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ON THE NONWANDERING SETS OF DIFFEOMORPHISMS OF SURFACES

TOKIHIKO KOIKE

§1. Introduction

Let M be a compact manifold without boundary. Let $f: M \to M$ be a C^1 diffeomorphism. Then the nonwandering set $\Omega(f)$ is defined to be the closed invariant set consisting of $x \in M$ such that for any neighborhood U of x, there exists an integer $n \neq 0$ satisfying $f^n(U) \cap U \neq \phi$. In particular, the set Per(f) of all periodic points is included in $\Omega(f)$.

Generally, in the study of the orbit structure of diffeomorphisms their nonwandering sets play an essential role. Several results relating to the non-wandering sets established in these ten years or so have developed a new aspect of dynamics—the study of the orbit structure of dynamical systems. In his survey [8], Smale set up a concept called Axiom A, i.e. (a) $\Omega(f) = \overline{\operatorname{Per}(f)}$, (b) Tf has a hyperbolic structure over $\Omega(f)$, i.e. there exists a Tfinvariant continuous splitting $E^s \oplus E^u$ of $TM | \Omega(f)$ —the restriction of the tangent bundle TM to $\Omega(f)$ —such that for some constants $C > 0, 0 < \lambda < 1$,

$$egin{array}{ll} \|Tf^n(v)\|\leq C\lambda^n\,\|v\|\,, & orall\,v\in E^s,\ orall\,n>0\,, \ \|Tf^{-n}(v)\|\leq C\lambda^n\,\|v\|\,, & orall\,v\in E^u,\ orall\,n>0\,. \end{array}$$

After that, many important results were obtained in this direction.

On the other hand, Pugh [7] proved a very important theorem about the nonwandering sets. To state it, we shall explain the concept of genericity. Let $\text{Diff}^1(M)$ be the set of all C^1 diffeomorphisms endowed with the C^1 topology. Then a property of diffeomorphisms is called *generic* if the diffeomorphisms having it form a residual subset of $\text{Diff}^1(M)$.

PUGH'S DENSITY THEOREM. The property $\Omega(f) = \overline{\operatorname{Per}(f)}$ is generic in $\operatorname{Diff}^{1}(M)$.

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TOKIHIKO KOIKE

In this paper we shall study the nonwandering sets of diffeomorphisms of surfaces from the viewpoint of genericity. Our results are as follows: Let M^2 be a compact connected surface without boundary.

THEOREM 1. The property that int $\Omega(f)$, = ϕ , or f is an Anosov diffeomorphism is generic in Diff¹ (M^2).

Remark. For a topological space X, the closure and the interior of $A \subset X$ are denoted by \overline{A} and int A respectively.

A diffeomorphism $f: M \to M$ is called Anosov if Tf has a hyperbolic structure over M. For surfaces except a torus, there is no Anosov diffeomorphisms ([9], p. 90). So, in this case Theorem 1 is written as follows:

THEOREM 1'. The property int $\Omega(f) = \phi$ is generic in Diff¹ (M^2) if M^2 is not a torus.

A diffeomorphism f is said to be topologically Ω -stable if $\Omega(f)$ is homeomorphic to $\Omega(g)$ for all $g C^1$ near f. We have the following from Theorem 1.

COROLLARY. If $f \in \text{Diff}^1(M^2)$ is topologically Ω -stable, then int $\Omega(f) = \phi$ or f is an Anosov diffeomorphism.

The main stage in proving Theorem 1 is the following. First we shall fix our notation.

DEFINITION. For an open subset U of M, we denote by $\mathscr{H}(U)$ the set of $f \in \text{Diff}^1(M)$ whose periodic points in U are all hyperbolic, and by $\mathscr{D}(U)$ the set of $f \in \text{Diff}^1(M)$ whose periodic points are dense in U.

THEOREM 2. Let M^2 be a compact connected surface. Then for any open subset U of M^2 ,

$$\mathscr{D}(U)\,\cap\,\operatorname{int}\mathscr{H}(U)\subset\mathscr{D}(M^{\scriptscriptstyle 2})$$
 .

Theorem 1 is proved in Section 2 and Theorem 2 in Section 4. Sections 3 and 5 are devoted to two propositions necessary for the proof of Theorem 2. In Appendix we shall prove a lemma about a non-transversal homoclinic point, which is necessary in Section 5.

Throughout this paper except Appendix, 'M' will denote a compact connected surface without boundary.

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§2. Proofs of Theorem 1 and Corollary

In this section we prove Theorem 1, assuming Theorem 2. We denote by \mathscr{A} the set of all Anosov diffeomorphisms of M.

LEMMA 1. If $f \in \operatorname{int} \overline{\mathscr{D}(M)}$, then $f \in \overline{\mathscr{A}}$. Hence \mathscr{A} is open and dense in $\operatorname{int} \overline{\mathscr{D}(M)}$.

Proof. Let $f \in \operatorname{int} \overline{\mathscr{D}(M)}$. First, we suppose $f \notin \operatorname{int} \mathscr{H}(M)$. Some diffeomorphism g near f has a non-hyperbolic periodic point p. Since the dimension of M is 2, it is possible to make p a sink or a source of a small C^1 perturbation g_1 of g, i.e., if n is the period of p, then the eigenvalues of $T_p g_1^n$ have absolute values <1 (or >1). Obviously, $g_1 \notin \overline{\mathscr{D}(M)}$. This contradicts the hypothesis, because g_1 can be chosen sufficiently near f. Thus $f \in \operatorname{int} \mathscr{H}(M)$. We can choose $f_1 \in \operatorname{int} \mathscr{H}(M) \cap \mathscr{D}(M)$ near f. We here apply a theorem of Mañé [3], i.e. $\operatorname{int} \mathscr{H}(M) \cap \mathscr{D}(M) = \mathscr{A}$ if the dimension of M is 2. Hence we have $f_1 \in \mathscr{A}$. Therefore, $f \in \overline{\mathscr{A}}$.

For each point $x \in M$, we define

$$\mathscr{U}_x = \{f \in \operatorname{Diff}^1(M); x \notin \operatorname{int} \operatorname{Per}(f)\}$$
.

Then we have

LEMMA 2. If $f \notin \mathscr{U}_x$, then $f \in \mathscr{D}(M)$ or $f \in int \mathscr{U}_x$.

Proof. Let $f \notin \mathscr{U}_x$. By definition, $x \in \operatorname{int} \operatorname{Per}(f)$. Let U be a small neighborhood of x in $\operatorname{Per}(f)$. When $f \in \operatorname{int} \mathscr{H}(U)$, by Theorem 2, we have $f \in \mathscr{D}(M)$. So it is sufficient to show that $f \in \operatorname{int} \mathscr{U}_x$, when $f \notin \operatorname{int} \mathscr{H}(U)$. Then some f_1 near f has a non-hyperbolic periodic point p in U. Similarly, it is possible to make p a sink or a source of some C^1 perturbation f_2 of f_1 . Since U is a small neighborhood of x, we can choose $h \in \operatorname{Diff}^1(M)$ with h(x) = p in a small C^1 neighborhood of the identity of M. Put g = $h^{-1} \cdot f_2 \cdot h$. Clearly g is C^1 near f. Naturally $x = h^{-1}(p)$ is a sink or source of g. Hence, for any $g_1 \in \operatorname{Diff}^1(M)$ near g we have $x \notin \operatorname{int} \operatorname{Per}(g_1)$, or $g_1 \in$ \mathscr{U}_x . This implies $g \in \operatorname{int} \mathscr{U}_x$. Since g is near f, it follows that $f \in \operatorname{int} \mathscr{U}_x$. q.e.d.

LEMMA 3. int $\mathscr{U}_x \cup \operatorname{int} \overline{\mathscr{D}(M)}$ is dense in $\operatorname{Diff}^1(M)$.

Proof. Suppose $f \in \overline{\operatorname{int} \mathscr{U}_x}$. It suffices to show $f \in \overline{\mathscr{D}(M)}$. When $f \notin \mathscr{U}_x$,

by Lemma 2, we have $f \in \mathscr{D}(M)$. When $f \in \mathscr{U}_x$ hence $f \in \mathscr{U}_x - \operatorname{int} \mathscr{U}_x$, there is a sequence $f_n \notin \mathscr{U}_x \cup \operatorname{int} \mathscr{U}_x$ converging to f. By Lemma 2, $f_n \in \mathscr{D}(M)$. Hence $f \in \overline{\mathscr{D}(M)}$ follows. q.e.d.

Now Theorem 1 is proved as follows: By Lemmas 1 and 3, $\mathscr{U}_x \cup \mathscr{A}$ is generic in Diff¹(*M*). Really it contains an open dense subset of Diff¹(*M*). By the Pugh's density theorem, the set

$$\mathscr{C} = \{f \in \operatorname{Diff}^{1}(M); \Omega(f) = \overline{\operatorname{Per}(f)}\}$$

is generic. Let K be a dense countable subset of M. Then

$$egin{aligned} \mathscr{B} &= igcap_{x \in K} (\mathscr{U}_x \, \cup \, \mathscr{A}) \, \cap \, \mathscr{C} \ &= \left(\left(igcap_{x \in K} \, \mathscr{U}_x
ight) \, \cap \, \mathscr{C}
ight) \, \cup \, \mathscr{A} \end{aligned}$$

is generic in Diff¹(*M*). Now we need only check that if $f \in (\bigcap_{x \in K} \mathscr{U}_x) \cap \mathscr{C}$ then int $\Omega(f) = \phi$. From $f \in \bigcap_{x \in K} \mathscr{U}_x$, we have int $\overline{\operatorname{Per}(f)} \cap K = \phi$. But, since *K* is dense in *M*, int $\overline{\operatorname{Per}(f)} = \phi$. On the other hand, $f \in \mathscr{C}$ means $\overline{\operatorname{Per}(f)} = \Omega(f)$. Hence int $\Omega(f) = \phi$ follows. q.e.d.

Proof of Corollary. Let $f \in \text{Diff}^1(M)$ be topologically Ω -stable. First suppose $f \notin \overline{\mathscr{A}}$. By Theorem 1, there is $g \in \text{Diff}^1(M)$ near f such that int $\Omega(g) = \phi$. By stability, it follows from the theorem of domain invariance that int $\Omega(f) = \phi$.

Next suppose $f \in \overline{\mathscr{A}}$. There is $f_1 \in \mathscr{A}$ near f. Since $\Omega(f_1) = M$ ([9], p. 89), by stability, we have $\Omega(f) = M$. Hence by stability, $\Omega(g) = M$ for all g near f. By Mañé [3], it follows that f is Anosov. q.e.d.

§3. Laminations

In this section we prepare a proposition for the proof of Theorem 2. Let us begin with definitions.

DEFINITION. Let $f \in \text{Diff}^1(M)$. For a hyperbolic periodic point p of f, we denote by $W^s(p; f)$ (resp. $W^u(p; f)$) the stable (resp. unstable) manifold of f at p. We define $E^s(p; f)$ to be the tangent space of $W^s(p; f)$ at p. Likewise $E^u(p; f)$ is defined.

In what follows, we shall drop 'f' in these symbols when it does not give rise to confusion.

DEFINITION. A hyperbolic periodic point is called a *saddle* if it is not a sink nor source. We denote by Sd(f) the set of all saddles of f.

DEFINITION. A C^1 lamination of M is a continuous foliation whose leaves are C^1 immersed submanifolds such that their tangent spaces, as a whole, form a continuous subbundle of TM.

Refer to [1, § 7] for general definitions. We shall prove the following.

PROPOSITION 1. Let $f \in \text{Diff}^1(M)$. Let U be an open subset of M such that:

(1) U is invariant under f.

(2) The periodic points in U are all saddles and are dense in U.

(3) There is a continuous splitting $E^s \oplus E^u$ of TM | U whose splitting at $\forall p \in Sd(f) \cap U$ is $E^s(p; f) \oplus E^u(p; f)$.

Then there is an f-invariant C^1 lamination W^s on U such that (a) all laminae are tangent to E^s , (b) stable manifolds $W^s(p; f)$, $\forall p \in Sd(f) \cap U$, are its laminae. Likewise there is an f-invariant lamination W^u on U with the corresponding properties.

Proof. We want to construct a lamination on a neighborhood of $\forall x_0 \in U$. First, we take a coordinate neighborhood (Q, φ) of x_0 with the following properties.

$$(4) \quad Q \subset U.$$

(5)
$$\varphi(Q) = [-1, 1] \times [-1, 1].$$

 $(6) \quad \varphi(x_0) = (0, 0).$

(7) Identify Q with $[-1, 1] \times [-1, 1]$ and E^s with $T\varphi(E^s)$. There is a C^0 map $w: Q \to \mathbf{R}$ such that |w(x)| < 1/4, and the vector (1, w(x)) spans $E^s(x), \forall x \in Q$. $E^s(x)$ is the fiber of E^s at x.

We, first of all, notice that stable manifolds $W^{s}(p)$, $\forall p \in \mathrm{Sd}(f) \cap U$ are tangent to E^{s} . Because, if at a point $x \in W^{s}(p)$, $E^{s}(x)$ is not tangent to $W^{s}(p)$, then $E^{s}(f^{\alpha n}(x)) = Tf^{\alpha n}(E^{s}(x))$ (α is the period of p) tends to $E^{u}(p)$ as $n \to \infty$ by hyperbolicity of $T_{p}f^{\alpha}$, contradicting continuity of E^{s} . Likewise unstable manifolds $W^{u}(p)$, $\forall p \in \mathrm{Sd}(f) \cap U$, are tangent to E^{u} .

Let $\pi_1: Q \to [-1, 1]$ be the projection on the first factor. Write $Q_1 = [-1, 1] \times [-1/2, 1/2] \subset Q$. For $\forall p \in \text{Sd}(f) \cap Q$, let K_p be the connected component of $W^s(p) \cap Q$ containing p. Let $h_p: K_p \to [-1, 1]$ be the mapping defined by

$$h_p(x) = \pi_1(x) , \quad \forall x \in K_p .$$

We want to show that h_p is a homeomorphism if $p \in \mathrm{Sd}\,(f) \cap Q_1$.

First, h_p is one to one, because K_p is an integral curve of the vector field $x \mapsto (1, w(x))$, $\forall x \in Q$, which spans E^s over Q. So we show h_p is onto. We notice that K_p cannot meet the top nor the bottom of Q, because the slope of K_p is less than 1/4. So h_p not being onto implies $\overline{K}_p - K_p \neq \phi$. Let $q \in \overline{K}_p - K_p$. See the figure.



Thus K_p includes one of the components of $W^s(p) - \{p\}$, say C. Since $f^{2\alpha}(C) = C$, clearly we have $f^{2\alpha}(q) = q$, namely $q \in \text{Per}(f)$. Hence, by (2), $q \in \text{Sd}(f)$. For $\forall x \in C$, $f^{-2\alpha n}(x)$ tends to q as $n \to \infty$. This implies $C \subset W^u(q)$. Thus C is tangent to E^s and E^u at once, which contradicts (3). Hence h_p must be onto.

We denote by Π the set of all $p \in \mathrm{Sd}(f) \cap Q$ such that h_p is onto. By the above $\mathrm{Sd}(f) \cap Q_1 \subset \Pi$. Let $\pi_2 : Q \to [-1, 1]$ be the projection on the second factor. When we put $V_0 = \{\pi_2 h_p^{-1}(0); p \in \Pi\} \subset [-1, 1]$, it is easy to see that V_0 is dense in [-1/2, 1/2]. For $\forall p \in \Pi$, we write $k_u = \pi_2 \cdot h_p^{-1}$, where $u = \pi_2 \cdot h_p^{-1}(0)$. Hence graph $(k_u) = K_p$. We define a function $v = k(t, u), t \in [-1, 1], u \in [-1/2, 1/2]$ by the following:

$$k(t, u) = \lim_{u' \in U_0} k_{u'}(t) , \qquad u' \in V_0 .$$

The aim of the following is to prove that curves $t \mapsto (t, k(t, u)), u \in [-1/2, 1/2]$, are C^1 differentiable and tangent to E^s , and they form, as a whole, a C^1 lamination on a neighborhood of x_0 .

1. k(t, u) is well-defined: Let (t, u) be fixed. Take $u_1, u_2 \in V_0$ with $u_1 < u < u_2$. If $p \in \text{Sd}(f) \cap Q$ is in the domain between graph (k_{u_1}) and graph (k_{u_2}) , then p belongs to Π . This is proved by the method proving in the above that h_p is onto, and by the fact that subarcs K_p, K_q of different two stable manifolds never meet each other. Remark that this fact also plays an important role in the following.

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So it is obvious that $\{K_p; p \in \Pi\}$ meet the vertical segment $\{t\} \times [k_{u_1}(t), k_{u_2}(t)] \subset Q$ densely. That is, the set $\{k_{u'}(t); u' \in V_0\}$ is dense in $[k_{u_1}(t), k_{u_2}(t)]$. Therefore, given $\varepsilon > 0$, there is a finite sequence of numbers $u'_1, u'_2, \dots, u'_n \in V_0$ such that

 $(8) \quad u_1 = u'_1 < u'_2 < \cdots < u'_n = u_2,$

(9) $k'_{u_{i+1}}(t) - k'_{u_i}(t) < \varepsilon, \ \forall 1 \le i < n.$

Let j be the suffix with $u'_j < u < u'_{j+1}$. By (9), for $\forall u', u'' \in V_0 \cap [u'_j, u'_{j+1}]$,

$$|k_{u'}(t) - k_{u''}(t)| < k_{u'_{j+1}}(t) - k_{u'_{j}}(t) < \varepsilon$$
.

Hence $\{k_{u'}(t); u' \rightarrow u, u' \in V_0\}$ is a Cauchy sequence.

2. The convergence $k_u(t) \to k(t, u)$ is C° uniform: Given $\varepsilon > 0$, choose a finite sequence of numbers $t_1, t_2, \dots, t_n \in [-1, 1]$ such that

- (10) $-1 = t_1 < t_2 < \cdots < t_n = 1,$
- (11) $t_{i+1} t_i < \varepsilon/2, \ \forall 1 \le i < n.$

We can take $u_1, u_2 \in V_0$ such that

(12) $u_1 < u < u_2$

(13) $k_{u_2}(t_i) - k_{u_1}(t_i) < \varepsilon, \forall 1 \le i \le n.$

By the way, if $|t - t_i| < \varepsilon$, by (7) we have

$$egin{aligned} |k_{u_1}(t)-k_{u_1}(t_i)|&=\left|\int_{t_i}^trac{d}{dt}k_{u_1}(t)\,dt
ight|\ &=\left|\int_{t_i}^tw(t,\,k_{u_1}(t))dt
ight|\ &\leq |t-t_i|/4$$

Likewise $|k_{u_2}(t) - k_{u_2}(t_i)| < \varepsilon/4$. Let $u' \in V_0$, $u_1 < u' < u_2$. For $\forall t \in [-1, 1]$, choose t_i with $|t_i - t| < \varepsilon$. Then

$$egin{aligned} |k(t,\,u)-k_{u'}(t)| &\leq k_{u_2}(t)-k_{u_1}(t) \ &\leq |k_{u_2}(t)-k_{u_2}(t_i)|+|k_{u_2}(t_i)-k_{u_1}(t_i)| \ &+|k_{u_1}(t)-k_{u_1}(t_i)| < arepsilon/4+arepsilon/2+arepsilon/4=arepsilon \end{aligned}$$

3. $\{(d/dt)k_{u'}; u' \rightarrow u, u' \in V_0\}$ is uniformly convergent: Because

$$\frac{d}{dt}k_{u'}(t) = w(t, k_{u'}(t)),$$

q.e.d.

and $k_u(t)$ is uniformly convergent.

q.e.d.

Therefore, v = k(t, u), $(t, u) \in [-1, 1] \times [-1/2, 1/2]$, is C^1 differentiable in t and satisfies the differential equation dv/dt = w(t, v).

It is easy to see that the mapping $H: [-1, 1] \times [-1/2, 1/2] \to Q$ defined by H(t, u) = (t, k(t, u)) is a homeomorphism (into). So we can define a C^1 lamination on a neighborhood of x_0 by letting its laminae be curves $t \mapsto$ $H(t, u), u \in [-1/2, 1/2]$. To guarantee the existence of a global lamination W^s on U, we need only check that two local laminations thus defined are always consistent with each other. But, otherwise, there must be a pair of stable manifolds having an intersection by the construction of laminae.

Clearly the lamination W^s satisfies the desired conditions. q.e.d.

§4. Theorem 2

For simplicity we denote by U_f the f orbit of $U \subset M$. The following proposition plays a basic role in proving Theorem 2.

PROPOSITION 2. Let U be an open subset of M. If $f \in \operatorname{int} \mathscr{H}(U)$, then there is a continuous splitting $E^* \oplus E^u$ of $TM | \overline{\operatorname{Sd}(f) \cap U_f}$ whose splitting at $\forall p \in \operatorname{Sd}(f) \cap U_f$ is $E^s(p; f) \oplus E^u(p; f)$.

The proof will be given in the next section. Now we prove Theorem 2.

THEOREM 2. For any open subset U of M, we have

$$\mathscr{D}(U)\,\cap\,\mathrm{int}\,\mathscr{H}(U)\subset\mathscr{D}(M)$$
 .

Proof. Let $f \in \mathcal{D}(U) \cap \operatorname{int} \mathscr{H}(U)$. Clearly $\operatorname{Per}(f) \cap U_f \subset \operatorname{Sd}(f)$. So, Sd (f) is dense in U_f . Applying Proposition 2, we have a splitting $E^s \oplus$ E^u of $TM | \overline{U}_f$ whose splitting at $\forall p \in \operatorname{Sd}(f) \cap U_f$ is $E^s(p; f) \oplus E^u(p; f)$. Hence, by Proposition 1, there are f-invariant laminations W^s and W^u such that $W^s(p; f)$ and $W^u(p; f)$, $\forall p \in \operatorname{Sd}(f) \cap U_f$, are respectively their laminae.

It is sufficient to show $\overline{U}_f = M$, because Per(f) is dense in U_f . For this, we need only prove that for $\forall x_0 \in \overline{U}_f$, there is a neighborhood of x_0 included in \overline{U}_f . Let us write $\Sigma = \mathrm{Sd}(f) \cap U_f$. We claim

(1) Let $p \in \Sigma$. Let $\varphi: \mathbb{R} \to W^s(p)$, $\varphi(0) = p$, be a parametrization of $W^s(p)$. Then $\varphi(\infty) = \lim_{t \to \infty} \varphi(t)$ never exists.

Proof of (1). Suppose there exists $\varphi(\infty)$. Let α be the period of p. First, $\varphi(\infty) \notin U_f$, because by Proposition 1 $W^s(p)$ is a lamina of W^s . It is also clear that $f^{2\alpha}(\varphi(\infty)) = \varphi(\infty)$. Since the laminations W^s , W^u are transversal, we have $q \in \Sigma$ with $\varphi\{(0, \infty)\} \cap W^u(q) \neq \phi$. Let $y \in \varphi\{(0, \infty)\} \cap W^u(q)$. Denote by β the period of q. Since $y \in W^u(q)$, $f^{-2\alpha\beta n}(y) \to q$ as $n \to \infty$. Since $y \in \varphi\{(0, \infty)\}$, $f^{-2\alpha\beta n}(y) \to \varphi(\infty)$ as $n \to \infty$. Hence $q = \varphi(\infty)$. This is a contradiction, because $\varphi(\infty) \notin U_f$.

By continuity of $E^s \oplus E^u$, we may choose a coordinate neighborhood (Q, ψ) of x_0 satisfying the following (2) ~ (4).

- (2) $\psi(Q) = [-1, 1] \times [-1, 1]$
- $(3) \quad \psi(x_0) = (0, 0)$

(4) Identify Q with its image by ψ and E^s , E^u with $T\psi(E^s)$, $T\psi(E^u)$ respectively. Then we have C^o functions w_s , $w_u: Q \cap \overline{U}_f \to [-1/4, 1/4]$ such that $(1, w_s(x))$, $(w_u(x), 1) \in T_x Q$ span respectively $E^s(x)$, $E^u(x)$ for $\forall x \in Q \cap \overline{U}_f$.

Let $p \in \Sigma \cap Q$. We denote by K_p^s (resp. K_p^w) the connected component of $W^s(p) \cap Q$ (resp. $W^u(p) \cap Q$) containing p. We express the coordinate system in Q as (t, v). Noting that K_p^s is an integral curve of the vector field $x \mapsto (1, w_s(x))$ ($x \in Q \cap U_f$), we have a function $v = k_p(t)$ with graph (k_p) $= K_p^s$. Let Π be the set of all $p \in \Sigma \cap Q$ such that the domain of k_p is [-1, 1]. Put $Q_1 = [-1, 1] \times [-1/2, 1/2] \subset Q$. As in the previous section, we can prove $\Sigma \cap Q_1 \subset \Pi$ by virtue of (1).

Let us fix a point $p_0 \in [-1/4, 1/4] \times [-1/4, 1/4] \cap \Sigma$. Similarly as above, we have a function t = h(v), $v \in [-1, 1]$ with graph $(h) = K_{p_0}^u$. For $\forall p \in \Pi$, $K_p^s \cap K_{p_0}^u$ consists of just a point. Let $\pi_2(t, v) = v$ be the projection. Define $V_0 = \{\pi_2(K_p^s \cap K_{p_0}^u); p \in \Pi\}$. Since $\Sigma \cap Q_1 \subset \Pi$, V_0 is dense in [-1/2, 1/2]. For $\forall u' \in V_0$, we put $k(t, u') = k_p(t)$, where $\pi_2(K_p^s \cap K_{p_0}^u) = u'$. See the figure.



Now we define a function v = k(t, u), $(t, u) \in [-1, 1] \times [-1/2, 1/2]$ by

$$\underline{k}(t, u) = \lim_{u' \uparrow u} k(t, u') , \qquad u' \in V_0 .$$

First, this is well-defined, because k(t, u') is monotonuous in $u' \in V_0$. As in the previous section, we have similarly that this convergence is C^1 uniform in $t \in [-1, 1]$.

Likewise we define another function $v = \overline{k}(t, u)$, $(t, u) \in [-1, 1] \times [-1/2, 1/2]$ by

$$\overline{k}(t, u) = \lim_{u' \downarrow u} k(t, u') , \qquad u' \in V_0 .$$

We want to show $\underline{k} = \overline{k}$. Suppose that for some $t_1, u_1 \underline{k}(t_1, u_1) \neq \overline{k}(t_1, u_1)$. Let D be the region in Q between the graphs of $\underline{k}(\cdot, u_1)$ and $\overline{k}(\cdot, u_1)$. First we have $D \cap U_f = \phi$. If not, we can take two points $p_1, p_2 \in \Sigma \cap D$. By (1), they belong to Π . So the region in Q between $K_{p_1}^s$ and $K_{p_2}^s$ is included in D. But this is impossible, because $\underline{k}(t_2, u_1) = \overline{k}(t_2, u_1)$ where $(t_2, u_1) \in K_{p_0}^u$. Thus $D \cap U_f = \phi$.

We also have $D \cap U_f \neq \phi$. This is shown as follows. Put $x_1 = (t_1, \underline{k}(t_1, u_1))$. We notice that the graphs of $k(\cdot, u')$, $u' \in V_0$, are included in U_f . So, $x_1 = \lim(t_1, k(t_1, u'))$ $(u' \uparrow u_1, u' \in V_0)$ is contained in \overline{U}_f . Hence we can choose a point $p \in \Sigma$ near x_1 . Then K_p^u meets the graph of $\underline{k}(\cdot, u_1)$ at a point near x_1 . So it meets D, too. Since $K_p^u \subset U_f$, we have $D \cap U_f \neq \phi$.

Thus we have a contradiction. Therefore, $\underline{k} = \overline{k}$. Hereafter we write $k = \underline{k} = \overline{k}$.

It is easily shown that the mapping $H: [-1, 1] \times [-1/2, 1/2] \to Q$ defined by H(t, u) = (t, k(t, u)) is a homeomorphism (into). Moreover, its image is in \overline{U}_f . So it is sufficient to show that Im $(H) \supset [-1/2, 1/2] \times [-1/4, 1/4]$.

By (4), $K_{p_0}^u$ meets the segments $[-1/2, 1/2] \times \{1/2\}$, and $[-1/2, 1/2] \times \{-1/2\} \subset Q$. Let these intersections be y_1, y_2 respectively. By definition, graph $(k(\cdot, 1/2))$ goes through y_1 , and graph $(k(\cdot, 1/2))$ through y_2 . Hence it follows from $|(\partial/\partial t)k(t, u)| = |w_s(t, k(t, u)| < 1/4$ that for $\forall t \in [-1/2, 1/2]$, k(t, 1/2) > 1/4 and k(t, -1/2) < -1/4. Hence, as u goes from -1/2 to 1/2 with $t \in [-1/2, 1/2]$ fixed, k(t, u) varies from k(t, -1/2) < -1/4 to k(t, 1/2) > 1/4. By continuity of k, it follows that for $\forall t \in [-1/2, 1/2]$, $\{t\} \times [-1/4, 1/4] \subset \text{Im}(H)$. That is, $[-1/2, 1/2] \times [-1/4, 1/4] \subset \text{Im}(H)$. Hence $x_0 = (0, 0) \in \text{int } \overline{U}_t$.

Thus we have proved Theorem 2.

q.e.d.

§5. Proposition 2

In the proof of Theorem 2, Proposition 2 still remains to be proved.

NONWANDERING SETS

PROPOSITION 2. Let U be an open subset of M. If $f \in \operatorname{int} \mathscr{H}(U)$, then there is a continuous splitting $E^s \oplus E^u$ of $TM|\overline{\operatorname{Sd}(f) \cap U_f}$ whose splitting at $\forall p \in \operatorname{Sd}(f) \cap U_f$ is $E^s(p; f) \oplus E^u(p; f)$.

Proof. We state two assertions, which will be proved later, and using them, we obtain the proof of Proposition 2.

Let GM be the bundle over M whose fiber at x consists of all 1dimensional subspaces of T_xM . Let d be the metric on GM induced from a Riemann metric on M.

Assertion 1. There is a C^1 neighborhood \mathcal{U} of f such that

 $\inf \left\{ d(E^s(p;g),\,E^u(p;g));\ g\in \mathscr{U},\ p\in \mathrm{Sd}\,(g)\,\cap\,\,U_g
ight\} > 0 \;.$

Assertion 2. There is a positive integer ν such that

$$\| \mathit{T} f^{*} | \mathit{E}^{s}(p) \| / \| \mathit{T} f^{*} | \mathit{E}^{u}(p) \| \leq 1/2 \;, \qquad orall p \in \mathrm{Sd}\,(f) \,\cap \, U_{f} \;.$$

Now Proposition 2 is proved as follows: Let $x \in \operatorname{Sd}(f) \cap U_f$. Let $p_n, q_n \in \operatorname{Sd}(f) \cap U_f$, $n = 1, 2, \cdots$ be two sequences converging to x such that $E^s(p_n), E^u(p_n); E^s(q_n), E^u(q_n)$ have a limit. Denote their limits by F^s , F^u ; G^s , G^u respectively. It is sufficient to prove $F^s = G^s$ and $F^u = G^u$. Suppose $F^s \neq G^s$, for example. It follows from Assertion 1 that $F^s \neq F^u$, $G^s \neq G^u$. Our argument is divided into three cases.

1. The case $F^s \neq G^u$. It follows from Assertion 2 that

$$\|T_x f^{k
u} | F^s \| / \|T_x f^{k
u} | F^u \| \leq 1/2^k \;, \qquad orall k > 0 \;.$$

Since $G^s \neq F^s$ and $G^u \neq F^s$, we have by this that given $\varepsilon > 0$, there is k > 0 such that

$$egin{aligned} &d(T_x f^{k
u}(G^s), \, T_x f^{k
u}(F^u)) < arepsilon \ , \ , \ , \ d(T_x f^{k
u}(G^u), \, T_x f^{k
u}(F^u)) < arepsilon \ . \end{aligned}$$

Hence we have

$$d(T_x f^{\scriptscriptstyle k
u}(G^{\scriptscriptstyle s}),\,T_x f^{\scriptscriptstyle k
u}(G^{\scriptscriptstyle u})) < 2arepsilon$$
 .

This clearly contradicts Assertion 1.

2. The case $F^{u} \neq G^{s}$. This is the same with the case 1, if F and G are interchanged.

3. The case $F^s = G^u$ and $F^u = G^s$. By Assertion 2, we have

$$egin{aligned} &\|T_x f^{*} \,|\, F^{s} \| / \|\, T_x f^{*} \,|\, F^{u} \,\| &\leq 1/2 \;, \ &\|T_x f^{*} \,|\, G^{s} \,\| / \|\, T_x f^{*} \,|\, G^{u} \,\| &\leq 1/2 \;. \end{aligned}$$

The above inequalities contradict each other, because $F^* = G^u$ and $F^u = G^s$. Thus we have derived a contradiction from the assumption $F^* \neq G^s$. Hence we have Proposition 2. q.e.d.

To prove Assertions 1, 2 we prepare the following.

ASSERTION 3. For some small C^1 neighborhood \mathscr{U}_1 of f, there is a constant $0 < \lambda < 1$ such that for $\forall g \in \mathscr{U}_1$, $\forall p \in \mathrm{Sd}(g) \cap U_g$

$$egin{array}{ll} \|Tg^{{}^{lpha(p)}}|E^{s}(p;g)\|<\lambda\;,\ \|Tg^{{}^{{}^{-lpha(p)}}}|E^{u}(p;g)\|<\lambda\;, \end{array}$$

where $\alpha(p)$ means the g period of p.

Proof of Assertion 3. Suppose otherwise. We may assume without loss of generality that for any $\varepsilon > 0$, there exists g in the $\varepsilon - C^1$ neighborhood of f with $||Tg^{\alpha(p)}|E^s(p;g)|| > 1 - \varepsilon$ for some $p \in \mathrm{Sd}(g) \cap U$. Let ε_1 $= 1 - ||Tg^{\alpha(p)}|E^s(p;g)||$. Clearly $0 < \varepsilon_1 < \varepsilon$.

By Lemma B₂ in Appendix, we have a $C\varepsilon - C^1$ perturbation h of the identity of M (C is a constant as in that lemma) such that

- (1) h(p) = p.
- (2) $T_p h = (1 \varepsilon_1)^{-1} I_p$ where $I_P: T_p M \longleftarrow$ is the identity.
- (3) h(x) = x for x outside a small neighborhood of p.

We define $g_1 = h \cdot g \in \text{Diff}^1(M)$. By (1), (3), $g_1 = g$ on the orbit of p. Clearly $E^s(p;g)$ is invariant under $T_p g^{\alpha}(p)$. But we have

$$egin{aligned} &\|T_pg_1^{a(p)}\,|\,E^{s}\!(p;g)\| = \|T_ph\!\cdot T_pg^{a(p)}\,|\,E^{s}\!(p;g)\| \ &= (1-arepsilon_{\iota})^{-1}\,\|T_pg^{a(p)}\,|\,E^{s}\!(p;g)\| = 1 \;. \end{aligned}$$

Since the dimension of $E^{s}(p; g)$ is one, it follows that p is not hyperbolic for g_{i} . By construction, g_{i} is near f in Diff¹(M), so $f \notin int \mathscr{H}(U)$. This is a contradiction. q.e.d.

Proof of Assertion 1. Suppose it is not true. Then, for any $\varepsilon > 0$ we have $g \in \mathscr{U}_1$ with

$$\tan d(E^s(p;g), E^u(p;g)) < 2^{-1}\varepsilon(1-\lambda)$$

for some $p \in \text{Sd}(g) \cap U_g$, where \mathscr{U}_1 and λ are the ones given in Assertion 3. Let α be the period of p. Take a small neighborhood Q of p with (1) $Q \not\ni g^n(p), \forall 1 \leq n \leq \alpha - 1.$

We denote by $W_r^s(p;g)(W_r^u(p;g))$ the local stable (unstable) manifold of size r > 0. We choose orthogonal coordinates (t, v) in Q with origin at p such that the *t*-axis is $W_r^s(p;g)$.

The function $v = \psi(t)$ representing $W_r^u(p; g)$ has the form:

- (2) $\psi(t) = c \cdot t + R(t), t \in (-r, r).$
- (3) $|c| < 2^{-1} \varepsilon (1 \lambda).$
- $(4) \quad R(0) = R'(0) = 0.$

By (4), taking r small, we may assume:

$$(5) |R'(t)| < 2^{-1} \varepsilon (1-\lambda), \ \forall t \in (-r, r).$$

So we have

(6) $|R(t)| < 2^{-1} \varepsilon (1-\lambda)r, \forall t \in (-r, r).$

Noting $p = g^{\alpha}(p) = (0, 0)$, we define C^1 mappings $h_1, h_2: (-r, r) \rightarrow (-r, r)$ respectively by

 $(7) \quad h_1(t) = \pi_1 g^{\alpha}(t, 0),$

(8) $h_2(t) = \pi_1 g^{-\alpha}(t, \psi(t))$, where π_1 is the projection on the first factor. Since $|h'_1(0)| < \lambda$, $|h'_2(0)| < \lambda$, by taking r small enough we have

 $(9) |h_1(t)| \le \lambda |t|, |h_2(t)| \le \lambda |t|, \forall t \in (-r, r).$

Put b = r/2 and $\delta = (1 - \lambda)b$. For $\forall t \in (-r, r)$ we have

(10) $|\psi(t)| \leq |c| r + |R(t)| < \varepsilon r(1 - \lambda) = 2\varepsilon \delta$,

(11) $|\psi'(t)| \leq |c| + |R'(t)| < \varepsilon(1-\lambda) < \varepsilon.$

Let $x_1 = (b, 0), x_2 = (b, \psi(b))$. Then

$$egin{aligned} |\pi_1 g^lpha(x_1) - b| &= |h_1(b) - b| > b - \lambda b = \delta \ , \ |\pi_1 g^lpha(x_2) - b| &= |h_2(b) - b| > b - \lambda b = \delta \ . \end{aligned}$$

Hence we have

- (12) $||g^{\alpha}(x_1) x_1|| > \delta$,
- (13) $||g^{-\alpha}(x_2) x_1|| > \delta.$

We define a C^1 mapping $k: Q \to Q$ as follows: Let $\phi: \mathbb{R} \to \mathbb{R}$ be a C^1 function with $\phi(-\infty, 1/2] = 1, \ \phi[1, \infty) = 0.$

(14) $k(t, v) = (t, v - \phi(\{(t - b)^2 + v^2\}/\delta^2) \cdot \psi(t)).$

Then the following holds:

- (15) $k(t, \psi(t)) = (t, 0)$, if |t b| is sufficiently small.
- (16) k(x) = x, if $||x x_1|| > \delta$.
- (17) k is near the identity of Q in the C^1 sense when ε is small.

The last is shown as follows. By (10), (17) is true in the C° sense.

By (10), (11) and the fact that $\phi(\{(t-b)^2 + v^2\}/\delta^2) = 0$ if $|t-b| > \delta$, we have

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$$egin{aligned} &\left\| rac{\partial}{\partial t} \{k(t,\,v)\,-\,(t,\,v)\}
ight\| = |\phi'(\{(t\,-\,b)^2\,+\,v^2\}/\delta^2)\cdot 2\delta^{-2}(t\,-\,b)\cdot\psi(t) \ &+ \phi(\{(t\,-\,b)^2\,+\,v^2\}/\delta^2)\cdot\psi'(t)\} \ &\leq |\phi'|\cdot 2\delta^{-2}\delta\cdot 2arepsilon\delta\,+\,|\phi|\,arepsilon \ &= (4\,|\phi'|\,+\,|\phi|)arepsilon
ightarrow 0 \;. \end{aligned}$$

We also have the same result about $\partial/\partial v$. Thus (17) follows.

We extend k to a mapping of $M \to M$ by letting k(x) = x for x outside Q. By (17) we make k a diffeomorphism of M. Then we define $g_1 = k \cdot g \in \text{Diff}^1(M)$. By (1), (16), we have

(18) $g_1^n(p) = g^n(p), \forall n \in \mathbb{Z}.$

In particular, p is a periodic point of g_1 .

By (1) and (16) we have

$$g_1^{-\alpha}(x_1) = (g^{-1}k^{-1})^{\alpha}(x_1) = g^{-\alpha}(x_2)$$
.

So it follows from (13), (9) that

$$g_1^{-nlpha}(g^{-lpha}(x_2))=g^{-nlpha}(g^{-lpha}(x_2))\;, \qquad orall n\geq 1\;.$$

Hence we have

(19) $g_1^{-n\alpha}(x_1) = g^{-n\alpha}(x_2), \forall n \geq 1.$

This implies that $x_1 \in W^u(p; g_1)$, because $g_1^{-n\alpha}(x_1)$ approaches p as $n \to \infty$. By (15), we can prove similarly that any point of the form (t, 0) with |t - b| small enough is contained in $W^u(p; g_1)$.

By (12) and (16), we have

$$g_1^{\alpha}(x_1) = (k \cdot g)^{\alpha}(x_1) = k \cdot g^{\alpha}(x_1) = g^{\alpha}(x_1)$$
.

Similarly we have

(20) $g_1^{n\alpha}(x_1) = g^{n\alpha}(x_1), \forall n \ge 1.$

This implies that $x_1 \in W^s(p; g_1)$. Also, we can prove similarly that any point of the form (t, 0) with |t - b| small enough is contained in $W^s(p; g_1)$.

Thus it is proved that x_1 is a non-transversal homoclinic point of g_1 . It is clear that the g_1 orbit of x_1 meets U and hence g_1 has a nontransversal homoclinic point in U. By Lemma A in Appendix, we have a small perturbation of g_1 with a non-hyperbolic periodic point in U. This contradicts the hypothesis, i.e. $f \in int \mathcal{H}(U)$. q.e.d

For the proof of Assertion 2 we first prove the following. For $\forall p \in$ Sd $(f) \cap U_f$, we define N(p) to be the smallest positive integer n such that

$$|Tf^{n}|E^{s}(p;f)||/||Tf^{n}|E^{u}(p;f)|| < \lambda$$
.

Clearly, N(p) does not exceed the period of p.

Assertion 4. $\sup \{N(p); p \in \mathrm{Sd}(f) \cap U_f\} < \infty$.

Proof. Given $\varepsilon > 0$, take a positive integer n_0 such that

 $(1) (1-\lambda)^{n_0} < \lambda \varepsilon^2.$

Suppose the above is not true. Then there is $p \in \text{Sd}(f) \cap U_f$ with $N(p) \ge n_0 + 3$. Let τ be the greatest integer such that $2\tau + 2 \le N(p)$. Let α be the period of p. Then,

(2) $n_0 + 2 \le 2\tau + 2 \le N(p) \le \alpha$.

We take unit vectors $V^s \in E^s(p; f)$, $V^u \in E^u(p; f)$. In what follows, we simply write

(3)
$$p_n = f^{n-1}(p),$$

$$(4) \quad V_n^s = Tf^{n-1}(V^s), \ V_n^u = Tf^{n-1}(V^u), \ \forall n \in \mathbb{Z}.$$

Note that $p_{\alpha} = p_0$ but $V_{\alpha}^s \neq V_0^s, \ V_{\alpha}^u \neq V_0^u.$

By Lemma B₂ in Appendix we construct $h = h_{\epsilon} \in \text{Diff}^{1}(M)$ with the following properties (5) ~ (11) in such a way that h approaches the identity in the C^{1} sense as $\epsilon \to 0$.

- (5) $h(p_n) = p_n, \forall 0 \leq n < \alpha.$
- (6) $h(x) = x, \forall x \text{ outside a small neighborhood of } \{p_n; 0 \le n < \alpha\}.$
- (7) $T_{p_1}h(V_1^s) = V_1^s, \ T_{p_1}h(V_1^u) = V_1^u + \varepsilon V_1^s.$
- (8) $\forall 2 \leq n \leq \tau + 1;$

$$T_{p_n}h(V_n^s) = (1-\varepsilon)^{-1}V_n^s, \qquad T_{p_n}h(V_n^u) = (1-\varepsilon)V_n^u.$$

(9) $\forall \tau + 2 \le n \le 2\tau + 1;$

$$T_{p_n}h(V_n^s) = (1-\varepsilon)V_n^s \,, \qquad T_{p_n}h(V_n^u) = (1-\varepsilon)^{-1}V_n^u \,.$$

(10) $\forall 2\tau + 2 \leq n \leq \alpha - 1; T_{p_n}h: T_{p_n}M \iff$ is the identity.

(11) $T_{p_{\alpha}}h(V_{\alpha}^{s}) = V_{\alpha}^{s}, T_{p_{\alpha}}h(V_{\alpha}^{u}) = V_{\alpha}^{u} - \varepsilon V_{\alpha}^{s}.$

Then we define $g = h \cdot f \in \text{Diff}^1(M)$. By (5),

(12) $g^n(p) = f^n(p), \forall n \in \mathbb{Z}.$

- It follows from (8), (9), (10) that
 - (13) $T_{p_1}g^n = T_{p_1}f^n, \forall 2\tau \leq n \leq \alpha 2.$

Now we want to show that

(14) $T_{p_0}g^{\alpha} = T_{p_0}f^{\alpha}$.

For this, it is sufficient to show the following:

(15) $T_{p_0}g(V_0^s) = V_{\alpha}^s, \ T_{p_0}g(V_0^u) = V_{\alpha}^u.$

The first is easily shown, so we check the latter:

$$\begin{split} T_{p_0}g^{\alpha}(V_0^u) &= T_{p_{\alpha-1}}gT_{p_1}g^{\alpha-2}T_{p_0}g(V_0^u) \\ &= (T_{p_{\alpha}}hT_{p_{\alpha-1}}f) \cdot (T_{p_1}f^{\alpha-2}) \cdot (T_{p_1}hT_{p_0}f)(V_0^u) \qquad \text{(by (13))} \\ &= T_{p_{\alpha}}hT_{p_1}f^{\alpha-1}T_{p_1}h(V_1^u) \\ &= T_{p_{\alpha}}hT_{p_1}f^{\alpha-1}(V_1^u + \varepsilon V_1^s) \qquad \text{(by (7))} \\ &= T_{p_{\alpha}}h(V_{\alpha}^u + \varepsilon V_{\alpha}^s) \qquad \text{(by (4))} \\ &= (V_{\alpha}^u - \varepsilon V_{\alpha}^s) + \varepsilon V_{\alpha}^s \qquad \text{(by (11))} \\ &= V_{\alpha}^u \,. \end{split}$$

It follows from (14) that g^{α} is hyperbolic at p_0 and

(16) $E^{u}(p_{0};g) = E^{u}(p_{0};g).$

It is also clear by the construction of h that

(17) $E^{s}(p_{n};g) = E^{s}(p_{n};f), \forall 0 \leq n < \alpha.$

Now we are in a position to conclude the proof. We estimate $d(E^{s}(p_{\tau+1}; g), E^{u}(p_{\tau+1}; g))$. By virtue of (16) and (17), this is equal to the angle θ between $T_{p_{0}}g^{\tau+1}(V_{0}^{u})$ and $E^{s}(p_{\tau+1}; f)$.

Write $T_{p_0}g^{\tau+1}(V_0^u) = (w_s, w_u)$ regarding $E^s(p_{\tau+1}; f) \oplus E^u(p_{\tau+1}; f)$. Let us compute w_s, w_u .

$$egin{aligned} T_{p_0}g^{ au+1}(V_0^u) &= T_pg^{ au}(arepsilon V_1^s+V_1^u) & ext{(by (7))} \ &= arepsilon T_pg^{ au}(V_1^s)+T_pg^{ au}(V_1^u) \ &= arepsilon(1-arepsilon)^{- au}T_pf^{ au}(V_1^s)+(1-arepsilon)^{ au}T_pf^{ au}(V_1^u) \ \end{aligned}$$

Hence

(18) $w_s = \varepsilon (1 - \varepsilon)^{-\tau} T_p f^{\tau}(V_1^s), \ w_u = (1 - \varepsilon)^{\tau} T_p f^{\tau}(V_1^u).$ By (2) and the definition of N(p), it follows that

$$egin{aligned} \|w_u\|/\|w_s\|&=arepsilon^{-1}(1-arepsilon)^{2 au}\,\|T_pf^{\,arepsilon}(V_1^u)\|/\|T_pf^{\,arepsilon}(V_1^s)\|&$$

Hence it follows that

$$\cos heta = (w_s + w_u) \cdot w_u / \|w_s + w_u\| \|w_u\| > (1 - arepsilon)/(1 + arepsilon) \longrightarrow 1$$
 ,

as $\varepsilon \to 0$.

Therefore, θ approaches 0 as $\varepsilon \to 0$, which contradicts Assertion 1. q.e.d.

Proof of Assertion 2. By Assertion 4, let

$$N = \sup \left\{ N(p); \, p \in \mathrm{Sd}\left(f
ight) \cap \ U_{f}
ight\} < \infty$$

Put $C = ||Tf|| ||Tf^{-1}||$. We take a positive integer *m* with $C^{N}\lambda^{m} < 1/2$. Let $\nu = (m + 1)N$.

For $\forall p \in \text{Sd}(f) \cap U_f$, we define $q_1, q_2, \dots, q_{r+1} \in \text{Sd}(f)$ as follows:

- (1) $q_1 = p$.
- $(2) \quad q_{i+1} = f^{N(q_i)}(q_i), \ 1 \leq i \leq r.$
- (3) $\nu N \leq \sum_{i=1}^{r} N(q_i) < \nu.$

Since $N(q_i) \leq N$, $\forall 1 \leq i \leq r$, it follows that $rN \geq \nu - N = mN$ and hence $r \geq m$.

Noting E^s , E^u are 1 dimensional, we have

(The second inequality follows from the definition of $N(q_i)$.) q.e.d.

§6. Appendix

Let M be a compact manifold without boundary. Let $f: M \to M$ be a C^1 diffeomorphism. The purpose here is to prove the following.

LEMMA A. If $z \in M$ is a non-transversal homoclinic point of f, then f can be approximated by a diffeomorphism with z as a non-hyperbolic periodic point.

Remark. A similar result was proved by Newhouse [4] in a different way.

We will apply the perturbation lemmas below to the proof of Lemma A. We fix a metric d on M and a C^1 metric d^1 on a neighborhood of I in Diff¹(M), where I is the identity of M.

LEMMA B₁. There are constants C > 0, $\eta > 0$ depending only on d and d^1 with the following property: Let $x_1, x_2 \in M$. If $d(x_1, x_2) < \varepsilon \delta$ for $0 < \varepsilon < \eta$, $0 < \delta < \eta$, then we have a $(C\varepsilon) - C^1$ perturbation k of I, i.e. $d^1(k, I) < C\varepsilon$, such that $k(x_1) = x_2$, and if $d(y, x_1) > \delta$, k(y) = y.

LEMMA B₂. There are constants C > 0, $\eta > 0$ depending only on d^1 with the following property: Let $x \in M$ and let $L_x: T_x M \longleftarrow$ be a linear mapping. Let I_x be the identity of $T_x M$. If $||L_x - I_x|| < \varepsilon$ for $0 < \varepsilon < \eta$, then

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for any $\delta > 0$ we have a $(C_{\varepsilon}) - C^{1}$ perturbation k of I such that k(x) = x, $T_{x}k = L_{x}$, and if $d(y, x) > \delta$, k(y) = y.

These facts are well-known and can be proved easily, so we omit their proofs.

Proof of Lemma A. It is sufficient to consider the case where $z \in W^s(p) \cap W^u(p)$ for some fixed point p because the other cases can be treated similarly. For convenience we denote by s, u the dimension of $W^s(p)$ and $W^u(p)$ respectively. In what follows, D^s (resp. D^u) denotes the unit disc of \mathbb{R}^s (resp. \mathbb{R}^u) centered at 0, and $B_r(x)$ the ball neighborhood of x of radius r > 0 in M.

We take a coordinate neighborhood (U, ψ) of p with the following properties (1) ~ (4).

(1) $\psi(U) = D^s \times D^u$.

From now on, we identify U with $D^s \times D^u$.

- (2) $D^s \times \{0\} \subset W^s(p), \{0\} \times D^u \subset W^u(p).$
- (3) $\exists 0 < \lambda < 1;$

$$\|T_p f(v, 0)\| \le \lambda \|v\|, \qquad \forall v \in \mathbf{R}^s,$$

$$\|T_p f^{-1}(0, w)\| \le \lambda \|w\|, \qquad \forall w \in \mathbf{R}^u.$$

(Note $T_p U \approx \mathbb{R}^s \times \mathbb{R}^u$. $\|\cdot\|$ means the Euclidean norm.) (4) $\forall x \in U \cap f(U) \cap f^{-1}(U);$

 $||T_x f - T_p f|| < lpha$, $||T_x f^{-1} - T_p f^{-1}|| < lpha$,

where $\alpha = (1 - \lambda)/4$.

Remark. As regards (3), refer to Nitecki [5], pp. $71 \sim 73$.

Let $x \in U \cap f(U) \cap f^{-1}(U)$. For $(v, w) \in \mathbb{R}^s \times \mathbb{R}^u$, we write $(v_1, w_1) = T_x f(v, w)$, $(v_2, w_2) = T_x f^{-1}(v, w)$. Then we have (5) ~ (8) below. (5) If $||v||/||w|| \le 1/2$, $||v_1||/||w_1|| \le 1/2$.

Proof. Let $\pi_1: \mathbb{R}^s \times \mathbb{R}^u \to \mathbb{R}^s$, $\pi_2: \mathbb{R}^s \times \mathbb{R}^u \to \mathbb{R}^u$ be projections. $v_1 = \pi_1 T_x f(v, w)$ $= \pi_1 (T_x f - T_p f)(v, w) + \pi_1 T_p f(v, 0) + \pi_1 T_p f(0, w)$.

Hence we have

$$||v_1|| = \alpha(||v|| + ||w||) + \lambda ||v|| \le (\lambda/2 + \alpha/2 + \alpha) ||w|| \le ||w||/2.$$

Similarly

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$$w_1 = \pi_2 T_x f(v, w)$$

= $\pi_2 (T_x f - T_p f)(v, w) + \pi_2 T_p f(v, 0) + \pi_2 T_p f(0, w) .$

and hence

$$||w_1|| \ge \lambda^{-1} ||w|| - \alpha(||v|| + ||w||) \ge (\lambda^{-1} - \alpha/2 - \alpha) ||w|| \ge ||w||.$$

Thus $||v_1||/||w_1|| \le 1/2$ follows.

(6) If $||w||/||v|| \le 1/2$, $||w_2||/||v_2|| \le 1/2$.

The proof is similar to (5).

(7) If $||w||/||v|| \le 1/2$, $||v_1|| \le \lambda_1 ||v||$ where $\lambda_1 = (1 + \lambda)/2$.

Proof. Decompose v_1 as in (5). Then we estimate

$$\|v_1\| \leq lpha(\|v\| + \|w\|) + \lambda \|v\| \leq (\lambda + 2lpha) \|v\| \leq \lambda_1 \|v\|$$

Thus we have (7).

(8) If $||v||/||w|| \le 1/2$, $||w_2|| \le \lambda_1 ||w||$.

The proof is similar to (7).

We choose integers n_1, n_2 such that $f^{n_1}(z) \in D^s \times \{0\}, f^{-n_2}(z) \in \{0\} \times D^u$ respectively. Remark that these sets really imply their inverse images by ψ . Take $\delta > 0$ so small that

 $\begin{array}{ll} (9) & f^n(z) \notin B_{\delta}(z_1) \, \cup \, B_{\delta}(z_2), \; \forall n; \, -n_2 < n < n_1 \\ \text{where} \; z_1 = f^{n_1}(z), \; z_2 = f^{-n_2}(z). \end{array}$

Regarding $U \approx D^s \times D^u$, we write

(10) $z_1 = (a_1, 0), z_2 = (0, a_2).$

Let $\varepsilon > 0$ be arbitrary. We define

$$egin{aligned} F^u &= \{(a_1,\,w)\in D^s imes D^u;\,\|w\|$$

If n_3 is sufficiently large, then $f^{-n_3}(F^s)$, $f^{n_3}(F^u)$ are represented by C^1 mappings $h_1: D^s \to D^u$, and $h_2: D^u \to D^s$ respectively. Furthermore, we can assume

(11) $\|h_1\| < \varepsilon \delta, \|h_2\| < \varepsilon \delta$

(12) $||Th_1|| < \epsilon/2, ||Th_2|| < \epsilon/2.$

Let V be a nonzero vector in $T_z W^s(p) \cap T_z W^u(p)$. We put

(13) $V_1 = T_z f^{n_1}(V), V_2 = T_z f^{-n_2}(V).$

Clearly V_1 has the form $(v_1, 0)$ with $v_1 \in \mathbb{R}^s$, and V_2 has the form $(0, w_2)$ with $w_2 \in \mathbb{R}^u$. We put

(14) $x_1 = (a_1, h_1(a_1)), x_2 = (h_2(a_2), a_2).$ Since $x_1 = f^{-n_3}(F^s) \cap F^u, x_2 = F^s \cap f^{n_3}(F^u)$, it follows that q.e.d.

q.e.d.

(15) $x_2 = f^{n_3}(x_1)$. We put (16) $w'_1 = T_{a_1} h_1(v_1).$ By the definition of h_1 there is $v_2 \in \mathbf{R}^s$ such (17) $(v_1, w_1') = T_{x_2} f^{-n_3}(v_2, 0).$ Let us write $(v_i^*, w_i^*) = T_{x_2} f^{-i}(v_2, 0), i = 0, 1, \dots, n_3$. Since $||w_0^*||/||v_0^*|| = 0$ < 1/2, it follows inductively by (6) that $||w_i^*||/||v_i^*|| \le 1/2$, $i = 0, 1, \dots, n_3$. Hence it follows by (7) that (18) $||v_2|| \leq \lambda_1^{n_3} ||v_1||.$ Likewise we put (19) $v'_2 = T_{a_2}h_2(w_2).$ By the definition of h_2 there is $w_1 \in \mathbf{R}^u$ such that (20) $(v'_2, w_2) = T_{x_1} f^{n_3}(0, w_1).$ Applying (5) and (8) as above, we have $(21) ||w_1|| < \lambda_1^{n_3} ||w_2||.$ By (18), (21), for sufficiently large n_3 we have (22) $||w_1||/||v_1|| < \varepsilon/2$, (23) $||v_2||/||w_2|| < \varepsilon/2.$ We define (24) $V'_1 = (v_1, w_1 + w'_1), V'_2 = (v_2 + v'_2, w_2).$ Then we have $T_{x_1}f^{n_3}(V_1') = T_{x_1}f^{n_3}(v_1, w_1 + w_1')$ $= T_{x_1}f^{n_3}(v_1, w_1') + T_{x_1}f^{n_3}(0, w_1)$ $= (v_2, 0) + (v'_2, w)$ (by (17), (20)) $= V_{2}'$. That is, (25) $T_{x_1}f^{n_3}(V_1') = V_2'$. By (24), (13), (22), (23) and (12), we estimate (26) $||V_1 - V_1'||/||V_1|| < \varepsilon$, (27) $||V_2 - V_2'||/||V_2'|| < \varepsilon.$

By (26) we have a linear mapping $L_1: \mathbb{R}^m \to \mathbb{R}^m$ $(m = \dim M)$ such that (28) $L_1(V_1) = V'_1$,

(29) $||L_1 - I|| < \varepsilon$, where I is the identity of \mathbb{R}^m .

For example, take an orthogonal basis $\{V_1, e_2, \dots, e_m\}$, and define L_1 by

$$L_1(t_1V_1 + t_2e_2 + \cdots + t_me_m) = t_1V_1' + t_2e_2 + \cdots + t_me_m ,
onumber \ \forall t_i \in I\!\!\!R; \, 1 \leq i \leq m .$$

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Similarly, by (27) we have a linear mapping $L_2: \mathbb{R}^m \to \mathbb{R}^m$ such that

- $(30) \quad L_2(V_2') = V_2,$
- (31) $||L_2 I|| < \varepsilon$.

By the way, we defined $z_1 = f^{n_1}(z)$, $z_2 = f^{-n_2}(z)$. By (10), (11) and (14) we have

 $(32) ||z_1-x_1|| < \varepsilon \delta,$

 $(33) ||z_2 - x_2|| < \varepsilon \delta.$

By (29), (31), (32) and (33) we can apply Lemmas B_1 and B_2 to constructing $k \in \text{Diff}^1(M)$ such that

- (34) $k(z_1) = x_1, T_z, k = L_1.$
- $(35) \quad k(x_2) = z_2, \ T_{x_2}k = L_2.$
- (36) $k(x) = x, \forall x \notin B_{\delta}(z_1) \cup B_{\delta}(z_2).$

(37) k is a $(C\varepsilon) - C^1$ perturbation of the identity of M (C is the one in Lemmas B₁ and B₂).

Now we shall conclude the proof. Define $g = k \cdot f \in \text{Diff}^1(M)$. First, it follows easily from (9), (15), (34), (35) and (36) that z is a periodic point of g of period $n_1 + n_2 + n_3$. We show that

$$T_z g^{n_1+n_2+n_3}(V) = V$$
,

which implies that z is not hyperbolic.

$$T_{z}g^{n_{1}+n_{2}+n_{3}}(V) = T_{x_{1}}g^{n_{2}+n_{3}}T_{z_{1}}kT_{z}f^{n_{1}}(V) \quad (by (9), (36))$$

$$= T_{x_{1}}g^{n_{2}+n_{3}}L_{1}(V_{1}) \quad (by (13), (34))$$

$$= T_{x_{1}}g^{n_{2}+n_{3}}(V'_{1}) \quad (by (28))$$

$$= T_{z_{2}}g^{n_{2}}L_{2}(V'_{2}) \quad (by (25), (35))$$

$$= T_{z_{2}}f^{n_{2}}(V_{2}) \quad (by (9), (36); (30))$$

$$= V \quad (by (13)).$$

Clearly g is near f in Diff¹ (M) by virtue of (37).

q.e.d.

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Kyoto University