

ON THE JACOBI DIFFERENTIAL OPERATORS ASSOCIATED TO MINIMAL ISOMETRIC IMMERSIONS OF SYMMETRIC SPACES INTO SPHERES I

TOSHINOBU NAGURA*)

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Introduction

Let $F: M \rightarrow \bar{M}$ be a minimal isometric immersion of a compact Riemannian manifold M . For a variation $\{F_t\}$ of F the second variation of the volume $V(t)$ of $F_t(M)$ is described by a differential operator \tilde{S} , called the Jacobi differential operator, on the normal bundle as

$$\left. \frac{d^2 V(t)}{dt^2} \right|_{t=0} = \int_M \langle \tilde{S}(E^N), E^N \rangle dx,$$

where E^N denotes the infinitesimal normal variation of $\{F_t\}$ (see section 1). The Jacobi differential operator \tilde{S} is self-adjoint and strongly elliptic. Therefore the index and the nullity of F are obtained from the spectra of \tilde{S} . Here the index and the nullity are defined as those of the Hessian at F of the volume integral on the space of immersions of M into \bar{M} modulo diffeomorphisms of M . For the study of minimal isometric immersions it seems to be important to study \tilde{S} and its spectra. However there have been few studies on these problems except for the recent works of Hasegawa and others. Hasegawa [4] studies the spectral geometry of minimal submanifolds.

Let M be a compact symmetric space, \bar{M} a unit sphere, and F an equivariant

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minimal isometric immersion. Under this situation we study the Jacobi differential operator \tilde{S} , applying the representation theory of compact Lie groups. In section 1 we recall some results on minimal isometric immersions. In section 2 we study equivariant isometric immersions of compact homogeneous spaces and their Killing nullities (see Hsiang and Lawson [6] p. 14 for Killing nullities). In section 3 we study equivariant minimal isometric immersions of compact symmetric spaces into unit spheres. And we compute the Jacobi differential operator \tilde{S} in this case (Theorem 1). In section 4, recalling some results on invariant differential operators, we give some propositions, which give criterions in order that our operator \tilde{S} reduces to the Casimir operator. In section 5 the problem of computing the spectra of \tilde{S} is reduced to the eigenvalue problems for certain linear mappings S_σ of finite dimensional vector spaces (Theorem 3).

In the forthcoming papers we shall study the linear mappings S_σ in detail under certain conditions, and study the index and the nullity of minimally immersed spheres into spheres.

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1. Preliminaries

1.1. Let (M, g) be an n -dimensional compact connected Riemannian manifold without boundary, and (\bar{M}, \bar{g}) an m -dimensional Riemannian manifold. Let $F: M \rightarrow \bar{M}$ be an isometric immersion of M into \bar{M} . We consider the tangent space $T_x(M)$ of M at $x \in M$ as a vector subspace of the tangent space $T_{F(x)}(\bar{M})$ of \bar{M} at $F(x) \in \bar{M}$. We denote by $N_x(M)$ the orthogonal complement of $T_x(M)$ in $T_{F(x)}(\bar{M})$, which is called the *normal space* of the immersed submanifold M of \bar{M} at x . Let $T(M)$ (resp. $T(\bar{M})$) be the tangent bundle of M (resp. of \bar{M}). We denote by $T(\bar{M})|_M$ the bundle induced by F from $T(\bar{M})$. The bundle $N(M) = \bigcup_{x \in M} N_x(M)$ is called the *normal bundle* of M . We denote by $\mathfrak{X}(M)$ (resp. $\Gamma(N(M))$) the space of all C^∞ cross-sections of $T(M)$ (resp. of $N(M)$).

Let $B: T_x(M) \times T_x(M) \rightarrow N_x(M)$ be the second fundamental form of M , and $A: N_x(M) \times T_x(M) \rightarrow T_x(M)$ the Weingarten form of M . The second fundamental form B is a symmetric bilinear mapping, and $A_v, v \in N_x(M)$, is a self-adjoint linear mapping of $T_x(M)$. Let ∇ (resp. $\bar{\nabla}$) be the Riemannian connection of M (resp. \bar{M}). Let D be the normal connection of M . For any vector fields $X, Y \in \mathfrak{X}(M)$ and for any normal vector field $\xi \in \Gamma(N(M))$, we have the following equations (cf. Kobayashi and Nomizu [7] Vol. II Chap. 7 section 3):

$$(1.1.1) \quad \bar{\nabla}_X Y = \nabla_X Y + B(X, Y),$$

$$(1.1.2) \quad \nabla_x \xi = -A_\xi X + D_x \xi,$$

$$(1.1.3) \quad g(\xi, B(X, Y)) = g(A_\xi X, Y).$$

We denote by H the mean curvature of M . Let $\{e_1, \dots, e_n\}$ be an orthonormal basis of $T_x(M)$. Then we have

$$H_x = \sum_{i=1}^n B(e_i, e_i).$$

The isometric immersion $F: M \rightarrow \bar{M}$ is said to be *minimal*, if the mean curvature H of M vanishes identically.

1.2. Let \bar{R} be the curvature tensor of \bar{M} . For $x \in M$ we define linear mappings \bar{A} and \bar{R} of $N_x(M)$ as follows:

$$(1.2.1) \quad \bar{A}(v) = \sum_{i,j=1}^n g(v, B(e_i, e_j))B(e_i, e_j),$$

$$(1.2.2) \quad \bar{R}(v) = \sum_{i=1}^n (\bar{R}(e_i, v)e_i)^N \quad \text{for } v \in N_x(M),$$

where $\{e_1, \dots, e_n\}$ is an orthonormal basis of $T_x(M)$ and $(\bar{R}(*, *)^N)$ denotes the normal component of $\bar{R}(*, *)^*$. The linear mappings \bar{A} and \bar{R} are independent of the choice of an orthonormal basis.

If \bar{M} is a space of constant sectional curvature k , we have for any vector fields X, Y and Z on \bar{M} (cf. Kobayashi and Nomizu [7] Vol. I p. 203):

$$\bar{R}(X, Y)Z = k(g(Z, Y)X - g(Z, X)Y).$$

Therefore we have

$$(1.2.3) \quad \bar{R}(v) = -nk v \quad \text{for } v \in N_x(M).$$

We denote by Δ the Laplace operator on $N(M)$ (cf. Simons [10] p. 64). Let $\{E_1, \dots, E_n\}$ be an orthonormal local basis of $T(M)$ on a neighborhood of $x \in M$. Then we have

$$(1.2.4) \quad \Delta f(x) = \sum_{i=1}^n (D_{E_i} D_{E_i} f)(x) - \sum_{i=1}^n (D_{\nabla_{E_i} E_i} f)(x) \quad \text{for } f \in \Gamma(N(M)).$$

We define a differential operator \tilde{S} , called the *Jacobi differential operator*, on $N(M)$ as follows:

$$(1.2.5) \quad \tilde{S} = -\Delta - \bar{A} + \bar{R}.$$

Let I be an open interval containing $0 \in \mathbf{R}$. A 1-parameter family $\{F_t\}_{t \in I}$ of immersions of M into \bar{M} is called a *variation* of F , if $F = F_0$ and if the mapping $f: I \times M \rightarrow \bar{M}$, defined by $f(t, x) = F_t(x)$, is differentiable. The *variation vector field* E of the variation $\{F_t\}_{t \in I}$ is defined by

$$E_x = df \left(\left(\frac{\partial}{\partial t} \right)_{(0,x)} \right).$$

Proposition 1.2.1 (cf. Simons [10] p. 73). *Let $F: M \rightarrow \bar{M}$ be a minimal isometric immersion, $\{F_t\}_{t \in I}$ a variation of F , and E the variation vector field of $\{F_t\}$. We denote by $V(t)$ the volume of M with respect to the Riemannian metric induced by the immersion F_t . Let E^N be the normal component of E , which is a cross-section of $N(M)$. Then we have*

$$(1.2.6) \quad \left. \frac{d^2V(t)}{dt^2} \right|_{t=0} = \int_M \bar{g}(\tilde{S}(E^N), E^N) dx,$$

where dx is the Riemannian measure of (M, g) .

The vector space $\Gamma(N(M))$ is a pre-Hilbert space with the inner product (\cdot, \cdot) :

$$(f, f') = \int_M \bar{g}(f, f') dx \quad \text{for } f, f' \in \Gamma(N(M)).$$

We denote by $L^2(N(M))$ the completion of $\Gamma(N(M))$. We consider $\Gamma(N(M))$ as a linear subspace of $L^2(N(M))$. The Jacobi differential operator \tilde{S} is a self-adjoint strongly elliptic operator on $\Gamma(N(M))$. Therefore we have

Proposition 1.2.2 (cf. Simons [10] p. 74). (1) *The Jacobi differential operator \tilde{S} is diagonalizable in the sense that there exists a complete orthonormal system $\{e_\alpha\}_{\alpha \in A}$ of $L^2(N(M))$ such that each e_α is contained in $\Gamma(N(M))$ and that each e_α is an eigenvector of \tilde{S} .*

(2) *Each eigenspace of \tilde{S} is finite dimensional. Let*

$$\lambda_1 < \lambda_2 < \dots < \lambda_i < \dots$$

be the eigenvalues of \tilde{S} . Then the sequence $\{\lambda_i\}_{i=1,2,\dots}$ is divergent to ∞ .

REMARK 1.2.1. By Proposition 1.2.2 the spectra of \tilde{S} acting on $\Gamma(N(M))$ coincide with ones of \tilde{S} acting on $\Gamma(N(M))^c$, the complexification of $\Gamma(N(M))$.

We define a bilinear form $I(\cdot, \cdot)$ on $\Gamma(N(M))$ as follows:

$$I(V, W) = \int_M \bar{g}(\tilde{S}(V), W) dx \quad \text{for } V, W \in \Gamma(N(M)).$$

The *index* and the *nullity* of F are those of the bilinear form $I(\cdot, \cdot)$. By Proposition 1.2.1 and 1.2.2 the index of F is the sum of the dimensions of the eigenspaces corresponding to negative eigenvalues of \tilde{S} , and the nullity of F is the dimension of the 0-eigenspace of \tilde{S} .

2. Equivariant isometric immersions

2.1. In section 2 we assume the followings. Let G be a compact con-

nected Lie group, and K a closed subgroup of G . Let \mathfrak{g} be the Lie algebra of G , and \mathfrak{k} the Lie subalgebra of \mathfrak{g} corresponding to the Lie subgroup K . Let \langle , \rangle be an $Ad(G)$ -invariant inner product on \mathfrak{g} . Then we have an orthogonal decomposition $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$, where \mathfrak{p} is the orthogonal complement of \mathfrak{k} . We denote by M the quotient space G/K . We canonically identify \mathfrak{p} with the tangent space $T_o(M)$ of M at $o = \pi(e)$, where π is the natural projection of G onto $M = G/K$. We also denote by \langle , \rangle the G -invariant Riemannian metric on M which coincides with the inner product \langle , \rangle on $\mathfrak{p} = T_o(M)$. Let $F: (M, c\langle , \rangle) \rightarrow \bar{M}$ be an isometric immersion for some $c > 0$ which is equivariant in the following sense: There exists a Lie group homomorphism ρ of G into $I(\bar{M})$, the group of all isometries of \bar{M} , such that $F(x(yK)) = \rho(x)F(yK)$ for $x, y \in G$. We also denote by \langle , \rangle the Riemannian metric on \bar{M} . Moreover we assume that the image $F(M)$ of M does not coincide with \bar{M} .

We define an action σ of G on $\Gamma(N(M))$ by

$$(\sigma(x)\tilde{f})(yK) = d(\rho(x))\tilde{f}(x^{-1}y) \quad \text{for } \tilde{f} \in \Gamma(N(M))$$

$$\text{and } x, y \in G,$$

where $d(\rho(x))$ denotes the differential of the isometry $\rho(x)$. We define an action of G on $\Gamma(T(\bar{M})|_M)$ in the same way as for $\Gamma(N(M))$, where $\Gamma(T(\bar{M})|_M)$ is the space of all C^∞ cross-sections of $T(\bar{M})|_M$. We also denote by σ the action of G on $\Gamma(T(\bar{M})|_M)$. Then we have by the equivariance of F

$$\begin{cases} \Delta \circ \sigma(x) = \sigma(x) \circ \Delta, \\ \tilde{A} \circ \sigma(x) = \sigma(x) \circ \tilde{A}, \\ \tilde{R} \circ \sigma(x) = \sigma(x) \circ \tilde{R}. \end{cases}$$

Therefore we have

$$(2.1.1) \quad \tilde{S} \circ \sigma(x) = \sigma(x) \circ \tilde{S}.$$

Moreover if F is minimal, each eigenspace of \tilde{S} is G -invariant.

Put $U = N_o(M)$. Then K acts on U by the differential of $\rho(k)$, $k \in K$, at $F(o)$. We denote by ϕ this action of K on U . We denote by E the vector bundle $G \times_K U$ associated with G by ϕ . Put

$$C^\infty(G; U)_K = \left\{ f: G \rightarrow U \text{ } C^\infty \text{ mapping; } f(xk) = \phi(k)^{-1}f(x) \right\}$$

$$\text{for } x \in G \text{ and } k \in K$$

The space $\Gamma(E)$ of C^∞ cross-sections of E is identified with $C^\infty(G; U)_K$ by the following correspondence:

$$(2.1.2) \quad C^\infty(G; U)_K \ni f \mapsto \tilde{f} \in \Gamma(E), \tilde{f}(xK) = x \circ f(x) \quad \text{for } x \in G,$$

where $x \circ f(x)$ is the image of $(x, f(x)) \in G \times U$ by the natural projection $G \times U \rightarrow$

$G \times_K U$. We define an action L of G on $C^\infty(G; U)_K$ as follows:

$$(2.1.3) \quad (L_x f)(y) = f(x^{-1}y) \quad \text{for } f \in C^\infty(G; U)_K \text{ and } x, y \in G.$$

Put $V = T_{F(o)}(\bar{M})$ and $W = T_o(M)$. Then K also acts on V (resp. W) by the differential of $\rho(k)$ (resp. of k), $k \in K$, at $F(o)$ (resp. at o). We denote by J (resp. H) the associated vector bundle $G \times_K V$ (resp. $G \times_K W$). We define a space $C^\infty(G; V)_K$ (resp. $C^\infty(G; W)_K$) and an action L of G on $C^\infty(G; V)_K$ (resp. on $C^\infty(G; W)_K$) in the same way. We can identify $T(\bar{M})|_M$ (resp. $N(M)$ and $T(M)$) with J (resp. E and H) and $\Gamma(T(\bar{M})|_M)$ (resp. $\Gamma(N(M))$ and $\mathfrak{X}(M)$) with $C^\infty(G; V)_K$ (resp. $C^\infty(G; U)_K$ and $C^\infty(G; W)_K$) in the following way.

Proposition 2.1.1. (1) *The vector bundle homomorphism*

$$\iota: J \rightarrow T(\bar{M})|_M, \quad \iota(x \circ v) = d(\rho(x))v \quad \text{for } x \in G \text{ and } v \in V,$$

is an isomorphism, and ι induces an isomorphism of E (resp. H) onto $N(M)$ (resp. $T(M)$).

(2) Also denoting by ι the isomorphism of $C^\infty(G; V)_K$ onto $\Gamma(T(\bar{M})|_M)$ induced from $\iota: J \rightarrow T(\bar{M})|_M$, the following diagram is commutative:

$$\begin{array}{ccc} C^\infty(G; V)_K & \xrightarrow{\iota} & \Gamma(T(\bar{M})|_M) \\ \downarrow L_x & & \downarrow \sigma(x) \\ C^\infty(G; V)_K & \xrightarrow{\iota} & \Gamma(T(\bar{M})|_M) \end{array} \quad \text{for } x \in G.$$

The isomorphism $\iota: C^\infty(G; V)_K \rightarrow \Gamma(T(\bar{M})|_M)$ induces an isomorphism of $C^\infty(G; U)_K$ (resp. $C^\infty(G; W)_K$) onto $\Gamma(N(M))$ (resp. $\mathfrak{X}(M)$).

For $f \in C^\infty(G; V)_K$ we denote by \tilde{f} the image of f by the isomorphism ι .

2.2. For $x \in G$ we define a diffeomorphism τ_x of M by $\tau_x(yK) = xyK$. Then τ_x is an isometry of (M, \langle, \rangle) . For $X \in \mathfrak{g}$ we denote by X^* the infinitesimal transformation on M which generates the 1-parameter group of transformations $\tau_{\exp tX}$ on M . We define differential operators \tilde{A}_0 and Δ_0 on $N(M)$ as follows:

$$(2.2.1) \quad \tilde{A}_0(\tilde{f}) = \sum_{i=1}^{n+p} B(E_i^*, A_{\tilde{f}} E_i^*),$$

$$(2.2.2) \quad \Delta_0(\tilde{f}) = \sum_{i=1}^{n+p} D_{E_i^*} D_{E_i^*}(\tilde{f}) \quad \text{for } \tilde{f} \in \Gamma(N(M)),$$

where $\{E_1, \dots, E_{n+p}\}$ is an orthonormal basis of \mathfrak{g} . The operators \tilde{A}_0 and Δ_0 are independent of the choice of an orthonormal basis of \mathfrak{g} .

Proposition 2.2.1. *For the operators \tilde{A}_0 and \tilde{A} we have the following equation:*

$$(2.2.3) \quad c\tilde{A} = \tilde{A}_0.$$

Proof. Choose an orthonormal basis $\{E_1, \dots, E_{n+p}\}$ of \mathfrak{g} with the property that $\{E_1, \dots, E_n\}$ (resp. $\{E_{n+1}, \dots, E_{n+p}\}$) is an orthonormal basis of \mathfrak{p} (resp. \mathfrak{k}). Then $\left\{\frac{1}{\sqrt{c}}(E_1^*)_o, \dots, \frac{1}{\sqrt{c}}(E_n^*)_o\right\}$ is an orthonormal basis of $T_o(M)$ and $(E_{n+1}^*)_o = \dots = (E_{n+p}^*)_o = 0$. For $x \in G$ put $F_i = Ad(x)E_i$, $i=1, 2, \dots, n+p$. Then $\{F_1, \dots, F_{n+p}\}$ is an orthonormal basis of \mathfrak{g} , and we have

$$\begin{aligned} (F_i^*)_{xK} &= \left. \frac{d(\exp t(Ad(x)E_i) \cdot xK)}{dt} \right|_{t=0} \\ &= \left. \frac{d(x(\exp tE_i) \cdot o)}{dt} \right|_{t=0} = d\tau_x(E_i^*)_o. \end{aligned}$$

Therefore $\left\{\frac{1}{\sqrt{c}}(F_1^*)_{xK}, \dots, \frac{1}{\sqrt{c}}(F_n^*)_{xK}\right\}$ is an orthonormal basis of $T_{xK}(M)$ and $(F_{n+1}^*)_{xK} = \dots = (F_{n+p}^*)_{xK} = 0$. For $v \in N_{xK}(M)$ we have

$$\begin{aligned} \tilde{A}_0(v) &= \sum_{i=1}^{n+p} B((F_i^*)_{xK}, A_v((F_i^*)_{xK})) \\ &= c \sum_{i=1}^n B\left(\frac{1}{\sqrt{c}}(F_i^*)_{xK}, A_v\left(\frac{1}{\sqrt{c}}((F_i^*)_{xK})\right)\right). \end{aligned}$$

By (1.1.3) we have

$$\begin{aligned} A_v\left(\frac{1}{\sqrt{c}}(F_i^*)_{xK}\right) &= \sum_{j=1}^n \left\langle A_v\left(\frac{1}{\sqrt{c}}(F_i^*)_{xK}\right), \frac{1}{\sqrt{c}}(F_j^*)_{xK} \right\rangle \frac{1}{\sqrt{c}}(F_j^*)_{xK} \\ &= \sum_{j=1}^n \left\langle v, B\left(\frac{1}{\sqrt{c}}(F_i^*)_{xK}, \frac{1}{\sqrt{c}}(F_j^*)_{xK}\right) \right\rangle \frac{1}{\sqrt{c}}(F_j^*)_{xK}. \end{aligned}$$

Hence we have by (1.2.1)

$$\begin{aligned} \tilde{A}_0(v) &= c \sum_{i,j=1}^n \left\langle v, B\left(\frac{1}{\sqrt{c}}(F_i^*)_{xK}, \frac{1}{\sqrt{c}}(F_j^*)_{xK}\right) \right\rangle \times \\ &\quad B\left(\frac{1}{\sqrt{c}}(F_i^*)_{xK}, \frac{1}{\sqrt{c}}(F_j^*)_{xK}\right) \\ &= c\tilde{A}(v). \end{aligned}$$

Q.E.D.

Proposition 2.2.2. *If the curve $c(t) = \exp tX \cdot o$ is a geodesic of M for any $X \in \mathfrak{p}$, we have*

$$(2.2.4) \quad c\Delta = \Delta_0.$$

Proof. Fix $x \in G$ and let $\{E_1, \dots, E_{n+p}\}$ and $\{F_1, \dots, F_{n+p}\}$ be orthonormal bases in the proof of Proposition 2.2.1. Then we have for $\tilde{f} \in \Gamma(N(M))$

$$(2.2.5) \quad (\Delta_0 \tilde{f})(xK) = \sum_{i=1}^n (D_{F_i^*} D_{F_i^*} \tilde{f})(xK).$$

We have

$$\begin{aligned} (F_i^*)_{x(\exp sE_i) \cdot o} &= \frac{d \{ \exp t(\text{Ad}(x)E_i) \cdot (x(\exp sE_i) \cdot o) \}}{dt} \Big|_{t=0} \\ &= \frac{d \{ x(\exp(t+s)E_i) \cdot o \}}{dt} \Big|_{t=0}. \end{aligned}$$

Hence the curve $x(\exp tE_i) \cdot o$ is an integral curve of F_i^* . Since the curves $x(\exp tE_i) \cdot o$, $i=1, \dots, n$, are geodesics, then

$$(2.2.6) \quad \nabla_{(F_i^*)_{xK}} F_i^* = 0.$$

Let U be a normal neighborhood of xK . Let X_i , $i=1, \dots, n$, be the vector fields on U adapted to $(F_i^*)_{xK}$, i.e. $(X_i)_q = \tau_{xK}^q(F_i^*)_{xK}$, where τ_{xK}^q is the parallel translation along the unique geodesic segment in U which joins xK and q . Then there exists $\varepsilon > 0$ such that $(X_i)_{x(\exp tE_i) \cdot o} = (F_i^*)_{x(\exp tE_i) \cdot o}$ for $-\varepsilon < t < \varepsilon$. Hence $(D_{X_i} \tilde{f})(x(\exp tE_i) \cdot o) = (D_{F_i^*} \tilde{f})(x(\exp tE_i) \cdot o)$ for $\tilde{f} \in \Gamma(N(M))$ and $-\varepsilon < t < \varepsilon$. Hence we have

$$(2.2.7) \quad (D_{X_i} D_{X_i} \tilde{f})(xK) = (D_{F_i^*} D_{F_i^*} \tilde{f})(xK).$$

We have by (1.2.4), (2.5.5), (2.2.6) and (2.2.7)

$$\begin{aligned} (\Delta \tilde{f})(xK) &= \sum_{i=1}^n (D_{\frac{1}{\sqrt{c}} X_i} D_{\frac{1}{\sqrt{c}} X_i} \tilde{f})(xK) \\ &= \frac{1}{c} \sum_{i=1}^n (D_{X_i} D_{X_i} \tilde{f})(xK) \\ &= \frac{1}{c} \sum_{i=1}^n (D_{F_i^*} D_{F_i^*} \tilde{f})(xK) \\ &= \frac{1}{c} (\Delta_0 \tilde{f})(xK), \end{aligned}$$

which proves (2.2.4). Q.E.D.

REMARK 2.2.1. Suppose that the pair (G, K) is a Riemannian symmetric pair and that the inner product $\langle \cdot, \cdot \rangle$ on \mathfrak{g} is invariant under the involutive automorphism of \mathfrak{g} associated to the pair (G, K) . Then the condition of Proposition 2.2.2 is satisfied (cf. Helgason [5] pp. 174–177).

In what follows, for a Riemannian symmetric pair (G, K) the inner product $\langle \cdot, \cdot \rangle$ on \mathfrak{g} will be always assumed to have the above property.

2.3. In this subsection we moreover assume that the equivariant isometric immersion $F: (M, c\langle \cdot, \cdot \rangle) \rightarrow \bar{M}$ is minimal and that \bar{M} is compact.

Let E be a Killing vector field on \bar{M} and E^N the normal component of the restriction of E to M . The dimension of the space $\{E^N; E \text{ is a Killing vector field on } \bar{M}\}$ is called the *Killing nullity* of F . We have $\tilde{S}(E^N)=0$ (Simons [10] p. 74). Hence the nullity is not less than the Killing nullity. Let $I(\bar{M}, M)$ be the group of isometries of \bar{M} which leave $F(M)$ invariant. Then $I(\bar{M}, M)$ is a closed subgroup of $I(\bar{M})$. Since \bar{M} is compact, the Killing nullity of F is equal to $\dim I(\bar{M})/I(\bar{M}, M)$.

Proposition 2.3.1. *Assume that \bar{M} is a compact connected Riemannian homogeneous space and that the equivariant isometric immersion $F: M \rightarrow \bar{M}$ is minimal. Then the Killing nullity of F is strictly positive.*

Proof. If the Killing nullity is equal to 0, then $\dim I(\bar{M}) = \dim I(\bar{M}, M)$. Since \bar{M} is connected, the group $I(\bar{M}, M)$ is transitive on \bar{M} (cf. Helgason [5] p. 114). Therefore we have $F(M) = I(\bar{M}, M)(F(M)) = \bar{M}$, which is a contradiction. Q.E.D.

3. Equivariant minimal isometric immersions into spheres

3.1. In section 3 the assumptions and the notation are the same as in subsection 2.1. Moreover we assume that V is a Euclidean vector space with an inner product $\langle \cdot, \cdot \rangle$ and that \bar{M} is the unit sphere S of V with the center 0, the origin of V . Since the isometric immersion $F: M \rightarrow S$ is equivariant, there exists an orthogonal representation $\rho: G \rightarrow GL(V)$ such that $\rho(k)v_0 = v_0$ for any $k \in K$, where $v_0 = F(o)$.

We identify the tangent space of V with V itself in a canonical way. Then we have $d(\rho(x)) = \rho(x)$ for $x \in G$. Since the induced bundle $T(V)|_M$ is trivial, we consider $\Gamma(T(V)|_M)$, the space of all C^∞ cross-sections of $T(V)|_M$, as the space of all V -valued C^∞ functions on M .

Under the above identification we have an orthogonal decomposition of the tangent space $T_{v_0}(V)$ as follows:

$$(3.1.1) \quad T_{v_0}(V) = V^0 + V^T + V^N,$$

where $V^0 = \mathbf{R}v_0$, $V^T = T_o(M)$ and $V^N = N_o(M)$. By Proposition 2.1.1 we have the following proposition.

Proposition 3.1.1. (1) *The vector bundle homomorphism*

$$\iota: G \times_K V \rightarrow T(V)|_M, \quad \iota(x \circ v) = \rho(x)v \quad \text{for } x \in G \text{ and } v \in V,$$

is an isomorphism, and ι induces an isomorphism of $G \times_K V^N$ (resp. $G \times_K V^T$) onto $N(M)$ (resp. $T(M)$).

(2) *The following diagram is commutative:*

$$\begin{array}{ccc} C^\infty(G; V)_K & \xrightarrow{\iota} & \Gamma(T(V)|_M) \\ \downarrow L_x & & \downarrow \sigma(x) \\ C^\infty(G; V)_K & \xrightarrow{\iota} & \Gamma(T(V)|_M) \end{array} \quad \text{for } x \in G.$$

The isomorphism $\iota: C^\infty(G; V)_K \rightarrow \Gamma(T(V)|_M)$ induces an isomorphism of $C^\infty(G; V^N)_K$ (resp. $C^\infty(G; V^T)_K$) onto $\Gamma(N(M))$ (resp. $\mathfrak{X}(M)$).

For $f \in C^\infty(G; V)_K$ we denote $\iota(f)$ by \tilde{f} . We denote by S the operator of $C^\infty(G; V^N)_K$ corresponding to \tilde{S} by the isomorphism ι .

Let $\bar{\nabla}$ be the connection in $T(V)|_M$ induced from the flat connection in $T(V)$. Then we have for $f \in C^\infty(G; V)_K$ and a vector field $Y \in \mathfrak{X}(M)$

$$(3.1.2) \quad \bar{\nabla}_Y \tilde{f} = Y\tilde{f},$$

where we consider \tilde{f} as a V -valued function on M . For $X \in \mathfrak{g}$ we denote by \hat{X} the right invariant vector field on G such that $\hat{X}_e = X_e$, where we consider \mathfrak{g} as the Lie algebra of left invariant vector fields on G and e is the unit element of G .

Lemma 3.1.2. *We have*

$$(3.1.3) \quad \bar{\nabla}_{X^*} \tilde{f} = \iota(\hat{X}f + d\rho(\text{Ad}(*^{-1})X)f) \quad \text{for } f \in C^\infty(G; V)_K \text{ and } X \in \mathfrak{g}.$$

Here $d\rho(\text{Ad}(*^{-1})X)f$ is the V -valued C^∞ function defined by

$$(d\rho(\text{Ad}(*^{-1})X)f)(x) = d\rho(\text{Ad}(x^{-1})X)f(x),$$

$d\rho$ is the differential of the homomorphism ρ , and X^* denotes the infinitesimal transformation which generates the 1-parameter group of transformations $\tau_{\exp tX}$.

Proof. Let g be an element of $C^\infty(G; V)_K$ such that $\tilde{g} = \bar{\nabla}_{X^*} \tilde{f}$. By (2.1.2) and Proposition 3.1.1 we have for $f \in C^\infty(G; V)_K$ and $x \in G$

$$\tilde{f}(xK) = \iota(x \circ f(x)) = \rho(x)f(x).$$

Hence we have by (3.1.2)

$$\begin{aligned} g(x) &= \rho(x)^{-1}(\bar{\nabla}_{X^*} \tilde{f})(xK) = \rho(x)^{-1}X^*_{xK} \tilde{f} \\ &= \rho(x)^{-1} \lim_{t \rightarrow 0} \frac{1}{t} (\tilde{f}((\exp tX)xX) - \tilde{f}(xK)) \\ &= \rho(x)^{-1} \lim_{t \rightarrow 0} \frac{1}{t} \{ \rho((\exp tX)x)f((\exp tX)x) - \rho(x)f(x) \} \\ &= \lim_{t \rightarrow 0} \frac{1}{t} \{ \rho(\exp t(\text{Ad}(x^{-1})X))f((\exp tX)x) - f((\exp tX)x) \\ &\quad + f((\exp tX)x) - f(x) \} \\ &= d\rho(\text{Ad}(x^{-1})X)f(x) + (\hat{X}f)(x). \end{aligned}$$

This proves the lemma.

Q.E.D.

REMARK 3.1.1. Since left translations of G are commutative with right translations of G , we have $\hat{X}f \in C^\infty(G; V)_K$. Therefore we have $d\rho(\text{Ad}(*^{-1})X)f \in C^\infty(G; V)_K$.

Lemma 3.1.3. (1) *We have for $X \in \mathfrak{g}$ and $f \in C^\infty(G; V^N)_K$*

$$(3.1.4) \quad D_{X^*} \hat{f} = \iota(\hat{X}f + \{d\rho(\text{Ad}(*^{-1})X)f\}^N),$$

$$(3.1.5) \quad -A_{\bar{f}} X^* = \iota(\{d\rho(\text{Ad}(*^{-1})X)f\}^T),$$

where we denote by g^N (resp. g^T) the V^N -component (resp. V^T -component) of $g \in C^\infty(G; V)_K$ with respect to the decomposition (3.1.1).

(2) *We have for $X \in \mathfrak{g}$ and $f \in C^\infty(G; V^T)_K$*

$$(3.1.6) \quad B(X^*, \hat{f}) = \iota(\{d\rho(\text{Ad}(*^{-1})X)f\}^N).$$

Proof. The lemma is an easy consequence of (1.1.1), (1.1.2), Proposition 3.1.1 and Lemma 3.1.2. Q.E.D.

For the differential operators \bar{A}_0 and Δ_0 defined in subsection 2.2, we obtain the following two propositions.

Proposition 3.1.4. *We have for $f \in C^\infty(G; V^N)_K$*

$$(3.1.7) \quad \bar{A}_0(\hat{f}) = \iota\left(-\sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^T\}^N\right),$$

where $\{E_1, \dots, E_{n+p}\}$ is an orthonormal basis of \mathfrak{g} .

Proof. Applying Lemma 3.1.3, we have

$$\begin{aligned} \bar{A}_0(\hat{f}) &= \sum_{i=1}^{n+p} B(E_i^*, A_{\bar{f}} E_i^*) \\ &= \sum_{i=1}^{n+p} \iota\left(-\left(d\rho(\text{Ad}(*^{-1})E_i)\{d\rho(\text{Ad}(*^{-1})E_i)f\}^T\right)^N\right). \end{aligned}$$

Put $\text{Ad}(x)E_i = \sum_{j=1}^{n+p} a^j_i(x)E_j$ for $x \in G$. Then $(a^j_i(x))_{i,j=1,\dots,n+p}$ is an orthogonal matrix. We have for $x \in G$

$$\begin{aligned} &\sum_{i=1}^{n+p} \left(d\rho(\text{Ad}(*^{-1})E_i)\{d\rho(\text{Ad}(*^{-1})E_i)f\}^T\right)^N(x) \\ &= \sum_{i=1}^{n+p} \left(d\rho(\text{Ad}(x^{-1})E_i)\{d\rho(\text{Ad}(x^{-1})E_i)f(x)\}^T\right)^N \\ &= \sum_{j,k=1}^{n+p} \left(\sum_{i=1}^{n+p} a^j_i(x^{-1})a^k_i(x^{-1})\{d\rho(E_j)(d\rho(E_k)f(x))^T\}^N\right) \\ &= \sum_{j=1}^{n+p} \{d\rho(E_j)(d\rho(E_j)f)^T\}^N(x). \end{aligned}$$

Therefore

$$\tilde{A}_0(\tilde{f}) = \iota\left(-\sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^T\}^N\right).$$

Q.E.D.

Proposition 3.1.5. *We have for $f \in C^\infty(G; V^N)_K$*

$$(3.1.8) \quad \Delta_0 \tilde{f} = \iota\left(\sum_{i=1}^{n+p} E_i E_i f + 2 \sum_{i=1}^{n+p} (d\rho(E_i)(E_i f))^N + \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N\right),$$

where $\{E_1, \dots, E_{n+p}\}$ is an orthonormal basis of \mathfrak{g} .

Proof. Applying Lemma 3.1.3, we have

$$\begin{aligned} \Delta_0 \tilde{f} &= \sum_{i=1}^{n+p} D_{E_i^*} D_{E_i^*} \tilde{f} \\ &= \iota\left(\sum_{i=1}^{n+p} (\hat{E}_i(\hat{E}_i f + \{d\rho(\text{Ad}(*^{-1})E_i f)\}^N) \right. \\ &\quad \left. + \{d\rho(\text{Ad}(*^{-1})E_i)(\hat{E}_i f + \{d\rho(\text{Ad}(*^{-1})(E_i f)\}^N)\}^N)\right) \\ &= \iota\left(\sum_{i=1}^{n+p} \hat{E}_i \hat{E}_i f + \sum_{i=1}^{n+p} \hat{E}_i \{d\rho(\text{Ad}(*^{-1})E_i) f\}^N \right. \\ &\quad \left. + \sum_{i=1}^{n+p} \{d\rho(\text{Ad}(*^{-1})E_i)(\hat{E}_i f)\}^N \right. \\ &\quad \left. + \sum_{i=1}^{n+p} \{d\rho(\text{Ad}(*^{-1})E_i)\{d\rho(\text{Ad}(*^{-1})E_i) f\}^N\}^N\right). \end{aligned}$$

We have (cf. Takeuchi [12] p. 51)

$$(3.1.9) \quad \sum_{i=1}^{n+p} \hat{E}_i \hat{E}_i = \sum_{i=1}^{n+p} E_i E_i.$$

Put $\text{Ad}(x)E_i = \sum_{j=1}^{n+p} a^j_i(x)E_j$. Then we have for $x \in G$

$$(3.1.10) \quad \begin{aligned} (\hat{E}_i)_x &= dr_x(E_i)_e = dl_x(dl_{x^{-1}} dr_x(E_i)_e) \\ &= dl_x(\text{Ad}(x^{-1})E_i)_e \\ &= \sum_{j=1}^{n+p} a^j_i(x^{-1}) dl_x(E_j)_e \\ &= \sum_{j=1}^{n+p} a^j_i(x) (E_j)_x, \end{aligned}$$

where r_x (resp. l_x) denotes the right translation (resp. left translation) by $x \in G$.

We obtain

$$(3.1.11) \quad \{d\rho(\text{Ad}(*^{-1})E_i) f\}(x) = d\rho(\text{Ad}(x^{-1})E_i) f(x)$$

$$\begin{aligned}
 &= \sum_{j=1}^{n+p} a^j(x^{-1})d\rho(E_j)f(x) \\
 &= \sum_{j=1}^{n+p} a^j(x)d\rho(E_j)f(x).
 \end{aligned}$$

By (3.1.11) and (3.1.10) we have

$$\begin{aligned}
 &\sum_{i=1}^{n+p} \hat{E}_i \{d\rho(\text{Ad}(*^{-1})E_i)f\}^N \\
 &= \sum_{i,j=1}^{n+p} ((\hat{E}_i a^j)(d\rho(E_j)f)^N + a^j \{d\rho(E_j)(\hat{E}_i f)\}^N) \\
 &= \sum_{i,j=1}^{n+p} (\hat{E}_i a^j)(d\rho(E_j)f)^N + \sum_{j,k=1}^{n+p} \sum_{i=1}^{n+p} a^i a^k \{d\rho(E_j)(E_k f)\}^N \\
 &= \sum_{i,j=1}^{n+p} (\hat{E}_i a^j)(d\rho(E_j)f)^N + \sum_{j=1}^{n+p} \{d\rho(E_j)(E_j f)\}^N.
 \end{aligned}$$

Since the inner product \langle , \rangle on \mathfrak{g} is $\text{Ad}(G)$ -invariant, we have

$$\begin{aligned}
 (\hat{E}_i a^j)(x) &= \lim_{t \rightarrow 0} \frac{1}{t} (\langle \text{Ad}((\exp tE_i)x)E_j, E_i \rangle - \langle \text{Ad}(x)E_j, E_i \rangle) \\
 &= \lim_{t \rightarrow 0} \frac{1}{t} \langle \text{Ad}(\exp tE_i)\text{Ad}(x)E_j - \text{Ad}(x)E_j, E_i \rangle \\
 &= \langle \text{ad}(E_i)\text{Ad}(x)E_j, E_i \rangle \\
 &= -\langle \text{Ad}(x)E_j, \text{ad}(E_i)E_i \rangle = 0
 \end{aligned}$$

Therefore we obtain

$$(3.1.12) \quad \sum_{i=1}^{n+p} \hat{E}_i \{d\rho(\text{Ad}(*^{-1})E_i)f\}^N = \sum_{i=1}^{n+p} \{d\rho(E_i)(E_i f)\}^N.$$

We have by (3.1.10) and (3.1.11)

$$\begin{aligned}
 (3.1.13) \quad &\sum_{i=1}^{n+p} \{d\rho(\text{Ad}(*^{-1})E_i)(\hat{E}_i f)\}^N \\
 &= \sum_{j,k=1}^{n+p} \sum_{i=1}^{n+p} a^i a^k \{d\rho(E_j)(E_k f)\}^N \\
 &= \sum_{j=1}^{n+p} \{d\rho(E_j)(E_j f)\}^N.
 \end{aligned}$$

We have by (3.1.11)

$$\begin{aligned}
 (3.1.14) \quad &\sum_{i=1}^{n+p} \{d\rho(\text{Ad}(*^{-1})E_i) \{d\rho(\text{Ad}(*^{-1})E_i)f\}^N\}^N \\
 &= \sum_{i=1}^{n+p} \left\{ \sum_{j=1}^{n+p} a^j d\rho(E_j) \left\{ \sum_{k=1}^{n+p} a^k d\rho(E_k)f \right\}^N \right\}^N \\
 &= \sum_{j,k=1}^{n+p} \sum_{i=1}^{n+p} a^i a^k \{d\rho(E_j)(d\rho(E_k)f)^N\}^N
 \end{aligned}$$

$$= \sum_{j=1}^{n+p} \{d\rho(E_j)(d\rho(E_j)f)^N\}^N.$$

We obtain (3.1.8) by (3.1.9), (3.1.12), (3.1.13) and (3.1.14).

Q.E.D.

3.2. In the rest of this section we moreover assume that the equivariant isometric immersion $F: (M, c\langle \cdot, \cdot \rangle) \rightarrow S$ is minimal. Let Δ_M be the Laplace operator of the Riemannian manifold $(M, \langle \cdot, \cdot \rangle)$ acting on functions. Then we have (cf. Wallach [13] p. 20)

$$\Delta_M = \sum_{i=1}^{n+p} (E_i^*)^2,$$

where $\{E_1, \dots, E_{n+p}\}$ is an orthonormal basis of \mathfrak{g} . Hence the Laplace operator $\Delta_M(c)$ of $(M, c\langle \cdot, \cdot \rangle)$ is given by the following equation:

$$(3.2.1) \quad \Delta_M(c) = \frac{1}{c} \sum_{i=1}^{n+p} (E_i^*)^2.$$

Let $\{e_1, \dots, e_N\}$ be an orthonormal basis of V and (x_1, \dots, x_N) the coordinate system on V with respect to $\{e_1, \dots, e_N\}$. Put $F = (f_1, \dots, f_N)$, i.e. $f_i(xK) = \langle e_i, F(xK) \rangle$. Then it is known (Takahashi [11] p. 383) that

$$(3.2.2) \quad \Delta_M(c)f_i = -nf_i, \quad i=1, \dots, N.$$

We define an action L of G on $C^\infty(M)$, the space of C^∞ functions on M , as follows:

$$(L_x f)(yK) = f(x^{-1}yK) \quad \text{for } x, y \in G \text{ and } f \in C^\infty(M).$$

Proposition 3.2.1. *Let $\rho: G \rightarrow GL(V)$ be an orthogonal representation of G . Let $F: (M, c\langle \cdot, \cdot \rangle) \rightarrow S$, $F(xK) = \rho(x)F(o)$, be an equivariant minimal isometric immersion. If F is full, i.e. if the image $F(M)$ of M is not contained in any great spheres, then the following equation holds:*

$$(3.2.3) \quad \sum_{i=1}^{n+p} d\rho(E_i)d\rho(E_i) = -nc1_V,$$

where 1_V denotes the identity transformation of V .

Proof. Let $\{e_1, \dots, e_N\}$ be an orthonormal basis of V and put $F = (f_1, \dots, f_N)$ with respect to this basis. We define a linear mapping $\phi: V \rightarrow C^\infty(M)$ by $\phi(v)(xK) = \langle v, F(xK) \rangle$ for $v \in V$ and $x \in G$. Then the subspace $\phi(V)$ of $C^\infty(M)$ is spanned by f_1, \dots, f_N . We have for $x, y \in G$ and $v \in V$

$$\begin{aligned} \phi(\rho(x)v)(yK) &= \langle \rho(x)v, F(yK) \rangle = \langle v, \rho(x^{-1})F(yK) \rangle \\ &= \langle v, F(x^{-1}yK) \rangle = \phi(v)(x^{-1}yK) \\ &= (L_x \phi(v))(yK). \end{aligned}$$

Hence ϕ is a G -module homomorphism. Let $\psi: G \rightarrow GL(\phi(V))$ be a representation defined by $\psi(x) = L_x|_{\phi(V)}$. Then we have for $X \in \mathfrak{g}$

$$(3.2.4) \quad d\psi(X) = -X^* .$$

We assert that $\dim \phi(V) = N$. If the assertion is not true, there exist real numbers c_1, \dots, c_N , which are not all equal to zero, such that $\sum_{i=1}^N c_i f_i = 0$. Then the image $F(M)$ is contained in the hyperplane $\sum_{i=1}^N c_i x_i = 0$, which is a contradiction. Therefore $\phi: V \rightarrow \phi(V)$ is a G -module isomorphism. It follows from (3.2.4), (3.2.1) and (3.2.2) that

$$\begin{aligned} \sum_{i=1}^{n+\rho} d\psi(E_i) d\psi(E_i) f_k &= \sum_{i=1}^{n+\rho} E_i^* E_i^* f_k \\ &= c \Delta_M(c) f_k = -n c f_k . \end{aligned}$$

Hence we have $\sum_{i=1}^{n+\rho} d\psi(E_i) d\psi(E_i) = n c 1_{\phi(V)}$, where $1_{\phi(V)}$ denotes the identity transformation of $\phi(V)$. Since $\phi: V \rightarrow \phi(V)$ is a G -module isomorphism, we have

$$\sum_{i=1}^{n+\rho} d\rho(E_i) d\rho(E_i) = -n c 1_V .$$

Q.E.D.

REMARK 3.2.1. Suppose that the linear isotropy representation of G/K is irreducible. Let $\rho: G \rightarrow GL(V)$ be a real spherical representation of (G, K) , i.e. ρ is an irreducible orthogonal representation of G such that there is a unit vector $v \in V$ with the property that $\rho(k)v = v$ for any $k \in K$. Then we can construct a full equivariant minimal isometric immersion of $M = G/K$ in the following way. Let S be the unit sphere of V with the center 0. Define a mapping $F: M \rightarrow S$ by $F(xK) = \rho(x)v$ for $x \in G$. Then there exists a positive number c such that $F: (M, c\langle \cdot, \cdot \rangle) \rightarrow S$ is a minimal isometric immersion (cf. Wallach [13] p. 21).

Let \mathfrak{t} be a Cartan subalgebra of \mathfrak{g} . We denote by \mathfrak{g}^c the complexification of \mathfrak{g} . For a linear subspace \mathfrak{u} of \mathfrak{g} we denote by \mathfrak{u}^c the complex linear subspace of \mathfrak{g}^c generated by \mathfrak{u} . Let \mathfrak{r} be the root system of \mathfrak{g}^c with respect to \mathfrak{t} . A non-zero element $\lambda \in \mathfrak{t}$ is a root, if and only if there exists a non-zero element $X \in \mathfrak{g}^c$ such that $[H, X] = \sqrt{-1} \langle \lambda, H \rangle X$ for any $H \in \mathfrak{t}$. Choosing a linear order in \mathfrak{t} , we denote by \mathfrak{r}^+ the set of all positive roots. Put

$$\delta = \frac{1}{2} \sum_{\lambda \in \mathfrak{r}^+} \lambda .$$

Let (G, K) be a Riemannian symmetric pair and $D(G, K)$ the set of all equivalence classes of complex spherical representations of (G, K) . Recall that an irreducible complex representation $\phi: G \rightarrow GL(W)$ is called a complex spherical representation of (G, K) , if there exists a non-zero vector $w \in W$ such that

$\phi(k)w=w$ for any $k \in K$. For a complex irreducible representation $\phi: G \rightarrow GL(W)$, we denote by $[\phi]$ the equivalence class to which ϕ belongs. For $[\phi] \in D(G, K)$ we denote by $\mathfrak{o}_{[\phi]}(M)$ the subspace of $C^\infty(M)^c$ generated by G -submodules of $C^\infty(M)^c$ which are isomorphic to ϕ , where $C^\infty(M)^c$ is the complexification of $C^\infty(M)$ (We will not distinguish G -modules and representations of G). Then $\mathfrak{o}_{[\phi]}(M)$ is isomorphic to ϕ as G -module and the Laplace operator Δ_M acts on $\mathfrak{o}_{[\phi]}(M)$ as a scalar operator $c_{[\phi]}$. The scalar $c_{[\phi]}$ is given by $-\langle \Lambda + 2\delta, \Lambda \rangle$, where Λ is the highest weight of ϕ (cf. Takeuchi [12] p. 20, p. 207).

If the Riemannian symmetric pair (G, K) is of rank 1, there exists a dominant integral form Λ_0 such that the highest weight Λ of each complex spherical representation ϕ is given by $\Lambda = k\Lambda_0$ for some non-negative integer k (cf. Takeuchi [12] p. 166). Hence the scalar $c_{[\phi]}$ is given by $-\langle k\Lambda_0 + 2\delta, k\Lambda_0 \rangle = -(k^2\langle \Lambda_0, \Lambda_0 \rangle + 2k\langle \delta, \Lambda_0 \rangle)$. Since both $\langle \Lambda_0, \Lambda_0 \rangle$ and $\langle \delta, \Lambda_0 \rangle$ are positive, it follows that $c_{[\phi]} \neq c_{[\phi']}$ for $[\phi], [\phi'] \in D(G, K)$ with $[\phi] \neq [\phi']$. Therefore we have the following lemma.

Lemma 3.2.2. *If (G, K) is a Riemannian symmetric pair of rank 1, then each eigenspace of the Laplace operator Δ_M acting on $C^\infty(M)^c$ is irreducible.*

Proposition 3.2.3. *Assume that (G, K) is a Riemannian symmetric pair of rank 1. Let $\rho: G \rightarrow GL(V)$ be an orthogonal representation and the mapping $F: (M, \langle \cdot, \cdot \rangle) \rightarrow S, F(xK) = \rho(x)F(o)$, an equivariant minimal isometric immersion. If F is full, the complexification $\rho: G \rightarrow GL(V^c)$ of ρ is irreducible. Therefore $\rho: G \rightarrow GL(V)$ is irreducible.*

Proof. Put $F = (f_1, \dots, f_N)$ as in the proof of Proposition 3.2.1. We also denote by $\langle \cdot, \cdot \rangle$ the Hermitian inner product on V^c which is the extension of the inner product $\langle \cdot, \cdot \rangle$ on V . Let $\phi: V^c \rightarrow C^\infty(M)^c$ be the \mathbf{C} -linear mapping defined by $\phi(v)(xK) = \langle v, F(xK) \rangle$ for $v \in V^c$ and $x \in G$. We assert that $\{f_1, \dots, f_N\}$ is linear independent over \mathbf{C} . If the assertion is not true, there exist complex numbers c_1, \dots, c_N , which are not all equal to zero, such that $\sum_{i=1}^N c_i f_i = 0$. Put $c_i = a_i + \sqrt{-1}b_i$, where a_i and b_i are real numbers. Then at least one of the equations $\sum_{i=1}^N a_i x_i = 0$ and $\sum_{i=1}^N b_i x_i = 0$ defines a hyperplane. Since every f_i is real valued, the image $F(M)$ is contained in this hyperplane. This is a contradiction. Hence by the proof of Proposition 3.2.1 we have that $\phi: V^c \rightarrow \phi(V^c)$ is a G -module isomorphism and that $\Delta_M f = -ncf$ for $f \in \phi(V^c)$. Therefore it follows from Lemma 3.2.2 that $\phi(V^c)$ is an irreducible G -module. Hence $\rho: G \rightarrow GL(V^c)$ is irreducible. Q.E.D.

REMARK 3.2.2. Assume that (G, K) is a Riemannian symmetric pair of rank 1. Then full equivariant minimal isometric immersions of $M = G/K$ into

spheres are in one-to-one correspondence with complex spherical representations of (G, K) . In fact a complex spherical representation of (G, K) corresponds to a full equivariant minimal isometric immersion $F: (M, \langle \cdot, \cdot \rangle) \rightarrow S$ by Proposition 3.2.3. Conversely since (G, K) is of rank 1, every zonal spherical function is real-valued (Do Carmo and Wallach [3] p. 98). Therefore every complex spherical representation of (G, K) is the complexification of a real spherical representation of (G, K) . Hence a full equivariant minimal isometric immersion corresponds to a complex spherical representation of (G, K) (Remark 3.2.1).

3.3. In this subsection we assume that (G, K) is a Riemannian symmetric pair.

Theorem 1. *Let $\rho: G \rightarrow GL(V)$ be an orthogonal representation and $F: (M, \langle \cdot, \cdot \rangle) \rightarrow S$, $F(xK) = \rho(x)F(o)$, a full equivariant minimal isometric immersion. Then we have for $f \in C^\infty(G; V^N)_K$*

$$(3.3.1) \quad Sf = -\frac{1}{c} \left(\sum_{i=1}^{n+p} E_i E_i f - 2c_\rho f \right) + 2 \sum_{i=1}^{n+p} \{d\rho(E_i)(E_i f)\}^N + 2 \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N,$$

where $c_\rho = -nc$ and $\{E_1, \dots, E_{n+p}\}$ is an orthonormal basis of \mathfrak{g} .

Proof. Since the condition of Proposition 2.2.2 is satisfied (Remark 2.2.1), it follows from (1.2.5), (1.2.3), (2.2.3) and (2.2.4) that $\tilde{S} = -\frac{1}{c}(\Delta_0 + \tilde{A}_0 + nc1_{\Gamma(N(M))})$, where $1_{\Gamma(N(M))}$ is the identity transformation of $\Gamma(N(M))$. Hence we have by (3.1.7) and (3.1.8)

$$\tilde{S}f = \iota \left(-\frac{1}{c} \left(\sum_{i=1}^{n+p} E_i E_i f + 2 \sum_{i=1}^{n+p} (d\rho(E_i)(E_i f))^N + \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N - \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^T\}^N - c_\rho f \right) \right).$$

Applying (3.2.3), we have

$$\begin{aligned} & \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^T\}^N \\ &= \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)\}^N - \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N \\ & \quad - \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^0\}^N \\ &= -ncf - \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N - \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^0\}^N. \end{aligned}$$

In the above equation $(d\rho(E_i)f)^0$ denotes the V^0 -component of $d\rho(E_i)f$ with respect to the orthogonal decomposition (3.1.1). Since $d\rho(\mathfrak{g})v_0=V^T$, we have $\sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^0\}^N=0$. Hence we have

$$Sf = -\frac{1}{c} \left(\sum_{i=1}^{n+p} E_i E_i f + 2 \sum_{i=1}^{n+p} \{d\rho(E_i)(E_i f)\}^N \right. \\ \left. + 2 \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N - 2c_\rho f \right).$$

Q.E.D.

REMARK 3.3.1. It follows from Remark 3.1.1, (3.1.9), (3.1.12) and (3.1.14) that $\sum_{i=1}^{n+p} E_i E_i f$, $\sum_{i=1}^{n+p} \{d\rho(E_i)(E_i f)\}^N$, $\sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N \in C^\infty(G; V^N)_K$ for $f \in C^\infty(G; V^N)_K$. Moreover each of the above three operators is commutative with L_x for all $x \in G$.

We define an operator $S_1: C^\infty(G; V^N)_K \rightarrow C^\infty(G; V^N)_K$ by

$$S_1 f = \sum_{i=1}^{n+p} \{d\rho(E_i)(E_i f)\}^N + \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N \\ \text{for } f \in C^\infty(G; V^N)_K.$$

By Proposition 3.1.1 the operator S_1 corresponds to a first order differential operator on $N(M)$. We denote by \tilde{S}_1 the corresponding differential operator on $N(M)$. If $S_1=0$, the operator S reduces to the simple operator

$$-\frac{1}{c} \left(\sum_{i=1}^{n+p} E_i E_i - 2c_\rho 1_{C^\infty(G; V^N)_K} \right),$$

where $1_{C^\infty(G; V^N)_K}$ is the identity transformation of $C^\infty(G; V^N)_K$. The following lemma provides a sufficient condition for $S_1=0$. In fact this condition is also necessary (see Proposition 4.2.2).

Lemma 3.3.1. *If $(d\rho(X)v)^N=0$ for $X \in \mathfrak{p}$ and $v \in V^N$, then we have $S_1=0$.*

Proof. Choose an orthonormal basis $\{E_1, \dots, E_{n+p}\}$ of \mathfrak{g} such that $\{E_1, \dots, E_n\}$ (resp. $\{E_{n+1}, \dots, E_{n+p}\}$) is an orthonormal basis of \mathfrak{p} (resp. of \mathfrak{k}). We have for $x \in G$, $f \in C^\infty(G; V^N)_K$ and E_i , $i=n+1, \dots, n+p$,

$$(E_i f)(x) = \lim_{t \rightarrow 0} \frac{1}{t} (f(x(\exp tE_i)) - f(x)) \\ = \lim_{t \rightarrow 0} \frac{1}{t} (\rho(\exp -tE_i)f(x) - f(x)) \\ = -d\rho(E_i)f(x).$$

Hence

$$\begin{aligned} S_1 f &= \sum_{i=1}^{n+p} \{d\rho(E_i)(E_i f)\}^N + \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N \\ &= \sum_{i=1}^n \{d\rho(E_i)(E_i f)\}^N - \sum_{i=n+1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)\}^N \\ &\quad + \sum_{i=1}^n \{d\rho(E_i)(d\rho(E_i)f)^N\}^N + \sum_{i=n+1}^{n+p} \{d\rho(E_i)(d\rho(E_i)f)^N\}^N. \end{aligned}$$

Since V^N is invariant under $\rho(k)$ for $k \in K$, we have $(d\rho(E_i)f)^N = d\rho(E_i)f$, $i = n+1, \dots, n+p$. Therefore we have

$$S_1 f = \sum_{i=1}^n \{d\rho(E_i)(E_i f)\}^N + \sum_{i=1}^n \{d\rho(E_i)(d\rho(E_i)f)^N\}^N.$$

Thus we obtain the proposition.

Q.E.D.

REMARK 3.3.2. In the following cases the operator S_1 vanishes.

(1) The case of the minimal isometric immersion of S^n induced from the representation ρ_2 , which is defined as follows: When $(G, K) = (SO(n+1), SO(n))$, the highest weight ϕ_1 of the canonical representation of $SO(n+1)$ has the property of Λ_0 in the proof of Lemma 3.2.2. Our representation ρ_2 is the real spherical representation whose complexification has the highest weight $2\phi_1$ (Remark 3.2.2).

(2) The cases of minimal symmetric R -spaces (see Nagura [8]), which include (1) as a special case.

3.4. Let N be a connected Riemannian manifold and \tilde{N} the universal Riemannian covering manifold of N . Then we have by the universal property

Lemma 3.4.1. *For each isometry $x \in I(N)$ there exists an isometry $\tilde{x} \in I(\tilde{N})$ such that $\pi \circ \tilde{x} = x \circ \pi$, where $\pi: \tilde{N} \rightarrow N$ is the covering map.*

In this subsection we assume that G acts on M almost effectively. This means that \mathfrak{k} does not contain any trivial ideals of \mathfrak{g} .

Proposition 3.4.2. *Let \tilde{M} be the universal Riemannian covering manifold of M . If the equivariant minimal isometric immersion $F: (M, c\langle \cdot, \cdot \rangle) \rightarrow S$, $F(xK) = \rho(x)F(o)$, is full and if $\dim G = \dim I(\tilde{M})$, then the Killing nullity of F is equal to $\frac{m(m-1)}{2} - \dim G$. Here $m = \dim V$.*

Proof. Let $I^o(S, M)$ be the identity component of $I(S, M)$. By the argument in subsection 2.3 it is sufficient to show that $\dim I^o(S, M) = \dim G$. It is trivial that $I^o(S, M)$ contains $\rho(G)$. Put $K' = \{x \in G; \rho(x)F(o) = F(o)\}$. Since F is an immersion, $\dim K' = \dim K$ and hence the Lie algebra of K' coincides with \mathfrak{k} . Therefore G acts on V almost effectively and we have

$$(3.4.1) \quad \dim \rho(G) = \dim G.$$

Since the image $F(M)$ of M is the orbit of G through $F(o)$, $F(M)$ is a regular submanifold of S . Let $I^\circ(F(M))$ be the identity component of $I(F(M))$, the group of all isometries of the Riemannian manifold $F(M)$. Since F is full, we may consider $\rho(G)$ as a closed subgroup of $I^\circ(F(M))$. It follows from Lemma 3.4.1, the assumption of the proposition and (3.4.1) that

$$\dim I^\circ(F(M)) \leq \dim I(\tilde{M}) = \dim \rho(G).$$

Therefore we have

$$I^\circ(F(M)) = \rho(G).$$

Let A be an element of $I^\circ(S, M)$. Since $F(M)$ is a regular submanifold of S , A induces an isometry of $F(M)$, which is contained in $I^\circ(F(M))$. Then there exists an element $x \in G$ such that the actions $\rho(x)$ and A coincide on $F(M)$. Since F is full, we have $A = \rho(x)$. Therefore $I^\circ(S, M)$ coincides with $\rho(G)$. Thus we obtain the proposition. Q.E.D.

REMARK 3.4.1. The condition $\dim G = \dim I(\tilde{M})$ is satisfied, when the pair (G, K) is an almost effective Riemannian symmetric pair and when G is semi-simple.

4. Invariant differential operators

4.1. Let G be a connected Lie group and K a closed subgroup of G . We assume that the quotient space $M = G/K$ is reductive, i.e. the Lie algebra \mathfrak{g} of G may be decomposed into a vector space direct sum of the Lie algebra \mathfrak{k} of K and an $\text{Ad}(K)$ -invariant subspace \mathfrak{p} . We identify \mathfrak{p} with the tangent space $T_o(M)$ at the origin $o \in M$.

Let $\phi: K \rightarrow GL(U)$ be a real (or complex) representation and put $\xi = G \times_K U$. For each $x \in G$ we define an automorphism $\alpha_x: \xi \rightarrow \xi$ by

$$\alpha_x(y \circ u) = xy \circ u \quad \text{for } y \in G \text{ and } u \in U.$$

We also denote by α_x the automorphism α_x of $\Gamma(\xi)$, the space of all C^∞ cross-sections of ξ , defined by $(\alpha_x \tilde{f})(yK) = \alpha_x(\tilde{f}(x^{-1}yK))$ for $\tilde{f} \in \Gamma(\xi)$ and $y \in G$. We have for $\tilde{f} \in \Gamma(\xi)$, $\tilde{a} \in C^\infty(M)$ and $x, y \in G$

$$\begin{aligned} (\alpha_x(\tilde{a}\tilde{f}))(yK) &= \alpha_x(\tilde{a}(x^{-1}yK)\tilde{f}(x^{-1}yK)) \\ &= \tilde{a}(x^{-1}yK)\alpha_x(\tilde{f}(x^{-1}yK)) \\ &= (\tau_{x^{-1}}^* \tilde{a})(yK)(\alpha_x \tilde{f})(yK). \end{aligned}$$

Hence we obtain

$$(4.1.1) \quad \alpha_x(\tilde{a}\tilde{f}) = (\tau_{x^{-1}}^* \tilde{a})(\alpha_x \tilde{f}).$$

Put

$$C^\infty(G; U)_K = \left. \begin{array}{l} \{f: G \rightarrow U, \text{ } C^\infty \text{ mapping; } f(xK) = \phi(k^{-1})f(x) \\ \text{for } x \in G \text{ and } k \in K \end{array} \right\}.$$

Then as in subsection 2.1 we have the isomorphism $\iota: C^\infty(G; U)_K \rightarrow \Gamma(\xi)$, $(\iota(f))(xK) = x \circ f(x)$, and the following commutative diagram:

$$\begin{array}{ccc} C^\infty(G; U)_K & \xrightarrow{\iota} & \Gamma(\xi) \\ \downarrow L_x & & \downarrow \alpha_x \\ C^\infty(G; U)_K & \xrightarrow{\iota} & \Gamma(\xi). \end{array}$$

We denote by \tilde{f} the image $\iota(f)$ of f . Put

$$C^\infty(G)_K = \{a \in C^\infty(G): a(xk) = a(x) \text{ for } x \in G \text{ and } k \in K\}.$$

Then the pull back $\pi^*: C^\infty(M) \rightarrow C^\infty(G)_K$ is an isomorphism, where $\pi: G \rightarrow M = G/K$ is the natural projection. We denote by \tilde{a} the inverse image $\pi^{*-1}(a)$ of $a \in C^\infty(G)_K$. For $f \in C^\infty(G; U)_K$ and $a \in C^\infty(G)_K$ we have $af \in C^\infty(G; U)_K$ and

$$(4.1.2) \quad \iota(af) = \tilde{a}\tilde{f}.$$

Let $\psi: K \rightarrow GL(V)$ be a real (or complex) representation and put $\eta = G \times_K V$. We define automorphisms $\beta_x: \eta \rightarrow \eta$ and $\beta_x: \Gamma(\eta) \rightarrow \Gamma(\eta)$ in the same manner as for ξ . Let $\text{Diff}_h(\xi, \eta)$ be the set of all h -th order differential operators from ξ to η . A differential operator $D \in \text{Diff}_h(\xi, \eta)$ is said to be *invariant*, if $D \circ \alpha_x = \beta_x \circ D$ for every $x \in G$. Let D be an h -th order differential operator from ξ to η . Then for each $p \in M$ the symbol $\sigma_h(D)$ of D defines an h -th order homogeneous polynomial mapping from the cotangent space $T_p^*(M)$ to $\text{Hom}(\xi_p, \eta_p)$ (cf. Palais [9] p. 62), where $\text{Hom}(\xi_p, \eta_p)$ denotes the vector space of all linear mappings from ξ_p to η_p .

Let ${}^t(d\tau_x)$ be the transposed mapping of the differential $d\tau_x$ of τ_x , $x \in G$. Then we have for $\tilde{a} \in C^\infty(M)$ and $x, y \in G$

$$(4.1.3) \quad d(\tau_{x^{-1}}^* \tilde{a})_{xyK} = \tau_{x^{-1}}^*(d\tilde{a})_{yK} = {}^t(d\tau_{x^{-1}})(d\tilde{a})_{yK}.$$

Proposition 4.1.1. *Assume that a differential operator $D \in \text{Diff}_h(\xi, \eta)$ is invariant. Then we have for $x, y \in G$, $v \in T_{yK}^*(M)$ and $\omega \in \xi_{yK}$*

$$(4.1.4) \quad \sigma_h(D)({}^t(d\tau_{x^{-1}})v)(\alpha_x(\omega)) = \beta_x(\sigma_h(D)(v)(\omega)).$$

Proof. Take $\tilde{a} \in C^\infty(M)$ (resp. $\tilde{f} \in \Gamma(\xi)$) which satisfies $\tilde{a}(yK) = 0$ and $d\tilde{a}_{yK} = v$ (resp. $\tilde{f}(yK) = \omega$). Then we have

$$(\tau_{x^{-1}}^* \tilde{a})(xyK) = \tilde{a}(yK) = 0$$

and

$$(\alpha_x \tilde{f})(xyK) = \alpha_x(\tilde{f}(yK)) = \alpha_x(\omega).$$

By (4.1.3) we have

$$d(\tau_{x^{-1}}^* \tilde{a})_{xyK} = {}^t(d\tau_{x^{-1}})(d\tilde{a})_{yK} = {}^t(d\tau_{x^{-1}})v.$$

Applying (4.1.1), we have

$$\alpha_x \left(\frac{1}{h!} \tilde{a}^h \tilde{f} \right) = \frac{1}{h!} (\tau_{x^{-1}}^* \tilde{a})^h (\alpha_x \tilde{f}).$$

Hence it follows from the definition of the symbol $\sigma_h(D)$ and the invariance of D that

$$\begin{aligned} \sigma_h(D)({}^t(d\tau_{x^{-1}})v)(\alpha_x(\omega)) &= D \left(\frac{1}{h!} (\tau_{x^{-1}}^* \tilde{a})^h (\alpha_x \tilde{f}) \right) (xyK) \\ &= D \left(\alpha_x \left(\frac{1}{h!} \tilde{a}^h \tilde{f} \right) \right) (xyK) \\ &= \beta_x \left(D \left(\frac{1}{h!} \tilde{a}^h \tilde{f} \right) (yK) \right) \\ &= \beta_x(\sigma_h(D)(v)(\omega)). \end{aligned}$$

Q.E.D.

Corollary 1. *Assume that $D \in \text{Diff}_h(\xi, \eta)$ is invariant. If $\sigma_h(D)_o = 0$, then $\sigma_h(D) = 0$.*

Proof. The corollary is an immediate consequence of the proposition.
Q.E.D.

If D is a first order differential operator, the symbol $\sigma_1(D)_p$, $p \in M$, defines a bilinear mapping from $T_p^*(M) \times \xi_p$ to η_p . We also denote by $\sigma_1(D)_p$ the linear mapping from $T_p^*(M) \otimes \xi_p$ to η_p induced from the bilinear mapping $\sigma_1(D)_p$. We have easily the following corollary.

Corollary 2. *If a differential operator $D \in \text{Diff}_1(\xi, \eta)$ is invariant, then the linear mapping $\sigma_1(D)_o: \mathfrak{p}^* \otimes U = T_o^*(M) \otimes \xi_o \rightarrow \eta_o = V$ is a K -module homomorphism, i.e. for each $k \in K$*

$$\sigma_1(D)_o \circ {}^t \text{Ad}_{\mathfrak{p}}(k^{-1}) \otimes \phi(k) = \psi(k) \circ \sigma_1(D)_o,$$

where the action $\text{Ad}_{\mathfrak{p}}(k)$ is the restriction of $\text{Ad}(k)$ to \mathfrak{p} and \mathfrak{p}^* denotes the dual space of \mathfrak{p} .

4.2. In this subsection the assumptions and the notation are the same as in subsection 3.3.

The differential operator \tilde{S}_1 on $N(M)$ defined in subsection 3.3 is invariant by Remark 3.3.1. Choose an orthonormal basis $\{E_1, \dots, E_{n+p}\}$ of \mathfrak{g} such that $\{E_1, \dots, E_n\}$ (resp. $\{E_{n+1}, \dots, E_{n+p}\}$) is an orthonormal basis of \mathfrak{p} (resp. \mathfrak{k}). Let $\{\phi_1, \dots, \phi_{n+p}\}$ be the basis of the dual space of \mathfrak{g} dual to $\{E_1, \dots, E_{n+p}\}$. We consider $\{\phi_1, \dots, \phi_n\}$ as a basis of $T_o^*(M)$. Then we obtain

Lemma 4.2.1. *We have for $\phi_i \in T_o^*(M)$, $i=1, \dots, n$, and $v \in V^N$*

$$(4.2.1) \quad \sigma_1(\tilde{S}_1)(\phi_i)(v) = (d\rho(E_i)v)^N.$$

Proof. Let N be an open neighborhood of $o \in M$ such that $\pi^{-1}(N)$ is diffeomorphic to $N \times K$, where $\pi: G \rightarrow G/K$ is the natural projection. Let (x_1, \dots, x_n) be the local coordinate system on N defined by $x_i(\exp(\sum_{j=1}^n s_j E_j)K) = s_i$ for $-\varepsilon < s_i < \varepsilon$, where ε is some positive number. For $v \in V^N$ we define a V^N -valued C^∞ function α_v on $\pi^{-1}(N)$ by

$$\alpha_v(\exp(\sum_{j=1}^n s_j E_j)k) = \rho(k^{-1})v \quad \text{for } k \in K.$$

Taking $\varepsilon' > 0$ such that $\varepsilon' < \varepsilon$, put

$$N' = \{\exp(\sum_{j=1}^n s_j E_j)K; -\varepsilon' < s_j < \varepsilon'\}.$$

Then there exists a V^N -valued C^∞ function α'_v on G such that $\alpha_v = \alpha'_v$ on $\pi^{-1}(N')$. We define a V^N -valued C^∞ function β_v on G by

$$\beta_v(x) = \int_K \rho(k)\alpha'_v(xk)dk \quad \text{for } x \in G,$$

where dk denotes the normalized Haar measure of K . Then $\beta_v \in C^\infty(G; V^N)_K$. In fact we have for $x \in G$ and $h \in K$

$$\begin{aligned} \beta_v(xh) &= \int_K \rho(k)\alpha'_v(xhk)dk \\ &= \int_K \rho(h^{-1}(hk))\alpha'_v(xhk)dk \\ &= \rho(h^{-1}) \int_K \rho(hk)\alpha'_v(xhk)dk \\ &= \rho(h^{-1})\beta_v(x). \end{aligned}$$

We have for $x = \exp(\sum_{j=1}^n s_j E_j)h$ ($-\varepsilon' < s_j < \varepsilon'$)

$$\begin{aligned} \beta_v(x) &= \rho(h^{-1}) \int_K \rho(k)\alpha'_v(\exp(\sum_{j=1}^n s_j E_j)k)dk \\ &= \rho(h^{-1}) \int_K v dk = \rho(h^{-1})v. \end{aligned}$$

Therefore $\tilde{\beta}_v(o) = \iota(e_o \beta_v(e)) = v$. Take $\tilde{f}_i \in C^\infty(M)$ such that $\tilde{f}_i = x_i$ on N' and then take $f_i \in C^\infty(G)_x$ such that $\pi^* \tilde{f}_i = f_i$. Then $\tilde{f}_i(o) = 0$ and $(d\tilde{f}_i)_o = \phi_i$. We have by (4.1.2)

$$\begin{aligned} \sigma_1(\tilde{S}_1)(\phi_i)(v) &= \tilde{S}_1(\tilde{f}_i \tilde{\beta}_v)(o) = \tilde{S}_1(\iota(f_i \beta_v))(o) \\ &= \iota(S_1(f_i \beta_v))(o) = S_1(f_i \beta_v)(e) \\ &= \sum_{j=1}^{n+p} \{d\rho(E_j)(E_j(f_i \beta_v))(e)\}^N. \end{aligned}$$

We have by (3.1.13)

$$\begin{aligned} &\sum_{j=1}^{n+p} \{d\rho(E_j)(E_j(f_i \beta_v))(e)\}^N \\ &= \sum_{j=1}^{n+p} \{d\rho(\text{Ad}(*^{-1})E_j)(\hat{E}_j(f_i \beta_v))(e)\}^N \\ &= \sum_{j=1}^{n+p} \{d\rho(E_j)\{(\hat{E}_j f_i)(e)\beta_v(e) + f_i(e)(\hat{E}_j \beta_v)(e)\}\}^N \\ &= (d\rho(E_i)v)^N. \end{aligned}$$

This proves (4.2.1).

Q.E.D.

Proposition 4.2.2. *The following three conditions are equivalent:*

- (1) $(d\rho(X)v)^N = 0$ for $X \in \mathfrak{p}$ and $v \in V^N$.
- (2) $\tilde{S}_1 = 0$.
- (3) $\sigma_1(\tilde{S}_1) = 0$.

Proof. Lemma 3.3.1 shows that (1) implies (2). It is evident that (2) implies (3). Lemma 4.2.1 shows that (3) implies (1). Q.E.D.

The vector spaces V^N and $\mathfrak{p} \otimes V^N$ are K -modules in a natural manner. Since K is compact, we may decompose V^N (resp. $\mathfrak{p} \otimes V^N$) into a direct sum of irreducible K -modules.

Proposition 4.2.3. *If any irreducible component of $\mathfrak{p} \otimes V^N$ is not isomorphic to any irreducible component of V^N , then $S_1 = 0$.*

Proof. Since the representation $\text{Ad}_{\mathfrak{p}}: K \rightarrow GL(\mathfrak{p})$ is orthogonal, the contragradient representation of $\text{Ad}_{\mathfrak{p}}$ coincides with itself. Hence it follows from Corollary 2 for Proposition 4.1.1 and Schur's lemma (cf. Chevalley [2] p. 182) that $\sigma_1(\tilde{S}_1)_o = 0$. Therefore we have our proposition by the above proposition.

Q.E.D.

5. Reduction to the finite dimensional eigenvalue problems

5.1. Let G be a compact connected Lie group and K a closed subgroup of G . We denote by M the quotient space G/K . The G -invariant Riemannian

metric \langle , \rangle on M is the same as in subsection 2.1. Let $D(G)$ be the set of equivalence classes of complex irreducible representations of G . For a complex irreducible representation $\sigma: G \rightarrow GL(W)$ we denote by $\sigma^*: G \rightarrow GL(W^*)$ the contragradient representation of σ on the dual space W^* of W . Let $C^\infty(G)^c$ be the space of \mathbb{C} -valued C^∞ functions on G . We define actions L_x and R_x of G on $C^\infty(G)^c$ by the followings:

$$(L_x f)(y) = f(x^{-1}y), (R_x f)(y) = f(yx) \quad \text{for } f \in C^\infty(G)^c.$$

For $[\sigma] \in D(G)$ let $\mathfrak{o}^L_{[\sigma]}(G)$ (resp. $\mathfrak{o}^R_{[\sigma]}(G)$) be the subspace of $C^\infty(G)^c$ generated by G -submodules of $C^\infty(G)^c$ which are isomorphic to σ by the G -action L (resp. by the G -action R). Then we have $\mathfrak{o}^L_{[\sigma]}(G) = \mathfrak{o}^R_{[\sigma^*]}(G)$.

Let U be a complex vector space with a Hermitian inner product \langle , \rangle and $C^\infty(G; U)$ the space of U -valued C^∞ functions on G . We also denote by L_x (resp. R_x) the action of G on $C^\infty(G; U)$: $(L_x f)(y) = f(x^{-1}y)$ (resp. $(R_x f)(y) = f(yx)$) for $f \in C^\infty(G; U)$. Note that our L_x (resp. R_x) is nothing but the tensor product $L_x \otimes 1_U$ (resp. $R_x \otimes 1_U$) on $C^\infty(G)^c \otimes U = C^\infty(G; U)$. Let $\sigma: G \rightarrow GL(W)$ be a complex irreducible representation. We define a multilinear mapping $\Phi^\sigma: W \times W^* \times U \rightarrow C^\infty(G; U)$ by

$$\Phi^\sigma(w, \omega, u)(x) = \omega(\sigma^{-1}(x)w)u \quad \text{for } w \in W, \omega \in W^* \text{ and } u \in U.$$

We also denote by Φ^σ the induced linear mapping of $W \otimes W^* \otimes U$ to $C^\infty(G; U)$. We define an action $L_\sigma(x)$ (resp. $R_{\sigma^*}(x)$) of G on $W \otimes W^* \otimes U$ by $L_\sigma(x) = \sigma(x) \otimes 1_{W^*} \otimes 1_U$ (resp. $R_{\sigma^*}(x) = 1_W \otimes \sigma^*(x) \otimes 1_U$). Then we have $\Phi^\sigma \circ L_\sigma(x) = L_x \circ \Phi^\sigma$ and $\Phi^\sigma \circ R_{\sigma^*}(x) = R_x \circ \Phi^\sigma$ for every $x \in G$.

Theorem 5.1.1 (cf. Takeuchi [12] p. 15). (1) *We consider $W \otimes W^* \otimes U$ (resp. $C^\infty(G; U)$) as a G -module with the G -action L_σ (resp. L). Then Φ^σ is a G -module isomorphism of $W \otimes W^* \otimes U$ onto $\mathfrak{o}^L_{[\sigma]}(G) \otimes U$.*

(2) *We consider $W \otimes W^* \otimes U$ (resp. $C^\infty(G; U)$) as a G -module with the G -action R_{σ^*} (resp. R). Then Φ^σ is a G -module isomorphism of $W \otimes W^* \otimes U$ onto $\mathfrak{o}^R_{[\sigma^*]}(G) \otimes U = \mathfrak{o}^L_{[\sigma]}(G) \otimes U$.*

Let $\phi: K \rightarrow GL(U)$ be a unitary representation and \langle , \rangle the Hermitian inner product on U . Put $\xi = G \times_K U$. Then ξ has a natural Hermitian fibre metric, which will be also denoted by \langle , \rangle . We define a subspace $C^\infty(G; U)_K$ of $C^\infty(G; U)$ by

$$C^\infty(G; U)_K = \left\{ f \in C^\infty(G; U); f(xk) = \phi(k^{-1})f(x) \right. \\ \left. \text{for } x \in G \text{ and } k \in K \right\}.$$

We identify the space $\Gamma(\xi)$ of C^∞ cross-sections of ξ with $C^\infty(G; U)_K$. Then $C^\infty(G; U)_K$ is a G -module with the G -action L . We define a Hermitian inner product \langle , \rangle on $C^\infty(G; U)_K$ as follows:

$$\langle f, g \rangle = \int_G \langle f(x), g(x) \rangle dx,$$

where dx is the normalized Haar measure of G . Then we have

$$\langle L_x f, L_x g \rangle = \langle f, g \rangle \quad \text{for every } x \in G.$$

The space $C^\infty(G; U)_K$ is a pre-Hilbert space. We denote by $L^2(\xi)$ the completion of $C^\infty(G; U)_K$. Identifying as $C^\infty(G; U) = C^\infty(G)^c \otimes U$, we define an action J of K on $C^\infty(G; U)$ by $J(k) = R_k \otimes \phi(k)$ for $k \in K$. Then we have

$$(5.1.1) \quad C^\infty(G; U)_K = \{f \in C^\infty(G; U); J(k)f = f \quad \text{for } k \in K\}.$$

For a complex irreducible representation $\sigma: G \rightarrow GL(W)$, we define an action J_σ of K on $W \otimes W^* \otimes U$ by $J_\sigma(k) = 1_W \otimes \sigma^*(k) \otimes \phi(k)$. Then we have

$$(5.1.2) \quad \Phi^\sigma \circ J_\sigma(k) = J(k) \circ \Phi^\sigma \quad \text{for every } k \in K.$$

Let $\mathfrak{o}_{[\sigma]}(\xi)$ be the subspace of $C^\infty(G; U)_K$ generated by all G -submodules of $C^\infty(G; U)_K$ which are isomorphic to W . Then $\mathfrak{o}_{[\sigma]}(\xi)$ is a G -submodule of $\mathfrak{o}^L_{[\sigma]}(G) \otimes U$. Put

$$\begin{aligned} \mathfrak{o}(\xi) &= \{f \in C^\infty(G; U)_K; \dim \{L_x f; x \in G\}_c < \infty\}, \\ D(G; K, \phi) &= \left\{ [\sigma] \in D(G); \sigma^*|_K \otimes \phi \text{ contains a trivial} \right. \\ &\quad \left. \text{representation} \right\}, \end{aligned}$$

and

$$(W^* \otimes U)_0 = \{\alpha \in W^* \otimes U; (\sigma^*(k) \otimes \phi(k))(\alpha) = \alpha \quad \text{for } k \in K\}.$$

Then $W \otimes (W^* \otimes U)_0$ is a G -module with the G -action L_σ . We have the following Peter-Weyl theorem for vector bundles.

Theorem 5.1.2. (Bott [1] p. 173). (1) *The G -module isomorphism $\Phi^\sigma: W \otimes W^* \otimes U \rightarrow \mathfrak{o}^L_{[\sigma]}(G) \otimes U$ in (1) of Theorem 5.1.1 induces a G -module isomorphism of $W \otimes (W^* \otimes U)_0$ onto $\mathfrak{o}_{[\sigma]}(\xi)$.*

(2) *We have the following orthogonal decompositions:*

$$\begin{aligned} \mathfrak{o}(\xi) &= \sum_{[\sigma] \in D(G; K, \phi)} \mathfrak{o}_{[\sigma]}(\xi) \quad (\text{algebraic direct sum}), \\ L^2(\xi) &= \sum_{[\sigma] \in D(G; K, \phi)} \mathfrak{o}_{[\sigma]}(\xi) \quad (\text{direct sum as Hilbert space}). \end{aligned}$$

We have the following theorem for an invariant differential operator.

Theorem 2. *Let D be an invariant differential operator on ξ and consider it as an operator on $C^\infty(G; U)_K$ (see the commutative diagram in subsection 4.1). Let $\sigma: G \rightarrow GL(W)$ be an irreducible representation with $[\sigma] \in D(G; K, \phi)$. Then D leaves $\mathfrak{o}_{[\sigma]}(\xi)$ invariant and there exists a unique linear mapping D_σ of $(W^* \otimes U)_0$ such that*

$$D \circ \Phi^\sigma = \Phi^\sigma \circ (1_W \otimes D_\sigma).$$

Proof. For $f \in \mathfrak{o}(\xi)$ the subspace $\{L_x Df: x \in G\}_C = \{DL_x f: x \in G\}_C$ of $C^\infty(G, U)$ is finite dimensional, and hence D leaves $\mathfrak{o}(\xi)$ invariant. It follows from Schur's lemma that every $\mathfrak{o}_{[\sigma]}(\xi)$ is invariant under D . Let D' be the linear mapping of $W \otimes (W^* \otimes U)_0$ corresponding to $D|_{\mathfrak{o}_{[\sigma]}(\xi)}$ by the G -module isomorphism $\Phi^\sigma: W \otimes (W^* \otimes U)_0 \rightarrow \mathfrak{o}_{[\sigma]}(\xi)$. Let $\{\alpha_1, \dots, \alpha_{m_\sigma}\}$ be a basis of $(W^* \otimes U)_0$. We define linear mappings $f^i_j, i, j=1, 2, \dots, m_\sigma$, of W as follows:

$$D'(w \otimes \alpha_j) = \sum_{i=1}^{m_\sigma} f^i_j(w) \otimes \alpha_i \quad \text{for } w \in W.$$

Then we have for $x \in G$

$$\begin{aligned} D'(L_\sigma(x)(w \otimes \alpha_j)) &= D'(\sigma(x)w \otimes \alpha_j) \\ &= \sum_{i=1}^{m_\sigma} f^i_j(\sigma(x)w) \otimes \alpha_i. \end{aligned}$$

On the other hand we have

$$\begin{aligned} D'(L_\sigma(x)(w \otimes \alpha_j)) &= L_\sigma(x)(D'(w \otimes \alpha_j)) \\ &= \sum_{i=1}^{m_\sigma} \sigma(x) f^i_j(w) \otimes \alpha_i. \end{aligned}$$

Hence

$$f^i_j(\sigma(x)w) = \sigma(x) f^i_j(w), \quad i, j = 1, \dots, m_\sigma.$$

It follows from Schur's lemma that there exist complex numbers $c^i_j, i, j=1, \dots, m_\sigma$, such that $f^i_j = c^i_j 1_W$. Hence we have

$$D'(w \otimes \alpha_j) = w \otimes \left(\sum_{i=1}^{m_\sigma} c^i_j \alpha_i \right).$$

A linear mapping D_σ of $(W^* \otimes U)_0$ defined by

$$D_\sigma \alpha_j = \sum_{i=1}^{m_\sigma} c^i_j \alpha_i, \quad j = 1, \dots, m_\sigma,$$

is the required one.

Q.E.D.

REMARK 5.1.1. If an invariant differential operator D on ξ is self-adjoint with respect to the inner product \langle , \rangle , each $D|_{\mathfrak{o}_{[\sigma]}(\xi)}$ is diagonalizable. If furthermore D is elliptic, every eigensection of D belongs to $\mathfrak{o}(\xi)$. Thus the problem of computing the spectra of D is reduced to the study of the eigenvalues of D_σ for each $[\sigma] \in D(G; K, \phi)$.

5.2. In this subsection the assumptions and the notation are the same as in subsection 3.3. Moreover we assume that the minimal isometric immersion $F: (M, c\langle , \rangle) \rightarrow S$ is full. We also denote by \langle , \rangle the Hermitian inner pro-

duct on V^c , the complexification of V , which is the extension of the inner product \langle , \rangle on V . Then the orthogonal representation $\rho: G \rightarrow GL(V)$ extends to the unitary representation $\rho: G \rightarrow GL(V^c)$. Let $(V^N)^c$ be the subspace of V^c generated by V^N and $\rho^N: K \rightarrow GL((V^N)^c)$ the unitary representation induced from $\rho: G \rightarrow GL(V^c)$. We may identify the complexification $\Gamma(N(M))^c$ of $\Gamma(N(M))$ with $C^\infty(G; (V^N)^c)_K$. Let $(V^T)^c$ (resp. $(V^0)^c$) be the complex linear subspace of V^c generated by V^T (resp. V^0). We have the direct sum decomposition $V^c = (V^0)^c + (V^T)^c + (V^N)^c$. For $v \in V^c$ we denote by v^N the $(V^N)^c$ -component of v with respect to this decomposition of V^c .

Let $\sigma: G \rightarrow GL(W)$ be a complex irreducible representation with $[\sigma] \in D(G; K, \rho^N)$. Put

$$(W^* \otimes (V^N)^c)_0 = \left\{ \omega \in W^* \otimes (V^N)^c; (\sigma^*(k) \otimes \rho^N(k))(\omega) = \omega \right\} \\ \text{for } k \in K$$

Let S' be the linear mapping of $W \otimes (W^* \otimes (V^N)^c)_0$ corresponding to $S|_{\mathfrak{v}_{[\sigma]}(N(M))^c}$ by the G -isomorphism $\Phi^\sigma: W \otimes (W^* \otimes (V^N)^c)_0 \rightarrow \mathfrak{v}_{[\sigma]}(N(M)^c)$, where $N(M)^c$ denotes the complexification of the normal bundle $N(M)$. Then we have by Theorem 1 and (2) of Theorem 5.1.1

$$S' = -\frac{1}{c} (1_W \otimes \{ (c_{\sigma^*} - 2c_\rho) 1_{W^* \otimes (V^N)^c} + 2 \sum_{i=1}^{n+\beta} d\sigma^*(E_i) \otimes (d\rho(E_i)^*)^N \\ + 2 \sum_{i=1}^{n+\beta} 1_{W^*} \otimes \{ d\rho(E_i) (d\rho(E_i)^*)^N \}^N \}),$$

where c_{σ^*} is the scalar determined by the Casimir operator $\sum_{i=1}^{n+\beta} d\sigma^*(E_i) d\sigma^*(E_i)$ of σ^* . Let c_σ be the scalar determined by the Casimir operator $\sum_{i=1}^{n+\beta} d\sigma(E_i) d\sigma(E_i)$ of σ . Then $c_{\sigma^*} = c_\sigma$. Put

$$S_\sigma = -\frac{1}{c} \{ (c_\sigma - 2c_\rho) 1_{W^* \otimes (V^N)^c} + 2 \sum_{i=1}^{n+\beta} d\sigma^*(E_i) \otimes (d\rho(E_i)^*)^N \\ + 2 \sum_{i=1}^{n+\beta} 1_{W^*} \otimes \{ d\rho(E_i) (d\rho(E_i)^*)^N \}^N \}.$$

Then it follows from Remark 5.1.1, Theorem 2 and (2) of Theorem 5.1.2 that the problem of computing the spectra of \tilde{S} is reduced to the eigenvalue problems of the linear mappings S_σ of $(W^* \otimes (V^N)^c)_0$ with $[\sigma] \in D(G; K, \rho^N)$.

Summarizing, we get the following theorem.

Theorem 3. *Let $F: (M, c\langle , \rangle) \rightarrow S$, $F(xK) = \rho(x)F(o)$, be a full equivariant minimal isometric immersion of a compact symmetric space $M = G/K$ into a unit sphere S . For a complex irreducible representation $\sigma: G \rightarrow GL(W)$ with $[\sigma] \in D(G; K, \rho^N)$, let $\{\lambda_{\sigma; 1}, \dots, \lambda_{\sigma; m_\sigma}\}$ be the eigenvalues of S_σ on $(W^* \otimes (V^N)^c)_0$. Then the spectra of the Jacobi differential operator \tilde{S} are given by*

$$[\sigma] \in D(G; K, \rho^N) \cup \underbrace{\{\lambda_{\sigma; 1}, \dots, \lambda_{\sigma; 1}, \dots, \lambda_{\sigma; m_\sigma}, \dots, \lambda_{\sigma; m_\sigma}\}}_{d_\sigma},$$

where $d_\sigma = \dim W$.

For a complex irreducible representation $\sigma: G \rightarrow GL(W)$ with $[\sigma] \in D(G; K, \rho^N)$, it follows from Remark 3.3.1 and Theorem 2 that each of the linear mappings $\sum_{i=1}^{n+p} d\sigma^*(E_i) \otimes (d\rho(E_i))^N$ and $\sum_{i=1}^{n+p} 1_{W^*} \otimes \{d\rho(E_i)(d\rho(E_i))^N\}^N$ leaves $(W^* \otimes (V^N)^c)_0$ invariant. For the study of the linear mapping S_σ it is important to study these linear mappings. We shall study these linear mappings.

Let \mathfrak{g}^c be the complexification of \mathfrak{g} and $(,)$ the symmetric bilinear form on \mathfrak{g}^c which is the \mathbf{C} -bilinear extension of the inner product \langle , \rangle on \mathfrak{g} . Choose bases $\{F_1, \dots, F_{n+p}\}$ and $\{F'_1, \dots, F'_{n+p}\}$ of \mathfrak{g}^c with the property $(F_i, F'_j) = \delta_{ij}$. Let $\chi: G \rightarrow GL(U)$ be an arbitrary unitary representation (not necessarily irreducible). We define a linear mapping $L(\chi, \rho)$ of $U \otimes V^c$ by

$$L(\chi, \rho) = \sum_{i=1}^{n+p} d\chi(F_i) \otimes d\rho(F'_i).$$

The linear mapping $L(\chi, \rho)$ is independent of the choice of bases. In fact let $\{H_1, \dots, H_{n+p}\}$ and $\{H'_1, \dots, H'_{n+p}\}$ be bases of \mathfrak{g}^c with $(H_i, H'_j) = \delta_{ij}$. Let $H_i = \sum_{k=1}^{n+p} a^k_i F_k$ and $H'_i = \sum_{h=1}^{n+p} b^h_i F'_h$, $i=1, \dots, n+p$. Then we have

$$\delta_{ij} = (H_i, H'_j) = \sum_{k=1}^{n+p} a^k_i b^j_k.$$

Hence if we put $A = (a^i_j)_{i,j=1, \dots, n+p}$ and $B = (b^i_j)_{i,j=1, \dots, n+p}$, we have $B = A^{-1}$. Therefore we have

$$\begin{aligned} \sum_{i=1}^{n+p} d\chi(H_i) \otimes d\rho(H'_i) &= \sum_{k,h=1}^{n+p} \sum_{i=1}^{n+p} a^k_i b^h_i d\chi(F_k) \otimes d\rho(F'_h) \\ &= \sum_{k=1}^{n+p} d\chi(F_k) \otimes d\rho(F'_k). \end{aligned}$$

We denote by $C_{\chi \otimes \rho}$ (resp. C_χ and C_ρ) the Casimir operator of the representation $\chi \otimes \rho$ (resp. χ and ρ). Since $\sum_{i=1}^{n+p} d\chi(F_i) \otimes d\rho(F'_i) = \sum_{i=1}^{n+p} d\chi(F'_i) \otimes d\rho(F_i)$, we have

$$(5.2.1) \quad 2L(\chi, \rho) = C_{\chi \otimes \rho} - C_\chi \otimes 1_{V^c} - 1_U \otimes C_\rho.$$

We obtain the following lemma by (5.2.1) and the fact that the Casimir operator commutes with the action of G .

Lemma 5.2.1. *We have*

$$(\chi \otimes \rho)(x) \circ L(\chi, \rho) = L(\chi, \rho) \circ (\chi \otimes \rho)(x) \quad \text{for } x \in G.$$

Put

$$(U \otimes V^c)_0 = \{ \omega \in U \otimes V^c; (\chi \otimes \rho)(k)\omega = \omega \quad \text{for } k \in K \}.$$

Then we have by the above lemma

$$(5.2.2) \quad L(\chi, \rho)((U \otimes V^c)_0) \subset (U \otimes V^c)_0.$$

Now we come back to our complex irreducible representation $\sigma: G \rightarrow GL(W)$. We denote by p_1 the projection to the first component of the following direct sum decomposition:

$$W^* \otimes V^c = (W^* \otimes (V^N)^c) + (W^* \otimes \{(V^T)^c + (V^0)^c\}).$$

Then we have

Lemma 5.2.2.

$$(5.2.3) \quad \sum_{i=1}^{n+p} d\sigma^*(E_i) \otimes (d\rho(E_i))^* = p_1 \sum_{i=1}^{n+p} d\sigma^*(E_i) \otimes d\rho(E_i) \quad \text{on } W^* \otimes V^c,$$

$$(5.2.4) \quad \sum_{i=1}^{n+p} d\sigma^*(E_i) \otimes d\rho(E_i)((W^* \otimes V^c)_0) \subset (W^* \otimes V^c)_0,$$

where $(W^* \otimes V^c)_0 = \{ \omega \in W^* \otimes V^c, (\sigma^*(k) \otimes \rho(k))\omega = \omega \quad \text{for } k \in K \}.$

Proof. The first equality is trivial. Since $\sum_{i=1}^{n+p} d\sigma^*(E_i) \otimes d\rho(E_i) = L(\sigma^*, \rho)$, we have (5.2.4) by (5.2.2). Q.E.D.

Lemma 5.2.3. *We have*

$$(5.2.5) \quad \begin{aligned} \rho(k) \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)v)^N\}^N \\ = \sum_{i=1}^{n+p} (d\rho(E_i) \{d\rho(E_i)\rho(k)v\}^N)^N \quad \text{for } k \in K \text{ and } v \in V^c. \end{aligned}$$

Proof. For $k \in K$ the linear mapping $\rho(k)$ leaves $(V^N)^c$, $(V^T)^c$ and $(V^0)^c$ invariant respectively. Therefore we have

$$\begin{aligned} \rho(k) \sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)v)^N\}^N \\ = \sum_{i=1}^{n+p} (\{\rho(k)d\rho(E_i)\rho(k^{-1})\} [\{\rho(k)d\rho(E_i)\rho(k^{-1})\}(\rho(k)v)]^N)^N \\ = \sum_{i=1}^{n+p} (d\rho(\text{Ad}(k)E_i) \{d\rho(\text{Ad}(k)E_i)(\rho(k)v)\}^N)^N. \end{aligned}$$

Since $\{\text{Ad}(k)E_1, \dots, \text{Ad}(k)E_{n+p}\}$ is an orthonormal basis of \mathfrak{g} , we have

$$\begin{aligned} \sum_{i=1}^{n+p} (d\rho(\text{Ad}(k)E_i) \{d\rho(\text{Ad}(k)E_i)(\rho(k)v)\}^N)^N \\ = \sum_{i=1}^{n+p} (d\rho(E_i) \{d\rho(E_i)(\rho(k)v)\}^N)^N. \end{aligned}$$

Q.E.D.

In the forthcoming papers we shall study the linear mappings

$$\sum_{i=1}^{n+p} d\sigma^*(E_i) \otimes d\rho(E_i): (W^* \otimes V^c)_0 \rightarrow (W^* \otimes V^c)_0$$

and

$$\sum_{i=1}^{n+p} \{d\rho(E_i)(d\rho(E_i)^*)^N\}^N: (V^N)^c \rightarrow (V^N)^c.$$

These studies, together with Lemma 5.2.2 and Lemma 5.2.3, will give us information on the linear mapping S_σ .

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Department of Mathematics
Faculty of Science
Kobe University
Kobe 657, Japan

