

20. COMPUTER PROGRAMS

In this section we give a typical computer program which implements one of the algorithms of Section 17 with the help of the discretization procedure stated in Section 18. The program is written in FORTRAN 77. We also show how this program can be modified to cover other cases.

We begin by documenting the program.

PROGRAM ITEIG

* PURPOSE *

COMPUTATION OF ITERATES FOR APPROXIMATING A SIMPLE EIGENVALUE AND A CORRESPONDING EIGENVECTOR OF AN INTEGRAL OPERATOR BY THE RAYLEIGH-SCHRÖDINGER SCHEME USING THE FREDHOLM METHOD(2)

* REFERENCES *

ALGORITHM 17.8 AND TABLE 19.1 ALONG WITH THE DISCRETIZATION PROCEDURE OF SECTION 18 IN THE MONOGRAPH ENTITLED SPECTRAL PERTURBATION AND APPROXIMATION WITH NUMERICAL EXPERIMENTS BY B.V. LIMAYE. THE PROGRAM WAS WRITTEN BY R.P. KULKARNI AND B.V. LIMAYE.

* PARAMETERS *

L - THE DESIRED NUMBER OF ITERATIONS
M - THE ORDER OF THE MATRIX T_M WHICH DISCRETIZES AN INTEGRAL OPERATOR T
N - THE ORDER OF THE MATRIX A
N1 - THE SERIAL NUMBER OF THE SELECTED EIGENVALUE OF A

* MAJOR DATA STRUCTURES *

T_M - M BY M MATRIX WHICH DISCRETIZES THE INTEGRAL OPERATOR T
A - N BY N REAL SYMMETRIC MATRIX FOR WHICH WE INITIALLY SOLVE AN EIGENVALUE PROBLEM

- D - N VECTOR CONTAINING EIGENVALUES OF A IN ASCENDING ORDER
- Z - N BY N MATRIX WHOSE I-TH COLUMN CONTAINS AN EIGENVECTOR OF A CORRESPONDING TO D(I); AND HAS EUCLIDEAN NORM ONE
- LAM - L+1 VECTOR CONTAINING THE SELECTED NONZERO SIMPLE EIGENVALUE OF A IN LAM(0) AND THE SUCCESSIVE EIGENVALUE ITERATES IN LAM(1) TO LAM(L)
- U - AN EIGENVECTOR OF A CORRESPONDING TO LAM(0)
- V - THE EIGENVECTOR OF THE CONJUGATE TRANSPOSE OF A, WHICH EQUALS A, CORRESPONDING TO LAM(0) AND HAVING ITS INNER PRODUCT WITH U EQUAL TO 1/LAM(0)
- PH - M BY L+1 MATRIX CONTAINING THE INITIAL EIGENVECTOR IN THE FIRST COLUMN AND THE SUCCESSIVE EIGENVECTOR ITERATES IN THE REMAINING COLUMNS
- AV - M BY N MATRIX WHICH TRANSFORMS CERTAIN N VECTORS ASSOCIATED WITH A INTO M VECTORS
- IV - M BY N MATRIX WHICH TRANSFORMS N VECTORS INTO M VECTORS BY USING LINEAR INTERPOLATION OF FUNCTIONS
- KM,KN, KH,KV - M BY M, N BY N, N BY M, M BY N MATRICES RESPECTIVELY, WHICH STORE THE WEIGHTED VALUES OF THE KERNEL OF THE INTEGRAL OPERATOR T AT VARIOUS NODES
- TAH - N BY M MATRIX USED FOR CALCULATING EIGENVALUE ITERATES
- TAHPH - N VECTOR DENOTING THE PRODUCT OF TAH AND A COLUMN OF PH
- C - N+1 BY N MATRIX CONTAINING THE COEFFICIENTS OF A LINEAR SYSTEM USED FOR CALCULATING EIGENVECTOR ITERATES
- ZETA - SCALING FACTOR FOR THE FIRST ROW OF C
- BETA - N+1 VECTOR CONTAINING THE RIGHT HAND SIDE OF A LINEAR SYSTEM WHOSE COEFFICIENT MATRIX IS C
- SUM - N VECTOR USED IN CALCULATING BETA

- SOL - LEAST SQUARES SOLUTION OF A LINEAR SYSTEM WHOSE COEFFICIENT MATRIX IS C
- ALPHA - N BY L+1 MATRIX CONTAINING $\text{LAM}(0) \times U$ IN THE FIRST COLUMN AND THE SUCCESSIVE SOLUTION VECTORS SOL IN THE REMAINING COLUMNS
- AVAL - M VECTOR DENOTING THE PRODUCT OF AV AND A COLUMN OF ALPHA
- PRIT - M VECTOR DENOTING A WEIGHTED SUM OF PREVIOUS EIGENVECTOR ITERATES
- TMPH - M VECTOR DENOTING THE PRODUCT OF TM AND A COLUMN OF PH
- RESID - MAXIMUM NORM OF THE RESIDUAL, USED IN STOPPING CRITERIA
- RELIN - RELATIVE INCREMENT IN AN EIGENVECTOR ITERATE, USED IN STOPPING CRITERIA

* SUBROUTINES CALLED *

- EIGRS - COMPUTES THE EIGENVALUES AND EIGENVECTORS OF A REAL SYMMETRIC MATRIX (ROUTINE IN IMSL LIBRARY EDITION 9.2, EQUIVALENT TO ROUTINE EVCSF IN IMSL MATH/LIBRARY EDITION 10.0)
- LLBQF - COMPUTES THE HIGH ACCURACY SOLUTION OF A LINEAR LEAST SQUARES PROBLEM (ROUTINE IN IMSL LIBRARY, EDITION 9.2, EQUIVALENT TO ROUTINE LSBRR IN IMSL MATH/LIBRARY, EDITION 10.0)

* FUNCTIONS CALLED *

- KERNEL - REAL FUNCTION WHICH YIELDS KERNEL OF THE INTEGRAL OPERATOR T
- NODE - REAL FUNCTION WHICH YIELDS NODES FOR GENERATING THE MATRICES KM, KN, KH, KV AND IV
- WEIGHT - REAL FUNCTION WHICH YIELDS WEIGHTS FOR GENERATING THE MATRICES KM, KN, KH AND KV
- MAXNORM - REAL FUNCTION WHICH YIELDS THE MAXIMUM NORM OF A VECTOR

PROGRAM ITEIG(TAPE1,TAPE2)

PARAMETER (L=30, M=100, N=10, N1=10)

```

INTEGER  L,M,N,N1,I,J,K,JOBN,IZ,IER,IA,NN,IB,NB,IND,IX
REAL     KM(M,M),KN(N,N),KH(N,M),KV(M,N),IV(M,N),
1        A(N,N),D(N),Z(N,N),WK((2*N+1)*(N+3)+N),
1        LAM(0:L),U(N),V(N),AV(M,N),PH(M,0:L),ALPHA(N,0:L),
1        C(N+1,N),TAH(N,M),TM(M,M),
1        TAHPH(N),SUM(N),BETA(N+1),CC(4),SOL(N),IWK(N),
1        AVAL(M),PRIT(M),TMPH(M),X(M),Y(M),
1        ZETA,RESID,RELIN,
1        KERNEL,NODE,WEIGHT,MAXNORM

```

```

WRITE(2,10)
10  FORMAT(1H ,5X,"RAYLEIGH-SCHRODINGER SCHEME",/)
WRITE(2,20)
20  FORMAT(1H ,5X,"FREDHOLM METHOD(2)",/)
WRITE(2,30)
30  FORMAT(1H ,5X,"KERNEL:EXP(S*T)",/)
WRITE(2,40)
40  FORMAT(1H ,5X,"NODES:GAUSS TWO POINTS",/)
WRITE(2,50)
50  FORMAT(1H ,5X,"WEIGHTS:1/N",/)
WRITE(2,60)N,N1,M
60  FORMAT(1H ,5X,"N=",I2,3X,"N1=",I2,3X,"M=",I3,/)
WRITE(2,70)
70  FORMAT(1H ,5X,"PRECISION FOR STOPPING CRITERIA:1.0E-12",/)

```

```

*   GENERATION OF KM, KN, KH AND KV
      DO 110 I=1,M
        DO 120 J=1,M
          KM(I,J) = WEIGHT(J,M)*KERNEL(NODE(I,M),NODE(J,M))
120    CONTINUE
110   CONTINUE

      DO 130 I=1,N
        DO 140 J=1,N
          KN(I,J) = WEIGHT(J,N)*KERNEL(NODE(I,N),NODE(J,N))
140    CONTINUE
130   CONTINUE

      DO 150 I=1,N
        DO 160 J=1,M
          KH(I,J) = WEIGHT(J,M)*KERNEL(NODE(I,N),NODE(J,M))
160    CONTINUE
150   CONTINUE

      DO 170 I=1,M
        DO 180 J=1,N
          KV(I,J) = WEIGHT(J,N)*KERNEL(NODE(I,M),NODE(J,N))
180    CONTINUE
170   CONTINUE

```

```

*      GENERATION OF IV
      J=1
      DO 190 I=1,M
        IF (NODE(I,M).LT.NODE(1,N)) THEN
          IV(I,J) = 1.0
        ELSEIF (NODE(I,M).LT.NODE(2,N)) THEN
          IV(I,J) = (NODE(2,N)-NODE(I,M))
1          /((NODE(2,N)-NODE(1,N))
        ELSE
          IV(I,J) = 0.0
        ENDIF
190     CONTINUE
      DO 200 J=2,N-1
        DO 210 I=1,M
          IF (NODE(I,M).LT.NODE(J-1,N)) THEN
            IV(I,J) = 0.0
          ELSEIF (NODE(I,M).LT.NODE(J,N)) THEN
            IV(I,J)=(NODE(J-1,N)-NODE(I,M))
1            /((NODE(J-1,N)-NODE(J,N))
          ELSEIF (NODE(I,M).LT.NODE(J+1,N)) THEN
            IV(I,J)=(NODE(J+1,N)-NODE(I,M))
1            /((NODE(J+1,N)-NODE(J,N))
          ELSE
            IV(I,J) = 0.0
          ENDIF
210     CONTINUE
200     CONTINUE
      J=N
      DO 220 I=1,M
        IF (NODE(I,M).LT.NODE(N-1,N)) THEN
          IV(I,J) = 0.0
        ELSEIF (NODE(I,M).LT.NODE(N,N)) THEN
          IV(I,J) = (NODE(N-1,N)-NODE(I,M))
1          /((NODE(N-1,N)-NODE(N,N))
        ELSE
          IV(I,J) = 1.0
        ENDIF
220     CONTINUE

```

```

*      STEP 1(I): EIGNELEMENTS OF A

```

```

      DO 310 I=1,N
        DO 320 J=1,N
          A(I,J) = KN(I,J)
320     CONTINUE
310     CONTINUE

      JOBN = 12
      IZ = N
      CALL EIGRS(A,N,JOBN,D,Z,IZ,WK,IER)

      WRITE(2,330)
330     FORMAT(1H ,5X,"EIGENVALUES OF A",/)
      WRITE(2,340)(D(I),I=1,N)
340     FORMAT(1H ,3X,3E21.13)

```

```

    LAM(0) = D(N1)
    DO 350 I=1,N
        U(I) = Z(I,N1)
350    CONTINUE

*   STEP 1(II): EIGENVECTOR OF CONJUGATE TRANSPOSE OF A

    DO 360 I=1,N
        V(I) = Z(I,N1)/LAM(0)
360    CONTINUE

*   STEP 2

*   GENERATION OF AV
    DO 410 I=1,M
        DO 420 J=1,N
            AV(I,J) = 0.0
            DO 430 K=1,N
                AV(I,J) = AV(I,J)+IV(I,K)*KN(K,J)
430            CONTINUE
420        CONTINUE
410    CONTINUE

*   COMPUTATION OF PH(0)
    DO 440 I=1,M
        PH(I,0) = 0.0
        DO 450 J=1,N
            PH(I,0) = PH(I,0)+AV(I,J)*U(J)
450        CONTINUE
440    CONTINUE

*   COMPUTATION OF ALPHA(0)
    DO 460 I=1,N
        ALPHA(I,0) = LAM(0)*U(I)
460    CONTINUE

*   GENERATION OF C
    ZETA = 0.0
    DO 470 I=1,N
        IF (ZETA .LT. ABS(D(I)-D(N1))) THEN
            ZETA = ABS(D(I)-D(N1))
        ENDIF
470    CONTINUE
        ZETA = ZETA*LAM(0)

        DO 480 J=1,N
            C(1,J) = ZETA*V(J)
480        CONTINUE
        DO 490 I=2,N+1
            DO 500 J=1,N
                C(I,J) = A(I-1,J)
500            CONTINUE
490        CONTINUE
        DO 510 I=1,N
            C(I+1,I) = A(I,I)-LAM(0)
510    CONTINUE

```

```

*   GENERATION OF TAH
      DO 520 I=1,N
        DO 530 J=1,M
          TAH(I,J) = KH(I,J)
530     CONTINUE
520     CONTINUE

*   GENERATION OF TM
      DO 540 I=1,M
        DO 550 J=1,M
          TM(I,J) = KM(I,J)
550     CONTINUE
540     CONTINUE

      WRITE (2,690)
690     FORMAT (/,1H ,6X,`J`,9X,`LAM(J)`,10X,`RESID`,5X,`RELIN`
              J = 0
              WRITE (2,700) J,LAM(J)
700     FORMAT (/,1H ,5X,I2,2X,E19.13,2E10.2)

*   THE ITERATION STARTS

      DO 710 J=1,L

*   STEP 2(I):COMPUTATION OF J-TH EIGENVALUE ITERATE

      DO 720 I=1,N
        TAHPH(I) = 0.0
        DO 730 K=1,M
          TAHPH(I) = TAHPH(I)+TAH(I,K)*PH(K,J-1)
730     CONTINUE
720     CONTINUE

        LAM(J) = 0.0
        DO 740 I=1,N
          LAM(J) = LAM(J)+TAHPH(I)*V(I)
740     CONTINUE

*   STEP 2(II):SOLUTION OF (N+1)*N LINEAR SYSTEM

*   CALCULATION OF RIGHT HAND SIDE
      DO 810 I=1,N
        SUM(I) = 0.0
        DO 820 K=0,J-1
          SUM(I) = SUM(I)+LAM(J-K)*ALPHA(I,K)
820     CONTINUE
810     CONTINUE

        BETA(1) = 0.0
        DO 830 I=1,N
          BETA(I+1) = -TAHPH(I)+SUM(I)
830     CONTINUE

```

```

*   LEAST SQUARES SOLUTION
      IA = N+1
      NN = N+1
      IB = N+1
      NB = 1
      IND = 0
      IX = N
CALL  LLBQF(C, IA, NN, N, BETA, IB, NB, IND, CC, SOL, IX, IWK, WK, IER)
      DO 840 I=1, N
      .   ALPHA(I, J) = SOL(I)
840   CONTINUE

*   STEP 2(III): COMPUTATION OF THE J-TH EIGENVECTOR ITERATE

      DO 910 I=1, M
      AVAL(I) = 0.0
      DO 920 K=1, N
      .   AVAL(I) = AVAL(I) + AV(I, K) * ALPHA(K, J)
920   CONTINUE
910   CONTINUE

      DO 930 I=1, M
      PRIT(I) = 0.0
      DO 940 K=1, J
      .   PRIT(I) = PRIT(I) + (LAM(K-1) - LAM(K)) * PH(I, J-K)
940   CONTINUE
930   CONTINUE

      DO 950 I=1, M
      TMPH(I) = 0.0
      DO 960 K=1, M
      .   TMPH(I) = TMPH(I) + TM(I, K) * PH(K, J-1)
960   CONTINUE
950   CONTINUE

      DO 970 I=1, M
      PH(I, J) = (AVAL(I) + PRIT(I) + TMPH(I)) / LAM(0)
970   CONTINUE

*   CALCULATION OF RESIDUAL AND RELATIVE INCREMENT
      DO 980 I=1, M
      X(I) = TMPH(I) - LAM(J) * PH(I, J-1)
980   CONTINUE

      RESID = MAXNORM(X, M)

      DO 990 I=1, M
      X(I) = PH(I, J) - PH(I, J-1)
      Y(I) = PH(I, J)
990   CONTINUE

      RELIN = MAXNORM(X, M) / MAXNORM(Y, M)

      WRITE(2, 700) J, LAM(J), RESID, RELIN

```



```

*   STOPPING CRITERIA
      IF (RESID.LT.1.0E-12) THEN
        WRITE(2,1000)
1000      FORMAT(/,1H ,5X, "RESID.LT.1.0E-12")
      ENDIF
      IF (RELIN.LT.1.0E-12) THEN
        WRITE(2,1010)
1010      FORMAT(/,1H ,5X, "RELIN.LT.1.0E-12")
      ENDIF
      IF (RESID.LT.1.0E-12.AND.RELIN.LT.1.0E-12) THEN
        GO TO 1100
      ENDIF

710   CONTINUE

1100  CONTINUE
      STOP
      END

```

```

REAL FUNCTION KERNEL(S,T)
REAL S,T
KERNEL = EXP(S*T)
RETURN
END

```

```

REAL FUNCTION NODE(I,N)
INTEGER I,I1,I2,N
I1 = I/2
I2 = I-I1*2
IF (I2.NE.0) THEN
  NODE = (FLOAT(I)-1.0/SQRT(3.0))/N
ELSE
  NODE = (FLOAT(I)-1.0+1.0/SQRT(3.0))/N
ENDIF
RETURN
END

```

```

REAL FUNCTION WEIGHT(I,N)
INTEGER I,N
WEIGHT = 1.0/FLOAT(N)
RETURN
END

```

```

REAL FUNCTION MAXNORM(X,M)
INTEGER M
REAL X(M)
MAXNORM = 0.0
DO 1110 I=1,M
  IF (MAXNORM.LT.ABS(X(I))) THEN
    MAXNORM = ABS(X(I))
  ENDIF
1110 CONTINUE
RETURN
END

```

OUTPUT OF PROGRAM ITEIG

RAYLEIGH-SCHRODINGER SCHEME

FREDHOLM METHOD(2)

KERNEL:EXP(S*T)

NODES:GAUSS TWO POINTS

WEIGHTS:1/N

N=10 N1=10 M=100

PRECISION FOR STOPPING CRITERIA:1.0E-12

EIGENVALUES OF A

-.1133820135241E-14	.1047006402339E-14	.2699346339808E-12
.4796177191072E-10	.9238598296043E-08	.1050078986292E-05
.7441265877077E-04	.3552405730829E-02	.1059756286955E+00
.1353028494291E+01		

J	LAM(J)	RESID	RELIN
0	.1353028494291E+01		
1	.1352614455737E+01	.18E-01	.23E-01
2	.1353030065281E+01	.16E-03	.23E-03
3	.1353030261682E+01	.39E-05	.50E-05
4	.1353030164665E+01	.92E-07	.13E-06
5	.1353030164536E+01	.15E-08	.20E-08
6	.1353030164578E+01	.60E-10	.86E-10
7	.1353030164578E+01	.69E-12	.84E-12

RESID.LT.1.0E-12

RELIN.LT.1.0E-12

Computation of actual accuracy

As we have seen in Section 18, the computed eigenvalue iterates $\lambda_j = \text{LAM}(J)$ will converge, under suitable conditions, to the simple eigenvalue $\lambda^{(M)}$ of the matrix [TM] which is nearest to $\lambda_0 = \text{LAM}(0)$, and the computed eigenvector iterates ζ_j will converge to the corresponding eigenvector $\zeta^{(M)}$ of [TM] which satisfies

$$\langle [\text{TAH}]\zeta^{(M)}, V \rangle = \lambda^{(M)} .$$

We consider some additions to the program ITEIG which allow us to find the actual accuracy reached at each iterate by computing $\lambda^{(M)}$, $\zeta^{(M)}$, $\lambda^{(M)} - \lambda_j$ and the maximum norm of $\zeta^{(M)} - \zeta_j$, $j = 0, 1, \dots, L$. This is done only for illustrative purposes. The whole point of PROGRAM ITEIG is to avoid calculating $\lambda^{(M)}$ and $\zeta^{(M)}$.

* MAJOR DATA STRUCTURES *

- M1 - THE SERIAL NUMBER OF THE EIGENVALUE OF TM NEAREST TO LAM(0)
- DD - M VECTOR CONTAINING EIGENVALUES OF TM
- ZZ - M BY M MATRIX WHOSE I-TH COLUMN CONTAINS AN EIGENVECTOR OF
TM CORRESPONDING TO DD(I)
- TAHZZ - N VECTOR DENOTING THE PRODUCT OF TAH AND THE M1-TH COLUMN
OF ZZ AND HAS EUCLIDEAN NORM ONE
- SCP - THE SCALAR PRODUCT OF TAHZZ AND V
- PHI - THE EIGENVECTOR OF TM CORRESPONDING TO DD(M1) WHOSE INNER
PRODUCT WITH V EQUALS DD(M1)

We declare in the beginning of PROGRAM ITEIG

INTEGER M1

REAL DD(M), ZZ(M,M), WWK(M+M*(M+1)/2), TAHZZ(N), SCP, PHI(M)

and add the following lines at places indicated by the statement numbers; the WRITE statements and their formats 690 and 700 are also changed.

```

*   ADDENDUM TO PROGRAM ITEIG
*
*   EIGENELEMENTS OF TM FOR COMPARISON
      JOBN = 12
      IZ = M
      CALL EIGRS (TM,M,JOBN,DD,ZZ,IZ,WWK,IER)
*
*   EIGENVALUE OF TM NEAREST TO LAM(0)
      DO 615 I=M,1,-1
        IF (DD(I).LE.LAM(0)) THEN
          M1 = I
          IF ( M1.EQ.M) THEN
            GO TO 635
          ELSE
            GO TO 625
          ENDIF
        ENDIF
615   CONTINUE
      M1 = 1
625   IF (ABS(LAM(0)-DD(M1)).GT. ABS(LAM(0)-DD(M1+1))) THEN
          M1 = M1+1
        ENDIF
635   CONTINUE

      WRITE (2,645) M1,DD(M1)
645   FORMAT (/ ,1H ,5X, 'M1=',I3,5X, 'LAM =',E19.13,/,/)

      DO 655 I=1,N
        TAHZZ(I) = 0.0
        DO 665 J=1,M
          TAHZZ(I) = TAHZZ(I)+TAH(I,J)*ZZ(J,M1)
665   CONTINUE
655   CONTINUE

      SCP = 0.0
      DO 675 I=1,N
        SCP = SCP+TAHZZ(I)*V(I)
675   CONTINUE

      DO 685 I=1,M
        PHI(I) = ZZ(I,M1)/SCP*DD(M1)
        X(I) = PHI(I)-PH(I,0)
685   CONTINUE

      WRITE (2,690)
690   FORMAT (1H ,6X, 'J',9X, 'LAM(J)',8X, 'LAM-LAM(J)',1X,
1     'PH-PH(J)',3X, 'RESID',5X, 'RELIN')
      J = 0
      WRITE (2,700) J,LAM(J),DD(M1)-LAM(J),MAXNORM(X,M)
700   FORMAT (/ ,1H ,5X, I2,2X,E19.13,4E10.2)

      DO 995 I=1,M
        X(I) = PHI(I)-PH(I,J)
995   CONTINUE

      WRITE(2,700) J,LAM(J),DD(M1)-LAM(J),MAXNORM(X,M),
1     RESID,RELIN

```

OUTPUT OF PROGRAM ITEIG WITH THE ADDENDUM

RAYLEIGH-SCHRODINGER SCHEME

FREDHOLM METHOD(2)

KERNEL:EXP(S*T)

NODES:GAUSS TWO POINTS

WEIGHTS:1/N

N=10 N1=10 M=100

PRECISION FOR STOPPING CRITERIA:1.0**-12

EIGENVALUES OF A

-.1133820135241E-14	.1047006402339E-14	.2699346339808E-12
.4796177191072E-10	.9238598296043E-08	.1050078986292E-05
.7441265877077E-04	.3552405730829E-02	.1059756286955E+00
.1353028494291E+01		

M1=100 LAM = .1353030164578E+01

J	LAM(J)	LAM-LAM(J)	PH-PH(J)	RESID	RELIN
0	.1353028494291E+01	.17E-05	.13E-01		
1	.1352614455737E+01	.42E-03	.13E-03	.18E-01	.23E-01
2	.1353030065281E+01	.99E-07	.29E-05	.16E-03	.23E-03
3	.1353030261682E+01	-.97E-07	.73E-07	.39E-05	.50E-05
4	.1353030164665E+01	-.86E-10	.11E-08	.92E-07	.13E-06
5	.1353030164536E+01	.42E-10	.48E-10	.15E-08	.20E-08
6	.1353030164578E+01	.50E-13	.52E-12	.60E-10	.86E-10
7	.1353030164578E+01	-.28E-13	.75E-13	.69E-12	.84E-12

RESID.LT.1.0E-12

RELIN.LT.1.0E-12

Modifications of the program ITEIG

We discuss how PROGRAM ITEIG can be easily adapted to deal with a large number of different situations.

(i) Parameter values

By simply assigning different values to the parameters in the second line of the program, one can alter the maximum number L of the iterations, the size M of the grid which discretizes the integral operator T , the order N of the matrix A in the initial eigenvalue problem, and the serial number $N1$ of the selected eigenvalue of A with which we start the iteration process.

(ii) Various iteration schemes

Instead of the Rayleigh-Schrödinger scheme (11.18) used in PROGRAM ITEIG, we can use the fixed point scheme (11.19), the modified fixed point scheme (11.31), or the Ahués scheme (11.35). The algorithms 17.9, 17.10 and 17.11 indicate the required changes in the program ITEIG for implementing these schemes. There is no need for the vector PRIT in these schemes. Hence the DO loops 930 and 940 can be dropped altogether. In fact, there is no need for the double arrays ALPHA(N,0:L) and PH(M,0:L); instead, single arrays ALPHA(N), PH(M) and PRPH(M) (representing the current solution of the linear system, the current eigenvector iterate and the previous eigenvector iterate, respectively) will suffice.

Fixed point scheme: Change the DO loops 820 and 970 as follows:

```

DO 820 K = 0, J-1
      SUM(I) = SUM(I)+LAM(J)*ALPHA(I,K)
820 CONTINUE

```

and

```
DO 970 I = 1, M
```

```
PH(I,J) = (AVAL(I)+(LAM(O)-LAM(J))*PH(I,J-1)+TMPH(I))/LAM(O)
```

```
970 CONTINUE
```

Modified fixed point scheme: Declare

```
REAL T2AH(N,M),T2M(M,M),T2AHPH(N),MU(L),T2MPH(M)
```

Add the following comments and statements after the nested

DO loops 540 and 550 :

* GENERATION OF T2AH

```
DO 555 I = 1,N
```

```
DO 565 J = 1,M
```

```
T2AH(I,J) = 0.0
```

```
DO 575 K = 1,M
```

```
T2AH(I,J) = T2AH(I,J)+TAH(I,K)*TM(K,J)
```

```
575 CONTINUE
```

```
565 CONTINUE
```

```
555 CONTINUE
```

* GENERATION OF T2M

```
DO 585 I = 1,M
```

```
DO 595 J = 1,M
```

```
T2M(I,J) = 0.0
```

```
DO 605 K = 1,M
```

```
T2M(I,J) = T2M(I,J)+TM(I,K)*TM(K,J)
```

```
605 CONTINUE
```

```
595 CONTINUE
```

```
585 CONTINUE
```

Add the following lines after statement 740:

```

DO 745 I = 1,N
    T2AHPH(I) = 0.0
    DO 755 K = 1,M
        T2AHPH(I) = T2AHPH(I)+T2AH(I,K)*PH(K,J-1)
755    CONTINUE
745    CONTINUE

    MU(J) = 0.0
    DO 765 I = 1,N
        MU(J) = MU(J)+T2AHPH(I)*V(I)
765    CONTINUE

    DO 775 I = 1,M
        T2MPH(I) = 0.0

        DO 785 K =1,M
            T2MPH(I) = T2MPH(I)+T2M(I,K)*PH(K,J-1)
785    CONTINUE
775    CONTINUE

```

Delete the DO loops 810 and 820.

Change the DO loops 830 and 970 as follows:

```

DO 830 I = 1,N
    BETA(I+1) = (-T2AHPH(I)+MU(J)/LAM(J)*TAHPH(I))/LAM(J)
830    CONTINUE

```

and

```

DO 970 I = 1,M
    PH(I,J) = (LAM(J)*AVAL(I)+(LAM(O)-MU(J)/LAM(J))*TMPH(I)
1          + T2MPH(I))/(LAM(O)*LAM(J))
970    CONTINUE

```


Ahués scheme: Same additions and deletions as in the case of the modified fixed point scheme. Also, change the DO loops 830 and 970 as follows:

```

      DO 830 I = 1,N
          BETA(I+1) = (-T2AHPH(I)+LAM(J)*TAHPH(I)
1              +LAM(O)*(MU(J)-LAM(J)*LAM(J))*U(I))/LAM(J)
830     CONTINUE

```

and

```

      DO 970 I = 1,M
          PH(I,J) = (LAM(J)*AVAL(I)+(LAM(J)*LAM(J)-MU(J))*PH(I,O)
1              +(LAM(O)-LAM(J))*TMPH(I)
1              +T2MPH(I))/(LAM(O)*LAM(J))
970     CONTINUE

```

(iii) Various methods

By altering, if necessary, the matrices A, AV and TAH appearing in the nested DO loops 310-320, 410-430 and 520-530, respectively, one can employ any of the following methods: Projection, Sloan, Galerkin(1) and (2), Nyström, Fredholm(1). The required alterations can be quickly found from Table 19.1. For example, to employ the Nyström method we need only alter the matrix AV; for this purpose we replace the nested DO loops 410-430 by

```

      DO 410 I = 1,M
          DO 420 J = 1,N
              AV(I,J) = KV(I,J)
420     CONTINUE
410     CONTINUE

```

With these changes, the program will work provided the matrix A is real and symmetric. If it is not, further changes are necessary. They are outlined later.

(iv) Kernel, nodes and weights

By changing the definitions of KERNEL, NODE and WEIGHT in the function subprograms given at the end of PROGRAM ITEIG, we can vary the kernel of the integral operator T as well as the nodes and the weights used in the quadrature formula which discretizes T. With these changes, the program will work if the matrix A remains real and symmetric. Otherwise further changes are required, as detailed below.

(v) General complex matrix A

The matrix A appearing in the DO loops 310-320 is real and symmetric, and it remains so for the Fredholm and the Nyström methods as long as the kernel is real and symmetric and the weights are all real and equal. When A is not real and symmetric, make the following changes

1. COMPLEX (instead of REAL) declarations of appropriate arguments; use of the FORTRAN 77 intrinsic function CONJG which yields the conjugate of a complex number.

2. Instead of the routine EIGRS of the IMSL LIBRARY, Edition 9.2 (or its equivalent EVCSF of the IMSL MATH/LIBRARY, Edition 10.0), the following IMSL routines need to be called in appropriate cases.

A	Edition 9.2	Edition 10.0
Complex Hermitian	EIGCH	EVCHF
Real general	EIGRF	EVCRG
Complex general	EIGCC	EVCCG

A set of Library interface routines is available to link the routines in the old and the new editions. The routines in Edition 9.2 treat a complex matrix of order N as a real vector of length $2N^2$; an appropriate equivalence statement may be required when an array is of one type in the calling program but of another type in the subroutine.

For the routines in Edition 10.0, the eigenvalues appear in a complex N vector `EVAL` in increasing lexicographic order and the I -th column of a complex N by N matrix `EVEC` gives an eigenvector corresponding to `EVAL(I)`; each eigenvector `U` is normalized such that

$$\max\{|\operatorname{Re} U(1)| + |\operatorname{Im} U(1)|, \dots, |\operatorname{Re} U(N)| + |\operatorname{Im} U(N)|\} = 1 .$$

We then pick a simple nonzero eigenvalue `LAM(0)` of `A` and a corresponding eigenvector `U` according to our choice.

3. Let `ACT` denote the conjugate transpose of the matrix `A`. If `A` is normal (i.e., `ACT` commutes with `A`), then `U` itself is an eigenvector of `ACT` corresponding to `CONJG(LAM(0))`. Hence in this case we simply need to replace `LAM(0)` by `CONJG(LAM(0))` in the DO loop 360. If `A` is Hermitian, then `ACT = A` and `CONJG(LAM(0)) = LAM(0)`, and there is no change in the DO loop 360.

For a general (real or complex) matrix `A`, we generate `ACT` as follows:

```
* GENERATION OF ACT
      DO 360 I = 1,N
          DO 370 J = 1,N
              ACT(I,J) = CONJG(A(J,I))
          370 CONTINUE
      360 CONTINUE
```

We can then solve the eigenvalue problem for `ACT` just as we do for `A`. Let `CONJG(LAM(0))` be the N_2 -th entry of the vector `D` or `EVAL`, so that an eigenvector of `ACT` corresponding to `CONJG(LAM(0))` appears in the N_2 -th column of the matrix `Z` or `EVEC`. To obtain an eigenvector `V` of `ACT` whose inner product with `U` is $1/\operatorname{LAM}(0)$, we proceed as follows. The complex argument `SP` denotes 'scalar product'.

```

COMPLEX SP
  SP = 0.0
  DO 380 I = 1,N
    SP = SP+U(I)*CONJG(Z(I,N2))
380  CONTINUE
  DO 390 I = 1,N
    V(I) = Z(I,N2)/CONJG(SP*LAM(0))
390  CONTINUE

```

Alternatively, we can find V as the least squares solution of a linear system with its coefficient matrix $CBAR$ and right hand side $BETABAR$, defined as follows:

```

COMPLEX CBAR(N+1,N), BETABAR(N+1)
* GENERATION OF CBAR
  DO 360 J = 1,N
    CBAR(1,J) = CONJG(U(J))
360  CONTINUE
  DO 370 I = 2, N+1
    DO 380 J = 1,N
      CBAR(I,J) = ACT(I-1,J)
380  CONTINUE
370  CONTINUE
  DO 390 I = 1,N
    CBAR(I+1,I) = ACT(I,I)-CONJG(LAM(0))
390  CONTINUE
    BETABAR(1) = 1/CONJG(LAM(0))
  DO 400 I = 1,N
    BETABAR(I+1) = 0.0
400  CONTINUE

```

If ACT is a real matrix, the IMSL subroutine LLBQF of Edition 9.2 or LSBRR of Edition 10.0 can be used for the solution of the above least squares problem. The LINPACK routines SQRDC and SQRSL also give the solution of a least squares problem with a real coefficient matrix. Their complex analogues CQRDC and CQRSL are available.

Since V is, in general, a complex array, and since the inner product is conjugate linear in the second variable, we change V(I) to CONJG(V(I)) in the DO loop 740 of PROGRAM ITEIG which gives LAM(J) and in the DO loop 765 of its modification which gives MU(J).

4. If the functions KERNEL and WEIGHT are real-valued, LAM(0) is real and the entries of U and V are real, then the coefficient matrix C and the right hand side vector BETA are real. We can then continue to use the IMSL routine LLBQF or LSBRR for obtaining the least squares solution ALPHA in the DO loop 840. Otherwise, LINPACK routines CQRDC and CQRSL can be employed to handle the complex case.

Unless A is normal and U has Euclidean norm 1, the scaling factor ZETA for the first row of C may be inappropriate (Cf. (18.15) and (18.17)). Hence the DO loop 470 may be dropped and the DO loop 480 be changed as follows:

```

DO 480 J = 1,N
      C(1,J) = CONJG(V(J))
480  CONTINUE

```

We describe an alternative method for obtaining the solution SOL in the DO loop 840. It is based on our discussion of (18.18) and (18.20).

Instead of generating the matrix C in the DO loops 470 to 510, we generate an N by N matrix B as follows.

```

COMPLEX B(N,N)
* GENERATION OF B
  DO 470 I = 1,N
    DO 480 J = 1,N
      B(I,J) = A(I,J)-LAM(0)*LAM(0)*U(I)*CONJG(V(J))
480   CONTINUE
CONTINUE
DO 490 I = 1,N
  B(I,I) = B(I,I)-LAM(0)
490  CONTINUE

```

Then SOL can be obtained as the solution of the linear system with coefficient matrix B and right hand side $BETA(I+1), I=1, \dots, N$. The following IMSL routines can be used to compute this solution.

B	Edition 9.2	Edition 10.0
Real symmetric	LEQ2S	LSASF
Complex Hermitian	-	LSAHF
Real general	LEQT2F	LSARG
Complex general	LEQ2C	LSACG