

ALGORITHMS WITH MEDIANT CONVERGENTS AND THEIR METRICAL THEORY

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(Received February 16, 1988)

(Revised January 30, 1989)

0 Introduction

Let $x \in (0, 1)$ be an irrational number and $x = [0: a_1, a_2, \dots]$ be the continued fraction expansion of x . The principal convergents p_n/q_n of x are obtained by so called continued fraction transformation S as follows: let S be a transformation on $X = [0, 1)$ such that

$$Sx = \begin{cases} \frac{1}{x} - \left[\frac{1}{x} \right] & \text{if } x \in (0, 1) \\ 0 & \text{if } x = 0 \end{cases}$$

and put $a_n(x) = \left[\frac{1}{S^{n-1}x} \right]$, then the principal convergents p_n/q_n , $n=1, 2, \dots$ of α are given by

$$\begin{pmatrix} q_n & q_{n-1} \\ p_n & p_{n-1} \end{pmatrix} = \begin{pmatrix} a_1 & 1 \\ 1 & 0 \end{pmatrix} \cdots \begin{pmatrix} a_n & 1 \\ 1 & 0 \end{pmatrix}.$$

We know in [1] and [5] that the transformation S has an invariant measure ν with density

$$d\nu = \frac{1}{\log 2} \frac{dx}{(1+x)}$$

and that the natural extension \bar{S} of S on $\bar{X} = [0, 1) \times [0, 1)$ given by

$$\bar{S}(x, y) = \left(\frac{1}{x} - \left[\frac{1}{x} \right], \frac{1}{[1/x] + y} \right)$$

has an invariant measure $\bar{\nu}$ with density

$$d\bar{\nu} = \frac{1}{\log 2} \frac{dx dy}{(1+xy)^2},$$

and that the dynamical systems (X, S, ν) and $(\bar{X}, \bar{S}, \bar{\nu})$ are ergodic.

As an application of Birkhoff's ergodic theorem, we obtain several metrical results.

Theorem. For almost $x \in [0, 1)$,

- (1) $\lim_{n \rightarrow \infty} \frac{1}{n} \log q_n = \frac{\pi^2}{12 \log 2},$
- (2) $\lim_{n \rightarrow \infty} -\frac{1}{n} \log \left| x - \frac{p_n}{q_n} \right| = \frac{\pi^2}{6 \log 2},$
- (3) $\lim_{N \rightarrow \infty} \frac{1}{N} \#\{n \mid 0 \leq n \leq N, q_n | q_n x - p_n| < \lambda\}$
 $= \begin{cases} \frac{\lambda}{\log 2} & \text{for } 0 \leq \lambda < 1/2 \\ \frac{-\lambda + \log 2\lambda + 1}{\log 2} & \text{for } 1/2 \leq \lambda < 1, \end{cases}$
- (4) $\lim_{N \rightarrow \infty} \frac{\#\{(q, p) \mid q | qx - p| < \lambda, (q, p) = 1, q < N\}}{\log N} = \frac{\pi^2}{12} \lambda \quad \text{for } 0 < \lambda < 1/2.$

Remark. The first proof of the statement (1) and (2) is given by Kinchine, and the proof from ergodic theoretical standpoint is given by C. Ryll-Nardzewski in [7]. The statement (3) is obtained from the ergodicity of the natural extension of S (see [2] and [5]). The number theoretical proof of statement (4) is given by P. Erdős for "any" $\lambda > 0$ in [4], and an ergodic theoretical proof for $0 < \lambda < 1/2$ is found in [5].

In this paper, an algorithm T which induces the mediant convergents $\left\{ \frac{k p_n + p_{n-1}}{k q_n + q_{n-1}} \mid k = 1, \dots, a_{n+1} - 1, n = 1, 2 \dots \right\}$ of x is proposed as follows: let T be a transformation on X such that

$$Tx = \begin{cases} \frac{x}{1-x} & \text{if } x \in I_0 = [0, 1/2) \\ \frac{1-x}{x} & \text{if } x \in I_1 = [1/2, 1], \end{cases}$$

and put

$$\varepsilon_n(x) = \begin{cases} 0 & \text{if } T^{n-1}x \in I_0 \\ 1 & \text{if } T^{n-1}x \in I_1. \end{cases}$$

Let us define the matrices

$$A_0 = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad A_1 = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$$

and

$$\begin{pmatrix} r_n & s_n \\ t_n & u_n \end{pmatrix} = A_{\varepsilon_1} A_{\varepsilon_2} \cdots A_{\varepsilon_n}.$$

Then the convergents $w_n/v_n, n=1, 2, \dots$, where $v_n=r_n+s_n$ and $w_n=t_n+u_n$, are not only principal convergents of x but also mediant convergents of x . However, the mediant convergents transformation T has only a σ -finite but infinite invariant measure μ with density $d\mu=dx/x$, and so the ergodic theorem is not useful to observe the limit distribution. Therefore a modified algorithm T_1 , which is constructed by the jump transformation from T , is provided as follows:

$$T_1x = \begin{cases} \frac{1-x}{x} & \text{if } x \in [1/2, 1) \\ \frac{x}{1-x} & \text{if } x \in [1/3, 1/2) \\ \frac{x}{1-(k-2)x} & \text{if } x \in [1/(k+1), 1/k) \quad (k \geq 3). \end{cases}$$

We see in Theorem 2.1 the algorithm T_1 generates the approximation fractions $w_n^{(1)}/v_n^{(1)}$ of $x, n=1, 2, \dots$, which is not only the principal convergents but also the first mediant convergents $\frac{p_n+p_{n-1}}{q_n+q_{n-1}}$ and the last mediant convergents $\frac{p_n-p_{n-1}}{q_n-q_{n-1}}$.

We see also the transformation T_1 has a finite invariant measure μ_1 with density

$$d\mu_1 = \begin{cases} \frac{1}{2 \log 2} \frac{dx}{1+x} & \text{if } x \in [0, 1/3) \\ \frac{1}{2 \log 2} \frac{dx}{x} & \text{if } x \in [1/3, 1), \end{cases}$$

and the dynamical system is ergodic.

By constructing of natural wxtension of T_1 and applying ergodic theorem, we obtain the metrical results.

Result. For almost all $x \in [0, 1)$,

- (1) $\lim_{n \rightarrow \infty} \frac{1}{n} \log v_n^{(1)} = \frac{\pi^2}{24 \log 2},$
- (2) $\lim_{n \rightarrow \infty} -\frac{1}{n} \log \left| x - \frac{w_n^{(1)}}{v_n^{(1)}} \right| = \frac{\pi^2}{12 \log 2},$
- (3) $\lim_{N \rightarrow \infty} \frac{\#\{n | v_n^{(1)} | v_n^{(1)} x - w_n^{(1)} | < \lambda, 1 \leq n \leq N\}}{N} = \begin{cases} \frac{\lambda}{2 \log 2} & \text{for } \lambda \leq 1 \\ \frac{2-\lambda+2 \log \lambda}{2 \log 2} & \text{for } 1 \leq \lambda < 2, \end{cases}$
- (4) $\lim_{N \rightarrow \infty} \frac{\#\{(q, p) | q | qx - p | < \lambda, (q, p) = 1, q < N\}}{\log N} = \frac{\pi^2}{12} \lambda \quad \text{for } 0 < \lambda < 1.$

1 Mediant convergent transformation

In this section an algorithm which induces mediant convergents is proposed.

Let $X=[0, 1]$ and let the map T be defined on X by

$$(1,1) \quad Tx = \begin{cases} \frac{x}{1-x}, & \text{if } x \in I_0 \\ \frac{1-x}{x}, & \text{if } x \in I_1, \end{cases}$$

where $I_0=[0, 1/2]$ and $I_1=[1/2,1]$ (see figure 1).

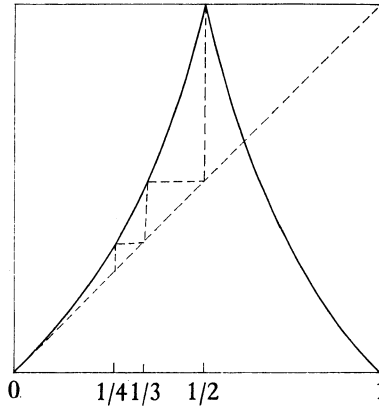


figure 1

We denote the inverse branches of T by

$$(1,2) \quad V_0(x) = \frac{x}{x+1} \quad \text{and} \quad V_1(x) = \frac{1}{x+1}.$$

All inverse branches are modular transformations. So we use the following matrix representations for them:

$$(1,3) \quad A_0 = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \left(= \frac{0+1 \cdot x}{1+1 \cdot x} \right) \quad \text{and} \quad A_1 = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \left(= \frac{1+0 \cdot x}{1+1 \cdot x} \right).$$

For irrational $x \in (0, 1)$ put

$$(1,4) \quad \varepsilon_n = \varepsilon_n(x) = \begin{cases} 0, & \text{if } T^{n-1}x \in I_0 \\ 1, & \text{if } T^{n-1}x \in I_1 \end{cases}$$

and

$$(1,5) \quad \begin{pmatrix} r_n & s_n \\ t_n & u_n \end{pmatrix} = \begin{pmatrix} r_n(x) & s_n(x) \\ t_n(x) & u_n(x) \end{pmatrix} = A_{\varepsilon_1(x)} A_{\varepsilon_2(x)} \cdots A_{\varepsilon_n(x)}.$$

Then we obtain the following.

Proposition 1.1. *For any irrational $x \in X$ we have*

$$(1,6) \quad x = \frac{t_n(x) + T^n x \cdot u_n(x)}{r_n(x) + T^n x \cdot s_n(x)}$$

Proof. Let $X_{\epsilon_1 \dots \epsilon_n}$ be a cylinder set of rank n , that is,

$$X_{\epsilon_1 \dots \epsilon_n} = \{x; T^{k-1}x \in I_{\epsilon_k} \quad 1 \leq k \leq n\}.$$

Then T^n is a bijective map from $X_{\epsilon_1 \dots \epsilon_n}$ to I , and the matrix representation of the inverse branch of T^n restricted to $X_{\epsilon_1 \dots \epsilon_n}$ is $\begin{pmatrix} r_n & s_n \\ t_n & u_n \end{pmatrix}$.

Let S be the simple continued fraction transformation:

$$(1,7) \quad Sx = \frac{1}{x} - k, \quad \text{if } x \in \left[\frac{1}{k+1}, \frac{1}{k} \right) \quad (k \geq 1)$$

We denote the inverse branches of S by

$$(1,8) \quad W_k(x) = \frac{1}{x+k}$$

and the associated matrices by

$$(1,9) \quad C_k = \begin{pmatrix} k & 1 \\ 1 & 0 \end{pmatrix} \quad \left(= \frac{1+0 \cdot x}{k+1 \cdot x} \right).$$

For each irrational $x \in (0, 1)$ put

$$a_n = a_n(x) = k, \quad \text{if } S^{n-1}x \in \left[\frac{1}{k+1}, \frac{1}{k} \right),$$

and

$$(1,10) \quad \begin{pmatrix} q_n & q_{n-1} \\ p_n & p_{n-1} \end{pmatrix} = \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix} \dots \begin{pmatrix} a_n(x) & 1 \\ 1 & 0 \end{pmatrix}$$

where

$$\begin{pmatrix} q_0 & q_{-1} \\ p_0 & p_{-1} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

The following formula is well known: For any irratoinal $x \in (0, 1)$

$$(1,11) \quad x = \frac{p_n + S^n x \cdot p_{n-1}}{q_n + S^n x \cdot q_{n-1}} \quad (n \geq 1).$$

The relation between T and S is given by

$$(1,12) \quad Sx = T^k x, \quad \text{if } x \in \left[\frac{1}{k+1}, \frac{1}{k} \right).$$

If $x \in \left[\frac{1}{k+1}, \frac{1}{k} \right)$, then $(\varepsilon_1(x), \dots, \varepsilon_k(x)) = (0, 0, \dots, 0, 1)$. Therefore the inverse map W_k of S is represented by

$$W_k = V_{\varepsilon_1(x)} V_{\varepsilon_2(x)} \cdots V_{\varepsilon_k(x)}$$

, that is,

$$(1,13) \quad \begin{pmatrix} k & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \cdots \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}.$$

Lemma 1.1. Put $j = j(n; x) = \#\{k; \varepsilon_k(x) = 1, k \leq n\}$ and $\bar{1} = \bar{1}(n; x) = \max\{k; \varepsilon_k(x) = 1, k \leq n\}$ where $\bar{1} = \bar{1}(n; x) = 0$ if $\{k; \varepsilon_k(x) = 1, k \leq n\} = \emptyset$. Then, for any irrational $x \in (0, 1)$

$$(1,14) \quad \begin{pmatrix} r_n(x) & s_n(x) \\ t_n(x) & u_n(x) \end{pmatrix} = \begin{pmatrix} q_j & q_{j-1} \\ p_j & p_{j-1} \end{pmatrix} \begin{pmatrix} 1 & n-1 \\ 0 & 1 \end{pmatrix} \quad (n \geq 1)$$

Proof. If $j=0$, then

$$\begin{aligned} \begin{pmatrix} r_n(x) & s_n(x) \\ t_n(x) & u_n(x) \end{pmatrix} &= \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \cdots \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}}_n = \begin{pmatrix} 1 & n \\ 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} q_0 & q_{-1} \\ p_0 & p_{-1} \end{pmatrix} \begin{pmatrix} 1 & n \\ 0 & 1 \end{pmatrix} \end{aligned}$$

If $j \geq 1$, then $S^j x = T^{a_1 + \dots + a_j} x$ and $T^n x = T^{n-1}(T^1 x) = T^{n-1}(S^j x)$. Therefore, by (1,13), the representation of the inverse branch of T^n is

$$\begin{pmatrix} a_1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_2 & 0 \\ 1 & 1 \end{pmatrix} \cdots \begin{pmatrix} a_j & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & n-1 \\ 0 & 1 \end{pmatrix}.$$

The fraction $\frac{p_n}{q_n}$ is called the n -th principal convergent of x and the fractions

$\left\{ \frac{\lambda \cdot p_n + p_{n-1}}{\lambda \cdot q_n + q_{n-1}}; \lambda = 1, 2, \dots, a_{n+1} - 1 \right\}$ are called mediant convergents of $\frac{p_n}{q_n}$.

Theorem 1.1. Put $v_n(x) = r_n(x) + s_n(x)$ and $w_n(x) = t_n(x) + u_n(x)$. Then for any irrational $x \in (0, 1)$

$$\left\{ \frac{w_n}{v_n}; n \geq 1 \right\} = \bigcup_{k=0}^{\infty} \left\{ \frac{\lambda \cdot p_k + p_{k-1}}{\lambda \cdot q_k + q_{k-1}}; \lambda = 1, 2, \dots, a_{k+1} \right\}.$$

Proof. Put

$$\begin{aligned} \bar{1} &= \bar{1}(n; x) = \min_k \{k; \varepsilon_k(x) = 1, n < k\} \\ \underline{1} &= \underline{1}(n; x) = \max_k \{k; \varepsilon_k(x) = 1, k \leq n\}. \end{aligned}$$

Then from (1,12) we have

$$\bar{1}-\underline{1} = a_{j+1}(x).$$

By the lemma 1.1.

$$\begin{pmatrix} r_n + s_n \\ t_n + u_n \end{pmatrix} = \begin{pmatrix} (n-\underline{1}+1)q_j + q_{j-1} \\ (n-\underline{1}+1)p_j + p_{j-1} \end{pmatrix}.$$

Putting $\lambda = n-\underline{1}+1$, we have $1 \leq \lambda \leq a_{j+1}$ and so we obtain the result.

We now call a fraction

$$\frac{w_n}{v_n} = \frac{t_n(x) + u_n(x)}{r_n(x) + s_n(x)}$$

the n -th mediant convergent of x , and the algorithm (X, T) the mediant convergent transformation. We prepare some formulae concerning the approximation.

Proposition 1.2. For any irrational $x \in (0, 1)$

$$(1,15) \quad \left| x - \frac{w_n(x)}{v_n(x)} \right| = \frac{1 - T^n x}{v_n^2(x) \left\{ \frac{r_n}{v_n} (1 - T^n x) + T^n x \right\}}.$$

In particular,

$$\left| x - \frac{w_n(x)}{v_n(x)} \right| \quad \text{and} \quad |v_n(x) \cdot x - w_n(x)|$$

converge to 0 as $n \rightarrow \infty$.

Proof. By proposition 1.1. and since $r_n u_n - s_n t_n = \pm 1$, we have

$$\begin{aligned} \left| x - \frac{w_n}{v_n} \right| &= \left| \frac{t_n + T^n x \cdot u_n}{r_n + T^n x \cdot s_n} - \frac{t_n + u_n}{r_n + s_n} \right| \\ &= \frac{1 - T^n x}{v_n (r_n + T^n x \cdot s_n)}. \end{aligned}$$

From $r_n \nearrow \infty$ and the definition of v_n, w_n , we obtain the proposition.

For any 0-1 sequence $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$, let φ_{ε_i} be the affine transformation of the (ξ_{i-1}, η_{i-1}) -plane into the (ξ_i, η_i) -plane such that

$$\varphi_{\varepsilon_i}: \begin{pmatrix} \xi_{i-1} \\ \eta_{i-1} \end{pmatrix} = A_{\varepsilon_i} \begin{pmatrix} \xi_i \\ \eta_i \end{pmatrix}.$$

Then we have

Proposition 1.3. *For any irrational $x \in (0, 1)$*

$$(1,16) \quad |x \cdot \xi_0 - \eta_0| = g(x)g(Tx) \cdots g(T^{n-1}x) |T^n x \cdot \xi_n - \eta_n|.$$

In particular,

$$(1,17) \quad |x \cdot v_n - w_n| = g(x)g(Tx) \cdots g(T^{n-1}x)(1 - T^n x)$$

where

$$g(x) = \begin{cases} 1-x, & \text{if } x \in I_0 \\ x, & \text{if } x \in I_1. \end{cases}$$

Proof. By $\varphi_{e_1(x)}$ the linear form $x\xi_0 - \eta_0$ is transformed into the following linear form:

$$x \cdot \xi_0 - \eta_0 = \begin{cases} (1-x)(Tx \cdot \xi_1 - \eta_1), & \text{if } x \in I_0 \\ -x(Tx \cdot \xi_1 - \eta_1), & \text{if } x \in I_1. \end{cases}$$

This shows that formula (1,16) is valid for $n=1$. The general case is obtained by induction. Using the relation

$$\begin{pmatrix} \xi_0 \\ \eta_0 \end{pmatrix} = A_{e_1(x)} \cdots A_{e_n(x)} \begin{pmatrix} \xi_n \\ \eta_n \end{pmatrix} = \begin{pmatrix} r_n & s_n \\ t_n & u_n \end{pmatrix} \begin{pmatrix} \xi_n \\ \eta_n \end{pmatrix}.$$

We obtain (1,17) by putting $(\xi_n, \eta_n) = (1, 1)$.

It is well known that the simple continued fraction transformation (X, S) has the invariant measure ν with density $d\nu = \frac{1}{\log 2} \frac{dx}{1+x}$ and that the dynamical system (X, S, ν) is ergodic. The following was proved in [3] and [6].

Theorem. *The mediant convergent transformation (X, T) has a σ -finite invariant measure μ :*

$$d\mu = \frac{dx}{x}$$

and the dynamical system (X, T, μ) is ergodic.

This can also be seen by using a suitable jump transformation [9].

Here we introduce the natural extension of (X, T) . We will see afterwards that the natural extension is useful for number theoretical considerations.

Let $\bar{X} = [0, 1] \times [0, 1]$ and let the map \bar{T} be defined on \bar{X} by

$$(1,18) \quad \bar{T}(x, y) = \begin{cases} \left(\frac{x}{1-x}, \frac{y}{1+y} \right), & \text{if } x \in I_0 \\ \left(\frac{1-x}{x}, \frac{1}{1+y} \right), & \text{if } x \in I_1 \\ = \begin{cases} (Tx, V_0y), & \text{if } x \in I_0 \\ (Tx, V_0y), & \text{if } x \in I_1. \end{cases} \end{cases}$$

Then we see the map \bar{T} is one to one and onto.

Theorem 1.3. *Let $\bar{\mu}$ be the measure on \bar{X} given by*

$$(1,19) \quad d\bar{\mu} = \frac{dx dy}{(x+y-xy)^2}.$$

Then $\bar{\mu}$ is a σ -finite invariant measure for \bar{T} , and the natural extension $(\bar{X}, \bar{T}, \bar{\mu})$ is ergodic.

Proof. The Jacobian $J(\bar{T})$ of \bar{T} is

$$J(\bar{T}) = \begin{cases} \frac{1}{(1-x)^2} \cdot \frac{1}{(1+y)^2}, & \text{if } x \in I_0 \\ \frac{1}{x^2} \cdot \frac{1}{(1+y)^2}, & \text{if } x \in I_1. \end{cases}$$

Putting $k(x, y) = \frac{1}{(x+y-xy)^2}$, it is not difficult to see that the following equation holds:

$$k(\bar{T}(x, y))J(\bar{T}) = k(x, y).$$

Hence $\bar{\mu}$ is an invariant measure for \bar{T} . The ergodicity of $(\bar{X}, \bar{T}, \bar{\mu})$ is due to [6].

Sub-lemma. *Let $(\varepsilon_1, \dots, \varepsilon_n)$ be a 0-1 sequence. Put*

$$\begin{pmatrix} r_n & s_n \\ t_n & u_n \end{pmatrix} = A_{\varepsilon_1} \cdots A_{\varepsilon_n}$$

and

$$(1,20) \quad \begin{pmatrix} r'_n & s'_n \\ t'_n & u'_n \end{pmatrix} = A_{\varepsilon_n} \cdots A_{\varepsilon_1}.$$

Then

$$(1,21) \quad t'_n + u'_n = r_n \quad \text{and} \quad r'_n + s'_n = r_n + s_n.$$

The proof is easily obtained by induction.

Fundamental-lemma.

$$\bar{T}^n(x, 1) = \left(T^n x, \frac{r_n}{r_n + s_n} \right).$$

Proof. By the definition of \bar{T} and notation (1,20), we have

$$\bar{T}^n(x, y) = \left(T^n x, \frac{t'_n + u'_n y}{r'_n + s'_n y} \right).$$

In particular,

$$\bar{T}^n(x, 1) = \left(T^n x, \frac{r_n}{r_n + s_n} \right) \quad (\text{sub-lemma}).$$

We know the following basic properties:

(1) If $q|qx-p| < 1/2$ and $(q, p)=1$, then $\frac{p}{q}$ is a principal convergent of x , i.e.,

there exists k such that $\frac{p}{q} = \frac{p_k}{q_k}$ (Legendre's theorem [8]).

(2) If $q|qx-p| \leq 1$ and $(q, p)=1$, then $\frac{p}{q}$ is a principal or a mediant convergent of x .

Conversely, for all irrational x

(3) $q_n |q_n x - p_n| < 1$ for all $n \geq 1$.

For the mediant convergents $\frac{w_n}{v_n}$, the values $v_n |v_n \cdot x - w_n|$ are unbounded in general. In fact, put

$$(1,22) \quad f(x, y) = \frac{1-x}{y(1-x)+x} \quad \text{on } \bar{X}.$$

Then from proposition 1.2. and the fundamental lemma we have

$$(1,23) \quad v_n |v_n \cdot x - w_n| = f(\bar{T}^n(x, 1)) \quad n \geq 1.$$

This suggests that the values $v_n |v_n \cdot x - w_n|$ are unbounded for some x .

Let $D_\lambda (\lambda > 0)$ be the subset of \bar{X} defined by

$$D_\lambda = \{(x, y) \in \bar{X}; f(x, y) \leq \lambda\}.$$

Then we have

Proposition 1.4. For any irrational $x \in (0, 1)$

$$v_n |v_n \cdot x - w_n| \leq \lambda \quad \text{iff} \quad \bar{T}^n(x, 1) \in D_\lambda.$$

2 Nearest mediant convergent transformation

In this section another algorithm which will be called nearest mediant convergents transformation is proposed.

Let $X=[0, 1]$ and let the map T_1 be defined on X by

$$(2,1) \quad T_1x = \begin{cases} \frac{1-x}{x}, & \text{if } x \in J_1 \\ \frac{x}{1-x}, & \text{if } x \in J_2 \\ \frac{x}{1-(k-2)x}, & \text{if } x \in J_k \quad (k \geq 3) \end{cases}$$

where

$$J_n = \left[\frac{1}{n+1}, \frac{1}{n} \right)$$

(see figure 2).

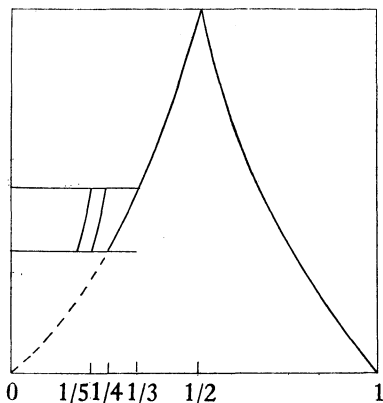


figure 2

The relations between the maps T , S and T_1 are as follows:

$$(2,2) \quad T_1x = \begin{cases} Tx, & \text{if } x \in J_1 \cup J_2 \\ T^{k-2}x, & \text{if } x \in \bigcup_{k \geq 3} J_k \end{cases}$$

and

$$(2,3) \quad Sx = \begin{cases} T_1x, & \text{if } x \in J_1 \\ T_1^2x, & \text{if } x \in J_2 \\ T_1^3x, & \text{if } x \in \bigcup_{k \geq 3} J_k. \end{cases}$$

We denote the inverse branches of T_1 by

$$(2,4) \quad \begin{aligned} Z_1(x) &= \frac{1}{1+x} & x \in [0, 1] \\ Z_2(x) &= \frac{x}{1+x} & x \in [1/2, 1] \end{aligned}$$

and

$$Z_k(x) = \frac{x}{1+(k-2)x} \quad x \in [1/3, 1/2] \quad (k \geq 3)$$

and their associated matrices by

$$(2,5) \quad B_1 = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad B_2 = \begin{pmatrix} 1 & k-2 \\ 0 & 1 \end{pmatrix}.$$

Then, the relations (2,2) and (2,3) have the representations:

$$(2,6) \quad B_k = \begin{cases} A_1, & \text{if } k=1 \\ A_0, & \text{if } k=2 \\ \underbrace{A_0 \cdots A_0}_{k-2}, & \text{if } k \geq 3 \end{cases}$$

and

$$(2,7) \quad C_k = \begin{pmatrix} k & 1 \\ 1 & 0 \end{pmatrix} = \begin{cases} B_1, & \text{if } k=1 \\ B_2 B_1, & \text{if } k=2 \\ B_k B_2 B_1, & \text{if } k \geq 3. \end{cases}$$

Put $\delta_n = \delta_n(x) = k$, if $T_1^{n-1}x \in J_k$. Then the sequences of digits δ_n have the following Markov property:

$$(2,8) \quad \begin{aligned} &\text{if } \delta_i \geq 3, && \text{then } \delta_{i+1} = 2 \\ &\text{if } \delta_i = 2, && \text{then } \delta_{i+1} = 1. \\ &\text{if } \delta_i = 1, && \text{then there is no restriction on } \delta_{i+1}. \end{aligned}$$

Let the 2×2 matrix $\begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix}$ be defined by

$$(2,9) \quad \begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix} = B_{\delta_1(x)} B_{\delta_2(x)} \cdots B_{\delta_n(x)}.$$

Then we have the following.

Proposition 2.1. For any irrational $x \in (0, 1)$

$$(2,10) \quad x = \frac{t_n^{(1)} + u_n^{(1)} \cdot T_1^n x}{r_n^{(1)} + s_n^{(1)} \cdot T_1^n x}$$

The proof is easily obtained by using the identity:

$$x = Z_{\delta_1(x)}(Z_{\delta_2(x)} \cdots Z_{\delta_n(x)}(T_1^n x)) .$$

Sub-lemma

- (i) If $x \in J_k$ ($k \geq 3$), then
 - (1) $a_1(x) = \delta_1(x) = k, \delta_2(x) = 2, \delta_3(x) = 1$
 - (2) $T_1^3 x = Sx$
 - (3) $B_{\delta_1(x)} B_{\delta_2(x)} B_{\delta_3(x)} = \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix}$
- (ii) If $x \in J_2$, then
 - (1) $a_1(x) = \delta_1(x) = 2, \delta_2(x) = 1$
 - (2) $T_1^2 x = Sx$
 - (3) $B_{\delta_1(x)} B_{\delta_2(x)} = \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix}$
- (iii) If $x \in J_1$, then
 - (1) $a_1(x) = \delta_1(x) = 1$
 - (2) $T_1 x = Sx$
 - (3) $B_{\delta_1(x)} = \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix}$.

Lemma 2.1. Let $j = j(n : x) = \# \{k : \delta_k(x) = 1, k \leq n\}$ and $l = l(n : x) = \max \{k : \delta_k(x) = 1, k \leq n\}$. Then the matrix $\begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix}$ has one of the following forms:

$$\begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix} = \begin{cases} \begin{pmatrix} q_j & q_{j-1} \\ p_j & p_{j-1} \end{pmatrix}, & \text{if } n=l \\ \begin{pmatrix} q_j & q_{j-1} \\ p_j & p_{j-1} \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, & \text{if } n-l=1 \text{ and } S^j x \in J_2 \\ \begin{pmatrix} q_j & q_{j-1} \\ p_j & p_{j-1} \end{pmatrix} \begin{pmatrix} 1 & a_{j+1}-2 \\ 0 & 1 \end{pmatrix}, & \text{if } n-l=1 \text{ and } S^j x \in J_k \\ \begin{pmatrix} q_j & q_{j-1} \\ p_j & p_{j-1} \end{pmatrix} \begin{pmatrix} 1 & a_{j+1}-2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, & \text{if } n-l=2 \text{ and } S^j x \in J_k \end{cases}$$

Proof. From the sublemma we have

$$B_{\delta_1(x)} B_{\delta_2(x)} \cdots B_{\delta_n(x)} = \begin{cases} \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix} B_{\delta_4(x)} \cdots B_{\delta_n(x)}, & \text{if } x \in J_k \\ \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix} B_{\delta_3(x)} \cdots B_{\delta_n(x)}, & \text{if } x \in J_2 \\ \begin{pmatrix} a_1(x) & 1 \\ 1 & 0 \end{pmatrix} B_{\delta_2(x)} \cdots B_{\delta_n(x)}, & \text{if } x \in J_1. \end{cases}$$

Repeating this procedure with x replaced by Sx, S^2x, \dots, S^jx and so on, we obtain the lemma. For $j=0$, lemma 2.1. is also valid.

Theorem 2.1. Put $v_n^{(1)} = r_n^{(1)}(x) + s_n^{(1)}(x)$ and $w_n^{(1)} = t_n^{(1)}(x) + u_n^{(1)}(x)$. Then for any irrational $x \in (0, 1)$

$$\left\{ \frac{w_n^{(1)}}{v_n^{(1)}}; n \geq 1 \right\} = \bigcup_{k=1}^{\infty} \left\{ \frac{p_k - p_{k-1}}{q_k - q_{k-1}}, \frac{p_k}{q_k}, \frac{p_k + p_{k-1}}{q_k + q_{k-1}} \right\}.$$

Proof. By lemma 2.1.

$$\frac{w_n^{(1)}}{v_n^{(1)}} = \begin{cases} \frac{p_j + p_{j-1}}{q_j + q_{j-1}}, & \text{if } n=l \\ \frac{2p_j + p_{j-1}}{2q_j + q_{j-1}} = \frac{p_{j+1}}{q_{j+1}}, & \text{if } n-l=1 \text{ and } S^j x \in J_2, \\ \frac{(a_{j+1}-1)p_j + p_{j-1}}{(a_{j+1}-1)q_j + q_{j-1}} = \frac{p_{j+1} - p_j}{q_{j+1} - q_j}, & \text{if } n-l=1 \text{ and } S^j x \in J_k \\ \frac{p_{j+1}}{q_{j+1}}, & \text{if } n-l=2 \text{ and } S^j x \in J_k \end{cases}$$

Therefore for any $n \geq 1$.

$$\frac{w_n^{(1)}}{v_n^{(1)}} \in \bigcup_{k=1}^{\infty} \left\{ \frac{p_k - p_{k-1}}{q_k - q_{k-1}}, \frac{p_k}{q_k}, \frac{p_k + p_{k-1}}{q_k + q_{k-1}} \right\}.$$

Conversely, from (2,7), for any $\frac{p_k + p_{k-1}}{q_k + q_{k-1}}$ there exists n such that

$$\begin{pmatrix} q_k & q_{k-1} \\ p_k & p_{k-1} \end{pmatrix} = \begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix}.$$

Therefore

$$\frac{q_k + q_{k-1}}{p_k + p_{k-1}} = \frac{w_n^{(1)}}{v_n^{(1)}}.$$

Similarly, for any $\frac{p_k}{q_k}$, if $a_k \geq 2$ then there exists an n such that

$$\begin{pmatrix} q_{k-1} & q_{k-2} \\ p_{k-1} & p_{k-2} \end{pmatrix} \begin{pmatrix} 1 & a_k - 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix},$$

if $a_k = 1$ then there exists an n such that

$$\begin{pmatrix} q_{k-1} & q_{k-2} \\ p_{k-1} & p_{k-2} \end{pmatrix} = \begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix}.$$

Therefore

$$\frac{p_k}{q_k} = \frac{w_n^{(1)}}{v_n^{(1)}}.$$

Finally, for any $\frac{p_k - p_{k-1}}{q_k - q_{k-1}} \left(\neq \frac{p_{k-2}}{q_{k-2}} \right)$, there exists an n such that

$$\begin{pmatrix} q_{k-1} & q_{k-2} \\ p_{k-1} & p_{k-2} \end{pmatrix} \begin{pmatrix} 1 & a_k - 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix},$$

hence

$$\frac{p_k - p_{k-1}}{q_k - q_{k-1}} = \frac{w_n^{(1)}}{v_n^{(1)}}.$$

We now call the fraction $\frac{w_n^{(1)}}{v_n^{(1)}} = \frac{t_n^{(1)}(x) + u_n^{(1)}(x)}{r_n^{(1)}(x) + s_n^{(1)}(x)}$ the n -th nearest mediant convergent of x , and the algorithm (X, T_1) the nearest mediant convergent transformation. We prepare also some formula concerning the approximation.

Proposition 2.2. For any irrational $x \in (0, 1)$

$$(2,11) \quad \left| x - \frac{w_n^{(1)}(x)}{v_n^{(1)}(x)} \right| = \frac{1 - T_1^n x}{(v_n^{(1)})^2 \left\{ \frac{r_n^{(1)}}{v_n^{(1)}} (1 - T_1^n x) + T_1^n x \right\}}$$

The proof is the same as for proposition 1.2.

Proposition 2.3. For any irrational $x \in (0, 1)$

$$(2,12) \quad |x \cdot v_n^{(1)}(x) - w_n^{(1)}(x)| = g_1(x)g_1(T_1x) \cdots g_1(T_1^{n-1}x)(1 - T_1^n x)$$

where

$$g_1(x) = \begin{cases} x, & \text{if } x \in J_1 \\ 1 - x, & \text{if } x \in J_2 \\ 1 - (k - 2)x, & \text{if } x \in J_k \quad (k \geq 3). \end{cases}$$

Proof. The proof is similar to that of Proposition 1.3. In fact, for each sequence $(\delta_1(x), \dots, \delta_n(x))$, we consider the affine transformations φ_{δ_i} from (ξ_{i-1}, η_{i-1}) -plane to the (ξ_i, η_i) -plane defined by

$$\varphi_{\delta_i}: \begin{pmatrix} \xi_{i-1} \\ \eta_{i-1} \end{pmatrix} = B_{\delta_i} \begin{pmatrix} \xi_i \\ \eta_i \end{pmatrix}.$$

The absolute value of the linear form $x \cdot \xi_0 - \eta_0$ is transformed in the following way:

$$|x \cdot \xi_0 - \eta_0| = g_1(x) |T_1 x \cdot \xi_1 - \eta_1|.$$

Therefore, we have

$$(2,13) \quad |x \cdot \xi_0 - \eta_0| = g_1(x) \cdots g_1(T_1^{n-1}x) |T_1^n x \cdot \xi_n - \eta_n| \quad (n \geq 1).$$

On the other hand we know

$$\begin{pmatrix} \xi_0 \\ \eta_0 \end{pmatrix} = B_{\delta_1(x)} \cdots B_{\delta_n(x)} \begin{pmatrix} \xi_n \\ \eta_n \end{pmatrix} = \begin{pmatrix} r_n^{(1)} & s_n^{(1)} \\ t_n^{(1)} & u_n^{(1)} \end{pmatrix} \begin{pmatrix} \xi_n \\ \eta_n \end{pmatrix}.$$

Hence, we obtain the result by putting the value $(\xi_n, \eta_n) = (1, 1)$ into (2,13).

Now, we introduce the natural extension of (X, T_1) . Let R be the subset of \bar{X} such that

$$\begin{aligned} R &= \{(x, y) \in \bar{X}; x \geq 1/3 \text{ or } (x \leq 1/3 \text{ and } y \geq 1/2)\} \\ &= J_1 \times I \cup J_2 \times I \cup \left(\bigcup_{k \geq 3} J_k \times I_1 \right) \end{aligned}$$

where $I = [0, 1]$ and $I_1 = [1/2, 1]$, and let the map \bar{T}_1 be defined on R by

$$\bar{T}_1(x, y) = \begin{cases} \left(\frac{1-x}{x}, \frac{1}{1+y} \right), & \text{if } (x, y) \in J_1 \times I \\ \left(\frac{x}{1-x}, \frac{y}{1+y} \right), & \text{if } (x, y) \in J_2 \times I \\ \left(\frac{x}{1-(k-2)x}, \frac{y}{1+(k-2)y} \right), & \text{if } (x, y) \in J_k \times I_1 \end{cases}$$

In other words,

$$= \begin{cases} (T_1 x, Z_1(y)), & \text{if } (x, y) \in J_1 \times I \\ (T_1 x, Z_2(y)), & \text{if } (x, y) \in J_2 \times I \\ (T_1 x, Z_k(y)), & \text{if } (x, y) \in J_k \times I_1. \end{cases}$$

Theorem 2.1. *The transformation (R, \bar{T}_1) is the induced map of (\bar{X}, \bar{T}) on R . Therefore, the transformation (R, \bar{T}_1) has an invariant probability measure $\bar{\mu}_R$ with density*

$$d\bar{\mu}_R = \frac{1}{2 \log 2} \cdot \frac{dx dy}{(x+y-xy)^2}.$$

Moreover, the dynamical system $(R, \bar{T}_1, \bar{\mu}_R)$ is ergodic.

Proof. From the definition (2,1), we can easily see that

$$\begin{aligned} \bar{T}(J_1 \times I) &= I \times [1/2, 1] \\ \bar{T}(J_2 \times I) &= J_1 \times [0, 1/2] \end{aligned}$$

and for $k \geq 3$

$$\bar{T}^{k-2}(J_k \times I) = J_2 \times \left[\frac{1}{k}, \frac{1}{k-1} \right]$$

and

$$\bar{T}^j(J_k \times I) \cap R = \phi \quad (1 \leq j < k-2).$$

(see figure 3).

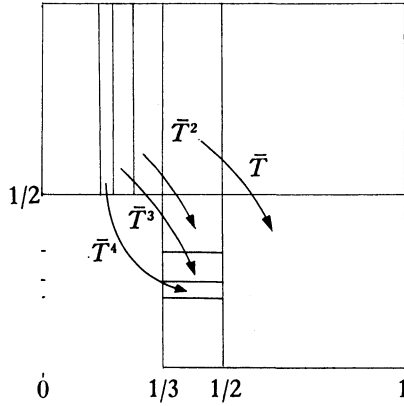


figure 3

Therefore let \bar{T}_R be the induced automorphism of \bar{T} on R , then

$$\bar{T}_R(x, y) = \bar{T}_1(x, y).$$

Hence by proposition 2.1. the invariant measure $\bar{\mu}_R$ is given by

$$d\bar{\mu}_R = \frac{1}{2 \log 2} \cdot \frac{dxdy}{(x+y-xy)^2}$$

where $2 \log 2$ is a normalizing constant. The ergodicity of the dynamical system $(R, \bar{T}_1, \bar{\mu}_R)$ follows from the ergodicity of $(\bar{X}, \bar{T}, \bar{\mu})$.

Taking the marginal distribution we have

Corollary 2.1. *The transformation (X, T_1) has an invariant measure μ_1 :*

$$d\mu_1 = \begin{cases} \frac{1}{2 \log 2} \cdot \frac{dx}{1+x}, & \text{if } x \in [0, 1/3] \\ \frac{1}{2 \log 2} \cdot \frac{dx}{x}, & \text{if } x \in [1/3, 1] \end{cases}$$

and the dynamical system (X, T_1, μ_1) is ergodic.

Corollary 2.3.

$$\bar{T}_1^n(x, 1) = \left(T_1^n x, \frac{r_n^{(1)}}{r_n^{(1)} + s_n^{(1)}} \right)$$

Proof. There exists an $m = m(n, x, 1)$ such that $\bar{T}_1^n(x, 1) = \bar{T}^m(x, 1)$ and so $r_m = r_n^{(1)}$ and $s_m = s_n^{(1)}$. Therefore we obtain the result, from the fundamental lemma in § 1.

Corollary 2.3.

- (i) Let a fraction $\frac{p}{q}$ satisfies $q|q \cdot x - p| < 1$ and $(q, p) = 1$. Then there exists a k such that $\frac{p}{q} = \frac{w_k^{(1)}}{v_k^{(1)}}$ (Fatou).
- (ii) If $\frac{w_n^{(1)}}{v_n^{(1)}}$ is the n -th convergent of x , then $v_n^{(1)}|v_n^{(1)} \cdot x - w_n^{(1)}| \leq 2$.

Proof. To prove (i), note that by property 1.2. and theorem 1.1., there exists n such that $\frac{p}{q} = \frac{w_n}{v_n}$, that is, $\frac{w_n}{v_n}$ is the n -th mediant convergent and satisfies

$$v_n |v_n x - w_n| \leq 1.$$

From proposition 1.4. this is equivalent to

$$\bar{T}^n(x, 1) \in D_1.$$

Since D_1 is a subset of R , there exists k such that

$$\bar{T}_R^k(x, 1) = \bar{T}^n(x, 1)$$

, in other words, $\bar{T}_R^k(x, 1) = \bar{T}_1^k(x, 1)$. Therefore

$$\frac{w_n}{v_n} = \frac{w_k^{(1)}}{v_k^{(1)}}.$$

Part (ii) can be seen as follows. By proposition 2.1. and corollary 2.2.

$$v_n^{(1)} |v_n^{(1)} \cdot x - w_n^{(1)}| = f(\bar{T}_1^k(x, 1)).$$

On the other hand, $\bar{T}_1^k(x, 1) \in R$ and $D_2 \supset R$. Therefore

$$v_n^{(1)} |v_n^{(1)} \cdot x - w_n^{(1)}| \leq 2.$$

3. Some metrical results

In this section we prove Erdős' theorem for $0 < \lambda \leq 1$ by using the ergodic theorem.

Proposition 3.1. For almost all $x \in (0, 1)$

$$(3,1) \quad \lim_{n \rightarrow \infty} \frac{1}{n} \log v_n^{(1)}(x) = \frac{\pi^2}{24 \log 2}.$$

Proof. Let $\{a_k(x); k \leq N\}$ be a sequence of digits with respect to a simple continued fraction. Put

$$n(m) = \#\{k; a_k(x) = 1, k \leq m\} + 2\#\{k; a_k(x) = 2, k \leq m\} + 3\#\{k; a_k(x) \geq 3, k \leq m\}.$$

Then, from theorem 2.1. we have

$$v_n^{(1)} = q_m \quad \text{for all } m \geq 1.$$

By using the ergodic theorem for the dynamical system (X, S, ν) , we know ([1]) that for almost all $x \in (0, 1)$

$$(1) \quad \lim_{m \rightarrow \infty} \frac{n(m)}{m} = \nu(J_1) + 2\nu(J_2) + 3\nu(\bigcup_{k \geq 3} J_k) = 2$$

and

$$(2) \quad \lim_{m \rightarrow \infty} \frac{1}{m} \log q_m = \frac{\pi^2}{12 \log 2}.$$

Therefore,

$$\lim_{m \rightarrow \infty} \frac{1}{n(m)} \log v_n^{(1)} = \lim_{m \rightarrow \infty} \frac{m}{n(m)} \frac{1}{m} \log q_m = \frac{\pi^2}{24 \log 2}.$$

Noting that $mn(m+1) - n(m) \leq 3$ and $v_{n+1}^{(1)} > v_n^{(1)}$, we get the result.

Proposition 3.3. For almost all $x \in (0, 1)$

$$(i) \quad \lim_{n \rightarrow \infty} -\frac{1}{n} \log |v_n^{(1)} \cdot x - w_n^{(1)}| = \frac{\pi^2}{24 \log 2}$$

and

$$(ii) \quad \lim_{n \rightarrow \infty} -\frac{1}{n} \log \left| x - \frac{w_n^{(1)}}{v_n^{(1)}} \right| = \frac{\pi^2}{12 \log 2}$$

Proof. From proposition 2.2. we have

$$-\frac{1}{n} \log |v_n^{(1)} \cdot x - w_n^{(1)}| = \frac{1}{n} \log v_n^{(1)} - \frac{1}{n} \log f(\bar{T}_1^n(x, 1)).$$

We show that for almost all $x \in (0, 1)$

$$(3,2) \quad \lim_{n \rightarrow \infty} \frac{1}{n} \log f(\bar{T}_1^n(x, 1)) = 0.$$

From (1,21) and theorem 2.2. we have

$$\bar{\mu}_1(f(\bar{T}_1^n(x, y)) > \eta) = \bar{\mu}_1(f(x, y) < \eta) = \frac{\eta}{2 \log 2}$$

for $0 < \eta \leq 1$.

Therefore, we see that for any $\varepsilon > 0$

$$\sum_{n=1}^{\infty} \bar{\mu}_1 \{ f(\bar{T}_1^n(x, y)) < e^{-n\varepsilon} \} < +\infty.$$

Hence, by using the Borel-Cantelli lemma,

$$\# \left\{ n; -\frac{1}{n} \log f(\bar{T}_1^n(x, y)) > \varepsilon \right\} < +\infty$$

for almost all (x, y) , that is,

$$(3,3) \quad \lim_{n \rightarrow \infty} \frac{1}{n} \log f(\bar{T}_1^n(x, y)) = 0 \quad \text{for a.a. } (x, y).$$

Note that the following inequality holds:

$$|f(x, y) - f(x, y')| \leq c |y - y'|$$

where

$$c = \frac{1}{\min_{(x, y) \in \mathbb{R}} \left(y + \frac{x}{1-x} \right)}.$$

In particular, remarking that from the definition of \bar{T}_1

$$\bar{T}_1^n(x, y) = \left(T_1^n x, \frac{t_n^{(1)} + y \cdot u_n^{(1)}}{r_n^{(1)} + y \cdot s_n^{(1)}} \right),$$

we have from sublemma in § 1

$$\begin{aligned} |f(\bar{T}_1^n(x, y)) - f(\bar{T}_1^n(x, 1))| &\leq c \left| \frac{t_n^{(1)} + y u_n^{(1)}}{r_n^{(1)} + y s_n^{(1)}} - \frac{t_n^{(1)} + u_n^{(1)}}{r_n^{(1)} + s_n^{(1)}} \right| \\ &< \frac{c}{r_n^{(1)} + s_n^{(1)}} = \frac{c}{v_n^{(1)}}. \end{aligned}$$

Therefore, from proposition 3.1. there exists $0 < \eta < 1$ such that

$$|f(\bar{T}_1^n(x, y)) - f(\bar{T}_1^n(x, 1))| < c \cdot \eta^n,$$

and so (3,3) imply (3,2). This completes the proof of (i). Part (ii) is obtained from

$$-\frac{1}{n} \log \left| x - \frac{w_n^{(1)}}{v_n^{(1)}} \right| = 2 \frac{1}{n} \log v_n^{(1)} - \frac{1}{n} \log f(\bar{T}_1^n(x, 1)).$$

Theorem 3.1. For almost all $x \in (0, 1)$

$$\lim_{N \rightarrow \infty} \frac{\#\{n; v_n^{(1)} | v_n^{(1)} \cdot x - w_n^{(1)} | \leq \lambda, 1 \leq n \leq N\}}{N} = \begin{cases} \frac{\lambda}{2 \log 2} & \text{for } 0 \leq \lambda < 1 \\ \frac{2 - \lambda + 2 \log \lambda}{2 \log 2} & \text{for } 1 \leq \lambda < 2. \end{cases}$$

Proof. From proposition 1.4. we get

$$\frac{\#\{n; v_n^{(1)} | v_n^{(1)} \cdot x - w_n^{(1)} | \leq \lambda, 1 \leq n \leq N\}}{N} = \frac{\sum_{n=1}^N \chi_\lambda(\bar{T}_1^n(x, 1))}{N},$$

where χ_λ is the indicator function of the set D_λ .

On the other hand, it is clear from the ergodic theorem that

$$\lim_{N \rightarrow \infty} \frac{\sum_{n=1}^N \chi_\lambda(\bar{T}_1^n(x, y))}{N} = \bar{\mu}_1(D_\lambda)$$

for almost all (x, y) .

Note that

$$\begin{aligned} & \{(x, y): \chi_\lambda(\bar{T}_1^n(x, y)) \neq \chi_\lambda(\bar{T}_1^n(x, 1))\} \\ & \subset \{(x, y): \lambda - c\eta^n < f(\bar{T}_1^n(x, y)) < \lambda + c\eta^n\} \end{aligned}$$

where c and η are the same constants as in the proof of proposition 3.2. Therefore, we have

$$\bar{\mu}_1\{\chi_\lambda(\bar{T}_1^n(x, y)) \neq \chi_\lambda(\bar{T}_1^n(x, 1))\} < \frac{c\eta^n}{\log 2}.$$

Hence, by using the Borel-Cantelli lemma, for almost all (x, y)

$$\#\{n; \chi_\lambda(\bar{T}_1^n(x, y)) \neq \chi_\lambda(\bar{T}_1^n(x, 1))\} < \infty.$$

By easy calculation for $\bar{\mu}_1(D_\lambda)$, we obtain the conclusion.

Theorem 3.3. For $1 \geq \lambda \geq 0$

$$\lim_{N \rightarrow \infty} \frac{\#\{(q, p); |qx - p| < \lambda, (q, p) = 1, q \leq N\}}{\log N} = \lambda \frac{12}{\pi^2}$$

for almost all x .

Proof. If $v_{n-1}^{(1)} \leq N < v_n^{(1)}$, then by corollary 2.3.

$$\begin{aligned} & \#\{(q, p); |qx - p| < \lambda, (q, p) = 1, q \leq N\} \\ & \cong \#\{(v_k^{(1)}, w_k^{(1)}); v_k^{(1)} | v_k^{(1)}x - w_k^{(1)}| < \lambda, k \leq n-1\}. \end{aligned}$$

Hence, by theorem 3.1. and proposition 3.1.

$$\begin{aligned} & \lim_{N \rightarrow \infty} \frac{\#\{(q, p); |qx - p| < \lambda, (q, p) = 1, q \leq N\}}{\log N} \\ & \cong \lim_{n \rightarrow \infty} \frac{\#\{k; v_k^{(1)}v | x_k^{(1)} - w_k^{(1)}| < \lambda, 1 \leq k \leq n-1\}}{\log v_n^{(1)}} \\ & = \lambda \cdot \frac{12}{\pi^2} \quad \text{for almost all } x. \end{aligned}$$

Replacing $v_n^{(1)}$ by $v_{n-1}^{(1)}$ we obtain the reverse inequality.

Acknowledgements

This paper was written during a stay at Institut für Mathematik, Universität Salzburg in 1985.

The author would like to thank Prof. F. Schweiger and Dr. M. Thaler for their interest in the problem and for valuable advice.

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