel{(2)}{=} \int_{g^{-1}\left(A_{2}\right)} f\left(g\left(\omega_{1}\right)\right) \lambda\left(d \omega_{1}\right) \\
& \stackrel{(3)}{=} \int_{\Omega_{1}} I_{A_{2}}\left(g\left(\omega_{1}\right)\right) f\left(g\left(\omega_{1}\right)\right) \lambda\left(d \omega_{1}\right) \\
& \stackrel{(4)}{=} \int_{\Omega_{1}} I_{A_{2}}\left(\omega_{2}\right) f\left(\omega_{2}\right) g(\lambda)\left(d \omega_{2}\right) \\
& \stackrel{(5)}{=} \int_{A_{2}} f\left(\omega_{2}\right) g(\lambda)\left(d \omega_{2}\right) .
\end{aligned}
$$

Here (1) is the definition of $g\left(\lambda_{1}\right)\left(A_{2}\right)$, (2) is the definition of $\lambda_{1}$, (3) is a reformulation, (4) is the transport theorem applied to $I_{A_{2}}\left(\omega_{2}\right) f\left(\omega_{2}\right)$ and, finally, (5) is again a reformulation.

Proof of Corollary 2.1. We first define the map $h: \mathbb{R} \rightarrow \mathbb{R}^{n}, x \mapsto$ $\left(1, x, x^{2}, \ldots, x^{n-1}\right)^{t}$ and apply Lemma 2.1 with $\Omega_{1}=\mathbb{R}^{n}, \Omega_{2}=\left(\mathbb{R}^{n}\right)^{n}$,

$$
\begin{aligned}
& g\left(x_{1}, \ldots, x_{n}\right)=\left(h\left(x_{1}\right), \ldots, h\left(x_{n}\right)\right), \\
& f\left(\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right)=\frac{1}{n!}\left(\operatorname{det}\left[\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right]\right)^{2}
\end{aligned}
$$

and

$$
\lambda\left(d x_{1}, \ldots, d x_{n}\right)=\alpha\left(d x_{1}\right) \cdots \alpha\left(d x_{n}\right) .
$$

A simple application of the Vandermonde determinant then implies that

$$
\lambda_{1}\left(d x_{1}, \ldots, d x_{n}\right)=\frac{1}{n!} \prod_{i<j}\left(x_{i}-x_{j}\right)^{2} \alpha\left(d x_{1}\right) \cdots \alpha\left(d x_{n}\right) .
$$

Lemma 2.1 now gives

$$
g\left(\lambda_{1}\right)\left(d \mathbf{X}_{1}, \ldots, d \mathbf{X}_{n}\right)=\frac{1}{n!}\left(\operatorname{det}\left[\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right]\right)^{2} g(\lambda)\left(d \mathbf{X}_{1}, \ldots, d \mathbf{X}_{n}\right),
$$

but

$$
g(\lambda)\left(d \mathbf{X}_{1}, \ldots, d \mathbf{X}_{n}\right)=h(\alpha)\left(d \mathbf{X}_{1}\right) \cdots h(\alpha)\left(d \mathbf{X}_{n}\right) .
$$

With the map $S:\left(\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right) \mapsto \mathbf{X}_{1}+\cdots+\mathbf{X}_{n}$ applied to $g\left(\lambda_{1}\right)$ we obtain, using Theorem 2.1, the Laplace transform of $S\left(g\left(\lambda_{1}\right)\right)$, namely, $L_{S\left(g\left(\lambda_{1}\right)\right)}(\boldsymbol{\theta})$ as

$$
\begin{aligned}
\int_{\left(\mathbb{R}^{n}\right)^{n}} & \frac{1}{n!}\left(\operatorname{det}\left[\mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right]\right)^{2} \exp \left\{\left\langle\boldsymbol{\theta}, \mathbf{X}_{1}+\cdots+\mathbf{X}_{n}\right\rangle\right\} h(\alpha)\left(d \mathbf{X}_{1}\right) \cdots h(\alpha)\left(d \mathbf{X}_{n}\right) \\
& =\operatorname{det} L_{h(\alpha)}^{\prime \prime}(\boldsymbol{\theta})
\end{aligned}
$$

From the definition of $h(\alpha)$ we have

$$
L_{h(\alpha)}(\boldsymbol{\theta})=\int_{\mathbb{R}} \exp \left\{\theta_{1}+\theta_{2} x+\cdots+\theta_{n} x^{n-1}\right\} \alpha(d x) .
$$

Hence

$$
\operatorname{det} L_{h(\alpha)}^{\prime \prime}(\boldsymbol{\theta})=\operatorname{det}\left[\int_{\mathbb{R}} x^{i+j-2} \exp \left\{\theta_{1}+\theta_{2} x+\cdots+\theta_{n} x^{n-1}\right\} \alpha(d x)\right]_{i, j=1, \ldots, n} .
$$

We now take $\left(\theta_{1}, \ldots, \theta_{n}\right)=(0, t, 0, \ldots, 0)$ and obtain

$$
\begin{aligned}
\operatorname{det} L_{h(\alpha)}^{\prime \prime}(0, t, 0, \ldots, 0) & =\operatorname{det}\left[\left(\frac{d}{d t}\right)^{i+j-2} L_{\alpha}(t)\right]_{i, j=1, \ldots, n} \\
& =L_{S\left(g\left(\lambda_{1}\right)\right)}(0, t, \ldots, 0) .
\end{aligned}
$$

Finally note that if $p$ is the projection map $\left(y_{1}, \ldots, y_{n}\right) \mapsto y_{2}$, then $s$ as defined in Corollary 2.1 is $s=p \circ S \circ g$. Thus $\beta=s\left(\lambda_{1}\right)=p\left(S\left(g\left(\lambda_{1}\right)\right)\right)$. Since $L_{S\left(g\left(\lambda_{1}\right)\right)}(0, t, 0, \ldots, 0)=L_{p\left(S\left(g\left(\lambda_{1}\right)\right)\right)}(t)$, we have

$$
L_{\beta}(t)=\operatorname{det}\left[\left(\frac{d}{d t}\right)^{i+j-2} L_{\mu}(t)\right]_{i, j=1, \ldots, n}
$$

Proof of Theorem 2.2. We apply Theorem 2.1 to dimension $n+1$ instead of $n$ with $\alpha\left(d x_{0}, \ldots, d x_{n}\right)=\delta_{1}\left(d x_{0}\right) \mu\left(d x_{1}, \ldots, d x_{n}\right)$. Thus if $\boldsymbol{\theta} \in \Theta(\mu)$ and $\theta_{0} \in \mathbb{R}$, we have $L_{\alpha}\left(\theta_{0}, \boldsymbol{\theta}\right)=\exp \left(\theta_{0}\right) L_{\mu}(\boldsymbol{\theta})$ and

$$
L_{\alpha}^{\prime \prime}\left(\theta_{0}, \boldsymbol{\theta}\right)=\exp \left(\theta_{0}\right)\left[\begin{array}{cc}
L_{\mu}(\boldsymbol{\theta}) & \left(L_{\mu}^{\prime}(\boldsymbol{\theta})\right)^{t} \\
L_{\mu}^{\prime}(\boldsymbol{\theta}) & L_{\mu}^{\prime \prime}(\boldsymbol{\theta})
\end{array}\right]
$$

Setting $\theta_{0}=0$ we obtain (i). The second equality (ii) is obtained by observing that

$$
\begin{aligned}
& L_{\mu}(\boldsymbol{\theta})=\exp k_{\mu}(\boldsymbol{\theta}) \\
& L_{\mu}^{\prime}(\boldsymbol{\theta})=L_{\mu}(\boldsymbol{\theta}) k_{\mu}^{\prime}(\boldsymbol{\theta}) \\
& L_{\mu}^{\prime \prime}(\boldsymbol{\theta})=L_{\mu}(\boldsymbol{\theta})\left[k_{\mu}^{\prime \prime}(\boldsymbol{\theta})+k_{\mu}^{\prime}(\boldsymbol{\theta}) \otimes k_{\mu}^{\prime}(\boldsymbol{\theta})\right]
\end{aligned}
$$

and hence that

$$
\begin{aligned}
\operatorname{det}\left[\begin{array}{cc}
L_{\mu}(\boldsymbol{\theta}) & \left(L_{\mu}^{\prime}(\boldsymbol{\theta})\right)^{t} \\
L_{\mu}^{\prime}(\boldsymbol{\theta}) & \left(L_{\mu}^{\prime}(\boldsymbol{\theta})\right)
\end{array}\right] & =\left(L_{\mu}(\boldsymbol{\theta})\right)^{n+1} \operatorname{det}\left[\begin{array}{cc}
1 & \left(k_{\mu}(\boldsymbol{\theta})\right)^{t} \\
k_{\mu}^{\prime}(\boldsymbol{\theta}) & k_{\mu}^{\prime \prime}(\boldsymbol{\theta})+k_{\mu}^{\prime}(\boldsymbol{\theta}) \otimes k_{\mu}^{\prime}(\boldsymbol{\theta})
\end{array}\right] \\
& =L_{\mu}^{n+1}(\boldsymbol{\theta}) \operatorname{det} k_{\mu}^{\prime}(\boldsymbol{\theta}) .
\end{aligned}
$$

## 3. Applications.

3.1. Quadratic variances. First we give a brief summary of natural exponential families (NEF) in $\mathbb{R}^{n}$ and some important properties associated with them.

To each $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ and $\boldsymbol{\theta} \in \Theta(\mu)$, the set of probabilities

$$
F=F(\mu)=\{P(\boldsymbol{\theta}, \mu)(d \mathbf{X}) ; \boldsymbol{\theta} \in \Theta(\mu)\},
$$

where

$$
P(\boldsymbol{\theta}, \mu)(d \mathbf{X})=\exp \left\{\langle\boldsymbol{\theta}, \mathbf{X}\rangle-k_{\mu}(\boldsymbol{\theta})\right\} \mu(d \mathbf{X})
$$

is defined as the natural exponential family generated by $\mu$. The measure $\mu$ is said to be a basis of $F$. It is well known that $k_{\mu}(\boldsymbol{\theta})$ is strictly convex and real analytic on $\Theta(\mu)$ and that its first derivative $k_{\mu}^{\prime}(\boldsymbol{\theta})$, where

$$
k_{\mu}^{\prime}(\boldsymbol{\theta})=\int_{\mathbb{R}^{n}} \mathbf{X} P(\boldsymbol{\theta}, \mu)(d \mathbf{X})
$$

defines a map from $\Theta(\mu)$ to $M_{F}$. If $F=F(\mu)$, then $M_{F}=k_{\mu}^{\prime}(\Theta(\mu))$ is called the mean domain of $F$. The map $\boldsymbol{\theta} \mapsto k_{\mu}^{\prime}(\boldsymbol{\theta})$ is a bijection between $\Theta(\mu)$ and $M_{F}$, and hence we can consider the inverse of $k_{\mu}^{\prime}(\boldsymbol{\theta})$, namely, $\psi_{\mu}: M_{F} \rightarrow \Theta(\mu)$. For each $\mathbf{m} \in M_{F}$ we let $P(\mathbf{m}, F)=P\left(\psi_{\mu}(\mathbf{m}), \mu\right)$ and the bijective map $M_{F} \Rightarrow F, \mathbf{m} \mapsto P(\mathbf{m}, F)$ defines a parametrization of $F$ by the mean.

Since $P(\mathbf{m}, F)$ is a distribution in $\mathbb{R}^{n}$, its covariance matrix is

$$
V_{F}(\mathbf{m})=\int_{\mathbb{R}^{n}}(\mathbf{X}-\mathbf{m})(\mathbf{X}-\mathbf{m})^{t} P(\mathbf{m}, F)(d \mathbf{X})
$$

for each $\mathbf{m} \in M_{F}$.
The ( $n \times n$ ) matrix $V_{F}(\mathbf{m})$ defined on $M_{F}$ is called the variance function of $P(\mathbf{m}, F)$ or $F$. Note that $V_{F}(\mathbf{m})=k_{\mu}^{\prime \prime}\left(\psi_{\mu}(\mathbf{m})\right)$. In fact, $k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$ is a Hessian operator and in the canonical basis has the matrix representation

$$
\left(\frac{\partial^{2} k_{\mu}}{\partial \theta_{i} \partial \theta_{j}}\right)_{i, j=1, \ldots, n} .
$$

The generalized variance [Wilks (1932)] of $F$ is $\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$.
Casalis (1994) introduced natural exponential family (NEF) with variance functions of the form

$$
\begin{equation*}
V_{F}(\mathbf{m})=a \mathbf{m} \otimes \mathbf{m}+B(\mathbf{m})+c, \tag{3.1}
\end{equation*}
$$

where $a \in \mathbb{R}, B(\mathbf{m})$ is a matrix ( $n \times n$ ) of elements linear in $\mathbf{m}$ and $c$ is a matrix ( $n \times n$ ) of constants. Casalis calls these NEF simple quadratic. We choose instead to call the set of NEF with $V_{F}(\mathbf{m})$ as in (3.1) the Casalis class of NEF; it generalizes the Morris class from $\mathbb{R}$ to $\mathbb{R}^{n}$. Casalis has made an exhaustive study and shows that there are exactly $(2 n+4)$ such types. The following definition makes precise the term "type."

Definition 3.1. Let $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ and let $\Lambda(\mu)$ (called the Jørgensen set) be the set of positive numbers $\lambda$ such that there exists a measure $\mu_{\lambda} \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ for which $L_{\mu}(\boldsymbol{\theta})=\left(L_{\mu}(\boldsymbol{\theta})\right)^{\lambda}$ is the Laplace transform of $\mu_{\lambda}$. Two NEFs $F_{1}$ and $F_{2}$ are said to be of the same type if there exist $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right), \lambda \in \Lambda(\mu)$ and an affinity $\phi$ in $\mathbb{R}^{n}$ such that with $\mu^{\prime}=\phi\left(\mu_{\lambda}\right)$ one has $F_{1}=F(\mu)$ and $F_{2}=F\left(\mu^{\prime}\right)$.

Below we give a list of the $(2 n+4)$ types together with their cumulant transforms and variance functions as given by Casalis. We also include the value of $\operatorname{det} k^{\prime \prime}(\boldsymbol{\theta})$ in each case, the computation of which is straightforward.

1. Poisson-Gaussian types $(n+1):(P G)_{k}, k=0, \ldots, n$,

$$
\mu(d \mathbf{X})=\left\{\sum_{j \in \mathbb{N}^{k}} \frac{\delta_{j}\left(d \mathbf{X}_{1}\right)}{j!}\right\} \frac{\exp \left\{-\frac{1}{2} \sum_{i=k+1}^{n} x_{i}^{2}\right\}}{(2 \pi)^{(n-k) / 2}}\left(d \mathbf{X}_{2}\right)
$$

where $d X_{1}=d x_{1}, \ldots, d x_{k}, d X_{2}=d x_{k+1}, \ldots, d x_{n}, \quad \Theta(\mu)=M_{F}=\mathbb{R}^{n}$, $k_{\mu}(\boldsymbol{\theta})=\sum_{i=1}^{k} e^{\theta_{i}}+\sum_{i=k+1}^{n}\left(\theta_{i}^{2} / 2\right)$, $\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\exp \left(\theta_{1}+\cdots+\theta_{n}\right)$, $\delta_{j}$ is Dirac mass at $j, \mathbf{X}_{1}=\left(x_{1}, \ldots, x_{k}\right), \quad \mathbf{X}_{2}=\left(x_{k+1}, \ldots, x_{n}\right)$ and $V_{F}(\mathbf{m})=$ $\operatorname{diag}\left(m_{1}, \ldots, m_{k}, 1, \ldots, 1\right)$.
2. Multinomial type ( $M$ ). Let $N$ be a positive integer, let $e_{0}$ be the null vector and let $\left(e_{1}, \ldots, e_{n}\right)$ be the canonical basis of $\mathbb{R}^{n}$. Define

$$
\mu=\left(\sum_{i=0}^{n} \delta_{e_{i}} \mathbb{R}\right)^{*^{N}} .
$$

Then $\Theta(\mu)=\mathbb{R}^{n}, M_{F}=\left\{\mathbf{m} \in \mathbb{R}^{n} ; m_{i}>0, \forall i, \sum_{i=1}^{n} m_{i}<N\right\}, k_{\mu}(\boldsymbol{\theta})=$ $N \log \left(1+\sum_{i=1}^{n} e^{\theta_{i}}\right)$,

$$
\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\exp \left\{-\frac{(n+1)}{N} k_{\mu}(\boldsymbol{\theta})+\theta_{1}+\cdots+\theta_{n}+n \log N\right\}
$$

and $V_{F}(\mathbf{m})=\operatorname{diag}\left(m_{1}, \ldots, m_{n}\right)-(\mathbf{m} \otimes \mathbf{m}) / N$.
3. Hyperbolic ( $H$ ). For $\lambda>0$ we define

$$
\mu_{\lambda}(d \mathbf{X})=\nu_{\lambda}\left(d X_{1}\right) \alpha_{\lambda+\sum_{i=1}^{n-1} x_{i}}(d y)
$$

where

$$
\nu_{\lambda}=\left(\delta_{0}-\sum_{i=1}^{n-1} \delta_{e_{i}}\right)^{*^{(-\lambda)}}, \quad \alpha_{p}(d y)=\frac{2^{p-2}|\Gamma((p+i y) / 2)|^{2}}{\Gamma(p)(\Gamma(p / 2))^{2}} d y
$$

$p>0$ and $d \mathbf{X}_{1}=d x_{1}, \ldots, d x_{n-1}$. Then $\Theta(\mu)=\left\{\left(\theta_{1}, \ldots, \theta_{n}\right) ;-\pi / 2<\theta_{n}<\right.$ $\pi / 2$ and $\left.e^{\theta_{1}}+\cdots+e^{\theta_{n-1}}<\cos \theta_{n}\right\}, \quad M_{F}=(0, \infty)^{n-1} \times \mathbb{R}, \quad k_{\mu}(\boldsymbol{\theta})=$ $-p\left\{\log \left\{\cos \theta_{n}-\sum_{i=1}^{n-1} e^{\theta_{i}}\right\}\right.$,

$$
\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\exp \left\{\frac{(n+1)}{\lambda} k_{\mu}(\boldsymbol{\theta})+\theta_{1}+\cdots+\theta_{n}+n \log \lambda\right\}
$$

and

$$
V_{F}(\mathbf{m})=\operatorname{diag}\left(m_{1}, \ldots, m_{n-1}, \lambda+\sum_{i=1}^{n-1} m_{i}\right)+\frac{\mathbf{m} \otimes \mathbf{m}}{\lambda} .
$$

The NEF corresponding to the law of $\left(\mathbf{X}_{1}, \mathbf{Y}\right)$ is $F\left(\mu_{\lambda}\right)$, where $\mathbf{X}_{1}=$ ( $X_{1}, \ldots, X_{n-1}$ ) follows a negative multinomial law with parameter $\lambda$ and conditionally on $\mathbf{X}_{1}$ the random variable $Y$ follows the hyperbolic secant law with parameter $\left(\lambda+\sum_{i=1}^{n-1} X_{i}\right)$.
4. Negative multinomial-gamma types $(n+1)$. $(N M-G a)_{k}: k=0,1, \ldots, n$. For $0 \leq k \leq n$ and $\lambda>0$ we define $\mu_{\lambda}$ by

$$
\mu_{\lambda}(d \mathbf{X})=\nu_{\lambda}\left(d \mathbf{X}_{1}\right) \eta_{\left(\lambda+\sum_{i=1}^{k} x_{i}\right)}(d y) \prod_{i=k+2}^{n} \alpha_{y}\left(d z_{i}\right),
$$

where $\nu_{\lambda}$ is the measure defined in (3), $\eta_{p}(d y)=y^{p-1} /(\Gamma(p)) I_{\mathbb{R}}+(y) d y$ and $\alpha_{y}(d z)=1 / \sqrt{2 \pi y} \exp \left(-z^{2} / 2 y\right) d z$.
The NEF corresponding to the law of $(X, Y, Z)$ is $F\left(\mu_{\lambda}\right)$, where $X=$ $\left(X_{1}, \ldots, X_{k}\right)$ has the negative multinomial law with parameter $\lambda, Y$ conditionally on $X$ has a gamma law with shape parameter $\left(\lambda+\sum^{k} X_{i}\right)$ and $Z=\left(Z_{k+2}, \ldots, Z_{n}\right)$ conditionally on ( $X, Y$ ) is multinormal with covariance $Y I_{n-k-1}$. Note that this definition includes an arbitrary parameter in $\mathbb{R}^{k}$ for $X$, an arbitrary scale parameter for $Y$ and an arbitrary mean parameter for $Z$. The limiting cases $k=0, k=n-1$ and $k=n$ have obvious interpretations when an empty sum is replaced by zero. We then have

$$
\begin{aligned}
\Theta(\mu) & =\left\{\boldsymbol{\theta} \left\lvert\,-e^{\theta_{1}}-\cdots-e^{\theta_{k}}-\theta_{k+1}-\frac{\theta_{k+2}^{2}}{2} \cdots-\frac{\theta_{n}^{2}}{2}>0\right.\right\}, \\
M_{F} & =(0, \infty)^{k+1} \times \mathbb{R}^{n-k-1}, \\
k_{\mu}(\boldsymbol{\theta}) & =-\lambda \log \left[-\sum_{i=1}^{k} e^{\theta_{i}}-\theta_{k+1}-\sum_{i=k+2}^{n} \frac{\theta_{i}^{2}}{2}\right], \\
\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta}) & =\exp \left\{\frac{n+1}{\lambda} k_{\mu}(\boldsymbol{\theta})+\theta_{1}+\cdots+\theta_{n}+n \log \lambda\right\}
\end{aligned}
$$

and

$$
V_{F}(\mathbf{m})=\operatorname{diag}\left(m_{1}, \ldots, m_{k}, 0, m_{k+1}, \ldots, m_{k+1}\right)+\frac{\mathbf{m} \otimes \mathbf{m}}{\lambda} .
$$

We now prove the following theorem.

Theorem 3.1. Let $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ such that $F=F(\mu)$ belongs to the Casalis class $\left[\right.$ thus $V_{F}(\mathbf{m})$ is given by (3.1)]. Let $\nu_{0}$ be defined from $\mu$ as in Theorem 2.2. Then $F\left(\nu_{0}\right)$ and $F(\mu)$ are of the same type.

Proof. From the above listing we see by inspection that there exists $(\mathbf{A}, b, c) \in \mathbb{R}^{n} \times \mathbb{R} \times \mathbb{R}$ such that

$$
\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})=\exp \left\{b k_{\mu}(\boldsymbol{\theta})+\langle\boldsymbol{\theta}, \mathbf{A}\rangle+c\right\} .
$$

From Theorem 2.2 we see that

$$
\begin{aligned}
k_{\nu_{0}}(\boldsymbol{\theta}) & =(n+1) k_{\mu}(\boldsymbol{\theta})+\log \left[\operatorname{det}\left\{V_{F(\mu)}\left(k_{\mu}^{\prime}(\boldsymbol{\theta})\right)\right\}\right] \\
& =(n+1+b) k_{\mu}(\boldsymbol{\theta})+\langle\boldsymbol{\theta}, \mathbf{A}\rangle+c .
\end{aligned}
$$

Hence

$$
k_{\nu_{0}}^{\prime}(\boldsymbol{\theta})=(n+1+b) k_{\mu}^{\prime}(\boldsymbol{\theta})+\mathbf{A} .
$$

Writing $\mathbf{m}^{*}=k_{\nu_{0}}^{\prime}(\boldsymbol{\theta})$ and $b^{*}=n+1+b$, we have

$$
\mathbf{m}^{*}=b^{*} \mathbf{m}+\mathbf{A} \quad \text { and } \quad V_{F\left(\nu_{0}\right)}\left(\mathbf{m}^{*}\right)=b^{*} V_{F(\mu)}\left(\frac{\mathbf{m}^{*}-\mathbf{A}}{b^{*}}\right) .
$$

This shows that $F\left(\nu_{0}\right)$ and $F(\mu)$ are of the same type.
This result generalizes Lindsay's verification for the Morris families for $n=1$.

The Casalis class does not cover the whole set of NEF with a quadratic variance. For instance, let $E$ be the space of $(d \times d)$ real symmetric matrices and let $S$ be the cone in $E$ of positive definite matrices. Consider the standard Wishart distribution $W(2 p, \Sigma)$ concentrated on $\bar{S}$ with $\Sigma$ in $S$ and $p$ in

$$
\begin{equation*}
\Lambda=\left\{\frac{1}{2}, 1, \frac{3}{2}, \ldots, \frac{d-1}{2}\right\} \cup\left(\frac{d-1}{2},+\infty\right) . \tag{3.2}
\end{equation*}
$$

Then it is known that the NEF

$$
\begin{equation*}
F_{p}=\{W(2 p, \Sigma) ; \Sigma \in S\} \tag{3.3}
\end{equation*}
$$

has a quadratic variance [Letac (1989)].
We now prove the following theorem.
Theorem 3.2. Let $\mu \in \mathscr{M}(E)$ such that $F(\mu)=F_{p}$ with $F_{p}$ given by (3.3) and $p$ in $\Lambda$ given by (3.2). Let $\nu_{0}$ be defined from $\mu$ as in Theorem 2.2. Then $F\left(\nu_{0}\right)=F_{p^{\prime}}$, where $p^{\prime}=p\{1+(d(d+1) / 2)\}+(d+1)$.

Proof. Without loss of generality we take $\mu=\mu_{p}$, where

$$
\mu_{p}(d X)=\frac{1}{\Gamma_{d}(p)}(\operatorname{det} X)^{p-1-((d-1) / 2)} I_{S}(X) d X
$$

where

$$
\Gamma_{d}(p)=2^{d p} \pi^{(d(d-1)) / 4} \prod_{i=0}^{d-1} \Gamma\left(p-\frac{i}{2}\right), \quad \Theta\left(\mu_{p}\right)=-S
$$

$S$ being the cone of ( $d \times d$ ) symmetric positive definite matrices and $p>$ ( $d-1$ )/2. Furthermore,

$$
L_{\mu_{p}}(\theta)=\int_{S} \exp \left\{\frac{1}{2} \operatorname{tr}(\theta X)\right\} \mu_{p}(d X)=(\operatorname{det}(-2 \theta))^{-p}
$$

so that

$$
k_{\mu_{p}}(\theta)=-p \log (\operatorname{det}(-2 \theta))
$$

Then

$$
\operatorname{det} k_{\mu_{p}}^{\prime \prime}(\theta)=p^{(d(d+1)) / 2}(\operatorname{det}(-\theta))^{-d-1}
$$

To see the above step we use three classical facts:
(a) The differential of $S \rightarrow \mathbb{R}, \theta \mapsto-\log (\operatorname{det} \theta)$ is $\theta^{-1}$.
(b) The differential of $S \rightarrow S, \theta \mapsto \theta^{-1}$ is $d \theta^{-1}=-\theta^{-1} d \theta \theta^{-1}$.
(c) If $A$ is any ( $d \times d$ ) matrix, the determinant of the linear endomorphism $\phi_{A}$ of the space of symmetric $(d \times d)$ matrices defined by $\phi_{A}(M)=$ $A M A^{t}$ is $\operatorname{det} \phi_{A}=(\operatorname{det} A)^{d+1}$.

Hence with $n=(d(d+1)) / 2$ (dimension of $E)$ we have

$$
k_{\nu_{0}}(\theta)=\frac{p^{\prime}}{p} k_{\mu_{p}}(\theta)+\log \text { const }
$$

where $p^{\prime}$ is defined in Theorem 3.2. Thus $F\left(\nu_{0}\right)=F_{p^{\prime}}$.
3.2. Rao-Blackwell estimation of $\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$. The following theorem provides the key to obtaining the Rao-Blackwell estimator of the generalized variance of a NEF generated by $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ in the case of $(n+1)$ observations.

Theorem 3.3. Let $\mu \in \mathscr{M}\left(\mathbb{R}^{n}\right)$ and let $\nu_{0}$ be the image measure defined in Theorem 2.2. Denote by $\mu^{*(n+1)}$ the image measure of $\mu\left(d \mathbf{X}_{0}\right) \mu\left(d \mathbf{X}_{1}\right) \cdots$ $\mu\left(d \mathbf{X}_{n}\right)$ by the map $S_{0}$ of Theorem 2.2. Suppose that there exists $C(\mathbf{X})$ such that

$$
\nu_{0}(d \mathbf{X})=C(\mathbf{X}) \mu^{*(n+1)}(d \mathbf{X}) .
$$

Then $C\left(\mathbf{X}_{0}+\mathbf{X}_{1}+\cdots+\mathbf{X}_{n}\right)$ is the Rao-Blackwell estimator of $\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$ based on $(n+1)$ observations $\mathbf{X}_{0}, \ldots, \mathbf{X}_{n}$.

Proof. From Theorem 2.2 we have, for each $\boldsymbol{\theta} \in \Theta(\mu)$,

$$
\begin{aligned}
\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta}) & =\frac{L_{\nu_{0}}(\boldsymbol{\theta})}{L_{\mu^{*(n+1)}}(\boldsymbol{\theta})} \\
& =\int_{\left(\mathbb{R}^{n}\right)^{n+1}} C\left(\mathbf{X}_{0}+\cdots+\mathbf{X}_{n}\right) \prod_{i=0}^{n} P(\boldsymbol{\theta}, \mu)\left(d \mathbf{X}_{i}\right) .
\end{aligned}
$$

As an illustration of Theorem 3.3 we give below the Rao-Blackwell estimators of the Casalis class as well as the Wishart families.

Example 3.1. Cases of the Casalis class.
Case 1. Poisson-Gaussian types $(P G)_{k}, k=0,1, \ldots, n$, give for $x_{1} \neq 0$, $\ldots, x_{k} \neq 0$,

$$
C(\mathbf{X})=\frac{\nu_{0}(d \mathbf{X})}{\mu^{*(n+1)}(d \mathbf{X})}=\frac{\mu_{n+1} * \delta_{\mathbf{e}_{1}+\cdots+\mathbf{e}_{k}}(d \mathbf{X})}{\mu_{n+1}(d \mathbf{X})}=x_{1} \cdots x_{k} .
$$

Note that it is independent of the Gaussian component.
Case 2. In the multinomial case we have

$$
\begin{aligned}
L_{\nu_{0}}(\boldsymbol{\theta}) & =N^{n}\left(1+\sum_{i=1}^{n} \exp \left(\theta_{i}\right)\right)^{(n+1)(N-1)} \exp \left(\sum_{i=1}^{n} \theta_{i}\right) \\
L_{\mu^{*(n+1)}}(\boldsymbol{\theta}) & =\left(1+\sum_{i=1}^{n} \exp \left(\theta_{i}\right)\right)^{(n+1) N}
\end{aligned}
$$

Note that $\nu_{0}$ is concentrated on the tetrahedron $T_{0}$ in $\mathbb{R}^{n}$ with vertices $\mathbf{p}=\sum_{i=1}^{n} \mathbf{e}_{i},(n+1)(N-1) \mathbf{e}_{j}+\mathbf{p}, j=1,2, \ldots, n$, while $\mu^{*(n+1)}$ is concentrated on the tetrahedron $T_{1}$ in $\mathbb{R}^{n}$ with vertices $\mathbf{0},(n+1) N \mathbf{e}_{j}$, which contain $T_{0}$. If $\mathbf{X}=\left(x_{1}, \ldots, x_{n}\right)$ is in $T_{0}$, then

$$
\nu_{0}(\mathbf{X})=N^{n}[(n+1)(N-1)]!/\left(x_{1}-1\right)!\cdots\left(x_{n}-1\right)!,
$$

whereas $\mu^{*(n+1)}(\mathbf{X})=[(n+1) N]!/ x_{1}!\cdots x_{n}$ !
Thus

$$
\begin{aligned}
C(\mathbf{X}) & =\frac{\nu_{0}(\mathbf{X})}{\mu^{*(n+1)}}(\mathbf{X}) \\
& =\frac{N^{n}[(n+1)(N-1)]}{[(n+1) N]} x_{1} \cdots x_{n} \quad \text { if } X \in T_{0}
\end{aligned}
$$

and $C(\mathbf{X})=0$ if $X \notin T_{0}$.
Case 3 . For the hyperbolic type ( $H$ ) we have

$$
L_{\mu_{\lambda}^{*(n+1)}}(\boldsymbol{\theta})=\left(\cos \theta_{n}-\sum_{i=1}^{n-1} e^{\theta_{i}}\right)^{-\lambda(n+1)}=L_{\mu_{\lambda(n+1)}}(\boldsymbol{\theta}),
$$

while from Theorem 2.2,

$$
L_{\nu_{0}}(\boldsymbol{\theta})=\lambda^{n} L_{\mu_{(\lambda+1)(n+1)}}(\boldsymbol{\theta}) \exp \left(\sum_{i=1}^{n-1} \theta_{i}\right)
$$

Hence for $x_{1} \neq 0, \ldots, x_{k} \neq 0$,

$$
C(\mathbf{X})=\frac{\nu_{0}(d \mathbf{X})}{\mu_{\lambda(n+1)}(d \mathbf{X})}=\frac{\lambda^{n} \mu_{(\lambda+1)(n+1)} * \delta_{\mathbf{e}_{1}+\cdots+\mathbf{e}_{n-1}}(d \mathbf{X})}{\mu_{\lambda(n+1)}(d \mathbf{X})}
$$

[Observe that the density corresponding to $\nu_{0}$ suffers a translation for the support of $\left(x_{1}, \ldots, x_{k}\right)$ by one unit because of the factor $\exp \left(\sum_{i=1}^{n-1} \theta_{i}\right)$.]

Letting $\beta=\sum_{j=1}^{n-1} x_{j}+\lambda_{1}$, we obtain

$$
C(\mathbf{X})=\frac{2^{4} \lambda^{n}\left(\beta^{2}+x_{n}^{2}\right) x_{1} \cdots x_{n-1}}{\lambda_{1}\left(\lambda_{1}+1\right) \cdots\left(\lambda_{1}+n\right) \beta^{2}}
$$

Case 4. For the negative multinomial-gamma type, $(N M-G a)_{k}, k=$ $0,1, \ldots, n$, we have for $x_{1} \neq 0, \ldots, x_{k} \neq 0$,

$$
L_{\mu}(\boldsymbol{\theta})=\left[-\sum_{i=1}^{k} e^{\theta_{i}}-\theta_{k+1}-\sum_{i=k+2}^{n} \frac{\theta_{i}^{2}}{2}\right]^{-\lambda}
$$

so that $L_{\mu^{*}(n+1)}(\boldsymbol{\theta})=\left[L_{\mu}(\boldsymbol{\theta})\right]^{n+1}$, while from Theorem 2.2,

$$
L_{\nu_{0}}(\boldsymbol{\theta})=\lambda^{n}\left[-\sum_{i=1}^{k} \exp \left(\theta_{i}\right)-\theta_{k+1}-\sum_{i=k+2}^{n} \frac{\theta_{i}^{2}}{2}\right]^{-(\lambda+1)(n+1)} \exp \left(\sum_{i=1}^{k} \theta_{i}\right)
$$

Thus we obtain

$$
C(\mathbf{X})=\frac{\lambda^{n} \Gamma(\lambda(n+1))}{\Gamma((\lambda+1)(n+1))} x_{1} \cdots x_{k}\left(x_{k+1}\right)^{n-k+1}
$$

The Rao-Blackwell estimator of $\operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$ is therefore $C\left(\mathbf{X}_{0}+\cdots+\mathbf{X}_{n}\right)$ with $C(\mathbf{X})$ as given above.

Example 3.2. For the Wishart families we observe that (Theorem 3.2)

$$
\nu_{0}(d X)=\frac{2^{d(d+1)} p^{(d(d+1)) / 2}}{\Gamma_{d}\left(p_{0}\right)}(\operatorname{det} X)^{p_{0}-1-((d-1) / 2)} I_{S}(X)(d X)
$$

with $p_{0}=p\left[1+\frac{1}{2}(d(d+1))\right]+(d+1)$, while

$$
\mu^{*(n+1)}(d X)=\frac{1}{\Gamma_{d}\left(p_{0}-d-1\right)}(\operatorname{det} X)^{p_{0}-(d+1)-1-((d-1) / 2)} I_{S}(X)(d X)
$$

so that

$$
C(X)=\frac{2^{d(d+1)} p^{(d(d+1)) / 2} \Gamma_{d}\left(p_{0}-d-1\right)}{\Gamma_{d}\left(p_{0}\right)}(\operatorname{det} X)^{d+1}
$$

If $X_{1}, \ldots, X_{m}$ are i.i.d. random variables with Wishart distribution $W(2 p, \Sigma)$ with $\theta=-\Sigma^{-1} / 2$, then from the well-known formula [Muirhead (1982)]

$$
\mathbb{E}\left((\operatorname{det} X)^{r}\right)=(\operatorname{det}(-2 \theta))^{r} 2^{d r} \frac{\Gamma_{d}(r+p)}{\Gamma_{d}(p)},
$$

we have

$$
\mathbb{E}\left(\operatorname{det}\left(X_{1}+\cdots+X_{m}\right)\right)^{r}=(\operatorname{det}(-2 \theta))^{r} 2^{d r} \frac{\Gamma_{d}(r+m p)}{\Gamma_{d}(p)}
$$

Since $\operatorname{det} k_{\mu_{p}}^{\prime \prime}(\theta)=\operatorname{const}(\operatorname{det}(-2 \theta))^{d+1}$ for $r=d+1$, we obtain

$$
\mathbb{E}\left(\operatorname{det}\left(X_{1}+\cdots+X_{q}\right)\right)^{d+1}=\left(\operatorname{det} k_{\mu_{p}}^{\prime \prime}\right) \times \text { const. }
$$

Thus with $q$ observations $X_{1}, \ldots, X_{q}$, $\operatorname{const}\left(\operatorname{det}\left(X_{1}+\cdots+X_{q}\right)\right)^{d+1}$ is the Rao-Blackwell estimator of det $k_{\mu_{p}}^{\prime}(\theta)$. Hence our method is not very efficient since it gives the estimator only for the case $q=1+(d(d+1) / 2)$.

Our results in the case of NEF with simple quadratic variance structure can be regarded as a partial (since we consider $n+1$ observations) generalization of the result for Morris families in one dimension, namely, the Rao-Blackwell estimator of $k_{\mu}^{\prime \prime}(\theta)$ is $V_{F(\mu)}\left(\left(X_{1}+\cdots+X_{q}\right) / q\right) q /(q+a)$, where $V_{F(\mu)}(m)=a m^{2}+b m+c[$ Letac (1992) $]$.
3.3. Characterization of Gaussian laws in $\mathbb{R}^{n}$. Theorem 2.2 also implies the following remarkable fact about Gaussian laws in $\mathbb{R}^{n}$. If $\mathbf{X}_{0}, \mathbf{X}_{1}, \ldots, \mathbf{X}_{n} \in$ $\mathbb{R}^{n}$, then

$$
v\left(\mathbf{X}_{0}, \mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right)=\frac{1}{(n+1)!} \operatorname{det}\left[\begin{array}{cccc}
1 & 1 & \cdots & 1 \\
\mathbf{X}_{0} & \mathbf{X}_{1} & \cdots & \mathbf{x}_{n}
\end{array}\right]
$$

is the algebraic volume of the tetrahedron with vertices $\mathbf{X}_{0}, \ldots, \mathbf{X}_{n}$. Let $\mu$ in $\mathscr{M}\left(\mathbb{R}^{n}\right)$ be also a probability; consider the two probabilities in $\left(\mathbb{R}^{n}\right)^{n+1}$ :

$$
\begin{aligned}
& P_{1}=\mu \otimes \cdots \otimes \mu, \\
& P_{0}=K v^{2} P_{1},
\end{aligned}
$$

where $K$ is a normalization constant. Denote by $Q_{0}$ and $Q_{1}$ the respective images of $P_{0}$ and $P_{1}$ by the map

$$
\left(\mathbf{X}_{0}, \mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right) \mapsto \mathbf{X}_{0}+\cdots+\mathbf{X}_{n}
$$

A reformulation of Theorem 2.2 gives

$$
\begin{equation*}
L_{Q_{0}}(\boldsymbol{\theta})=L_{Q_{1}}(\boldsymbol{\theta})\left(\operatorname{det}\left(k_{\mu}^{\prime \prime}(\boldsymbol{\theta})\right) / \operatorname{det}\left(k_{\mu}^{\prime}(0)\right)\right) . \tag{3.4}
\end{equation*}
$$

Now suppose that $\mu$ is Gaussian (with any mean and covariance). Then $Q_{0}$ and $Q_{1}$ have the same distribution (obviously a Gaussian one). It is tantaliz-
ing to think of a converse. For $n=1$ it is trivial. For general $n$, it relies on the following delicate result of Pogorelov (1978).

ThEOREM 3.4. Let $f$ be a $C^{\infty}$ convex function on $\mathbb{R}^{n}$ such that the determinant of the Hessian matrix $f^{\prime \prime}$ is a constant. Then $f^{\prime \prime}$ itself is a constant.

This is a reformulation of Pogorelov's result (on page 90). We then have the following characterization of Gaussian laws in $\mathbb{R}^{n}$ :

Theorem 3.5. Let $\mu, Q_{0}$ and $Q_{1}$ be as defined above. Assume further that the Laplace transform of $\mu$ is finite everywhere in $\mathbb{R}^{n}$. Then $Q_{0}=Q_{1}$ if and only if $\mu$ is Gaussian.

Proof. The "if" part is obvious from (3.4). The "only if" part comes also from (3.4), which gives that $\boldsymbol{\theta} \mapsto \operatorname{det} k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$ is a constant. Since $\boldsymbol{\theta} \mapsto k_{\mu}(\boldsymbol{\theta})$ is a real analytic strictly convex function which is defined on all $\mathbb{R}^{n}$, Pogorelov's theorem applies and $k_{\mu}^{\prime \prime}(\boldsymbol{\theta})$ is a constant. This implies that $\mu$ is Gaussian with covariance $k_{\mu}^{\prime}(\boldsymbol{\theta})$ and arbitrary mean.

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