# ON THE GAUSS MAP OF B-SCROLLS 

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#### Abstract

B\)-scrolls over null curves in the 3-dimensional LorentzMinkowski space $L^{3}$ are characterized as the only ruled surfaces with null rulings whose Gauss map satisfies the condition $\Delta G=\Lambda G, \Lambda$ being an endomorphism of $L^{3}$. This note completes the classification of such surfaces given by S. M. Choi in Tsukuba J. Math. 19 (1995), 285-304.


## 1. Introduction

Let $M$ be a connected surface in Euclidean 3-space $\boldsymbol{R}^{3}$ and let $G: M \rightarrow$ $\boldsymbol{S}^{2} \subset \boldsymbol{R}^{3}$ be its Gauss map. It is well known (see [9]) that $M$ has constant mean curvature if and only if $\Delta G=\|d G\|^{2} G, \Delta$ being the Laplace operator on $M$ corresponding to the induced metric on $M$ from $R^{3}$. As a special case one can consider Euclidean surfaces whose Gauss map is an eigenfunction of the Laplacian, i.e., $\Delta G=\lambda G, \lambda \in \boldsymbol{R}$. In [3], C. Baikoussis and D. E. Blair asked for ruled surfaces in $R^{3}$ whose Gauss map satisfies $\Delta G=\Lambda G$, where $\Lambda$ stands for an endomorphism of $\boldsymbol{R}^{3}$. They showed that the only ones are planes and circular cylinders. Recently, S. M. Choi in [5], investigates the Lorentz version of the above result and she essentially obtains the same result. Namely, the only ruled surfaces in $L^{3}$ whose Gauss map satisfies $\Delta G=\Lambda G$ are the planes $R^{2}$ and $L^{2}$, as well as the cylinders $S_{1}^{1} \times R^{1}, R_{1}^{1} \times S^{1}$ and $H^{1} \times R^{1}$.

It should be pointed out that all surfaces obtained above have diagonalizable shape operator. However, it is well known that a self-adjoint linear operator on a 2-dimensional Lorentz vector space has a matrix of exactly three types, two of them being non-diagonalizable. This makes a chief difference with regard to the

[^0]Riemannian submanifolds that has been greatly exploited (see, for example, [1], [2] and [7]). To illustrate the current situation, we bring here the famous example of L. K. Graves (see [8]), the so called B-scroll. This is a surface which can be parametrized as a "ruled surface" in $L^{3}$ with null directrix curve and null rulings, i.e., $X(s, t)=x(s)+t B(s), x(s)$ being a null curve and $B(s)$ a null vector field along $x(s)$ satisfying $\left\langle x^{\prime}, B\right\rangle=-1$.

The main purpose of this short note is to complete Choi's classification of ruled surfaces in $L^{3}$ whose Gauss map satisfies the condition $\Delta G=\Lambda G$. Actually, we will show that $B$-scrolls over null curves are the only ruled surfaces in $L^{3}$ with null rulings satisfying the above condition.

We would like to thank to the referee for bringing to our attention the preprint [6], where some related topics are considered.

## 2. Setup

Let $x: I \subset R \rightarrow L^{3}$ be a regular curve in $\boldsymbol{L}^{3}$ and $B: I \subset R \rightarrow L^{3}$ a vector field along $x$. Consider the ruled surface parametrized by $X(s, t)=x(s)+t B(s)$. Let us write down, as usually, $X_{s}:=\partial X / \partial s=x^{\prime}+t B^{\prime}$ and $X_{t}:=\partial X / \partial t=B$. Observe that, at $t=0, X_{s}(s, 0)=x^{\prime}(s)$ and $X_{t}(s, 0)=B(s)$. Then $X(s, t)$ is a regular surface in $L^{3}$ provided that the plane $\Pi=\operatorname{span}\left\{x^{\prime}, B\right\}$ is non degenerate in $L^{3}$. In fact, the matrix of the metric of $X(s, t)$ is given by

$$
\mathbf{g}(s, t)=\left(\begin{array}{cc}
\left\langle x^{\prime}, x^{\prime}\right\rangle+2 t\left\langle x^{\prime}, B^{\prime}\right\rangle+t^{2}\left\langle B^{\prime}, B^{\prime}\right\rangle & \left\langle x^{\prime}, B\right\rangle+t\left\langle B^{\prime}, B\right\rangle \\
\left\langle x^{\prime}, B\right\rangle+t\left\langle B^{\prime}, B\right\rangle & \langle B, B\rangle
\end{array}\right),
$$

so that when the plane $\Pi$ is spacelike (respectively, timelike) $X(s, t)$ parametrizes a spacelike surface (respectively, timelike surface) on the domain

$$
\{(s, t) \in I \times \boldsymbol{R}: \operatorname{det} \mathbf{g}(s, t)>0 \quad \text { (respectively, } \operatorname{det} \mathbf{g}(s, t)<0)\}
$$

According to the causal character of $x^{\prime}$ and $B$, there are four possibilities:
(1) $x^{\prime}$ and $B$ are non-null and linearly independent.
(2) $x^{\prime}$ is null and $B$ is non-null with $\left\langle x^{\prime}, B\right\rangle \neq 0$.
(3) $x^{\prime}$ is non-null and $B$ is null with $\left\langle x^{\prime}, B\right\rangle \neq 0$.
(4) $x^{\prime}$ and $B$ are null with $\left\langle x^{\prime}, B\right\rangle \neq 0$.

Let us first see that, with an appropiate change of the curve $x$, cases (2) and (3) can be locally reduced to (1) and (4), respectively. Let $X(s, t)$ be in case (2). Reparametrizing the null curve $x$ and normalizing the rulings $B$ if necessary, we may assume that

$$
\langle B, B\rangle=\varepsilon= \pm 1, \quad \text { and } \quad\left\langle x^{\prime}, B\right\rangle=-1
$$

so that

$$
\begin{equation*}
g(s, t)=\operatorname{det} \mathbf{g}(s, t)=\varepsilon\left(2 t\left\langle x^{\prime}, B^{\prime}\right\rangle+t^{2}\left\langle B^{\prime}, B^{\prime}\right\rangle\right)-1<0 \tag{2.1}
\end{equation*}
$$

We are looking for a curve $\gamma(s)=x(s)+t(s) B(s)$ in the surface with $\left\langle\gamma^{\prime}, \gamma^{\prime}\right\rangle=\varepsilon$ and such that $\gamma^{\prime}$ and $B$ are linearly independent. Writing $\gamma^{\prime}=x^{\prime}+t^{\prime} B+t B^{\prime}$, the condition $\left\langle\gamma^{\prime}, \gamma^{\prime}\right\rangle=\varepsilon$ is equivalent to the following differential equation for $t=t(s)$

$$
\begin{equation*}
\left(t^{\prime}\right)^{2}-2 \varepsilon t^{\prime}+g(s, t)=0 \tag{2.2}
\end{equation*}
$$

From (2.1) the discriminant of (2.2) is positive and we can locally integrate (2.2) to obtain $t$. Besides, $\gamma^{\prime}$ and $\boldsymbol{B}$ are linearly independent because $\left\langle\gamma^{\prime}, \gamma^{\prime}\right\rangle=\langle\boldsymbol{B}, \boldsymbol{B}\rangle=$ $\varepsilon$ and $\left\langle\gamma^{\prime}, B\right\rangle=-1+t^{\prime} \varepsilon \neq \pm \varepsilon$ due to (2.2). This shows that $X(s, t)$ can be reparametrized as in case (1) taking $\gamma$ as the directrix curve. On the other hand, if $X(s, t)$ is in case (3), reparametrizing the null curve $x$ and normalizing the rulings $B$ if necessary, we may assume that

$$
\left\langle x^{\prime}, x^{\prime}\right\rangle=\varepsilon= \pm 1, \quad \text { and } \quad\left\langle x^{\prime}, B\right\rangle=-1
$$

We are now looking for a curve $\gamma(s)=x(s)+t(s) B(s)$ in the surface with $\left\langle\gamma^{\prime}, \gamma^{\prime}\right\rangle=0$ and $\left\langle\gamma^{\prime}, B\right\rangle \neq 0$. Writing $\gamma^{\prime}=x^{\prime}+t^{\prime} B+t B^{\prime}$, the condition $\left\langle\gamma^{\prime}, \gamma^{\prime}\right\rangle=0$ now becomes

$$
\begin{equation*}
2 t^{\prime}=\varepsilon+2 t\left\langle x^{\prime}, B^{\prime}\right\rangle+t^{2}\left\langle B^{\prime}, B^{\prime}\right\rangle \tag{2.3}
\end{equation*}
$$

Equation (2.3) can be locally integrated to obtain $t$. Moreover, $\left\langle\gamma^{\prime}, \boldsymbol{B}\right\rangle=$ $\left\langle x^{\prime}, B\right\rangle \neq 0$. Thus, using the curve $\gamma$ as the directrix, $X(s, t)$ can be reparametrized as in case (4).

Since case (1) has been discussed in [5], we will pay attention to the latter one which we aim to characterize in terms of the Laplacian of its Gauss map. Therefore, let $M$ be a ruled surface in $L^{3}$ parametrized by $X(s, t)=x(s)+t B(s)$, where the directrix $x(s)$, as well as the rulings $B(s)$, are null. Furthermore, and without loss of generality, we may assume $\left\langle x^{\prime}, B\right\rangle=-1$. First of all, we will do a detailed study of this kind of surfaces.

The matrix of the metric on $M$ writes, with respect to coordinates ( $s, t$ ), as follows

$$
\left(\begin{array}{cc}
2 t\left\langle x^{\prime}, B^{\prime}\right\rangle+t^{2}\left\langle B^{\prime}, B^{\prime}\right\rangle & -1 \\
-1 & 0
\end{array}\right)
$$

In terms of local coordinates $\left(y_{1}, \ldots, y_{n}\right)$, the Laplacian $\Delta$ of a manifold is defined by (see [4, p. 100])

$$
\Delta=-\frac{1}{\sqrt{|g|}} \sum_{i, j} \frac{\partial}{\partial y_{i}}\left(g g^{i j} \frac{\partial}{\partial y_{j}}\right)
$$

where $g=\operatorname{det}\left(g_{i j}\right)$ and $\left(g_{i j}\right)$ denotes the components of the metric with respect to $\left(y_{1}, \ldots, y_{n}\right)$. Then the Laplacian on the surface $M$ is nothing but

$$
\Delta=-2 \frac{\partial^{2}}{\partial s \partial t}-2\left\{\left\langle x^{\prime}, B^{\prime}\right\rangle+t\left\langle B^{\prime}, B^{\prime}\right\rangle\right\} \frac{\partial}{\partial t}-\left\{2 t\left\langle x^{\prime}, B^{\prime}\right\rangle+t^{2}\left\langle B^{\prime}, B^{\prime}\right\rangle\right\} \frac{\partial^{2}}{\partial t^{2}}
$$

Now we will recall the notion of cross product in $L^{3}$. There is a natural orientation in $L^{3}$ defined as follows: an ordered basis $\{X, Y, Z\}$ in $L^{3}$ is positively oriented if $\operatorname{det}[X Y Z]>0$, where $[X Y Z]$ is the matrix with $X, Y, Z$ as row vectors. Now let $\omega$ be the volume element on $L^{3}$ defined by $\omega(X, Y, Z)=\operatorname{det}[X Y Z]$. Then given $X, Y \in L^{3}$, the cross product $X \times Y$ is the unique vector in $L^{3}$ such that $\langle X \times Y, Z\rangle=\omega(X, Y, Z)$, for any $Z \in L^{3}$.

Then the Gauss map can be directly obtained from $X_{s} \times X_{t}$ getting

$$
G(s, t)=x^{\prime}(s) \times B(s)+t B^{\prime}(s) \times B(s) .
$$

By putting $C=x^{\prime} \times B$, then $\left\{x^{\prime}, B, C\right\}$ is a frame field along $x$ of $L^{3}$. In this frame, we easily see that $B^{\prime} \times B=-f B, f$ being the function defined by $f=\left\langle\boldsymbol{x}^{\prime}, B^{\prime} \times B\right\rangle$. Thus

$$
\begin{equation*}
G(s, t)=-t f(s) B(s)+C(s) . \tag{2.4}
\end{equation*}
$$

Also, and for later use, we find out that

$$
\begin{equation*}
B^{\prime}=-\left\langle x^{\prime}, B^{\prime}\right\rangle B-f C \tag{2.5}
\end{equation*}
$$

and

$$
\begin{equation*}
C^{\prime}=-f x^{\prime}-\left\langle x^{\prime}, x^{\prime \prime} \times B\right\rangle B . \tag{2.6}
\end{equation*}
$$

As for the shape operator $S$ we have that

$$
\begin{equation*}
G_{t}:=\frac{\partial G}{\partial t}=B^{\prime} \times B=-f B=-f X_{t} \tag{2.7}
\end{equation*}
$$

and

$$
\begin{equation*}
G_{s}:=\frac{\partial G}{\partial s}=-\left(\left\langle x^{\prime}, x^{\prime \prime} \times B\right\rangle+t f^{\prime}\right) X_{t}-f X_{s} . \tag{2.8}
\end{equation*}
$$

So $S$ writes down as

$$
\left(\begin{array}{cc}
f & 0 \\
t f^{\prime}+\left\langle x^{\prime}, x^{\prime \prime} \times B\right\rangle & f
\end{array}\right) .
$$

A straightforward computation yields

$$
\begin{equation*}
\Delta G=2\left\{f^{\prime}+t f\left\langle B^{\prime}, B^{\prime}\right\rangle\right\} B-2 f^{2} C \tag{2.9}
\end{equation*}
$$

We now present a very typical example.
Example. Let $x(s)$ be a null curve in $L^{3}$ with Cartan frame $\{A, B, C\}$, i.e., $A, B, C$ are vector fields along $x$ in $L^{3}$ satisfying the following conditions:

$$
\begin{gathered}
\langle A, A\rangle=\langle B, B\rangle=0, \quad\langle A, B\rangle=-1 \\
\langle A, C\rangle=\langle B, C\rangle=0, \quad\langle C, C\rangle=1
\end{gathered}
$$

and

$$
\begin{aligned}
x^{\prime} & =A \\
C^{\prime} & =-a A-\kappa(s) B
\end{aligned}
$$

$a$ being a constant and $\kappa(s)$ a function vanishing nowhere. Then the map

$$
\begin{aligned}
X: L^{2} & \rightarrow L^{3} \\
(s, t) & \rightarrow x(s)+t B(s)
\end{aligned}
$$

defines a Lorentz surface $M$ in $L^{3}$ that L. K. Graves [8] called a $B$-scroll. It is not difficult to see that a unit normal vector field is given by

$$
G(s, t)=-a t B(s)+C(s)
$$

and the shape operator writes down, relative to the usual frame $\{\partial X / \partial s, \partial X / \partial t\}$, as

$$
S=\left(\begin{array}{cc}
a & 0 \\
k(s) & a
\end{array}\right)
$$

Thus the $B$-scroll has non-diagonalizable shape operator with minimal polynomial $P_{S}(u)=(u-a)^{2}$. It has constant mean curvature $\alpha=a$ and constant Gaussian curvature $K=a^{2}$ and satisfies $\Delta G=\lambda G$, where $\lambda=2 a^{2}$.

## 3. Main results

It seems natural to state the following problem: is a $B$-scroll the only ruled surface in $L^{3}$ with null rulings satisfying the equation $\Delta G=\Lambda G$ ?

Then our major result states as follows.
Theorem 1. B-scrolls over null curves are the only ruled surfaces in $\mathbf{L}^{\mathbf{3}}$ with null rulings satisfying the equation $\Delta G=\Lambda G$.

From here and Choi's result we have got the complete classification of ruled surfaces in the 3-dimensional Lorentz-Minkowski space whose Gauss map satisfies $\Delta G=\Lambda G$.

Corollary 2. A ruled surface $M$ in $L^{3}$ satisfies the equation $\Delta G=\Lambda G$ if and only if $M$ is one of the following surfaces:
(1) $R^{2}, L^{2}$ and the cylinders $S_{1}^{1} \times R^{1}, R_{1}^{1} \times S^{1}$ and $H^{1} \times R^{1}$;
(2) $a \operatorname{B}$-scroll over a null curve.

Proof of the Theorem. Suppose that the Gauss map of $M$ satisfies the equation $\Delta G=\Lambda G$. From Choi's result we may suppose that $M$ has null rulings, so we only have to study the case (4). We are going to show that the function $f=\left\langle x^{\prime}, B^{\prime} \times B\right\rangle$ is constant or, equivalently, that the open set $\mathscr{U}=$ $\left\{s \in I: f(s) f^{\prime}(s) \neq 0\right\}$ is empty. Otherwise, for $s \in \mathscr{U}$, differentiating with respect to $t$ in $\Delta G=\Lambda G$, we have

$$
\begin{equation*}
2 f\left\langle B^{\prime}, B^{\prime}\right\rangle B=-f \Lambda B \tag{3.10}
\end{equation*}
$$

where we have used equations (2.4), (2.7) and (2.9). By (2.5) we obtain $\left\langle B^{\prime}, B^{\prime}\right\rangle=f^{2}$, so that from (3.10) we see that $-2 f^{2}$ is an eigenvalue of $\Lambda$, unless $f=0$. Then $f$ is a constant function, which is a contradiction that finishes the proof.

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