## ESSAY II. CONTINUATION OF AN EXAMPLE OF C. DELLACHERIE

1. THE PROCESS  $R_{+}$  .

We consider a single occurrence in continuous time  $t \ge 0$  which happens at an instant  $T_* \ge 0$  which may be random. For example,  $T_*$  may be the failure time of some mechanical apparatus. Analytically, the entire situation is described simply by the distribution function  $F(x) = P\{T_* \le x\}$ . We restrict F only by F(0-) = 0 and  $F(\infty) \le 1$ , and we define  $T_* = \infty$  where  $T_*$  is not finite, so that  $P\{T_* = \infty\} = 1 - F(\infty)$ . Without risk of confusion, we speak of the "occurrence of  $T_*$ ," thus identifying the event with its instant.

From the viewpoint of an observer waiting for  $T_{\star}$  to occur, the situation presents itself not as a distribution function but as a stochastic process, and as such it provides a basic example of general methods. Thus we associate with  $T_{\star}$  the process

(1.0)  $R_{t} = I_{[T,\infty]}(t) , -\infty \le t \le \infty,$ 

where I denotes the usual indicator function.

This process was studied by C. Dellacherie (1972), and by C. S. Chou and P. A. Meyer (1975). The closely related process  $T_{\star} \wedge t$  was also studied briefly by C. Dellacherie and P. A. Meyer (1975), who corrected some errors in [4]. Since we require some preliminary results from [4], we use that formulation in large part. However, our purpose is to study  $R_t$  in terms of its prediction process, as defined in F. B. Knight (1975) and P. A. Meyer (1976). This dictates that  $\{T_{\star} = 0\}$  and  $\{T_{\star} = \infty\}$  be permitted to have positive probability, which in turn makes it useful to set  $R_t = 0$  for  $-\infty \leq t < 0$ . Thus we introduce the probability space  $(\Omega, F^O, P)$  where  $\Omega = [0,\infty]$ ,  $F^O$  is the Borel  $\sigma$ -field, and P(dx) = F(dx), and we define  $T_{\star}(x) = x$  on  $\Omega$ , so that  $R_r(x) = I_{[x,\infty]}(t)$ ,  $-\infty \leq t \leq \infty$ . Then the  $\sigma$ -field  $F_t^O$  generated by  $R_s$ ,  $s \leq t$ , is  $\{\Phi, \Omega\}$  for t < 0, and is that generated by the atom  $(t,\infty]$  and the Borel sets of [0,t] for  $t \geq 0$ .

As an example of the "general theory of processes,"  $R_t$  was replaced in [4] by the supermartingale  $X_t = E(R_{\infty} - R_t | F_t^O) = I_{[0,T_*)}(t)$ , which was even a potential since  $P\{T_{\star} < \infty\} = 1$  was assumed. In the present case, the argument of [4, Chap. 5, T56] transfers with no substantial change to provide the Doob-Meyer decomposition of  $R_t$ . We need the usual augmented  $\sigma$ -fields  $F_t (= F_t^P)$  generated by  $F_t^O$  and all P-null sets in the completion of P on  $F^O$ . Observe that  $F_t = F_{t+}$ , where for any adapted family of  $\sigma$ -fields  $G_t$  we set  $G_{t+} = \bigcap_{s>t} G_s$  and  $G_{t-} = \bigvee_{s < t} G_s$ . THEOREM 1.1. The unique  $F_t$ -previsible increasing process  $R_t^{\times}$  such that  $R_0^{\times} = P\{R_0 = 1\}$  and  $R_t - R_t^{\times}$  is a martingale is given by

$$R_{t}^{\mathcal{H}} = 0 , \quad -\infty \leq t < 0 ,$$

$$R_{t}^{\mathcal{H}} = \int_{0-}^{T_{\star}} \wedge t (1 - F(u-))^{-1} dF(u) , \quad 0 \leq t < \infty ,$$

$$R_{\infty}^{\mathcal{H}} = \begin{cases} R_{\infty-}^{\mathcal{H}} & \text{on } \{T_{\star} < \infty\} \\ R_{\infty-}^{\mathcal{H}} + 1 & \text{on } \{T_{\star} = \infty\} . \end{cases}$$

REMARK. Uniqueness means unique up to a fixed P-null set.

In the present note we will go one step farther, and study  $R_t$  as an example in the theory of Markov processes (as well as of martingales). Indeed, a general feature of the prediction process construction is that it permits any process to be viewed as a homogeneous Markov process--more specifically, as a right process in the sense of P. A. Meyer and having still additional structure. It may be said here that  $R_t$  provides a more or less prototypical example of the prediction process of a positive purejump submartingale. The behavior of this prediction process depends, in turn, on classification of the stopping times of  $F_t$ , which accordingly is our next concern. However, the reader may prefer to skip this rather technical discussion, and go directly to Section 2 where the results are applied. The connections with Essay I are postponed until the end of the present essay, for reasons stated there.

We recall that a stopping time T is "totally inaccessible" if for every increasing sequence of stopping times  $T_n$  one has  $P\{\lim_{n\to\infty} T_n = T < \infty\} = 0$ , and "previsible" if  $P\{T = 0\} = 0$  or 1, and if when  $P\{T = 0\} = 0$  there exist  $T_n$  with  $1 = P\{T_n < T\} = P\{\lim_{n\to\infty} T_n = T\}$ . For the remaining concepts in our classification, as well as its existence and uniqueness, we refer to [5, Chap. IV, Theorem 81]. According to the basic representation theorem of our particular situation ([4, III, T53]) a random time T is an  $F_t$ -stopping time if and only if for some  $s \leq \infty$ ,

(1.1) 
$$P\{\{T_{\pm} \leq s \land T\} \cup \{T_{\pm} > s = T\}\} = 1$$

We note that s is unique unless  $P\{T_* > T\} = 0$ , and then we may choose  $s = \infty$ . The classification of stopping times depends on: THEOREM 1.2. The accessible part of a stopping time T is given by

(1.2) 
$$T_{A} = \begin{cases} T & \text{on } A \\ \infty & \text{on } A^{C} \end{cases}, \text{ where}$$
$$A = \{T > T_{\star}\} \cup \{T = s < T_{\star}\} \cup \underset{s_{k} \leq s}{\bigcup} \{T = T_{\star} = s_{k}\}$$

where  $s_k$  enumerate the values with  $P\{T_* = s_k\} > 0$ . REMARK. It is easy to see that this set is unique up to a P-null set even if s is not unique. PROOF. We have  $\{T = 0\} = \{T = 0 = T_*\} \cup \{T = 0 < T_*\}$ , hence if  $P\{T = 0\} > 0$  then either 0 is an  $s_k$  or s = 0. In either case  $\{T = 0\}$  is in (1.2), as it should be. Now let  $T_n$  be any nondecreasing sequence of stopping times, and let  $T_{\infty} = \lim_{n \to \infty} T_n$ . If we assume that  $P\{T_n < T_{\infty}\} = 1$  for all n (thus  $T_{\infty}$  is previsible) and let  $s_n$ correspond to  $T_n$  as in (1.1) with  $s_n = \infty$  whenever possible, then we see that  $\lim_{n \to \infty} s_n = s_{\infty}$  exists, and satisfies (1.1) for  $T_{\infty}$ . Then we have  $\{T_* < s_{\infty}\} \subset \{T_* < T_{\infty}\}$  up to a P-null set, and therefore

(1.3) 
$$P\{\{T_* < s_m \land T_m\} \cup \{s_m = T_* \land T_m\}\} = 1$$

Conversely, if a stopping time T satisfies (1.3) for some  $s_{\infty}$  and  $P\{T > 0\} = 1$ , then we can construct a sequence  $T_n \longrightarrow T$ ,  $P\{T_n < T\} = 1$ , as follows. If  $s_{\infty} = \infty$  then  $1 = P\{\{T_* < T\} \cup \{T_* = T = \infty\}\}$  and writing  $T = f(T_*)$  on  $\Omega$  we can define  $T_n = f_n(T_*)$  where  $f_n$  are any measurable functions with  $f_n(\infty) = n$ , and for  $x < \infty$ ,  $x < f_n(x) < f(x)$  and  $\lim_{n \to \infty} f_n(x) = f(x)$ . If  $0 < s_{\infty} < \infty$ , then we define for  $n^{-1} < s_{\infty}$ 

$$T_{n} = \begin{cases} f_{n}(T_{\star}) & \text{on} \quad \{T_{\star} \leq s_{\infty} - n^{-1}\} \cup \{T_{\star} = s_{\infty} < T\} \\ \\ s_{\infty} - n^{-1} & \text{elsewhere} \end{cases}$$

and observe that  $T_n$  satisfies (1.1) with  $s = s_{\infty} - n^{-1}$ . Finally, if  $s_{\infty} = 0$  then  $P\{T_{\star} = 0\} = 1$  and T is equivalent to a positive constant. It follows that (1.3) characterizes the previsible stopping times T with  $P\{T > 0\} = 1$ .

Next we observe that for constant c, any T is accessible on a set of the form  $\{T = c\}$ , hence on  $\{T = s\} \cup \bigcup_{s_k \leq s} \{T = T_* = s_k\}$ . It remains

to show that the rest of the accessible part is given by  $\{T > T_*\}$ . That this is contained in the accessible part follows by writing  $T_n = f_n(T_*)$ as in the preceeding paragraph. On the other hand, by (1.1) we have  $\{T \leq T_{\star}\} = \{T = T_{\star}\} \cup \{T_{\star} > s = T\}$  up to a P-null set, hence the only part of  $\{T \leq T_{\star}\}$  not already found excessible is  $\{T = T_{\star} \neq s_{k}\}$  for all  $k\}$ . To see that this last is not accessible, note that for any previsible stopping time  $T_m > 0$ , (1.3) implies that the set  $\{T = T_* = T_m\}$  is contained in  $\{T = T_* = T_{\infty} = s_{\infty}\}$  up to a P-null set, where  $s_{\infty}$  corresponds to  $T_{m}$  as in (1.3). Therefore, only sets  $\{T = T_{*} = s_{\nu}\}$  of positive probability can be in the accessible part, and the proof is complete. COROLLARY 1.3. A stopping time T is: a) totally inaccessible if and only if  $P{T > T_*} = 0$  and  $P{s = T \le T_*} = 0$  for  $0 \le s \le \infty$ , b) previsible if and only if  $P{T = 0} = 0$  or 1 and, for some s,  $P{T_{+} < s \land T} \cup$  $\{s = T_{+} \land T\}\} = 1$ . PROOF. Part b) is just (1.3), so we need only prove a). The condition is obviously sufficient by Theorem 1.2. On the other hand, if  $P{s = T \leq T_{*}} > 0$  for some s, then either s corresponds to T as in (1.1) and  $P{s = T < T_*} > 0$ , or else s is one of the  $s_k$ 's in Theorem 1.2 and  $P{T = T_* = s_k} > 0$ . In either case, T is partially accessible. COROLLARY 1.4. If  $P{T_{+} = s} = 0$  for all  $s \leq \infty$ , then  $T_{+}$  is totally inaccessible and a stopping time T is previsible if and only if  $P{T = T_{+}} = 0$  . Furthermore, the necessary and sufficient condition that  $F_{+}$  be free of times of discontinuity is that, for all  $s \ge 0$ ,  $P{T_* > s} > 0$  implies that  $P{T_* = s} = 0$ . REMARK. It is known from [4, Chap. III, T51] that absence of times of

discontinuity is equivalent to the previsibility of all T whose accessible part is  $\Omega$  (up to a P-null set).

PROOF. The first assertion is immediate from Theorem 1.2. For the second, assume  $P{T = T_{\star}} = 0$ , and let s correspond to T as in (1.1). Since  $P{T_{\star} = s} = 0$ , we have  $P{T_{\star} = s \land T} = 0$ , hence T satisfies Corollary 1.3 b). Conversely, if  $P{T = T_{\star}} > 0$  then T is inaccessible on this set, hence not previsible.

It remains to prove the last assertion. Assume that the condition holds; i.e., that the distribution of  $T_*$  has not atoms except perhaps its maximal value, and suppose that the accessible part of T is  $\Omega$ . Let s correspond to T as in (1.1). If  $P\{T_* = s\} > 0$ , then by Theorem 1.2 we have  $1 = P\{\{T > T_*\} \cup \{T = T_* = s\}\}$ , and since  $T_* \leq s$  holds on  $\{T > T_*\}$ , T is previsible by Corollary 1.3 b). If, on the other hand,

$$\begin{split} &\mathbb{P}\{\mathbf{T_{\star}}=s\}=0, \text{ then if } \mathbb{P}\{\mathbf{T}=\mathbf{T_{\star}}=s_k\}>0 \text{ for any } s_k, \text{ we see from} \\ &\mathbb{P}\{\mathbf{T_{\star}}>s_k\}=0 \text{ and (1.1) that } s_k < s, \text{ and hence } s_k \text{ may replace s in} \\ &(1.1). \text{ Thus either we have the former case, or } \mathbb{P}\{\mathbf{T}=\mathbf{T_{\star}}=s\}=0 \text{ for all } \\ &s \text{ . Then since } \mathbf{T}>\mathbf{T_{\star}} \text{ implies } \mathbf{T_{\star}}<s \text{ except on a P-null set, and} \\ &1=\mathbb{P}\{\{\mathbf{T}>\mathbf{T_{\star}}\}\cup\{\mathbf{T}=s<\mathbf{T_{\star}}\}\}, \text{ by Corollary 1.3 b) } \mathbf{T} \text{ is again} \\ &\text{ previsible. Thus (see the Remark) } F_t \text{ is free of discontinuities. The} \\ &\text{ converse is obvious, since } \mathbb{P}\{\mathbf{T_{\star}}>s\}>0 \text{ and } \mathbb{P}\{\mathbf{T_{\star}}=s\}>0 \text{ imply} \\ &F_{s-}\neq F_{s} \text{ .} \end{split}$$

## 2. THE PREDICTION PROCESS OF ${\rm R}_+$ .

We turn now to the construction of the prediction process of  $R_t$ , which we will denote by  $Z_t$ . According to its definition, the values of  $Z_t$ are the conditional probability distributions of  $T_{t+(\cdot)}$  given  $F_t$  (we recall that  $F_t = F_{t+}$ ). Clearly such distributions can be specified by the conditional distribution of  $T_t - t$  given  $F_t$ , whence they have the same form as F. Thus, writing  $Z_t(x) = Z_t(x,w)$  for the corresponding distribution function, we have  $Z_t(0) = 1$  if  $t \ge T_t$  or F(t) = 1, while  $Z_t(x) = (F(t + x) - F(t))/(1 - F(t))$  otherwise. The left-limit process of  $Z_t$ , in a suitable topology to be specified, is  $Z_{t-}(0) = 1$  if  $t > T_t$  or F(t-) = 1, and  $Z_{t-}(x) = (F(t + x) - F(t-))/(1-F(t-))$ otherwise.

The prediction process may be used to best advantage only by introducing it as a Markov process in its own right, instead of confining it to the probability space of  $R_t$  (this represents a partial shift of the author's views from those expressed in [9]). This is because there are technical difficulties in carrying out the theory of additive functionals of the prediction process if it is defined on the original probability space  $\Omega$ (as noted by R. K. Getoor (1978)). On the other hand, once we free ourselves from this restriction, the theory becomes comparatively straightforward. Furthermore, in a sense to be made precise, nothing concerning the process  $R_t$  is lost in the transition. Therefore, we introduce formally both a new state space and a new probability space.

DEFINITION 2.1. The prediction state space of  $\rm R_t$  is the space (E  $_Z, \ E_Z)$  where

$$\begin{split} E_{Z} &= \{ (F(t+\cdot) - F(t))/1 - F(t) , -\infty < t < \infty : F(t) \neq 1 ; \\ (F(t+\cdot) - F(t-))/(1 - F(t-)) , -\infty < t < \infty : F(t-) \neq 1 ; \\ F_{-\infty}, \text{ and } F_{+\infty} \} , \text{ with } F_{-\infty}(x) \equiv 0 , F_{+\infty}(x) \equiv 1 , \end{split}$$

and  $E_Z$  is the  $\sigma$ -field generated by the functions  $G(\mathbf{x})$ ,  $0 \leq \mathbf{x} \leq \infty$ , as G varies on  $E_Z$ . We denote elements of  $E_Z$  of the first two types by  $F_t$  and  $F_{t-}$  respectively (although, with this notation, they are not necessarily distinct). We let  $E_Z^+$  denote  $\{F_{-\infty}, F_{+\infty}, F_t, -\infty < t < \infty\}$ .

In the present very specialized situation, it is natural to introduce in E the topology of weak convergence of measures on  $\Omega$ , when  $\Omega$  is considered as a subset of the space  $\mbox{ D}$  with the Skorokhod  $\mbox{ J}_1\mbox{-topology}$ (Billingsley, [2], Chapter 3). Specifically, to each  $x \in \Omega$  we associate the element of D given by  $f_x(s) = R_t(x)$  with  $s = \frac{1}{2}(1 + \frac{2}{\pi} \arctan t)$ ,  $-\infty \le t \le \infty$ . We note that  $f_x(s) = 0$  for  $0 \le s < \frac{1}{2}$ , and that convergence in D of  $f_{x}$  is the same as convergence of x in the extended topology of  $[0,\infty]$  . It therefore follows that the continuous functions on  $\ \Omega$  in the D-topology are just C[0, $\infty$ ], and weak convergence of probabilities on  $\Omega$ becomes simply weak convergence of the corresponding distribution functions F on  $[0,\infty]$  . In particular, we note that  $\mathbf{E}_{\mathbf{Z}}$  is a Borel set and that  $\mathbf{E}_{\mathbf{Z}}$ is a Borel  $\sigma\text{-field}$  generated by this (metrizable) topology on  $\text{ E}_{\sigma}$  . Furthermore, since  $F_t$  is right-continuous for  $t < \min\{s: F(s) = 1\}$ , with left limits  $F_{t-}$  for t > 0, it is clear that  $Z_t$  is right-continuous with left limits in this topology. In fact, the space  $E_{\chi}$  is "almost" compact, the only limit points not necessarily included being those of  $F_{+}$ obtained as  $t \longrightarrow +\infty$ . This set is trivial if either  $F(\infty) < 1$  or F(t) = 1 for some  $t < \infty$ , but in general it cannot be avoided.

We turn next to the <u>prediction probability space</u> for the process  $Z_t$ , using the same notation  $Z_t$  for the process on the new space. DEFINITION 2.2. Let  $(\Omega_z, F_z, Z_t)$  consist of

a) The space of all paths z(t),  $0 \le t < \infty$ , with values in  $E_Z^+$  and which are right-continuous, with left limits for t > 0, in the topology of weak convergence,

b) The coordinate  $\sigma\text{-field}$  generated on  $\Omega_{\rm Z}$  by {z(t)  $\in$  A}, t  $\geq$  0, A  $\in$  E\_{\rm Z} .

c) The coordinate functions  $Z_{t} = Z_{t}(z) = z(t)$ .

We observe that the original  $F(=F_{0-})$  is in  $\Omega_z$ , and that the process on  $\Omega$  given by  $F_{\infty}$  for  $0 \le t < T_{\star}$  and by  $F_{\infty}$  for  $t \ge t_{\star}$  has its paths as points in  $\Omega_z$ . Hence we can define a probability P on  $(\Omega_z, F_z)$  such that the joint distributions of Z(t) are the same as those of the above process on  $\Omega$ . Furthermore, to every  $z \in E_z$  we can associate in the same way probability  $P^Z$  on  $(\Omega_z, F_z)$ , by using z in the role of F as the distribution of  $T_{\star}$ . Thus the points  $z \in E_z$  correspond to probabilities for  $Z_t$ . If  $z = F_t$  for some t,

 $-\infty \le t \le \infty$ , then  $P^{Z} \{Z_0 = z\} = 1$ . However, if  $z = F_{t-} \ne F_t$ , so that F(t) - F(t-) > 0, then  $P^{Z} \{Z_0 = F_t\} = 1$ .

We are now in a position to view the family  $\{P^{X}, z \in E_{Z}\}$  as a Markov process on  $(\Omega_{Z}, F_{Z})$ . The points z such that  $z = F_{t-} \neq F_{t}$ are the "branching points" of this process, in the terminology of Walsh and Meyer [13]. The transition function q(t,z,A) of the process is such that for each (t,z) the probability is concentrated on at most two points. Precisely, we have

DEFINITION 2.3. The transition function of  $Z_t$  is given by q(t,z,A),  $t \ge 0$ ,  $z \in E_z$ ,  $A \in E_z$ , where

i)  $q(t, F_{\infty}, \{F_{\infty}\}) = 1$ ,  $t \ge 0$ 

ii)  $q(t,z, {F_{\omega}}) = 1 - q(t,z, {F_{s+t}}) = F_{s}(t)$  if  $z = F_{s}$  and  $1 > F_{c}(t) (=F(s+t))$ ,  $t \ge 0$ ,

iii)  $q(t,z, {F_{\omega}}) = 1 - q(t,z, {F_{s+t}}) = F_{s-}(t)$  if  $z = F_{s-} \neq F_s$  and  $1 > F_s(t)$ , t > 0,

iv)  $q(t,z, \{F_m\}) = 1$  in cases ii) and iii) if  $1 = F_c(t)$ ,

v)  $q(0,z, \{F_{\infty}\}) = 1 - q(0,z, \{F_{S}\}) = F_{S}(0)$  in case iii).

It follows from the general theory of [9] and [11] (or can easily be seen directly) that  $(\Omega_{Z'}, F_{Z'}, Z_t, P^Z)$  becomes a right process on  $E_Z^+$  in the sense of P. A. Meyer, with transition function q, when we include the canonical translation operators  $\theta_t^Z$  and  $\sigma$ -fields  $F_t^Z$ . Of course, both  $E_Z^+$  and q are Borel, so the general U-space set-up of Getoor [6] is unnecessary (this is quite generally true for the prediction process). Furthermore, the process has unique left limits  $Z_{t-}$  in  $E_{Z'}$ , t > 0.

It is important to observe that probabilistically nothing is lost by considering (Z<sub>t</sub>, P<sup>F</sup>) in place of (R<sub>t</sub>, P). Thus we introduce on  $E_Z^+$  the Borel function

(2.1)  $\varphi(G) = \begin{cases} 0 & \text{if } G \neq F_{\infty} \\ 1 & \text{if } G = F_{\infty} \end{cases}.$ 

Then  $\varphi(Z_t)$  is  $p^F$ -equivalent to  $R_t$  in joint distribution, and is right-continuous with left limits. Hence it is a valid replacement for  $R_t$ . The  $\sigma$ -fields  $F_t^{o,Z}$  generated by  $Z_s$ ,  $s \leq t$ , are of course larger than those generated by  $\varphi(Z_s)$ ,  $s \leq t$ . But the entire difference can be traced to the fact that  $\varphi(Z_0)$  does not determine  $Z_0$ . Thus for each initial point z the above two fields have the same  $p^F$ -completion, and hence  $Z_t$  and  $\varphi(Z_t)$  generate the same completed  $\sigma$ -fields  $F_t^Z$ .

One basic feature of the prediction process which gives insight into the given process is its times of discontinuity. The analogue of the jump time  $T_{\star}$  on  $\Omega_{\tau}$  is of course the stopping time

(2.2) 
$$T_{z,*} = \inf \{t: z_t = f_{\omega}\}$$

However, this is not necessarily a time of discontinuity for  $Z_t$  under  $p^F$ , and by no means the only one. By Theorem 1.2 the accessible part of  $T_{Z,*}$  under  $p^F$  consists of  $\bigcup_k \{T_{Z,*} = s_k\}$ , where the  $s_k$  enumerate the jump points of F. But while  $R_t$  is discontinuous at  $t = s_k$  with probability  $F(s_k) - F(s_{k-})$ ,  $Z_t$  is discontinuous at  $t = s_k$  with probability  $1 - F(s_{k-}) (= p^F \{T_{Z,*} \ge s_k\})$  unless  $F(s_k) = 1$ , when it is continuous (since  $Z_{s_k}$  is then  $F_{s_k}$ -measurable). On the other hand, at the totally inaccessible part of  $T_{Z,*}$  (i.e. the part where F is continuous),  $Z_t$  like  $R_t$  has an inaccessible jump. It is clear that  $Z_t$  is continuities under  $p^F$ , and for other  $z \in E_Z$  the situation is analogous. Thus, the conclusion which roughly emerges is that  $Z_t$  has the same totally inaccessible jumps as  $R_t$  but it has additional accessible jumps.

This distinction in the behavior of  $R_t$  and  $Z_t$  at the previsible times  $s_k$  disappears when we replace  $R_t$  by the martingale  $R_t - R_t^{"}$ of Theorem 1.1. More generally, we introduce on  $\Omega_Z$  the <u>previsible additive</u> <u>functional</u>

(2.3) 
$$A_t = \int_0^T Z_* \wedge t (1 - G(u-))^{-1} dG(u) \text{ on } \{Z_0 = G\}, G \in E_z^+$$

(previsibility is clear since  $A_t$  is a Borel function of the previsible process  $T_{Z,\star} \wedge t$ ). The process  $\varphi(Z_t) - \varphi(Z_0) - Z_t$  is now seen to be a <u>martingale additive functional</u> of  $Z_t$ . More importantly, one easily checks that  $\varphi(Z_t) - \varphi(Z_0) = A_t$  and  $Z_t$  have the <u>same times of discontinuity</u> for each  $P^G$ . This is an expression of the general fact that a rightcontinuous martingale has its times of discontinuity contained in those of its prediction process, as proved in F. Knight [10, Lemma 1.5]. However, the application is not direct because the prediction process of  $\varphi(Z_t) - A_t$  for fixed  $G = Z_0$  has a different (and less convenient) state space than  $E_Z$ , and it cannot be identified with  $Z_t$ . For example, if F(s) - F(s-) = 1 for some s then  $\varphi(Z_t) - A_t \equiv 0$  for  $P^F$  while  $Z_t$ , although continuous, is not constant. We consider finally the Lévy system of  $Z_t$ , and its relevance to  $R_t$  and  $T_t - R_t^{\times}$ . By definition [1, Corollary 5.2] this is a pair (N,H) where N(x,dy) is a kernel on  $(E_z, E_z)$ , N(x,{x}) = 0, and H is a previsible additive functional such that for  $0 \le f(x,y) \in E_z \times E_z$ , with f(z,z) = 0,

(2.4) 
$$E^{*}(\sum_{0 \le s \le t} f(Z_{s}, Z_{s})) = E^{*} \int_{0}^{t} dH_{s}(\int_{E} N(Z_{s}, dy) f(Z_{s}, dy))$$

In the present case, although  $Z_t$  does not satisfy all the hypotheses of [1, Cor. 5.2] it is easy to specify such a system explicitly. One has only to take  $H_t = A_t$  from (2.3) and then define

(2.5)  

$$N(\mathbf{x}, d\mathbf{y}) = \begin{cases} q(0, \mathbf{x}, d\mathbf{y}) & \text{for } \mathbf{x} = \mathbf{F}_{t-} \neq \mathbf{F}_{t}, \quad -\infty < t < \infty \\ \delta(\mathbf{F}_{\infty}) & \text{otherwise, } \mathbf{x} \neq \mathbf{F}_{\infty}' \end{cases}$$

where  $\delta(F_{\infty})$  is the unit mass at  $F_{\infty}$  (we define  $N(F_{\infty}, \cdot)$  in any convenient way). As a compensator for the discontinuities of  $Z_t$ , the Lévy system is here more relevant to  $R_t - R_t^{\times}$  than to  $R_t$ , for the reasons of the preceeding paragraph. Thus we have an analogous "Lévy system" for  $R_t - R_t^{\times}$  in the form  $(N^{\times}, R_t^{\times})$  where

(2.6) 
$$N^{\varkappa}(-R^{\varkappa}_{s_{j}}, \{-R^{\varkappa}_{s_{j}} + 1\}) = F_{s_{j}}(0)$$
  
=  $1 - N^{\varkappa}(-R^{\varkappa}_{s_{j}}, \{-R^{\varkappa}_{s_{j}}\})$ 

for  $F(s_j) - F(s_j) > 0$ , and  $N^{*}(x,B) = I_B(x+1)$  for all  $x \notin \{-R_{s_j}^{*}\}$ . It is clear that (2.6) is obtained from (2.5) by just substituting the jumps of  $R_t - R_t^{*}$  for those of  $(Z_t, P^F)$  except at t = 0 and  $t = \infty$  which are disallowed as jump times of  $Z_t$ . Since (2.6) has a role analogous to (2.4) but for the martingale  $R_t - R_t^{*}$  instead of  $Z_t$ , it is natural to take it as the definition of a Lévy system for the martingale. Again, this is a very special case of a general existence theorem ([10, Theorem 1.3]).

## 3. CONNECTIONS WITH THE GENERAL PREDICTION PROCESS.

For the reader who is already familiar with Essay I, the present Section 2 is easily incorporated into that more general setting. However, it is somewhat more natural to treat all single-jump processes simultaneously, as realized by a single prediction process. This formalizes, so to speak, the essence of the underlying idea. It has been carried out by Professor John B. Walsh, who has consented to let us use the material that follows. We take w(t) = w<sub>2</sub>(t), with all other components discarded from the notation. Let  $\Omega_J$  (J for jump) be the set of functions of the form w(x) = I<sub>[T,∞)</sub>(x),  $0 \le T \le \infty$ . Then  $\Omega_J$  inherits from  $\Omega$  the topology of pointwise convergence of the corresponding T. Hence it is compact. Let H<sub>J</sub> be the set of all probability measures on  $\Omega_J$ , with the weak-\* topology. If we identify  $h \in H_J$  with the probability distribution it assigns to T, then convergence in H<sub>J</sub> becomes weak convergence of distribution functions on  $[0,\infty]$ , and H<sub>J</sub> is compact.

For  $h \in H_J$  (regarded as a measure on  $\Omega$  vanishing outside  $\Omega_J$ ), the prediction process  $Z_t$  remains in  $H_J$ , and so does  $Z_{t-}$  for t > 0. Thus  $H_J$  is a complete Borel packet, in the sense of Essay I, Definition 2.1, 3). The transition function of  $Z_t$  on  $H_J$  is given above by Essay 2, Definition 2.3. The elements of  $H_J \cap H_0$ , regarded as distributions of T, are just  $F_{\infty}$  and all F with F(0) = 0. Thus  $Z_t$  is a right process on  $H_J \cap H_0$ . In fact, we have more in the present case.

PROPOSITION 3.1.  $Z_t$  is a Ray process on  $H_J$ . PROOF. It is to be shown that  $\int_0^\infty e^{-\lambda t} q_t f dt \in C(H_J)$  if  $f \in C(H_J)$ , where

 $q_{+}f(h) = \int f(z)q(t,h,dz)$ . As before, we let  $F(t) = h\{T \leq t\}$ . Then we have

$$\int_0^\infty e^{-\lambda t} q_t f(h) dt = f(F_\infty) \int_0^\infty e^{-\lambda t} F(t) dt + \int_0^\infty e^{-\lambda t} f\left(\frac{F(t+\cdot) - F(t)}{1 - F(t)}\right) (1 - F(t) dt ,$$

where the last integrand is 0 if F(t) = 1. Now if  $h_n \rightarrow h$ , with corresponding  $F_n \rightarrow F$ , the first term on the right obviously converges to its limit with F in place of  $F_n$ . Also, if F(t) < 1 then  $\frac{F_n(t+\cdot) - F_n(t)}{1 - F(t)}$  has at most two weak limit points as  $n \rightarrow \infty$ :  $\frac{F(t+\cdot) - F(t)}{1 - F(t)}$  and  $\frac{F(t+\cdot) - F(t-)}{1 - F(t-)}$ . Thus at continuity points t of F with F(t) < 1 it converges to the same limit. Since f is bounded it is easy to see that the contribution to the last integral for  $t > \inf\{t : F(t) = 1\}$  tends to 0 as  $n \rightarrow \infty$ . Hence by dominated convergence, the last integrals also converge to their value at F, completing the proof. REMARK. It follows immediately that Conjecture 2.10 of Essay I holds for  $H_{T}$ .

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