

Put these terms a , b and c . Then

$$\begin{aligned}
c &= -\varepsilon y_n \\
&\times \begin{vmatrix} a_1 & a_2 & a_3 & \cdots \\ -1 - y_1 a_1 & x - y_1 a_2 & -y_1 a_3 & \cdots \\ -y_2 a_1 & -1 - y_2 a_2 & x - y_2 a_3 & \cdots \\ \vdots & \vdots & \ddots & \ddots \end{vmatrix} \\
&= -\varepsilon y_n \begin{vmatrix} a_1 & a_2 & a_3 & \cdots & a_n \\ -1 & x & 0 & \cdots & 0 \\ 0 & -1 & x & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & -1 & x \end{vmatrix} \\
&= -\varepsilon y_n (a_1 x^{n-1} + a_2 x^{n-2} + \cdots + a_n). \\
a &= x |A_{n-1}| \\
&= x \begin{vmatrix} x - y_1 a_2 & -y_1 a_3 & -y_1 a_4 & \cdots \\ -1 - y_2 a_2 & x - y_2 a_3 & -y_2 a_4 & \cdots \\ -y_3 a_2 & -1 - y_3 a_3 & x - y_3 a_4 & \cdots \\ \vdots & \vdots & \ddots & \ddots \end{vmatrix} \\
&= x^2 |A_{n-2}| - y_1 x \\
&\times \begin{vmatrix} a_2 & a_3 & a_4 & \cdots \\ -1 - y_2 a_2 & x - y_2 a_3 & -y_2 a_4 & \cdots \\ -y_3 a_2 & -1 - y_3 a_3 & x - y_3 a_4 & \cdots \\ \vdots & \vdots & \ddots & \ddots \end{vmatrix} \\
&= x^2 |A_{n-2}| - y_1 x \begin{vmatrix} a_2 & a_3 & \cdots & a_n \\ -1 & x & & 0 \\ & \ddots & \ddots & \\ 0 & & -1 & x \end{vmatrix} \\
&= x^2 |A_{n-2}| - y_1 x (a_2 x^{n-2} + \cdots + a_n).
\end{aligned}$$

Using induction we have

$$\begin{aligned}
a &= x^n - y_1 (a_2 x^{n-1} + \cdots + a_n x) \\
&\quad - y_2 (a_3 x^{n-1} + \cdots + a_n x^2) \\
&\quad - \cdots - y_{n-1} a_n x^{n-1}.
\end{aligned}$$

$$\begin{aligned}
b &= (-1)^{n+1} (-\varepsilon) \\
&\times \begin{vmatrix} -1 - y_1 a_1 & x - y_1 a_2 & -y_1 a_3 & \cdots \\ -y_2 a_1 & -1 - y_2 a_2 & x - y_2 a_3 & \cdots \\ -y_3 a_1 & -y_3 a_2 & -1 - y_3 a_3 & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{vmatrix} \\
&= -|B_{n-1}|.
\end{aligned}$$

$$\begin{aligned}
|B_{n-1}| &= \begin{vmatrix} -1 & & & & \\ 0 & & & & \\ \vdots & * & & & \\ 0 & & & & \end{vmatrix} + \begin{vmatrix} -y_1 a_1 & & & & \\ -y_2 a_1 & & & & \\ \vdots & & & & * \\ -y_{n-1} a_1 & & & & \end{vmatrix} \\
&= -|B_{n-2}| + |C_{n-1}|. \\
|C_{n-1}| &= -a_1 \begin{vmatrix} y_1 & x & 0 & \cdots & 0 \\ y_2 & -1 & x & \ddots & \vdots \\ y_3 & 0 & -1 & \ddots & 0 \\ \vdots & \vdots & \ddots & \ddots & x \\ y_{n-1} & 0 & \cdots & 0 & -1 \end{vmatrix} \\
&= (-1)^{n-1} a_1 (y_1 + y_2 x + \cdots + y_{n-1} x^{n-2}).
\end{aligned}$$

Using induction we have

$$\begin{aligned}
b &= -\varepsilon a_1 (y_1 + y_2 x + \cdots + y_{n-1} x^{n-2}) \\
&\quad - \varepsilon a_2 (y_2 + y_3 x + \cdots + y_{n-1} x^{n-3}) \\
&\quad - \cdots - \varepsilon a_{n-1} y_{n-1} - \varepsilon.
\end{aligned}$$

Put all together we have

$$\begin{aligned}
&|xE - SM^{-1}D_\mu M| \\
&= x^n - \sum_{i=1}^n (y_1 a_{i+1} + y_2 a_{i+2} + \cdots + y_{n-i} a_n \\
&\quad + \varepsilon y_{n-i+1} a_1 + \cdots + \varepsilon y_n a_i) x^{n-i} - \varepsilon.
\end{aligned}$$

If we put $M = E$, then we have

$$|xE - SD_\mu| = x^n - (\mu + 1)\varepsilon.$$

Comparing the coefficients of two polynomials, we have

$$(1) \quad \begin{pmatrix} x_1 & x_2 & x_3 & \cdots & x_n \\ \varepsilon x_2 & \varepsilon x_3 & \cdots & \varepsilon x_n & x_1 \\ \varepsilon x_3 & \cdots & \varepsilon x_n & x_1 & x_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \varepsilon x_n & x_1 & x_2 & \cdots & x_{n-1} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_n \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

Next we use

$$TSD_\mu \sim f(TSD_\mu) = TSM^{-1}D_\mu M.$$

As $T = E + E_{12}$, we have

$$\begin{aligned}
&|xE - TSM^{-1}D_\mu M| = |xE - SM^{-1}D_\mu M| + |F_n|. \\
&|F_n| = \begin{vmatrix} -1 - y_1 a_1 & -y_1 a_2 & \cdots \\ -1 - y_1 a_1 & x - y_1 a_2 & \cdots \\ \vdots & \ddots & \ddots \end{vmatrix}
\end{aligned}$$

$$\begin{aligned}
 &= \begin{vmatrix} -1 - y_1 a_1 & -y_1 a_2 & -y_1 a_3 & \cdots \\ 0 & x & 0 & \cdots \\ -y_2 a_1 & -1 - y_2 a_2 & x - y_2 a_3 & \cdots \\ \vdots & \vdots & \ddots & \ddots \end{vmatrix} \\
 &= x \begin{vmatrix} -1 - y_1 a_1 & -y_1 a_3 & -y_1 a_4 & \cdots \\ -y_2 a_1 & x - y_2 a_3 & -y_2 a_4 & \cdots \\ -y_3 a_1 & -1 - y_3 a_3 & x - y_3 a_4 & \cdots \\ \vdots & \vdots & \ddots & \ddots \end{vmatrix} \\
 &= x \begin{vmatrix} -y_1 a_1 & -y_1 a_3 & \cdots & -y_1 a_n \\ * & & & \end{vmatrix} \\
 &\quad + x \begin{vmatrix} -1 & 0 & \cdots & 0 \\ * & & & \end{vmatrix} \\
 &= -y_1 x \begin{vmatrix} a_1 & a_3 & a_4 & \cdots \\ 0 & x & 0 & \cdots \\ 0 & -1 & x & \ddots \\ \vdots & \ddots & \ddots & \ddots \end{vmatrix} - x |A_{n-2}| \\
 &= -y_1 a_1 x^{n-1} - x^{n-1} + y_2 (a_3 x^{n-2} + \cdots + a_n x) \\
 &\quad + \cdots + y_{n-1} a_n x^{n-2}.
 \end{aligned}$$

If we put $M = E$, then we have

$$|xE - TSD_\mu| = x^n - (\mu + 1)\varepsilon - (\mu + 1)x^{n-1}.$$

Therefore we have

$$(2) \begin{pmatrix} x_1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 0 & 0 & x_2 \\ 0 & \cdots & 0 & 0 & x_2 & x_3 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & x_2 & \cdots & \cdots & x_{n-1} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_{n-1} \\ a_n \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

As $x_1 a_1 = 1$, we have $x_1 \neq 0$ and $a_1 \neq 0$. If $a_n \neq 0$, then from (2), we have $x_2 = x_3 = \cdots = x_{n-1} = 0$. So from (1) we have $x_n = x_1 = 0$. Therefore $a_n = 0$. Similarly we have

$$a_n = a_{n-1} = \cdots = a_2 = 0, \quad x_2 = x_3 = \cdots = x_n = 0.$$

This means $f(D_\mu) = E + \mu E_{11} = D_\mu$, which completes the proof.

References

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- [2] Ono, T.: "Hasse principle" for $GL_2(D)$. Proc. Japan Acad., **75A**, 141-142 (1999).
- [3] Wada, H.: "Hasse principle" for $SL_n(D)$. Proc. Japan Acad., **75A**, 67-69 (1999).