

## Subordination of Semidynamical Systems

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**Abstract.** We develop the fundamental properties of multiplicative functional  $\mathcal{M}$  defined on a semidynamical system  $(X, \mathcal{B}, \Phi, w)$ . We give a characterization of semigroups which are subordinate to the deterministic semigroup  $\mathbf{H}$  and we show that they are generated by a multiplicative functional. We study the case when a multiplicative semigroup defined on a measurable space  $(X, \mathcal{B})$  is deterministic.

### 1. Introduction

The semidynamical system arise from a dynamical interpretation of functional differential equations with time lag and evolution type partial differential equations (i.e the heat diffusion equation). In this case a solution  $\Phi(t, x)$  with initial condition  $x$  is defined on  $[0, \rho(x)[$  only and jumps into a “coffin” state “ $w$ ” afterwards.

Also, a multiplicative functional arise when we “kill” a semidynamical system if it enters in a domain  $D$ .

So, starting from a semidynamical system  $(X, \mathcal{B}, \Phi, w)$  we give the definition of a terminal time as a first time some physical event occurs and for a subset  $U$  of  $X$ , we give the notion of a first hitting time and first entry time and we show particularly that any measurable hitting time is a terminal time.

Next, we give some characterization of deterministic semigroups. We show essentially that if  $Q_t = M_t H_t$  where  $\mathcal{M}$  is a right continuous multiplicative functional and  $\mathbf{H}$  is deterministic, then  $(Q_t)_{t \geq 0}$  is deterministic if and only if  $\mathcal{M} = 1_{[0, T[}$  where  $T$  is a terminal time and therefore  $(Q_t)_{t \geq 0}$  is subordinate to  $\mathbf{H}$  (Theorem 2).

Conversely, we prove that any semigroup which is subordinate to  $\mathbf{H}$  is generated by a multiplicative functional  $\mathcal{M}$  (Theorem 3).

Notice that any deterministic semigroup is multiplicative. However, if we consider a Lusin space (cf. [7]) we will show that under some restrictions any multiplicative semigroup is deterministic (Theorem 6). Note that this Theorem gives a generalization to the results given in [11], [12] and [3]. Indeed, in [11] and [12], the author considered a topological space

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$(X, \mathcal{T})$  which is locally compact and having a countable base. In [3], the authors showed that a multiplicative potential cone is associated to a deterministic semigroup. In our case, we show that every positive constant is excessive and that  $\mathbf{H}$  is the unique semigroup associated and also any multiplicative semigroup is a right continuous deterministic semigroup.

## 2. Preliminary

In this section, we will introduce some definitions which will be useful in the remainder of this paper (For more details see [3], [5], [10] and [15]).

DEFINITION 1. Let  $(X, \mathcal{B})$  be a separable measurable space with a distinguished point  $\omega$ . A measurable map  $\Phi : \mathbf{R}_+ \times X \rightarrow X$  is called a semidynamical system with cofinal point  $\omega$  if the following conditions are fulfilled:

(S<sub>1</sub>) For any  $x$  in  $X$ , there exists an element  $\rho(x)$  in  $[0, \infty]$  such that  $\Phi(t, x) \neq \omega$  for all  $t \in [0, \rho(x))$  and  $\Phi(t, x) = \omega$  for all  $t \geq \rho(x)$ ,

(S<sub>2</sub>) For any  $s, t \in \mathbf{R}_+$  and any  $x \in X$  we have

$$\Phi(s, \Phi(t, x)) = \Phi(s + t, x),$$

(S<sub>3</sub>)  $\Phi(0, x) = x$  for all  $x \in X$ ,

(S<sub>4</sub>) If  $\Phi(t, x) = \Phi(t, y)$  for all  $t > 0$ , then  $x = y$ .

Next, we will denote by  $X_0 = X \setminus \{\omega\}$ . For any  $x \in X_0$  we denote by  $\Gamma_x$  the trajectory of  $x$ , i.e:

$$\Gamma_x = \{\Phi(t, x); t \in [0, \rho(x))\}$$

and we define the function  $\Phi_x$  on  $[0, \rho(x))$  by  $\Phi_x(t) = \Phi(t, x)$ . So for any  $x, y \in X_0$  we put

$$x \underset{\Phi}{\leq} y \Leftrightarrow y \in \Gamma_x.$$

A maximal trajectory is a totally ordered subset  $\Gamma$  of  $X \setminus \{\omega\}$  with respect to the above order, such that there is no  $x_0 \in X_0 \setminus \Gamma$  which is minorant of  $\Gamma$  and such for any  $x \in \Gamma$ , we have  $\Gamma_x \subset \Gamma$ .

In what follows, we shall suppose that  $(X, \mathcal{B}, \Phi, \omega)$  is a transient semidynamical system (cf. [3]). It is proved that the map  $\Phi_x$  is a measurable isomorphism between  $[0, \rho(x))$  and  $\Gamma_x$  endowed with trace measurable structures.

In the next, let us denote by  $\mathcal{B}_0 = \{U \in \mathcal{B}; U \subset X_0\}$ . Let  $\Lambda$  be the Lebesgue measure associated with the semidynamical system  $(X, \mathcal{B}, \Phi, \omega)$  given by  $\Lambda(A) = \lambda(\Phi_x^{-1}(A))$  for any  $x \in X_0$ ,  $A \in \mathcal{B}_0$  and  $A \subset \Gamma_x$ , where  $\lambda$  is the Lebesgue measure on  $\mathbf{R}$  (cf. [4]). We recall (cf. [1]) that in the same way  $\Lambda$  can be defined on the  $\sigma$ -algebra  $\mathcal{B}_0(\Lambda)$  which is the set of all subsets  $A$  of  $X_0$  such that  $A \cap M \in \mathcal{B}_0$  for any countable union  $M$  of trajectories of  $X_0$ .

One can show that the resolvent family  $\mathbf{V} = (V_\alpha)_{\alpha \geq 0}$  may be considered on the measurable space  $(X_0, \mathcal{B}_0(\Lambda))$  and we denote by  $\mathcal{F}(X_0, \Lambda)$  the set of all positive  $\mathcal{B}_0(\Lambda)$  measurable

functions on  $X_0$ . For every  $f \in \mathcal{F}(X_0, \Lambda)$ , we have

$$V_\alpha f(x) = \int_0^\infty e^{-\alpha t} f(\Phi(t, x)) dt.$$

In the sequel, we define the inherent topology  $\mathcal{T}_\Phi^0$  as being the set of all subsets  $D$  of  $X_0$  satisfying the following condition:

$$\begin{aligned} &(\forall x \in X_0, \forall t_0 \in [0, \rho(x)[ \text{ such that } \Phi(t_0, x) \in D) \Rightarrow \\ &(\exists \varepsilon > 0, \text{ such that } \forall t \in ]t_0 - \varepsilon, t_0 + \varepsilon[ \cap [0, \rho(x)[, \Phi(t, x) \in D) \end{aligned}$$

(see [3], [10]).

Let us denote by  $\mathbf{H} = (H_t)_{t \in \mathbf{R}_+}$  the deterministic semigroup introduced in [11] and [13] and defined by

$$\varepsilon_x H_t = \begin{cases} \varepsilon_{\Phi(t,x)} & \text{if } t < \rho(x), \\ 0 & \text{if } t \geq \rho(x), \end{cases}$$

for every  $(t, x) \in \mathbf{R}_+ \times X_0$ .

Then, we get the following results (see [2]).

**THEOREM 1.** *The map  $t \rightarrow \Phi(t, x)$  is right continuous with respect to the inherent topology  $\mathcal{T}_\Phi^0$ .*

**PROOF.** Let  $f : X_0 \rightarrow \mathbf{R}^+$  be a bounded  $\mathcal{B}_0(\Lambda)$ -measurable function. For every  $x \in X_0$ , we have

$$\begin{aligned} V_0 f(\Phi(t, x)) &= \int_0^\infty f(\Phi(s, \Phi(t, x))) ds \\ &= \int_t^\infty f(\Phi(s, x)) ds. \end{aligned}$$

Therefore  $t \rightarrow (V_0 f)\Phi(t, x)$  is right continuous, i.e  $t \rightarrow \Phi(t, x)$  is right continuous with respect to  $\mathcal{T}_\Phi^0$ . □

**COROLLARY 1.** *The deterministic semigroup is right continuous.*

**NOTATION.** Throughout this paper we will denote by  $\varepsilon_x$  the Dirac measure concentrated in  $x$ . For every subset  $U$  of  $X$ , we denote  $U^C = X \setminus U$  and

$$1_U = \begin{cases} 1 & \text{if } x \in U, \\ 0 & \text{if not.} \end{cases}$$

### 3. Multiplicative functionals

**DEFINITION 2** (see Definition (6.1) of Ch.I from [6]). A mapping  $T : X \rightarrow [0, +\infty]$  is called a stopping time if it is  $\mathcal{B}_0(\Lambda)$  measurable.

DEFINITION 3 (see (10.1) of Ch.I from [6]). Let  $A$  be a subset of  $X$ . For each  $x \in X$ , we define the first entry time of  $A$  by

$$D_A(x) = \inf\{t \geq 0 : \Phi(t, x) \in A\}$$

and the first hitting time of  $A$  by

$$T_A(x) = \inf\{t > 0 : \Phi(t, x) \in A\}$$

where in both cases the infimum of the empty set is understood to be  $+\infty$ .

DEFINITION 4 (see (2.18) of Ch.II from [6]). A stopping time  $T$  is a terminal time if for each  $t \geq 0$ ,

$$T = t + T(\Phi(t, \cdot)) \quad \text{on } \{T > t\}.$$

PROPOSITION 1 (see (2.18) of Ch.II from [6]). Any measurable hitting time is a terminal time.

PROOF. Let  $(\alpha_n)_n$  be a sequence which decreases to 0 and such that  $\Phi(T_A(\Phi(t, x)) + \alpha_n, \Phi(t, x)) \in A$ . Since

$$\Phi(T_A(\Phi(t, x)) + \alpha_n, \Phi(t, x)) = \Phi(T_A(\Phi(t, x)) + \alpha_n + t, x)$$

we get

$$T_A(x) \leq t + \alpha_n + T_A(\Phi(t, x)).$$

By letting  $n \rightarrow \infty$  we get

$$(3.1) \quad T_A(x) \leq T_A(\Phi(t, x)) + t.$$

On the other hand, let  $t$  be such that  $T_A(x) > t$ , then there exists  $(\beta_n)_n$  which decreases to 0 such that  $\Phi(T_A(x) + \beta_n, x) \in A$ . Since

$$\Phi(T_A(x) - t + t + \beta_n, x) = \Phi(T_A(x) - t + \beta_n, \Phi(t, x))$$

we get that

$$T_A(\Phi(t, x)) \leq T_A(x) - t + \beta_n$$

for every  $n \in \mathbb{N}$ , which yields that

$$(3.2) \quad T_A(\Phi(t, x)) \leq T_A(x) - t.$$

The proof then is achieved by using (3.1) and (3.2).  $\square$

DEFINITION 5 (see Definition (1.1) of Ch.III from [6]). A family  $\mathcal{M} = \{M_t; 0 \leq t < \infty\}$  of measurable functions on  $(X, \mathcal{B})$  is called a multiplicative functional provided:

- (1) for every  $t \geq 0$ ,  $M_t$  is  $\mathcal{B}_0(A)$  measurable,
- (2) For each  $x \in X$ , for every  $t, s \geq 0$ ,

$$M_{t+s}(x) = M_t(x) \cdot M_s(\Phi(t, x)),$$

(3)  $0 \leq M_t(x) \leq 1$  for all  $t$  and  $x$ .

We say that  $\mathcal{M}$  is right continuous (or continuous) provided  $t \rightarrow M_t(x)$  is right continuous (or continuous) for every  $x \in X$ .

REMARK 1. We remark that  $M_0(x) = M_0^2(x)$  i.e that  $M_0(x) = 0$  or  $M_0(x) = 1$ . Thus, we say that an element  $x$  of  $X$  is permanent if  $M_0(x) = 1$ . Moreover the conditions (2) and (3) gives us that

$$M_t(x) \leq M_0(x) \quad \forall t \geq 0.$$

Hence, we will assume that every  $x \in X$  is permanent.

The following examples are issued from (1.2), (1.3), (1.4) and (1.5) of Chapter III in [6].

EXAMPLE 1. For each  $\alpha \geq 0$ , define  $M_t = e^{-\alpha t}$ . Then  $\{M_t; t \geq 0\}$  is a continuous multiplicative functional.

EXAMPLE 2. Let  $T$  be a terminal time and define

$$M_t(x) = 1_{[0, T(x)]}(t).$$

Then  $\mathcal{M} = \{M_t; 0 \leq t < \infty\}$  is a right continuous multiplicative functional. In fact, if  $s < T(\Phi(t, x))$  and  $t < T(x)$ , then

$$M_t(x)M_s(\Phi(t, x)) = 1.$$

Since

$$s < T(\Phi(t, x)) = T(x) - t \text{ on } \{T > t\}$$

we get  $t + s < T(x)$  and therefore

$$M_{t+s}(x) = 1_{[0, T(x)]}(t + s) = 1 = M_t(x)M_s(\Phi(t, x)).$$

Now, if  $s \geq T(\Phi(t, x))$  or  $t \geq T(x)$ , then  $M_t(x)M_s(\Phi(t, x)) = 0$ .

In the first case, we have

$$s \geq T(\Phi(t, x)) = T(x) - t \quad \text{if } T(x) > t$$

which yields that  $t + s \geq T(x)$  and therefore

$$M_{t+s}(x) = 1_{[0, T(x)]}(t + s) = 0.$$

In the second case,  $t \geq T(x) \Rightarrow t + s \geq T(x)$  which implies that  $M_{t+s}(x) = 0$ .

EXAMPLE 3. For every  $f \in \mathcal{F}(X_0, \Lambda)$ , define

$$M_t(x) = \exp\left(-\int_0^t f(\Phi(s, x))ds\right).$$

It is obvious that  $\mathcal{M}$  is a continuous multiplicative functional when  $f$  is bounded.

EXAMPLE 4. For every  $f \in \mathcal{F}(X_0, \Lambda)$ , define

$$T = \inf \left\{ t : \int_0^t f(\Phi(s, x)) ds = \infty \right\}$$

Then  $T$  is a terminal time and

$$M_t(x) = 1_{[0, T(x)]}(t) \exp \left( - \int_0^t f(\Phi(s, x)) ds \right)$$

defines a right continuous multiplicative functional.

#### 4. Subordinate semigroups

In this section, we will deal with the properties of multiplicative semigroups.

##### 4.1 Deterministic semigroup and subordination

DEFINITION 6. Let  $(X, \mathcal{B})$  be a measurable space and let  $\mathbf{P} = (P_t)_{t \geq 0}$  be a family of operators such that

- (1) For all  $A \in \mathcal{B}$ , the mapping  $(t, x) \rightarrow P_t 1_A(x)$  is measurable,
- (2) For all  $x \in X, t \geq 0$ , the mapping  $A \rightarrow P_t 1_A(x)$  is a measure on  $\mathcal{B}$ ,
- (3)  $P_{t+s} = P_t P_s$ ,
- (4)  $P_0 = Id$ .

Then  $(P_t)_{t \geq 0}$  is called a semigroup.

DEFINITION 7. Let  $\mathbf{P} = (P_t)_{t \geq 0}$  be a semigroup. We say that  $\mathbf{P}$  is multiplicative if for every measurable functions  $f$  and  $g$  on  $(X, \mathcal{B})$ , we have

$$P_t(f.g) = P_t f . P_t g .$$

DEFINITION 8. Let  $(X, \mathcal{B})$  be a measurable space. We say that a semigroup  $\mathbf{P}$  is deterministic if there exists a semidynamical system  $\Phi$  such that  $\mathbf{P}$  is the deterministic semigroup associated.

REMARK 2. Let  $(Q_t)_{t \geq 0}$  be a deterministic semigroup defined on a measurable space  $(X, \mathcal{B})$ . Then,  $(Q_t)_{t \geq 0}$  is multiplicative.

REMARK 3. If  $\mathcal{M}$  is a multiplicative functional defined on a semidynamical system  $(X, \mathcal{B}, \Phi, w)$ , we define for each  $t \geq 0$  an operator  $Q_t$  on  $\mathcal{F}(X_0, \Lambda)$  by

$$Q_t f(x) = M_t(x) . H_t f(x)$$

where  $(H_t)_{t \geq 0}$  is the deterministic semigroup. It is clear that  $(Q_t)_{t \geq 0}$  is a linear map from  $\mathcal{F}(X_0, \Lambda)$  to  $\mathcal{F}(X_0, \Lambda)$  such that  $Q_t \leq H_t$ . Moreover, we have

$$\begin{aligned} Q_{t+s} f(x) &= M_{t+s}(x) \cdot f(\Phi(t+s, x)) \\ &= M_t(x) \cdot M_s(\Phi(t, x)) \cdot f(\Phi(s, (\Phi(t, x)))) \\ &= M_t(x) \cdot (Q_s(f))(\Phi(t, x)) \\ &= Q_s Q_t f(x) \end{aligned}$$

and so  $\{Q_t; t \geq 0\}$  is a semigroup called the semigroup generated by  $\mathcal{M}$ .

**THEOREM 2.** *Let  $(X, \mathcal{B}, \Phi, w)$  be a semidynamical system and  $\mathbf{H}$  be the deterministic semigroup associated. Let  $(Q_t)_{t \geq 0}$  be a semigroup such that  $Q_t = M_t H_t$  where  $(M_t)_{t \geq 0}$  is a right continuous multiplicative functional. Then  $(Q_t)_{t \geq 0}$  is deterministic if and only if there exists a terminal time  $T$  such that  $M_t(x) = 1_{[0, T(x)]}(t)$ .*

**PROOF.** Suppose that  $(Q_t)_{t \geq 0}$  is deterministic, then by Remark 2  $(Q_t)_{t \geq 0}$  is multiplicative and therefore for  $f = g = 1$  we get

$$Q_t(f \cdot g)(x) = Q_t(f)(x) \cdot Q_t(g)(x)$$

for all  $x \in X$ , i.e  $M_t(x) = M_t(x)^2$ . Thus, for each  $x \in X$  there exists  $A(x)$  such that  $M_t(x) = 1_{A(x)}(t)$ .

On the other hand, since  $(M_t)_{t \geq 0}$  is multiplicative, then for each  $t, s \geq 0$  we have

$$\begin{aligned} 1_{A(x)}(t+s) &= M_{t+s}(x) \\ &= M_t(x) \cdot M_s(\Phi(t, x)) \\ &= 1_{A(x)}(t) \cdot 1_{A(\Phi(t, x))}(s). \end{aligned}$$

Hence

$$(4.1) \quad t + s \in A(x) \Leftrightarrow t \in A(x) \quad \text{and} \quad s \in A(\Phi(t, x)).$$

Note that for  $t = 0$  we have

$$Q_0 1(x) = M_0(x) P_0 1(x) = M_0(x) = 1 = 1_{A(x)}(0)$$

by Remark 1 which yields that  $0 \in A(x)$ .

Next, we shall prove that  $A(x)$  is an interval. Indeed, let  $t \in A(x)$  such that  $t > 0$  and let  $0 < t' < t$ . Then, there exists  $s > 0$  such that  $t = t' + s$ . By (4.1) we get that  $t' \in A(x)$ .

Set  $T(x) = \sup\{t \geq 0 : t \in A(x)\}$ . If  $T(x) < \infty$ , we shall prove that  $T(x) \notin A(x)$ . So assume that  $T(x) \in A(x)$ , then for all  $\varepsilon > 0$ , we have

$$\begin{aligned} 0 &= M_{T(x)+\varepsilon}(x) \\ &= 1_{A(x)}(T(x)) \cdot M_\varepsilon(\Phi(T(x), x)) \\ &= M_\varepsilon(\Phi(T(x), x)). \end{aligned}$$

By letting  $\varepsilon \rightarrow 0$ , we get

$$0 = M_0(\Phi(T(x), x)) = 1_{A(\Phi(T(x), x))}(0) = 1$$

which is impossible. Hence

$$A(x) = [0, T(x)[.$$

Hence, we define a mapping on  $X$ , by setting

$$T(x) = \sup\{t \geq 0 : t \in A(x)\}.$$

Next, we claim that  $T : X \rightarrow \overline{\mathbf{R}}_+$  is a stopping time. In fact, for each  $\alpha \geq 0$ , we have

$$\begin{aligned} \{T > \alpha\} &= \{x : \alpha \in [0, T(x)[\} \\ &= \{x : M_\alpha(x) \neq 0\} \end{aligned}$$

which is measurable.

Next, we claim that  $T$  is a terminal time. Indeed, let  $x \in X$  and let  $t \geq 0$  such that  $T(x) > t$  (i.e.  $t \in A(x)$ ).

For every  $s \in A(\Phi(t, x))$  we have by (4.1) that  $t + s \in A(x)$  and therefore  $t + s < T(x)$ .

Hence, by taking the supremum over all  $s \in A(\Phi(t, x))$ , we get

$$(4.2) \quad t + T(\Phi(t, x)) \leq T(x).$$

Conversely, for every  $s : t < s < T(x)$ , there exists  $s' > 0$  such that  $s = t + s' < T(x)$ . Since  $t + s' \in A(x)$ , again by (4.1) we get that  $s' \in A(\Phi(t, x))$ . Consequently, we get

$$s \leq t + T(\Phi(t, x))$$

which yields

$$(4.3) \quad T(x) \leq t + T(\Phi(t, x)).$$

Combining (4.2) and (4.3), we obtain

$$T(x) = t + T(\Phi(t, x)) \quad \text{on } \{T > t\}. \quad \square$$

DEFINITION 9. Let  $\mathbf{H}$  be the deterministic semigroup of  $(X, \mathcal{B}, \Phi, w)$ . A semigroup  $(Q_t)_{t \geq 0}$  is subordinate to  $\mathbf{H}$  if

$$Q_t f \leq H_t f$$

for each  $t \geq 0$  and  $f \in \mathcal{F}(X_0, \Lambda)$ .

Next, we will prove the following result called the Theorem of Meyer (see [6] and [14]).

THEOREM 3. *If  $(Q_t)_{t \geq 0}$  is subordinate to  $\mathbf{H}$ , then there exists a multiplicative function  $\mathcal{M}$  such that  $Q_t = M_t \cdot H_t$ .*



PROOF. Since  $\varepsilon_x Q_t \leq \varepsilon_x H_t$ , then by Radon Nikodym Theorem there exists a function  $M_t(x)$  such that  $0 \leq M_t(x) \leq 1$  and

$$\varepsilon_x Q_t = M_t(x)\varepsilon_x H_t = M_t(x)\varepsilon_{\Phi(t,x)}.$$

By setting  $f = 1$ , we get that

$$M_t(x) = Q_t 1(x)$$

and therefore for every  $t \geq 0$   $M_t$  is measurable. On the other hand, for every  $s, t \geq 0$  we have

$$\begin{aligned} M_{t+s}(x)f(\Phi(t+s, x)) &= Q_{t+s}f(x) \\ &= Q_t(Q_s f)(x) \\ &= M_t(x)(Q_s f)(\Phi(t, x)) \\ &= M_t(x)M_s(\Phi(t, x))f(\Phi(t+s, x)). \end{aligned}$$

Hence

$$M_{t+s}(x) = M_t(x).M_s(\Phi(t, x)). \quad \square$$

COROLLARY 2. *If  $(Q_t)_{t \geq 0}$  is subordinate to  $(H_t)_{t \geq 0}$  and  $(Q_t)_{t \geq 0}$  is deterministic, then there exists a terminal time  $T$  such that  $Q_t = 1_{[0, T[} H_t$ .*

DEFINITION 10. Let  $(X, \mathcal{B}, \Phi, w)$  be a semidynamical system. A semidynamical system  $\Phi'$  is said to be subordinated to  $\Phi$  if there exists a terminal time  $T$  such that

$$\Phi'(t, x) = \begin{cases} \Phi(t, x) & \text{if } t < T(x), \\ w & \text{if } t \geq T(x). \end{cases}$$

PROPOSITION 2. *Let  $(Q_t)_{t \geq 0}$  be a deterministic semigroup associated to a semidynamical system  $\Phi'$  and such that  $(Q_t)_{t \geq 0}$  is subordinate to  $(H_t)_{t \geq 0}$ . Then,  $\Phi'$  is subordinate to  $\Phi$ .*

PROOF. By Corollary 2, there exists a terminal time  $T$  such that  $Q_t = 1_{[0, T[} H_t$ . Hence

$$\varepsilon_x Q_t = \begin{cases} \varepsilon_x H_t = \varepsilon_{\Phi(t,x)} & \text{if } t < T(x), \\ 0 & \text{if } t \geq T(x). \end{cases}$$

It is obvious that  $\Phi'$  is subordinate to  $\Phi$ . □

EXAMPLE 5. Let  $T$  be a terminal time and set  $A = \{T = 0\}$ . Next, we claim that  $T \leq T_A$ . Indeed, let  $s \geq 0$  such that  $\Phi(s, x) \in A$ . Since

$$T(x) = s + T(\Phi(s, x)) = s \quad \text{on } \{T > s\}$$

we conclude that  $T(x) \leq s$  which yields that  $T(x) \leq T_A(x)$ . By setting

$$\Phi'(t, x) = \begin{cases} \Phi(t, x) & \text{if } t < T(x), \\ w & \text{if } t \geq T(x). \end{cases}$$

We get that  $\Phi'$  is subordinate to  $\Phi$ .

**4.2 Characterization of multiplicative semigroups.** In this section, we will show that under mild restrictions any multiplicative semigroup is deterministic with respect to some semidynamical system. So let  $(X, \mathcal{B})$  be a measurable space and let  $\mathbf{P} = (P_t)_{t \geq 0}$  be a multiplicative semigroup defined on  $(X, \mathcal{B})$ .

THEOREM 4. *There exists a stopping  $T$  time such that for each  $x \in X$ ,*

- (1)  $T(x) > 0$ ,
- (2)  $P_t 1(x) = 1_{[0, T(x)[}(t), \forall t \geq 0$ .

PROOF. Since  $\mathbf{P}$  is multiplicative, then  $P_t 1(x)$  is 1 or 0. Set

$$A(x) = \{t : P_t 1(x) = 1\}.$$

Then

$$P_t 1(x) = 1_{A(x)}(t).$$

Next, we shall prove that  $A(x)$  is an interval. Indeed, by (4) in Definition 6 we have that  $0 \in A(x)$  and we will prove that for each  $t \in A(x)$  we have  $[0, t] \subset A(x)$ . Let  $t \in A(x)$  and  $s < t$ , then  $t = s + s'$  for some  $s' > 0$ . Using the fact that  $t \in A(x)$ , we get

$$1 = P_t 1(x) = P_s(P_{s'} 1)(x) \leq P_s 1(x)$$

which gives us that  $P_s 1(x) = 1$  and therefore  $s \in A(x)$ .

Set  $T(x) = \sup A(x)$ . Suppose that  $T(x) < \infty$  and that  $T(x) \in A(x)$ . We choose a sequence  $(\varepsilon_n)$  which decreases to 0. Using the fact that  $T(x) = \sup A(x)$ , we get that

$$P_{T(x)}(P_{\varepsilon_n}) 1(x) = P_{T(x)+\varepsilon_n} 1(x) = 0.$$

On the other hand, for every  $y \in X$  we have  $P_{\varepsilon_n} 1(y) = 1_{[0, T(y)]}(\varepsilon_n)$  which converges to 1 as  $n \rightarrow \infty$ . Since  $P_{\varepsilon_n} 1$  is increasing, then  $P_{T(x)}(P_{\varepsilon_n}) 1(x)$  converges to  $P_{T(x)} 1(x) = 1$  which is impossible.

Finally, we shall prove that  $T$  is measurable. So, let  $\alpha \in \mathbf{R}$ , since the map  $x \rightarrow P_\alpha 1(x)$  is measurable, we get that the set  $\{x : P_\alpha 1(x) = 1\}$  is measurable. On the other hand,

$$\{x : P_\alpha 1(x) = 1\} = \{x : \alpha \in [0, T(x)[\} = \{T(x) > \alpha\}.$$

Thus,  $T$  is a stopping time. □

REMARK 4. For every measurable function  $f$  on  $X$ , we have that

$$P_t f(x) = 1_{[0, T(x)[}(t) P_t f(x)$$

and consequently, we have  $P_t f(x) = 0$  if  $t \geq T(x)$ .

Next, we introduce the following notation which will be needed later. Let us denote by  $\mathcal{E}_{\mathbf{P}}$  the set of excessive functions of  $\mathbf{P}$  (cf. [8]) and by

$$V1(x) = \int_0^\infty P_t 1(x) dt = T(x)$$

the potential of  $\mathbf{P}$ .

PROPOSITION 3. *The function 1 is excessive and therefore every nonnegative constant is excessive.*

PROOF. Since, by Theorem 4,  $T(x) > 0$  and  $P_t 1(x) = 1_{[0, T(x)[}(t)$ , then  $\sup_{t \geq 0} P_t 1(x) = 1$ . □

Next, we denote by

$$x \underset{\mathcal{E}_{\mathbf{P}}}{\leq} y$$

if  $s(y) \leq s(x)$  for all  $s \in \mathcal{E}_{\mathbf{P}}$  and by

$$\Gamma_x^{\mathcal{E}_{\mathbf{P}}} = \{y : x \underset{\mathcal{E}_{\mathbf{P}}}{\leq} y\}.$$

Note that if  $\mathcal{E}_{\mathbf{P}}$  separates the elements of  $X$ , then " $\underset{\mathcal{E}_{\mathbf{P}}}{\leq}$ " is an order on  $X$ .

THEOREM 5. *Suppose that  $V1 < \infty$  and that  $\mathcal{E}_{\mathbf{P}}$  is minstable and that it separates the elements of  $X$ . Then,  $\mathcal{E}_{\mathbf{P}}$  is equal to the set of all positive decreasing functions with respect to " $\underset{\mathcal{E}_{\mathbf{P}}}{\leq}$ " and lower semicontinuous with respect to the fine topology which is the coarsest topology on  $X$  for which all the excessive functions are continuous.*

PROOF. Let  $f, g$  two excessive functions, then

$$\sup_{t \geq 0} P_t(f.g) = \sup_{t \geq 0} P_t(f).P_t(g) = \sup_{t \geq 0} P_t(f).\sup_{t \geq 0} P_t(g) = f.g$$

and therefore  $f.g$  is excessive. On the other hand, by Proposition 3 all positive constants are excessive. By using Theorem 16 in [3], we get that  $\mathcal{E}_{\mathbf{W}}$  is equal to the set of all positive decreasing functions with respect to " $\underset{\mathcal{E}_{\mathbf{P}}}{\leq}$ " and lower semicontinuous with respect to the fine topology where  $\mathbf{W}$  is the resolvent associated to  $\mathbf{P}$ . On the other hand, by [8], we get that  $\mathcal{E}_{\mathbf{W}} = \mathcal{E}_{\mathbf{P}}$ . □

THEOREM 6. *Suppose that  $(X, \mathcal{B})$  is a Lusin space (cf. [7]),  $V1 < \infty$  and that  $\mathcal{E}_{\mathbf{P}}$  is minstable and that it separates the elements of  $X$ . Moreover, assume that for each  $x \in X$ , there exists  $\alpha_x < \beta_x$  such that  $T$  is an isomorphism from  $\Gamma_x^{\mathcal{E}_{\mathbf{P}}}$  to  $] \alpha_x, \beta_x ]$ . Then, the semigroup  $\mathbf{P}$  is a right continuous deterministic semigroup and  $T$  is a terminal time with respect to  $\mathbf{P}$ .*

PROOF. Let  $x \in X$  and  $t \in [0, T(x)[$ . Since  $\mathbf{P}$  is multiplicative, then for each  $A \in \mathcal{B}$  we have  $P_t(1_A) \in \{0, 1\}$ . By Hunt's approximation Theorem (see [8]) we get that

$$x \underset{\mathcal{E}_{\mathbf{P}}}{\leq} y \Leftrightarrow Vf(y) \leq Vf(x)$$

for every positive bounded measurable function on  $X$ . On the other hand, since  $V$  is proper, then there exists  $(B_n)_n \subset \mathcal{B}^{\mathbf{N}}$  such that

$$\mathcal{C} = \{B_n : n \in \mathbf{N}\}$$

is a ring of sets satisfying the following properties

- (1) For each  $n \in \mathbf{N}$ ,  $V1_{B_n}$  is bounded,
- (2)  $X = \bigcup_{n \in \mathbf{N}} B_n$ ,
- (3) The  $\sigma$ -algebra generated by  $\mathcal{C}$  is equal to  $\mathcal{B}$ .

Hence

$$\Gamma_x^{\mathcal{E}_P} = \bigcap_{n \in \mathbf{N}} \{V(1_{B_n}) \leq V(1_{B_n})(x)\}$$

is measurable. Next, we claim that  $1_{(\Gamma_x^{\mathcal{E}_P})^C}$  is excessive. Indeed, Let  $y \leq_{\frac{\mathcal{E}_P}{x}} z$ , then  $z \in \Gamma_x^{\mathcal{E}_P}$  when  $y \in \Gamma_x^{\mathcal{E}_P}$  and hence

$$1_{(\Gamma_x^{\mathcal{E}_P})^C}(z) = 1_{(\Gamma_x^{\mathcal{E}_P})^C}(y).$$

But if  $y \notin \Gamma_x^{\mathcal{E}_P}$ , we get

$$1_{(\Gamma_x^{\mathcal{E}_P})^C}(y) = 1 \geq 1_{(\Gamma_x^{\mathcal{E}_P})^C}(z)$$

which yields that  $1_{(\Gamma_x^{\mathcal{E}_P})^C}$  is decreasing with respect to  $\leq_{\frac{\mathcal{E}_P}{x}}$ .

Now, let  $\alpha$  be a real, then

$$\{1_{(\Gamma_x^{\mathcal{E}_P})^C} > \alpha\} = \begin{cases} X & \text{if } \alpha < 0, \\ (\Gamma_x^{\mathcal{E}_P})^C & \text{if } \alpha \in [0, 1[, \\ \emptyset & \text{if } \alpha \geq 1, \end{cases}$$

which gives us that  $1_{(\Gamma_x^{\mathcal{E}_P})^C}$  is lower semicontinuous with respect to the fine topology and therefore is excessive by Theorem 5.

Next, we claim that  $\varepsilon_x P_t$  is concentrated in  $(\Gamma_x^{\mathcal{E}_P})$ . Indeed, since  $1_{(\Gamma_x^{\mathcal{E}_P})^C}$  is excessive, we get that

$$\varepsilon_x P_t(1_{(\Gamma_x^{\mathcal{E}_P})^C}) \leq 1_{(\Gamma_x^{\mathcal{E}_P})^C}(x) = 0.$$

In the following, let

$$T : \Gamma_x^{\mathcal{E}_P} \rightarrow ]\alpha_x, \beta_x]$$

be an isomorphism. Let us denote by  $\mathcal{T}_x$  the topology defined on  $\Gamma_x^{\mathcal{E}_P}$  and generated by the collection of subsets  $V \subset \Gamma_x^{\mathcal{E}_P}$  such that  $\forall y \in V$  there exists  $\varepsilon > 0$  such that  $]T(y) -$

$\varepsilon, T(y) + \varepsilon[ \subset ]\alpha_x, \beta_x]$  if  $y \neq x$  and  $]T(y) - \varepsilon, T(y)] \subset ]\alpha_x, \beta_x]$  if  $y = x$ . It follows that  $T$  is an homeomorphism from  $(\Gamma_x^{\mathcal{E}P}, \mathcal{T}_x)$  to  $] \alpha_x, \beta_x ]$  and by Lusin Theorem (cf. [7]),  $T$  is a measurable isomorphism. Let us denote by

$$\text{Supp}(\varepsilon_x P_t) = \{y \in \Gamma_x^{\mathcal{E}P} : \forall V \in \mathcal{T}_x \varepsilon_x P_t(V) > 0\}.$$

In the sequel, let us assume that there exist  $y, z \in \text{Supp}(\varepsilon_x P_t)$  such that  $y \neq z$ . We can choose  $y \in U \in \mathcal{T}_x$  and  $z \in W \in \mathcal{T}_x$  such that  $U \cap W = \emptyset$ . Since

$$0 = \varepsilon_x P_t(1_U 1_W) = \varepsilon_x P_t(1_U) \varepsilon_x P_t(1_W)$$

we get that  $\varepsilon_x P_t(1_U) = 0$  or  $\varepsilon_x P_t(1_W) = 0$  which is impossible. Thus there exists a unique element  $y$  of  $\Gamma_x^{\mathcal{E}P}$  which will be denoted by  $\Phi_0(t, x)$  such that  $\varepsilon_x P_t = \varepsilon_{\Phi_0(t, x)}$ .

In what follows, Let  $X_w = X \cup \{w\}$  where  $w$  is an element not in  $X$  and  $\mathcal{B}_w$  be the  $\sigma$ -algebra on  $X_w$  generated by  $\mathcal{B}$  and  $\{w\}$ . Note that  $\{w\} \in \mathcal{B}_w$ . We define  $\Phi$  on  $X_w$  by

$$\Phi(t, x) = \begin{cases} \Phi_0(t, x) & \text{if } x \in X, \quad t \in [0, T(x)[, \\ w & \text{if } x \in X, \quad t \geq T(x), \\ w & \text{if } x = w, \quad t \geq 0. \end{cases}$$

Next, we claim that  $(X_w, \mathcal{B}_w, \Phi, w)$  is a semidynamical system. In fact, let  $s, t \geq 0$  such that  $t + s < T(x)$ . Then

$$\varepsilon_{\Phi(t+s, x)} = \varepsilon_x P_{t+s} = \varepsilon_x P_t P_s = \varepsilon_{\Phi(t, x)} P_s = \varepsilon_{\Phi(s, \Phi(t, x))}$$

which yields that  $\Phi(t + s, x) = \Phi(s, \Phi(t, x))$ .

For  $t = 0$ , we have  $\varepsilon_x = \varepsilon_{\Phi(0, x)}$  which gives us that  $\Phi(0, x) = x$ .

Now, consider  $x, y \in X$  such that  $\Phi(t, x) = \Phi(t, y)$  for every  $t > 0$ . Thus, we get that

$$1_{[0, T(x)[}(t) = 1_{[0, T(y)[}(t)$$

for every  $t > 0$ . Hence  $T(x) = T(y)$  and therefore  $x = y$ .

Next, we shall prove that  $\Phi$  is measurable and  $T$  is a terminal time. In fact, let  $t < T(x)$ . Since

$$\varepsilon_{\Phi(t, x)} P_s 1 = \varepsilon_{\Phi(t+s, x)} 1 = \varepsilon_x P_{(t+s)} 1,$$

we get that

$$1_{[0, T(\Phi(t, x))](s)} = 1_{[0, T(x)](t+s)}$$

which gives us that

$$s < T(\Phi(t, x)) \Leftrightarrow s + t < T(x)$$

and hence

$$(4.4) \quad t + T(\Phi(t, x)) = T(x).$$

Now, using the fact that  $T$  is a measurable isomorphism, we get that

$$\Phi(t, x) = T^{-1}(T(x) - t)$$

on the set  $\{t < T(x)\}$ .  $(X_w, \mathcal{B}_w)$  being a Lusin space, we get then that  $\Phi$  is measurable and hence is a semidynamical system. Moreover, by (4.4), we obtain that  $T$  is a terminal time.

Finally, since  $V1 < \infty$ , then  $(X_w, \mathcal{B}_w, \Phi, w)$  is a transient semidynamical system (cf. [3] and [9]) and by Corollary 1 we get that  $\mathbf{P}$  is right continuous.  $\square$

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