

50. Nonlinear Parabolic Variational Inequalities with Time-dependent Constraints

By Nobuyuki KENMOCHI

Department of Mathematics, Faculty of Education, Chiba University

(Communicated by Kôzaku YOSIDA, M. J. A., Nov. 12, 1977)

Let H be a (real) Hilbert space with the inner product $(\cdot, \cdot)_H$ and norm $\|\cdot\|_H$ in H , and X a uniformly convex Banach space with the strictly convex dual X^* , natural pairing $(\cdot, \cdot)_X: X^* \times X \rightarrow \mathbb{R}^1$ and with norm $\|\cdot\|_X$ in X . Suppose that X is a dense subspace of H and the natural injection from X into H is continuous. Then, identifying H with its dual in terms of the inner product $(\cdot, \cdot)_H$, we have the relation $X \subset H \subset X^*$ where H is dense in X^* . Let $0 < T < \infty$ and $2 \leq p < \infty$ with $1/p + 1/p' = 1$, and put $\mathcal{H} = L^2(0, T; H)$ and $\mathcal{X} = L^p(0, T; X)$ with $\mathcal{X}^* = L^{p'}(0, T; X^*)$; the natural pairing between \mathcal{X}^* and \mathcal{X} is denoted by $(\cdot, \cdot)_{\mathcal{X}}$ as well.

We are given a family $\{K(t); 0 \leq t \leq T\}$ of closed convex subsets of X satisfying that

(KI) for each $r \geq 0$ there are real-valued functions $\alpha_r \in W^{1,2}(0, T)$ and $\beta_r \in W^{1,1}(0, T)$ with the following property: for each $s, t \in [0, T]$ with $s \leq t$ and $z \in K(s)$ with $\|z\|_H \leq r$ there exists $z_1 \in K(t)$ such that

$$\|z_1 - z\|_H \leq |\alpha_r(t) - \alpha_r(s)|(1 + \|z\|_X^2)$$

and

$$\|z_1\|_X^p - \|z\|_X^p \leq |\beta_r(t) - \beta_r(s)|(1 + \|z\|_X^2).$$

We put $K_H =$ the closure of $K(0)$ in H and $\mathcal{K} = \{v \in \mathcal{X}; v(t) \in K(t) \text{ for a.e. } t \in [0, T]\}$.

We are also given a family $\{A(t); 0 \leq t \leq T\}$ of (nonlinear) operators from $D(A(t)) = X$ into X^* such that

(AI) \mathcal{A} defined by $[\mathcal{A}v](t) = A(t)v(t)$ is an operator from $D(\mathcal{A}) = \mathcal{X}$ into \mathcal{X}^* and maps bounded subsets of \mathcal{X} into bounded subsets of \mathcal{X}^* ;

(AII) for each $h \in \mathcal{X}$ there are a positive number c_0 and a function $c_1 \in L^1(0, T)$ satisfying

$$(A(t)z, z - h(t))_X \geq c_0[z]_X^p - c_1(t) \quad \text{a.e. on } [0, T]$$

for all $z \in X$, where $[\cdot]_X$ is a seminorm on X such that $[\cdot]_X + \|\cdot\|_H$ gives a norm on X equivalent to $\|\cdot\|_X$.

With the above notation, given $f \in \mathcal{X}^*$ and $u_0 \in K_H$, our problem $(V_s; f, u_0)$ is to find a function $u \in \mathcal{K}$ such that

- (i) $u' (= du/dt) \in \mathcal{X}^*$ and $(u' + \mathcal{A}u - f, u - v)_{\mathcal{X}} \leq 0$ for all $v \in \mathcal{K}$;
- (ii) $u(0) = u_0$ (note that $u \in C([0, T]; H)$ if $u \in \mathcal{K}$ and $u' \in \mathcal{X}^*$).

This is the strong formulation, while in its weak formulation $(V_w; f, u_0)$, instead of (i) and (ii), only the following (iii) is required:

(iii) $(v' + \mathcal{A}u - f, u - v)\mathcal{X} - \|u_0 - v(0)\|_H^2/2 \leq 0$ for all $v \in \mathcal{K}$ with $v' \in \mathcal{X}^*$.

Our object is to show the existence and uniqueness of a solution to $(V_w; f, u_0)$. For this purpose we introduce the following (possibly multivalued) operator $\mathcal{L}_{u_0}: [u, g] \in G(\mathcal{L}_{u_0})$ (the graph of \mathcal{L}_{u_0}) if and only if $u \in \mathcal{K}, g \in \mathcal{X}^*$ and $(v' - g, u - v)\mathcal{X} - \|u_0 - v(0)\|_H^2/2 \leq 0$ for all $v \in \mathcal{K}$ with $v' \in \mathcal{X}^*$. As is easily checked, u is a solution to $(V_w; f, u_0)$ if and only if it is a solution of the functional equation $\mathcal{L}_{u_0}u + \mathcal{A}u \ni f$.

Now given $u_0 \in K_H$, we consider the following operator $\mathcal{L}_{u_0}^s$ corresponding to the strong formulation of our problem: $[u, g] \in G(\mathcal{L}_{u_0}^s)$ if and only if $u \in \mathcal{K}$ with $u' \in \mathcal{X}^*, u(0) = u_0, g \in \mathcal{X}^*$ and $(u' - g, u - v)\mathcal{X} \leq 0$ for all $v \in \mathcal{K}$. Clearly, \mathcal{L}_{u_0} is an extension of $\mathcal{L}_{u_0}^s$. Also, applying the results in [8] and [10], we can prove:

Theorem 1. (i) For each $u_0 \in K_H, \mathcal{L}_{u_0}$ is maximal monotone.

(ii) If $u_0 \in K_H$ and $u \in D(\mathcal{L}_{u_0})$, then $u \in C([0, T]; H)$ and $u(0) = u_0$.

(iii) Let $u_{0,i} \in K_H$ and $[u_i, g_i] \in G(\mathcal{L}_{u_{0,i}})$ ($i = 1, 2$). Then for any $s, t \in [0, T]$ with $s \leq t$,

$$\|u_1(t) - u_2(t)\|_H^2 - \|u_1(s) - u_2(s)\|_H^2 \leq 2 \int_s^t (g_1 - g_2, u_1 - u_2)_X dr.$$

(iv) Let $\{u_{0,n}\} \subset K_H$ and $\{[u_n, g_n]\}$ with $[u_n, g_n] \in G(\mathcal{L}_{u_{0,n}})$ be sequences such that $u_{0,n} \rightarrow u_0$ strongly in $H, u_n \rightarrow u$ strongly (resp. weakly) in \mathcal{X} and $g_n \rightarrow g$ weakly (resp. strongly) in \mathcal{X}^* as $n \rightarrow \infty$. Then $[u, g] \in G(\mathcal{L}_{u_0})$ and $u_n \rightarrow u$ strongly in $C([0, T]; H)$ as $n \rightarrow \infty$.

(v) Let $[u, g] \in G(\mathcal{L}_{u_0})$ with $u_0 \in K_H$ and $\{u_{0,n}\}$ be a sequence in $K(0)$ such that $u_{0,n} \rightarrow u_0$ strongly in H as $n \rightarrow \infty$. Then there is a sequence $\{[u_n, g_n]\}$ such that $[u_n, g_n] \in G(\mathcal{L}_{u_{0,n}}^s), g_n \in \mathcal{A}, g_n \rightarrow g$ weakly in \mathcal{X}^* and $u_n \rightarrow u$ strongly both in $C([0, T]; H)$ and in \mathcal{X} as $n \rightarrow \infty$.

In addition to the assumptions we have made so far, assume that

(KII) $z_1 + z_2 - z_3 \in K(t)$ for any $z_1, z_2, z_3 \in K(t)$ and $t \in [0, T]$.

Then the following holds.

Proposition. For each $u_0 \in K_H, G(\mathcal{L}_{u_0})$ is convex and closed in $\mathcal{X} \times \mathcal{X}^*$ (and hence it is closed in the weak-weak topology of $\mathcal{X} \times \mathcal{X}^*$).

Next, by using the above results and a slightly modified version of [6; Theorem 2], concerning the equation $\mathcal{L}_{u_0}u + \mathcal{A}u \ni f$, we have:

Theorem 2. Suppose that \mathcal{A} is of type M (cf. [2]). Then for each $u_0 \in K_H$, the range of $\mathcal{L}_{u_0} + \mathcal{A}$ is the whole of \mathcal{X}^* , that is, the equation $\mathcal{L}_{u_0}u + \mathcal{A}u \ni f$ has a solution for every $f \in \mathcal{X}^*$.

Theorem 3. If there is a function $\omega \in L^1(0, T)$ such that $(A(t)z_1 - A(t)z_2, z_1 - z_2)_X + \omega(t)\|z_1 - z_2\|_H^2 \geq 0$ for all $z_1, z_2 \in K(t)$ and a.e. $t \in [0, T]$, then the equation $\mathcal{L}_{u_0}u + \mathcal{A}u \ni f$ admits at most one solution for each

$u_0 \in K_H$ and $f \in \mathcal{X}^*$, and the solution depends continuously on u_0 and f .

The detailed proofs of the results mentioned above and their applications will be given in [9].

Remarks. (i) In Theorem 2, if \mathcal{A} is a pseudo-monotone operator (cf. [2]) from \mathcal{X} into \mathcal{X}^* , then the same conclusion of Theorem 2 is valid without the assumption (KII) (cf. [3; Théorème 1]).

(ii) Given $f \in \mathcal{X}^*$, consider the variational problem, with periodic condition, to find $u \in \mathcal{K}$ such that $(v' + \mathcal{A}u - f, u - v)_{\mathcal{X}} \leq 0$ for all $v \in \mathcal{K}$ with $v' \in \mathcal{X}^*$ and $v(0) = v(T)$. To this problem the same type of treatment is available; in this case, we require that $K(T) \subset K(0)$, and the operator \mathcal{L}_p corresponding to \mathcal{L}_{u_0} is defined by the following: $[u, g] \in G(\mathcal{L}_p)$ if and only if $u \in \mathcal{K}$, $g \in \mathcal{X}^*$ and $(v' - g, u - v)_{\mathcal{X}} \leq 0$ for all $v \in \mathcal{K}$ with $v' \in \mathcal{X}^*$ and $v(0) = v(T)$. For details, see [9].

(iii) In case $K(t)$ is time-independent, we find many interesting results on the problem $(V_s; f, u_0)$ or $(V_w; f, u_0)$ formulated for $A(t)$ in various classes of nonlinear operators of monotone type (e.g., [3, 4, 11]). Recently, in case $A(t)$ is the subdifferential of a proper lower semi-continuous convex function, various results on the solvability of the evolution equation $(d/dt)u(t) + A(t)u(t) \ni f(t)$ with variable domains have been established (e.g., [1, 5, 7, 10, 12, 13]).

References

- [1] H. Attouch, Ph. Bénéilan, A. Damlamian, and C. Picard: Equations d'évolution avec condition unilatérale. C. R. Acad. Sci. Paris, **279**, 607-609 (1974).
- [2] H. Brézis: Equations et inéquations non linéaires dans les espaces vectoriels en dualité. Ann. Inst. Fourier, Grenoble, **18**, 115-175 (1968).
- [3] —: Perturbations non linéaires d'opérateurs maximaux monotones. C. R. Acad. Sci. Paris, **265**, 566-569 (1969).
- [4] —: Problèmes unilatéraux. J. Math. Pures Appl., **51**, 1-168 (1972).
- [5] —: Un problème d'évolution avec contraintes unilatérales dépendant du temps. C. R. Acad. Sci. Paris, **274**, 310-312 (1972).
- [6] N. Kenmochi: Existence theorems for certain nonlinear equations. Hiroshima Math. J., **1**, 435-443 (1971).
- [7] —: Some nonlinear parabolic variational inequalities. Israel J. Math., **22**, 304-331 (1975).
- [8] —: Nonlinear evolution equations with variable domains in Hilbert spaces (to appear).
- [9] —: Nonlinear evolution equations with time-dependent domains and applications (in preparation).
- [10] N. Kenmochi and T. Nagai: Weak solutions for certain nonlinear time-dependent parabolic variational inequalities. Hiroshima Math. J., **5**, 525-535 (1975).
- [11] J. L. Lions: Quelques méthodes de résolution de problèmes aux limites non linéaires. Dunod Gauthier-Villars, Paris (1969).
- [12] J. J. Moreau: Problème d'évolution associé à un convexe mobile d'un espace

- hilbertien. C. R. Acad. Sci. Paris, **267**, 791–794 (1973).
- [13] Y. Yamada: On evolution equations generated by subdifferential operators. J. Fac. Sci. Univ. Tokyo, **23**, 491–515 (1976).