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On Deformations of the C_l -Metrics on Spheres

Kazuyoshi Kiyohara

1. This note is a summary of our recent result concerning the existence problem of deformations of the standard metric by $C_{2\pi}$ -metrics on the *n*-dimensional sphere S^n . By definition a riemannian metric g on a manifold M is called a C_t -metric if all of its geodesics are closed and have the common length l. Let $\{g_t\}$ be a one-parameter family of $C_{2\pi}$ metrics on S^n with g_0 being the standard one, and put

$$\frac{d}{dt}g_t|_{t=0} = h$$

We call such a symmetric 2-form h an infinitesimal deformation. It is known that each infinitesimal deformation h satisfies the so-called zeroenergy condition, i.e.,

 $\int_0^{2\pi} h(\dot{\gamma}(s),\,\dot{\gamma}(s))ds = 0$

for any geodesic $\mathcal{T}(s)$ of (S^n, g_0) parametrized by arc-length (cf. [1] p. 151). In [3] we gave another necessary condition, the second order condition, for a symmetric 2-form to be an infinitesimal deformation, and showed that there are symmetric 2-forms which satisfy the zero-energy condition, but not satisfy the second order condition in the case of S^n $(n \ge 3)$. The present theorem is an extension of the result in [3]. We first review the second order condition, and then state the theorem.

2. Let K_2 be the vector space of symmetric 2-forms on S^n which satisfy the zero-energy condition. Let # be the bundle isomorphism from the cotangent bundle T^*S^n to the tangent bundle TS^n obtained by the riemannian metric g_0 . Define the function \hat{h} on T^*S^n for a symmetric 2-form h by

$$\hat{h}(\lambda) = h(\sharp(\lambda), \sharp(\lambda)), \lambda \in T^*S^n.$$

Let S^*S^n be the unit cotangent bundle with respect to the metric g_0 . We

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denote by \tilde{H}_2 the image of the map $\hat{}$, and by H_2 the vector space of functions on S^*S^n which are the restrictions of functions in \tilde{H}_2 to S^*S^n . Put $E_0 = (1/2)\hat{g}_0$. There is a homogeneous symplectic vector field X(h) on T^*S^n -{0-section} such that $X(h)E_0 = \hat{h}$, provided $h \in K_2$. Let G be the linear operator on $C^{\infty}(S^*S^n)$ defined by

$$G(f)(\lambda) = \frac{1}{2\pi} \int_0^{2\pi} f(\xi_t \lambda) dt, \ \lambda \in S^* S^n, f \in C^{\infty}(S^* S^n),$$

where $\{\xi_t\}$ is the geodesic flow associated with g_0 . Then we can define the symmetric bilinear map $F: K_2 \times K_2 \rightarrow G(C^{\infty}(S^*S^n))$ by

$$F(f,h) = G(X(f)\hat{h}), \qquad f,h \in K_2,$$

where $X(f)\hat{h}$ is considered as a function on S^*S^n by restriction. We say $h \in K_2$ satisfies the second order condition if $F(h, h) \in G(H_2)$. It can be seen that each infinitesimal deformation satisfies the second order condition (cf. [3] Theorem 1).

3. We now assume that $n \ge 3$. Consider S^n as the unit sphere in \mathbb{R}^{n+1} , and let $\iota: S^n \to \mathbb{R}^{n+1}$ be the inclusion. Let $x = (x_1, \dots, x_{n+1})$ be the canonical coordinate system on \mathbb{R}^{n+1} . Let $\mathbb{R}[x]_m$ be the vector space of homogeneous polynomials of degree m in the variables x, and set

$$\boldsymbol{R}[\boldsymbol{x}]_{\mathrm{od}} = \sum_{k \ge 0} \boldsymbol{R}[\boldsymbol{x}]_{2k+1}.$$

It is easy to see that $(\iota^* f)g_0 \in K_2$ for any $f \in \mathbf{R}[x]_{od}$.

Theorem. Let $f \in \mathbf{R}[x]_{od}$. Then $(\iota^*f)g_0$ satisfies the second order condition if and only if f has one of the following forms:

(i)
$$f \equiv h_1 + h_3 + \sum_{i=2}^m (\sum_k a_k x_k)^{2i} (\sum_j b_{ij} x_j) \mod (1 - \sum_i x_i^2),$$

 $a_k, b_{ij} \in \mathbf{R}, h_1 \in \mathbf{R}[x]_1, h_3 \in \mathbf{R}[x]_3;$

(ii)
$$f \equiv h_1 + h_3 + cA^*h \mod (1 - \sum_i x_i^2),$$

 $h_1 \in \mathbf{R}[x]_1, h_3 \in \mathbf{R}[x]_3, c \in \mathbf{R}, A \in O(n+1, \mathbf{R}), and$

$$h = \sum_{i=2}^{10} \alpha_{2i+1} x_1^{2i+1} + \sum_{i=2}^{6} \beta_{2i+1} x_1^{2i} x_2 + \sum_{i=2}^{6} \gamma_{2i+1} x_1^{2i-1} x_2^2 + \delta_5 x_1^2 x_2^3 + \varepsilon_5 x_1 x_2^4,$$

where the coefficients satisfy the conditions $\beta_{13} \in \mathbf{R}$, $\gamma_{13} \in \mathbf{R} - \{0\}$,

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$$\begin{aligned} \alpha_{5} &= \frac{10}{13} \gamma_{13} - \frac{5^{2}}{13^{2} \cdot 4^{3} \cdot 3} \frac{\beta_{13}^{4}}{\gamma_{13}^{2}} + \frac{15}{4} \frac{\beta_{13}^{2}}{\gamma_{13}} + 45, \\ \alpha_{7} &= -\frac{10}{13} \gamma_{13} - 5 \frac{\beta_{13}^{2}}{\gamma_{13}} - 120, \ \alpha_{9} &= \frac{5}{13} \gamma_{13} + \frac{15}{4} \frac{\beta_{13}^{2}}{\gamma_{13}} + 210, \\ \alpha_{11} &= -\frac{1}{13} \gamma_{13} - \frac{3}{2} \frac{\beta_{13}^{2}}{\gamma_{13}} - 252, \ \alpha_{13} &= \frac{1}{4} \frac{\beta_{13}^{2}}{\gamma_{13}} + 210, \\ \alpha_{15} &= -120, \ \alpha_{17} = 45, \ \alpha_{19} &= -10, \ \alpha_{21} = 1, \\ \beta_{5} &= \frac{75}{13} \beta_{13} - \frac{5^{2}}{13^{2} \cdot 3 \cdot 8} \frac{\beta_{13}^{3}}{\gamma_{13}}, \ \beta_{7} &= -\frac{140}{13} \beta_{13}, \ \beta_{9} &= \frac{135}{13} \beta_{13}, \\ \beta_{11} &= -\frac{66}{13} \beta_{13}, \ \gamma_{5} &= \frac{25}{13} \gamma_{13} - \frac{25}{13^{2} \cdot 8} \beta_{13}^{2}, \\ \gamma_{7} &= -\frac{70}{13} \gamma_{13}, \ \gamma_{9} &= \frac{90}{13} \gamma_{13}, \ \gamma_{11} &= -\frac{55}{13} \gamma_{13}, \\ \delta_{5} &= -\frac{25}{13^{2} \cdot 6} \gamma_{13} \beta_{13}, \ \varepsilon_{5} &= -\frac{25}{13^{2} \cdot 12} \gamma_{13}^{2}. \end{aligned}$$

Remark 1. In the case of S^2 , it has been proved by Guillemin [2] that all elements of K_2 are infinitesimal deformations.

Remark 2. Let u be an odd polynomial in one variable, and put $f=u(\sum_k a_k x_k)$. Then f belongs to the class (i) in Theorem. We can see that $(\iota^*f)g_0$ is an infinitesimal deformation. In fact this corresponds to a family of $C_{2\pi}$ -metrics constructed by Zoll and Weinstein (cf. [1] p. 120).

The details will be given in [4].

Bibliography

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Department of Mathematics Hokkaido University Kita-ku, Sapporo 060 Japan