

ON A CLASS OF SASAKIAN MANIFOLDS

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ABSTRACT. In the present paper, we shall discuss C -Bochner pseudo-symmetric Sasakian manifolds and also Sasakian manifolds satisfying the condition $B \cdot S = 0$ where B and S are the C -Bochner curvature tensor and the Ricci tensor of the manifolds respectively.

1. Introduction

A Riemannian manifold (M^n, g) is called locally symmetric if its curvature tensor R is parallel i.e., $\nabla R = 0$, where ∇ denotes the Levi Civita connection. As a proper generalization of locally symmetric manifolds the notion of semi-symmetric manifolds was defined by

$$(R(X, Y) \cdot R)(U, V)W = 0, \quad X, Y, U, V, W \in \chi(M^n)$$

and studied by many authors, e.g. ([13], [14], [20], [19]). A complete intrinsic classification of these spaces was given by Z. I. Szabo [18]. Ryszard Deszcz and others ([6], [7], [5]) weakened the notion of semi-symmetry and introduced the notion of pseudo-symmetric manifolds by

$$(R(X, Y) \cdot R)(U, V)W = L_R[((X \wedge Y) \cdot R)(U, V)W],$$

where L_R is some smooth function on M^n and

$$\begin{aligned} (R(X, Y) \cdot R)(U, V)W &= R(X, Y)R(U, V)W - R(R(X, Y)U, V)W \\ &\quad - R(U, R(X, Y)V)W - R(U, V)R(X, Y)W, \end{aligned}$$

$X \wedge Y$ is an endomorphism defined by

$$(X \wedge Y)Z = g(Y, Z)X - g(X, Z)Y.$$

We refer the reader to R. Deszcz [6] as a general reference for the ideas of pseudo-symmetric manifolds.

2000 *Mathematics Subject Classification.* 53C25.

Key words and phrases. Sasakian manifold, C -Bochner curvature tensor, Ricci tensor, Einstein manifold and η -Einstein manifold.

A Riemannian or a semi-Riemannian manifold is said to be C -Bochner pseudo-symmetric if

$$(1) \quad (R(X, Y) \cdot B)(U, V)W = L_B[((X \wedge Y) \cdot B)(U, V)W]$$

holds on the set $U_B = \{x \in M : B \neq 0 \text{ at } x\}$, where L_B is some function on U_B and B is the C -Bochner curvature tensor [11]. Recently M. Hotlos [9] has studied Bochner pseudo-symmetric para-Kähler manifold and prove that such a manifold is semi-symmetric. The present paper deals with a Sasakian manifold in which the condition (1) holds. In Section 3, we prove a result ensuring the existence of $n(= 2m + 1 \geq 5)$ -dimensional C -Bochner pseudo-symmetric Sasakian manifolds which are not C -Bochner semi-symmetric ones. This result also generalizes the result[3, Theorem 1] and is somewhat connected with the works of [1] and [4]. In the last section, we prove that if a Sasakian manifold M^n , $n \geq 5$, is η -Einstein then the condition $B \cdot S = 0$ holds on M^n , where S is the Ricci tensor.

2. Preliminaries

Let (M^n, g) be an $n(= 2m + 1 \geq 5)$ -dimensional contact Riemannian manifold with contact form η , the associated vector field ξ , $(1,1)$ -tensor field ϕ and the associated Riemannian metric g . If ξ is a Killing vector field then M^n is called a K -contact Riemannian manifold ([2], [17]). If in such a manifold the relation

$$(2) \quad (\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X$$

holds, where ∇ denotes the Levi Civita connection of g , then M^n is called a *Sasakian manifold*. It is well-known that every Sasakian manifold is K -contact but the converse is not true in general. However, a 3-dimensional K -contact manifold is Sasakian. On the other hand, the notion of C -Bochner curvature tensor on a Sasakian manifold was first introduced by Matsumoto and Chuman [11]. Also, C -Bochner curvature tensor has been studied by V. Mihova-Nehmer [12], I. Hasegawa and T. Nakahe [8], T. Ikawa and M. Kon [10], G. Pathak, U. C. De and Y. H. Kim [16].

A contact metric manifold is said to be η -Einstein if its Ricci tensor S is of the form

$$S = ag + b\eta \otimes \eta,$$

where a, b are functions on M^n .

Let R, Q, r denote respectively the curvature tensor of type $(1,3)$, Ricci operator and scalar curvature of M^n . It is known that in a contact manifold M^n the Riemannian metric may be so chosen that the following relations hold [2], [21].

$$(3) \quad a) \quad \phi\xi = 0, \quad b) \quad \eta(\xi) = 1, \quad c) \quad \eta \circ \phi = 0.$$

$$(4) \quad \phi^2 X = -X + \eta(X)\xi,$$

$$(5) \quad g(X, \xi) = \eta(X),$$

$$(6) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y)$$

for any vector fields X, Y . If M^n is a Sasakian manifold, then besides (3), (4), (5) and (6) the following relations hold ([2], [21]):

$$(7) \quad \nabla_X \xi = -\phi X,$$

$$(8) \quad \Phi(X, Y) = (\nabla_X \eta)Y,$$

$$(9) \quad \Phi(X, Y) = -\Phi(Y, X),$$

$$(10) \quad \Phi(X, \xi) = 0,$$

$$(11) \quad R(X, Y)\xi = \eta(Y)X - \eta(X)Y,$$

$$(12) \quad R(\xi, X)Y = (\nabla_X \phi)Y,$$

$$(13) \quad S(X, \xi) = (n-1)\eta(X).$$

The C -Bochner curvature tensor on a Sasakian manifold $M^n (n = 2m + 1 \geq 5)$ is defined by [11]

$$(14) \quad \begin{aligned} B(X, Y)Z = & R(X, Y)Z + \frac{1}{n+3}[S(X, Z)Y - S(Y, Z)X + g(X, Z)QY \\ & - g(Y, Z)QX + S(\phi X, Z)\phi Y - S(\phi Y, Z)\phi X + g(\phi X, Z)Q\phi Y \\ & - g(\phi Y, Z)Q\phi X + 2S(\phi X, Y)\phi Z + 2g(\phi X, Y)Q\phi Z - S(X, Z)\eta(Y)\xi \\ & + S(Y, Z)\eta(X)\xi - \eta(X)\eta(Z)QY + \eta(Y)\eta(Z)QX] \\ & - \frac{k+n-1}{n+3}[g(\phi X, Z)\phi Y - g(\phi Y, Z)\phi X + 2g(\phi X, Y)\phi Z] \\ & - \frac{k-4}{n+3}[g(X, Z)Y - g(Y, Z)X] \\ & + \frac{k}{n+3}[g(X, Z)\eta(Y)\xi + \eta(X)\eta(Z)Y \\ & - g(Y, Z)\eta(X)\xi - \eta(Y)\eta(Z)X], \end{aligned}$$

where $k = \frac{r+n-1}{n+1}$ and $S(X, Y) = g(QX, Y)$.

From (14), it can be easily verified that in a Sasakian manifold M^n , ($n \geq 5$), the C -Bochner curvature tensor satisfies the following properties:

$$(15) \quad B(X, Y)Z = -B(Y, X)Z,$$

$$(16) \quad B(\xi, Y)Z = 0,$$

$$(17) \quad B(X, Y)\xi = 0,$$

$$(18) \quad B(X, Y, Z, \xi) = 0,$$

and

$$(19) \quad B(X, Y, Z, U) = B(Z, U, X, Y),$$

for all vector fields X, Y, Z, U and $B(X, Y, Z, U) = g(B(X, Y)Z, U)$.

The above results will be used in the following sections.

3. C -Bochner pseudo-symmetric Sasakian manifolds

Let M^n be an $n(= 2m + 1 \geq 5)$ -dimensional C -Bochner pseudo-symmetric Sasakian manifold. Then putting $Y = \xi$ in (1) we have

$$(20) \quad \begin{aligned} (R(X, \xi) \cdot B)(U, V)W &= L_B[((X \wedge \xi) \cdot B)(U, V)W] \\ &= L_B[((X \wedge \xi)(B(U, V)W) - B((X \wedge \xi)U, V)W \\ &\quad - B(U, (X \wedge \xi)V)W - B(U, V)(X \wedge \xi)W]. \end{aligned}$$

The above equation can be written as

$$(21) \quad \begin{aligned} R(X, \xi)B(U, V)W - B(R(X, \xi)U, V)W - B(U, R(X, \xi)V)W \\ - B(U, V)R(X, \xi)W &= L_B[B(U, V, W, \xi)X - B(U, V, W, X)\xi \\ &\quad - \eta(U)B(X, V)W + g(X, U)B(\xi, V)W \\ &\quad - \eta(V)B(U, X)W + g(X, V)B(U, \xi)W \\ &\quad - \eta(W)B(U, V)X + g(X, W)B(U, V)\xi]. \end{aligned}$$

Now using (11), (16), (17) and (18) into (21) it follows that

$$\begin{aligned} -B(U, V, W, X)\xi - \eta(V)B(U, X)W - \eta(W)B(U, V)X \\ - \eta(U)B(X, V)W &= -L_B[B(U, V, W, X)\xi \\ &\quad + \eta(V)B(U, X)W + \eta(W)B(U, V)X + \eta(U)B(X, V)W]. \end{aligned}$$

Putting $V = \xi$ in the last equation and using (17) and (18) we obtain

$$(22) \quad (L_B - 1)B(U, X)W = 0.$$

From (22), we have easily the following theorem.

Theorem 3.1 *Let M^n be an $n(= 2m + 1 \geq 5)$ -dimensional C -Bochner pseudo-symmetric Sasakian manifold. Then, either $B \neq 0$ and $L_B = 1$ or $B = 0$ holds at each point of M^n .*

Since C -Bochner semi-symmetric Sasakian manifold can be regarded as a special C -Bochner pseudo-symmetric Sasakian manifold, from the above Theorem 3.1, we have immediately the following.

Corollary 3.2 *An $n(= 2m + 1 \geq 5)$ -dimensional C -Bochner semi-symmetric Sasakian manifold is C -Bochner flat.*

The above corollary was already proved in [3].

4. Sasakian manifolds satisfying $B \cdot S = 0$

Let M^n be an $n(= 2m + 1 \geq 5)$ -dimensional η -Einstein Sasakian manifold. Then we can write

$$(23) \quad S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y),$$

where a and b are constants.

Putting $X = Y = e_i$ in (23), where $\{e_i\}$ is an orthonormal basis of the tangent space at each point of the manifold and taking summation over i , $1 \leq i \leq n$ we obtain

$$(24) \quad r = na + b.$$

On the other hand, putting $X = Y = \xi$ in (23) and using (13) we also have

$$(25) \quad n - 1 = a + b.$$

Hence it follows from (24) and (25) that

$$a = \frac{r}{n-1} - 1 \quad , \quad b = n - \frac{r}{n-1}.$$

So the Ricci tensor S of an η -Einstein Sasakian manifold is given by

$$(26) \quad S(X, Y) = \left(\frac{r}{n-1} - 1 \right) g(X, Y) + \left(n - \frac{r}{n-1} \right) \eta(X)\eta(Y).$$

Now

$$(27) \quad \begin{aligned} (B(U, X) \cdot S)(Y, Z) &= -S(B(U, X)Y, Z) - S(Y, B(U, X)Z) \\ &= \left(1 - \frac{r}{n-1} \right) B(U, X, Y, Z) + \left(\frac{r}{n-1} - n \right) \eta(B(U, X)Y)\eta(Z) \\ &\quad + \left(1 - \frac{r}{n-1} \right) B(U, X, Z, Y) + \left(\frac{r}{n-1} - n \right) \eta(B(U, X)Z)\eta(Y). \end{aligned}$$

Using (19) and (18) in (27) we obtain $B \cdot S = 0$. Thus we can state the following:

Theorem 4.1 *Let (M^n, g) be an $n(= 2m + 1 \geq 5)$ -dimensional η -Einstein Sasakian manifold. Then the condition $B \cdot S = 0$ holds on M^n .*

Remark. It is known that an $n(= 2m + 1 \geq 5)$ -dimensional Sasakian manifold of constant ϕ -sectional curvature (namely, a Sasakian space form) is C -Bochner flat and η -Einstein and also that an $n(= 2m + 1 \geq 5)$ -dimensional C -Bochner flat Sasakian manifold is η -Einstein if and only if it is a Sasakian space form ([11], Theorem 2.4, Corollary 2.5). From these observations, it seems that the converse of the above Theorem 4.1 is not necessarily valid in general.

Acknowledgement. The authors would like to express their thanks to the referee for his valuable suggestions.

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Received October 2, 2007

Revised January 8, 2008