

The Structure Theorem for the Cut Locus of a Certain Class of Cylinders of Revolution I

Pakkinee CHITSAKUL

King Mongkut's Institute of Technology Ladkrabang

(Communicated by Y. Komori-Furuya)

Abstract. The aim of this paper is to determine the structure of the cut locus for a class of surfaces of revolution homeomorphic to a cylinder. Let M denote a cylinder of revolution which admits a reflective symmetry fixing a parallel called the equator of M . It will be proved that the cut locus of a point p of M is a subset of the union of the meridian and the parallel opposite to p respectively, if the Gaussian curvature of M is decreasing on each upper half meridian.

1. Introduction

It is a very difficult problem to determine the structure of the cut locus of a Riemannian manifold and it was difficult even for a quadric surface.

Since Elerath ([E]) succeeded in specifying the structure of the cut locus for paraboloids of revolution and (2-sheeted) hyperboloids of revolution, the structures of the cut locus for quadric surfaces of revolution have been studied. After his work, Sinclair and Tanaka ([ST]) determined the structure of the cut locus for a class of surfaces of revolution containing the ellipsoids. Notice that the structures of the cut locus for triaxial ellipsoids with unequal axes were also determined by Itoh and Kiyohara ([IK]).

On the structure of the cut locus for a cylinder of revolution $(R^1 \times S^1, dt^2 + m(t)^2 d\theta^2)$, Tsuji ([Ts]) first determined the cut locus of a point on the equator $t = 0$ if the cylinder is symmetric with respect to the equator and the Gaussian curvature is decreasing on the upper half meridian $t > 0, \theta = 0$. In 2003, Tamura ([Ta]) determined the structure of the cut locus by adding an assumption $m' \neq 0$ except $t = 0$. In this paper, we determine the structure of the cut locus without this assumption.

Here, let us review the notion of a cut point and the cut locus of a point. Let $\gamma : [0, a] \rightarrow M$ be a minimal geodesic segment in a complete Riemannian manifold M . The end point of $\gamma(a)$ is called a *cut point* of $\gamma(0)$ along γ , if any geodesic extension of γ is not minimal anymore. The *cut locus* C_p of a point p of M is by definition the set of the cut points along all minimal geodesic segments emanating from p .

Received August 16, 2013

2010 *Mathematics Subject Classification*: 53C22

Key words and phrases: cut point, cut locus, cylinder of revolution

In this paper we will prove the following theorem.

MAIN THEOREM. *Let (M, ds^2) be a complete Riemannian manifold $R^1 \times S^1$ with a warped product metric $ds^2 = dt^2 + m(t)^2 d\theta^2$ of the real line (R^1, dt^2) and the unit circle $(S^1, d\theta^2)$. Suppose that the warping function m is a positive-valued even function and the Gaussian curvature of M is decreasing along the half meridian $t^{-1}[0, \infty) \cap \theta^{-1}(0)$. If the Gaussian curvature of M is positive on $t = 0$, then the structure of the cut locus C_q of a point $q \in \theta^{-1}(0)$ in M is given as follows:*

1. *The cut locus C_q is the union of a subarc of the parallel $t = -t(q)$ opposite to q and the meridian opposite to q if $|t(q)| < t_0 := \sup\{t > 0 \mid m'(t) < 0\}$ and $\varphi(m(t(q))) < \pi$. More precisely,*

$$C_q = \theta^{-1}(\pi) \cup \left(t^{-1}(-t(q)) \cap \theta^{-1}[\varphi(m(t(q))), 2\pi - \varphi(m(t(q)))] \right).$$

2. *The cut locus C_q is the meridian $\theta^{-1}(\pi)$ opposite to q if $\varphi(m(t(q))) \geq \pi$ or if $|t(q)| \geq t_0$.*

Here, the function $\varphi(v)$ on $(\inf m, m(0))$ is defined as

$$\varphi(v) := 2 \int_{-\xi(v)}^0 \frac{v}{m\sqrt{m^2 - v^2}} dt = 2 \int_0^{\xi(v)} \frac{v}{m\sqrt{m^2 - v^2}} dt,$$

where $\xi(v) := \min\{t > 0 \mid m(t) = v\}$. Notice that the point q is an arbitrarily given point if the coordinates (t, θ) are chosen so as to satisfy $\theta(q) = 0$.

REMARK 1.1. If the Gaussian curvature of a cylinder of revolution is nonpositive everywhere, then any geodesic has no conjugate point. Therefore, it is clear to see that the cut locus of a point on the manifold is the meridian opposite to the point.

2. Preliminaries

Let f be the solution of the differential equation

$$f'' + Kf = 0 \tag{2.1}$$

with initial conditions $f(0) = c$ and $f'(0) = 0$. Here c denotes a fixed positive number and $K : [0, \infty) \rightarrow R$ denotes a continuous function.

LEMMA 2.1. *If $K(0) > 0$ and $f'(t) \neq 0$ for any $t > 0$, then $f'(t) < 0$ on $(0, \infty)$. Furthermore, if $f > 0$ on $[0, \infty)$, then $K(t) < 0$ for some $t > 0$.*

PROOF. Since $f''(0) = -K(0)f(0) < 0$ by (2.1), $f'(t)$ is strictly decreasing on $(0, \delta)$ for some $\delta > 0$. This implies that $0 = f'(0) > f'(t)$ for any $t \in (0, \delta)$. Since $f' \neq 0$ on $[0, \infty)$, $f'(t) < 0$ on $(0, \infty)$. Furthermore, we assume that $f > 0$ on $[0, \infty)$. Supposing that $K \geq 0$ on $[0, \infty)$, we will get a contradiction. By (2.1),

$$f''(t) = -K(t)f(t) \leq 0$$

on $[0, \infty)$. Hence $f'(t)$ is decreasing on $[0, \infty)$. In particular, $0 = f'(0) > f'(\delta) \geq f'(t)$ for any $t \geq \delta$. This contradicts the assumption $f > 0$. \square

LEMMA 2.2. *Suppose that $K(0) > 0$ and $f > 0$ on $[0, \infty)$. If $f'(t) = 0$ for some $t > 0$ and K is decreasing, then there exist a unique solution $t = t_0 \in (0, \infty)$ of $f'(t) = 0$ such that $f'(t) < 0$ on $(0, t_0)$ and $f'(t) > 0$ on (t_0, ∞) and there exists $t_1 \in (0, t_0)$ satisfying $K(t_1) = 0$. Hence $K \geq 0$ on $[0, t_1]$ and $K \leq 0$ on $[t_1, \infty)$.*

PROOF. Let $a > 0$ denote the minimum positive solution $t = a$ of $f'(t) = 0$. Suppose that there exist another solution $b (> a)$ satisfying $f'(b) = 0$. By the mean value theorem, there exist $t_1 \in (0, a)$ and $s_1 \in (a, b)$ satisfying $f''(t_1) = f''(s_1) = 0$. Hence $K(t_1) = K(s_1) = 0$ by (2.1). Since K is decreasing, $K = 0$ on $[t_1, s_1]$. Therefore, by (2.1), $f''(t) = 0$ on $[t_1, s_1]$. In particular, $f'(a) = f'(t_1) = 0$. Since $0 < t_1 < a$, t_1 is a positive solution t of $f'(t) = 0$, which is less than a . This is a contradiction. Therefore, there exists a unique positive solution $t = t_0$ of $f'(t) = 0$. From the mean value theorem and (2.1), there exists $t_1 \in (0, t_0)$ satisfying $K(t_1) = 0$. Since $K(t)$ is decreasing, $K \geq 0$ on $[0, t_1]$ and $K \leq 0$ on $[t_1, \infty)$. Hence by (2.1), $f''(t) = -K(t)f(t) \geq 0$ on $[t_1, \infty)$ and $f'(t) \geq f'(t_0) = 0$ for any $t > t_0$. Since f' has a unique positive zero, $f' > 0$ on (t_0, ∞) . It is clear from the proof of Lemma 2.1 that $f' < 0$ on $(0, t_0)$. \square

3. Review of the behavior of geodesics

From now on, M denotes a complete Riemannian manifold $R^1 \times S^1$ with a warped product Riemannian metric $ds^2 = dt^2 + m(t)^2 d\theta^2$ of the real line (R^1, dt^2) and the unit circle $(S^1, d\theta^2)$. Let us review the behavior of a geodesic $\gamma(s) = (t(s), \theta(s))$ on the manifold M . For each unit speed geodesic $\gamma(s) = (t(s), \theta(s))$, there exists a constant v satisfying

$$m(t(s))^2 \theta'(s) = v. \tag{3.1}$$

Hence, if $\eta(s)$ denotes the angle made by the velocity vector $\gamma'(s)$ of the geodesic $\gamma(s)$ and the tangent vector $(\partial/\partial\theta)_{\gamma(s)}$, then

$$m(t(s)) \cos \eta(s) = v \tag{3.2}$$

for any s . The constant v is called the *Clairaut constant* of γ . The reader should refer to Chapter 7 in [SST] for the Clairaut relation. Since $\gamma(s)$ is unit speed,

$$t'(s)^2 + m(t(s))^2 \theta'(s)^2 = 1 \tag{3.3}$$

holds. By (3.1) and (3.3), it follows that

$$t'(s) = \pm \frac{\sqrt{m(t(s))^2 - v^2}}{m(t(s))} \tag{3.4}$$

$$\theta(s_2) - \theta(s_1) = \varepsilon(t'(s)) \int_{t(s_1)}^{t(s_2)} \frac{v}{m\sqrt{m^2 - v^2}} dt \tag{3.5}$$

holds, if $t'(s) \neq 0$ on (s_1, s_2) and $\varepsilon(t'(s))$ denotes the sign of $t'(s)$.

The length $L(\gamma)$ of a geodesic segment $\gamma(s) = (t(s), \theta(s))$, $s_1 \leq s \leq s_2$ is

$$L(\gamma) = \varepsilon(t'(s)) \int_{t(s_1)}^{t(s_2)} \frac{m(t)}{\sqrt{m(t)^2 - v^2}} dt \tag{3.6}$$

if $t'(s) \neq 0$ on (s_1, s_2) .

From a direct computation, the Gaussian curvature G of M is given by

$$G(q) = -\frac{m''}{m}(t(q))$$

at each point $q \in M$. Since G is constant on $t^{-1}(a)$ for each $a \in R$, a smooth function K on R is defined by

$$K(u) := G(q)$$

for $q \in t^{-1}(u)$. Therefore m satisfies the following differential equation

$$m'' + Km = 0$$

with $m'(0) = 0$.

From now on, we assume that the Gaussian curvature G of M is positive on $t^{-1}(0)$, and $m(t) = m(-t)$ holds for any $t \in R$. Hence, M is symmetric with respect to the equator $t = 0$ and if K is decreasing on $[0, \infty)$, then by Lemma 2.2, $m'(t) < 0$ for all $t > 0$ or there exists a unique positive solution $t = t_0$ of $m'(t) = 0$ such that $m' < 0$ on $(0, t_0)$ and $m' > 0$ on (t_0, ∞) . Furthermore, if the latter case happens, there exists $t_1 \in (0, t_0)$ such that $K \geq 0$ on $[0, t_1]$ and $K \leq 0$ on $[t_1, \infty)$.

For technical reasons, we treat both geodesics on M and its universal covering space $\pi : \tilde{M} \rightarrow M$, where $\tilde{M} := (R^1 \times R^1, d\tilde{t}^2 + m(\tilde{t})^2 d\tilde{\theta}^2)$.

Choose any point p on the equator $t = 0$. We may assume that $\theta(p) = 0$ without loss of generality. Let $\gamma : [0, \infty) \rightarrow M$ denote a geodesic emanating from $p = \gamma(0)$ with Clairaut constant $v \in (\inf m, m(0))$. Notice that γ is uniquely determined up to the reflection with respect to $t = 0$. The geodesic $\gamma(s) = (t(s), \theta(s))$ is tangent to the parallel $t = \xi(v)$ (if $(t \circ \gamma)'(0) > 0$) or $t = -\xi(v)$ (if $(t \circ \gamma)'(0) < 0$), where $\xi(v) > 0$ denotes the least positive solution of $m(\xi(v)) = v$, that is,

$$\xi(v) := \min\{u > 0 \mid m(u) = v\}.$$

After γ is tangent to the parallel $t = \xi(v)$ or $-\xi(v)$, γ intersects the equator $t = 0$ again. Thus, after $\tilde{\gamma}$ is tangent to the *parallel arc* $\tilde{t} = \xi(v)$ or $-\xi(v)$, $\tilde{\gamma}$ intersect $\tilde{t} = 0$ again. Here $\tilde{\gamma}$ denotes a geodesic on \tilde{M} satisfying $\gamma = \pi \circ \tilde{\gamma}$.

From (3.5), we obtain,

$$\tilde{\theta}(s_0) - \tilde{\theta}(0) = \int_{-\xi(v)}^0 \frac{v}{m\sqrt{m^2 - v^2}} dt = \int_0^{\xi(v)} \frac{v}{m\sqrt{m^2 - v^2}} dt,$$

and

$$\tilde{\theta}(s_1) - \tilde{\theta}(s_0) = \int_{-\xi(v)}^0 \frac{v}{m\sqrt{m^2 - v^2}} dt = \int_0^{\xi(v)} \frac{v}{m\sqrt{m^2 - v^2}} dt,$$

where $s_0 := \min\{s > 0 \mid m(\tilde{t}(s)) = v\}$, $s_1 := \min\{s > 0 \mid \tilde{t}(s) = 0\}$.

By summing up the argument above, we have,

LEMMA 3.1. *Let $\tilde{\gamma}(s) = (\tilde{t}(s), \tilde{\theta}(s))$ denote a geodesic emanating from the point $\tilde{p} := (\tilde{t}, \tilde{\theta})^{-1}(0, 0)$ with Clairaut constant $v \in (\inf m, m(0))$. Then $\tilde{\gamma}$ intersects $\tilde{t} = 0$ again at the point $(\tilde{t}, \tilde{\theta})^{-1}(0, \varphi(v))$. Here,*

$$\varphi(v) := 2 \int_{-\xi(v)}^0 \frac{v}{m\sqrt{m^2 - v^2}} dt = 2 \int_0^{\xi(v)} \frac{v}{m\sqrt{m^2 - v^2}} dt. \tag{3.7}$$

LEMMA 3.2. *The length $l(v)$ of the subarc $(\tilde{t}(s), \tilde{\theta}(s)), 0 \leq \tilde{\theta}(s) \leq \varphi(v)$, of $\tilde{\gamma}(s)$ is given by*

$$l(v) = 2 \int_{-\xi(v)}^0 \frac{m}{\sqrt{m^2 - v^2}} dt = 2 \int_{-\xi(v)}^0 \frac{\sqrt{m^2 - v^2}}{m} dt + v\varphi(v), \tag{3.8}$$

and

$$\frac{\partial l}{\partial v}(v) = v\varphi'(v). \tag{3.9}$$

PROOF. From (3.6), we obtain,

$$l(v) = 2 \int_{-\xi(v)}^0 \frac{m}{\sqrt{m^2 - v^2}} dt.$$

Since

$$\frac{m}{\sqrt{m^2 - v^2}} = \frac{\sqrt{m^2 - v^2}}{m} + \frac{v^2}{m\sqrt{m^2 - v^2}}$$

holds, we get

$$l(v) = 2 \int_{-\xi(v)}^0 \frac{\sqrt{m^2 - v^2}}{m} dt + 2 \int_{-\xi(v)}^0 \frac{v^2}{m\sqrt{m^2 - v^2}} dt.$$

Hence, by (3.7), we get (3.8). By differentiating $l(v)$ with respect to v , we get,

$$l'(v) = 2 \int_{-\xi(v)}^0 \frac{\partial \sqrt{m^2 - v^2}}{\partial v} \frac{1}{m} dt + \varphi(v) + v\varphi'(v) = v\varphi'(v).$$

□

4. The decline of the function $\varphi(v)$

Let $\pi : \tilde{M} = (R^1 \times R^1, d\tilde{t}^2 + m(\tilde{t})^2 d\tilde{\theta}^2) \rightarrow M$ denote the universal covering space of M . We choose an arbitrary point \tilde{p} of $\tilde{t}^{-1}(-\infty, 0]$, and we denote the cut locus of \tilde{p} by $C_{\tilde{p}}$. Before proving some lemmas on the cut locus, let us review the structure of the cut locus of \tilde{M} . We refer to [ShT] or [SST] on the structure of the cut locus of a 2-dimensional complete Riemannian manifold.

It is known that the cut locus has a local tree structure. Since \tilde{M} is simply connected, the cut locus has no circle. If two cut points x and y are in a common connected component of the cut locus, then x and y are connected by a unique rectifiable arc in the cut locus.

Since \tilde{M} is homeomorphic to R^2 , we may define a global sector at each cut point. For general surfaces, only local sectors are defined (see [ShT], or [SST]). A global *sector* at each cut point x of the point \tilde{p} is by definition a connected component of $\tilde{M} \setminus \Gamma_x$, where Γ_x denotes the set of all points lying on a minimal geodesic segment joining \tilde{p} to x . Let $c : [0, a] \rightarrow C_{\tilde{p}}$ denote a rectifiable arc in the cut locus. Then for each cut point $c(t)$, $t \in (0, a)$, c bisects the sector at $c(t)$ containing $c[0, t)$ (respectively $c(t, a]$). For each sector of the point \tilde{p} on \tilde{M} , there exists an end point of $C_{\tilde{p}}$, since $C_{\tilde{p}}$ has no circle. Here, a cut point q of \tilde{p} is called an *end point* if q admits exactly one sector.

In this section, we assume that the Gaussian curvature G of M is increasing on the half meridian $t^{-1}(-\infty, 0] \cap \theta^{-1}(0)$ and that M has a reflective symmetry with respect to $t = 0$. Hence the Gaussian curvature of \tilde{M} is increasing on the lower half meridian $\tilde{t}^{-1}(-\infty, 0] \cap \tilde{\theta}^{-1}(0)$ and \tilde{M} has a reflective symmetry with respect to $\tilde{t} = 0$.

LEMMA 4.1. *Suppose that there exists a cut point of the point \tilde{p} in $\tilde{t}^{-1}(-\infty, 0)$. Then there exist two minimal geodesic segments α and β joining \tilde{p} to a cut point y of \tilde{p} such that the global sector $D(\alpha, \beta)$ bounded by α and β has an end point of $C_{\tilde{p}}$ and $D(\alpha, \beta) \subset \tilde{t}^{-1}(-\infty, 0)$.*

PROOF. Since the subset of cut points admitting at least two minimal geodesics is dense in the cut locus, the existence of two minimal geodesics α and β is clear (see [Bh]). Since \tilde{M} has a reflective symmetry with respect to $\tilde{t} = 0$, it is trivial that $D(\alpha, \beta) \subset \tilde{t}^{-1}(-\infty, 0)$. Let y denote the end point of α distinct from \tilde{p} . Since the proof is complete in the case where the cut point y is not an end point of the cut locus, we assume that y is an end point. Then, we get an arc c in the cut locus emanating from y . Any interior point y_1 on c is not an end point of the cut locus. It is clear that there exist two minimal geodesic segments joining \tilde{p} and y_1 which bound a sector containing y as an end point of the cut locus. □

LEMMA 4.2. *For any unit speed minimal geodesic segment $\gamma : [0, L(\gamma)] \rightarrow \tilde{M}$ joining \tilde{p} to any end point x of $C_{\tilde{p}}$ in the domain $D(\alpha, \beta)$, x is conjugate to \tilde{p} along γ and γ is shorter than α and β .*

PROOF. Note that for any end point x of the cut locus, the set of all minimal geodesic

segments joining \tilde{p} to x is connected. Therefore, x is conjugate to \tilde{p} along any minimal geodesic segments joining \tilde{p} to the end point of the cut locus. Let $\gamma : [0, L(\gamma)] \rightarrow \tilde{M}$ denote any minimal geodesic segment \tilde{p} to an end point x of $C_{\tilde{p}} \cap D(\alpha, \beta)$. We will prove that γ is shorter than α and β . It follows from Theorem B in [ShT] or [IT] that there exists a unit speed arc $c : [0, l] \rightarrow C_{\tilde{p}}$ joining the end point x to y , where y denotes the end point of α distinct from \tilde{p} . Since the function $d(\tilde{p}, c(\tau))$ is a Lipschitz function, it follows from Lemma 7.29 in [WZ] that the function is differentiable for almost all τ and

$$d(\tilde{p}, c(l)) - d(\tilde{p}, y) = \int_0^l \frac{d}{d\tau} d(\tilde{p}, c(\tau)) d\tau \tag{4.1}$$

holds. From the Clairaut relation (3.2), the inner angle $\theta(\tau)$ at $c(\tau)$ of the sector containing $c[0, \tau]$ is less than π . Hence, by the first variation formula, we get

$$\frac{d}{d\tau} d(\tilde{p}, c(\tau)) = \cos \frac{\theta(\tau)}{2} > 0$$

for almost all τ . Notice that for each $\tau \in (0, l)$, the curve c bisects the sector at $c(\tau)$ containing $c[0, \tau]$. Therefore, from (4.1),

$$L(\alpha) = L(\beta) = d(\tilde{p}, c(l)) > d(\tilde{p}, y) = L(\gamma).$$

□

LEMMA 4.3. *Let q be a point on $\tilde{\theta}^{-1}(0)$ and u_0 any real number. Then $d(q, c(\theta))$ is strictly increasing on $[0, \infty)$. Here $c : [0, \infty) \rightarrow \tilde{M}$ denotes $c(\theta) = (u_0, \theta)$ in the coordinates $(\tilde{t}, \tilde{\theta})$ and $d(\cdot, \cdot)$ denotes the Riemannian distance function on \tilde{M} .*

PROOF. Choose any positive numbers $\theta_1 < \theta_2$. Let $\alpha_i, i = 1, 2$, denote minimal geodesic segments joining the point q to $c(\theta_i)$ respectively. Since $\theta_2 > \theta_1$, there exists an intersection $\alpha_2(t_2)$ of α_2 and the meridian $\tilde{\theta} = \theta_1$. The point $c(\theta_1)$ is the unique nearest point on $\tilde{t} = u_0$ from $\alpha_2(t_2)$. Hence,

$$d(\alpha_2(t_2), c(\theta_1)) < d(\alpha_2(t_2), c(\theta_2)).$$

Therefore, by the triangle inequality, we get

$$\begin{aligned} d(q, c(\theta_2)) &= d(q, \alpha_2(t_2)) + d(\alpha_2(t_2), c(\theta_2)) > d(q, \alpha_2(t_2)) \\ &\quad + d(\alpha_2(t_2), c(\theta_1)) \geq d(q, c(\theta_1)). \end{aligned}$$

This implies that $d(q, c(\theta))$ is strictly increasing on $[0, \infty)$. □

LEMMA 4.4. *Suppose that $\gamma : [0, L(\gamma)] \rightarrow \tilde{M}$ is a minimal geodesic segment joining \tilde{p} to an end point $x \in C_{\tilde{p}}$, which is a point in the sector $D(\alpha, \beta)$ bounded by two minimal geodesic segments α and β emanating from \tilde{p} . Then, for any $s \in [0, L(\gamma)]$, $\tilde{t}(\alpha(s)) \geq \tilde{t}(\gamma(s)) \geq \tilde{t}(\beta(s))$ holds. Here we assume that*

$$\angle(\alpha'(0), (\partial/\partial\tilde{t})_{\tilde{p}}) < \angle(\gamma'(0), (\partial/\partial\tilde{t})_{\tilde{p}}) < \angle(\beta'(0), (\partial/\partial\tilde{t})_{\tilde{p}}),$$

where $\mathcal{L}(\cdot, \cdot)$ denotes the angle made by two tangent vectors.

PROOF. From (3.4), it follows that for sufficiently small $s > 0$, $\tilde{t}(\alpha(s)) > \tilde{t}(\gamma(s)) > \tilde{t}(\beta(s))$ holds. Hence the set $A := \{s \in (0, L(\gamma)) \mid \tilde{t}(\alpha(s)) > \tilde{t}(\gamma(s)) > \tilde{t}(\beta(s))\}$ is a nonempty open subset of $(0, L(\gamma))$. Let $(0, s_0)$ denote the connected component of A . It is sufficient to prove that $s_0 = L(\gamma)$. Suppose that $s_0 < L(\gamma)$. Thus, $\tilde{t}(\alpha(s_0)) = \tilde{t}(\gamma(s_0))$ or $\tilde{t}(\gamma(s_0)) = \tilde{t}(\beta(s_0))$ holds, since A is open. By applying Lemma 4.3 for $u_0 := \tilde{t}(\alpha(s_0))$ and $\tilde{t}(\beta(s_0))$, we get $\alpha(s_0) = \gamma(s_0)$ or $\gamma(s_0) = \beta(s_0)$, which is a contradiction. \square

LEMMA 4.5. For any point $\tilde{p} \in \tilde{t}^{-1}(-\infty, 0]$, there does not exist a cut point of \tilde{p} in $\tilde{t}^{-1}(-\infty, 0)$. In particular, the cut locus of \tilde{p} is a subset of $\tilde{t}^{-1}(0)$ if $\tilde{t}(\tilde{p}) = 0$. This implies that the cut locus C_p of a point $p \in t^{-1}(0)$ is a subset of $\theta^{-1}(\pi) \cup t^{-1}(0)$. Here the coordinates (t, θ) are chosen so as to satisfy $\theta(p) = 0$.

PROOF. Suppose that there exist a cut point of \tilde{p} in $\tilde{t}^{-1}(-\infty, 0)$. By Lemma 4.1, there exist two minimal geodesic segments α and β joining a cut point y of \tilde{p} which bound a sector $D(\alpha, \beta)$ containing an end point x of $C_{\tilde{p}}$. Let $\gamma : [0, L(\gamma)] \rightarrow \tilde{M}$ be a unit speed geodesic segment joining \tilde{p} to the end point x . From Lemmas 4.1 and 4.4, it follows that for any $s \in [0, L(\gamma)]$,

$$0 \geq \tilde{t}(\alpha(s)) \geq \tilde{t}(\gamma(s)) \geq \tilde{t}(\beta(s))$$

holds. Since the Gaussian curvature G is increasing on each lower half meridian, we obtain

$$G(\alpha(s)) \geq G(\gamma(s)) \geq G(\beta(s)).$$

By applying the Rauch comparison theorem for the pair of geodesic segments $\alpha|_{[0, L(\gamma)]}$ and γ , \tilde{p} admits a conjugate point on $\alpha|_{[0, L(\gamma)]}$ along α .

This contradicts the fact that α is minimal. Since \tilde{M} is symmetric with respect to $\tilde{t} = 0$, the cut locus of \tilde{p} is a subset of $\tilde{t}^{-1}(0)$, if $\tilde{t}(\tilde{p}) = 0$. This implies that $C_p \subset \theta^{-1}(\pi) \cup t^{-1}(0)$ for the point $p = t^{-1}(0) \cap \theta^{-1}(0)$. \square

PROPOSITION 4.6. Let M be a complete Riemannian manifold $R^1 \times S^1$ with a warped product metric $ds^2 = dt^2 + m(t)^2 d\theta^2$ of the real line (R^1, dt^2) and the unit circle $(S^1, d\theta^2)$. Here the warping function $m : R \rightarrow (0, \infty)$ is a smooth even function. If the Gaussian curvature is positive on the equator and decreasing on the upper half meridian $t^{-1}(0, \infty) \cap \theta^{-1}(0)$, then the function $\varphi(v)$ is decreasing on $(\inf m, m(0))$.

PROOF. Let $\tilde{M} := (R^1 \times R^1, d\tilde{t}^2 + m(\tilde{t})^2 d\tilde{\theta}^2)$ denote the universal covering space of M . Choose any point \tilde{p} on $\tilde{t}^{-1}(0)$. For each $v \in (\inf m, m(0))$, let $\alpha_v : [0, \infty) \rightarrow \tilde{M}$ denote the geodesic emanating from the point $\tilde{p} = \alpha_v(0)$ with Clairaut constant v and with $(\tilde{t} \circ \alpha_v)'(0) < 0$. From the Clairaut relation, we get $\mathcal{L}((\partial/\partial\tilde{\theta})_{\tilde{p}}, \alpha'_v(0)) = \cos^{-1} v/m(0)$. Choose any $v_1 < v_2$ with $v_1, v_2 \in (\inf m, m(0))$. Since

$$\cos^{-1} \frac{v_2}{m(0)} < \cos^{-1} \frac{v_1}{m(0)},$$

it follows from Lemma 4.5 that α_{v_1} does not cross the domain bounded by the subarc of α_{v_2} and $\tilde{t}^{-1}(0) \cap \tilde{\theta}^{-1}[\tilde{\theta}(\tilde{p}), \tilde{\theta}(\tilde{p}) + \varphi(v_2)]$. This implies that $\varphi(v_1) \geq \varphi(v_2)$. Therefore, $\varphi(v)$ is decreasing on $(\inf m, m(0))$. \square

5. The cut locus of a point on \tilde{M}

Choose any point q on \tilde{M} with $-t_0 < \tilde{t}(q) < 0$, where $t_0 := \sup\{t > 0 \mid m'(t) < 0\}$. Without loss of generality, we may assume that $\tilde{\theta}(q) = 0$. We consider two geodesics α_v and β_v emanating from the point $q = \alpha_v(0) = \beta_v(0)$ with Clairaut constant $v > 0$. Here we assume that

$$\angle((\partial/\partial\tilde{t})_q, \alpha'_v(0)) > \angle((\partial/\partial\tilde{t})_q, \beta'_v(0)).$$

LEMMA 5.1. *The two geodesics α_v and β_v intersect again at the point $(\tilde{t}, \tilde{\theta})^{-1}(u, \varphi(v))$ if $v \in (\inf m, m(0))$, where $u := -\tilde{t}(q)$.*

PROOF. Suppose that $v \in (\inf m, m(0))$. Since α_v is tangent to the parallel arc $\tilde{t} = -\xi(v)$, it follows from (3.5) that

$$\tilde{\theta}(\alpha_v(s_1)) - \tilde{\theta}(\alpha_v(0)) = \int_{-\xi(v)}^{-u} \frac{v}{m\sqrt{m^2 - v^2}} dt,$$

where $s_1 := \min\{s > 0 \mid \tilde{t}(\alpha_v(s)) = -\xi(v)\}$, and

$$\tilde{\theta}(\alpha_v(s_2)) - \tilde{\theta}(\alpha_v(s_1)) = \int_{-\xi(v)}^u \frac{v}{m\sqrt{m^2 - v^2}} dt,$$

where $s_2 := \min\{s > 0 \mid \tilde{t}(\alpha_v(s)) = u\}$. Hence, we obtain,

$$\tilde{\theta}(\alpha_v(s_2)) - \tilde{\theta}(\alpha_v(0)) = \int_{-\xi(v)}^u \frac{v}{m\sqrt{m^2 - v^2}} dt + \int_{-\xi(v)}^{-u} \frac{v}{m\sqrt{m^2 - v^2}} dt. \tag{5.1}$$

Since m is an even function,

$$\int_{-\xi(v)}^u \frac{v}{m\sqrt{m^2 - v^2}} dt = \int_{-\xi(v)}^0 \frac{v}{m\sqrt{m^2 - v^2}} dt + \int_{-u}^0 \frac{v}{m\sqrt{m^2 - v^2}} dt$$

holds. Therefore, by (5.1),

$$\tilde{\theta}(\alpha_v(s_2)) - \tilde{\theta}(\alpha_v(0)) = 2 \int_{-\xi(v)}^0 \frac{v}{\sqrt{m^2 - v^2}} dt = \varphi(v).$$

This implies that α_v passes through the point $(\tilde{t}, \tilde{\theta})^{-1}(u, \varphi(v))$. On the other hand, after β_v is tangent to $\tilde{t} = \xi(v)$ at $\beta_v(s_1^+)$, where $s_1^+ := \min\{s > 0 \mid \tilde{t}(\beta_v(s)) = \xi(v)\}$, the geodesic intersects $\tilde{t} = u$ again at $\beta_v(s_2^+)$, where $s_2^+ := \min\{s > s_1^+ \mid \tilde{t}(\beta_v(s)) = u\}$. By the similar

computation as above, we get

$$\tilde{\theta}(\beta_v(s_2^+)) - \tilde{\theta}(\beta_v(0)) = \varphi(v).$$

This implies that α_v and β_v pass through the common point $(\tilde{t}, \tilde{\theta})^{-1}(u, \varphi(v))$. □

LEMMA 5.2. *The two geodesic segments $\alpha_v|_{[0,s_2]}$ and $\beta_v|_{[0,s_2^+]}$ have the same length and its length equals $l(v)$, which is defined in Lemma 3.2. In particular, $s_2 = s_2^+$. Here, s_2 and s_2^+ denote the numbers defined in the proof of Lemma 5.1.*

PROOF. From (3.6), we have

$$L(\alpha_v|_{[0,s_1]}) = \int_{-\xi(v)}^{-u} \frac{m}{\sqrt{m^2 - v^2}} dt, \tag{5.2}$$

and

$$L(\alpha_v|_{[s_1,s_2]}) = \int_{-\xi(v)}^u \frac{m}{\sqrt{m^2 - v^2}} dt = \int_{-\xi(v)}^0 \frac{m}{\sqrt{m^2 - v^2}} dt + \int_0^u \frac{m}{\sqrt{m^2 - v^2}} dt,$$

where s_1 denotes the number defined in the proof of Lemma 5.1. Since m is even

$$L(\alpha_v|_{[s_1,s_2]}) = \int_{-\xi(v)}^0 \frac{m}{\sqrt{m^2 - v^2}} dt + \int_{-u}^0 \frac{m}{\sqrt{m^2 - v^2}} dt. \tag{5.3}$$

Therefore, we get, by (3.8), (5.2) and (5.3),

$$L(\alpha_v|_{[0,s_2]}) = 2 \int_{-\xi(v)}^0 \frac{m}{\sqrt{m^2 - v^2}} dt = l(v).$$

Analogously we have,

$$L(\beta_v|_{[0,s_2^+]}) = l(v).$$

□

LEMMA 5.3. *Let q be a point on \tilde{M} with $|\tilde{t}(q)| \in (0, t_0)$. Then, for any $v \in (\inf m, m(u)]$, where $u = -\tilde{t}(q)$, $\alpha_v|_{[0,s_2(v)]}$ and $\beta_v|_{[0,s_2(v)]}$ are minimal geodesic segments joining q to the point $(\tilde{t}, \tilde{\theta})^{-1}(u, \tilde{\theta}(q) + \varphi(v))$, and in particular, $\{(\tilde{t}, \tilde{\theta}) \mid \tilde{t} = u, \tilde{\theta} \geq \varphi(m(u)) + \tilde{\theta}(q)\}$ is a subset of the cut locus of the point q . Here, $s_2(v) := \min\{s > 0 \mid \tilde{t}(\alpha_v(s)) = u\}$ for each $v \in (\inf m, m(0))$.*

PROOF. Without loss of generality, we may assume that $\tilde{\theta}(q) = 0$. We will prove that $\alpha_v|_{[0,s_2(v)]}$ is a minimal geodesic segment joining q to the point $\alpha_v(s_2(v)) = (\tilde{t}, \tilde{\theta})^{-1}(u, \varphi(v))$. Suppose that $\alpha_{v_0}|_{[0,s_2(v_0)]}$ is not minimal for some $v_0 \in (\inf m, m(u)]$. Here we assume that v_0 is the minimum solution $v = v_0$ of $\varphi(v) = \varphi(v_0)$.

Let $\alpha : [0, d(q, x)] \rightarrow M$ be a minimal geodesic segment joining q to $x := \alpha_{v_0}(s_2(v_0)) = (\tilde{t}, \tilde{\theta})^{-1}(u, \varphi(v_0))$. Hence, $\varphi(v_1) = \varphi(v_0) = \tilde{\theta}(x)$ and α equals $\alpha_{v_1}|_{[0, s_2(v_1)]}$ or $\beta_{v_1}|_{[0, s_2(v_1)]}$, where $v_1 \in (\inf m, m(0))$ denotes the Clairaut constant of α . By Proposition 4.6, $\varphi(v) = \varphi(v_0)$ for any $v \in [v_0, v_1]$. Hence, by Lemmas 3.2 and 5.2 we get,

$$s_2(v_1) = L(\alpha) = L(\alpha_{v_1}|_{[0, s_2(v_1)]}) = L(\alpha_{v_0}|_{[0, s_2(v_0)]}) = s_2(v_0).$$

This implies that $\alpha_{v_0}|_{[0, s_2(v_0)]}$ is minimal, which is a contradiction, since we assumed that $\alpha_{v_0}|_{[0, s_2(v_0)]}$ is not minimal. Therefore, by Lemma 5.2, for any $v \in (\inf m, m(u)]$, the geodesic segments $\alpha_v|_{[0, s_2(v)]}$ and $\beta_v|_{[0, s_2(v)]}$ are minimal geodesic segments joining q to the point $(\tilde{t}, \tilde{\theta})^{-1}(u, \varphi(v)) = \alpha_v(s_2(v))$. In particular, the point $\alpha_v(s_2(v)) = \beta_v(s_2(v))$ is a cut point of q . □

PROPOSITION 5.4. *The cut locus of the point q in Lemma 5.3 equals the set*

$$\{(\tilde{t}, \tilde{\theta}) \mid \tilde{t} = u, \tilde{\theta} \geq |\varphi(m(u))|\}.$$

Here the coordinates $(\tilde{t}, \tilde{\theta})$ are chosen so as to satisfy $\tilde{\theta}(q) = 0$.

PROOF. By Lemma 5.3, geodesic segments $\alpha_v|_{[0, s_2(v)]}$ and $\beta_v|_{[0, s_2(v)]}$ are minimal geodesic segments for any $v \in (\inf m, m(u)]$. Hence their limit geodesics $\alpha^- := \alpha_{\inf m}$ and $\beta^+ := \beta_{\inf m}$ are rays, that is, any their subarcs are minimal.

Since \tilde{M} has a reflective symmetry with respect to $\tilde{\theta} = 0$, it is trivial from Lemma 5.3 that the set $\{(\tilde{t}, \tilde{\theta}) \mid \tilde{t} = u, \tilde{\theta} \geq |\varphi(m(u))|\}$ is a subset of the cut locus of q . Suppose that there exists a cut point $y \notin \{(\tilde{t}, \tilde{\theta}) \mid \tilde{t} = u, \tilde{\theta} \geq |\varphi(m(u))|\}$. Without loss of generality, we may assume that $\tilde{\theta}(y) > 0 = \tilde{\theta}(q)$ and $\tilde{t}(y) = -u < 0$. From Lemma 4.5, $\tilde{t}(y) > 0$ and y is not a point in the unbounded domain cut off by two rays α^- and β^+ , and hence the point lies in the domain D^+ cut off by β^+ and the submeridian $\tilde{t} > -u, \tilde{\theta} = \tilde{\theta}(q) = 0$. Since the cut locus of C_q has a tree structure, there exists an end point x of the cut locus in the D^+ . Hence, x is conjugate to q for any minimal geodesic segment γ joining q to x . Since such a minimal geodesic γ runs in the domain D^+ , the Clairaut constant of the segment is positive and less than $\inf m$. From the Clairaut relation (3.2), any geodesic cannot be tangent to any parallel arc $\tilde{t} = c$, if the Clairaut constant is positive and less than $\inf m$. From Corollary 7.2.1 in [SST], γ has no conjugate point of q , which is a contradiction. □

LEMMA 5.5. *Let q be a point on \tilde{M} with $|\tilde{t}(q)| \geq t_0$. Then the cut locus of q is empty.*

PROOF. Suppose that the cut locus of a point q with $|\tilde{t}(q)| \geq t_0$ is nonempty. Since \tilde{M} has a reflective symmetry with respect to $\tilde{t} = 0$, we may assume that $\tilde{t}(q) \leq -t_0$. Hence by Lemma 4.5, there exists an end point x of the cut locus C_q in $\tilde{t}^{-1}(0, \infty)$. Let $\gamma : [0, d(q, x)] \rightarrow \tilde{M}$ denote a minimal geodesic segment joining q to x . Then x is conjugate to q along γ , since x is an end point of C_q . Since $\tilde{\theta}(x) > 0 = \tilde{\theta}(q)$, the Clairaut constant v of γ is positive, by (3.1). Moreover, from the Clairaut relation (3.2), the Clairaut constant v

is less than $\inf m = m(t_0)$, since γ intersects $\tilde{t} = -t_0$. Therefore, γ cannot be tangent to any parallel arc $\tilde{t} = c$. From Corollary 7.2.1 in [SST], γ has no conjugate point of q , which is a contradiction. \square

Now our Main theorem is clear from Proposition 5.4 and Lemma 5.5.

ACKNOWLEDGMENTS. I would like to express my gratitude to Professor Minoru TANAKA who kindly gave me guidance for the lectures and numerous comments.

References

- [Bh] RICHARD L. BISHOP, Decomposition of cut loci, Proc. Amer. Math. Soc. **65** (1) (1977), 133–136.
- [E] D. ELERATH, An improved Toponogov comparison theorem for non-negatively curved manifolds, J. Differential Geom. **15** (1980), 187–216.
- [IK] J. ITOH and K. KIYOHARA, The cut loci and the conjugate loci on ellipsoids, Manuscripta Math. **114** (2004), 247–264.
- [IT] J. ITOH and M. TANAKA, The Lipschitz continuity of the distance function to the cut locus, Trans. of AMS, **353** (1) (2000), 21–40.
- [ShT] K. SHIOHAMA and M. TANAKA, *Cut loci and distance spheres on Alexandrov surfaces*, Séminaires & Congrès, Collection SMF No.1, Actes de la table ronde de Géométrie différentielle en l'honneur Marcel Berger (1996), 531–560.
- [SST] K. SHIOHAMA, T. SHIOYA and M. TANAKA, *The Geometry of Total Curvature on Complete Open Surfaces*, Cambridge tracts in mathematics **159**, Cambridge University Press, Cambridge, 2003.
- [ST] R. SINCLAIR and M. TANAKA, The cut locus of a two-sphere of revolution and Toponogov's comparison theorem, Tohoku Math. J. **59** (2007), 379–399.
- [Ta] K. TAMURA, On the cut locus of a complete Riemannian manifold homeomorphic to a cylinder, 2003, Master Thesis, Tokai University.
- [Ts] Y. TSUJI, On a cut locus of a complete Riemannian manifold homeomorphic to a cylinder, Proceedings of the school of Science, Tokai University, **32** (1997), 23–34.
- [WZ] R. L. WHEEDEN and A. ZYGMUND, *Measure and Integral*, Marcel Dekker, New York, Basel, 1977.

Present Address:

DEPARTMENT OF MATHEMATICS,
KING MONGKUT'S INSTITUTE OF TECHNOLOGY LADKRABANG,
LADKRABANG, BANGKOK, 10–520 THAILAND.
e-mail: kcpakkin@kmitl.ac.th