# ON É. CARTAN'S SPINOR THEORY 

Jun-ichi HANO

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## Introduction

This paper consists of expository remarks on the relevance of the manifold of maximal isotropic subspaces in $C^{2 n+1}$, with respect to a nondegenerate symmetric biliear form, to the spinors of $\mathfrak{g o}(2 n+1, \boldsymbol{C})$, introduced in Elie Cartan's lecture notes "Leçons sur la théorie des spineurs I, II (1938)" ([3]), Chapitre V.

Let us denote by $G^{*}$ the complex Lie group Spin $(2 n+1, \boldsymbol{C})$, the universal covering group of the complex special orthogonal group $S O(2 n+1, \boldsymbol{C})$, and consider the spin representation of $G^{*}$. The dimension of the representation space is $2^{n}$. We denot by $\boldsymbol{P}$ the complex projective space of all complex lines through the origin in the representation space, and by $\boldsymbol{V}$ the $G^{*}$-orbit in $\boldsymbol{P}$ through the point determined by the highest weight vectors. Since the center of $G^{*}$ leaves every point on $\boldsymbol{P}$ fixed, $\boldsymbol{V}$ is a quotient space of $S O(2 n+1, \boldsymbol{C})$.

Making use of the Clifford algebra ([1]), one can study the spin representation in detail and identify $\boldsymbol{V}$ with the space of all maximal isotropic subspaces in $\boldsymbol{C}^{2 n+1}$ with respect to a non-degenerate symmetric biliear form (cf. [6], Chap. IV, §9). Further, a concrete description of this projective imbedding $\boldsymbol{V} \rightarrow \boldsymbol{P}$ in terms of a suitable coordinate system of $\boldsymbol{V}$ can be obtained ([5], Lemma 2.1).

On the other hand, in his book, Elie Cartan introduces the above projective imbedding $\boldsymbol{V} \rightarrow \boldsymbol{P}$ in an explicit form without ado ([3] Chap. V, 92), and takes this setting as the starting point of his spinor theory. In this article, we attempt to shed light on this Cartan's approach.

We show first how this projective imbedding arises naturally within the context of the space $\boldsymbol{V}$ of all maxmal isotropic subspaces ( $\$ 1$ ), The process of determining coordinate transformations associated to a suitable coordinate chart covering of $\boldsymbol{V}$ leads to a holomorphic line bundle $\boldsymbol{F}$ over $\boldsymbol{V}$ with the property that, the square $\boldsymbol{F} \otimes \boldsymbol{F}$ is the $n$-th exterior product of the vector bundle whose fibre over a point $V$ is the vector space $V$ itself. The projective imbedding in question is determined by a vector space of holomorphic sections of the line bundle $\boldsymbol{F}^{-1}$. In this section, a certain determinant (Lemma in 1.5) plays a crucial role.

Next, we observe that the Lie algebra of holomorphic vector fields on $\boldsymbol{V}$ induced by the $S O(2 n+1, \boldsymbol{C})$-action is the restriction to $\boldsymbol{V}$ of a Lie algebra of infinitesimal projective transformations on the complex projective space $\boldsymbol{P}(\S 2)$. Thus, we have an isomorphism of $\mathfrak{s o}(2 n+1, \boldsymbol{C})$ into $\mathfrak{E l}\left(2^{n}, \boldsymbol{C}\right)$, which is the spin representation. This is one way to reach $\widehat{E}$. Cartan's original description of the spin representation ([2], XV. 37).

## 1. The manifold of maximal isotropic subspaces

1.1. The real cartesial space $\boldsymbol{R}^{m}$ is contained in the complex cartesial space $\boldsymbol{C}^{m}$ canonically and its standard inner product extends to a complex symmetric bilinear form on $\boldsymbol{C}^{m}$, which will be denoted by $S$.

A vector $v$ in $\boldsymbol{C}^{m}$ is said to be isotropic if $S(v, v)=0$, and a complex subspace $V$ of $\boldsymbol{C}^{m}$ is said to be isotropic if the restriction of $S$ to $V$ is identically zero. Suppose that a complex subspace $V$ is isotropic, then its complex conjugate subspace $\bar{V}$ is isotropic, and $V \cap \bar{V}=\{0\}$. Moreover, there is a unique real subspace $U$ in $\boldsymbol{R}^{m}$ whose complexfication $U^{c}$, i. e., the complex subspace spanned by $U$, is $V+\bar{V}$. Hence, $\operatorname{dim}_{R} U$ is even. As a special case of Witt's Theorem, it is known that every maximal isotropic subspace in $\boldsymbol{C}^{m}$ is of the same dimension $k$, where $k$ is the maximum integer such that $2 k \leq m$.

Let $V$ be the set of all maximal isotropic subspaces in $\boldsymbol{C}_{m}$ with rspect to the bilinear form $S$, ([3], [6] Chap. IV, 9). Depending on whether $m$ is even or odd, the description of the set is slightly different. In this papaer, we are concerned only the case where $m$ is odd.

Suppose that $m$ is odd and $m=2 n+1$. Using the standard basis $\left\{\varepsilon_{\lambda} ; \lambda=0,1\right.$, $\left.\ldots, n, 1^{\prime}, \ldots, n^{\prime}\right\}$ of $\boldsymbol{R}^{2 n+1}$, we put

$$
e_{0}=\varepsilon_{0}, e_{i}=(1 / \sqrt{2})\left(\varepsilon_{i}-\sqrt{-1} \varepsilon_{i^{\prime}}\right), e_{i^{\prime}}=(1 / \sqrt{2})\left(\varepsilon_{i}+\sqrt{-1} \varepsilon_{i^{\prime}}\right) .
$$

Then, $\left\{e_{\lambda} ; \lambda=0,1, \ldots, n, 1^{\prime}, \ldots, n^{\prime}\right\}$ is a basis of $C^{2 n+1}$, and

$$
S\left(\sum_{\lambda} a_{\lambda} e_{\lambda}, \Sigma_{\lambda} b_{\lambda} e_{\lambda}\right)=a_{0} b_{0}+\sum_{i} a_{i} b_{i^{\prime}}+\sum_{i} a_{i^{\prime}} b_{i}
$$

With this basis, the standard hermitian form is given by

$$
H\left(\sum_{\lambda} a_{\lambda} e_{\lambda}, \sum_{\lambda} b_{\lambda} e_{\lambda}\right)=\sum_{\lambda} a_{\lambda} \bar{b}_{\lambda}
$$

If $v=a_{0} e_{0}+\sum a_{i} e_{i}+\sum a_{i^{\prime}} e_{i^{\prime}}$, then $\bar{v}=a_{0} e_{0}+\sum \bar{a}_{i^{\prime}} e_{i}+\sum \bar{a}_{i} e_{i^{\prime}}$. Obviously, $H(u, v)=S(u, \bar{v}), u, v \in C^{2 n+1}$.
1.2. We shall prove that $V$ is a complex manifold in a primitive way; we first choose an open covering of $\boldsymbol{V}$ consisting of particular $2^{n}$ open subsets with complex coordinates, and then show that the coordnate transformations are holomorphic.

Let us denote by $N$ the set of integers $\{1, \ldots, n\}$ and by $\boldsymbol{N}$ the collection of all subsets in $N$, consisting of $2^{n}$ subsets including the empty set $\phi$. For $A, B \in \boldsymbol{N}, A$ $+B$ is the subset of those integers which belong to $A \cup B$ but not to $A \cap B$ ([4] Ch. II, §XI). This addition is not only commutative but also associative ;

$$
(A+B)+C=A+(B+C) \text { for } A, B, C \in \boldsymbol{N} .
$$

It is useful to notice that $A+B=C$ implies $A+C=B$.
Given $A, B \in N$, we denote by $p(A, B)$ the number of pairs $(i, j)$ such that $i \in A, j \in B$ and $i \geq j$, and put $\varepsilon(A, B)=(-1)^{p(A, B)}$. For $A, B, C \in \boldsymbol{N}$,

$$
\varepsilon(A, B+C)=\varepsilon(A, B) \varepsilon(A, C) \text { and } \varepsilon(A+B, C)=\varepsilon(A, C) \varepsilon(B, C)
$$

Let us denote by $\#(A)$ the nunber of integers in $\dot{A}$. Later we need the equality

$$
(-1)^{\sharp(A+C)}=(-1)^{\sharp(A+B)}(-1)^{\sharp(B+C)} \text {. }
$$

Now, we return to $\boldsymbol{V}$. Let $x_{0}, x_{1}, \ldots, x_{n}, x_{1^{\prime}}, \ldots, x_{n^{\prime}}$ be the complex coordinates of $\boldsymbol{C}^{2 n+1}$ with respect to the basis $\left\{e_{\lambda}\right\}$. These coordinate functions form the dual basis of $\left\{e_{\lambda}\right\}$.

Definition. Given $A=\left\{j_{1}, \ldots, j_{v}\right\} \in N, j_{1}<\ldots<j_{v}$, we denote by $A^{c}$ the complement of $A$ in the set $N$. Put $A^{C}=\left\{i_{1}, \ldots, i_{\mu}\right\}, i_{1}<\ldots<i_{k}$. Let $V_{A}$ be the set of all those maximal isotropic subspaces in $C^{2 n+1}$, on each of which the restrictions of $n$ linear functions

$$
x_{i_{1}}, \ldots, x_{i \mu}, x_{j_{1}}, \ldots, x_{j_{v^{\prime}}}
$$

are linearly independent. The subset $V_{A}$ will turn out to be open and dense in $V$.

The set $V$ is the union of these $2^{n}$ subsets $V_{A}, A \in N$.
Proof. Take an arbitrary $V \in V$. We use the same notation for the restriction of $x_{\lambda}$ to the subspace $V$. We will show that we can choose a basis $E$ of the dual space of $V$ consisting of $n$ restrictions from $\left\{x_{i}\right\}$ with the properties that $x_{0}$ does not belong to $E$ and that for each $i(1 \leq i \leq n)$, either $x_{i}$ or $x_{i^{\prime}}$ belong to $E$, but not both. This implies that $V$ belongs one of $V_{A}$.

Let $E^{\prime}$ be a basis of the dual of $V$ consisting of $n$ restrictions from $\left\{x_{\lambda}\right\}$. Suppose that $x_{0}$ is a member of the basis $E^{\prime}$. We express each $x_{\lambda} \notin E^{\prime}$ as a linear combination of these $n$ members in $E^{\prime}$, and obtain $n+1$ homogeneous linear equations whose solution space is $V$.

If $x_{0}$ does not appear in the above $n+1$ linear equations, then the vector $e_{0}$ is a solution of the these equations, and belongs to the isotropic subspace $V$. This is a contradibtion. Thus, the coefficient of $x_{0}$ is not zero in at least one linear equation, say $x_{\lambda}=\ldots, x_{\lambda} \notin E^{\prime}$ We replace $x_{0}$ by $x_{\lambda}$, obtaining a new basis $E$ not containing $x_{0}$.

Suppose that both $x_{k}$ and $x_{k^{\prime}}$ belong to $E$ for some $k$. Then, for some $l$, both $x_{l}$ and $x_{l^{\prime}}$ do not belong to the basis. As before, write each non-member $x_{\lambda}$ as a linear combination of members in the base $E$. Suppose that in the linear equations for all pairs $x_{l}$ and $x_{l^{\prime}}$ not belonging to $E$, both $x_{k}$ and $x_{k^{\prime}}$ do not appear. Then, we can find two vectors

$$
a_{0} e_{0}+e_{k}+\sum a_{\lambda} e_{\lambda} \text { and } b_{0} e_{0}+e_{k^{\prime}}+\sum b_{\lambda} e_{\lambda}
$$

satisfying the system of equations, where the index $\lambda$ in the summations runs through the collection of $\lambda$ such that $x_{\lambda} \notin \boldsymbol{E}$ and that if $\lambda=m$ then $x_{m} \in \boldsymbol{E}$, and if $\lambda=m^{\prime}$ then $x_{m} \in \boldsymbol{E}$. Since they are isotropic, $a_{0}=b_{0}=0$. We have

$$
S\left(e_{k}+\sum a_{\lambda} e_{\lambda}, e_{k^{\prime}}+\sum b_{\lambda} e_{\lambda}\right)=1
$$

This is a contradiction, as these vectors are in the isotropic subspace $V$.
Thus, for some $l$, both $x_{l}$ and $x_{l^{\prime}}$ do not belong to $E$ and at least in one of the two linear equations $x_{l}=\ldots$ and $x_{l^{\prime}} \ldots$ in the system, either $x_{k}$ or $x_{k^{\prime}}$ appears with non-zero coefficient. We can replace one of $x_{k}$ and $x_{k^{\prime}}$ by one of $x_{l}$ and $x_{l^{\prime}}$. Repeating this process, we obtain a desired basis. We have finished the proof.
1.3. The next step is to introduce a system of complex coordinates on each $V_{A}$. Let us begin with the simplest case. By definition, $V_{\phi}$ is the set of all maximal isotropic subspaces in $C^{2 n+1}$, on each of which the restrictions of $x_{1}, \ldots, x_{n}$ are linearly independent. A complex n-dimensional subspace $V$ of $C^{2 n+1}$ belongs to $V_{\phi}$ if and only if $V$ is the space of solutions of the following $n+1$ linear equations ([3], Ch. V, 92) :

$$
\begin{align*}
& x_{0}-(\sqrt{2}) \sum_{i=1}^{n} \xi_{i} x_{i}=0, \\
& x_{j^{\prime}}+(1 / \sqrt{2}) \xi_{j} x_{0}-\sum_{i=1}^{n} \xi_{j i} x_{i}=0 \quad(1 \leq j \leq n), \tag{1}
\end{align*}
$$

for some $\left(\xi_{i}, \xi_{j i}\right)$ in $\boldsymbol{C}^{n+n^{2}}$ satisfying the condition that

$$
\xi_{i j}+\xi_{j i}=0,(i, j=1, \ldots, n) .
$$

We regard $\xi=\left(\xi_{i}, \xi_{i j}\right), i<j$, as the coordinates of $V$. The map $V \mapsto \xi$ is a homeomorphism from $\boldsymbol{V}_{\boldsymbol{\phi}}$ onto $\boldsymbol{C}^{n(n+1) / 2}$.

Take an arbitrary $V \in V_{\phi}$ and let $\left(\xi_{i}, \xi_{i j}\right)$ be the coordinates of $V$ determined by the Cartan equations (1). For each $i(i=1, \ldots, n)$, there is a unique solution $v_{i}$ of the Cartan equations such that $x_{j}\left(v_{j}\right)=\delta_{i j}$. The $n$ column vectors $v_{1}, \ldots, v_{n}$ form a basis of $V$ dual to the basis $\left\{x_{1}, \ldots, x_{n}\right\}$. The $(2 n+1, n)$ matrix $\boldsymbol{M}_{\phi}(V)=\left(v_{1}, \ldots\right.$, $v_{n}$ ) is given by

$$
\left[\begin{array}{ccc}
\sqrt{2} \xi_{1} & \cdots & \sqrt{2} \xi_{n} \\
1 & \ddots & 0 \\
0 & & 1 \\
-\xi_{1}^{2} & -\xi_{j} \xi_{i}+\xi_{j i} & -\xi_{1} \xi_{n}+\xi_{1 n} \\
-\xi_{n} \xi_{1}+\xi_{n 1} & & -\xi_{n}^{2}
\end{array}\right]
$$

We will define coordinate functions on $V_{A}$ for an arbitrary $A \in \boldsymbol{N}$ in a similar way. Put $A=\left\{j_{1}, \cdots, j_{\nu}\right\}, j_{1}<\cdots<j_{\nu}$ and $A^{c}=\left\{i_{1}, \cdots, i_{\mu}\right\}, i_{1}<\cdots<i_{\mu}$. By definition, the restrictions of $n$ linear functions

$$
x_{i_{1}}, \cdots, x_{i \mu}, x_{j_{1}}, \cdots, x_{j_{\nu}}
$$

are linearly independent on each $V \in V_{A}$. As in the case of $V_{\Phi}$, an $n$ dimensional subspace $V$ belongs to $V_{A}$ if and only if $V$ is the solution space of the following $n+1$ linear equations :
$x_{0}-(\sqrt{2})\left(\sum_{a} \xi_{i_{a}}^{A} x_{i a}+\sum_{b} \xi_{j_{b}}^{A} x_{j_{b}}\right)=0$,
$x_{j_{b}}+(1 / \sqrt{2}) \xi_{j_{b}}^{A} x_{0}-\left(\sum_{a} \xi_{j_{b i a}}^{A} x_{i_{a}}+\sum_{d} \xi_{j_{b j} x_{d}}^{A} x_{i_{d}}\right)=0 \quad\left(j_{b} \in A\right)$,
$x_{i a}+(1 / \sqrt{2}) \xi_{i a}^{A} x_{0}-\left(\sum_{c} \xi_{i a i c}^{A} x_{i c}+\sum_{b} \xi_{i a j b}^{A} x_{j_{b}}\right)=0 \quad\left(i_{a} \in A^{c}\right)$,
for some constants $\xi_{i}^{A}(1 \leq i \leq n)$, $\xi_{j k}^{A}$ with $\xi_{j k}^{A}+\xi_{k j}^{A}=0(1 \leq j, k \leq n)$. The map $V$ $\mapsto\left(\cdots, \xi_{i}^{A}, \cdots, \xi_{i j}^{A}, \cdots\right)$ defines the coordinates of $V$, and the open subset $V_{A}$ is homeomorphic to $C^{n(n+1) / 2}$.

Take an arbitrary $V \in V_{A}$. For each $k(k=1, \cdots, n)$, let $\nu_{k}^{A}$ be a unique vector in $V$ satisfies the condition that

$$
x_{\lambda}\left(v_{k}^{A}\right)=\left\{\begin{array}{c}
1, \text { if } k \in A^{c} \text { and } \lambda=k \text { or if } k \in A \text { and } \lambda=k^{\prime}, \\
0, \text { otherwise. }
\end{array}\right.
$$

We denote by $\boldsymbol{M}_{A}(V)$ the matrix $\left(v_{1}^{A}, \cdots, v_{n}^{A}\right)$; the $\lambda$-th row of the matrix is ( $\delta_{k 1}, \cdots, \delta_{k n}$ ), if $\lambda=k \in A^{c}$ or if $\lambda=k^{\prime}$ and $k \in A$ ( $\delta$ is the Kronecker's delta), and $\left(-\xi_{k}^{A} \xi_{1}^{A}+\xi_{k 1}^{A}, \cdots,-\xi_{k}^{A} \xi_{n}^{A}+\xi_{k n}^{A}\right)$, if $\lambda=k \in A$ or if $\lambda=k^{\prime}$ and $k \in A^{c}$.
1.4. Suppose that $V \in V_{A} \cap V_{B}$. There exists a unique non-singular $(n, n)$-matrix $T_{A B}(V)$ such that

$$
\begin{equation*}
\boldsymbol{M}_{B}(V)=\boldsymbol{M}_{A}(V) T_{A B}(V) \tag{2}
\end{equation*}
$$

Obviously, $T_{B A}(V)=T_{A B}(V)^{-1}$, and if $V \in V_{A} \cap V_{B} \cap V_{C}, A, B, C \in N$, then

$$
\begin{equation*}
T_{A C}(V)=T_{A B}(V) \cdot T_{B C}(V) \tag{3}
\end{equation*}
$$

The complex vector bundle associated to the family of transition functions ( $V_{A}$ $\left.\cap \boldsymbol{V}_{B}, T_{A B}(V)\right), \boldsymbol{A}, \boldsymbol{B} \in \boldsymbol{N}$, is the vector bundle over $\boldsymbol{V}$ whose fibre over $V$ is the vector space $V$ isself.

Using the equality (2), we determine the inverse of $T_{A B}(V)$. For this purpose, we put $B=\left\{l_{1}, \cdots, l_{\rho}\right\}, l_{1}<\cdots<l_{\rho}$ and $B^{c}=\left\{k_{1}, \cdots, k_{\sigma}\right\}, k_{1}<\cdots<k_{\sigma}$. If $\lambda$ is either $k_{a}$ or $l_{b^{\prime}}, \boldsymbol{M}_{B}(V)_{\lambda m}=\delta_{|\lambda| m}, m=1, \cdots, n$, where $|\lambda|=k_{a}$ if $\lambda=k_{a}$, and $|\lambda|=l_{b}$ if $\lambda=$ $l_{b^{\prime}}$. From (2), it follows that

$$
\left(T_{A B}(V)^{-1}\right)_{|\lambda| m}=M_{A}(V)_{\lambda m}
$$

Therefore,

$$
\left(T_{A B}(V)^{-1}\right)_{t m}=\left\{\begin{array}{c}
-\xi_{t}^{A} \delta_{m}^{A}+\xi_{t m}^{A}, \text { if } t \in A+B,  \tag{4}\\
\delta_{t m}, \text { otherwise },
\end{array}\right.
$$

for $m=1, \cdots, n$.
Thus, the entries of $T_{A B}(V)$ are rational functions of the $\xi_{i}^{A}$,s and $\xi_{i j}^{A}$,s. From the equality (2), we obtain the following proposition :

On $V_{A} \cap V_{B}$, the coordinate functions $\xi_{i}^{B}$ 's and $\xi_{i j}^{B}$ 's are rational functions of the coordinate functions $\xi_{i}^{A}$ 's and $\xi_{i j}^{A}$ 's. Thus, $V$ is a complex manifold of dimension $n(n+1) / 2$.

We will determine explicitly these rational functions.
1.5. For the purpose we need some definitions ([3] Chap. IV, 92). Given a positive integer $m \geq 2$, let $x_{i}(1 \leq i \leq m)$ and $x_{i j}(1 \leq i, j \leq m)$ be variables such that $x_{i j}+x_{j i}=0, x_{i i}=0$. For $1 \leq i_{1}, \cdots, i_{2 k} \leq m, k \geq 2$, we put

$$
x_{i_{1} \cdots i_{2 k}}=\left(1 / 2^{k} k!\right) \sum \varepsilon\left(j_{1} \cdots j_{2 k}\right)\left(x_{j_{1} j_{2}}\right) \cdots\left(x_{j_{2 k-1} j_{2 k} k}\right),
$$

where in the summation $\left\{j_{1}, \cdots, j_{2 k}\right\}$ runs over all permutations of $i_{1}, \cdots, i_{2 k}$, and $\varepsilon\left(j_{1}, \cdots, j_{2 k}\right)$ denotes the sign of the permutation $j_{1}, \cdots, j_{2 k}$. Obviously, $x_{i_{1} \cdots i_{2 k}}$ is skew-symmetric with respect to the indecies, i.e., $x_{i_{1} \cdots i_{a} \cdots i_{b} \cdots i_{k}}=(-1) x_{i_{1} \cdots i_{b} \cdots i_{a} \cdots i_{k}}$. Another expression of $x_{i_{1} \ldots i_{2 k}}$ is

$$
\sum_{j_{2 a-1}<j_{2 a} ; j_{2}<\cdots<j_{2 k}} \varepsilon\left(j_{1} \cdots j_{2 k}\right)\left(x_{j_{1}, j_{2}}\right) \cdots\left(x_{j_{2 k-1}, j_{2 k}}\right)
$$

From this, it follows that

$$
\begin{equation*}
x_{i_{1} \cdots i_{2 k}}=\sum_{a=1}^{2 k-1}(-1)^{a-1} x_{i_{a} i_{2} k} x_{i_{1} \cdots i_{c}=\cdots i_{2 k-1}} . \tag{5}
\end{equation*}
$$

When the number of indeces is odd and equal to $2 k+1$, we put

$$
x_{i_{1} \cdots i_{2 k+1}}=\left(1 / 2^{k} k!\right) \sum \varepsilon\left(j_{1} \cdots j_{2 k+1}\right)\left(x_{j_{1}}\right)\left(x_{j_{2} j_{3}}\right) \cdots\left(x_{j_{2 k} j_{2 k+1}}\right) .
$$

Then,

$$
\begin{equation*}
x_{i_{1} \cdots i_{2 k+1}}=\sum_{a=1}^{2 k+1}(-1)^{a-1} x_{i_{a i} i \cdots \hat{i}_{e} \cdots i_{2 k+1}} . \tag{6}
\end{equation*}
$$

Again, $x_{i_{1} \ldots i_{2 k+1}}$ is skew-symmetric in indeces.
If $A=\left\{i_{1}, \cdots, i_{k}\right\}, 1 \leq i_{1}<\cdots<i_{k} \leq m$, we also denote by $x_{A}$ the function $x_{i_{1} \cdots i_{k}}$,
and if $A=\varnothing$, we put $x_{\varnothing}=1$.
The following lemma is crucial.
Lemma. Suppose that $1 \leq i_{1}, \cdots, i_{k} \leq m$. Form a ( $k, k$ )-matrix whose ( $a$, b)-entry is $-x_{i a} x_{i b}+x_{i a i b}$. Then,

$$
\operatorname{det}\left(-x_{i_{a}} x_{i_{b}}+x_{i_{a i b}}\right)=(-1)^{k}\left(x_{i_{1} \cdots i_{k}}\right)^{2} .
$$

We will carry out the computation of the above determinant at the end of this section.
1.6. We return to the manifold $\boldsymbol{V}$. On the open subset $V_{A}$, the function $\xi_{B}^{A}$ is defined in terms of the coordinate functions $\xi_{i j}^{A}$ 's by (5) or by (6) in the same way as $x_{B}$ is defined, for each $B \in \boldsymbol{N}$.

Applying the above lemma on the matrix $\left(T_{A B}\right)^{-1}$, whose form is given by (4), we have

$$
\begin{equation*}
\operatorname{det}\left(T_{A B}\right)^{-1}=(-1)^{\#(A+B)}\left(\xi_{A+B}^{A}\right)^{2} \text { on } V_{A} \cap V_{B} \tag{7}
\end{equation*}
$$

One implication of the above equality is that $V_{A} \cap V_{B}$ is the subset of $V_{A}$ where the function $\xi_{A+B}^{A}$ does not vanish, and is connected and dense in $\boldsymbol{V}$. This follows from the facts that $\xi_{A+B}^{A}$ is not identically zero and the subset of $V_{A}$ consisting of the points where the function does not vanish is connected and dense, and that the matrix $T_{A B}(V)$ is non-singular if and only if $V \in V_{A} \cap V_{B}$. Now, it is clear that the intersection of any number of open subsets $V_{A}$ 's is connected and dense in $\boldsymbol{V}$.

To state another implication of (7), we remark that from $T_{B A}=\left(T_{A B}\right)^{-1}$, it follows that

$$
\begin{equation*}
\left(\xi_{B+A}^{B}\right)^{-2}=\left(\xi_{A+B}^{A}\right)^{2} \text { on } \boldsymbol{V}_{A} \cap \boldsymbol{V}_{B} \tag{8}
\end{equation*}
$$

By the equalities (3), (7) and

$$
(-1)^{\sharp(A+C)}=(-1)^{\#(A+B)}(-1)^{\#(B+C)},
$$

we have

$$
\begin{equation*}
\left(\xi_{A+C}^{A}\right)^{-2}=\left(\xi_{A+B}^{A}\right)^{-2}\left(\xi_{B+C}^{B}\right)^{-2} \text { on } \boldsymbol{V}_{A} \cap \boldsymbol{V}_{B} \cap \boldsymbol{V}_{C}, \tag{9}
\end{equation*}
$$

The equalities (8) and (9) yield the following:
The family of the transition functions $\left(V_{A} \cap V_{B},\left(\xi_{A+B}^{A}\right)^{-2}\right), A, B \in N$, defines the holomorphic line bundle $L$ over $V$ whose fibre over a point $V \in V$ is the $n$-th exterior product $\wedge^{n}(V)$ of the vecor space $V$. (In fact, the set of transition functions ( $V_{A} \cap V_{B},(-1)^{*(A+B)}$ ) defines the trivial line bundle.)
1.7. The purpose of this section is to prove the following

Theorem 1. The set

$$
\left.\left\{\boldsymbol{V}_{A} \cap \boldsymbol{V}_{B}, \varepsilon(A, A+B)\left(\xi_{A+B}^{A}\right)^{-1}\right), A, B \in \boldsymbol{N}\right\}
$$

is a collection of transition functions and defines a holomorphic line bundle $\boldsymbol{F}$ over $\boldsymbol{V}$ such that $\boldsymbol{F}^{2}=\boldsymbol{L}$.

Proof. It suffices to show that

$$
\varepsilon(B, B+A)\left(\xi_{B+A}^{B}\right)^{-1}=\varepsilon(A, A+B)\left(\xi_{A+B}^{A}\right) \text { on } V_{A} \cap V_{B},
$$

and

$$
\begin{equation*}
\varepsilon(A, A+C)\left(\xi_{A+C}^{A}\right)^{-1}=\varepsilon(A, A+B)\left(\xi_{A+B}^{A}\right)^{-1} \varepsilon(B, B+C)\left(\xi_{B+C}^{B}\right)^{-1} \tag{10}
\end{equation*}
$$

on $V_{A} \cap \boldsymbol{V}_{B} \cap \boldsymbol{V}_{C}$, for $A, B, C \in \boldsymbol{N}$.
The first equality is a special case of the second one (10) where $C=A$, as $A$ $+C=\phi$ and $\xi_{\phi}^{A}=\varepsilon(A, \phi)=1$. In the second equality, we put $B+C=D(C=B$ $+D)$. We will verify the equality rewritten in the following form :

$$
\begin{equation*}
\varepsilon(B, D) \xi_{D}^{B}=\varepsilon(A, A+B+D) \xi_{A+B+D}^{A}\left(\varepsilon(A, A+B) \xi_{A+B}^{A}\right)^{-1} \tag{11}
\end{equation*}
$$

on $\boldsymbol{V}_{A} \cap \boldsymbol{V}_{B}$, for any $A, B \in \boldsymbol{N}$.
Furthermore, it is sufficient to prove the equality (10) for the case where $A=$ $\phi$. In fact, we can easily derive (11) from the equality

$$
\begin{equation*}
\varepsilon(B, D) \xi_{D}^{B}=\xi_{B+D}^{\phi}\left(\xi_{B}^{\phi}\right)^{-1} \text { on } \boldsymbol{V}_{\phi} \cap \boldsymbol{V}_{B}, \tag{12}
\end{equation*}
$$

for arbitrary $B, D \in N$. In the rest of the proof, we drop the superscript $\phi$ from the functions $\xi_{B}^{\phi}$.

By (9),

$$
\left(\xi_{D}^{B}\right)^{2}=\left(\xi_{B+D}\right)^{2}\left(\xi_{B}\right)^{-2} \text { on } \boldsymbol{V}_{\phi} \cap \boldsymbol{V}_{B}, \text { for any } D \in \boldsymbol{N} .
$$

Thus, the squares of both sides of the equality (12) are equal. Since the open set $\boldsymbol{V}_{\boldsymbol{\phi}} \cap \boldsymbol{V}_{B}$ is connected, it suffices to verify (11) at one convenient point in $\boldsymbol{V}_{\phi} \cap \boldsymbol{V}_{B}$ where both sides of the equality do not vanish. Let us choose a point $V_{1}$ in $V_{\phi}$ given by $\xi_{i}=1(1 \leq i \leq n), \xi_{j k}=1(1 \leq j<k<n)$. Then, $\xi_{D}\left(V_{1}\right)=1$ for every $D \in \boldsymbol{N}$. Hence $V_{1} \in \boldsymbol{V}_{\boldsymbol{\phi}} \cap \boldsymbol{V}_{\boldsymbol{B}}$ by the remark made right after (7). What we need is to show

$$
\begin{equation*}
\xi_{D}^{B}\left(V_{1}\right)=\varepsilon(B, D) \text { for every } D \in \boldsymbol{N} \tag{13}
\end{equation*}
$$

In order to prove the equality (13) for $D=\{i\}$, we look at the first rows of both side of the equality (2) $\boldsymbol{M}_{B}\left(V_{1}\right)=\boldsymbol{M}_{\phi}\left(V_{1}\right) T_{\phi B}\left(V_{1}\right)$. Then,

$$
\begin{equation*}
\left(\xi_{1}^{B}\left(V_{1}\right), \cdots, \xi_{n}^{B}\left(V_{1}\right)\right)\left(T_{A B}\left(V_{1}\right)\right)^{-1}=\left(\xi_{1}\left(V_{1}\right), \ldots, \xi_{n}\left(V_{1}\right)\right)=(1, \ldots, 1) . \tag{14}
\end{equation*}
$$

Using the expression of the matrix $\left(T_{A B}\right)^{-1}$ given by (4) and the equalities

$$
\left(\xi_{i} \xi_{j}+\xi_{i j}\right)\left(V_{1}\right)=\left\{\begin{array}{r}
0, \text { if } i<j, \\
-1, \text { if } i=j, \\
-2, \text { if } i>j,
\end{array}\right.
$$

we can easily show that $\xi\left\{\left(V_{1}\right)=\xi(B,\{i\}), 1 \leq i \leq n\right.$, satisfy (14). Thus, the equality (13) is verified for $D=\{i\}, 1 \leq i \leq n$.

Using (2) in a similar way, we prove the equality (13) at the point $V_{1}$ for $D$ $=\{i, j\}, 1 \leq i<j \leq n$. For an arbitrary $D$ with $\#(D)>2$, we verify (13) easily by making use of the definitions (5) and (6) for $\xi_{D}^{B}$ in $\mathbf{1 . 5}$ and a remark on $\varepsilon(B, *)$ in $\mathbf{1 . 2}$. We have finished the proof of the theorem.

Corollary 1. The cooordinate transformation on $V_{A} \cap V_{B}$ is given by

$$
\begin{aligned}
& \xi_{i}^{B}=\varepsilon(A+B,\{i\}) \xi_{A+B+\{i\}}^{A}\left(\xi_{A+B}^{A}\right)^{-1},(i=1, \ldots, n), \\
& \xi_{i j}^{B}=\varepsilon(A+B,\{i, j\}) \xi_{A+B+\{i j\}}^{A}\left(\xi_{A+B}^{A}\right)^{-1},(1 \leq i<j \leq n) .
\end{aligned}
$$

Proof. By putting $D=\{i\}$ and $\{i, j\}$ in (11), we obtain the above results.
Corollary 2. For each $C \in N$,

$$
\left\{\left(\boldsymbol{V}_{A}, \varepsilon(A, A+C) \xi_{A+c}^{A}\right), A \in \boldsymbol{N}\right\}
$$

defines a holomorphic section $S_{c}$ of the holomorphic line bundle $\boldsymbol{F}^{-1}$. The set of holomorphic sections $\left\{s_{c}, C \in \boldsymbol{N}\right\}$ determines a map c from $\boldsymbol{V}$ into the complex projective space $\boldsymbol{P}^{2 n-1}$. To be precise, if $V \in V_{A}$, the image $\iota(V) \in \boldsymbol{P}^{2 n-1}$ is the point with homogeneous coordinates

$$
\left[\varepsilon(A, A) \xi_{A}^{A}(V), \ldots, \varepsilon(A, A+C) \xi_{A+c}^{A}(V), \ldots, \varepsilon\left(A, A^{c}\right) \xi_{A c}^{A}(V)\right]
$$

The map $c$ is a holomorphic imbedding of the complex manifold $V$ into the complex projective space $\boldsymbol{P}^{2^{n-1}}$.

The restriction of c to $V_{\phi}$ is given by

$$
\begin{equation*}
V \mapsto\left[1, \ldots, \xi_{c}^{\phi}(V), \ldots, \xi^{\phi}(V)\right] . \tag{15}
\end{equation*}
$$

The expression (15) is found in Cartan's Lecture notes [3].
Proof. The equalities (10) shows that indeed $s_{c}$ is a secton of the line bundle $\boldsymbol{F}^{-1}$. Suppose that for $V \in V_{A}$ and $V^{\prime} \in V_{B}, \iota(V)=\iota\left(V^{\prime}\right)$. As $V \in V_{A}$, the $A$-th homogeneous coordinateof $\iota(V)$ is $\xi_{\phi}^{A}(V)=1$. As $V^{\prime} \in V_{B}$, the $A$-th homogeneous coordinate of the same point is $c \xi_{B+A}^{B}\left(V^{\prime}\right)$ with a non-zero constant $c$. Thus, $\xi_{B+A}^{B}$ $\left(V^{\prime}\right) \neq 0$, and hence $V^{\prime} \in V_{A}$ by the remark following (7). The map $\subset$ is obviously injective on $V_{A}$ by definition. We have shown that $V=V^{\prime}$. The holomorphic map $\iota$ is imbedding.
1.8. Proof of the lemma (1.5). We use the same notations as in $\mathbf{1 . 5}$. In order to prove the Lemma, it suffices to verify the equality

$$
\operatorname{det}\left|\begin{array}{ccc}
x_{1} x_{1} & & x_{1} x_{k}+x_{1 k} \\
& x_{i} x_{j}+x_{i j} & \\
x_{k} x_{1}+x_{k 1} & & x_{k} x_{k}
\end{array}\right|=\left(x_{1} \ldots k\right)^{2}
$$

We sketch the computation of the determinant. We begin with the case where $x_{1}=\ldots=x_{k}=0$, and the matrix is skew-symmetric. It is known that,

$$
\operatorname{det}\left(x_{i j}\right)=\left\{\begin{array}{c}
\left(x_{1 \ldots k}\right)^{2}, \text { if } k \text { is even, } \\
0, \text { if } k \text { is odd. }
\end{array}\right.
$$

Further, we need the determinant of the minor matrix $\Delta_{a b}$ obtained by deleting the $a$-th row and the $b$-th column of the matrix $\left(x_{i j}\right)$.

$$
\operatorname{det} \Delta_{a b}=\left\{\begin{array}{c}
0, \text { if } k \text { is even, } \\
x_{1 \ldots \hat{a} \ldots k} x_{1 \ldots \bar{b} \ldots k}, \text { if } k \text { is odd. }
\end{array}\right.
$$

One verifies the result by induction on $k$. Applying elementary column operations on the matrix $\Delta_{a b}$, one get a matrix of the form

$$
\left[\begin{array}{cc:ccc}
0 & x_{12} & * & \ldots & * \\
x_{21} & 0 & * & \ldots & * \\
\hdashline 0 & 0 & * & \\
& & \left(y_{i j}\right) &
\end{array}\right]
$$

where $y_{i j}=\left(x_{12} x_{i j}-x_{1 j} x_{i 2}-x_{1 i} x_{j 2}\right) / x_{12}$. Since $y_{i j}+y_{j i}=0$, one can use the induction hypothesis and obtains

$$
\operatorname{det} \Delta_{a b}=\left(x_{12}\right)^{2} y_{3 . . . \bar{a} \ldots k} y_{3 \ldots \bar{b} \ldots k} .
$$

Making use of the equality

$$
x_{12} y_{3 \ldots \hat{a} \ldots k}=x_{1 \ldots \hat{a} \ldots k}
$$

([7], p. 95), one finishes the computation.
Retern to the general case. Consider the determinamt in question as a polynomial of the $x_{i j}$ 's. The degree of the polynomial is at most $k$. We denote by $P v$ its homogeneous component of degree $v . \quad P_{0}=\operatorname{det}\left(x_{i} x_{j}\right)=0$. Further, one verifies easily that $P_{1}=\ldots=P_{k-2}=0$,

$$
P_{k-1}=\sum_{a, b}(-1)^{a+b} x_{a} x_{b} \Delta_{a b}=\left\{\begin{array}{c}
0, \text { if } n \text { is even, } \\
\left(x_{1 \cdots k}\right)^{2}, \text { if } n \text { is odd, and }
\end{array}\right.
$$

$$
P_{k}=\left[\begin{array}{c}
\left(x_{1 \ldots k}\right)^{2}, \text { if } n \text { is even, } \\
0, \text { if } n \text { is odd. }
\end{array}\right.
$$

We have finished the proof of the lemma.

## 2. The spin representation

2.1. The purpose of this section is to construct the spin representation of the complex orthogonal Lie algebra $\mathfrak{S D}(2 n+1, \boldsymbol{C})$ by making use of the projective immersion $\iota: V \rightarrow \boldsymbol{P}^{2^{n-1}}$ given in Corollary 2.

We donote by $G_{c}$ and by $G$ the matrix representations of the complex special orthogonal group $S O(2 n+1, C)$ and the special orthogonal group $S O(2 n+1)$ respectively, with respect to the basis $\left\{e_{\lambda}\right\}$ of $C^{2 n+1}$ defined in 1.1. The group $G_{c}$ is the set of all complex $(2 n+1,2 n+1)$ matrices with determinant equal to 1 and leaving the symmetric bilinear form $S$ invariant. Obviously, a matrix belonging to $G_{c}$ maps a maximal isotropic subspace with respect to $S$ onto a maximal isotropic subspace. The group $G$ is the intersection of $G_{c}$ and the unitary group $U(2 n+1)$.

As in the previous section, we donote $\boldsymbol{V}$ the set of all maximal isotropic subspaces in $\boldsymbol{C}^{2 n+1}$. The group $G$ acts on $\boldsymbol{V}$ transitively and hence so does the group $G_{c}$. We present a proof.

The subspace $V_{0}$ spanned by $e_{1}, \ldots, e_{n}$ is a maximal isotropic subspace. Take an maximal isotropic subspace $V$, and choose an orthonormal basis $\left\{f_{1}, \ldots, f_{n}\right\}$ of $V$ with respect to the hermitian form $H$ (1.1). Let $\bar{f}_{i}$ denote the complex conjugate of $f_{i}$ with respect to $\boldsymbol{R}^{2 n+1}$. Then there exists one and only one unit vector $f_{0}$ which is orthogonal to $f_{1}, \ldots, f_{n}, \bar{f}_{1}, \ldots, \bar{f}_{n}$ and satisfies the equality

$$
e_{0} \wedge e_{1} \wedge \ldots \wedge e_{n} \wedge \bar{e}_{1} \wedge \ldots \wedge \bar{e}_{n}=f_{0} \wedge f_{1} \wedge \ldots \wedge f_{n} \wedge \bar{f}_{1} \wedge \ldots \wedge \bar{f}_{n}
$$

Arranging these $2 n+1$ column vectors $f_{0}, f_{1}, \ldots, f_{n}, \bar{f}_{1}, \ldots, \bar{f}_{n}$, we obtain a matrix belonging to $G$, which maps $e_{i}$ to $f_{i}$ and $\bar{e}_{i}$ to $\bar{f}_{i}(1 \leq i \leq n)$, and hence $V_{0}$ to $V$. Thus, $G$ acts transitively on $V$.

Let $g$ and $g_{c}$ be the Lie algebras of $G$ and $G_{c}$ respectively. A complex $(2 n+1$, $2 n+1$ ) matrix $X$ belongs to $g_{c}$, if and only if its entries $X_{\lambda \mu}$ satisfy the following conditions:

$$
\begin{gathered}
X_{00}=0, X_{0 i^{\prime}}=-X_{i 0}, X_{0 i}=-X_{i^{\prime} 0,} X_{i^{\prime} j^{\prime}}=-X_{j i}, \\
X_{i j^{\prime}}=-X_{j i^{\prime}}, X_{i^{\prime} j}=-X_{j^{\prime} i},(i, j=1, \ldots, n),
\end{gathered}
$$

and $X$ belongs to $\mathfrak{g}$, if and only if $X$ is skew-hermitian and belongs to $g_{c}$.
2.2. The action of $G$ (resp. $G_{c}$ ) an $\boldsymbol{V}$ induces the Lie algebras of vector fields anti-isomorphic to $g$ (resp. $g_{c}$ ). Let us express these vector fields on $V_{\phi}$ in terms of the coordinates introduced in 1.2. Since we are only concerned with the open subset $V_{\phi}$ in this section, we delet the superscript $\phi$ from the notations of coordi-
nate functions.
Take an arbitrary $V \in V_{\phi}$ and let $\left(\xi_{i}, \xi_{i j}\right)$ be the coordinates of $V$ determined by the Cartan equations (1). As in 1.3, for each $i(1<i<n), v_{i}$ is the solution of the Cartan equations such that $x_{j}\left(v_{i}\right)=\delta_{i j}, 1<j<n$. The $n$ column vectors $v_{1}, \cdots$, $v_{n}$ form a basis of $V$.

Take $X \in g_{c}$, and put $\sigma_{t}=\exp t X$. Given $V \in V_{\phi}$, if the absolute value of $t$ is sufficiently small, $\sigma_{t} . V$ is in $V_{\phi}$, and is spanned by $\sigma_{t} . v_{1}, \cdots, \sigma_{t} . v_{n}$. The Cartan equations for $\sigma_{t} . v_{l}$ are

$$
\begin{aligned}
& x_{0}\left(\sigma_{t} \cdot v_{l}\right)-(1 / \sqrt{2}) \sum_{i=1}^{n} \xi_{i}\left(\sigma_{t} . V\right) x_{i}\left(\sigma_{t} \cdot v_{l}\right)=0, \\
& x_{j^{\prime}}\left(\sigma_{t} \cdot v_{l}\right)+\sqrt{2} \xi_{j}\left(\sigma_{t} . V\right) x_{0}\left(\sigma_{t} \cdot v_{l}\right)-\sum_{i=1}^{n} \xi_{i j}\left(\sigma_{t} . V\right) x_{i}\left(\sigma_{t} \cdot v_{l}\right)=0, \\
& (1 \leq j \leq n) .
\end{aligned}
$$

We differentiate both sides of the equalities at $t=0$ and obtain

$$
\begin{align*}
\dot{\xi}_{i j}(X) \equiv & \left(d / d t_{t=0}\right) \xi_{i j}\left(\sigma_{t} . V\right)  \tag{1}\\
= & (1 / \sqrt{2})\left\{\left(X_{00} \xi_{i}-X_{0 i} \xi_{j}+\sum_{k} X_{0 k^{\prime}}\left(\xi_{j} \xi_{k j}+\xi_{j} \xi_{k i}\right)\right\}\right.  \tag{2}\\
& +\sum_{k}\left(X_{k i} \xi_{j k}-X_{k j} \xi_{i k}\right)+X_{i^{\prime} j}-\sum_{k<l} X_{k l} \prime\left(\xi_{i k} \xi_{l j}-\xi_{i l} \xi_{k j}\right), \\
& (1 \leq i<j \leq n) .
\end{align*}
$$

The holomorphic vector field

$$
\begin{equation*}
\xi(X)=\sum_{i} \dot{\xi}_{i}(X) \partial / \partial \xi_{i}+\sum_{i<j} \dot{\xi}_{i j}(X) \partial / \partial \xi_{i j} \tag{3}
\end{equation*}
$$

is the ( 1,0 )-component of the real vector field on $\boldsymbol{V}_{\phi}$, induced by the one parameter group $\exp t X$. The correspondence $X \mapsto \xi(X)$ is a Lie algebra anti-isomorphism.
2.3. The next step is to lift the vector field $\xi(X)$ on $V \in g_{c}$, to an infinitesimal projective transformation $u(X)$ on $\boldsymbol{P}^{2^{n}}-1$ by making use of the projective immersion $t: \boldsymbol{V} \rightarrow \boldsymbol{P}^{2^{n-1}}$ defined in Corollary 2.

Let $\left[z_{A}\right], A \in \boldsymbol{N}$, be homogeneous coordinates on $\boldsymbol{P}^{2 n-1}$. We denote by $\boldsymbol{U}_{\phi}$ the open subset in $P^{2 n-1}$ defined by $z_{\phi} \neq 0$. Putting $u_{A}=z_{A} / z_{\phi}$, for $A \neq \phi$, we have a system of coordinates $\left(u_{A}\right)$ on $\boldsymbol{U}_{\phi}$. We denote by $\boldsymbol{N}^{\prime}$ the subset of $\boldsymbol{N}$ omitting the empty set $\phi$. It is convenient to stipulate that $\mu_{\phi}=1$. By (15),

$$
u_{A}(c(V))=\xi_{A}(V), A \in N^{\prime}, \text { for } V \in V_{\phi} .
$$

From the definition of $\xi_{i_{1} \cdots i_{k}}$ for $k \geq 3$ ((5) and (6) in 1.4), we have

$$
\partial \xi_{i_{1} \cdots i_{k}} / \partial \xi_{i}=\left\{\begin{array}{c}
-\varepsilon\left(\{i\},\left\{i_{1} \cdots i_{k}\right\}\right) \xi_{i, \cdots i \cdots i_{i}}, \quad \text { if } i \in\left\{i_{1} \cdots i_{k}\right\}, \text { and if } k \text { is odd, } \\
0, \text { otherwise, }
\end{array}\right.
$$

and

$$
\partial \xi_{i_{1} \cdots i_{k} /} / \partial \xi_{j k}=\left\{\begin{array}{c}
-\varepsilon\left(\{j k\},\left\{i_{1} \cdots i_{k}\right\}\right) \xi_{i \cdots, j \cdots \bar{j} \cdots i k}, \\
0, \text { otherwise },
\end{array}\right.
$$

where $j<k$.
Keeping these in mind, we define the following vector fields on $\boldsymbol{U}_{\phi}$ :

$$
\begin{equation*}
\partial / \partial u_{i}+\sum_{\left\{i _ { i } \cdots i _ { A } \supset \left\{i i_{2}, k \text { odd, } k \geq 3\right.\right.}-\varepsilon\left(\{i\},\left\{i_{1} \cdots i_{k}\right\}\right) u_{i \cdots \cdots i \cdots i_{k}} \partial / \partial u_{i_{1} \cdots i_{k}}, \tag{4}
\end{equation*}
$$

where $1 \leq i_{1}<\cdots<i_{k} \leq n,(1 \leq i \leq n)$, and

$$
\begin{equation*}
\partial / \partial u_{j k}+\sum_{\left\{i_{i} \cdots i_{k}\right\} \backslash\{j k\}, k \geq 3}-\varepsilon\left(\{j k\},\left\{i_{1} \cdots i_{k}\right\}\right) u_{i_{1} \cdots \cdots \cdots \cdots \cdots i_{k}} \partial / \partial u_{i_{1} \cdots i_{k}}, \tag{5}
\end{equation*}
$$

where $1<i_{1}<\cdots<i_{k} \leq n,(1 \leq j<k \leq n)$.
These vector fields are tangent to the image $\iota\left(\boldsymbol{V}_{\boldsymbol{\phi}}\right)$, and the vector field $\partial / \partial \xi_{i}$ (resp. $\partial / \partial \xi_{j k}$ ) is $\iota$-related to the vector field (4) (resp. (5)) on $\boldsymbol{U}_{\phi}$. A vector field $Y$ on $\boldsymbol{V}_{\phi}$ and a vector field $Z$ on $\boldsymbol{U}_{\phi}$ are said to be $\iota$-related, if at each point $p \in \boldsymbol{V}_{\phi}$, the image of $Y_{p}$ under the differential $\iota_{*}$ is $Z_{\iota(p)}$ ([4], Chap. III).
2.4. Given a $\left(2^{n}, 2^{n}\right)$-complex matrix $X^{*}$, the one-parameter group $\exp t X^{*}$ induces a vector field on $\boldsymbol{C}^{2^{n}}$ and on $\boldsymbol{P}^{2^{n}}-1$. If $X^{*}=\left(X^{*}{ }_{A B}\right)$, the ( 1,0 )-component of the corresponding vector field on $C^{2 n}$ is

$$
\sum_{A}\left(\sum_{B} X_{A B}^{*} z_{B}\right) \partial / \partial z_{A},
$$

and that of the vector field induced on $\boldsymbol{U}_{\boldsymbol{\phi}}$ is

$$
\begin{equation*}
\sum_{A \neq \phi}\left\{\sum_{B \in N}\left(X_{A B}^{*} u_{B}-X_{\phi B}^{*} u_{B} u_{A}\right)\right\} \partial / \partial u_{A} . \tag{6}
\end{equation*}
$$

The correspondence which assings to $X^{*} \in \mathfrak{\jmath l}\left(2^{n}, \boldsymbol{C}\right)$ the holomorphic vectorfield (6) on $\boldsymbol{U}_{\phi}$ is an anti-isomorphism.

If the vector field (6) vanishes on the submanifold $\boldsymbol{V}_{\boldsymbol{\phi}}$, then $X^{*}$ is a scalar matrix and its infinitesimal projective transformation is identically zero. This is an immediate consequence of the following fact:

Given $A \in \boldsymbol{N}^{\prime}$, the polynomials in the set

$$
\left\{\xi_{B} ; B \in N\right\} \cup\left\{\xi_{B} \xi_{A} ; B \in N^{\prime}\right\}
$$

are linearly independent over $\boldsymbol{C}$ on $\boldsymbol{V}_{\boldsymbol{\phi}}\left(=\boldsymbol{C}^{2 n+1}\right)$.
We prove this proposition by induction on $n$. When $n=2$, we verify it by inspection. Next, we show that the polynomials $\xi_{B}$ 's $B \in N$, are linearly independent by induction on $n$. Suppose that $\sum c_{B} \xi_{B}=0$. Apply $\partial / \partial \xi_{n}$ on both sides of the equality and obtain a linear equation involving only those $\xi_{c}$ 's, where $C=B$ $+\{i\}, n \in B$, and $\#(B)$ is odd, by the formulas for derivatives in 2.3. By induction hypothesis, $c_{B}=0$ if $n \in B$, and $\#(B)$ is odd. Do the same with $\partial / \partial \xi_{j n}, 1<j<n$. After thses operations, the original equality is reduced to $\sum c_{B^{\prime}} \xi_{B^{\prime}}=0$ where all $B^{\prime}$ $\subset\{1, \ldots, n-1\}$. By induction hypothesis $c_{B^{\prime}}=0$. Thus, $c_{B}=0$ for all $B$.

If a given set $A$ is $\{1, \ldots, n\}$, using degrees of polynomials and the linear
independence of $\left\{\xi_{B} ; B \in N\right\}$, we can prove the claim easily. If $A \neq\{1, \ldots, n\}$, say $A \subset\{1, \ldots, n-1\}$, applying $\partial / \partial \xi_{n}$ and $\partial / \partial \xi_{j n}$ in the same way as above, we prove the statement.

## 2.5.

Thorem 2. Given a matrix $X \in g_{c}$, there corresponds one and only one matrix $X^{*} \in \mathfrak{b l}\left(2^{n}, \boldsymbol{C}\right)$ such that the infinitesimal projective transformation induced by $X^{*}$ on $P^{2 n-1}$ is c-related to the vector fied $\xi(X)$ induced by $X$ on $V_{\phi}$ ((3)). The correspondence $X \mapsto X^{*}$ is an isomorphism and is the spin representation of the Lie algebra $\mathfrak{s o}(2 n+1, \boldsymbol{C})$. Under the isomorphism the image of g is contained in $\mathfrak{B u}\left(2^{n}\right)$.

Proof. We denote by $E_{\lambda \mu}$ the $(2 n+1,2 n+1)$ matrix whose $(\lambda, \mu)$-entry is 1 and all other entries are zero, for $\lambda, \mu=0,1, \ldots, 1^{\prime}, \ldots, n^{\prime}$, and similarly by $E_{A B}^{*}$ the $\left(2^{n}, 2^{n}\right)$ matrix whose ( $A, B$ )-entries is 1 and all other entries are zero, for $A$, $B \in N$. The Lie algebra $g_{c}$ is generated by

$$
E_{0 i}-E_{j^{\prime} 0}, E_{0 j}-E_{i 0}, 1 \leq i \leq n
$$

Let $X$ be one of these generators. First, we choose a vector field $u^{\prime}(X)$ on $\boldsymbol{U}_{\boldsymbol{\phi}}$ so that $\xi(X)$ and $u^{\prime}(X)$ are $c$-related. In the expression of $\xi(X)$ given by (1), (2) and (3), we substitute $\xi_{i}, \xi_{j k}, \partial / \partial \xi_{i}$ and $\partial / \partial \xi_{j k}$ by $u_{i}, u_{j k}$, the vector field (4) and the vector field (5) respectively, and obtain a desired $u^{\prime}(X)$. Next, adding to $u^{\prime}(X)$ a suitable vector field on $\boldsymbol{U}_{\phi}$ vanishing on the submanifold $V_{\phi}$, we have a vector field $u(X)$, which is not only $\iota$-related to $\xi(X)$ but also an infinitesimal projective transformation induced by some $X^{*} \in \mathfrak{z l}\left(2^{n}, \boldsymbol{C}\right)$. Once such $X^{*}$ is found, it is unique in virtue of $\mathbf{2 . 4}$.

$$
\text { If } \begin{aligned}
X= & E_{0 j}-E_{j^{\prime} 0}, \\
& \xi\left(E_{0 i}-E_{i^{\prime} 0}\right)=(1 / \sqrt{2})\left(\partial / \partial \xi_{i}+\sum_{j, j<i} \xi_{j} \partial / \partial \xi_{j i}-\sum_{j, i<j} \xi_{j} \partial / \partial \xi_{j i}\right) .
\end{aligned}
$$

On account of the equality for an even $k$

$$
\sum_{a=1}^{k}(-1)^{a-1} u_{i_{a}} u_{i_{1 \ldots \ldots} \ldots \ldots i_{s}}=0 \text { on } V_{\phi},
$$

we put

$$
\begin{aligned}
& u\left(E_{0 i}-E_{i^{\prime} 0}\right)= \\
& (1 / \sqrt{2}) \sum_{\left(i_{1} \ldots i_{i} \supset \supset(i)\right.}(-1)^{k} \varepsilon\left(\{i\},\left\{i_{1} \ldots i_{k}\right\}\right) u_{i_{1} \ldots \bar{i} \ldots i_{k}} \partial / \partial u_{i_{1} \ldots i_{k}} \\
& \left(1 \leq i_{1}<\ldots<i_{k} \leq n\right) .
\end{aligned}
$$

Then, $u\left(E_{0 i}-E_{i^{\prime} 0}\right)$ is the infinitesimal projective transformation associated to the ( $2^{n}, 2^{n}$ ) matrix

$$
\begin{equation*}
(1 \sqrt{2}) \sum_{A ; i \in A}(-1) \varepsilon(A,\{i\}) E^{*}{ }_{A A+\{i\rangle}, \tag{7}
\end{equation*}
$$

and is $\iota$-related to $\xi\left(E_{0 i}-E_{i^{\prime} 0}\right)$.
If $\quad X=E_{0 i^{\prime}}-E_{i 0}, \quad \xi\left(E_{0 i^{\prime}}-E_{i 0}\right)=(1 / \sqrt{2})\left\{\sum_{j}\left(\xi_{i j}+\xi_{j} \xi_{i}\right) \partial / \partial \xi_{j}+\sum_{j<k}\left(\xi_{j} \xi_{i k}\right.\right.$ $\left.\left.-\xi_{k} \xi_{i j}\right) \partial / \partial \xi_{j k}\right\}$.

Using the equality for an even $k$

$$
\sum_{a=1}^{k}(-1)^{a-1} u_{i_{a} l} u_{i_{1} \ldots i_{a} \ldots i_{k}}=u_{\iota} u_{i_{1} \ldots i_{k}}-u_{i_{1} \ldots i_{k} l} \text { on } V_{\phi},
$$

we put

$$
u\left(E_{0^{\prime}}-E_{i 0}\right)=(1 \sqrt{2}) \sum_{\left\{i_{1} \cdots i_{k}\right\}}\left(-u_{i_{1} \cdots i_{k} i}+u_{i} u_{i_{1} \ldots i_{k}}\right) \partial / \partial u_{i_{1} \cdots i_{k}}\left(1 \leq i_{1}<\ldots<i_{k} \leq n\right),
$$

which is $\iota$-related to $\xi\left(E_{0 i^{\prime}}-E_{i 0}\right)$, and is the infinitesimal projective transformation determined by the matrix

$$
\begin{equation*}
(1 / \sqrt{2}) \sum_{A \in \mathbf{N} ; i \notin A}(-1) \varepsilon(A,\{i\}) E_{A A+\{i\}}^{*} \tag{8}
\end{equation*}
$$

in $\mathfrak{s l}\left(2^{n}, \boldsymbol{C}\right)$.
Since the $\iota$-relatedness between $\xi(X)$ and $u(X)$ preserves the bracket product, it is obvious that there is a unique isomorphism $s$ from $g_{c}$ into $\mathfrak{B l}\left(2^{n}, \boldsymbol{C}\right)$ which maps $E_{0 i}-E_{i^{\prime} 0}$ to the matrix (8) and $E_{0 i^{\prime} .}-E_{i 0}$ to the matrix (9), $1 \leq i \leq n$.

In order to show that $s$ is the spin representaton, let

$$
H=\sqrt{-1} \sum_{i} \lambda_{i}\left(E_{i i}-E_{i^{\prime} i^{\prime}}\right), \lambda_{i} \in \boldsymbol{R} .
$$

The subspace spanned by these diagonal matrics is a Cartan subalgebra in $g_{c}$. From the equalitiy

$$
E_{i i}-E_{i^{\prime} i^{\prime}}=\left[E_{0 i}-E_{i^{\prime} 0}, E_{0 i^{\prime}}-E_{i 0}\right], 1 \leq i \leq n,
$$

in follows that

$$
\begin{equation*}
s(H)=\sqrt{-1} \sum_{\left\{i_{1} \cdots i_{k}\right\}}\left(1 / 2 \sum_{i=1}^{n} \lambda_{i}-\sum_{k=1}^{k} \lambda_{i a}\right) E_{\left\{i_{1} \cdots i_{k}\right\},\left\{i 1 \cdots i_{k}\right\}} . \tag{9}
\end{equation*}
$$

Thus, the highest weight of the representation $s$ is $(1 / 2) \sum_{i} \lambda_{i}$, and $s$ is the spin representation.

The compact form g is generated by

$$
\begin{aligned}
& -(1 / \sqrt{2})\left(E_{0 i}-E_{i^{\prime} 0}+E_{0 i^{\prime}}-E_{i 0}\right) \\
& (\sqrt{-1} / \sqrt{-2})\left(E_{0 i}-E_{i^{\prime} 0}+E_{0 i^{\prime}}-E_{i 0}\right), 1 \leq i \leq n,
\end{aligned}
$$

and their images under $s$ are

$$
\begin{aligned}
& (1 / 2) \sum_{A \in N} \varepsilon(A,\{i\}) E_{A A+i i\}}^{*}, \\
& (\sqrt{-1} / 2) \sum_{A \in N} \varepsilon(A,\{i\}) \delta(A,\{i\}) E_{A A+\{i\}}^{*},
\end{aligned}
$$

where $\delta(A,\{i\})=-1$ if $i \in A,=1$ if $i \notin A$, respectively, $1 \leq i \leq n$. These matrices are in $\mathfrak{S u}\left(2^{n}\right)$ and hence $s(\mathfrak{g}) \subset \mathfrak{S u}\left(2^{n}\right)$. We have finished the proof.
2.6. Under the spin representation $s: \mathfrak{S o}(2 n+1, \boldsymbol{C}) \rightarrow \mathfrak{g l}\left(2^{n}, \boldsymbol{C}\right)$,

$$
\begin{aligned}
& s\left(E_{0 i}-E_{i^{\prime} 0}\right)=(1 / \sqrt{2}) \sum_{A ; i \in A}(-1) \varepsilon(A,\{i\}) E_{A A+\{i\}}^{*}, 1 \leq i \leq n ; \\
& s\left(E_{0 i^{\prime}}-E_{i 0}\right)=(1 / \sqrt{2}) \sum_{A \in N ; i \notin A}(-1) \varepsilon(A,\{i\}) E_{A A+\{i j}^{*}, 1 \leq i \leq n ; \\
& s\left(E_{i i}-E_{i^{\prime} i^{\prime}}\right)=(1 / 2)\left\{-Z_{A \in N ; i \in A} E_{A A}^{*}+Z_{A \in N ; i \notin A} E_{A A}^{*}\right\}, 1 \leq i \leq n ; \\
& s\left(E_{j k}-E_{k^{\prime} j^{\prime}}\right)=Z_{A ; A \supset\{j k} \varepsilon(A,\{j k\})\left(E_{A+\{j\} A+\{k\}}^{*}-E_{A+\{k\} A+\{j\}}^{*}\right), 1 \leq j, k \leq n ; \\
& s\left(E_{j^{\prime} k}-E_{k^{\prime} j}\right)=Z_{A ; A \supset\{j k\}}(-1) \varepsilon(A,\{j k\}) E_{A A+\{j k\}}^{*}, 1 \leq j<k \leq n ; \\
& s\left(E_{j k^{\prime}}-E_{k j^{\prime}}\right)=Z_{A ; A \supset\{j k} \varepsilon(A,\{j k\}) E_{A+\{j k\} A}^{*}, 1 \leq j<k \leq n .
\end{aligned}
$$

2.7. The Clifford algebra $\mathfrak{a}$ over the vector space $\boldsymbol{R}^{2 n+1}$ equipped with the standard inner product is the quotient algebra of the tensor algebra over $\boldsymbol{R}^{2 n+1}$ modulo the ideal generated by $v \otimes v+(v, v) 1, v \in \boldsymbol{R}^{2 n+1}$ ([1], [3] and [6]). It is known that the spin representation is associated to a representation of the Clifford algebra $\mathfrak{a}$ on the same representation module $\boldsymbol{C}^{2 n}$. Here, we give its description. We use the same notation $s$ for the representation.

Let $\left\{\varepsilon_{\lambda}\right\}$ be the standard basis of $\boldsymbol{R}^{2 n+1}$ as in 1.1. The algebra $\mathfrak{a}$ is generated by 1 and the $\varepsilon_{\lambda}$ 's. We set

$$
\begin{aligned}
& s\left(\varepsilon_{0}\right)=\sqrt{-1}_{A \in N}(-1)^{\#(A)} E_{A A}^{*}, \\
& s\left(\varepsilon_{i}\right)=\sqrt{-1} Z_{A \in N}(-1)^{\#(A)} \varepsilon(A,\{i\}) E_{A A+\{i\}}^{*}, \\
& s\left(\varepsilon_{i^{\prime}}\right)=\sqrt{-1} Z_{A \in N}(-1)^{\#(A)} \varepsilon(A,\{i\}) \delta(A,\{i\}) E_{A A+\{i\}}^{*},
\end{aligned}
$$

where $\delta(A,\{i\})=-1$ if $i \in A,=1$ if $i \notin A(1 \leq i \leq n)$. Then, for $v=Z_{\lambda} v_{\lambda} \varepsilon_{\lambda} \in \boldsymbol{R}^{2 n+1}$, $s(v)^{2}+(v, v) \boldsymbol{I}=0$. Thus, $s$ is a representation of the algebra a. Moreover,

$$
s\left((1 / 2) \varepsilon_{0} e_{i}\right)=-s\left(E_{0 i}-E_{i^{\prime} 0}\right), \quad \text { and } \quad s\left((1 / 2) \varepsilon_{0} e_{i^{\prime}}\right)=-s\left(E_{0 i^{\prime}}-E_{i 0}\right)(1 \leq i \leq n)
$$

Hence, the spin representation is determined by the above representation of the algebra $\mathfrak{a}$.
2.8. Let $g_{1}$ be the subalgebra in $g$ consisting of matrices $X$ with

$$
X_{00}=X_{0 i^{i}}=X_{i 0}=X_{0 i}=X_{i^{\prime} 0}=0(i=1, \cdots, n) .
$$

The subalgebra is isomorphic to the orthogonal Lie algebra $\mathrm{o}(2 n)$. From the result 2.5, it is easy to show that the restriction to $g_{1}$ of the spinor representation of $\mathrm{o}(2 n$ $+1)$ on $\boldsymbol{C}^{2 \boldsymbol{n}}$ is the direct sum of the two inequivalent irreducible representations. The subspace in $C^{2^{n}}$ of vectors $z$ whose components $z_{A}=0$ if $\#(A)$ is odd, is an irreducible $g_{1}$-module whose highest weight is $(1 / 2)\left(\lambda_{1}+\cdots+\lambda_{n}\right)$; the subspace of vectors $z$ with $z_{A}=0$ if $\#(A)$ is even, is also irreducible and its highest weight is $(1 / 2)\left(\lambda_{1}+\cdots+\lambda_{n-1}-\lambda_{n}\right)$.

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Washington University<br>(jihano@ artsci.wustl.edu)

