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ITERATIVE STABILITY IN THE CLASS OF CONTINUOUS FUNCTIONS

Abstract

Let \mathcal{K} be the class of compact subsets of $I = [0, 1]$, and \mathcal{K}^* consist of the nonempty closed subsets of \mathcal{K} . We study the maps $\Lambda : C(I, I) \rightarrow \mathcal{K}$ and $\Omega : C(I, I) \rightarrow \mathcal{K}^*$ defined so that $\Lambda(f)$ is the set of ω -limit points of f , and $\Omega(f)$ is the collection of ω -limit sets of f . We find that, in general, neither map is continuous. We do get more positive results, however, if we restrict ourselves to certain types of ω -limit sets and better behaved classes of functions. We find that when f has only a finite number of ω -limit sets, each demonstrating a certain type of stability, the function Ω is continuous at f . The map $\Omega | \mathcal{E}$ is also studied, where \mathcal{E} is composed of those continuous functions with zero topological entropy, and a significant degree of stability of $\Omega | \mathcal{E}$ is established.

1 Introduction

The iterative behavior of continuous self-maps of a compact interval has received considerable attention in recent years. We will concern ourselves with some related questions concerning stability within the family of continuous self-maps of the interval $I = [0, 1]$. We begin with a rather general query. If f and g , both continuous self-maps of I , are close to one another, are their iterative characteristics in some way similar?

If by similar we mean that the functions are topologically conjugate to one another, then we can never achieve a positive result in the space $\{C(I, I), \|\cdot\|\}$, where we endow the set of continuous functions mapping I to I with the supremum metric. Since any f in $C(I, I)$ must have a fixed point, for any $\epsilon > 0$ we can find g in $C(I, I)$ so that $\|f - g\| < \epsilon$, yet g has considerably different dynamics than f on a neighborhood of the fixed point of f . In fact, we can take g to equal f outside of our neighborhood of the fixed point, and define g however we choose on that neighborhood so long as g is continuous.

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Near any fixed point of f , then, arbitrarily small perturbations can change the local dynamics considerably. It is still possible, however, that if f is perturbed only slightly to obtain g , then g will have ω -limit sets that are at least close to those of f . For example, if we let $f \equiv 0$ and take g so that $\|g - f\| < \epsilon$, then all the ω -limit sets of g are contained in $[0, \epsilon]$, and hence in some sense close to f 's unique ω -limit set $\{0\}$. We will pursue this idea at some length by making use of the Hausdorff metric \mathcal{H} on the class of closed sets \mathcal{K} contained in $[0,1]$. In our above example, the ω -limit sets of g and f would be ϵ -close to one another since every point in one is within ϵ of a point in the other.

We proceed through several sections.

In section 2 we present the notation and definitions we will use throughout the balance of the paper. We also recall some important, previously known results.

In section 3 we develop examples which show that the best possible result is not valid; in general, the ω -limit points of f and g need not be close to one another regardless of how close f and g are to each other. Nevertheless, these examples help us narrow our focus to the more positive results found in the ensuing sections.

In section 4 we focus our attention on convergent sequences $\{f_n\}$ in $C(I, I)$ that possess convergent ω -limit sets ω_n , and find that for functions of zero topological entropy, we are able to assert quite a bit about the relationship between $f = \lim_{n \rightarrow \infty} f_n$ and $\omega = \lim_{n \rightarrow \infty} \omega_n$. In this setting, the maximal perfect subset of ω is always an ω -limit set of f .

In section 5 we show that if f has only a finite number of ω -limit sets, and g is sufficiently close to f , then the ω -limit sets of g are close to those of f , provided that f 's ω -limit sets themselves meet a certain stability criterion.

In section 6 we conclude with some open problems and a few observations.

2 Preliminaries

We shall be concerned with the class $C(I, I)$ of continuous functions mapping the unit interval $I = [0,1]$ to itself, and the iterative properties this class of functions possesses. For f in $C(I, I)$ and any integer $n \geq 1$, f^n denotes the n^{th} iterate of f . For x in I , we call the set of all subsequential limits of the sequence $\{f^n(x)\}_{n=0}^{\infty}$ the ω -limit set of f generated by x , and write $\omega(x, f)$. We let $\Lambda(f) = \cup_{x \in I} \omega(x, f)$ represent the ω -limit points of f , while $\Omega(f) = \{\omega(x, f) : x \in I\}$ denotes the set composed of the ω -limit sets of f . To a very large extent, our study is one of the stability of $\Lambda(f)$ and $\Omega(f)$ as f undergoes perturbations.

We will be working primarily in four metric spaces. We will use the regular,

Euclidean metric d on $I = [0,1]$, and make occasional use of neighborhoods of closed sets F of the form $B_\epsilon(F) = \{x \in I : d(x, y) < \epsilon, y \in F\}$. Within $C(I, I)$ we will use the supremum metric given by $\|f - g\| = \sup\{|f(x) - g(x)| : x \in I\}$. Our third metric space $\{\mathcal{K}, \mathcal{H}\}$ is composed of the class of nonempty closed sets \mathcal{K} in I endowed with the Hausdorff metric \mathcal{H} given by $\mathcal{H}(E, F) = \inf\{\delta > 0 : E \subset B_\delta(F), F \subset B_\delta(E)\}$. This space is compact [4]. Our final metric space $\{\mathcal{K}^*, \mathcal{H}^*\}$ consists of nonempty closed subsets of \mathcal{K} . Thus, $K \in \mathcal{K}^*$ if K is a nonempty family of nonempty closed sets in I such that K is closed in \mathcal{K} with respect to \mathcal{H} . We endow \mathcal{K}^* with the metric \mathcal{H}^* , so that K_1 and K_2 are close with respect to \mathcal{H}^* if each member of K_1 is close to some member of K_2 with respect to \mathcal{H} , and vice versa.

Our interest in, and the utility of, the metric spaces $\{\mathcal{K}, \mathcal{H}\}$ and $\{\mathcal{K}^*, \mathcal{H}^*\}$ stems from the following two theorems from [1] and [2], respectively.

Theorem 2.1. *For any f in $C(I, I)$, the set $\Lambda(f)$ is closed in I .*

Theorem 2.2. *For any f in $C(I, I)$, the set $\Omega(f)$ is closed in $\{\mathcal{K}, \mathcal{H}\}$.*

To a large extent, then, our stability queries can be formulated via the maps $\Lambda : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}, \mathcal{H}\}$ given by $f \rightarrow \Lambda(f)$ and $\Omega : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}^*, \mathcal{H}^*\}$ given by $f \rightarrow \Omega(f)$.

In much of section 4 we will restrict our attention to a closed subset of $C(I, I)$ composed of those functions f having zero topological entropy, denoted by $\mathbf{h}(f) = 0$. The reader is referred to Theorem A of [9] for an extensive listing of equivalent formulations of topological entropy zero. For our purposes, it suffices to note that every periodic orbit of a continuous function with zero topological entropy has cardinality a power of two. The following theorem, due to Smítal[10], sheds considerable light on the structure of infinite ω -limit sets for functions with zero topological entropy.

Theorem 2.3. *If ω is an infinite ω -limit set for f in $C(I, I)$ possessing zero topological entropy, then there exists a sequence of closed intervals $\{J_k\}_{k=1}^\infty$ in $[0,1]$ such that*

- for each k , $\{f^i(J_k)\}_{i=1}^{2^k}$ are pairwise disjoint and $J_k = f^{2^k}(J_k)$.
- for each k , $J_{k+1} \cup f^{2^k}(J_{k+1}) \subseteq J_k$.
- for each k , $\omega \subseteq \bigcup_{i=1}^{2^k} f^i(J_k)$.
- for each k and i , $\omega \cap f^i(J_k) \neq \emptyset$.

We make the following definitions with Smital's Theorem in mind. Let ω be an infinite compact subset of I , and let f map ω into itself. We call f a simple map on ω if ω has a decomposition $S \cup T$ into compact portions that f exchanges, and f^2 is simple on each of these portions. From Smital's Theorem one sees that every map f with zero topological entropy is simple on each of its infinite ω -limit sets $\omega = \omega(x, f)$. Let $\{J_k\}_{k=1}^\infty$ be a nested sequence of compact periodic intervals of ω and f as described in Smital's Theorem. Every set of the form $\omega \cap f^i(J_n)$ is periodic of period 2^n , and we call each such set a periodic portion of rank n . This system of periodic portions of ω , or of the corresponding periodic intervals, is called the simple system of ω with respect to f .

We will need the following notation in section 5 when we study the function $\Omega : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}^*, \mathcal{H}^*\}$ at all points f for which $\Omega(f)$ is finite. Suppose $\omega \in \Omega(f)$, and $\omega = \omega(x, f)$ contains only finitely many points, say $|\omega| = n$. We say that ω is a stable ω -limit set of f if $f^n(x) - x$ is not unsigned in any deleted neighborhood of x .

3 Examples

This section will be dedicated primarily to the development of examples. These examples will provide us with some insight into the behavior of our functions Λ and Ω as well as focus our efforts in the ensuing sections.

Example 1. Consider $f_n(x) = x^{\frac{n-1}{n}}$. As n goes to infinity, we see that f_n goes to the identity function f . Thus, $\Lambda(f) = [0, 1]$. Since $\Lambda(f_n) = \{0, 1\}$ for all n , we see that Λ is not continuous at f , so that Ω must necessarily be discontinuous there, too. While this does rule out the best possible result - that Ω , and therefore Λ , are continuous - our example does not rule out a natural generalization of the theorem found in [2].

Recall that our four authors in [2] show that if $\{\omega_n\} \subseteq \Omega(f)$, and $\omega_n \rightarrow \omega$ in K , then $\omega \in \Omega(f)$. In example 1, $\{0\} \in \Omega(f_n)$ for every n , and $\{0\} \in \Omega(f)$. Perhaps, then, the following is true: If $\omega_n \in \Omega(f_n)$ for each n , $f_n \rightarrow f$ and $\omega_n \rightarrow \omega$, then $\omega \in \Omega(f)$. This conjecture simplifies to the result of [2] if we let $f_n = f$ for all n .

For our next example, we need the following definition. Let M be a nowhere dense compact set in I , with $A = \{a_0, a_1, \dots, a_{k-1}\} \neq \emptyset$ a set of limit points of M . Suppose there is a system $\{M_n^i\}_{n=0}^\infty, i = 0, 1, \dots, k-1$ of nonempty pairwise disjoint compact subsets of M such that $M \setminus \cup_{i,n} M_n^i = A$ and $\lim_{n \rightarrow \infty} M_n^i = a_i$ for each i . Let $f : M \rightarrow M$ be a continuous map with A a k -cycle of f such that $f(a_i) = a_{i-1}$ for $i > 0$ and $f(a_0) = a_{k-1}$. If $f(M_n^i) = M_n^{i-1}$ for $i > 0$ and any n , $f(M_n^0) = M_{n-1}^{k-1}$ for $n > 0$, and $f(M_0^0) = a_{k-1}$, then M is called a

homoclinic set of order k with respect to f .

Example 2. We will construct a sequence of homoclinic ω -limit sets ω_n for functions f_n in $C(I, I)$ so that $\omega_n \rightarrow \omega$, $f_n \rightarrow f$, yet ω is not contained in $\Lambda(f)$. This negates our conjectured generalization of the result from [2].

We begin by constructing our ω -limit sets ω_n . For each portion M_n^i , we take a scaled copy of the middle thirds Cantor set with the indicated convex closure.

For ω_1 , let $a_0 = \frac{1}{2}$ and $\overline{\text{conv}}M_n^0 = [\frac{1}{2} + \frac{1}{2^{2+n}}, \frac{1}{2} + \frac{1}{2^{2+n}} + \frac{1}{2^{3+n}}]$. Set $A_0 = a_0 \cup \{\cup_{n=0}^\infty M_n^0\}$. Now, let $a_1 = 0$ and $\overline{\text{conv}}M_n^1 = [\frac{1}{2^{2+n}}, \frac{1}{2^{2+n}} + \frac{1}{2^{3+n}}]$.

For ω_2 , we begin with the set A_0 described above, and take $a_1 = \frac{1}{4}$ and $\overline{\text{conv}}M_n^1 = [\frac{1}{4} + \frac{1}{2^{3+n}}, \frac{1}{4} + \frac{1}{2^{3+n}} + \frac{1}{2^{4+n}}]$; let $A_1 = a_1 \cup \{\cup_{n=0}^\infty M_n^1\}$. Now, let $a_2 = 0$ and $\overline{\text{conv}}M_n^2 = [\frac{1}{2^{3+n}}, \frac{1}{2^{3+n}} + \frac{1}{2^{4+n}}]$.

In general, for ω_m , we begin with the sets A_0, A_1, \dots, A_{m-2} and take $a_{m-1} = \frac{1}{2^m}$ and $\overline{\text{conv}}M_n^{m-1} = [\frac{1}{2^{m+1}} + \frac{1}{2^{m+2+n}}, \frac{1}{2^{m+1}} + \frac{1}{2^{m+2+n}} + \frac{1}{2^{m+3+n}}]$; let $A_{m-1} = a_{m-1} \cup \{\cup_{n=0}^\infty M_n^{m-1}\}$. Now, let $a_m = 0$ and $\overline{\text{conv}}M_n^m = [\frac{1}{2^{m+2+n}}, \frac{1}{2^{m+2+n}} + \frac{1}{2^{m+3+n}}]$.

We see that each of our sets ω_n will be homoclinic of order $n + 1$, and the sequence $\{\omega_n\}$ converges in \mathcal{K} to the set $\omega = \{0\} \cup \{\cup_{n=0}^\infty A_n\}$. How our functions $f_n : \omega_n \rightarrow \omega_n$ are defined is clear from our definition of a homoclinic trajectory as well as the construction of the sets ω_n . Moreover, since each resulting f_n is continuous, we can use [6] to extend $f_n : \omega_n \rightarrow \omega_n$ to a function we will also call f_n that is in $C(I, I)$ and has the property that $\omega_n = \omega(x, f_n)$ for some $x \in I$. Since we can take $f_n | A_1 \cup \dots \cup A_m = f_k | A_1 \cup \dots \cup A_m$ for all n and k greater than $m + 2$, and $A_n \rightarrow 0$ as $n \rightarrow \infty$, we can take our f_n so that $f = \lim_{n \rightarrow \infty} f_n$ exists, and $f(x) = 0$ for $x \in [\frac{1}{2}, 1]$. Thus, $\Lambda(f) \cap [\frac{1}{2}, 1] = \emptyset$ as $f(0) = \lim_{n \rightarrow \infty} f_n(0) = \lim_{n \rightarrow \infty} \frac{1}{2^n}$.

It is worth pointing out that not only is ω not an ω -limit set of f , but we lose a considerable portion of our ω -limit points as well. For each $n, A_0 \subseteq \omega_n \subseteq \Lambda(f_n)$ with $A_0 \subseteq [\frac{1}{2}, 1]$, yet $\Lambda(f) \cap [\frac{1}{2}, 1] = \emptyset$.

Example 3[3]. Let $f(x) = x$ on I , and for $\epsilon > 0$, choose $\frac{1}{n} < \epsilon$. An appropriate polygonal function f_n that possesses the orbit $0 \rightarrow \frac{1}{n} \rightarrow \frac{2}{n} \rightarrow \dots \rightarrow \frac{n-1}{n} \rightarrow 1 \rightarrow \frac{n-\frac{1}{2}}{n} \rightarrow \frac{n-\frac{3}{2}}{n} \rightarrow \dots \rightarrow \frac{1}{2} \rightarrow 0$ has a periodic orbit that spans I , and the property that $\|f - f_n\| \leq \frac{1}{n}$. Since $\Omega(f) = \{\{x\} : x \in I\}$, it follows that $\mathcal{H}^*(\Omega(f_n), \Omega(f)) = \frac{1}{2}$ for all n . By choosing a subsequence if necessary, one may assume that $\lim_{n \rightarrow \infty} \Omega(f_n)$ exists, since $\{\mathcal{K}^*, \mathcal{H}^*\}$ is compact. Then $\lim_{n \rightarrow \infty} f_n = f$, and $\mathcal{H}^*(\lim_{n \rightarrow \infty} \Omega(f_n), \Omega(f)) = \frac{1}{2}$. Thus, Ω is discontinuous at the identity function, a function with zero topological entropy. Unlike Example 2, however, in this example we did not lose any ω -limit points in going from $\Lambda(f_n)$ to $\Lambda(f)$, as $\Lambda(f) = [0, 1]$, but we did lose all of our non-trivial ω -limit sets in the limit.

We should note that both in Example 2 and Example 3, we can take the sequence $\{f_n\}$ to be equicontinuous as well as bounded, so that $\{f_n\}$ has a compact closure in $C(I, I)$. We conclude, then, that $f_n \rightarrow f, \omega_n \in \Omega(f_n)$ and $\omega_n \rightarrow \omega$ do not imply that ω is in $\Omega(f)$ even for compact sequences $\{f_n\}$.

We begin our next section with a closer examination of the relationship between the limit set ω and the limit function f . We will then revisit the continuity structure of Ω with our attention restricted to functions of zero topological entropy.

4 Finite ω -limit sets and zero topological entropy

Suppose $f_n \rightarrow f$ in $C(I, I), \omega_n \rightarrow \omega$ in \mathcal{K} and ω_n is an ω -limit set of f_n for each n . From our previous section's examples we know that ω need not be an ω -limit set of f , although in some cases it might be. The main result of this section shows us that if we have the additional hypothesis that ω is finite, then ω will always be an ω -limit set of f . Also, if we restrict ourselves to the closed class of functions $\mathcal{E} = \{f \in C(I, I) : \mathbf{h}(f) = 0\}$, and ω is infinite, then the necessarily unique maximal perfect subset of ω is an ω -limit set of f . We begin with a couple of lemmas. These show that, regardless of the cardinality of ω or the topological entropy of the members of $\{f_n\}, \omega$ always possesses certain properties reminiscent of an ω -limit set.

Lemma 4.1. *Suppose $f_n \rightarrow f, \omega_n \rightarrow \omega$ and $\omega_n \in \Omega(f_n)$ for each n . Then $f(\omega) = \omega$.*

PROOF. $f(\omega) \subseteq \omega$: Let $y \in \omega$, and take $\{y_n\}$ so that $y_n \in \omega_n$ for each n , and $y_n \rightarrow y$. Then $f_n(y_n) \rightarrow f(y)$, and since $f_n(y_n) \in \omega_n$, it follows that $f(y) \in \omega$.

$\omega \subseteq f(\omega)$: Let $y \in \omega$, and take $\{y_n\}$ so that $y_n \in \omega_n$ for each n , and $y_n \rightarrow y$. Suppose $x_n \in f_n^{-1}(y_n) \cap \omega_n$, with $\{x_{n_k}\} \subseteq \{x_n\}$ a convergent subsequence; say $x_{n_k} \rightarrow x$. Then $x \in \omega$, and $f(x) = y$, as $|f(x) - y| \leq |f(x) - f(x_{n_k})| + |f(x_{n_k}) - f_{n_k}(x_{n_k})| + |f_{n_k}(x_{n_k}) - y|$. \square

Our next lemma shows that not only is ω strongly invariant with respect to f , but also that f transports portions of ω outside of themselves in a way similar to what ω -limit sets experience.

Lemma 4.2. *Suppose $f_n \rightarrow f, \omega_n \rightarrow \omega$ and $\omega_n \in \Omega(f_n)$ for each n . If F is any nonempty proper closed subset of ω , then $F \cap \overline{f(\omega \setminus F)} \neq \emptyset$.*

PROOF. Suppose, to the contrary, that F and $\overline{f(\omega \setminus F)}$ are disjoint. Then there exist open sets G_1, G_2 such that $\omega \setminus F \subseteq G_1, F \subseteq G_2$ and $\overline{G_2}$ is disjoint from $\overline{f(G_1)}$. Say $\sigma = \min\{|x - y| : x \in \overline{G_2}, y \in \overline{f(G_1)}\}$. Since $\omega_n \rightarrow \omega$, there exists M a natural number such that $\omega_n \subseteq G_1 \cup G_2$ and $\omega_n \cap G_1 \neq \emptyset, \omega_n \cap G_2 \neq \emptyset$

for all $n \geq M$. Also, since $f_n \rightarrow f$, there is a natural number N so that $|f_m(x) - f(x)| < \frac{\sigma}{2}$ for all $m \geq N$ and $x \in I$. Let us take n , then, so that $n > \max\{M, N\}$, and set $F_n = \omega_n \cap \overline{G_2}$. Then F_n is a closed, nonempty, proper subset of ω_n , and $\overline{G_2}$ is disjoint from $\overline{f_n(G_1)}$. Let $x_n \in I$ so that $\omega_n = \omega(x_n, f_n)$. For all large k , $f_n^k(x_n)$ belongs to either G_1 or G_2 , and it belongs to each of them infinitely often. Thus there is an infinite sequence $k_1 < k_2 < k_3 < \dots$ so that $f_n^{k_i}(x_n) \in G_1$, and $f_n^{k_i+1}(x_n) \in G_2$. If y is a limit point of the sequence $f_n^{k_i}(x_n)$, then $y \in \overline{G_1}$, and $f(y) \in \overline{G_2}$, which is a contradiction. \square

We are now in a position to show that ω is an ω -limit set of f whenever ω is finite.

Theorem 4.1. *Suppose $f_n \rightarrow f, \omega_n \rightarrow \omega$ and $\omega_n \in \Omega(f_n)$ for each n . If ω is a finite set, then $\omega \in \Omega(f)$.*

PROOF. Say $\omega = \{z_1, z_2, \dots, z_k\}$. Since $f(\omega) = \omega$, it suffices to show that $f^j(z_i) \neq z_i$ whenever $1 \leq j < k$ for all $i = 1, 2, \dots, k$. Suppose, to the contrary, that there exists $i \in \{1, 2, \dots, k\}$ and $1 \leq j < k$ for which $f^j(z_i) = z_i$. Let us assume that $f^l(z_i) \neq z_i$ for all $l < j$. Set $\sigma = \min\{|z_m - z_p| : m \neq p\}$. Since $f_n \rightarrow f$, there exists $N_1 \in \mathbb{N}$ so that $n \geq N_1$ implies $\|f_n - f\| < \frac{\sigma}{8}$. Let $N_2 \in \mathbb{N}$ so that $N_2 > N_1$, and $n \geq N_2$ implies $\mathcal{H}(\omega, \omega_n) < \delta < \frac{\sigma}{8}$, where δ is chosen so that $|a - b| < \delta$ insures that $|f(a) - f(b)| < \frac{\sigma}{8}$. If $n > N_2$, and we take $x \in \omega_n$ so that $|x - z_l| < \delta$, then $|f_n(x) - f(z_l)| \leq |f_n(x) - f(x)| + |f(x) - f(z_l)| \leq \frac{\sigma}{8} + \frac{\sigma}{8} = \frac{\sigma}{4}$. It now follows that if $\omega_n^* = \omega_n \cap B_\delta(\cup_{l=0}^j f^l(z_i))$, then $f_n(\omega_n^*) \subseteq \omega_n^*$. If we let $F = \omega_n \setminus \omega_n^*$, then $F \cap f_n(\omega_n \setminus F) = \emptyset$. But this contradicts our hypothesis that ω_n is an ω -limit set for f_n . \square

In our previous result we were able to show that ω is an ω -limit set of f provided we place a restriction on the structure of ω . We are able to get a similar result by placing a restriction on the sequence $\{f_n\}$ rather than on the limit set ω . We restrict our attention to $\mathcal{E} = \{f \in C(I, I) : \mathbf{h}(f) = 0\}$, and after showing that \mathcal{E} is closed in $\{C(I, I), \|\cdot\|\}$, we go on to prove the following theorem.

Theorem 4.2. *Suppose $\{f_n\} \subseteq \mathcal{E}, f_n \rightarrow f, \omega_n \rightarrow \omega$ and $\omega_n \in \Omega(f_n)$ for each n . If ω is infinite and C is the set of isolated points of ω , then $\omega \setminus C \in \Omega(f)$.*

We begin our proof of this theorem with a verification that our set \mathcal{E} is indeed closed.

Lemma 4.3. *The set $\mathcal{E} = \{f \in C(I, I) : \mathbf{h}(f) = 0\}$ is closed in $\{C(I, I), \|\cdot\|\}$.*

PROOF. From [1], we know that the function $\mathbf{h} : C(I, I) \rightarrow \mathbf{R}^+ \cup \{+\infty\}$, given by $f \rightarrow \mathbf{h}(f)$, where $\mathbf{h}(f)$ is the topological entropy of f , is lower semicontinuous. Thus, if $\mathbf{h}(f) > \alpha > 0$, then $\mathbf{h}(g) > \alpha$ for all g sufficiently close to f .

In particular, then, the set $G = \{f \in C(I, I) : \mathbf{h}(f) > 0\}$ is open, and our conclusion follows. \square

Our next lemma, though rather technical, plays an important part in the proof of Theorem 4.2.

Lemma 4.4. *Suppose $\{f_n\} \subseteq \mathcal{E}$, $f_n \rightarrow f$, $\omega_n \rightarrow \omega$ and $\omega_n \in \Omega(f_n)$ for every n . If ω is infinite and $x \in \omega$, then x is not a periodic point of f .*

PROOF. Since $\mathbf{h}(f) = 0$, if x is periodic, the period of x is 2^m for some m in $\mathbb{N} \cup \{0\}$. Thus, x is a fixed point of the function $g = f^{2^m}$, and since $f_n \rightarrow f$, it follows that $g_n = f_n^{2^m} \rightarrow g$. Suppose $x_n \rightarrow x$ and x_n is periodic of period 2^n . Let $n \geq m$. Then x_n is periodic of period 2^{n-m} for g_n , and $x \in \tilde{\omega}$, the limit of any convergent subsequence $\{\omega(x_{n_k}, g_{n_k})\} \subseteq \{\omega(x_n, g_n)\}$. It suffices, then, to show that x is not a fixed point of f , for if x has a period of 2^m , $m > 0$, we replace the sequence $\{f_n\}$ with $\{g_n\} = \{f_n^{2^m}\}$, and the sequence $\{\omega_n\}$ with a convergent subsequence of $\{\omega(x_n, g_n)\}$. We proceed in two cases.

Case 1: Suppose ω_n is finite for each n . By renumbering and taking a subsequence if necessary, we may assume that $|\omega_n| = 2^n$ for each n . We prove our first case by again considering two possibilities.

First, let us suppose that $x = \min \omega$ or $x = \max \omega$ is a fixed point. We will prove our assertion in the case that $x = \min \omega$. Let $x_n = \min \omega_n$, and since $\omega_n \rightarrow \omega$, it follows that $x_n \rightarrow x$. Since $\{f_n\} \cup f$ is a closed and bounded set in $C(I, I)$, we know that it is equicontinuous. Let $\epsilon > 0$, and take $\epsilon > \delta > 0$ so that $|a - b| < \delta$ implies $|g(a) - g(b)| < \epsilon$ for any $g \in \{f_n\} \cup f$. Let $N \in \mathbb{N}$ so that $n > N$ implies $|x_n - x| < \delta$, and $|f_n(x_n) - x_n| < \delta$, too. Since $x_n = \min \omega_n$, $f_n(x_n) \geq x_n$, and since $f^{-1}(\max \omega_n) \leq f_n(x_n)$, it follows that $\overline{\text{conv}} \omega_n \subset B_{2\epsilon}(x)$. Thus, $|\overline{\text{conv}} \omega_n| \rightarrow 0$ as $n \rightarrow \infty$. This implies $x = \omega$, a contradiction.

Now, let us suppose that $x \in (\min \omega, \max \omega)$, and again we will take $\epsilon > \delta > 0$ so that $|a - b| < \delta$ implies $|g(a) - g(b)| < \epsilon$ for each $g \in \{f_n\} \cup f$. Suppose that $x_n \in \omega_n$ and $x_n \rightarrow x$. Choose $N \in \mathbb{N}$ so that $n > N$ implies $|x - x_n| < \frac{\delta}{2}$, and $|f_n^i(x_n) - x_n| < \frac{\delta}{2}$ for $i = 0, 1, 2, 3$. Set $a = \min\{f_n^i(x_n)\}_{i=0}^3$ and $b = \max\{f_n^i(x_n)\}_{i=0}^3$. Then $[a, b]$ contains at least one of $f_n^{-1}(\max \omega_n), f_n^{-1}(\min \omega_n)$ so that either $|\max \omega_n - x| < 2\epsilon$ or $|\min \omega_n - x| < 2\epsilon$. Thus we have either that $|\max \omega_n - x| \rightarrow 0$ or $|\min \omega_n - x| \rightarrow 0$ as $n \rightarrow \infty$. In either case we have a contradiction to our supposition that $x \in (\min \omega_n, \max \omega_n)$.

Case 2: Suppose ω_n is uncountable for all $n > N$, for some $N \in \mathbb{N}$.

Let $J_i^k, i = 1, 2$, be the rank 1 periodic portions of ω_k with respect to f_k . Since $\omega_k \rightarrow \omega$ and $f_k \rightarrow f$, it follows that $\{J_1^k\}$ and $\{J_2^k\}$ each converges to a portion J_1 and J_2 , respectively, of ω that f exchanges. Since $\omega = J_1 \cup J_2$,

if $x \in J_1$, then $f(x) \in J_2$, so $f(x) = x$ implies $J_1 \cap J_2 \neq \emptyset$. By considering the four rank 2 periodic portions of ω , however, one sees that $J_1 \cap J_2 \neq \emptyset$ is impossible. □

Using the notation of Theorem 4.2, Theorem 5.1[7] tells us that it suffices to show that $\omega \setminus C$ is a subset of the limit points of f , and $\omega \setminus C$ is both simple and strongly invariant with respect to f in order to prove our result.

Lemma 4.5. *Suppose $\{f_n\} \subseteq \mathcal{E}$, $f_n \rightarrow f, \omega_n \rightarrow \omega$ and $\omega_n \in \Omega(f_n)$ for every n . If ω is infinite and C is the set of isolated points of ω , then*

- $\omega \setminus C$ is a simple set with respect to f ,
- $\omega \setminus C \subseteq \Lambda(f)$, and
- $f(\omega \setminus C) = \omega \setminus C$.

PROOF. We prove our result in several steps.

1. We first show that ω is a simple set with respect to f . Suppose ω_m is a periodic orbit of f_m of order 2^m , or that ω_m is uncountable. In either case, if $m > 2$, there exist two disjoint compact portions J_1^m, J_2^m of ω_m that f_m interchanges. Since $\omega_m \rightarrow \omega$ and $f_m \rightarrow f$, it follows that $J_1^m \rightarrow J_1, J_2^m \rightarrow J_2$, and J_1 and J_2 are interchanged by f . Moreover, since $J_1^m \cup J_2^m \supseteq \omega_m$, one sees that $J_1 \cup J_2 \supseteq \omega$, and they are disjoint since no element of ω can be periodic. In a similar fashion one can show that, since J_1^m and J_2^m both have a disjoint decomposition into two compact subportions that f_m^2 interchanges, the same is true of J_1, J_2 and f .

2. We now show that $\omega \setminus C$ is contained in $\Lambda(f)$. Let $x \in \omega \setminus C$. Since ω is a simple set, there exists a nested sequence of compact periodic portions $\{J_k\}_{k=1}^\infty$ such that the period of J_k is 2^k for each k , and x is contained in each. Let $J = \bigcap_{k=1}^\infty J_k$. We begin by showing that x is not contained in $\text{int}(\overline{\text{conv}}(J))$, the interior of the convex closure of J . Suppose, to the contrary, that there exists $\delta > 0$ such that $B_\delta(x) \cap \text{int}(\overline{\text{conv}}(J)) = B_\delta(x)$. Then for sufficiently large $k, B_\delta(x)$ is contained in the interior of a component of the simple system for ω_k . From Proposition 3.1[5], it follows that $B_\delta(x) \cap \omega_k = \emptyset$, which contradicts x being an element of $\omega = \lim_{k \rightarrow \infty} \omega_k$. We continue our proof by considering two cases.

First, suppose $x = J$. Since each J_k is periodic with period $2^k, \overline{\text{conv}}J_k$ contains a point of period 2^k . Since $J_k \rightarrow x$, and $\Lambda(f)$ is closed, our conclusion follows.

Now, suppose $x = \min J$ or $x = \max J$. Let us assume that $x = \max J$. Then there exists $\{y_n\} \subseteq \omega$ such that $x < y_n$ for all n , and $y_n \rightarrow x$. Since there is a periodic point between any two of the compact periodic portions of rank k for each k , our conclusion follows.

3. We show that $\omega \setminus C$ is strongly invariant with respect to f . This, in conjunction with our first step, also establishes that $\omega \setminus C$ is a simple set with respect to f . Let $x \in \omega \setminus C$ with $\{y_n\} \subseteq \omega \setminus C$ such that $y_n \rightarrow x$. Since f is continuous and x is not an element of $\text{int}(\overline{\text{conv}}(J))$, we have that $f(y_n) \rightarrow f(x)$. Thus, $f(x)$ is not an isolated point of ω , so that $f(x) \in \omega \setminus C$, and more generally, $f(\omega \setminus C) \subseteq \omega \setminus C$. Now, let $y \in \omega \setminus C$, and suppose $\{y_n\}$ is a subset of $\omega \setminus C$ such that $y_n \rightarrow y$. Take $x_n \in \{f^{-1}(y_n)\} \cap \omega$, and let $\{x_{n_k}\}$ be a convergent subsequence of $\{x_n\}$; say $x_{n_k} \rightarrow x$. Then $x \in \omega$ since ω is closed, and as x is not isolated, x is not contained in C . Since f is continuous, $x_{n_k} \rightarrow x$ and $f(x_{n_k}) \rightarrow y$ imply that $f(x) = y$, and it follows that $f(\omega \setminus C) \supseteq \omega \setminus C$. \square

We would like to be able to extend the conclusion of Theorem 4.2 to the entire set ω , thereby establishing the semicontinuity of the map $\Omega | \mathcal{E}$. Using a construction found in [5], however, we are able to develop a sequence of functions $\{f_n\} \subseteq C(I, I)$ so that $\mathbf{h}(f_n) = 0$ for each n , there is a set ω contained in $\Omega(f_n)$ for each n , and $g = \lim_{n \rightarrow \infty} f_n$ exists; nevertheless, ω is not an element of $\Omega(g)$. We note that ω must necessarily be of the form $Q \cup C$, where Q is a Cantor set, and C is a countable set of points isolated in ω . This construction of Bruckner and Ceder can be thought of as a reversal of Smital's Theorem in that their function f is developed for a particular sequence of compact periodic intervals $\{J_k\}$.

Prior to developing Bruckner and Ceder's example, we recall a device from [8] that allows us to code the sets $f^i(J_k)$ found in Smital's Theorem with finite tuples of zeros and ones. Let \mathbb{N} denote the natural numbers, and take \mathcal{N} to be the set of sequences composed of zeros and ones. If $\mathbf{n} \in \mathcal{N}$ and $\mathbf{n} = \{n_i\}_{i=1}^{\infty}$, we let $\mathbf{n} | k = (n_1, n_2, \dots, n_k)$. Set $\mathbf{0} = \{0, 0, 0, \dots\}$ and $\mathbf{1} = \{1, 1, 1, \dots\}$. Now, define a function $\mathcal{A} : \mathcal{N} \rightarrow \mathcal{N}$ given by $\mathcal{A}(\mathbf{n}) = \mathbf{n} + \mathbf{10}$, where addition is modulus two from left to right. For each $k \in \mathbb{N}$ and $i \in \mathbb{N}$ put $F_{\mathbf{1}|k} = J_k$ and $F_{\mathcal{A}^i(\mathbf{1}|k)} = f^i(J_k)$. Thus, for every \mathbf{m} and \mathbf{n} in \mathcal{N} and $k \in \mathbb{N}$ there is a $j \in \mathbb{N}$ such that $\mathcal{A}^j(\mathbf{m} | k) = \mathbf{n} | k$; the above relations define $F_{\mathbf{n}|k}$ for all $\mathbf{n} \in \mathcal{N}$ and $k \in \mathbb{N}$. In the construction that follows, we will take $F_{\mathbf{n}|k,1}$ to lie to the left of $F_{\mathbf{n}|k,0}$ for all $\mathbf{n} \in \mathcal{N}$ and $k \in \mathbb{N}$.

Example 4. Let Q be any Cantor set in $(0, 1)$, and let C be a set that consists of exactly one point from each interval contiguous to Q together with the point $\frac{1}{2} \inf Q$. We let \mathcal{M} consist of all $\mathbf{n} \in \mathcal{N}$ that have a tail of ones. We define by induction a system of closed intervals $\{F_{\mathbf{n}|k} : \mathbf{n} \in \mathcal{N}, k \in \mathbb{N}\}$ so that for each \mathbf{n} and k , $F_{\mathbf{n}|k,1}$ and $F_{\mathbf{n}|k,0}$ are disjoint subintervals contained in the interior of $F_{\mathbf{n}|k}$ for which the nondegenerate components of $K = \bigcup_{\mathbf{n} \in \mathcal{N}} \bigcap_{k=1}^{\infty} F_{\mathbf{n}|k}$ coincide with all $F_{\mathbf{n}} = \bigcap_{k=1}^{\infty} F_{\mathbf{n}|k}$ with $\mathbf{n} \in \mathcal{M}$. These in turn coincide with all $[c, q]$ where $c \in C$ and q is the nearest point to the right of c in Q . We

also choose F_1 and F_0 so that $0 = \inf F_1$ and $1 = \sup F_0$.

For each $\mathbf{n} \in \mathcal{N}$ and $k \in \mathbb{N}$ let $F_{\mathbf{n}|k} = [a_{\mathbf{n}|k}, b_{\mathbf{n}|k}]$. If $\mathbf{n} \in \mathcal{M}$, then $\bigcap_{k=1}^\infty [a_{\mathbf{n}|k}, b_{\mathbf{n}|k}] = [a_{\mathbf{n}}, b_{\mathbf{n}}]$ where $a_{\mathbf{n}}$ and $b_{\mathbf{n}}$ are the endpoints of $F_{\mathbf{n}}$; the set C consists of all $a_{\mathbf{n}}$ for which $\mathbf{n} \in \mathcal{M}$. Let S consist of all x such that $\{x\} = F_{\mathbf{n}}$ for some $\mathbf{n} \in \mathcal{N}$. Then the closure of S is Q , and if B consists of all $b_{\mathbf{n}}$ for which $\mathbf{n} \in \mathcal{M}$, then $Q = S \cup B$. We also note that $F_{\mathcal{A}(\mathbf{n})}$ is a singleton whenever $F_{\mathbf{n}}$ is a singleton.

Let $L = Q \cup C \cup \{a_{\mathbf{n}|k} : \mathbf{n} \in \mathcal{N}, k \in \mathbb{N}\} \cup \{b_{\mathbf{n}|k} : \mathbf{n} \in \mathcal{N}, k \in \mathbb{N}\}$. We first define our function f on L . If $x \in S$, define $f(x)$ so that $\{f(x)\} = F_{\mathcal{A}(\mathbf{n})}$ when $\{x\} = F_{\mathbf{n}}$, and on $C \cup B$ define f so that $f(a_{\mathbf{n}}) = a_{\mathcal{A}(\mathbf{n})}$ and $f(b_{\mathbf{n}}) = b_{\mathcal{A}(\mathbf{n})}$. On the remaining points of L we set $f(a_{\mathbf{n}|k}) = a_{\mathcal{A}(\mathbf{n})|k}$ and $f(b_{\mathbf{n}|k}) = b_{\mathcal{A}(\mathbf{n})|k}$ whenever $\mathbf{n} \mid k \neq \mathbf{1} \mid k$, and take $f(a_{\mathbf{1}|k}) = a_{\mathbf{0}|k+1}$ and $f(b_{\mathbf{1}|k}) = b_{\mathbf{0}|k+1}$.

Bruckner and Ceder show that the function $f : L \rightarrow L$ is continuous, and then extend f linearly on the intervals contiguous to L obtaining a function also denoted by f that is continuous on all of $[0, 1]$. They go on to show that f has exactly one 2^k cycle for each $k \in \mathbb{N} \cup \{0\}$, but no other periodic points, so that $\mathbf{h}(f) = 0$. Since the orbit of the point a_0 is $\{a_{\mathbf{n}|k} : \mathbf{n} \in \mathcal{N}, k \in \mathbb{N}\}$, it follows that $Q \cup C = \omega(a_0, f) \in \Omega(f)$.

Suppose $c \neq a_{\mathbf{1}}$ is an isolated point of $Q \cup C$, and c is contained in (b, a) an interval contiguous to Q . We call (x, c) , for $b < x < c$, an exterior neighborhood of c . If $c = a_{\mathbf{1}}$, we take (x, c) to be an exterior neighborhood of c for any $x \in [0, c)$. The idea behind the development of our functions f_n is to modify Bruckner and Ceder's function f so that the trajectory of a_0 intersects the exterior neighborhoods of the set C less and less frequently. In the limit $g = \lim_{n \rightarrow \infty} f_n$, we will see that the trajectory of any point x in $[0, 1]$ can visit an exterior neighborhood of $a_{\mathbf{1}}$ at most one time.

We now define our sequence of functions $\{f_n\}$. Let f_1 be Bruckner and Ceder's function f , and define f_2 so that

- $f_2(x) = f(x)$ for $x \geq a_{\mathbf{1}}$,
- $f_2(a_{\mathbf{1}|k}) = a_{\mathbf{0}|k+2}$ for all k in \mathbb{N} ,

and extend f_2 linearly on $[0, a_{\mathbf{1}})$. This extension is possible since $a_{\mathbf{0}} = \lim_{k \rightarrow \infty} a_{\mathbf{0}|k+2} = \lim_{k \rightarrow \infty} f_2(a_{\mathbf{1}|k}) = f_2(a_{\mathbf{1}})$. In general we take f_l so that $f_l(x) = f(x)$ for $x \geq a_{\mathbf{1}}$ and $f_l(a_{\mathbf{1}|k}) = a_{\mathbf{0}|k+l}$ for all $k \in \mathbb{N}$, and then extend f_l linearly on $[0, a_{\mathbf{1}})$.

It follows that each of our functions f_n satisfies Bruckner and Ceder's Theorem 4.3 - in fact, their proof carries over except for the obvious changes in notation - so that f_n has zero topological entropy, and $Q \cup C = \omega(a_0, f_n) \in \Omega(f_n)$, since $\{a_{\mathbf{n}|1+nk} : \mathbf{n} \in \mathcal{N}, k \in \{0\} \cup \mathbb{N}\}$ is the orbit of the point a_0 .

If we let $g = \lim_{n \rightarrow \infty} f_n$, however, one sees that $g(x) = a_0$ for all x contained in $[0, a_1]$, so that the orbit of any point contained in the unit interval visits an exterior neighborhood of a_1 at most once. It follows that a_1 cannot be contained in any ω -limit set of g ; in particular, $Q \cup C$ cannot be an ω -limit set of g . As Theorem 4.2 indicates, however, Q - the maximal perfect subset of ω - is an ω -limit set of g . In fact, $Q = \omega(a_0, g)$.

5 Continuity of Ω when $\Omega(f)$ is finite

In this section we return to a study of the map $\Omega : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}^*, \mathcal{H}^*\}$. Our main result shows that if f has only a finite number of stable ω -limit sets, then f is a point of continuity of the map Ω . Again, we begin with a series of lemmas.

Lemma 5.1. *Suppose f in $C(I, I)$ has only a finite number of ω -limit sets; say that $|\Omega(f)| = m$. Then $\Omega(f)$ is a finite number of periodic ω -limit sets, each with cardinality a power of two, and $\mathbf{h}(f) = 0$.*

PROOF. Since $\Omega(f)$ is finite, it follows from Sarkovskii's Theorem that $\mathbf{h}(f) = 0$. If f has an uncountable ω -limit set, then f has a 2^n orbit for each $n \in \mathbb{N}$, which contradicts $|\Omega(f)| = m$. Thus, if ω is an ω -limit set of f , then $|\omega| = 2^n$ for some $n \leq m - 1$. □

Lemma 5.2. *Suppose f is in $C(I, I)$, $|\Omega(f)| = n$ and each of the ω -limit sets of f is stable. If for any $\epsilon > 0$ there exists $\delta > 0$ so that $\|f - g\| < \delta$ implies $\Lambda(g) \subseteq B_\epsilon(\Lambda(f))$, then the map $\Omega : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}^*, \mathcal{H}^*\}$ is continuous at f .*

PROOF. We show that for each $\epsilon > 0$ there is a $\delta > 0$ so that $\mathcal{H}^*(\Omega(g), \Omega(f)) < \epsilon$ whenever $\|f - g\| < \delta$. Let $\epsilon > 0$, take $\{x_1, x_2, \dots, x_k\} = \Lambda(f)$ such that $i < j$ implies $x_i < x_j$, and set $\gamma = \min\{x_1, x_{i+1} - x_i, 1 - x_k : i = 1, 2, \dots, k - 1\}$. We may assume $\epsilon < \frac{\gamma}{3}$. Since f is uniformly continuous, there exists $\delta_1, 0 < \delta_1 < \frac{\epsilon}{3}$, so that $|x - y| < \delta_1$ implies $|f^i(x) - f^i(y)| < \frac{\epsilon}{3}$ for $i = 1, 2, \dots, 2^{n-1}$. Let $\sigma_1 = \min\{|f^{2^{n-1}}(x) - x| : x \in I \setminus B_{\delta_1}(\Lambda(f))\}$, and set $\sigma = \min\{\delta_1, \frac{\sigma_1}{2}\}$. Let $\delta_2 > 0$ so that $\|f - g\| < \delta_2$ implies $\|f^i - g^i\| < \sigma$ for $i = 1, 2, \dots, 2^{n-1}$. By hypothesis, there exists $\delta, 0 < \delta < \delta_2$ such that $\|f - g\| < \delta$ implies $\Lambda(g) \subseteq B_{\delta_2}(\Lambda(f)) \subseteq B_\epsilon(\Lambda(f))$. Let $\omega_i = \omega(x_i, f)$, and take x_i^* in $B_{\delta_2}(x_i)$ so that $g^{2^{n-1}}(x_i^*) = x_i^*$. Then $|g^m(x_i^*) - f^m(x_i)| \leq |g^m(x_i^*) - f^m(x_i^*)| + |f^m(x_i^*) - f^m(x_i)| < \epsilon$ for $m = 1, 2, \dots, 2^{n-1}$, so $\mathcal{H}(\omega(x_i^*, g), \omega_i) < \epsilon$. Moreover, since $|g(x) - f(x_i)| < \frac{\gamma}{3}$ for all x in $B_{\delta_2}(x_i)$, and $\omega_g \in \Omega(g)$ implies $g(\omega_g) = \omega_g$, it follows that $\mathcal{H}(\omega_g, \omega_i) < \epsilon$ whenever $\omega_g \cap B_{\delta_2}(x_i) \neq \emptyset$. □

Lemma 5.3. *Suppose f is in $C(I, I)$, $|\Omega(f)| = n$ and each of the ω -limit sets of f is stable. Then for any $\epsilon > 0$ there exists $\delta > 0$ so that $\|f - g\| < \delta$ implies $P(g) \subseteq B_\epsilon(\Lambda(f))$, where $P(g)$ is the set of periodic points of g .*

PROOF. We begin with some notation that will be helpful in the course of our proof. Suppose that ω is a periodic ω -limit set for $g \in C(I, I)$, and set $x_M = \max \omega, x_m = \min \omega$, and take x_{M-i} in ω so that $g^i(x_{M-i}) = x_M$. We define x_{m-i} analogously. Let $[a, b] \rightarrow [c, d]$ indicate that $g([a, b]) \supseteq [c, d]$; we write $\langle c, d \rangle$ to represent the closed interval with endpoints c and d , not caring whether $c \geq d$ or $c \leq d$. Finally, let $Fix(g) = \{x \in I : g(x) = x\}$ be the set of fixed points of g .

By considering $f^{2^{n-1}}$ rather than f if necessary, we may assume that $\Omega(f) = \{\{x_1\}, \{x_2\}, \dots, \{x_m\}\}$. Let $\sigma_1 = \min\{|f(x) - x| : x \in I \setminus \cup_{i=1}^m B_\delta(x_i)\}$ and $\sigma_2 = \min\{|f^2(x) - x| : x \in I \setminus \cup_{i=1}^m B_\delta(x_i)\}$, and set $\sigma = \min\{\sigma_1, \sigma_2\}$. If $\|f - g\| < \sigma$, then g has no fixed points or points of period two in $I \setminus \cup_{i=1}^m B_\delta(x_i)$. We proceed in several steps.

1. Suppose $g_n \rightarrow f$ and $\omega_n = \omega(x^n, g_n)$ is periodic. Let us also suppose that x_i is a fixed point of f , and there exists an M in \mathbb{N} so that for any $\epsilon > 0$ there exists $N \in \mathbb{N}$ such that $x_{M-m}^n \in (x_i - \epsilon, x_i + \epsilon)$ for all ω_n , where $n > N$. Since $g_n \rightarrow f$ and $x_{M-m}^n \rightarrow x_i$, it follows that $g_n^m(x_{M-m}^n) = x_M^n$ converges to $f^m(x_i) = x_i$. It follows that $\omega_n \rightarrow x_i$.

2. Let x_i be the fixed point of f contained in $\overline{conv}\omega$, and suppose $y \in [x_i + \delta, x_M]$ such that $g(y) \geq x_i^* \in Fix(g)$. From our first part we may assume that $x_{m-1} > x_i + \delta$, and that $x_{M-1} < x_i + \delta$. Then $\langle y, x_{m-1} \rangle \rightarrow [x_m, x_i^*] \rightarrow \langle y, x_{m-1} \rangle$, which implies $\langle y, x_{m-1} \rangle$ contains a point of period two. But this contradicts $\|f - g\| < \sigma$. We conclude that if $y \in [x_i + \delta, x_M]$, then $g(y) < \min\{Fix(g)\}$. Similarly, y in $[x_m, x_i - \delta]$ implies $g(y) > \max\{Fix(g)\}$.

3. We show that $x_m \neq x_{M-1}$, and $x_M \neq x_{m-1}$. Suppose, to the contrary, that $x_m = x_{M-1}$ for $\omega = \omega(x, g)$ where $\|f - g\| < \sigma$. Let x_i be the fixed point of f contained in $\overline{conv}\omega$, and again we may assume that $x_{m-1} > x_i + \delta$. If $x_i + \delta \leq y < x_{m-1}$, then $[y, x_{m-1}] \rightarrow [x_m, g(y)] \rightarrow [g^2(y), x_M]$, which implies $g^2(y) > y$ since we have no point of period two in $I \setminus \cup_{i=1}^m B_\delta(x_i)$. Since g is continuous, it follows that $g^2(y) > y$ for all y in $[x_i + \delta, x_M]$. But $g^2(x_M) < x_M$, since $|\omega| > 2$, which is a contradiction.

4. From our first part, we again assume that $x_{M-1} < x_i - \delta$ and $x_{m-1} > x_i + \delta$. Let $y \in [x_m, x_i - \delta]$. Since g^2 is continuous, and $g^2(x_m) > x_m$, it follows that $g^2(y) > y$. Similarly, $y \in [x_i + \delta, x_M]$ implies $g^2(y) < y$. Now, set $x^* = \min\{x \in \omega : x \in [x_i + \delta, x_M]\}$. Then $x^* \leq x_{m-1} < x_M$, and $g^2(x^*) < x^*$. Let $I_1 = [x^*, x_M]$, so that $x_{m-1} \in I_1$, and $I_2 = g(I_1) \supseteq [x_m, g(x^*)]$. We consider two cases.

Case 1: Suppose x_{M-1} is in I_2 . Then $I_1 \rightarrow I_2 \rightarrow I_1$, which implies there

is y in I_1 such that $g^2(y) = y$, a contradiction.

Case 2: Suppose x_{M-1} is not an element of I_2 . Then $g(x^*) < x_{M-1}$. Let $I_1^* = [g(x^*), x_{M-1}]$. Then $I_2^* = [g^2(x^*), x_M] \supset \omega \cap [x_i + \delta, x_M]$. If $x_{M-2} \in I_2^*$, then there is a y in I_1^* such that $g^2(y) = y$. Thus, x_{M-2} is contained in $B_\delta(x_i)$, which implies $\omega \rightarrow x_i$ as $\delta \rightarrow 0$, from part 1. \square

We are now in a position to prove the main result of this section. In the course of the proof we will need the following result of Block and Coppel [1].

Lemma 5.4. *Let G be an open subinterval which contains no periodic point of $f \in C(I, I)$. Then G contains at most one point of any ω -limit set of f .*

Theorem 5.1. *Suppose $f \in C(I, I)$, $|\Omega(f)| = n$ and each of the ω -limit sets of f is stable. Then the map $\Omega : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}^*, \mathcal{H}^*\}$ is continuous at f .*

PROOF. Since $|\Omega(f)| = n$, we know from Lemma 5.1 that $\max\{|\omega_i| : \omega_i \in \Omega(f)\} \leq 2^{n-1}$, so that $f^{2^{n-1}}$ has $\sum_{i=0}^{n-1} 2^{o(i)}$ fixed points in $\Omega(f^{2^{n-1}})$, where $2^{o(i)} = |\omega_i|$. If there exists a $\delta > 0$ so that $\|f - g\| < \delta$ implies $\Lambda(g^{2^{n-1}}) \subseteq B_\epsilon(\Lambda(f^{2^{n-1}}))$, then $\Lambda(g) \subseteq B_\epsilon(\Lambda(f))$ since $\Lambda(h) = \Lambda(h^k)$ for any $h \in C(I, I)$ and $k \in \mathbb{N}$. Moreover, this would allow us to assert our conclusion. We can assume, then, that $\Omega(f) = \{\{x_0\}, \{x_1\}, \dots, \{x_{n-1}\}\}$, where $i < j$ implies $x_i < x_j$, and x_i is not a tangential ω -limit set for any i . It suffices to show that for any $\epsilon > 0$ there exists $\delta > 0$ such that $\|f - g\| < \delta$ implies $\mathcal{H}(\Lambda(g), \Lambda(f)) < \epsilon$. Let us suppose this is not the case. Say there exists $\{g_n\} \subset C(I, I)$ so that $g_n \rightarrow f, \omega_n \in \Omega(g_n)$ and $\omega_n \rightarrow \omega$ which is not contained in $B_\epsilon(\Lambda(f))$. Then $f(\omega) = \omega$, and ω must be infinite. Let $x \in \omega$. Then $\{f^n(x)\}_{n=0}^\infty \rightarrow x_i \in \Omega(f)$, and x_i cannot be isolated in ω , for then we would have a contradiction to Lemma 4.2 in section 4; just let $F = \omega \setminus \{x_i\}$. Thus, there is an $\epsilon > 0$ so that either $(x_{i-1} + \epsilon, x_i - \epsilon) = A$ or $(x_i + \epsilon, x_{i+1} - \epsilon) = B$ contains two points of ω . This, in turn, implies that there is an $N \in \mathbb{N}$ such that A or B contains two points of ω_n whenever $n > N$. Thus, A or B contains a periodic point x_n of g_n , and this contradicts Lemma 5.3. \square

Our final two results involve $R(\Omega)$, the range of our function $\Omega : \{C(I, I), \|\cdot\|\} \rightarrow \{\mathcal{K}^*, \mathcal{H}^*\}$. While they in no way characterize the elements of $R(\Omega)$, they do indicate that $R(\Omega)$ is a very special subset of $\{\mathcal{K}^*, \mathcal{H}^*\}$. In fact, the structure of elements in $R(\Omega)$ can be wildly complicated, as $\{[0, 1]\}$ is not in the closure of $R(\Omega)$, but \mathcal{K} is [3].

Theorem 5.2. *$R(\Omega)$ is nowhere dense in $\{\mathcal{K}^*, \mathcal{H}^*\}$.*

PROOF. Let $\Omega(f)$ be an element of $R(\Omega)$. Since $\Omega(f)$ is compact, for any $\epsilon > 0$ there exists an ϵ -net K_1, K_2, \dots, K_n of $\Omega(f)$. Moreover, we may take this ϵ -net

so that each K_i is finite yet not a singleton, and $i \neq j$ implies $K_i \cap K_j = \emptyset$. Suppose $\{x_1, x_2, \dots, x_m\} = \cup_{i=1}^n K_i$, and $i < j$ implies $x_i < x_j$. Set $\delta = \min\{x_{i+1} - x_i : i = 1, 2, \dots, m - 1\}$. If $\mathcal{K} \in \mathcal{K}^*$ such that $\mathcal{H}^*(\mathcal{K}, \{K_i\}_{i=1}^n) < \frac{\delta}{2}$, then \mathcal{K} is not an element of $R(\Omega)$, since any element of $R(\Omega)$ must contain a singleton, yet by our choice of δ , if $F \in \mathcal{K}$, then F must contain at least two points. \square

In fact, we can say a bit more about the structure of $R(\Omega)$ in $\{\mathcal{K}^*, \mathcal{H}^*\}$.

Theorem 5.3. *$R(\Omega)$ is a porous subset of $\{\mathcal{K}^*, \mathcal{H}^*\}$.*

PROOF. Let $E^* \in \mathcal{K}^*$, and take $E' \in \mathcal{K}^*$ so that E' is a $\frac{1}{2n}$ -net of E^* . Say $E' = \{E'_1, E'_2, \dots, E'_m\}$. Now, let $E = \{E_1, E_2, \dots, E_m\}$ be a set of subsets of $P = \{0, \frac{1}{3n}, \frac{2}{3n}, \frac{1}{n}, \dots, \frac{3n-1}{3n}, 1\}$, where $E_i = \{x \in P : |x - y| < \frac{1}{2n}, y \in E'_i\}$. Thus, $\mathcal{H}^*(E', E) < \frac{1}{2n}$, and $E_i \in E$ implies that E_i cannot be a singleton. Suppose $F \in \mathcal{K}^*$ and $\mathcal{H}^*(F, E) < \frac{1}{6n}$. Then $F_i \in F$ implies F_i is not a singleton, so that $F \notin R(\Omega)$. It follows that $B_{\frac{1}{6n}}(E) = \{F \in \mathcal{K}^* : \mathcal{H}^*(F, E) < \frac{1}{6n}\}$ has a null intersection with $R(\Omega)$. Since $\mathcal{H}^*(E^*, E) \leq \mathcal{H}^*(E^*, E') + \mathcal{H}^*(E', E) < \frac{1}{n}$, we see that $B_{\frac{1}{6n}}(E) \subset B_{\frac{7}{6n}}(E^*)$ and the porosity of $R(\Omega)$ at E^* must be at least $\frac{2}{7}$. Since this holds for any set E^* in $\{\mathcal{K}^*, \mathcal{H}^*\}$, we conclude that $R(\Omega)$ is porous. \square

6 Conclusion

While we have made some progress in understanding how perturbations in a continuous function affect its iterative behavior, our study of this subject in the context of the maps $\Lambda : C(I, I) \rightarrow \mathcal{K}$ and $\Omega : C(I, I) \rightarrow \mathcal{K}^*$ is far from complete.

If we go back to considering the overall continuity structure of our maps Λ and Ω , an entire series of problems comes to mind. For example, how can one characterize the points of continuity of Ω and Λ ? What are their Baire classifications? Are they measurable? Problems that are perhaps more tractable, yet still very interesting, can be posed by restricting our attention to subsets $S \subseteq C(I, I)$, such as one parameter families of continuous functions, or those functions that are in some sense nonchaotic or smooth.

Our final result of section 5 - that $R(\Omega)$ is porous, hence nowhere dense, in $\{\mathcal{K}^*, \mathcal{H}^*\}$ - begs a series of follow-on queries related to characterizing $R(\Omega)$ in \mathcal{K}^* . Is $R(\Omega)$ a Borel set? How does $\Omega(f)$ reflect the chaotic properties of f , if it does at all?

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