ON SELF A-EQUIVALENCE OF BOUNDARY LINKS

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1. Introduction

An *n*-component oriented tame link $\ell = k_1 \cup ... \cup k_n$ in the oriented 3-space R^3 is called a boundary link if there are mutually disjoint oriented surfaces $F_1, ..., F_n$ in R^3 such that $\partial \mathcal{F} = \ell$, $\partial F_i = k_i$ for $\mathcal{F} = F_1 \cup ... \cup F_n$ and each i = 1, ..., n. Then \mathcal{F} is called the spanning surface of ℓ .

It is known that boundary links are link-homotopic to a trivial link, [2].

For self #-equivalences (definition, see [11], [12], [13]) of boundary links, the followings are known:

- 1. Boundary links are self #-equivalent(I) to a trivial link, [11], [13].
- 2. Boundary links are self #-equivalent(II) to a trivial link if and only if the Arf invariant of each component is zero, [2].

In this paper, we consider another self local equivalence, called a self Δ -equivalence, of boundary links. Namely, for a link ℓ , let E^3 be a 3-ball such that $\ell \cap E^3$ is a tangle illustrated in Fig.1(a). The transformation from Fig.1(a) to 1(b) is called a Δ -move, [5].



Fig.1

Especially if 3 arcs in Fig.1(a) are contained in a component of ℓ , it is called a self Δ -move. For two links ℓ and ℓ' , if ℓ can be deformed into ℓ' by a finite sequence of (self) Δ -moves, ℓ is said to be (self) Δ -equivalent to ℓ' . It is known that self Δ -equivalence implies self #-equivalence(I) of links, [1], [6] and [12]. But the converse is not true, [7].

The aim of this paper is to give some partial answers to the following Conjecture.

Conjecture. Let ℓ be an n-component boundary link. Then ℓ is self Δ -equivalent to the trivial link.

A link $\ell=k_1\cup...\cup k_n$ is called a boundary link in the strong sense if there are mutually disjoint singular disks $D_1,...,D_n$ in R^3 such that $\partial \mathcal{D}=\ell,\partial D_i=k_i$ for $\mathcal{D}=D_1\cup...\cup D_n$ and each i=1,...,n.

If ℓ is a boundary link in the strong sense, there are disks $D_1, ..., D_n$ satisfying the above. By the orientation preserving cut along each singularity of D_i , we obtain a spanning surface of ℓ . Namely ℓ is the boundary link. (But the converse is not true, namely there are links which are boundary links but not boundary links in the strong sense by Proposition 4.3.)

Theorem 4.2. If ℓ is a boundary link in the strong sense, ℓ is self Δ -equivalent to the trivial link.

A link ℓ is said to be p-trivial if there is a p-component sublink L of ℓ such that L is the trivial link.

Theorem 4.5. Let ℓ be an n-component boundary link. If ℓ is (n-1)-trivial, ℓ is self Δ -equivalent to the trivial link.

Lastly, we shall prove the Conjecture is true for n=2 by using Theorem 4.5.

Theorem 4.6. If $\ell = k_1 \cup k_2$ is a boundary link, ℓ is self Δ -equivalent to the trivial link.

2. Ribbon Δ -cobordism of links.

To prove Theorems, we introduce the Δ -cobordism of links.

For two n-component links ℓ , L in $R^3[a]$, $R^3[b]$ respectively for a < b, ℓ is said to be Δ -cobordant to L if there are mutually disjoint annuli $A_1,...,A_n$ in $R^3[a,b]$ satisfying the followings for $A=A_1\cup...\cup A_n$, where $R^n[a,b]=\{(x_0,...,x_n)\in R^{n+1}|a\leq x_n\leq b\}$ and $R^n[c]=\{(x_0,...,x_n)\in R^{n+1}|x_n=c\}: A\cap R^3[a]=\ell$ and $A\cap R^3[b]=\tilde{L}$, the reflect inverse of L, and $A_i\cap R^3[a]\neq \phi$, $A_i\cap R^3[b]\neq \phi$ for each

i=1,...,n and $\mathcal A$ are locally flat except finite points contained in the interior of $\mathcal A$, which are the singularity of $\mathcal A$, denoted by $\mathcal S(\mathcal A)$, such that, for each point P of $\mathcal S(\mathcal A)$, $(\partial N(P:R^3[a,b]),\partial N(P:\mathcal A))$ is the Borromean rings, Fig.2, where N(x:X) means the regular neighborhood of x in X. The annuli $\mathcal A$ satisfying the above conditions are called Δ -annuli between ℓ and L. Especially, for Δ -annuli $\mathcal A$ between ℓ ($\subset R^3[a]$) and $L(\subset R^3[b])$ for a < b, if $\mathcal A$ do not have minimal points, [3], ℓ is said to be ribbon Δ -cobordant to L. Moreover if $\mathcal S(\mathcal A) = \phi$, ℓ is said to be ribbon cobordant to L. Therefore ℓ is a ribbon link, [15], if and only if ℓ is ribbon cobordant to the trivial link.

The following is proved in [15].

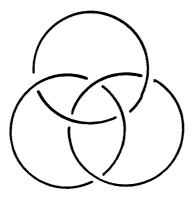


Fig.2

Lemma 2.1. Any ribbon link is self Δ -equivalent to the trivial link.

By using Lemma 2.1 and the similar proof to that of Lemma 1.19. in [10], we easily obtain Lemma 2.2 which is an extention of Lemma 2.1.

Lemma 2.2. Suppose that ℓ is a link ribbon Δ -cobordant to the trivial link. Then ℓ is self Δ -equivalent to the trivial link.

3. Local moves realizable by a finite sequence of (self) Δ -moves

In this section, we introduce some (self) local moves realizable by a finite sequence of (self) Δ -moves, which are used to prove Theorems.

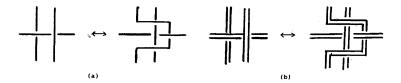


Fig.3

The following local moves of links are called a Π -move(Fig.3(a)) and a parallel Π -move(Fig.3(b)) respectively.

Lemma 3.1. A Π -move and a parallel Π -move can be realized by a finite sequence of Δ -moves.

Proof. A Π -move can be realized by a Δ -move by the following way, Fig.4

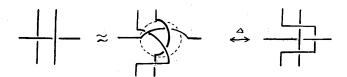


Fig.4

As a parallel Π -move can be realized by a finite sequence of Π -moves, it can be done by a finite sequence of Δ -moves.

As a parallel Δ -move illustrated in Fig.5 can be realized by a parallel Π -move, we obtain Lemma 3.2 by Lemma 3.1.

Lemma 3.2. A parallel Δ -move can be realized by a finite sequence of Δ -moves.

Next we consider the following move, called a C_m -move, Fig.6.

Lemma 3.3. A C_m -move can be realized by a finite sequence of Δ -moves.

Proof. A C_m -move can be realized by a finite sequence of Π -moves, Fig.7. Hence we obtain Lemma 3.3 by Lemma 3.1.

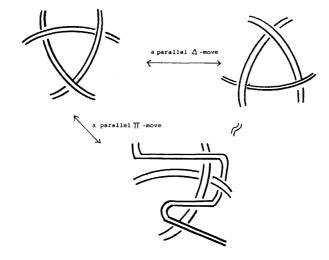


Fig.5

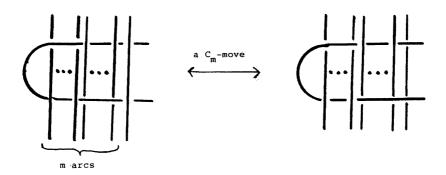


Fig.6

$$\begin{array}{c|c} & & & & \\ \hline \end{array}$$
 \approx $\begin{array}{c|c} & & & \\ \hline \end{array}$ $\stackrel{\text{5.6}}{\longrightarrow}$ $\begin{array}{c|c} & & & \\ \hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array}$

Fig.7

Lemma 3.4. A parallel C_1 -move illustrated in Fig.8 can be realized by a finite sequence of Δ -moves.

Proof. A parallel C_1 -move can be realized by 4-time C_2 -moves illustrated in Fig.8. Hence we obtain Lemma 3.4 by Lemma 3.2.

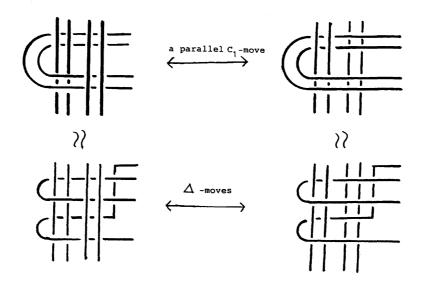


Fig.8

4. Proof of Theorems.

Now let us prove Theorems.

To prove Theorem 4.2, we define a link, called a double link, which is a kind of boudary link in the strong sence and prove Lemma 4.1.

Let $\mathcal{V}=V_1\cup\ldots\cup V_n$ be a disjoint union of n solid tori V_1,\ldots,V_n in R^3 and k_i a doubled knot in V_i , [16]. Then $\ell=k_1\cup\ldots\cup k_n$ is called a doubled link (in \mathcal{V}).

Lemma 4.1. Any doubled link is self Δ -equivalent to the trivial link.

Proof. Let $\ell = k_1 \cup ... \cup k_n$ be a doubled link in $\mathcal{V} = V_1, \cup ... \cup, V_n$. Since the Δ -move is a kind of unknotting operations of knots, [5], we obtain a doubled link $\ell_1 = k'_1 \cup (\ell - k_1)$ in $\mathcal{V}_1 = V'_1 \cup (\mathcal{V} - V_1)$, $k'_1 \subset V'_1$, such that V'_1 is a trivial solid torus and ℓ_1 is self Δ -equivalent to ℓ by Lemma 3.2. Hence, by choosing ℓ_1 instead of ℓ

if necessary, we can assume that ℓ is a doubled link in $\mathcal{V}=V_1\cup\ldots\cup V_n$ such that V_1 is trivial in R^3 . Moreover, if k_1 is m-full twisted in V_1 , we apply m-time self Δ -moves to k_1 in V_1 illustrated in Fig.9 and obtain the trivial knot, denoted by k_1 again, in V_1 . Hence there is a disk D_1 with $\partial D_1=k_1$, where D_1 is obtained by connecting 2 parallel disk, each of which is parallel to the disk C_1 with ∂C_1 =(the longitude of ∂V_1), with a 1-full twisted band in V_1 . Deform D_1 into $R^2[1]$ by an ambient isotopy φ_1 of R^3 and denote $\varphi_1(D_1), \varphi_1(\ell), \varphi_1(k_i), \varphi_1(V_i)$ and $\varphi_1(c_i)$ by D_1, ℓ, k_i, V_i and c_i respectively again, where c_i means the core of V_i .

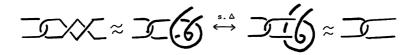


Fig.9

Suppose that $D_1 \cap V_i \neq \phi$ for some $i \geq 2$. As the intersection number of D_1 and c_i , denoted by $I(D_1, c_i)$, is equal to $Link(k_1, c_i)(=0)$, there is the closure of connected component B_i^3 of $V_i - D_1$ such that $B_i^3 \cap D_1$ is contained is the positive, or negative side of D_1 , denoted by D_1^+, D_1^- respectively, Fig.10(a).

Suppose that $D_1 \cap k_2 \neq \phi$. Then $D_1 \cap V_2 \neq \phi$ and there is B_2^3 satisfying the above, Fig.10(a). By deforming B_2^3 slightly with D_1 fixed, we may assume that $B_2^3 \subset R^2[1,\infty)$ (or $R^2(-\infty,1]$). Now let $B_2^3 \subset R^2[1,\infty)$. Moreover we can deform B_2^3 unknotted in $R^2[1,\infty)$ by Lemma 3.2.

Let E^2 be a non-singular disk in $R^2[1,\infty)$ with $E^2 \cap B_2^3 = \partial E^2 \cap \partial B_2^3$ (={an arc}) and $E^2 \cap D_1 = \partial E^2 \cap \partial D_1$ (={an arc}). If $k_2 \cap B_2^3$ does not contain the Hopf tangle, deform it into B_2^3 illustrated in Fig.10(a), (b).

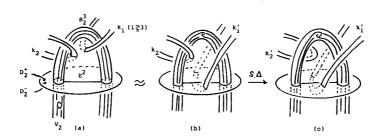


Fig. 10

If $E^2 \cap k_i \neq \phi$ for some $i \geq 3$, deform $E^2 \cap k_i$ into $R^2(-\infty,1]$ along E^2 by an ambient isotopy of R^3 , Fig.10(a), (b). After this deformation, if $E^2 \cap k_2 \neq \phi$, we apply a finite sequence of self C_1 -move to k_2 , Fig.10(b), (c), and obtain a knot k_2' from k_2 such that $E^2 \cap k_2' = \phi$. By deforming B_2^3 along E^2 into $R^2(-\infty,1]$, we obtain a doubled link $\ell' = k_1 \cup k_2' \cup ... \cup k_n'$ from ℓ such that ℓ' is a doubled link self Δ -equivalent to ℓ by Lemma 3.3 and $\#(k_2' \cap D_1) = \#(k_2 \cap D_1) - 4$, where #(X) means the number of points of X.

By performing the above discussion successively, we obtain a doubled link $L = k_1 \cup K_2 ... \cup K_n$ self Δ -equivalent to ℓ such that $K_2 \cap D_1 = \phi$

Next we apply the above discussion to K_2 . If K_2 is not trivial, we can obtain a doubled link $L'=K_2'\cup (L-K_2)$ such that K_2' is trivial and $K_2'\cap D_1=\phi$ by a finite sequence of self Δ -moves. Hence we write L' and K_2' by L and K_2 respectively again. There is a disk D_2 with $\partial D_2=K_2$ by the same construction with that of D_1 such that $D_1\cap D_2=\phi$ and an ambient isotopy φ_2 of R^3 such that $\varphi_2(D_1)=D_1$ and $\varphi_2(D_2)\subset R^2[2]$. Let us denote $\varphi_2(D_2)$ and $\varphi_2(V_j)$ for $j\geq 3$ by D_2 and V_j respectively.

Suppose that $D_2 \cap V_3 \neq \phi$. As $I(D_2, c_3) = 0$, there is the closure of a connected component B_3^3 of $V_3 - D_1 - D_2$ such that $B_3^3 \cap D_p$ is contained in D_p^+ or D_p^- for p = 1 or 2 by the construction of D_1 and D_2 . Hence we can apply the same discussion, which is used to remove $B_2^3 \cap D_1$, to $B_3^3 \cap D_p$. By doing the above successively, we obtain a doubled link $\mathcal{L} = k_1 \cup K_2 \cup \kappa_3 \cup ... \cup \kappa_n$ self Δ -equivalent to L such that κ_3 is trivial and $\kappa_3 \cap (D_1 \cup D_2) = \phi$, where $\partial D_1 = k_1$, $\partial D_2 = K_2$.

Performing the above in turn, we obtain the trivial link self Δ -equivalent to ℓ . \square

Let us prove Theorem 4.2 by using Lemmas 2.2 and 4.1.

Theorem 4.2. If ℓ is a boundary link in the strong sense, ℓ is self Δ -equivalent to the trivial link.

Proof. Suppose that $\ell=k_1\cup...\cup k_n$ is a boundary link in the strong sense. Then there are mutually disjoint disks $D_1,...,D_n$ with $\partial \mathcal{D}=\ell,\partial D_i=k_i$, where $\mathcal{D}=D_1\cup...\cup D_n$.

Any singularity of \mathcal{D} , denoted by $\mathcal{S}(\mathcal{D})$, can be deformed into simple (not self intersection) clasp singularity, Fig.11, which does not intersect with each other by deforming ℓ on \mathcal{D} suitably, [9]. Hence we can assume that $\mathcal{S}(\mathcal{D})$ consists of mutually disjoint simple arcs of clasp type. For an arc α of $\mathcal{S}(D_i)$, the pre-images α^*, α'^* of α are said to be next on the pre-image D_i^* of D_i if there is an arc d of $\partial D_i^* - \alpha^* - \alpha'^*$ which does not contain a point of the pre-image of $\mathcal{S}(D_i)$, Fig.12. Suppose that α^*, α'^* are next on D_i^* and $d(\subset \partial D_i^*)$ an arc as above and let $\delta^* = \overline{\partial N(\alpha^* \cup \alpha'^* \cup d: D_i^*) - \partial D_i^*}$, Fig.12. Then $\delta^* \cap$ (the pre-image of $\mathcal{S}(D_i) = \phi$ by the choice of α^* and α'^* . Performing the fission, [3], on D_i along δ , we obtain two disks D_{i0}, D_{i1} on D_i such that ∂D_{i0} is a doubled knot and $\mathcal{S}(D_{i1}) = \mathcal{S}(D_i) - \alpha$,

Fig.12(b).

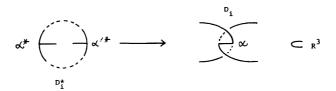


Fig.11

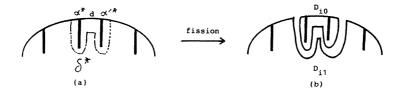


Fig.12

Next suppose that α^* , ${\alpha'}^*$ are not next on D_i^* , namely there are $\beta^*, {\beta'}^*$, the preimage β of $\mathcal{S}(D_i)$, such that each of $\partial D_i^* - \alpha^* - {\alpha'}^*$ contains a point of β^* or one of ${\beta'}^*$. In this case, exchange α and β along a subarc of ∂D_i from Fig.13(a) to 13(b). This deformation can be accomplished by a finite sequence of self Δ -moves. We write the disk in Fig.13(b) by \tilde{D}_i . If the pre-images $\tilde{\alpha}^*, \tilde{\alpha'}^*$ of $\tilde{\alpha}$ of $\mathcal{S}(\tilde{D}_i)$, Fig.13(b), are next on \tilde{D}_i^* , we perform the above fission. If they are not next on \tilde{D}_i^* , we perform the deformations from Fig.13(a) to 13(b) again.

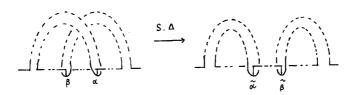


Fig.13

By doing the above discussions for each D_i successively, we obtain a doubled link L self Δ -equivalent to the trivial link by Lemma 4.1. Since L is obtained by a finite sequence of fissions of ℓ , ℓ is ribbon Δ -cobordant to the trivial link \mathscr{O} . Therefore ℓ is self Δ -equivalent to \mathscr{O} by Lemma 2.2.

By the following, there are links which are boundary links but not boundary links in the strong sense.

Proposition 4.3. Let A be non-twisted annulus in R^3 . If $S(A) = \phi$, $\ell(= \partial A)$ is a boundary link. But if ℓ is not the trivial link, ℓ is not the boundary link in the strong sense.

Proof. If A is non-twisted and $S(A) = \phi$, i.e., A is non-singular, it is easily seen that $\ell = k_1 \cup k_2$ is a boundary link.

Suppose that ℓ is a boundary link in the strong sense. Namely there are mutually disjoint disks D_1, D_2 such that $\partial(D_1 \cup D_2) = \ell$, $\partial D_i = k_i$. Since $\mathcal{S}(A) = \phi$ and $D_1 \cap D_2 = \phi$, $A \cup D_1$ is a singular disk with $\partial(A \cup D_1) = k_2$ such that $k_2 \cap \mathcal{S}(A \cup D_1) = \phi$. Hence k_2 is the trivial knot,[4], [8], and so ℓ is the trivial link. Therefore, if ℓ is not the trivial link, ℓ is not the boundary link in the strong sense.

Theorem 4.5. Let ℓ be an n-component boundary link. If ℓ is (n-1)-trivial, ℓ is self Δ -equivalent to the trivial link.

Proof. If $\ell = k_1 \cup ... \cup k_n$ is (n-1)-trivial, there is a knot, say k_1 , such that $\ell - k_1$ is the trivial link. Hence there is an ambient isotopy φ of R^3 such that $\varphi(k_j) \subset R^2[j]$ for j = 2, ..., n.

As ℓ is a boudary link, $\varphi(\ell)$ is also a boudary link. We denote $\varphi(\ell), \varphi(k_i)$ by ℓ, k_i again respectively and so there is a spanning surface $\mathcal{F} = F_1 \cup ... F_n$ of ℓ with $\partial F_i = k_i, i = 1, ..., n$. Let F_1 consist of a disk D_1 and a disjoint union of 2p bands \mathscr{B} with $D_1 \cap \mathscr{B} = \partial D_1 \cap \partial \mathscr{B} = (4p \text{ arcs})$ for $p = g(F_1)$. Since k_j is trivial for j = 2, ..., n, we may assume that F_j is obtained by attaching tubes to a disk $D_j^*(\subset R^2[j])$ for $\partial D_j^* = k_j$. Let $B_j^3 = N(D_j^* : R^3)$. Then $B_2^3, ..., B_n^3$ are mutually disjoint 3-balls in R^3 such that $(\ell - k_1) \cap B_j^3 = k_j$. By the construction of F_j , we may assume that the connected component of $F_j \cap B_j^3$ whose boundary contains k_j is a perforated disk.

Since $F_1 \cap (\ell - K_1) = \phi$, we may assume that $F_1 \cap B_j^3 = \mathcal{B} \cap B_j^3$ by deforming F_1 suitably.

Let us denote $(\mathcal{F} - F_1) \cap \partial B_j^3$ by Γ_j . Then Γ_j consists of disjoint loops. If Γ_j contains a loop γ_0 such that there is a disk σ on ∂B_j^3 with $\partial \sigma = \gamma_0$ and $\sigma \cap \mathscr{B} = \phi$, we can eliminate γ_0 by attaching a 2-handle along to $\mathcal{F} - F_1$. Hence we may assume that, for each γ of Γ_j , each disk on ∂B_j^3 bounded by γ intersects with \mathscr{B} , Fig.14(a). Attach 2-handles to $\mathcal{F} - F_1$ along the disks on ∂B_j^3 bounded by loops of Γ_j , from an

innermost loop of Γ_j in turn, illustrated in Fig.14(b). Then we obtain a non-singular disk in B_i^3 and spheres from $\mathcal{F} - F_1$ which are mutually disjoint.

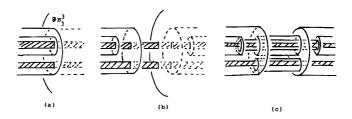


Fig.14

Now attach 1-handles $\mathcal J$ along the bands $\mathscr B$ such that, for each tube T of $\mathcal J,T\cap\partial B_j^3$ is a loop c_T and there is a disk σ_T of $\partial B_j^3-c_T$ with $\sigma_T\cap\mathscr B=\{\text{an arc}\}$, Fig.14(c). As a result, we obtain a spanning surface $\mathcal F_0=F_1\cup F_{20}\cup\ldots\cup F_{n0}$ from $\mathcal F=F_1\cup\ldots\cup F_n$ such that each F_{j0} consists of a perforated disk E_j in B_j^3 and tubes $\mathcal J_j(=F_{j0}\cap\mathcal J)$.

Let D_j be the disk in B_j^3 with $\partial D_j = k_j$ and $D_j \supset E_j$ and $\mathcal{D} = D_2 \cup ... \cup D_n$ and T an outermost tube of \mathcal{J} , namely $T \cap \mathcal{D} = \partial T \cap \mathcal{D} = \{$ two loops, say δ and δ' $\}$. Suppose that $\partial T \subset D_2$. Let α be an arc on T which connects a point of δ and one of δ' . If α is knotted in $R^3 - D_2$, we may deform it unknotted by a finite sequence of self Δ -moves, for the Δ -move is an unknotting operation of knots, [5], and obtain an unknotted tube \tilde{T} from T and a boundary link $\tilde{\ell}$ which is (n-1)-trivial and self Δ -equivalent to ℓ by Lemma 3.2. Therefore, by choosing \tilde{T} , $\tilde{\ell}$ instead of T, ℓ respectively, we may assume that T is unknotted. (If there is a tube T' of \mathcal{J} which runs along the inside of T, we deform T' and obtain a tube \tilde{T}' from T' such that \tilde{T}' runs along the inside of \tilde{T} .)

Since T is an outermost and unknotted tube of \mathcal{J} , we may take a disk σ in R^3 such that $\sigma \cap T = \alpha$ and $\sigma \cap \mathcal{D} = \sigma \cap E_2 = \{\text{an arc}\}$. If $\sigma \cap (\mathcal{J} - T) = \phi$, we deform T along σ and eliminate T, Fig.15. Next assume that $\sigma \cap (\mathcal{J} - T) \neq \phi$. Then there is a tube T_0 of $\mathcal{J} - T$ such that $\sigma \cap T_0 \neq \phi$. Then there is a band B of \mathcal{B} such that $\sigma \cap B \neq \phi$. Perform the fission, [3], of k_1 along $\sigma \cup T$ illustrated in Fig.16(b), we obtain a link $\ell_1 \cup \mathcal{L}_1$ from ℓ such that ℓ_1 is a boundary link and (n-1)-trivial and \mathcal{L}_1 is a 2-component trivial link, Fig.16(b). Next deform \mathcal{L}_1 towards to the foot of a band B_0 which runs through the inside of T, Fig.16(b),(c). As a result, we obtain a 2-component link $\tilde{\mathcal{L}}_1$ from \mathcal{L}_1 . By doing the above fissions and deformations successively, we obtain a link $\ell_r \cup \tilde{\mathcal{L}}_1 \cup \ldots \cup \tilde{\mathcal{L}}_r$ from ℓ such that ℓ_r is a boundary link which is (n-1)-trivial with $\sigma \cap \ell_r = \phi$ and $\tilde{\mathcal{L}}_1 \cup \ldots \cup \tilde{\mathcal{L}}_r$ is a 2r-component trivial link. Therefore, by deforming T along σ , we can eliminate T and so decrease $\#\mathcal{S}(\ell_r \cap \mathcal{D}) (= \#\mathcal{S}(\ell \cap \mathcal{D}))$.

By performing the above discussion from an outermost tube of ${\mathcal J}$ in turn, we

obtain a link $L = \mathcal{L} \cup k_2 \cup ... \cup k_n$ from ℓ such that $L - \mathcal{L} (= \ell - k_1)$ is the trivial link split from \mathcal{L} and \mathcal{L} is obtained by a finite sequence of fissions of k_1 , Fig.17.

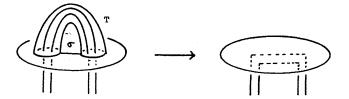


Fig.15

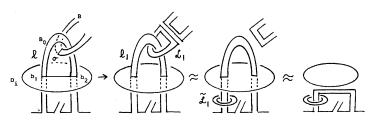


Fig.16

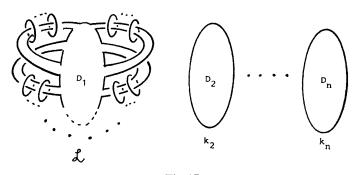


Fig.17

Since \mathcal{L} is Δ -equivalent (not self) to the trivial link by [5], ℓ is ribbon Δ -cobordant to the trivial link. Hence ℓ is self Δ -equivalent to the trivial link by Lemma 2.2.

Lastly, let us prove Theorem 4.6.

Theorem 4.6. If $\ell = k_1 \cup k_2$ is a boundary link, ℓ is self Δ -equivalent to the trivial link.

To prove it, it is enough to do the following by Theorem 4.5.

Lemma 4.7. For any 2-component boundary link $\ell = k_1 \cup k_2$, ℓ is self Δ -equivalent to a boundary link $L = K_1 \cup K_2$ such that K_1 is the trivial knot.

To prove Lemma 4.7, we prepare some Lemmas.

For an *n*-component boundary link ℓ , a spanning surface $\mathcal{F} = F_1 \cup ... \cup F_n$ of ℓ is said to be normal if the bands of F_i are situated as illustrated in Fig.18 for each i = 1, ..., n.

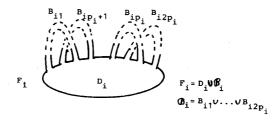


Fig.18

Since a Δ -move is a kind of unknotting operation of knots, [5], we obtain Lemma 4.8 by applying a finite sequence of self Δ -moves to each band B_{ij} of a normal surface \mathcal{F} of ℓ and by using Lemma 3.2.

Lemma 4.8. For a boundary link ℓ and a normal surface \mathcal{F} of ℓ , there are a boundary link ℓ_0 self Δ -equivalent to ℓ and a normal surface \mathcal{F}_0 of ℓ_0 such that each band of \mathcal{F}_0 is unknotted.

Since ℓ_0 is a boundary link self Δ -equivalent to ℓ , it is enough to prove Lemms 4.7 for ℓ_0 .

Lemma 4.9. Let ℓ_0 , \mathcal{F}_0 be those of Lemma 4.8. Then there are a boundary link ℓ_1 self Δ -equivalent to ℓ_0 and a normal surface \mathcal{F}_1 of ℓ_1 such that each band of \mathcal{F}_1 is unknotted and non-twisted in \mathbb{R}^3 .

Proof. Let $\mathcal{F}_0 = F_1 \cup F_2$ be a normal surface of ℓ_0 satisfying Lemma 4.8 and $B(=B_{1j})$, $B'(=B_{1p_1+j})$ a pair of bands of F_1 associated to a genus, Fig.19.

Suppose that B is twisted, Fig.19(a). Now we deform one full twist of B from Fig.19(a) to 19(b) and transform it along $\partial(B \cup B')$ from Fig.19(b) to 19(c),(d). During these transformations, a circle c can jump the other twists of $B \cup B'$ and subarcs of ∂B_{1i} by a finite sequence of self Δ -moves, Fig.3(a). We can eliminate the twist in

Fig.19(d) by a finite sequence of self Δ -moves from Fig.19(d) to 19(e),(f). The link in Fig.19(f) is ambient isotopic to that of Fig.19(h) whose spanning surface $\mathcal{F}_0' = F_1' \cup F_2'$ is normal. By these deformations, we can eliminate a full twist of B without increasing the number of full twists of the other bands of \mathcal{F}_0' . Moreover $\partial \mathcal{F}_0'$ is self Δ -equivalent to ℓ_0 .

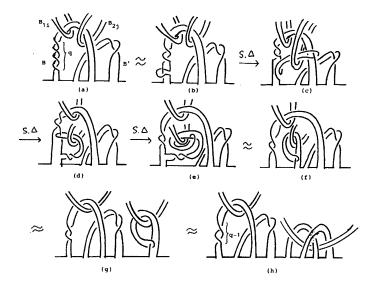


Fig.19

By repeating these deformations successively, we obtain a link ℓ_1 and a normal surface \mathcal{F}_1 of ℓ_1 satisfying Lemma 4.9.

Let E^3 be a 3-ball and $\mathcal{L} = \kappa_1 \cup \kappa_2$ a 2-component link illustrated in Fig.20, where κ_i is the trivial knot and $\kappa_i \cap \partial E^3 (= \alpha_i)$ is an arc for i = 1, 2.

Lemma 4.10. Let E^3 , \mathcal{L} and α_i be those of the above. Suppose that $L = K_1 \cup K_2$ be a 2-component link such that each K_i is the trivial knot with $Link(K_1, K_2) = q$ and $K_i \cap \partial E^3 = \alpha_i$. Then L can be deformed into \mathcal{L} by a finite sequence of Δ -moves and an ambient isotopy of E^3 with $\alpha_1 \cup \alpha_2$ fixed.

Proof. Since each K_i is trivial, there is a non-singular disk D_i in E^3 with $\partial D_i = K_i$ such that $\mathcal{S}(D_1 \cap D_2)$ consists of finite simple clasp singularities. The alternation of upper and under passes and the elimination of twists of bands, the change of order of clasps of $\mathcal{S}(D_1 \cap D_2)$ on D_1, D_2 can be realized by a finite sequence of Δ -moves (not self Δ -moves) illustrated in Fig.21(a),(b) and (c) respectively. Since these Δ -moves can

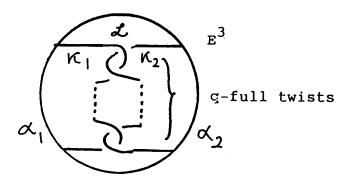


Fig.20

be done in the interior of E^3 , $\alpha_1 \cup \alpha_2$ is fixed. Hence we obtain the link $\mathcal L$ illustrated in Fig.20 from L by a finite sequence of Δ -moves and ambient isotopy of E^3 with $\alpha_1 \cup \alpha_2$ fixed.

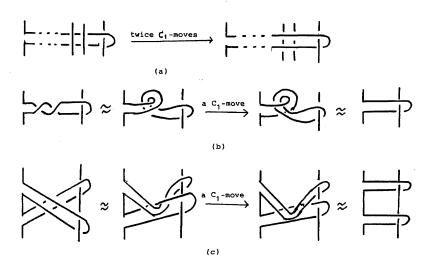


Fig.21

Let ℓ_1 and $\mathcal{F}_1(=F_1 \cup F_2)$ be those of Lemma 4.9. Two bands B_{ij}, B_{ip_i+j} associated to a genus of \mathcal{F}_1 are said to be well-situated if B_{ij} and B_{ip_i+j} are situated illustrated in Fig.22. Moreover \mathcal{F}_1 is said to be well-situated if each pair B_{ij}, B_{ip_i+j} of \mathcal{F}_1 is well-situated for i=1,2 and $j=1,...,p_i(=g(F_i))$.

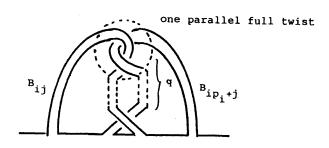


Fig.22

The following is easily obtained by Lemma 3.4 and 4.10.

Lemma 4.11. Let ℓ_1 and \mathcal{F}_1 be those of Lemma 4.9. Then there are a boundary link ℓ_2 self Δ -equivalent to ℓ_1 and a normal surface \mathcal{F}_2 of ℓ_2 which is well-situated.

Proof of Lemma 4.7. We write ℓ_2, \mathcal{F}_2 satisfying Lemma 4.11 by ℓ , $\mathcal{F}(=F_1 \cup F_2)$ again respectively and let F_i consist of a disk D_i and $2p_i$ bands B_{ij} of \mathscr{B}_i illustrated in Fig.18.

Suppose that the bands B_{11}, B_{1p_1+1} of $F_1(\subset \mathcal{F})$ have q parallel full twists, Fig.23 (a). Deform B_{1p_1+1} along B_{11} from Fig.23(a) to 23(b) and from 23(b) to 23(c) by an ambient isotopy φ of R^3 such that $\tilde{B}_{11} \subset D_1$, where $\tilde{B}_{ij} = \varphi(B_{ij})$. Let D_{11} be a disk of $\overline{D_1} - \tilde{B}_{11}$ illustrated in Fig.23(c). If there is a band \tilde{B}_{2i} such that $\tilde{B}_{2i} \cap D_{11} \neq \phi$, we deform \tilde{B}_{2i} on $D_{11} \cup \tilde{B}_{1p_1+1}$ from Fig.23(c) to 23(d) and obtain \tilde{B}'_{2i} from \tilde{B}_{2i} satisfying that $\tilde{B}'_{2i} \cap D_{11} = \phi$. By repeating these deformations, we obtain a surface $\mathcal{F}' = F_1' \cup F_2'$ from $\mathcal{F} = F_1 \cup F_2$ such that $F_2' \cap D_{11} = \phi$. Then we can apply Lemma 3.3 to $\partial F_1'$ in Fig.23(d) and obtain the link ℓ' in Fig.23(e) by a finite sequence of self Δ -moves. After this, we deform $\tilde{B}_{11} \cap \tilde{B}'_{2i}$ into D_{11} along \tilde{B}_{11} from Fig.23(e) to 23(f) and obtain a link ℓ'' which is ambient isotopic to ℓ' and so self Δ -equivalent to ℓ . Moreover we easily see that ℓ'' is the boundary link and ambient isotopic to the link $\ell^{(1)}$ illustrated in Fig.23(g). By applying the above deformations to B_{11}, B_{1p_1+1} successively, we obtain the bands $B_{11}^{(q)}, B_{1p_1+1}^{(q)}$ and the link $\ell^{(q)}$ illustrated in Fig.23(h) such that $\ell^{(q)}$ is the boundary link self Δ -equivalent to ℓ .

Now we denote the bands obtained by these deformations of \mathscr{B}_i by $\mathscr{B}_i^{(q)}$. If the other band $B_{1s}^{(q)}(s \neq 1, p_1 + 1)$ of $\mathscr{B}_1^{(q)}$ does not link with $B_{11}^{(q)}, B_{11}^{(q)} \cup B_{1p_1+1}^{(q)}$ can be removed by an ambient isotopy of R^3 , Fig.24(a),(b).

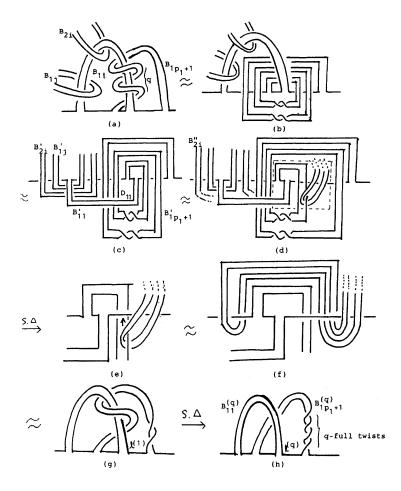


Fig.23

Next suppose that there is a band $B_{1s}^{(q)}(s \neq 1, p_1 + 1)$ which links with $B_{11}^{(q)}$. If there is a band $B_{2j}^{(q)}$ of $\mathscr{B}_2^{(q)}$ which links with $B_{11}^{(q)}$, deform $B_{2j}^{(q)}$ along $B_{1p_1+1}^{(q)}$ illustrated in Fig.25(a),(b).(If there is not a band $B_{2j}^{(q)}$ of $\mathscr{B}_2^{(q)}$ satisfying the above, it is not necessary to do the above deformation, Fig.25(a),(b).) After this deformation, we perform a finite sequence of self Δ -moves, Lemma 3.3, to $\mathscr{B}_1^{(q)}$ and obtain the bands $B_{11}^{(q)'}, B_{1p_1+1}^{(q)'}(\subset \mathscr{B}_1^{(q)'})$ from $B_{11}^{(q)}, B_{1p_1+1}^{(q)}(\subset \mathscr{B}_1^{(q)})$ such that $B_{1p_1+1}^{(q)'}$ is nontwisted and does not link with the other bands of $\mathscr{B}_1^{(q)'}$, Fig.25(b),(c) and deform $B_{2j}^{(q)'}$ along $B_{1p_1+1}^{(q)'}$ from Fig.25(c) to 25(d) and apply the deformation illustrated in Fig.24 to $B_{1p_1+1}^{(q)'}$ instead of $B_{11}^{(q)}$.

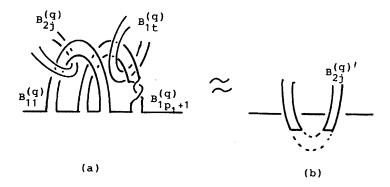
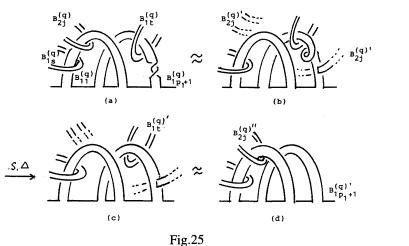


Fig.24

By doing the above discussions for each band of \mathscr{B}_1 , we obtain a link $L=K_1\cup$ K_2 such that L is self Δ -equivalent to ℓ and K_1 is the trivial knot. Moreover we easily see that L is the boundary link by the above deformatinos.

Now the proof of Lemma 4.7 is complete.



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