

The adjacency operators of the infinite directed graphs
 and the von Neumann algebras generated by partial isometries

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1. Introduction.

A directed graph $G = (V, E)$ is a pair of countable sets V and E . An element $v \in V$ is called a vertex and an element $(v, u) \in E$ is called an arc with an initial vertex v and a terminal vertex u . For each vertex $v \in V$, the outdegree $d^+(v)$, the indegree $d^-(v)$ and the valency $d(v)$ are defined as follows ;

$$d^+(v) = |\{(v, u) ; (v, u) \in E\}|, \quad d^-(v) = |\{(u, v) ; (u, v) \in E\}|$$

and

$$d(v) = d^+(v) + d^-(v)$$

respectively where $|\{\cdot\}|$ means the cardinal number of a set $\{\cdot\}$. A graph has bounded valency if there is a constant $\alpha > 0$ such that $d(v) \leq \alpha$ for every vertex $v \in V$. Throughout this paper, we assume that a graph is a directed graph without multiple arcs and has bounded valency.

Mohar defined an adjacency operator for infinite undirected graphs in [2], and Fujii, Sasaoka and Watatani defined one for infinite graphs in [1]. An adjacency operator is in general unbounded, but we treat only bounded adjacency operator under the our assumption that a graph has bounded valency.

Let H be the Hilbert space $\ell^2(V)$ with the canonical basis $\{e_v ; v \in V\}$ defined by $e_v(u) = \delta_{v,u}$ for $u, v \in V$.

Let us define a closed operator $A = A(G)$ with the domain $D(A)$ by

$$D(A) = \left\{ x = \sum_{v \in V} x_v e_v \in H ; \sum_{u \in V} \left| \sum_{(v,u) \in E} x_v \right|^2 < \infty \right\}$$

$$Ax = \sum_{u \in V} \sum_{(v,u) \in E} x_v e_u \quad \text{for } x \in D(A).$$

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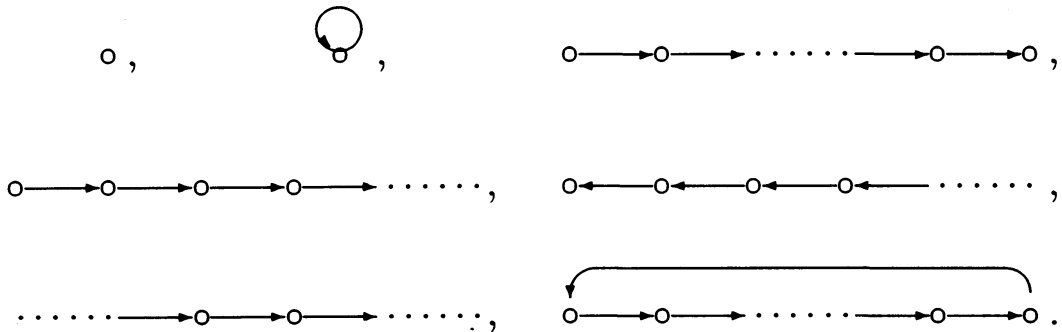
Now, we call $A = A(G)$ the adjacency operator of G . Then we have the following lemma [1 ; Theorem 2].

Lemma 1. *Let A be the adjacency operator of a graph G . Then, A is bounded if and only if G has bounded valency.*

We firstly show some properties of an adjacency operator which is a partial isometry.

An operator T on a Hilbert space K is a partial isometry if A^*A and AA^* are projections. In [1], a characterization that an adjacency operator is a partial isometry was given as follows :

Lemma 2. *Let A be the adjacency operator of a graph G . Then, A is a partial isometry if and only if the connected components of G are one of the following ;*



2. Results.

An operator T on K is called a power partial isometry if T^m is a partial isometry for $m = 1, 2, \dots$.

If we treat the adjacency operator $A = A(G)$ of an infinite directed graph G and A is a partial isometry, then we can show by considering Lemma 2 that A is a power partial isometry.

Proposition 3. *Let A be the adjacency operator of a graph G . If A is a partial isometry, then A is a power partial isometry.*

Proof. By Lemma 2, the operator A is represented by the direct sum in the following ;

$$A = \sum_{n=1}^{\infty} \oplus U_n \quad \text{on} \quad H = \sum_{n=1}^{\infty} \oplus H_n$$

where U_n is an operator satisfying one of the following conditions ;

(1) $U_n = 0$ on H_n ,

(2) $U_n =$ the identity on H_n ,

(3) $\dim H_n = s < \infty$ and $\{e_{n(k)}\}_{k=1}^s$ is a basis for H_n , and then

$$U_n e_{n(k)} = e_{n(k+1)} \quad (1 \leq k \leq s-1) \quad \text{and} \quad U_n e_{n(s)} = 0,$$

(4) $\dim H_n = s < \infty$ and $\{e_{n(k)}\}_{k=1}^s$ is a basis for H_n , and then

$$U_n e_{n(k)} = e_{n(k+1)} \quad (1 \leq k \leq s-1) \quad \text{and} \quad U_n e_{n(s)} = e_{n(1)},$$

(5) $\dim H_n = \infty$ and $\{e_{n(k)}\}_{k=1}^{\infty}$ is a completely orthonormal basis for H_n , and then

$$U_n e_{n(k)} = e_{n(k+1)} \quad (k = 1, 2, \dots),$$

(6) $\dim H_n = \infty$ and $\{e_{n(k)}\}_{k=1}^{\infty}$ is a completely orthonormal basis for H_n , and then

$$U_n e_{n(1)} = 0 \quad \text{and} \quad U_n e_{n(k)} = e_{n(k-1)} \quad (k = 2, 3, \dots),$$

(7) $\dim H_n = \infty$ and $\{e_{n(k)}\}_{k=-\infty}^{\infty}$ is a completely orthonormal basis for H_n , and then

$$U_n e_{n(k)} = e_{n(k+1)} \quad (k \in Z).$$

Then, each subspace H_n reduces A .

In the case of (1) (resp. (2)), $U_n^m = 0$ (resp. $U_n^m =$ the identity) on H_n ($m = 1, 2, \dots$). And so, U_n is a power partial isometry on H_n .

In the case of (3), $U_n^m e_{n(k)} = e_{n(k+m)}$ ($1 \leq k \leq s-m$) and $U_n^m e_{n(k)} = 0$ ($s-m \leq k \leq s$). And so U_n is a power partial isometry on H_n .

In the case of (4) and (7), since U_n is a unitary operator on H_n , U_n is a power partial isometry on H_n .

Furthermore, in the cases of (5) and (6), since U_n is a unilateral shift on H_n , U_n is a power partial isometry on H_n .

Since each subspace H_n reduces A , A is a power partial isometry on H by the above mentioned arguments. This gives the proof of Proposition 3.

As a property for the power partial isometries, Saito [5] showed the following result :

Let T be a power partial isometry on a Hilbert space K which is quasi-nilpotent. Then the von Neumann algebra $M(T)$ generated by T is of type I where $M(T)$ means the von Neumann algebra generated by T and the identity I .

Furthermore, Saito denoted as a remark in [5] that the type of von Neumann algebra generated by a general power partial isometry may be unknown.

For this remark, we can give an answer for a power partial isometry which is not necessarily quasi-nilpotent.

In particular, the following theorem is an extension of result obtained by Saito [5; Theorem 3].

Let U be an operator on a Hilbert space K . Then U is called a truncated shift of index n ($n = 1, 2, \dots$) if U is the operator such that K is the n -fold direct sum $K = K_0 \oplus K_0 \oplus \dots \oplus K_0$, and $U = 0$ if $n = 1$ and

$$U\langle f_1, f_2, \dots, f_n \rangle = \langle 0, f_1, f_2, \dots, f_{n-1} \rangle$$

if $n > 1$. Then, Saito showed the following result [5; Theorem 3].

Let T be the operator represented by the finite direct sum of truncated shifts

$$T = \sum_{k=1}^r \oplus U_{n(k)} \quad (1 \leq n(1) < n(2) < \dots < n(r))$$

where $U_{n(k)}$ is a truncated shift of index $n(k)$. Then the von Neumann algebra $M(T)$ generated by T is of type I.

Even if T is the operator represented by the infinite direct sum of truncated shifts, we show in the following theorem that the von Neumann algebra $M(T)$ is of type I.

Theorem 4. *Let T be the operator acting on a Hilbert space K represented by the infinite direct sum of truncated shifts*

$$T = \sum_{k=1}^{\infty} \oplus U_{n(k)} \quad (1 \leq n(1) < n(2) < \dots < n(k) < \dots)$$

where $U_{n(k)}$ is a truncated shift of index $n(k)$. Then the von Neumann algebra $M(T)$ generated by T is of type I.

Proof. Let T be the infinite direct sum of truncated shifts

$$T = \sum_{k=1}^{\infty} \oplus U_{n(k)} \quad \text{acting on} \quad K = \sum_{k=1}^{\infty} \oplus K_{n(k)}$$

where each $K_{n(k)}$ is the $n(k)$ -fold direct sum $K_{n(k)} = K_0^{(k)} \oplus K_0^{(k)} \oplus \cdots \oplus K_0^{(k)}$. Then, every $K_{n(k)}$ reduce T ($k = 1, 2, \dots$). Let $E^{(k)}$ be the projection of K onto $K_{n(k)}$, then $E^{(k)}$ is an element of the commutant $M(T)'$ of $M(T)$. Since

$$T^{*n(1)-1} T^{n(1)-1} = (E^{(1)} - E_1^{(1)}) \oplus (E_{12}^{(2)} \oplus O_{11}^{(2)}) \oplus \cdots \oplus (E_{12}^{(k)} \oplus O_{11}^{(k)}) \oplus \cdots,$$

where $E_1^{(1)}$ is the projection on $K_0^{(1)} \oplus O_0^{(1)} \oplus O_0^{(1)} \oplus \cdots \oplus O_0^{(1)}$ and each $O_{11}^{(k)}$ is the zero operator on the $(n(1) - 1)$ -fold direct sum

$$(O_0^{(k)} \oplus O_0^{(k)} \oplus \cdots \oplus O_0^{(k)}) \oplus \overbrace{K_0^{(k)} \oplus \cdots \oplus K_0^{(k)}}^{n(1)-1}$$

and $E_{12}^{(k)}$ is the projection on the $(n(k) - n(1) + 1)$ -fold direct sum

$$\overbrace{K_0^{(k)} \oplus \cdots \oplus K_0^{(k)}}^{n(k)-n(1)+1} (\oplus O_0^{(k)} \oplus O_0^{(k)} \oplus \cdots \oplus O_0^{(k)}) \quad (k = 2, 3, \dots),$$

$$I - T^{*n(1)-1} T^{n(1)-1} = E_1^{(1)} \oplus (O_{12}^{(2)} \oplus E_{11}^{(2)}) \oplus \cdots \oplus (O_{12}^{(k)} \oplus E_{11}^{(k)}) \oplus \cdots$$

is an element of $M(T)$ where $O_{12}^{(k)}$ is the zero operator on the $(n(k) - n(1) + 1)$ -fold direct sum

$$\overbrace{K_0^{(k)} \oplus \cdots \oplus K_0^{(k)}}^{n(k)-n(1)+1} (\oplus O_0^{(k)} \oplus O_0^{(k)} \oplus \cdots \oplus O_0^{(k)})$$

and $E_{11}^{(k)}$ is the projection of K onto the $(n(1) - 1)$ -fold direct sum

$$(O_0^{(k)} \oplus O_0^{(k)} \oplus \cdots \oplus O_0^{(k)}) \oplus \overbrace{K_0^{(k)} \oplus \cdots \oplus K_0^{(k)}}^{n(1)-1}.$$

Furthermore, since

$$TT^* = (E^{(1)} - E_1^{(1)}) \oplus (E^{(2)} - E_1^{(2)}) \oplus \cdots \oplus (E^{(k)} - E_1^{(k)}) \oplus \cdots$$

where $E_1^{(k)}$ is the projection on

$$K_0^{(k)} \oplus \overbrace{O_0^{(k)} \oplus O_0^{(k)} \oplus \cdots \oplus O_0^{(k)}}^{n(k)-1} \quad (k = 1, 2, 3, \dots),$$

$$I - TT^* = E_1^{(1)} \oplus E_1^{(2)} \oplus E_1^{(3)} \oplus \cdots \oplus E_1^{(k)} \oplus \cdots$$

is an element of $M(T)$. Thus,

$$(I - T^{*n(1)-1} T^{n(1)-1})(I - TT^*)$$

$$= \{E_1^{(1)} \oplus (O_{12}^{(2)} \oplus E_{11}^{(2)}) \oplus \cdots \oplus (O_{12}^{(k)} \oplus E_{11}^{(k)}) \oplus \cdots\}$$

$$\cdot \{E_1^{(1)} \oplus E_1^{(2)} \oplus E_1^{(3)} \oplus \cdots \oplus E_1^{(k)} \oplus \cdots\}$$

$$= E_1^{(1)}$$

is an element of $M(T)$. By applying a similar argument for

$$I - T^{*n(1)-2} T^{n(1)-2} \quad \text{and} \quad I - T^2 T^{*2},$$

we can show that $E_1^{(1)} + E_2^{(1)}$ is an element of $M(T)$ and so $E_2^{(1)}$ is also an element of $M(T)$ where $E_s^{(k)}$ is the projection on

$$O_0^{(k)} \oplus \cdots \oplus O_0^{(k)} \oplus \overbrace{K_0^{(k)}}^s \oplus O_0^{(k)} \oplus \cdots \oplus O_0^{(k)} \quad (k = 1, 2, 3, \dots).$$

Continuing this process, we can show that $E_1^{(1)}, E_2^{(1)}, \dots, E_{n(1)}^{(1)}$ are elements of $M(T)$ and so $E^{(1)}$ is an element of $M(T)$. Hence, $E^{(1)}$ is a central element of $M(T)$. Next, applying the above process for

$$I - T^{*n(2)-1} T^{n(2)-1} \quad \text{and} \quad I - TT^*,$$

$$I - T^{*n(2)-2} T^{n(2)-2} \quad \text{and} \quad I - T^2 T^{*2}, \quad \dots$$

since $E_1^{(1)}, E_2^{(1)}, \dots, E_{n(1)}^{(1)}$ are elements of $M(T)$ and $E^{(1)}$ is a central element of $M(T)$, we can show that $E_1^{(2)}, E_2^{(2)}, \dots, E_{n(2)}^{(2)}$ are elements of $M(T)$ and so

$E^{(2)}$ is a central element of $M(T)$. Continuing this process, we can show that $E_1^{(k)}, E_2^{(k)}, \dots, E_{n(k)}^{(k)}$ are elements of $M(T)$ and so $E^{(k)}$ is an element of $M(T)$ ($k = 1, 2, \dots$). Therefore, since every $U_{n(k)}$ is a truncated shift, $M(U_{n(k)})$ is a von Neumann algebra of type $I_{n(k)}$ and so $M(T)$ is a von Neumann algebra of type I. Thus, we have the complete proof of Theorem 4.

Theorem 5. *Let A be the adjacency operator of a graph G . If A is a partial isometry, then the von Neumann algebra $M(A)$ generated by A is of type I.*

Proof. By Lemma 2 and the proof of Proposition 3, we can assume that A has a representation of the direct sum in the following ;

$$A = \sum_{n=1}^6 \oplus U_n \quad \text{on} \quad H = \sum_{n=1}^6 \oplus H_n$$

such that

- (1) $U_1 = 0$ on H_1 ,
- (2) $U_2 =$ the identity on H_2 ,
- (3) U_3 is the finite or infinite direct sum of truncated shifts with the different indices on H_3 ,
- (4) H_4 and H_5 are the infinite dimensional subspaces and U_4 (resp. U_5) is a unilateral shift (resp. a backward shift) on H_4 (resp. H_5),
- (5) U_6 is a unitary operator on H_6 .

Let E_n be the projection of H onto H_n . Then, since each H_n reduces A , E_n is an element of the commutant $M(A)'$ of $M(A)$. Furthermore, we show that each E_n is an element of $M(A)$ and so E_n is a central element of $M(A)$.

Since

$$E_1 = I - \sum_{n=2}^6 \oplus U_n^* U_n \quad \text{and} \quad E_2 = (I - \sum_{n=3}^6 \oplus U_n^* U_n) - E_1,$$

E_1 and E_2 are elements of $M(A)$.

Now, since $U_3^{*m}U_3^m$ and $U_5^{*m}U_5^m$ (resp. $U_4^{*m}U_4^m$ and $U_6^{*m}U_6^m$) converge to 0 as $m \rightarrow \infty$ in the weak topology (resp. equal to the identity for every $m = 1, 2, \dots$ on H_4 and H_6 respectively), $E_4 + E_6$ is an element of $M(A)$ and so $E_3 + E_5$ is also an element of $M(A)$.

Furthermore, $U_5^mU_5^{*m} = E_5$ for every $m = 1, 2, \dots$ and $U_3^mU_3^{*m} \rightarrow 0$ as $m \rightarrow \infty$ in the weak topology. Thus, E_5 and so E_3 are elements of $M(A)$. By a similar argument, since $U_6^mU_6^{*m} = E_6$ for every $m = 1, 2, \dots$ and $U_4^mU_4^{*m} \rightarrow 0$ as $m \rightarrow \infty$ in the weak topology. Thus, E_6 and so E_4 are elements of $M(A)$.

Since $M(AE_1) = \mathbb{C}E_1$, $M(AE_2) = \mathbb{C}E_2$ and $M(AE_6)$ acting on H_1 , H_2 and H_6 respectively are abelian, these von Neumann algebras are of type I where \mathbb{C} is the complex number field. Furthermore, since U_4 and U_5 are unilateral shift, $M(AE_4)$ and $M(AE_5)$ are von Neumann algebras of type I on H_4 and H_5 respectively. And furthermore, the von Neumann algebra $M(AE_3)$ acting on H_3 is of type I by Theorem 4. Therefore,

$$M(A) = \sum_{n=1}^6 \oplus M(AE_n)$$

is a von Neumann algebra of type I. We get the complete proof of Theorem 5.

3. Remarks and Example.

We showed in the previous section the following ; if the adjacency operator A of a graph is a partial isometry, then the von Neumann algebra generated by A is of type I. Thus, we have a following remark.

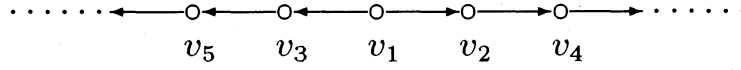
Remark 1. Saito showed in [4] that for a certain von Neumann algebra M the following properties are equivalent ;

- (a) M has a single generator.
- (b) M is generated by one partial isometry.

Precisely certain von Neumann algebra mentioned above means an AF-von Neumann algebra, of type II_1 , of type II_∞ or type III. But, if we consider a generator by the restriction in the adjacency operators of a graph, then we can't get a similar result to Saito's result by our Theorem 5.

Next, we shall give an example in which we consider a generator of von Neumann algebra of type I except the partial isometries.

Example. We consider an example of graph $G = (V, E)$ as below ;



Put e_n the element e_{v_n} of the Hilbert space $H = \ell^2(V)$, then the adjacency operator $A = A(G)$ with respect to G is determined by the following ;

$$e_1 \rightarrow e_2 + e_3, \quad e_{2n} \rightarrow e_{2(n+1)}, \quad e_{2n+1} \rightarrow e_{2(n+1)+1} \quad (n \geq 1).$$

Thus, the operators A^*A and AA^* are of the following form ;

$$A^*A : e_1 \rightarrow 2e_1, \quad e_n \rightarrow e_n \quad (n \geq 2)$$

and

$$AA^* : e_1 \rightarrow 0, \quad e_2 \rightarrow e_2 + e_3, \quad e_3 \rightarrow e_2 + e_3, \quad e_n \rightarrow e_n \quad (n \geq 4).$$

And so A is not a partial isometry.

Now, define the projections $P_{[e_n]}$, $P_{[e_n+e_{n+1}]}$, $P_{[e_n, e_{n+1}]}$, $P_{[e_n, e_{n+1}, e_{n+2}, \dots]}$ (resp.) on the one dimensional subspace $[e_n]$ and $[e_n + e_{n+1}]$, the two dimensional subspace $[e_n, e_{n+1}]$ and the infinite dimensional subspace $[e_n, e_{n+1}, e_{n+2}, \dots]$ (resp.). Then $A^*A = 2P_{[e_1]} + P_{[e_2, e_3, e_4, \dots]}$ and $AA^* = P_{[e_2, e_3]} + P_{[e_4, e_5, e_6, \dots]}$. Furthermore, since $(A^*A)^2 = 4P_{[e_1]} + P_{[e_2, e_3, e_4, \dots]}$, $P_{[e_1]}$ and $P_{[e_2, e_3, e_4, \dots]}$ are elements of $M(A)$. By a similar way, we can show that $P_{[e_2, e_3]}$ and $P_{[e_4, e_5, e_6, \dots]}$ are elements of $M(A)$.

On the other hand, since

$$\left(\frac{1}{\sqrt{2}} AP_{[e_1]} \right)^* \left(\frac{1}{\sqrt{2}} AP_{[e_1]} \right) = \frac{1}{2} AP_{[e_1]} A^* = P_{[e_2+e_3]},$$

$P_{[e_2+e_3]}$ is an element of $M(A)$ and $\frac{1}{\sqrt{2}} AP_{[e_1]}$ is a partial isometry with the initial projection $P_{[e_1]}$ and the final projection $P_{[e_2+e_3]}$. Thus, the projection $P_{[e_2-e_3]}$ is also an element of $M(A)$ because $P_{[e_2, e_3]}$ and $P_{[e_2+e_3]}$ are elements of $M(A)$. Now, since we can show by an elementary computation that $P_{[e_2+e_3]}$ is

not a central element of the von Neumann algebra $P_{[e_2, e_3]}M(A)P_{[e_2, e_3]}$, $M(A)$ contains the matrix units with respect to $\{P_{[e_2+e_3]}, P_{[e_2-e_3]}\}$ and so with respect to $\{P_{[e_2]}, P_{[e_3]}\}$. Hence, $M(A)$ contains the matrix units with respect to $\{P_{[e_1]}, P_{[e_2]}, P_{[e_3]}\}$. By repeating a similar argument, we can show that $M(A)$ contains the matrix units with respect to $\{P_{[e_1]}, P_{[e_2]}, P_{[e_3]}, P_{[e_4]}, P_{[e_5]}\}$, $\dots\dots\dots$, $\{P_{[e_1]}, \dots, P_{[e_{2n}]}, P_{[e_{2n+1}]}\}$. Thus, we can get the property $M(A) = B(H)$ and so the conclusion of this example.

Remark 2. We showed the generator of von Neumann algebra of type I in the previous part. But we don't know whether an adjacency operator generates a von Neumann algebra of type II or type III. This is a problem that we must consider after this. In general case, Percy [3] firstly showed that there exists a partial isometry V (resp. W) generating a von Neumann algebra of type II_1 (resp. II_∞). But, if we consider this Percy's result in the adjacency operators, we can't expect a similar result by considering our previous result (i.e. Theorem 5).

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