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# A GENERAL ITERATIVE ALGORITHM FOR NONEXPANSIVE MAPPINGS IN BANACH SPACES 

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#### Abstract

Let $E$ be a real $q$-uniformly smooth Banach space whose duality map is weakly sequentially continuous. Let $T: E \rightarrow E$ be a nonexpansive mapping with $F(T) \neq \emptyset$. Let $A: E \rightarrow E$ be an $\eta$-strongly accretive map which is also $\kappa$-Lipschitzian. Let $f: E \rightarrow E$ be a contraction map with coefficient $0<\alpha<1$. Let a sequence $\left\{y_{n}\right\}$ be defined iteratively by $y_{0} \in$ $E, y_{n+1}=\alpha_{n} \gamma f\left(y_{n}\right)+\left(I-\alpha_{n} \mu A\right) T y_{n}, n \geq 0$, where $\left\{\alpha_{n}\right\}, \gamma$ and $\mu$ satisfy some appropriate conditions. Then, we prove that $\left\{y_{n}\right\}$ converges strongly to the unique solution $x^{*} \in F(T)$ of the variational inequality $\left\langle(\gamma f-\mu A) x^{*}, j(y-\right.$ $\left.\left.x^{*}\right)\right\rangle \leq 0, \forall y \in F(T)$. Convergence of the correspondent implicit scheme is also proved without the assumption that $E$ has weakly sequentially continuous duality map. Our results are applicable in $l_{p}$ spaces, $1<p<\infty$.


## 1. Introduction

Let $E$ be a real Banach space and $E^{*}$ be the dual space of $E$. A mapping $\varphi:[0, \infty) \rightarrow[0, \infty)$ is called a gauge function if it is strictly increasing, continuous and $\varphi(0)=0$. Let $\varphi$ be a gauge function, a generalized duality mapping with respect to $\varphi, J_{\varphi}: E \rightarrow 2^{E^{*}}$ is defined by, $x \in E$,

$$
J_{\varphi} x=\left\{x^{*} \in E^{*}:\left\langle x, x^{*}\right\rangle=\|x\| \varphi(\|x\|),\left\|x^{*}\right\|=\varphi(\|x\|)\right\}
$$

where $\langle.,$.$\rangle denotes the duality pairing between element of E$ and that of $E^{*}$. If $\varphi(t)=t$, then $J_{\varphi}$ is simply called the normalized duality mapping and is denoted by $J$. For any $x \in E$, an element of $J_{\varphi} x$ is denoted by $j_{\varphi}(x)$.
If however $\varphi(t)=t^{q-1}$, for some $q>1$, then $J_{\varphi}$ is still called the generalized

[^0]duality mapping and is denoted by $J_{q}$ (see, for example [9, 10]).
The space $E$ is said to have weakly (sequentially) continuous duality map if there exists a gauge function $\varphi$ such that $J_{\varphi}$ is singled valued and (sequentially) continous from $E$ with weak topology to $E^{*}$ with weak* topology. It is well known that all $l_{p}$ spaces, $(1<p<\infty)$ have weakly sequentially continuous duality mappings. It is well known (see, for example, [16]) that $J_{q}(x)=\|x\|^{q-2} J(x)$ if $x \neq 0$, and that if $E^{*}$ is strictly convex then $J_{q}$ is single valued.
A mapping $A: D(A) \subset E \rightarrow E$ is said to be accretive if $\forall x, y \in D(A)$, there exists $j_{q}(x-y) \in J_{q}(x-y)$ such that
\[

$$
\begin{equation*}
\left\langle A x-A y, j_{q}(x-y)\right\rangle \geq 0 \tag{1.1}
\end{equation*}
$$

\]

where $D(A)$ denotes the domain of $A$. $A$ is called $\eta$-strongly accretive if $\forall x, y \in$ $D(A)$, there exists $j_{q}(x-y) \in J_{q}(x-y)$ and $\eta \in(0,1)$ such that

$$
\begin{equation*}
\left\langle A x-A y, j_{q}(x-y)\right\rangle \geq \eta\|x-y\|^{q} . \tag{1.2}
\end{equation*}
$$

$A$ is $\kappa$-Lipschitzian if for some $\kappa>0,\|A(x)-A(y)\| \leq \kappa\|x-y\| \forall x, y \in D(A)$. A mapping $T: E \rightarrow E$ is called nonexpansive if

$$
\|T x-T y\| \leq\|x-y\|, \forall x, y \in E
$$

A point $x \in E$ is called a fixed point of $T$ if $T x=x$. The set of fixed points of $T$ is denoted by $F(T):=\{x \in E: T x=x\}$. In Hilbert spaces, accretive operators are called monotone where inequalities (1.1) and (1.2) hold with $j_{q}$ replaced by the identity map on $H$.

Moudafi [5] introduced the viscosity approximation method for nonexpansive mappings. Let $f$ be a contraction on $H$, starting with an arbitrary $x_{0} \in H$, define a sequence $\left\{x_{n}\right\}$ recursively by

$$
\begin{equation*}
x_{n+1}=\alpha_{n} f\left(x_{n}\right)+\left(1-\alpha_{n}\right) T x_{n}, n \geq 0 \tag{1.3}
\end{equation*}
$$

where $\left\{\alpha_{n}\right\}$ is a sequence in $(0,1)$. $\mathrm{Xu}[12]$ proved that under certain appropriate conditions on $\left\{\alpha_{n}\right\}$, the sequence $\left\{x_{n}\right\}$ generated by (1.3) strongly converges to the unique solution $x^{*}$ in $F(T)$ of the variational inequality

$$
\left\langle(I-f) x^{*}, x-x^{*}\right\rangle \geq 0, \text { for } x \in F(T)
$$

In [13], it is proved, under some conditions on the real sequence $\left\{\alpha_{n}\right\}$, that the sequence $\left\{x_{n}\right\}$ defined by $x_{0} \in H$ chosen arbitrary,

$$
\begin{equation*}
x_{n+1}=\alpha_{n} b+\left(I-\alpha_{n} A\right) T x_{n}, \quad n \geq 0 \tag{1.4}
\end{equation*}
$$

converges strongly to $x^{*} \in F(T)$ which is the unique solution of the minimization problem

$$
\min _{x \in F(T)} \frac{1}{2}\langle A x, x\rangle-\langle x, b\rangle,
$$

where $A$ is a strongly positive bounded linear operator. That is, there is a constant $\bar{\gamma}>0$ with the property

$$
\langle A x, x\rangle \geq \bar{\gamma}\|x\|^{2}, \forall x \in H
$$

Combining the iterative method (1.3) and (1.4), Marino and Xu [7] consider the following general iterative method:

$$
\begin{equation*}
x_{n+1}=\alpha_{n} \gamma f\left(x_{n}\right)+\left(I-\alpha_{n} A\right) T x_{n}, \quad n \geq 0 \tag{1.5}
\end{equation*}
$$

They proved that if the sequence $\left\{\alpha_{n}\right\}$ of parameters satisfies appropriate conditions, then the sequence $\left\{x_{n}\right\}$ generated by (1.5) converges strongly to $x^{*} \in F(T)$ which solves the variational inequality

$$
\left\langle(\gamma f-A) x^{*}, x-x^{*}\right\rangle \leq 0, x \in F(T)
$$

which is the optimality condition for the minimization problem

$$
\min _{x \in F(T)} \frac{1}{2}\langle A x, x\rangle-h(x)
$$

where $h$ is a potential function for $\gamma f$ (i.e. $h^{\prime}(x)=\gamma f(x)$ for $x \in H$ ).
Let $K$ be a nonempty, closed and convex subset of a real Hilbert space $H$. The variational inequality problem: Find a point $x^{*} \in K$ such that

$$
\left\langle A x^{*}, y-x^{*}\right\rangle \geq 0, \forall y \in K
$$

is equivalent to the following fixed point equation

$$
\begin{equation*}
x^{*}=P_{K}\left(x^{*}-\delta A x^{*}\right), \tag{1.6}
\end{equation*}
$$

where $\delta>0$ is an arbitrary fixed constant, $A$ is a nonlinear operator on $K$ and $P_{K}$ is the nearest point projection map from $H$ onto $K$, i.e., $P_{K} x=y$ where $\|x-y\|=\inf _{u \in K}\|x-u\|$ for $x \in H$. Consequently, under appropriate conditions on $A$ and $\delta$, fixed point methods can be used to find or approximate a solution of the variational inequality. Considerable efforts have been devoted to this problem (see, for example, $[14,17]$ and the references contained therein). For instance, if $A$ is strongly monotone and Lipschitz then, a mapping $B: H \rightarrow H$ defined by $B x=P_{K}(x-\delta A x), x \in H$ with $\delta>0$ sufficiently small is a strict contraction. Hence, the Picard iteration, $x_{0} \in H, x_{n+1}=B x_{n}, n \geq 0$ of the classical Banach contraction mapping principle converges to the unique solution of the variational inequality. It has been observed that the projection operator $P_{K}$ in the fixed point formulation (1.6) may make the computation of the iterates difficult due to possible complexity of the convex set $K$. In order to reduce the possible difficulty with the use of $P_{K}$, Yamada [17] introduced the following hybrid descent method for solving the variational inequality:

$$
\begin{equation*}
x_{n+1}=T x_{n}-\lambda_{n} \mu A\left(T x_{n}\right), n \geq 0 \tag{1.7}
\end{equation*}
$$

where $T$ is a nonexpansive mapping, $A$ is an $\eta$-strongly monotone and $\kappa$-Lipschitz operator with $\eta>0, \kappa>0,0<\mu<\frac{2 \eta}{\kappa^{2}}$. He proved that if $\left\{\lambda_{n}\right\}$ satisfies appropriate conditions then, $\left\{x_{n}\right\}$ converges strongly to the unique solution $x^{*}$ of the variational inequality

$$
\left\langle A x^{*}, x-x^{*}\right\rangle \geq 0, x \in F(T)
$$

Very recently, Tian [6] combined the Yamada's method (1.7) with the iterative method (1.5) and introduced the following general iterative method in Hilbert spaces:

$$
\begin{equation*}
x_{n+1}=\alpha_{n} \gamma f\left(x_{n}\right)+\left(I-\alpha_{n} \mu A\right) T x_{n}, \quad n \geq 0 . \tag{1.8}
\end{equation*}
$$

Then, he proved that the sequence $\left\{x_{n}\right\}$ generated by (1.8) converges strongly to the unique solution $x^{*} \in F(T)$ of the variational inequality

$$
\left\langle(\gamma f-\mu A) x^{*}, x-x^{*}\right\rangle \leq 0, x \in F(T)
$$

We remark immediately here that the results of Tian [6] improved the results of Yamada [17], Moudafi [5], Xu [12] and Marino and Xu [13] in Hilbert spaces.

In this paper, motivated and inspired by the above research results, our purpose is to extend the result of Tian [6] to $q$-uniformly smooth Banach space whose duality mapping is weakly sequentially continuous. Thus, our results are applicable in $l_{p}$ spaces, $1<p<\infty$. Furthermore, our results extend the results of Moudafi [5], Xu [12] and Marino and Xu [13] to Banach spaces much more general than Hilbert.

## 2. Preliminaries

Let $E$ be a real Banach space. Let $K$ be a nonempty closed convex and bounded subset of a Banach space $E$ and let the diameter of $K$ be defined by $d(K):=$ $\sup \{\|x-y\|: x, y \in K\}$. For each $x \in K$, let $r(x, K):=\sup \{\|x-y\|: y \in K\}$ and let $r(K):=\inf \{r(x, K): x \in K\}$ denote the Chebyshev radius of $K$ relative to itself. The normal structure coefficient $N(E)$ of $E$ (see, for example, [1]) is defined by $N(E):=\inf \left\{\frac{d(K)}{r(K)}: K\right.$ is a closed convex and bounded subset of E with $d(K)>0\}$. A space $E$ such that $N(E)>1$ is said to have uniform normal structure. It is known that all uniformly convex and uniformly smooth Banach spaces have uniform normal structure (see, for example, $[2,4]$ ).

Let $\mu$ be a linear continuous functional on $\ell^{\infty}$ and let $a=\left(a_{1}, a_{2}, \ldots\right) \in \ell^{\infty}$. We will sometimes write $\mu_{n}\left(a_{n}\right)$ in place of the value $\mu(a)$. A linear continuous functional $\mu$ such that $\|\mu\|=1=\mu(1)$ and $\mu_{n}\left(a_{n}\right)=\mu_{n}\left(a_{n+1}\right)$ for every $a=$ $\left(a_{1}, a_{2}, \ldots\right) \in \ell^{\infty}$ is called a Banach limit. It is known that if $\mu$ is a Banach limit, then

$$
\liminf _{n \rightarrow \infty} a_{n} \leq \mu_{n}\left(a_{n}\right) \leq \limsup _{n \rightarrow \infty} a_{n}
$$

for every $a=\left(a_{1}, a_{2}, \ldots\right) \in \ell^{\infty}$ (see, for example, $[2,3]$ ).
Let $E$ be a normed space with $\operatorname{dimE} \geq 2$. The modulus of smoothness of $E$ is the function $\rho_{E}:[0, \infty) \rightarrow[0, \infty)$ defined by

$$
\rho_{E}(\tau):=\sup \left\{\frac{\|x+y\|+\|x-y\|}{2}-1:\|x\|=1 ;\|y\|=\tau\right\}
$$

The space $E$ is called uniformly smooth if and only if $\lim _{t \rightarrow 0^{+}} \frac{\rho_{E}(t)}{t}=0$. For some positive constant $q, E$ is called $q$-uniformly smooth if there exists a constant $c>0$ such that $\rho_{E}(t) \leq c t^{q}, t>0$. It is known that

$$
L_{p}\left(\text { or } l_{p}\right) \text { spaces are }\left\{\begin{array}{l}
2-\text { uniformly smooth, if, } 2 \leq p<\infty \\
p-\text { uniformly smooth, if, } 1<p \leq 2
\end{array}\right.
$$

It is well known that if $E$ is smooth then the duality mapping is singled-valued, and if $E$ is uniformly smooth then the duality mapping is norm-to-norm uniformly continuous on bounded subset of E .
We shall make use of the following well known results.
Lemma 2.1. Let $E$ be a real normed space. Then

$$
\|x+y\|^{2} \leq\|x\|^{2}+2\langle y, j(x+y)\rangle
$$

for all $x, y \in E$ and for all $j(x+y) \in J(x+y)$.
Lemma 2.2. (Xu, [15]) Let E be a real q-uniformly smooth Banach space for some $q>1$, then there exists some positive constant $d_{q}$ such that

$$
\|x+y\|^{q} \leq\|x\|^{q}+q\left\langle y, j_{q}(x)\right\rangle+d_{q}\|y\|^{q} \forall x, y \in E \text { and } j_{q}(x) \in J_{q}(x) .
$$

Lemma 2.3. (Xu, [11]) Let $\left\{a_{n}\right\}$ be a sequence of nonnegative real numbers satisfying the following relation:

$$
a_{n+1} \leq\left(1-\alpha_{n}\right) a_{n}+\alpha_{n} \sigma_{n}+\gamma_{n}, n \geq 0
$$

where, (i) $\left\{\alpha_{n}\right\} \subset[0,1], \sum \alpha_{n}=\infty$; (ii) limsup $\sigma_{n} \leq 0$; (iii) $\gamma_{n} \geq 0 ;(n \geq 0)$, $\sum \gamma_{n}<\infty$. Then, $a_{n} \rightarrow 0$ as $n \rightarrow \infty$.
Lemma 2.4. (Lim and Xu, [4]) Suppose $E$ is a Banach space with uniform normal structure, $K$ is a nonempty bounded subset of $E$, and $T: K \rightarrow K$ is uniformly $k$-Lipschitzian mapping with $k<N(E)^{\frac{1}{2}}$. Suppose also there exists a nonempty bounded closed convex subset $C$ of $K$ with the following property $(P)$ :

$$
(P) x \in C \text { implies } \omega_{w}(x) \subset C \text {, }
$$

where $\omega_{w}(x)$ is the $\omega$-limit set of $T$ at $x$, i.e., the set

$$
\left\{y \in E: y=\text { weak }-\lim _{j} T^{n_{j}} x \text { for some } n_{j} \rightarrow \infty\right\}
$$

Then, $T$ has a fixed point in $C$.
Lemma 2.5. (Jung, [8]) Let $C$ be a nonempty, closed and convex subset of a reflexive Banach space $E$ which satisfies Opial's condition and suppose $T: C \rightarrow E$ is nonexpansive. Then $I-T$ is demiclosed at zero, i.e., $x_{n} \rightharpoonup x, x_{n}-T x_{n} \rightarrow 0$ implies that $x=T x$.
Lemma 2.6. Let $E$ be a real Banach space, $f: E \rightarrow E$ a contraction with coefficient $0<\alpha<1$, and $A: E \rightarrow E$ a $\kappa$-Lipschitzian and $\eta$-strongly accretive operator with $\kappa>0, \eta \in(0,1)$. Then for $\gamma \in\left(0, \frac{\mu \eta}{\alpha}\right)$,

$$
\langle(\mu A-\gamma f) x-(\mu A-\gamma f) y, j(x-y)\rangle \geq(\mu \eta-\gamma \alpha)\|x-y\|^{2}, \quad \forall x, y \in E
$$

That is, $\mu A-\gamma f$ is strongly accretive with coefficient $\mu \eta-\gamma \alpha$.

## 3. Main Results

We begin with the following lemma.
Lemma 3.1. Let $E$ be a q-uniformly smooth real Banach space with constant $d_{q}, q>1$. Let $f: E \rightarrow E$ be a contraction mapping with constant of contraction $\alpha \in(0,1)$. Let $T: E \rightarrow E$ be a nonexpansive mapping such that $F(T) \neq \emptyset$ and $A: E \rightarrow E$ be an $\eta$-strongly accretive mapping which is also $\kappa$-Lipschitzian. Let $\mu \in\left(0, \min \left\{1,\left(\frac{q \eta}{d_{q} \kappa^{q}}\right)^{\frac{1}{q-1}}\right\}\right)$ and $\tau:=\mu\left(\eta-\frac{\mu^{q-1} d_{q} \kappa^{q}}{q}\right)$. For each $t \in(0,1)$ and $\gamma \in\left(0, \frac{\tau}{\alpha}\right)$ define a map $T_{t}: E \rightarrow E$ by

$$
T_{t} x=t \gamma f(x)+(I-t \mu A) T x, x \in E
$$

Then, $T_{t}$ is a strict contraction. Furthermore

$$
\left\|T_{t} x-T_{t} y\right\| \leq[1-t(\tau-\gamma \alpha)]\|x-y\|
$$

Proof. Without loss of generality, assume $\eta<\frac{1}{q}$. Then, as $\mu<\left(\frac{q \eta}{d_{q} \kappa^{q}}\right)^{\frac{1}{(q-1)}}$, we have $0<q \eta-\mu^{q-1} d_{q} \kappa^{q}$. Furthermore, from $\eta<\frac{1}{q}$ we have $q \eta-\mu^{q-1} d_{q} \kappa^{q}<1$ so that $0<q \eta-\mu^{q-1} d_{q} \kappa^{q}<1$. Also as $\mu<1$ and $t \in(0,1)$ we obtained that $0<t \mu\left(q \eta-\mu^{q-1} d_{q} \kappa^{q}\right)<1$.

For each $t \in(0,1)$, define $S_{t} x=(I-t \mu A) T x, x \in E$, then for $x, y \in K$

$$
\begin{align*}
\left\|S_{t} x-S_{t} y\right\|^{q}= & \|(I-t \mu A) T x-(I-\mu A) T y\|^{q} \\
= & \|(T x-T y)-t \mu(A(T x)-A(T y))\|^{q} \\
\leq & \|T x-T y\|^{q}-q t \mu\left\langle A(T x)-A(T y), j_{q}(T x-T y)\right\rangle \\
& +t^{q} \mu^{q} d_{q}\|A(T x)-A(T y)\|^{q} \\
\leq & \|T x-T y\|^{q}-q t \mu \eta\|T x-T y\|^{q} \\
& +t^{q} \mu^{q} \kappa^{q} d_{q}\|T x-T y\|^{q} \\
\leq & {\left[1-t \mu\left(q \eta-t^{q-1} \mu^{q-1} \kappa^{q} d_{q}\right)\right]\|x-y\|^{q} } \\
\leq & {\left[1-q t \mu\left(\eta-\frac{\mu^{q-1} \kappa^{q} d_{q}}{q}\right)\right]\|x-y\|^{q} } \\
\leq & {\left[1-t \mu\left(\eta-\frac{\mu^{q-1} \kappa^{q} d_{q}}{q}\right)\right]^{q}\|x-y\|^{q} } \\
= & (1-t \tau)^{q}\|x-y\|^{q} . \tag{3.1}
\end{align*}
$$

It then follows from (3.1) that,

$$
\left\|S_{t} x-S_{t} y\right\| \leq(1-t \tau)\|x-y\|
$$

Using the fact that $T_{t} x=t \gamma f(x)+S_{t} x, x \in E$, we obtain for all $x, y \in E$ that

$$
\begin{aligned}
\left\|T_{t} x-T_{t} y\right\| & =\left\|t \gamma(f(x)-f(y))+\left(S_{t} x-S_{t} y\right)\right\| \\
& \leq t \gamma\|f(x)-f(y)\|+\left\|S_{t} x-S_{t} y\right\| \\
& \leq t \gamma \alpha\|x-y\|+(1-t \tau)\|x-y\| \\
& =[1-t(\tau-\gamma \alpha)]\|x-y\| .
\end{aligned}
$$

Therefore

$$
\left\|T_{t} x-T_{t} y\right\| \leq[1-t(\tau-\gamma \alpha)]\|x-y\|,
$$

which implies that $T_{t}$ is a strict contraction. Therefore, by Banach contraction mapping principle, there exists a unique fixed point $x_{t}$ of $T_{t}$ in $E$. That is,

$$
\begin{equation*}
x_{t}=t \gamma f\left(x_{t}\right)+(I-t \mu A) T x_{t} . \tag{3.2}
\end{equation*}
$$

Proposition 3.2. Let $\left\{x_{t}\right\}$ be defined by (3.2), then
(i) $\left\{x_{t}\right\}$ is bounded for $t \in\left(0, \frac{1}{\tau}\right)$.
(ii) $\lim _{t \rightarrow 0}\left\|x_{t}-T x_{t}\right\|=0$.

Proof. (i) For any $p \in F(T)$, we have

$$
\begin{aligned}
\left\|x_{t}-p\right\| & =\left\|(I-t \mu A) T x_{t}-(I-t \mu A) p+t\left(\gamma f\left(x_{t}\right)-\mu A(p)\right)\right\| \\
& \leq(1-t \tau)\left\|x_{t}-p\right\|+t \gamma \alpha\left\|x_{t}-p\right\|+t\|\gamma f(p)-\mu A(p)\| \\
& =[1-t(\tau-\gamma \alpha)]\left\|x_{t}-p\right\|+t\|\gamma f(p)-\mu A(p)\| .
\end{aligned}
$$

Therefore,

$$
\left\|x_{t}-p\right\| \leq \frac{1}{\tau-\gamma \alpha}\|\gamma f(p)-\mu A(p)\|
$$

Hence, $\left\{x_{t}\right\}$ is bounded. Furthermore $\left\{f\left(x_{t}\right)\right\}$ and $\left\{A\left(T x_{t}\right)\right\}$ are also bounded. (ii) From (3.2), we have

$$
\begin{equation*}
\left\|x_{t}-T x_{t}\right\|=t\left\|\gamma f\left(x_{t}\right)-\mu A\left(T x_{t}\right)\right\| \rightarrow 0 \text { as } t \rightarrow 0 \tag{3.3}
\end{equation*}
$$

Next, we show that $\left\{x_{t}\right\}$ is relatively norm compact as $t \rightarrow 0$. Let $\left\{t_{n}\right\}$ be a sequence in $(0,1)$ such that $t_{n} \rightarrow 0$ as $n \rightarrow \infty$. Put $x_{n}:=x_{t_{n}}$. From (3.3), we obtain that

$$
\left\|x_{n}-T x_{n}\right\| \rightarrow 0 \text { as } n \rightarrow \infty
$$

Theorem 3.3. Assume that $\left\{x_{t}\right\}$ is defined by (3.2), then $\left\{x_{t}\right\}$ converges strongly as $t \rightarrow 0$ to a fixed point $\tilde{x}$ of $T$ which solves the variational inequality problem:

$$
\begin{equation*}
\langle(\mu A-\gamma f) \tilde{x}, j(\tilde{x}-z)\rangle \leq 0, z \in F(T) \tag{3.4}
\end{equation*}
$$

Proof. By Lemma 2.6, $(\mu A-\gamma f)$ is strongly accretive, so the variational inequality (3.4) has a unique solution in $F(T)$. Below we use $x^{*} \in F(T)$ to denote the unique solution of (3.4).

We next prove that $x_{t} \rightarrow x^{*}(t \rightarrow 0)$. Now, define a map $\phi: E \rightarrow \mathbb{R}$ by

$$
\phi(x):=\mu_{n}\left\|x_{n}-x\right\|^{2}, \forall x \in E,
$$

where $\mu_{n}$ is a Banach limit for each $n$. Then, $\phi(x) \rightarrow \infty$ as $\|x\| \rightarrow \infty, \phi$ is continuous and convex, so as $E$ is reflexive, it follows that there exits $y^{*} \in E$ such that $\phi\left(y^{*}\right)=\min _{u \in E} \phi(u)$. Hence, the set

$$
K^{*}:=\left\{x \in E: \phi(x)=\min _{u \in E} \phi(u)\right\} \neq \emptyset .
$$

We now show that $T$ has a fixed point in $K^{*}$. We shall make use of Lemma 2.4. If $x$ is in $K^{*}$ and $y:=\omega-\lim _{j} T^{m_{j}} x$, then from the weak lower semi-continuity of $\phi$ (since $\phi$ is lower semi-continuous and convex) and $\lim _{n \rightarrow \infty}\left\|x_{n}-T x_{n}\right\|=0$, we have (since $\lim _{n \rightarrow \infty}\left\|x_{n}-T x_{n}\right\|=0$ implies $\lim _{n \rightarrow \infty}\left\|x_{n}-T^{m} x_{n}\right\|=0, m \geq 1$, this is easily proved by induction),

$$
\begin{aligned}
\phi(y) & \leq \liminf _{j \rightarrow \infty} \phi\left(T^{m_{j}} x\right) \leq \limsup _{m \rightarrow \infty} \phi\left(T^{m} x\right) \\
& =\limsup _{m \rightarrow \infty}\left(\mu_{n}\left\|x_{n}-T^{m} x\right\|^{2}\right) \\
& =\limsup _{m \rightarrow \infty}\left(\mu_{n}\left\|x_{n}-T^{m} x_{n}+T^{m} x_{n}-T^{m} x\right\|^{2}\right) \\
& \leq \limsup _{m \rightarrow \infty}\left(\mu_{n}\left\|T^{m} x_{n}-T^{m} x\right\|^{2}\right) \leq \limsup _{m \rightarrow \infty}\left(\mu_{n}\left\|x_{n}-x\right\|^{2}\right)=\phi(x) \\
& =\min _{u \in E} \phi(u) .
\end{aligned}
$$

So, $y \in K^{*}$. By Lemma 2.4, $T$ has a fixed point in $K^{*}$ and so $K^{*} \cap F(T) \neq \emptyset$. Now let $y \in K^{*} \cap F(T)$. Then, it follows that $\phi(y) \leq \phi(y+t(\gamma f-\mu A) y)$ and using Lemma 2.1, we obtain that
$\left\|x_{n}-y-t(\gamma f-\mu A) y\right\|^{2} \leq\left\|x_{n}-y\right\|^{2}-2 t\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y-t(\gamma f-\mu A) y\right)\right\rangle$.
This implies that $\mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y-t(\gamma f-\mu A) y\right)\right\rangle \leq 0$. Moreover,
$\mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)\right\rangle=\mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)-j\left(x_{n}-y+t(\mu A-\gamma f) y\right)\right\rangle$
$+\mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y+t(\mu A-\gamma f) y\right)\right\rangle \leq \mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)-j\left(x_{n}-\right.\right.$ $y+t(\mu A-\gamma f) y)\rangle$.
Since $j$ is norm-to-norm uniformly continuous on bounded subsets of $E$, we obtain as $t \rightarrow 0$ that

$$
\mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)\right\rangle \leq 0
$$

Now, using (3.2), we have

$$
\begin{aligned}
\left\|x_{n}-y\right\|^{2} & =t_{n}\left\langle\gamma f\left(x_{n}\right)-\mu A y, j\left(x_{n}-y\right)\right\rangle+\left\langle\left(I-t_{n} \mu A\right)\left(T x_{n}-y\right), j\left(x_{n}-y\right)\right\rangle \\
& =t_{n}\left\langle\gamma f\left(x_{n}\right)-\mu A y, j\left(x_{n}-y\right)\right\rangle+\left\langle(I-\mu A) T x_{n}-(I-\mu A) y, j\left(x_{n}-y\right)\right\rangle \\
& \leq\left[1-t_{n}(\tau-\gamma \alpha)\right]\left\|x_{n}-y\right\|^{2}+t_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)\right\rangle .
\end{aligned}
$$

So,

$$
\left\|x_{n}-y\right\|^{2} \leq \frac{1}{\tau-\gamma \alpha}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)\right\rangle
$$

Again, taking Banach limit, we obtain

$$
\mu_{n}\left\|x_{n}-y\right\|^{2} \leq \frac{1}{\tau-\gamma \alpha} \mu_{n}\left\langle(\gamma f-\mu A) y, j\left(x_{n}-y\right)\right\rangle \leq 0
$$

which implies that $\mu_{n}\left\|x_{n}-y\right\|^{2}=0$. Hence, there exists a subsequence of $\left\{x_{n}\right\}_{n=1}^{\infty}$ which we still denoted by $\left\{x_{n}\right\}_{n=1}^{\infty}$ such that $\lim _{n \rightarrow \infty} x_{n}=y$. We now show that $y$ solves the variational inequality (3.4). Since

$$
x_{t}=t \gamma f\left(x_{t}\right)+(I-t \mu A) T x_{t}
$$

we can derive that

$$
(\mu A-\gamma f)\left(x_{t}\right)=-\frac{1}{t}(I-T) x_{t}+\mu\left(A x_{t}-A T x_{t}\right)
$$

It follows that for $z \in F(T)$,

$$
\begin{align*}
\left\langle(\mu A-\gamma f)\left(x_{t}\right), j\left(x_{t}-z\right)\right\rangle= & -\frac{1}{t}\left\langle(I-T) x_{t}-(I-T) z, j\left(x_{t}-z\right)\right\rangle \\
& +\mu\left\langle\left(A x_{t}-A T x_{t}\right), j\left(x_{t}-z\right)\right\rangle \\
\leq & \mu\left\langle\left(A x_{t}-A T x_{t}\right), j\left(x_{t}-z\right)\right\rangle \tag{3.5}
\end{align*}
$$

Since $T$ is nonexpansive, then, $I-T$ is accretive, which implies, $\left\langle(I-T) x_{t}-(I-\right.$ $\left.T) z, j\left(x_{t}-z\right)\right\rangle \geq 0$. Now replacing $t$ in (3.5) with $t_{n}$ and letting $n \rightarrow \infty$, noticing that $\left(A x_{t_{n}}-A T x_{t_{n}}\right) \rightarrow(A y-A y)$ we obtain

$$
\langle(\mu A-\gamma f) y, j(y-z)\rangle \leq 0
$$

since $z \in F(T)$ is arbitrary, we get $y=x^{*}$.
Assume now that there exists another subsequence $\left\{x_{m}\right\}_{m=1}^{\infty}$ of $\left\{x_{n}\right\}_{n=1}^{\infty}$ such that $\lim _{m \rightarrow \infty} x_{m}=u^{*}$. Then, since $\lim _{n \rightarrow \infty}\left\|x_{n}-T x_{n}\right\|=0$, we have that $u^{*} \in F(T)$. Repeating the argument above with $y$ replaced by $u^{*}$ we will get that $u^{*}$ solves the variational inequality (3.4), and so by uniqueness, we obtain $x^{*}=y=u^{*}$. This complete the proof.

Theorem 3.4. Let E be a real q-uniformly smooth Banach space with whose duality map is weakly sequentially continuous. Let $T: E \rightarrow E$ be a nonexpansive mapping with $F(T) \neq \emptyset$. Let $A: E \rightarrow E$ be an $\eta$-strongly accretive map which is also $\kappa$-Lipschitzian. Let $f: E \rightarrow E$ be a contraction map with coefficient $0<\alpha<1$. Let $\left\{\alpha_{n}\right\}_{n=1}^{\infty}$ be a real sequence in [0,1] satisfying:
(C1) $\lim \alpha_{n}=0$,
(C2) $\sum \alpha_{n}=\infty$ and
(C3) $\sum\left|\alpha_{n+1}-\alpha_{n}\right|<\infty$.
Let $\mu, \gamma$ and $\tau$ be as in Lemma 3.1. Define a sequence $\left\{y_{n}\right\}_{n=1}^{\infty}$ iteratively in $E$ by $y_{0} \in E$,

$$
\begin{equation*}
y_{n+1}=\alpha_{n} \gamma f\left(y_{n}\right)+\left(I-\alpha_{n} \mu A\right) T y_{n} . \tag{3.6}
\end{equation*}
$$

Then, $\left\{y_{n}\right\}_{n=1}^{\infty}$ converges strongly to $x^{*} \in F(T)$ which is also a solution to the following variational inequality

$$
\begin{equation*}
\left\langle(\gamma f-\mu A) x^{*}, j\left(y-x^{*}\right)\right\rangle \leq 0, \forall y \in F(T) . \tag{3.7}
\end{equation*}
$$

Proof. Since the mapping $T: E \rightarrow E$ is nonexpansive, then from Theorem 3.3, the variational inequality (3.7) has a unique solution $x^{*}$ in $F(T)$. Furthermore, the sequence $\left\{y_{n}\right\}$ satisfies

$$
\left\|y_{n}-x^{*}\right\| \leq \max \left\{\left\|y_{0}-x^{*}\right\|, \frac{\left\|\gamma f\left(x^{*}\right)-\mu A x^{*}\right\|}{\tau-\gamma \alpha}\right\}, \forall n \geq 0
$$

It is obvious that this is true for $n=0$. Assume it is true for $n=k$ for some $k \in \mathbb{N}$, from the recursion formula (3.6), we have

$$
\begin{aligned}
\left\|y_{k+1}-x^{*}\right\| & =\left\|\alpha_{k} \gamma f\left(y_{k}\right)+\left(I-\alpha_{k} \mu A\right) T y_{k}-x^{*}\right\| \\
& =\left\|\alpha_{k}\left(\gamma f\left(y_{k}\right)-\mu A x^{*}\right)+\left(I-\alpha_{k} \mu A\right) T y_{k}-\left(I-\alpha_{k} \mu A\right) x^{*}\right\| \\
& \leq\left[1-\alpha_{k}(\tau-\gamma \alpha)\right]\left\|y_{k}-x^{*}\right\|+\alpha_{k}(\tau-\gamma \alpha) \frac{\left\|\gamma f\left(x^{*}\right)-\mu A x^{*}\right\|}{\tau-\gamma \alpha} \\
& \leq \max \left\{\left\|y_{k}-x^{*}\right\|, \frac{\left\|\gamma f\left(x^{*}\right)-\mu A x^{*}\right\|}{\tau-\gamma \alpha}\right\}
\end{aligned}
$$

and the claim follows by induction. Thus, the sequence $\left\{y_{n}\right\}_{n=1}^{\infty}$ is bounded and so are $\left\{f\left(y_{n}\right)\right\}_{n=1}^{\infty}$ and $\left\{T y_{n}\right\}_{n=1}^{\infty}$. Also from (3.6), we have

$$
\begin{aligned}
\left\|y_{n+1}-y_{n}\right\|= & \| \alpha_{n} \gamma\left(f\left(y_{n}\right)-f\left(y_{n-1}\right)\right)+\gamma\left(\alpha_{n}-\alpha_{n-1}\right) f\left(y_{n-1}\right) \\
& +\left(I-\mu \alpha_{n} A\right) T y_{n}-\left(I-\mu \alpha_{n} A\right) T y_{n-1}+\mu\left(\alpha_{n}-\alpha_{n-1}\right) A T y_{n-1} \| \\
\leq & \left(1-\alpha_{n}(\tau-\gamma \alpha)\right)\left\|y_{n}-y_{n-1}\right\|+M\left|\alpha_{n}-\alpha_{n-1}\right|
\end{aligned}
$$

for some $M>0$. By Lemma 2.3, we have $\lim _{n \rightarrow \infty}\left\|y_{n+1}-y_{n}\right\|=0$. Furthermore, we obtain

$$
\begin{align*}
\left\|y_{n}-T y_{n}\right\| & \leq\left\|y_{n}-y_{n+1}\right\|+\left\|y_{n+1}-T y_{n}\right\|  \tag{3.8}\\
& =\left\|y_{n}-y_{n+1}\right\|+\alpha_{n}\left\|\gamma f\left(y_{n}\right)-\mu A T y_{n}\right\| \rightarrow 0 \text { as } n \rightarrow \infty .
\end{align*}
$$

Let $\left\{y_{n_{j}}\right\}$ be a subsequence of $\left\{y_{n}\right\}$ such that

$$
\underset{n \rightarrow \infty}{\limsup }\left\langle(\gamma f-\mu A) x^{*}, j\left(y_{n}-x^{*}\right)\right\rangle=\lim _{j \rightarrow \infty}\left\langle(\gamma f-\mu A) x^{*}, j\left(y_{n_{j}}-x^{*}\right)\right\rangle
$$

Assume also $y_{n_{j}} \rightharpoonup z$ as $j \rightarrow \infty$, for some $z \in E$. Then, using this, (3.8) and the demiclosedness of $(I-T)$ at zero, we have $z \in F(T)$. Since $j$ is weakly sequentially continuous, we have

$$
\begin{aligned}
\underset{n \rightarrow \infty}{\limsup }\left\langle(\gamma f-\mu A) x^{*}, j\left(y_{n}-x^{*}\right)\right\rangle & =\lim _{j \rightarrow \infty}\left\langle(\gamma f-\mu A) x^{*}, j\left(y_{n_{j}}-x^{*}\right)\right\rangle \\
& =\left\langle(\gamma f-\mu A) x^{*}, j\left(z-x^{*}\right)\right\rangle \leq 0 .
\end{aligned}
$$

Finally, we show that $y_{n} \rightarrow x^{*}$. From the recursion formula (3.6), let

$$
T_{n} y_{n}:=\alpha_{n} \gamma f\left(y_{n}\right)+\left(I-\alpha_{n} \mu A\right) T y_{n}
$$

and from Lemma 3.1, we have

$$
\begin{aligned}
\left\|y_{n+1}-x^{*}\right\|^{2}= & \left\|T_{n} y_{n}-T_{n} x^{*}+T_{n} x^{*}-x^{*}\right\|^{2} \\
= & \left\|T_{n} y_{n}-T_{n} x^{*}+\alpha_{n}(\gamma f-\mu A) x^{*}\right\|^{2} \\
\leq & \left\|T_{n} y_{n}-T_{n} x^{*}\right\|^{2}+2 \alpha_{n}\left\langle(\gamma f-\mu A) x^{*}, j\left(y_{n+1}-x^{*}\right)\right\rangle \\
\leq & {\left[1-\alpha_{n}(\tau-\gamma \alpha)\right]\left\|y_{n}-x^{*}\right\|^{2} } \\
& +2 \alpha_{n}(\tau-\gamma \alpha) \frac{\left\langle(\gamma f-\mu A) x^{*}, j\left(y_{n+1}-x^{*}\right)\right\rangle}{\tau-\gamma \alpha}
\end{aligned}
$$

and by Lemma 2.3 we have that $y_{n} \rightarrow x^{*}$ as $n \rightarrow \infty$. This completes the proof. We have the following corollaries.

Corollary 3.5. Let $E=l_{p}$ space, $(1<p<\infty)$ and $\left\{x_{n}\right\}_{n=1}^{\infty}$ be generated by $x_{0} \in E$,

$$
x_{n+1}=\alpha_{n} \gamma f\left(x_{n}\right)+\left(I-\alpha_{n} \mu A\right) T x_{n} .
$$

Assume that $\left\{\alpha_{n}\right\}_{n=1}^{\infty}$ is a sequence in [0,1] satisfying $(C 1)-(C 3)$, then $\left\{x_{n}\right\}_{n=1}^{\infty}$ converges strongly to $x^{*} \in F(T)$ which solves the variational inequality

$$
\begin{equation*}
\left\langle(\gamma f-\mu A) x^{*}, y-x^{*}\right\rangle \leq 0, \forall y \in F(T) \tag{3.9}
\end{equation*}
$$

Corollary 3.6. (Tian [6]) Let $E=H$ be a real Hilbert space and $\left\{x_{n}\right\}_{n=1}^{\infty}$ be generated by $x_{0} \in H$,

$$
x_{n+1}=\alpha_{n} \gamma f\left(x_{n}\right)+\left(I-\alpha_{n} \mu A\right) T x_{n} .
$$

Assume that $\left\{\alpha_{n}\right\}_{n=1}^{\infty}$ is a sequence in [0,1] satisfying $(C 1)-(C 3)$, then $\left\{x_{n}\right\}_{n=1}^{\infty}$ converges strongly to $x^{*} \in F(T)$ which solves the variational inequality (3.9)

Corollary 3.7. (Marino and Xu [7]) Let $\left\{x_{n}\right\}_{n=1}^{\infty}$ be generated by $x_{0} \in H$,

$$
x_{n+1}=\alpha_{n} \gamma f\left(x_{n}\right)+\left(I-\alpha_{n} A\right) T x_{n} .
$$

Assume that $\left\{\alpha_{n}\right\}_{n=1}^{\infty}$ is a sequence in [0,1] satisfying $(C 1)-(C 3)$, then $\left\{x_{n}\right\}_{n=1}^{\infty}$ converges strongly to $x^{*} \in F(T)$ which solves the variational inequality (3.9).

Corollary 3.8. (Xu [12]) Let $\left\{x_{n}\right\}_{n=1}^{\infty}$ be generated by $x_{0} \in H$,

$$
x_{n+1}=\alpha_{n} f\left(x_{n}\right)+\left(1-\alpha_{n}\right) T x_{n}, \quad n \geq 0 .
$$

Assume that $\left\{\alpha_{n}\right\}_{n=1}^{\infty}$ is a sequence in [0,1] satisfying $(C 1)-(C 3)$, then $\left\{x_{n}\right\}_{n=1}^{\infty}$ converges strongly to $x^{*} \in F(T)$.

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