## 24. On the Existence of Solutions of a System of Quadratic Equations and Its Geometrical Application

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S.S. Chern and N.H. Kuiper recently proved a theorem in a paper<sup>1)</sup> which is contained in the following theorem as the cases q=2, 3.

Theorem 1. Let M be a compact Riemannian manifold with the property that at every point there is a q-dimensional linear subspace in the tangent space along whose plane elements the sectional curvatures are non-positive. Then M cannot be isometrically imbedded in an Euclidean space of dimension n+q-1.

According to their argument, in order to prove the above theorem, it is sufficient to prove an algebraic theorem as follows:

Theorem 2. Let

$$egin{aligned} arPsi_{lpha(x)} &\equiv A_{lpha ij} \ x^i x^j = 0, \end{aligned} \ A_{lpha ij} &= A_{lpha ii} \ ; \ i,j = 1,2,\ldots,n \ ; \ lpha = 1,2,\ldots,N \end{aligned}$$

$$A_{\alpha ij} = A_{\alpha ji}; i, j = 1, 2, ..., n; \alpha = 1, 2, ..., N$$

$$be a system of quadratic equations in x^{i}. If$$

$$L(x, y) \equiv \sum_{\alpha=1}^{N} (A_{\alpha ih} A_{\alpha jk} - A_{\alpha ik} A_{\alpha jh}) x^{i} y^{j} x^{h} y^{k} \leq 0$$

$$(2)$$

for any  $x^i$ ,  $y^j$ , it has a non-trivial real solution in  $x^i$ , when N < n.

S.S. Chern and N.H. Kuiper stated the theorem as a probable conjecture<sup>3)</sup> and proved only the cases n=2,3 separately by means of an algebraic method. We shall give a simple proof of Theorem 2 by means of an analytical method.

Proof of Theorem 2. Let us consider  $x^1, \ldots, x^n$  as the orthonormal coordinates of a point x in an Euclidean space of dimension n. Let be  $H(x) = \sum_{\alpha=1}^{N} \Psi_{\alpha}(x) \Psi_{\alpha}(x)$  and  $x_0 = (x_0^i)$  be a point on the unit (n-1)-sphare  $S^{n-1}$ :  $\delta_{ij} x^i x^j = 1^{4}$  at which H(x) attains its minimum  $\lambda^2$  on  $S^{n-1}$ . It is sufficient in order to prove the theorem that  $\lambda=0$ .

Now, we can replace (1) by  $\Psi_a^*(x) = \sum_{\beta=1}^N \alpha_\alpha^\beta \Psi_\beta(x) = 0$ , where  $(\alpha_\alpha^\beta)$  is an orthogonal  $N \times N$ -matrix, since  $H(x) = \sum_{\alpha=1}^N \Psi_\alpha^*(x) \Psi_\alpha^*(x)$ . Accordingly, without loss of generality, we may put

$$\Psi_{\alpha}(x_0)=0 \qquad (\alpha=2,3,\ldots,N)$$
,

hence  $\lambda = \Psi_1(x_0)$ .

At the point  $x_0$  we must have

<sup>1)</sup> S. S. Chern and N. H. Kuiper: Some theorems on the isometric imbedding of compact Riemann manifolds in Euclidean space, Annals of Math., 56, 422-430 (1952).

<sup>2)</sup> We shall make use of the summation convention for the repeated indices i, j, h.k.

<sup>3)</sup> S. S. Chern and N. H. Kuiper (loc. cit.), p. 427.

<sup>4)</sup>  $\delta_{ij}$  is 0 if  $i \neq j$ , and 1 if i = j.

$$dH=0$$
,  $d^2H \ge 0$ 

on  $S^{n-1}$ , which are clearly equivalent to the conditions

$$\lambda A_{1ij}x^iy^j=0, \qquad (3)$$

$$\lambda A_{1ij}y^iy^j + 2\sum_{n=1}^N A_{\alpha ih}x_0^iy^h A_{\alpha jk}x_0^jy^k \ge 0 \tag{4}$$

for any  $y \in S^{n-1}$  such that

$$\delta_{ij}x_0^i y^j = 0. ag{5}$$

Now, let us suppose that  $\lambda \neq 0$ . Then we get from (3), (5) the relation

$$A_{14i}x_0^j = \lambda \delta_{ij}x_0^j. \tag{6}$$

There exists at least a point  $y_0 = (y_0^i)$  on  $S^{n-1}$  whose coordinates satisfy the following conditions

$$A_{\alpha ij}x_0^iy_0^j=0, \qquad \alpha=1,2,\ldots,N$$
 (7)

since N < n. By virtue of (6) and the above assumption  $\lambda \neq 0$ , we have  $\delta_{ij}x_0^iy_0^j = 0$ . Hence we can substitute  $y_0$  for y in (3), (4). Then (4) becomes  $\lambda A_{1ij}y_0^iy_0^j \ge 0$ . On the other hand, we get from (2), (7) the relation  $L(x_0, y_0) = \lambda A_{1ij}y_0^iy_0^j \le 0$ . Hence we obtain the relation

$$A_{1ij}y_0^iy_0^j=0$$
 .

By the relations (7),  $\Psi_{\alpha}(x_0)=0$  for  $\alpha>1$  and  $\Psi_1(y_0)=0$ , without loss of generality, we may, in addition, put

$$\Psi_{a}(y_{0}) = \mu$$
,  $\Psi_{a}(y_{0}) = 0$ ,  $\alpha = 3, 4, \ldots, N$ ,

hence  $H(y_0) = \mu^2$ .

Now, we can represent any point on the great circle on  $S^{n-1}$  through the point  $x_0$ ,  $y_0$  by  $x_0 \cos \theta + y_0 \sin \theta$  ( $0 \le \theta \le 2\pi$ ), where  $x_0$ ,  $y_0$  denote also their position vectors. If we put  $f(\theta) = H(x_0 \cos \theta + y_0 \sin \theta)$ , we can easily see that

$$f(\theta) = \lambda^2 \cos^4 \theta + \mu^2 \sin^4 \theta.$$

Hence we have  $f'(\theta) = 4\cos\theta\sin\theta$  ( $-\lambda^2\cos^2\theta + \mu^2\sin^2\theta$ ),  $f''(\theta) = 4(\cos^2\theta - \sin^2\theta)(-\lambda^2\cos^2\theta + \mu^2\sin^2\theta) + 8\cos\theta\sin\theta$  ( $\lambda^2 + \mu^2$ ) where dashes denote the derivatives with respect to  $\theta$ . Accordingly, we get the relations f'(0) = 0,  $f''(0) = -4\lambda^2 < 0$  which contradict to the assumption that H(x) takes its minimum on  $S^{n-1}$  at  $x_0$ . Thus we see that  $\lambda = 0$ . The proof is complete.