

16. Transmutation Theory for Certain Radial Operators

By Robert CARROLL

University of Illinois

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1. Introduction. For $Q_0 u = (\Delta_q u)' / \Delta_q$ based on a radial Laplace-Beltrami operator we studied general transmutation theory for operators $\hat{Q} u = Q_0 u + \hat{q}(x)u$ in [4] using various solutions of $\hat{Q} u = -k^2 u$ as important ingredients. In the present work we consider operators $\tilde{Q} u = x^2 Q_0 u + x^2 \{k^2 - \tilde{q}(x)\}u$ (with corresponding eigenfunction equations $\tilde{Q} u = \lambda^2 u$) and will concentrate on the case $\Delta_q = x^2$ which arises in various scattering problems (cf. [1], [2], [6]–[9], [11], [12]) so a certain amount of guideline information is available (cf. also [5]-B transmutes P into Q , $B: P \rightarrow Q$, if $QBf = BPf$ for suitable f). We show here that with suitable modifications most of the constructions and techniques of the \hat{Q} theory have a version in the \tilde{Q} theory and we describe some of the basic transmutations and connection formulas.

2. Basic constructions. We take $\Delta_q = x^2$ and set $\varphi = xu$ so $\tilde{Q} u = \lambda^2 u$ is

$$(2.1) \quad x^2 \varphi'' + x^2 \{k^2 - \tilde{q}(x)\} \varphi = \lambda^2 \varphi$$

(\tilde{q} real) and one writes $\lambda^2 = \sigma(\sigma + 1) = \nu^2 - 1/4$ (so $\sigma \sim l =$ angular momentum and $\nu \sim l + 1/2$). We denote by $\varphi(\nu, k, x)$ the “regular solution” of (2.1) ($\varphi \sim x^{\nu+1/2}$ as $x \rightarrow 0$) and by $f(\nu, \pm k, x)$ the “Jost solutions” (e.g. $f(\nu, -k, x) \sim e^{ikx}$ as $x \rightarrow \infty$) with the “Jost function” $f(\nu, -k) = W(f(\nu, -k, x), \varphi(\nu, k, x))$ ($W(f, g) = fg' - f'g$). Assume e.g. $\int_0^\infty x |\tilde{q}| dx < \infty$ and

$\int_0^\infty x^2 |\tilde{q}| dx < \infty$ as in [2] but we do not emphasize hypotheses on \tilde{q} (cf. [1], [6], [9], [11], [12]); we want mainly $\varphi \sim \varphi_0$ and $f \sim f_0$ as e.g. $|\nu| \rightarrow \infty$, $\operatorname{Re} \nu > 0$, where (corresponding to $\tilde{q} = 0$)

$$(2.2) \quad \begin{aligned} \varphi_0(\nu, k, x) &= 2^\nu \Gamma(\nu + 1) k^{-\nu} x^{1/2} J_\nu(kx); \\ f_0 &= ((1/2)\pi kx)^{1/2} e^{(1/2)i\pi(\nu+1/2)} H_\nu^1(kx); \end{aligned}$$

($f_0 = f_0(\nu, -k, x)$) and

$$f_0(\nu, -k) = 2^\nu (2/\pi)^{1/2} \Gamma(\nu + 1) k^{-\nu+1/2} \exp \{(1/2)i\pi(\nu - 1/2)\}.$$

We think of k as fixed here and one knows then that $f(\nu, -k, x)$ is entire in ν while $\varphi(\nu, k, x)$ and $f(\nu, -k)$ are analytic for $\operatorname{Re} \nu > 0$ (the range of analyticity can be enlarged with suitable hypotheses on \tilde{q}). We follow formally now the procedure in [2] with some refinements and elaboration. Thus set $g(\nu, -k, r) = f(\nu, -k, r)/r$ and let Z denote the zeros ν_j (if any) of $f(\nu, -k)$ in $\operatorname{Re} \nu > 0$ with

$$M^2(\nu_j, k) = \int_0^\infty g^2(\nu_j, -k, r) dr.$$

Such ν_j are simple zeros and one sets $d\rho(\nu) = \sum \delta(\nu - \nu_j) / M^2(\nu_j, k)$ for $\nu \in Z$ with $d\rho(\nu) = 2i\nu^2 d\nu / \pi f(\nu, -k) f(-\nu, -k)$ for $\nu \in [0, i\infty)$. From [2] one has the formal completeness relation

$$\delta(r-s) = \langle g(\nu, -k, r), g(\nu, -k, s) \rangle_\rho \sim \int g(\nu, -k, r) g(\nu, -k, s) d\rho(\nu)$$

and we show then (g_1, ρ^1 , etc. refer to an operator \tilde{Q}_1 based on potential \tilde{q}_1).

Theorem 2.1. Define $\beta(r, s) = \langle g(\nu, -k, r), g_1(\nu, -k, s) \rangle_\rho$ and $\tilde{\beta}(r, s) = \langle g(\nu, -k, r), g_1(\nu, -k, s) \rangle_{\rho^1}$ with $\tilde{\mathcal{B}}f(s) = \langle \beta(r, s), f(r) \rangle$ and $\tilde{B}f(r) = \langle \tilde{\beta}(r, s), f(s) \rangle$ for suitable f . The r and s brackets refer to distribution pairings on $[0, \infty)$ and one has triangularity $\beta(r, s) = 0$ for $s > r$ with $\tilde{\beta}(r, s) = 0$ for $r > s$. Set $\mathcal{G}f(\nu) = \hat{f}(\nu) = \int_0^\infty f(s) g(\nu, -k, s) ds$ so that formally $G\hat{f}(r) = \mathcal{G}^{-1}\hat{f}(r) = f(r) = \langle \hat{f}(\nu), g(\nu, -k, r) \rangle_\rho$. Then $\tilde{B} : \tilde{Q}_1 \rightarrow \tilde{Q}$ and $\tilde{\mathcal{B}}(\sim \tilde{B}^{-1}) : \tilde{Q} \rightarrow \tilde{Q}_1$ are transmutations with $\tilde{\mathcal{B}}\{g(\nu, -k, \cdot)\}(r) = g_1(\nu, -k, r)$ and $\tilde{B}\{g_1(\nu, -k, \cdot)\}(r) = g(\nu, -k, r)$. Set $B = \tilde{\mathcal{B}}^*$ (so $Bf(r) = \langle \beta(r, s), f(s) \rangle$) and correspondingly $\mathcal{B} = \tilde{B}^*$; then $\mathcal{G}Bf = \mathcal{G}_1 f$ and $\mathcal{G}f = \mathcal{G}_1 \mathcal{B}f$ (with $\mathcal{B} = B^{-1}$).

We indicate next a connection to an exterior transmutation developed in [7], [8]. Thus for Q_0 based on $\Delta_q = x^{n-1}$ one considers $\tilde{Q} = x^2 Q_0 + x^2 \{k^2 - \tilde{q}(x)\}$ and $\tilde{P} = x^2 Q_0 + x^2 k^2$. For suitable \tilde{q} a kernel $K(r, s)$ is constructed in [7], [8] (by successive approximations) such that the formula

$$(2.3) \quad u(r, \cdot) = \{B_\epsilon h\}(r, \cdot) = h(r, \cdot) + \int_r^\infty s^{n-3} K(r, s) h(s, \cdot) ds$$

links suitable solutions h of $(\Delta_n + k^2)h = 0$ to corresponding solutions u of $\{\Delta_n + (k^2 - \tilde{q}(r))\}u = 0$. The kernel $K(r, s)$ satisfies $\tilde{Q}_r K = \tilde{P}_s K$ for $s > r$ with $2r^{n-2} K(r, r) = \int_r^\infty s \tilde{q}(s) ds$. If we write $\check{K}(r, s) = K(r, s) Y(s-r)$ (Y the Heaviside function) then one can show

Theorem 2.2. For suitable \tilde{q} the map $B_\epsilon f(r) = f(r) + \langle \check{K}(r, s), f(s) \rangle$ is a transmutation $\tilde{P} \rightarrow \tilde{Q}$ and for $n=3$, $\delta(s-r) + \check{K}(r, s) \sim \tilde{\beta}(r, s) = \langle g(\nu, -k, r), g_1(\nu, -k, s) \rangle_{\rho^1}$ (where $\tilde{Q}_1 \sim \tilde{P}$ and ρ^1 is the "free" measure indicated below).

Example 2.3. We denote by "free" the case where $\tilde{q} = 0$ so that (2.2) holds. In this event $f(\nu, -k)$ has no zeros for $\text{Re } \nu > 0$ and $d\rho(\nu) = -(\nu/\pi k) \sin \pi \nu d\nu$ is the "free" measure. The inversion theory for \mathcal{G} is the Kontorovič-Lebedev theory which can be treated in various forms (cf. [10]). The version which we obtain below (cf. (2.5)) specializes for $\tilde{q} = 0$ to

$$(2.4) \quad \tilde{G}(\nu) = \int_0^\infty G(s) H_\nu^+(ks) ds; \quad rG(r) = \frac{1}{2} \int_{-i\infty}^{i\infty} \nu \tilde{G}(\nu) J_\nu(kr) d\nu.$$

In order to arrive at a general form of (2.4) we suppose $f(\nu, -k)$ has no zeros for $\operatorname{Re} \nu > 0$ so that $d\rho(\nu) = \rho(\nu)d\nu$. From properties of $f(\pm\nu, -k, x)$ and $\varphi(\pm\nu, k, x)$ one has

$$rf(r) = \langle \hat{f}(\nu), f(\nu, -k, r) \rangle_\rho = \frac{1}{2} \int_{-i\infty}^{i\infty} \hat{f}(\nu) f(\nu, -k, r) \rho(\nu) d\nu$$

and from this

$$(2.5) \quad rf(r) = -(i/\pi) \int_{-i\infty}^{i\infty} \nu \hat{f}(\nu) \Phi(\nu, k, r) d\nu$$

where $\Phi(\nu, k, r) = \varphi(\nu, k, r)/f(\nu, -k)$ (cf. [4]) and using the formal relation (*) $-(i\mu/\pi) \int_0^\infty \Phi(\mu, k, s)g(\nu, -k, s)ds/s = \delta(\mu - \nu)$ arising from (2.5) we show

Theorem 2.4. *Given absolutely continuous $d\rho(\nu) = \rho(\nu)d\nu$ the inversion (2.5) holds. If \tilde{Q} and \tilde{Q}_1 both have continuous spectrum then B is characterized by $B\{g_1(\nu, -k, \cdot)\}(r) = (\hat{\rho}/\rho_1)(\nu)g(\nu, -k, r)$ and in addition*

$$(2.6) \quad B\{\Phi_1(\nu, k, s)/s\}(r) = \langle \beta(r, s), \Phi_1(\nu, k, s)/s \rangle = \Phi(\nu, k, r)/r.$$

One can construct a formal proof of (2.6) following [4] (using analytic continuation) but a simpler formal verification can be obtained by looking at $\langle \beta(r, s), g(\nu, -k, r) \rangle = g_1(\nu, -k, s)$ as an extension of \mathfrak{G} to β , so that $\hat{\beta}(\nu, s) = g_1(\nu, -k, s)$, using the inversion (2.5), and then applying (*) for Φ_1 and g_1 .

3. General techniques. First, assuming $g(\nu, -k, 1) = 0$ on the spectrum,

$$(3.1) \quad U(r, s) = \langle \hat{f}(\nu)/g(\nu, -k, 1), g(\nu, -k, r)g(\nu, -k, s) \rangle_\rho$$

where $\hat{f}(\nu) = \mathfrak{G}f(\nu)$ makes sense formally and using the idea of generalized translation developed by Hutson-Pym (cf. [3], [4]) one has for suitable \tilde{q}

Theorem 3.1. *$U(r, s) = T_s^r f(s)$ represents a generalized translation for \tilde{Q} determined by $\tilde{Q}_r U = \tilde{Q}_s U$, $U(1, s) = f(s)$, and $D_r U(1, s) = Cf(s) = \langle \Gamma(s, \eta), f(\eta) \rangle$ where*

$$\Gamma(s, \eta) = \langle g(\nu, -k, s)g(\nu, -k, \eta), Dg(\nu, -k, 1)/g(\nu, -k, 1) \rangle_\rho$$

($\tilde{Q}C = C\tilde{Q}$ and $Cf(1) = f'(1)$).

The "Cauchy problem" indicated in Theorem 3.1 is to be considered in two regions $r, s \geq 1$ and $0 \leq r, s \leq 1$. It can be transformed into two halfplane Cauchy problems $\eta \geq 0$ and $\eta \leq 0$ respectively by setting $\eta = \log r$ and $\xi = \log s$, from which standard uniqueness results can be transported; the "data" is given on $-\infty < \xi < \infty$.

Theorem 3.2. *Let \tilde{Q} and \tilde{Q}_1 be based on $\Delta_0 = x^{n-1}$ as above and let A and C be linear operators commuting with \tilde{Q}_1 . Let φ be the unique solution of $\tilde{Q}_r \varphi = \tilde{Q}_s^1 \varphi$ ($\tilde{Q}^1 \sim \tilde{Q}_1$), $\varphi(1, s) = Af(s)$, and $D_r \varphi(1, s) = Cf(s)$. Then $Bf(r) = \varphi(r, 1)$ determines a transmutation $B: \tilde{Q}_1 \rightarrow \tilde{Q}$.*

Remark 3.3. In this spirit one can formally construct B and \tilde{B}

via Cauchy type problems as follows ($n=3$). Let $U_1(t, s)$ have the form (3.1) with (ρ, g, \mathfrak{G}) replaced by $(\rho^1, g_1, \mathfrak{G}_1)$ etc. Set $\varphi(r, s) = \langle \beta(r, t), U_1(t, s) \rangle$ and $\tilde{\varphi}(r, s) = \langle \tilde{\beta}(r, t), U_1(t, s) \rangle$ so that $\varphi(r, 1) = Bf(r)$ and $\tilde{\varphi}(r, 1) = \tilde{B}f(r)$. For suitable f we obtain e.g. $\tilde{\varphi}(1, s) = \tilde{A}f(s) = \langle f(\sigma), \mathfrak{A}(s, \sigma) \rangle$, $D_r \tilde{\varphi}(1, s) = \tilde{C}f(s) = \langle f(\sigma), \mathfrak{C}(s, \sigma) \rangle$, where formally $\mathfrak{A}(s, \sigma) = \langle \alpha(\nu, k) g_1(\nu, -k, s), g_1(\nu, -k, \sigma) \rangle_{\rho^1}$ and $\mathfrak{C}(s, \sigma) = \langle \gamma(\nu, k) g_1(\nu, -k, s), g_1(\nu, -k, \sigma) \rangle_{\rho^1}$ ($\alpha(\nu, k) = g(\nu, -k, 1) / g_1(\nu, -k, 1)$ and $\gamma(\nu, k) = Dg(\nu, -k, 1) / g_1(\nu, -k, 1)$). Similar formulas apply for $\varphi(1, s)$ and $D_r \varphi(1, s)$ with ρ^1 replaced by ρ in the corresponding $\mathfrak{A}(s, \sigma)$ and $\mathfrak{C}(s, \sigma)$.

By modifying some techniques in [4] one shows (cf. also [3])

Theorem 3.4. *For suitable f, h and T_s^r defined as in Theorem 3.1 there results $\langle T_s^r f(s), h(s) \rangle = \langle f(s), T_s^r h(s) \rangle$ and setting $(f * h)(r) = \langle T_s^r f(s), h(s) \rangle$ it follows that $(f * h)^\wedge = \hat{f} \hat{h} / g(\nu, -k, 1)$.*

Remark 3.5. Following [4] it is possible to develop various Gelfand-Levitan (G-L) equations. For example based on the equations $g(\nu, -k, r) = \langle \tilde{\beta}(r, s), g_1(\nu, -k, s) \rangle$ and $g_1(\nu, -k, t) = \langle \beta(u, t), g(\nu, -k, u) \rangle$ a G-L equation arises in the form $\beta(r, t) = \langle \tilde{\beta}(r, s), A(s, t) \rangle$ where $A(s, t) = \langle g_1(\nu, -k, s), g_1(\nu, -k, t) \rangle_{\rho}$.

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