

Spin Transformations. I.

By

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(Received July, 10, 1941.)

§ 1. Introduction.

Any 4-4 matrices γ_i which satisfy the relations

$$\gamma_{(i}\gamma_{j)} = g_{ij}I \quad i, j = 1, 2, 3, 4 \quad (1.1)$$

for any given fundamental tensor g_{ij} in a 4-dimensional Riemannian space are given as follows⁽¹⁾:

$$\gamma_i = S^{-1}h_i^r \hat{\gamma}_r S, \quad (1.2)$$

where S is any 4-4 matrix, $\hat{\gamma}_i$ are any 4-4 matrices satisfying $\hat{\gamma}_{(i}\hat{\gamma}_{j)} = \delta_{ij}I$, and h_j^i satisfy the following relations:

$$\sum_{r=1}^4 h_i^r h_j^r = g_{ij}, \quad (1.3)$$

i. e. arbitrary γ_i are given by $H = \|h_{ij}\|$ (i indicate the rows and j the columns) and a spin matrix S . Now let us consider the space Γ_4 consisting of all $\gamma_i (= h_i^r \hat{\gamma}_r)$ where $\hat{\gamma}_r$ are fixed and h_j^i may take all the values satisfying relations (1.3). An element γ_i of Γ_4 evidently satisfies (1.1). Further, let us consider the spin transformation S of the elements γ_i 's of Γ_4 , such that $'\gamma_i = S^{-1}\gamma_i S$. The set of all such S we write \mathfrak{S} ; then, clearly, \mathfrak{S} makes a group. So for any γ_i and $'\gamma_i$ satisfying (1.1), there exists S such that transitive group leaving Γ_4 invariant. There now arises the problem of determining group \mathfrak{S} .

If any two elements γ_i and $'\gamma_i$ of Γ_4 be written as follows:

$$\gamma_i = h_i^r \hat{\gamma}_r \quad \text{and} \quad '\gamma_i = k_i^r \hat{\gamma}_r,$$

then, from (1.3), we have $H^*H = K^*K = G$, where $H = \|h_j^i\|$, $K = \|k_j^i\|$, and $G = \|g_{ij}\|$, and the asterisk denotes the transposed matrix. If we put $HK^{-1} \equiv A$, we have $A^*A = I$, i. e. A is an orthogonal matrix. Then we say that γ_i and $'\gamma_i$ have the same or opposite orientations, according as the orthogonal matrix A is proper or improper. Specially, if we take δ_{ij} for

(1) Pauli, Ann. d. Physik. **18** (1933).

Newman, Jour. London Math. Soc. **7** (1932), p. 93.

g_{ij} , then $H = \|h_j^i\|$ satisfying (1.3) becomes an orthogonal matrix, and then the space Γ_4 of γ_i can be considered as a vector space whose basis is $\{\gamma_i\}$. If we say that γ_i and γ_j ($i \neq j$) are perpendicular when, and only when, $\gamma_i \gamma_j = 0$, then $\{\gamma_i\}$ forms an orthogonal ennuple in the space Γ_4 . In this case the orientation of the system γ_i is equivalent to the orientation of an orthogonal ennuple h_j^i .

In this paper we assume that A is a real matrix, i. e. the elements of A are all real numbers. Now if, for any two elements $\gamma_i = h_j^i \gamma_j$, and $\gamma_i = k_j^i \gamma_j$ of Γ_4 , HK^{-1} is real, we say that the systems $\{\gamma_i\}$ and $\{\gamma_i\}$ are equivalent; and this equivalence is obviously reflective and transitive. Then all the elements of Γ_4 are classified into certain sets R_4, S_4, \dots of elements such that elements of the same set are equivalent to one another. Thus, in this paper, instead of Γ_4 we shall consider any sub-space of Γ_4 , say R_4 , in which any two elements are related to each other by real orthogonal matrices. By \mathfrak{S} we denote the set of S such that $\gamma_i = S^{-1} \gamma_i S$ for any two elements γ_i and γ_i of R_4 . \mathfrak{S} is clearly a sub-group of \mathfrak{O} .

Brauer and Weyl⁽¹⁾ have algebraically classified the spin matrices S of \mathfrak{O} , and therefore of \mathfrak{S} , into two classes; but in order to determine the concrete forms, the infinitesimal method has been adopted there. In this paper, however, where consideration is purely abstract, regarding γ_i as any operator satisfying $\gamma_i \gamma_j = \delta_{ij} I$ we shall algebraically evaluate S and then classify the elements of \mathfrak{S} . That is to say, in § 2-4 we actually evaluate S for any given γ_i and γ_i in a sub-space R_4 ; and as its corollary, we prove the existence of operator S such that $\gamma_i = S^{-1} \gamma_i S$ for any given γ_i and γ_i in R_4 ⁽²⁾. In § 5 we classify the elements of \mathfrak{S} into two classes, one preserving the orientations and the other changing them; and in § 6 we determine the concrete forms of spin operators S of \mathfrak{S} . In § 7 we describe the infinitesimal method; and in § 8 we discuss the relations of our method to the infinitesimal method, and then obtain the simple relation between Cayley's parametrization of an orthogonal matrix and the spin operator. In § 9-11 we extend the result above-obtained for 8-8 matrix, and show that the same procedure can be extended to 2^n - 2^n matrix.

The result of this paper holds good also for the general case in which the condition of reality is removed.⁽³⁾ Therefore we can apply this result to 4-dimensional space-time. Lastly we shall suggest that the case of 8-8 matrix seems to be applicable to the atomic nucleus.

(1) R. Brauer and H. Weyl, Amer. Jour. of Math. **57** (1935), pp. 425-449.

(2) The proof of the existence of operator S for any operator γ_i and γ_i satisfying $\gamma_i \gamma_j = \gamma_j \gamma_i = \delta_{ij} I$ has been given by Eddington. Our result is a special case of that result. Cf. A. S. Eddington; Jour. Lond. Math. Soc. **7** (1932), pp. 58-68.

(3) We shall give the proof in the next paper.

§ 2. Determination of S .

Take any two elements $\gamma_i = h_i^r \hat{\gamma}_r$ and $\gamma'_i = k_i^r \hat{\gamma}_r$ of Γ_4 where $i, r = 1, 2, 3, 4$, and consider the matrices $H \equiv \|h_i^j\|$ and $K \equiv \|k_i^j\|$; then HK^{-1} becomes an orthogonal matrix. Now we shall determine S satisfying the relation

$$\gamma'_i = k_i^r \hat{\gamma}_r = S^{-1} \gamma_i S = S^{-1} h_i^r \hat{\gamma}_r S. \quad (2.1)$$

If we put $HK^{-1} \equiv A = \|a_j^i\|$, from (2.1) we have

$$\hat{\gamma}'_i = S^{-1} a_j^i \hat{\gamma}_j S. \quad (2.2)$$

Expanding S by basic elements,

$$S = AI + A^{ij} \hat{\gamma}_i \hat{\gamma}_j + A^{5i} \hat{\gamma}_i + A^{i5} \hat{\gamma}_i \hat{\gamma}_5 + A^{ij} \hat{\gamma}_i \hat{\gamma}_j, \quad (2.3)$$

where

$$\left. \begin{aligned} \hat{\gamma}'_{(i} \hat{\gamma}_{j)} &= \delta_{ij} I \\ A^{ij} &= -A^{ji}, \quad \text{and} \quad \hat{\gamma}'_5 = \hat{\gamma}'_1 \hat{\gamma}'_2 \hat{\gamma}'_3 \hat{\gamma}'_4, \end{aligned} \right\} \quad (2.4)$$

and taking into account the relations:

$$\left. \begin{aligned} \hat{\gamma}'_i \hat{\gamma}'_j \hat{\gamma}'_k &= -\hat{\epsilon}_{ijk} \hat{\gamma}'_l \hat{\gamma}'_5 \quad (i, j \neq k) \\ \hat{\gamma}'_i \hat{\gamma}'_j \hat{\gamma}'_5 &= -\frac{1}{2} \hat{\epsilon}_{ij}{}^{kl} \hat{\gamma}'_k \hat{\gamma}'_l \quad (i \neq j) \end{aligned} \right\} \quad (2.5)$$

where $\hat{\epsilon}_{ijkl} = 0$ when any two of i, j, k, l are equal,

= 1 when (i, j, k, l) is an even permutation of $(1, 2, 3, 4)$,

= -1 when (i, j, k, l) is an odd permutation of $(1, 2, 3, 4)$,

from (2.2) and (2.3) we have

$$\left. \begin{aligned} \text{(i)} \quad (a_i^k - \delta_i^k) A_k &= 0, \\ \text{(ii)} \quad (a_i^j - \delta_i^j) A + 2(a_i^k + \delta_i^k) A_k^j &= 0, \\ \text{(iii)} \quad (a_i^k + \delta_i^k) A_k^5 &= 0, \\ \text{(iv)} \quad (a_i^j + \delta_i^j) A^5 &= (a_i^k - \delta_i^k) A^{lp} \hat{\epsilon}_{kip}{}^j, \\ \text{(v)} \quad (a_i^p + \delta_i^p) (\delta_p^j A^k - \delta_p^k A^j) &= (a_i^l - \delta_i^l) A^{p5} \hat{\epsilon}_{lp}{}^{jk}. \end{aligned} \right\} \quad (2.6)$$

Thus the problem of determining S for given H and K becomes that of solving A 's from (2.6) for given a_j^i .

§ 3. Determination of S for same orientations.

In order to solve (2.6), we use the following well-known theorems:

Lemma 1. *If F is a real skew-symmetric matrix whose degree is even, say $2n$, there exists a real orthogonal matrix P such that*

$$P^{-1}FP = \tilde{F} = \begin{pmatrix} 0 & a_1 \\ -a_1 & 0 \end{pmatrix} \dot{+} \begin{pmatrix} 0 & a_2 \\ -a_2 & 0 \end{pmatrix} \dot{+} \dots \dot{+} \begin{pmatrix} 0 & a_n \\ -a_n & 0 \end{pmatrix}.$$

Lemma 2. *If A is a real proper orthogonal matrix whose degree is even, say $2n$, there exists a real orthogonal matrix T such that*

$$T^{-1}AT = \tilde{A} = \begin{pmatrix} \cos \theta_1 & \sin \theta_1 \\ -\sin \theta_1 & \cos \theta_1 \end{pmatrix} \dot{+} \begin{pmatrix} \cos \theta_2 & \sin \theta_2 \\ -\sin \theta_2 & \cos \theta_2 \end{pmatrix} \dot{+} \dots \dot{+} \begin{pmatrix} \cos \theta_n & \sin \theta_n \\ -\sin \theta_n & \cos \theta_n \end{pmatrix}.$$

When $\|a_j^i\|$ is real and proper, by Lemma 2 we can choose a real orthogonal matrix T such that

$$T^{-1}AT = \tilde{A} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \dot{+} \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix}. \quad (3.1)$$

Put $T = \|t_j^i\|$ and $t_i^r \hat{\gamma}_r = \hat{\gamma}_i$; then $\hat{\gamma}_i \hat{\gamma}_j = \delta_{ij} I$, because T is an orthogonal matrix. If we write $\hat{\gamma}_5$ for $\hat{\gamma}_1 \hat{\gamma}_2 \hat{\gamma}_3 \hat{\gamma}_4$, then $\hat{\gamma}_5 = \det. |T| \cdot \hat{\gamma}_5$ and $\det. |T| = +1$ or -1 , according as the matrix T is proper or improper. If we put $T^{-1} = \|T_j^i\|$, then $\hat{\gamma}_i = T_i^r \hat{\gamma}_r$. Substituting this into (2.2), we get:

$$\hat{\gamma}_i = S^{-1} t_i^r a_r^s T_s^j \hat{\gamma}_j S$$

or

$$\hat{\gamma}_i = S^{-1} \tilde{a}_i^j \hat{\gamma}_j S, \quad (3.2)$$

where $\|\tilde{a}_j^i\| = \tilde{A} = T^{-1}AT$ and

$$S = {}^i A I + {}^i A^5 \hat{\gamma}_5 + {}^i A^i \hat{\gamma}_i + {}^i A^{i5} \hat{\gamma}_i \hat{\gamma}_5 + {}^i A^{ij} \hat{\gamma}_i \hat{\gamma}_j, \quad (3.3)$$

where

$${}^i A = A, \quad {}^i A^5 = \epsilon A^5, \quad {}^i A^i = T_k^i A^k, \quad {}^i A^{i5} = \epsilon T_k^i A^{k5}, \quad {}^i A^{ij} = T_k^i T_l^j A^{kl}, \quad (3.4)$$

or

$$A = {}^i A, \quad A^5 = \epsilon {}^i A^5, \quad A^i = t_r^i {}^i A^r, \quad A^{i5} = \epsilon t_r^i {}^i A^{r5}, \quad A^{ij} = t_k^i t_l^j A^{kl}, \quad (3.5)$$

and $\epsilon \equiv \det. |T|$. To simplify description, we write A, A^5, \dots etc., and a_j^i , instead of ${}^i A, {}^i A^i, \dots$ etc., and \tilde{a}_j^i . Then we have, from (3.2), the same relation as (2.6), in which

$$A = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \dot{+} \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix}.$$

To solve (2.6), we consider the problem in the following cases:

| | | |
|-----------|-----------------|-----------------|
| Case I. | $ I+A \neq 0,$ | $ I-A \neq 0;$ |
| Case II. | $ I+A = 0,$ | $ I-A \neq 0;$ |
| Case III. | $ I+A \neq 0,$ | $ I-A = 0;$ |
| Case IV. | $ I+A = 0,$ | $ I-A = 0.$ |

In what follows we use the letters of indices as follows:

$$i, j, k, l, \dots = 1, 2, 3, 4$$

$$a, b, \dots = 1, 2$$

$$x, y, \dots = 3, 4$$

Case I. From (2.6) (i) and (iii) we have $\Lambda_k = \Lambda_k^5 = 0$, and from (ii), we have $\Lambda^{ax} = 0$, $\Lambda^{12} = \frac{1}{2} \tan \frac{\theta}{2} \Lambda$, $\Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda$. From (iv), $\Lambda^5 = \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \Lambda$. Then (v) becomes an identity. Thus we have

$$\left. \begin{aligned} \Lambda^k = \Lambda^{k5} = 0, \quad \Lambda^{ax} = 0, \quad \Lambda^{12} = \frac{1}{2} \tan \frac{\theta}{2} \Lambda, \quad \Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda, \\ \Lambda^5 = \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \Lambda, \quad \text{and } \Lambda \text{ is arbitrary.} \end{aligned} \right\} \quad (3.6)$$

Case II. From $|I+A|=0$, $\theta \equiv \pi$ or $\varphi \equiv \pi \pmod{2\pi}$. First we assume that $\theta \equiv \pi \pmod{2\pi}$ and $\varphi \not\equiv \pi \pmod{2\pi}$. Then $\alpha_a^i = -\delta_a^i$. From (i) $\Lambda_k = 0$, and from (ii) $\Lambda = 0$, $\Lambda^{ax} = 0$, $\Lambda^{xy} = 0$; from (iii) $\Lambda^{x5} = 0$, from (iv) $\Lambda^{12} = \frac{1}{2} \cot \frac{\varphi}{2} \Lambda^5$, and from (v) $\Lambda^{x5} = 0$. Rewriting (3.6) as follows:

$$\Lambda = 2\Lambda^{12} \cot \frac{\theta}{2}, \quad \Lambda^{12} = \frac{1}{2} \cot \frac{\varphi}{2} \Lambda^5, \quad \Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda,$$

and putting $\theta \equiv \pi \pmod{2\pi}$, we see that $\Lambda = 0$; consequently $\Lambda^{34} = 0$, and $\Lambda^{12} = \frac{1}{2} \cot \frac{\varphi}{2} \Lambda^5$. Thus, from (3.6), we can obtain the result for when $\theta \equiv \pi \pmod{2\pi}$. When $\theta \equiv \pi$ and $\varphi \equiv \pi \pmod{2\pi}$, we have again the same result.

Case III. Here $\theta \equiv 0$ or $\varphi \equiv 0 \pmod{2\pi}$. By the same treatment as above we have (3.6), in which θ or φ is congruent to 0 mod. 2π .

Case IV. Here, we can take $\alpha_a^i = \delta_a^i$ and $\alpha_x^i = -\delta_x^i$. Then we have: $\Lambda^k = \Lambda^{k5} = 0$, $\Lambda = \Lambda^5 = \Lambda^{aj} = 0$; and Λ^{34} is arbitrary. So in the same way as in Case II, we have (3.6), in which $\theta \equiv 0$ and $\varphi \equiv \pi \pmod{2\pi}$.

Thus, as the general solution of (3.2) we have

$$\left. \begin{aligned} \Lambda^k = \Lambda^{k5} = 0, \quad \Lambda^{ax} = 0, \quad \Lambda^{12} = \frac{1}{2} \tan \frac{\theta}{2} \Lambda, \quad \Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda, \\ \Lambda^5 = \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \Lambda. \end{aligned} \right\} \quad (3.7)$$

As is easily seen from this, for given γ_i and γ'_i of R_4 S is determined uniquely except for a numerical factor, and Λ , Λ^5 , Λ^{ij} are real except for a common factor. Returning to Λ , Λ^5 , ... in (3.5), from these in (3.7) $\Lambda^k = \Lambda^{k4} = 0$. Thus S defined by (2.2) for the real proper orthogonal matrix $A = \|a_j^i\|$, i. e. for γ_i and γ'_i of R_4 of the same orientations, must be of the form

$$S = \Lambda I + \Lambda^5 \gamma_5^{\circ} + \Lambda^{ij} \gamma_i^{\circ} \gamma_j^{\circ},$$

where Λ , Λ^5 , Λ^{ij} are real function except for a common factor.

§ 4. Determination of S for opposite orientations.

When $\gamma_i (=h_i^r \hat{\gamma}_r)$ and $'\gamma_i (=k_i^r \hat{\gamma}_r)$ have opposite orientations, taking $\bar{\gamma}_i (= \bar{h}_i^r \hat{\gamma}_r)$ of R_4 with opposite orientations compared with γ_j , and considering T such that

$$T^{-1}\gamma_i T = \bar{\gamma}_i, \quad (4.1)$$

we have, from (2.1),

$$S^{-1}T\bar{\gamma}_i T^{-1}S = '\gamma_i. \quad (4.2)$$

If we put $T^{-1}S=U$, we see from (4.2) that U is a transformation of $\bar{\gamma}_i$ into $'\gamma_i$ preserving the orientation; therefore, when the reality $\bar{H}K^{-1}$ is taken into account, U has the following form:

$$U = \Lambda I + \Lambda^5 \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j. \quad (4.3)$$

Therefore, if T is determined by (4.1), S is determined by $S=TU$. Specially, if we take $\bar{H}=|\bar{h}_i^j|$ as follows:

$$H\bar{H}^{-1} \equiv A \equiv \begin{pmatrix} -1 & & & \\ & -1 & & \\ & & -1 & \\ & & & 1 \end{pmatrix} \text{ i. e. } \begin{cases} \bar{h}_a^i = -h_a^i \\ \bar{h}_4^i = h_4^i \end{cases} \begin{matrix} (a=1, 2, 3) \\ (i=1, 2, 3, 4) \end{matrix} \quad (4.4)$$

T is obtained from (2.6) by putting $a_a^i = -\delta_a^i$, $a_4^i = \delta_4^i$ ($a=1, 2, 3$, $i=1, 2, 3, 4$); that is to say, $\Lambda_a = 0$ (from (i)), $\Lambda = 0$ (from (ii)), $\Lambda^{ij} = 0$ and $\Lambda^5 = 0$ (from (iv)), $\Lambda^{55} = 0$ (from (v)), i. e. $T = \lambda \hat{\gamma}_4$. Therefore S transforming any two of γ_i 's of opposite orientations is obtained as follows:

$$S = \lambda \hat{\gamma}_4 (\Lambda I + \Lambda^5 \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j) = '\Lambda^i \hat{\gamma}_i + '\Lambda^{55} \hat{\gamma}_5 \hat{\gamma}_5,$$

i. e. S has the following form:

$$S = \Lambda^i \hat{\gamma}_i + \Lambda^{55} \hat{\gamma}_5 \hat{\gamma}_5,$$

where Λ^i, Λ^{55} are real except for a common factor.

§ 5. Classification of $\bar{\mathcal{E}}$.

Putting together the results obtained in § 3 and § 4, we have:

Theorem 1. For any two given elements $\gamma_i = h_i^r \hat{\gamma}_r$ and $'\gamma_i = k_i^r \hat{\gamma}_r$ of the space R_4 , there exists one, and only one, (except for a numerical factor) S such that $'\gamma_i = S^{-1}\gamma_i S$. When γ_i and $'\gamma_i$ have the same orientations, S has the following form:

$$S = \Lambda I + \Lambda^5 \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j;$$

and when γ_i and $'\gamma_i$ have opposite orientations, S' has the following form:

$$S = \Lambda^i \hat{\gamma}_i + \Lambda^{55} \hat{\gamma}_5 \hat{\gamma}_5.$$

And in both cases, the coefficients of $I, \hat{\gamma}_5, \hat{\gamma}_i, \hat{\gamma}_i \hat{\gamma}_j, \hat{\gamma}_i \hat{\gamma}_5$, are real except for a common factor.

We denote the operator of the form $\Lambda I + \Lambda^5 \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j$ by S_1 , and the operator of the form $\Lambda^i \hat{\gamma}_i + \Lambda^{i5} \hat{\gamma}_i \hat{\gamma}_5$ by S_2 . Then, from the identity:

$$\begin{aligned} & \hat{\gamma}_5 (\Lambda I + \Lambda^i \hat{\gamma}_i + \Lambda^5 \hat{\gamma}_5 + \Lambda^{i5} \hat{\gamma}_i \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j) \hat{\gamma}_5 \\ &= \Lambda I - \Lambda^i \hat{\gamma}_i + \Lambda^5 \hat{\gamma}_5 - \Lambda^{i5} \hat{\gamma}_i \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j, \end{aligned}$$

we know that S_1 is characterized by the relation $\hat{\gamma}_5 S_1 \hat{\gamma}_5 = S_1$, and S_2 by $\hat{\gamma}_5 S_2 \hat{\gamma}_5 = -S_2$. So that γ_i and γ'_i have the same, or opposite, orientations, according as S mediating γ_i and γ'_i satisfies $\hat{\gamma}_5 S \hat{\gamma}_5 = S$ or $\hat{\gamma}_5 S \hat{\gamma}_5 = -S$ and conversely.⁽¹⁾

Next we consider the case when γ_i , and consequently S , are 4-4 matrices. If we take Dirac's matrices as $\hat{\gamma}_i$,⁽²⁾ then

$$S_1 = \left(\begin{array}{cc|cc} \times & \times & & 0 \\ \times & \times & & 0 \\ \hline & & \times & \times \\ 0 & & \times & \times \end{array} \right) \quad \text{and} \quad S_2 = \left(\begin{array}{cc|cc} & & \times & \times \\ & & \times & \times \\ \hline 0 & & & 0 \\ \times & \times & & \end{array} \right).$$

Next, instead of $\hat{\gamma}_i$ satisfying $\hat{\gamma}_i \hat{\gamma}_j = \delta_{ij} I$, we take any operator $\tilde{\gamma}_i$ satisfying $\tilde{\gamma}_i \tilde{\gamma}_j = g_{ij} I$, and consider the analogous problem. That is, we consider the space $\tilde{\Gamma}_4$ consisting of all $\tilde{\gamma}_i (= h_i^r \gamma_r)$ where γ_i are fixed and h_i^j may take all the values satisfying $\tilde{h}_j^i \tilde{h}_r^j g_{rs} = g_{ir}$, and we shall investigate the form of spin operator S such that $\gamma'_i = S^{-1} \gamma_i S$ for any two $\gamma_i (= \tilde{h}_i^r \tilde{\gamma}_r)$ and $\tilde{\gamma}_i (= h_i^r \tilde{\gamma}_r)$ of $\tilde{\Gamma}_4$. Here the condition that HK^{-1} with respect to $\hat{\gamma}_i$ is real becomes that $\tilde{H} \tilde{H} \tilde{K}^{-1} \tilde{H}^{-1}$ is real where $\tilde{\gamma}_i = \tilde{h}_i^k \tilde{\gamma}_k$ and $\tilde{H} = \|\tilde{h}_j^i\|$. Thus, as in Γ_4 , in $\tilde{\Gamma}_4$ we shall restrict ourselves to one of the sub-spaces of $\tilde{\Gamma}_4$, say \tilde{R}_4 .⁽³⁾ Then we have the same result as in Theorem 1,⁽⁴⁾ $\hat{\gamma}_i$ and $\hat{\gamma}_5$ being replaced by

$$\tilde{\gamma}_i \quad \text{and} \quad \tilde{\gamma}_5 = \frac{1}{\sqrt{\det. |\tilde{H}|}} \tilde{\gamma}_1 \tilde{\gamma}_2 \tilde{\gamma}_3 \tilde{\gamma}_4.$$

- (1) This is the same result as that obtained by Brauer and Weyl. Brauer and Weyl, loc. cit.

$$\begin{aligned} (2) \quad \hat{\gamma}_1 &= \left(\begin{array}{cc|cc} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ \hline & & 0 & 0 \\ & & 0 & 0 \end{array} \right), & \hat{\gamma}_2 &= \left(\begin{array}{cc|cc} 0 & 0 & 0 & -i \\ 0 & 0 & i & 0 \\ \hline & & 0 & 0 \\ & & 0 & 0 \end{array} \right), & \hat{\gamma}_3 &= \left(\begin{array}{cc|cc} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ \hline & & 0 & 0 \\ & & 0 & 0 \end{array} \right), \\ \hat{\gamma}_4 &= \left(\begin{array}{cc|cc} 0 & -i & 0 & 0 \\ i & 0 & 0 & 0 \\ \hline & & 0 & 0 \\ & & 0 & 0 \end{array} \right) & \text{and} & \hat{\gamma}_5 &= \left(\begin{array}{cc|cc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ \hline & & -1 & 0 \\ & & 0 & -1 \end{array} \right). \end{aligned}$$

- (3) The meaning of \tilde{R}_4 is analogous to that of R_4 in Γ_4 .

- (4) By making use of \tilde{H} , the problem in $\tilde{\Gamma}_4$ can be reduced to the case of R_4 . Returning to \tilde{R}_4 , we have the same result as in Theorem 1.

§ 6. Determination of $\bar{\mathcal{C}}$.

In this section we shall determine the set $\bar{\mathcal{C}}$ of the operators S which leave the space R_4 invariant, that is $S^{-1}R_4S=R_4$. But $'\gamma_i=S^{-1}'\gamma_iS$, in which $\gamma_i(=h_i^r\dot{\gamma}_r)$ is any element of the space R_4 , and we shall find the condition that $'\gamma_i$ can be written as $'\gamma_i=k_i^r\dot{\gamma}_r$, and HK^{-1} is real where $H=\|h_j^i\|$, $K=\|k_j^i\|$, and

$$\sum_{r=1}^4 h_i^r h_j^r = g_{ij}, \quad \dot{\gamma}_i \dot{\gamma}_j = \delta_{ij} I. \quad (6.1)$$

Since, necessarily, $'\gamma_i \dot{\gamma}_j = g_{ij} I$, we have $\sum_{r=1}^4 k_i^r k_j^r = g_{ij}$. By Theorem 1, if γ_i and $'\gamma_i$ have the same orientations, and HK^{-1} is real, S must be of the form:

$$S=S_1 \equiv \Lambda I + \Lambda^5 \dot{\gamma}_5 + \Lambda^{ij} \dot{\gamma}_i \dot{\gamma}_j, \quad (6.2)$$

where $\Lambda, \Lambda^5, \Lambda^{ij}$ are real except for a common factor; and if they have opposite orientations, S must be of the form:

$$S=S_2 \equiv \Lambda^i \dot{\gamma}_i + \Lambda^{5i} \dot{\gamma}_i \dot{\gamma}_5, \quad (6.3)$$

where Λ^i, Λ^{5i} are real except for a common factor. Thus, in order that $S^{-1}'\gamma_i S \equiv '\gamma_i$ may belong to the space R_4 , S must be either S_1 or S_2 .

When S is of the form S_1 , if we put $R \equiv \|\Lambda^{ij}\|$ (i indicates the rows and j the columns), from the fact that $R^* + R = 0$ and Λ^{ij} are real except for a common factor, we know by Lemma 1 that, after a suitable real orthogonal transformation $T = \|t_j^i\|$, R is transformed as follows:

$$T^{-1}RT = 'R = \begin{pmatrix} 0 & '\Lambda^{12} \\ -'\Lambda^{12} & 0 \end{pmatrix} + \begin{pmatrix} 0 & '\Lambda^{34} \\ -'\Lambda^{34} & 0 \end{pmatrix}.$$

If we put $'\dot{\gamma}_i = t_i^r \dot{\gamma}_r$, or $\dot{\gamma}_i = T_i^r \dot{\gamma}_r$ where $T^{-1} = \|T_j^i\|$, S can be written as follows:

$$S=S_1 = '\Lambda I + '\Lambda^5 \dot{\gamma}_5 + '\Lambda^{ij} \dot{\gamma}_i \dot{\gamma}_j, \quad (6.4)$$

where

$$'\Lambda = \Lambda, \quad '\Lambda^5 = \epsilon \Lambda^5, \quad '\Lambda^{ij} = T_k^i T_l^j \Lambda^{kl} = \sum_l T_k^i \Lambda^{kl} t_j^l, \quad \epsilon = \det_r |T| \quad (6.4)$$

(Cf. (3.4)). Now, if we assume that there exists S^{-1} for S of the form S_1 , the conditions that, for S given by (6.4), $S^{-1}'\gamma_i S \equiv '\gamma_i$ belong to the space R_4 are, from § 3, as follows:

$$'\Lambda^{12} = \frac{1}{2} \tan \frac{\theta}{2} '\Lambda, \quad '\Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} '\Lambda, \quad '\Lambda^5 = \tan \frac{\theta}{2} \tan \frac{\varphi}{2} '\Lambda. \quad (6.6)$$

Eliminating θ and φ above, we obtain the condition:

$$'\Lambda^{12} '\Lambda^{34} = \frac{1}{4} '\Lambda^5 '\Lambda, \quad (6.7)$$

or, in the original Λ 's,

$$\frac{1}{2} \hat{\epsilon}_{ijkl} \Lambda^{ij} \Lambda^{kl} = \Lambda \Lambda^{5(1)}; \quad (6.8)$$

which is the required condition.

When $S = S_2 = \Lambda^i \hat{\gamma}_i + \Lambda^{i5} \hat{\gamma}_i \hat{\gamma}_5$, $\hat{\gamma}_4 S$ is of the form S_1 ; therefore, putting $\hat{\gamma}_4 S \equiv T$, we have $S^{-1} \gamma_i S = T^{-1} \hat{\gamma}_4 \hat{\gamma}_i \hat{\gamma}_4 T$. But if we put $\hat{\gamma}_4 \hat{\gamma}_i \hat{\gamma}_4 = \bar{\gamma}_i$, then $\bar{\gamma}_i = \bar{h}_i^r \hat{\gamma}_r$ and $\bar{h}_i^a = -h_i^a$, $\bar{h}_i^4 = h_i^4$ ($a=1, 2, 3$); therefore $\bar{\gamma}_i$ belongs to R_4 . Thus $S^{-1} \gamma_i S = T^{-1} \bar{h}_i^r \hat{\gamma}_r T = \gamma_i$; therefore, if we assume that there exists S^{-1} for S , the necessary and sufficient condition for γ_i to belong to the space R_4 is that the coefficient of expansion of T satisfy (6.8). Now T can be written as follows:

$$T = \hat{\gamma}_4 S = \Lambda I + \Lambda^5 \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j$$

where

$$\Lambda = \Lambda^4, \quad \Lambda^5 = \Lambda^{45}, \quad \Lambda^{a4} = -\frac{1}{2} \Lambda^a, \quad \Lambda^{ab} = \frac{1}{2} \Lambda^{c5} \hat{\epsilon}_{c4}^{ab} \quad (a, b, c=1, 2, 3),$$

and $\Lambda, \Lambda^5, \Lambda^{ij}$ are real except for a common factor, because of the reality of Λ^i, Λ^{i5} . Substituting these $\Lambda, \Lambda^5, \Lambda^{ij}$ into (6.8), we have:

$$\Lambda' \Lambda^5 = \frac{1}{2} \hat{\epsilon}_{ijkl} \Lambda^{ij'} \Lambda^{kl}$$

$$\text{i. e.} \quad \Lambda_4 \Lambda^{45} = \hat{\epsilon}_{a4bc} \Lambda^{a4'} \Lambda^{bc} + \hat{\epsilon}_{abc4} \Lambda^{ab'} \Lambda^{c4} = -\Lambda_a \Lambda^{a5},$$

so that

$$\Lambda_i \Lambda^{i5} = 0 \quad (6.9)$$

So the condition for S of the form S_2 is $\Lambda_i \Lambda^{i5} = 0$.

From the identities:

$$\begin{aligned} & (\Lambda I + \Lambda^5 \hat{\gamma}_5 + \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j) (\Lambda I + \Lambda^5 \hat{\gamma}_5 - \Lambda^{ij} \hat{\gamma}_i \hat{\gamma}_j) \\ &= [CA]^2 + (\Lambda^5)^2 + 2\Lambda^{ij} \Lambda_{ij} I + (2\Lambda \Lambda^5 - \hat{\epsilon}_{ijkl} \Lambda^{ij} \Lambda^{kl}) \hat{\gamma}_5, \end{aligned}$$

and

$$(\Lambda^i \hat{\gamma}_i + \Lambda^{i5} \hat{\gamma}_i \hat{\gamma}_5) (\Lambda^i \hat{\gamma}_i - \Lambda^{i5} \hat{\gamma}_i \hat{\gamma}_5) = (\Lambda^i \Lambda_i + \Lambda^{i5} \Lambda_i^5) I - 2\Lambda^i \Lambda_i^5 \hat{\gamma}_5,$$

we see that for S of the form S_1 satisfying (6.8), or of the form S_2 satisfying (6.9), there exists $S^{-1(2)}$

Thus we have the following theorem.

(1) (6.7) can be written as follows:

$$\frac{1}{2} \hat{\epsilon}_{ijkl} \Lambda^{ij'} \Lambda^{kl} = \epsilon \Lambda \Lambda^5$$

$$\therefore \frac{1}{2} \hat{\epsilon}_{ijkl} T_p^i T_q^j T_r^k T_s^l \Lambda^{pq} \Lambda^{rs} = \epsilon \Lambda \Lambda^5,$$

$$\text{i. e.} \quad \frac{1}{2} \hat{\epsilon}_{pqrs} \Lambda^{pq} \Lambda^{rs} = \Lambda \Lambda^5,$$

i. e. we have (6.8).

(2) The trivial case when $S=0$ is excluded.

Theorem 2. *The set $\bar{\mathcal{S}}$ of S 's which leave the space R_4 invariant consists of two parts \mathcal{S}_1 and \mathcal{S}_2 ; \mathcal{S}_1 , consists of S 's which have the form $S_1 = \Lambda I + \Lambda^5 \overset{\circ}{\gamma}_5 + \Lambda^{ij} \overset{\circ}{\gamma}_i \overset{\circ}{\gamma}_j$, $\Lambda, \Lambda^5, \Lambda^{ij}$ being real except for a common factor, and whose coefficients Λ, Λ^5 , and Λ^{ij} satisfy the following relation*

$$\frac{1}{2} \epsilon_{ijkl} \Lambda^{ij} \Lambda^{kl} = \Lambda \Lambda^5; \quad (6.10)$$

\mathcal{S}_2 consists of S 's which have the form $S_2 = \Lambda^i \overset{\circ}{\gamma}_i + \Lambda^{i5} \overset{\circ}{\gamma}_i \overset{\circ}{\gamma}_5$, Λ^i, Λ^{i5} being real except for a common factor, and whose coefficients Λ^i and Λ^{i5} satisfy the following relation

$$\Lambda_i \Lambda^{i5} = 0. \quad (6.11)$$

The element S of \mathcal{S}_1 reserves the orientation of γ_i in R_4 , and S of \mathcal{S}_2 changes the orientation of γ_i of R_4 .

In the case of \tilde{R}_4 , if we make use of \tilde{H} as in § 5, the problem of determining $\bar{\mathcal{S}}$ can be reduced to the case of R_4 . Then, returning to \tilde{R}_4 , we have the same result as in Theorem 2,⁽¹⁾ (6.10) and (6.11) being replaced by

$$\frac{1}{2} \tilde{\epsilon}_{ijkl} \tilde{\Lambda}^{ij} \tilde{\Lambda}^{kl} = \tilde{\Lambda} \tilde{\Lambda}^5, \quad (6.12)$$

and

$$\tilde{\Lambda}^i \tilde{\Lambda}_i^5 = 0, \quad (6.13)$$

respectively, where $\tilde{\Lambda}, \tilde{\Lambda}^i, \dots$ etc. are coefficients of expansion of S with respect to $\tilde{\gamma}_i$, and $\tilde{\epsilon}_{ijkl} = \det. |\tilde{H}| \cdot \epsilon_{ijkl} = \pm \sqrt{\det. |g_{ij}|} \cdot \epsilon_{ijkl}$.

§ 7. Infinitesimal Description of S .

The problems discussed in the previous sections have been, in short, to determine S satisfying the relations

$$a_i^j \overset{\circ}{\gamma}_j = S \overset{\circ}{\gamma}_i S^{-1}, \quad (i, j = 1, 2, 3, 4) \quad (7.1)$$

for any real orthogonal matrix $A = \|a_j^i\|$, where $\overset{\circ}{\gamma}_i (\overset{\circ}{\gamma}_j) = \delta_{ij} I$. If we denote the vector space whose basis is $\overset{\circ}{\gamma}_i$ by Γ , the transformations in the space Γ consist of two kinds, one being a coordinate transformation: $\overset{\circ}{\gamma}_i = a_j^i \overset{\circ}{\gamma}_j$, and the other a spin transformation: $\overset{\circ}{\gamma}_i = S^{-1} \overset{\circ}{\gamma}_i S$. The problem discussed in this paper, in other words, is to investigate the relations of these two

(1) In the case of \tilde{R}_4 , the condition of reality of coefficients of S does not hold good, but there exists S^{-1} for S provided that $S \neq 0$, because $(\tilde{\Lambda})^2 + (\tilde{\Lambda}^5)^2 + 2\tilde{\Lambda}^{ij} \tilde{\Lambda}_{ij} = (\lambda^2 + (\lambda^5)^2 + 2\lambda^{ij} \lambda_{ij})$ and $\tilde{\Lambda}^i \tilde{\Lambda}_i + \tilde{\Lambda}^{i5} \tilde{\Lambda}_i^5 = \lambda^i \lambda_i + \lambda^{i5} \lambda_i^5$ where $\lambda_i, \lambda^i, \dots$ are coefficients of expansion of S with respect to $\tilde{\gamma}_i$.

(2) The up-and-down of indices is carried on for the tensors with ripple-marks with respect to g_{ij} , and for the tensors with no ripple-mark with respect to δ_{ij} .

transformations. When A is an improper orthogonal matrix, the corresponding S is obtained as a product of two S 's, say S_1, S_2 , in which S_1 corresponds to a special improper orthogonal matrix and S_2 is any corresponding to the general proper orthogonal matrix. Thus the determination of S is reduced to the case when A is proper. Now, by Lemma 2, in suitably chosen orthogonal coordinates, any real proper orthogonal matrix A can be reduced to the direct sum of matrices of the form

$$\begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

But the linear transformation A of the form above in the space Γ can be regarded as a finite form generated by the infinitesimal transformation of type $I + \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \delta\theta$, where θ is a parameter. Thus, any real proper orthogonal transformation A is an integral of an infinitesimal transformation,⁽¹⁾ so that S corresponding to any real proper orthogonal transformation A can be regarded as an integral of an infinitesimal S corresponding to a real infinitesimal orthogonal transformation. If we put $S = I + \sigma$ (σ is infinitesimal), and $A = I + \tau$ (τ is infinitesimal satisfying $\tau^* + \tau = 0$), then, by (7.1), we have

$$t_{ij}^{\circ} \dot{\gamma}_j = \sigma \dot{\gamma}_i - \dot{\gamma}_i \sigma, \quad (7.2)$$

where $\|t_{ij}^{\circ}\| = \tau$. Expanding σ in $\dot{\gamma}_i$'s, from (7.2) we have

$$\sigma = \lambda I + \frac{1}{4} t_{ij}^{\circ} \dot{\gamma}_i \dot{\gamma}_j, \quad (7.3)$$

so that the infinite form of S can be obtained as follows:

$$S = e^{\sigma} = e^{\lambda I} \cdot e^{\frac{1}{4} t_{ij}^{\circ} \dot{\gamma}_i \dot{\gamma}_j}. \quad (7.4)$$

But by Lemma 1, by choosing suitable orthogonal coordinates in Γ , t^{ij} except t^{12} and t^{34} can be equated to zero. Put $t^{12} = \theta$ and $t^{34} = \varphi$; then, by making use of the formulae: $(\dot{\gamma}_1 \dot{\gamma}_2)^2 = (\dot{\gamma}_3 \dot{\gamma}_4)^2 = -I$, we have

$$\left. \begin{aligned} S &= e^{\lambda I} e^{\frac{1}{2} \theta \dot{\gamma}_1 \dot{\gamma}_2} e^{\frac{1}{2} \varphi \dot{\gamma}_3 \dot{\gamma}_4} \\ &= e^{\lambda I} \left(I \cos \frac{\theta}{2} + \dot{\gamma}_1 \dot{\gamma}_2 \sin \frac{\theta}{2} \right) \left(I \cos \frac{\varphi}{2} + \dot{\gamma}_3 \dot{\gamma}_4 \sin \frac{\varphi}{2} \right) \\ &= a \left(I + \tan \frac{\theta}{2} \dot{\gamma}_1 \dot{\gamma}_2 \right) \left(I + \tan \frac{\varphi}{2} \dot{\gamma}_3 \dot{\gamma}_4 \right) \\ &= a \left(I + \tan \frac{\theta}{2} \dot{\gamma}_1 \dot{\gamma}_2 + \tan \frac{\varphi}{2} \dot{\gamma}_3 \dot{\gamma}_4 + \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \dot{\gamma}_5 \right), \end{aligned} \right\} \quad (7.5)$$

(1) The complex proper orthogonal transformation is not necessarily generated by the repetition of an infinitesimal orthogonal transformation.

H. Taber, Bull. New York Math. Soc. **3** (1894), pp. 251-259. or

H. Taber, Proc. Lond. Math. Soc. **21** (1895), pp. 364-376.

where a is an arbitrary numerical factor and $\hat{\gamma}_5 = \hat{\gamma}_1 \hat{\gamma}_2 \hat{\gamma}_3 \hat{\gamma}_4$. Since the coefficients of $\hat{\gamma}_{[i} \hat{\gamma}_{j]}$ in (7.5) are the same as those expressed by (6.6), they satisfy condition (6.8). Conversely, from the discussion in § 6, in a suitable coordinate system in I , S of the form S_1 (cf. Theorem 2) satisfying condition (6.8) can be written as (7.5), and consequently as (7.4). Therefore condition (6.8) is equivalent to the condition that S of the form S_1 is generated by the repetition of an infinitesimal spin transformation corresponding to an infinitesimal orthogonal transformation.

Thus S can be determined also by the infinitesimal method. But the method used in § 2–§ 6 is purely algebraic, whereas the infinitesimal method is analytic. In both methods, however, $\hat{\gamma}_i$ are taken as mere operators; therefore in this sense both methods are abstract.

§ 8. The relation between Cayley's parametrization of an orthogonal matrix and the spin matrix.

If an orthogonal matrix A is given, provided that $\det. |I+A| \neq 0$, we can construct a matrix T such that $T = (I-A)(I+A)^{-1}$. Here T becomes skew-symmetric. This construction of T from A is called Cayley's parametrization, and the orthogonal matrix A in which $\det. |I+A| \neq 0$ is called non-exceptional, and A in which $\det. |I+A| = 0$ is called exceptional.

The spin matrix S leaving the space Γ_4 invariant and reserving the orientation of γ_i is solved for a proper orthogonal matrix $A = \|a_j^i\|$ in (2.6). (ii), (iv) in (2.6) can be rewritten in matrix form as follows:

$$(A-I)A = 2R(A+I) \quad (8.1)$$

$$(A+I)A^5 = R'(A-I) \quad (8.2)$$

where $R = \|A^{ij}\|$, $R' = \|A^{lp} \hat{\epsilon}_{jp}^i\|$ (i denotes the rows and j the columns). Therefore, when A is non-exceptional, $R = \frac{A}{2}(I-A)(I+A)^{-1}$; this shows that $R = -\frac{A}{2}T$, where T is a Cayley's skew-symmetric matrix of A .

Likewise, when $\det. |I-A| \neq 0$, from (8.2) we can determine R' , and consequently R , in matrix form. Therefore, except when $\det. |I+A| = \det. |I-A| = 0$, R is determined in matrix form from (8.1) or (8.2) without our assuming the reality of A . The result of § 3 shows that, for this last exceptional case also, there exists R , provided that A is real.⁽¹⁾

Now, an infinitesimal real orthogonal transformation A can be written as $A = I + \tau$, where infinitesimal matrix τ is real and skew-symmetric. Therefore $A = \left(I + \frac{1}{2}\tau\right) \left(I - \frac{1}{2}\tau\right)^{-1} = \left(I - \left(-\frac{1}{2}\tau\right)\right) \left(I + \left(-\frac{1}{2}\tau\right)\right)^{-1}$. Compar-

(1) In the next paper we shall show that R or R' always exists without the assumption of reality of A , and then determine condition (6.10) for complex A .

ing this with Cayley's parametrization $A=(I-T)(I+T)^{-1}$, we have $T=\frac{1}{2}\tau$. So that, from (7.3), $R=\left\|\frac{1}{4}t^{ij}\right\|=\frac{1}{4}\tau=-\frac{1}{2}T$, i. e. $A=(I+2R)(I-2R)^{-1}$ i. e. $(A-I)=2R(A+I)$. This is simply (8.1). Thus relation (8.1), i. e. the relation between Cayley's parametrization and the spin matrix S , is the finite algebraic form of the relation between the infinitesimal rotation and the corresponding S .

§ 9. Extension of the problem to 8-8 matrices.

We shall extend the problem discussed above to 8-8 matrices. The actual form of 8-8 matrices E_λ satisfying $E_{(\lambda}E_{\mu)}=\delta_{\lambda\mu}I$ has been given by Newman⁽¹⁾ as follows:

$$E_\lambda=S^{-1}\hat{E}_\lambda S, \quad (\lambda=1, 2, \dots, 7) \quad (9.1)$$

where

$$\hat{E}^\alpha=\begin{pmatrix} & i\hat{\gamma}^\alpha \\ -i\hat{\gamma}_\alpha & \end{pmatrix}, \quad (\alpha=1, 2, \dots, 5) \quad \hat{E}_6=\begin{pmatrix} I \\ I \end{pmatrix}, \quad \hat{E}_7=\begin{pmatrix} I \\ -I \end{pmatrix}, \quad (9.2)$$

and $\hat{\gamma}_{(\alpha}\hat{\gamma}_{\beta)}=\delta_{\alpha\beta}I$ ($\alpha, \beta=1, 2, \dots, 5$). Since $\hat{\gamma}_5=\epsilon\hat{\gamma}_1\hat{\gamma}_2\hat{\gamma}_3\hat{\gamma}_4$ ($\epsilon=\pm 1$), E_λ given by (9.1) satisfies the following relations:

$$E_1E_2\dots E_5E_6=i\epsilon E_7. \quad (9.3)$$

But if we are to aim at application to physics, it is desirable that \hat{E}_α ($\alpha=1, 2, \dots, 5$) should have the form $\hat{E}_\alpha=\begin{pmatrix} A_\alpha & 0 \\ 0 & B_\alpha \end{pmatrix}$, where A_α and B_α are 4-4 matrices. To find such \hat{E}_α , from $\hat{E}_{(\alpha}\hat{E}_{\beta)}=\delta_{\alpha\beta}I$, $A_{(\alpha}A_{\beta)}=B_{(\alpha}B_{\beta)}=\delta_{\alpha\beta}I$, so that of necessity $A_\alpha=\bar{\gamma}_\alpha$ and $B_\alpha=\bar{\gamma}_\alpha$.⁽²⁾ If we put

$$\hat{E}_\lambda(\lambda=6,7)\equiv\begin{pmatrix} X_\lambda & Y_\lambda \\ Z_\lambda & U_\lambda \end{pmatrix},$$

$X_\lambda, Y_\lambda, Z_\lambda$, and U_λ being 4-4 matrices), from $\hat{E}_{(\alpha}\hat{E}_{\beta)}=0$ we have

$$\left. \begin{aligned} \text{(i)} & \quad \hat{\gamma}_\alpha X_\lambda + X_\lambda \hat{\gamma}_\alpha = 0, \\ \text{(ii)} & \quad \bar{\gamma}_\alpha U_\lambda + U_\lambda \bar{\gamma}_\alpha = 0, \\ \text{(iii)} & \quad \hat{\gamma}_\lambda Y_\lambda + Y_\lambda \hat{\gamma}_\alpha = 0, \\ \text{(iv)} & \quad \bar{\gamma}_\alpha Z_\lambda + Z_\lambda \bar{\gamma}_\alpha = 0. \end{aligned} \right\} \quad (9.4)$$

From (i) and (ii) we have $X_\lambda=U_\lambda=0$; and since $\bar{\gamma}_\alpha$ can always be written as follows:

(1) M. H. A. Newman: loc. cit.

(2) $\bar{\gamma}_\alpha$ does not mean conjugate imaginary of $\hat{\gamma}_\alpha$, but another matrix satisfying $\bar{\gamma}_{(\alpha}\bar{\gamma}_{\beta)}=\delta_{\alpha\beta}I$.

$$\begin{aligned}\bar{\dot{\gamma}}_i &= T^{-1}h_i^r\dot{\gamma}_rT, \\ \bar{\dot{\gamma}}_5 &= T^{-1}\dot{\gamma}_5T,\end{aligned}\quad \left(\sum_{r=1}^4 h_i^r h_j^r = \delta_{ij}, \quad i, j, r=1, 2, \dots, 4\right)$$

from (iii),

$$\begin{aligned}\dot{\gamma}_i Y_\lambda + Y_\lambda T^{-1}h_i^k \dot{\gamma}_k T &= 0, \quad \text{i. e.} \quad \dot{\gamma}_i = -Y_\lambda T^{-1}h_i^k \dot{\gamma}_k T Y_\lambda^{-1}, \\ \dot{\gamma}_5 Y_\lambda + Y_\lambda T^{-1}\dot{\gamma}_5 T &= 0, \quad \text{i. e.} \quad \dot{\gamma}_5 = -Y_\lambda T^{-1}\dot{\gamma}_5 T Y_\lambda^{-1}.\end{aligned}$$

($\det. |\hat{E}_\lambda| \neq 0$, $\therefore \det. |Y_\lambda|$, $\det. |Z_\lambda| \neq 0$). Then, by Theorem 1, TY_λ^{-1} must have the form S_2 ; therefore the matrix $\|h_j^i\|$ must be improper; so that $\dot{\gamma}_i$ and $\bar{\dot{\gamma}}_i$ are of opposite orientations. Then it is possible to find a 4-4 matrix V such that

$$\left. \begin{aligned}\text{(i)} \quad \bar{\dot{\gamma}}_i &= T^{-1}h_i^r \dot{\gamma}_r T = -V^{-1}\dot{\gamma}_i V, \\ \text{(ii)} \quad \bar{\dot{\gamma}}_5 &= T^{-1}\dot{\gamma}_5 T = -V^{-1}\dot{\gamma}_5 V.\end{aligned} \right\} \quad (9.5)$$

For, $VT^{-1}h_i^r \dot{\gamma}_r TV^{-1} = -\dot{\gamma}_i$ can always be solved with respect to TV^{-1} for given h_j^i and $\dot{\gamma}_i$. And we see that the solution TV^{-1} satisfies (ii) of (9.5), because $\det. |h_j^i| = -1$. When TV^{-1} is found, V is determined, i. e. there exists V satisfying (9.5). Then (iii) and (iv) of (9.4) become:

$$\left. \begin{aligned}\text{(i)} \quad \dot{\gamma}_a Y_\lambda - Y_\lambda V^{-1}\dot{\gamma}_a V &= 0, \quad \text{i. e.} \quad \dot{\gamma}_a Y_\lambda V^{-1} - Y_\lambda V^{-1}\dot{\gamma}_a = 0, \\ \text{(ii)} \quad -V^{-1}\dot{\gamma}_a V Z_\lambda + Z_\lambda \dot{\gamma}_a &= 0, \quad \text{i. e.} \quad \dot{\gamma}_a V Z_\lambda - V Z_\lambda \dot{\gamma}_a = 0,\end{aligned} \right\} \quad (9.6)$$

$$\therefore \quad Y_\lambda V^{-1} = a_\lambda I, \quad V Z_\lambda = b_\lambda I.$$

Therefore

$$\hat{E}_a = \begin{pmatrix} \dot{\gamma}_a & \\ & -V^{-1}\dot{\gamma}_a V \end{pmatrix}, \quad \hat{E}_\lambda = \begin{pmatrix} a_\lambda V & \\ b_\lambda V^{-1} & \end{pmatrix},$$

and from $\hat{E}_\lambda \hat{E}_\lambda = I$, $a_\lambda b_\lambda = 1$, and from $\hat{E}_\lambda \hat{E}_\mu + \hat{E}_\mu \hat{E}_\lambda = 0$ ($\lambda \neq \mu$), $a_\lambda b_\mu + b_\mu a_\lambda = 0$, i. e. $b_\lambda = \frac{1}{a_\lambda}$ and $a_\lambda^2 + a_\mu^2 = 0$. Thus we have:

$$\hat{E}_\lambda = \begin{pmatrix} \dot{\gamma}_a & \\ & -V^{-1}\dot{\gamma}_a V \end{pmatrix}, \quad \hat{E}_6 = \begin{pmatrix} aV & \\ \frac{1}{a}V & \end{pmatrix}, \quad \hat{E}_7 = \begin{pmatrix} \pm iaV & \\ \mp \frac{i}{a}V & \end{pmatrix}. \quad (9.7)$$

Specially, if we put $V = \dot{\gamma}_4$ and $a = 1$, we have

$$\hat{E}_a + \begin{pmatrix} \dot{\gamma}_a & \\ & \dot{\gamma}_a \end{pmatrix}, \quad \hat{E}_4 = \begin{pmatrix} \dot{\gamma}_4 & \\ & -\dot{\gamma}_4 \end{pmatrix}, \quad \hat{E}_5 = \begin{pmatrix} \dot{\gamma}_5 & \\ & \dot{\gamma}_5 \end{pmatrix}, \quad \hat{E}_6 = \begin{pmatrix} \dot{\gamma}_4 & \\ & \dot{\gamma}_4 \end{pmatrix}, \quad \hat{E}_7 = \begin{pmatrix} -i\dot{\gamma}_4 & \\ & i\dot{\gamma}_4 \end{pmatrix}. \quad (9.8)$$

If we take $\dot{\gamma}_5$ such that $\dot{\gamma}_5 = \dot{\gamma}_1 \dot{\gamma}_2 \dot{\gamma}_3 \dot{\gamma}_4$, we have $\hat{E}_1 \hat{E}_2 \dots \hat{E}_6 = i\hat{E}_7$; and (9.7) and (9.8) are the required form of E_λ .

Next we shall consider the general case when $E_{(\alpha} E_{\beta)} = g_{\alpha\beta} I$ ($\alpha, \beta = 1, 2, \dots, 6$). This exists then h_β^α , such that

$$\sum_{\gamma=1}^6 h_a^\gamma h_\beta^\gamma = g_{a\beta}. \quad (9.9)$$

Any matrices E_a satisfying $E_{(a}E_{\beta)} = g_{a\beta}I$ are given by $E_a = h_a^\beta \hat{E}_\beta$, where \hat{E}_a are suitable 8-8 matrices satisfying $\hat{E}_{(a}\hat{E}_{\beta)} = \delta_{a\beta}I$. Then, by (9.1), the general forms of E_a are given as follows:

$$E_a = S^{-1}h_a^\beta \hat{E}_\beta S. \quad (9.10)$$

Likewise, if we consider E_i such that $E_{(i}E_{j)} = g_{ij}I$ ($i, j=1, 2, 3, 4$) the general forms of E_i are given as follows:

$$E_i = S^{-1}h_i^j \hat{E}_j S, \quad (9.11)$$

where $\sum_{r=1}^4 h_i^r h_j^r = g_{ij}$ and \hat{E}_i are any 8-8 matrices satisfying $\hat{E}_{(i}\hat{E}_{j)} = \delta_{ij}I$.

In 4-4 matrix, $I, \gamma_5, \gamma_5, \gamma_5 \gamma_5$ and $\gamma_{[i}\gamma_{j]}$ from a basis, provided that $\gamma_5 = \pm \frac{1}{\sqrt{\det. |g_{ij}|}} \gamma_{[1}\gamma_2\gamma_3\gamma_4]$, where $\gamma_{(i}\gamma_{j)} = g_{ij}I$. Likewise we know that, if $g_{a\beta}$ is given, the basis of 8-8 matrix is obtained as follows:

$$I, E_a, E_\gamma, E_a E_\gamma, E_{[a}E_{\beta]}, E_{[a}E_{\beta]}E_\gamma, E_{[a}E_{\beta]}E_{\gamma]},$$

where E_a are determined by (9.10) and $E_\beta = \pm \frac{i}{\sqrt{\det. |g_{a\beta}|}} E_{[1}E_2 \dots E_6]$. But if g_{ij} is given, E_i are given by (9.11), and there more E_5, E_6, E_7 are added in the forms $S^{-1}E_5 S, S^{-1}E_6 S, S^{-1}E_7 S$ respectively. Thus two cases occur: (1) when the fundamental tensor of 6-dimensional Riemannian space is given, (2) when the fundamental tensor of 4-dimensional Riemannian space is given. But case (1) looks, at present, physically meaningless, therefore we shall describe only the result.

In case (1) we consider the space Γ constituted by all E_a ($= h_a^\beta \hat{E}_\beta$) ($a, \beta=1, 2, \dots, 6$) where \hat{E}_a are fixed and h_a^β may take all the values satisfying $\sum_{\gamma=1}^6 h_a^\gamma h_\beta^\gamma = g_{a\beta}$. As in Γ_4, F_8 splits into certain sub-spaces R_3, S_3, \dots such that elements of the same sub-space are related to one another by real orthogonal transformations. Then the set $\bar{\mathcal{S}}$ of operators S which leave any sub-space, say R_3 invariant, i.e. $S^{-1}R_3 S = R_3$, consists of two parts \mathcal{S}_1 and \mathcal{S}_2 .⁽¹⁾ \mathcal{S}_1 consists of S 's which have the form $\Lambda I + \Lambda^\gamma \hat{E}_\gamma + \Lambda^{\lambda\mu} \hat{E}_\lambda \hat{E}_\mu + \Lambda^{\lambda\mu\tau} \hat{E}_\lambda \hat{E}_\mu \hat{E}_\tau \equiv S_1$, and whose coefficients $\Lambda, \Lambda^\gamma, \Lambda^{\lambda\mu}$, and $\Lambda^{\lambda\mu\tau}$ satisfying the following relations:

$$\Lambda \Lambda^{\lambda\mu\tau} + \frac{i}{4} \hat{e}_{\lambda\mu}^{\rho\sigma\nu} \Lambda^{\rho\sigma} \Lambda^{\omega\nu} = 0,$$

$$(\Lambda)^2 \Lambda^\gamma - \frac{i}{6} \hat{e}_{\lambda\mu\nu\rho\sigma} \Lambda^{\lambda\mu} \Lambda^{\omega\nu} \Lambda^{\rho\sigma} = 0,$$

(1) The trivial one $S=0$ is excluded.

where $\hat{\epsilon}_{\lambda\mu\nu\rho\sigma} = 0$ when any two of $(\lambda\mu\nu\rho\sigma)$ are equal,
 $= 1$ when $(\lambda\mu\nu\rho\sigma)$ is an even permutation of $(12\dots 6)$,
 $= -1$ when $(\lambda\mu\nu\rho\sigma)$ is an odd permutation of $(12\dots 6)$;

\mathfrak{S}_2 consists of S 's which have the form $\Lambda^\lambda \hat{E}_\lambda + \Lambda^{\lambda'} \hat{E}_{\lambda'} + \Lambda^{\lambda''} \hat{E}_{\lambda''} \hat{E}_{\lambda''} \hat{E}_{\lambda''} \equiv S_2$,
and whose coefficients Λ^λ , $\Lambda^{\lambda'}$, and $\Lambda^{\lambda''}$ satisfy the following relations:

$$\begin{aligned}\Lambda^\lambda \Lambda^{\mu\nu\omega} \hat{\epsilon}_{\lambda\mu\nu\omega\rho\sigma} &= 0, \\ \Lambda_\lambda \Lambda^{\lambda'} &= 0, \\ \Lambda^\lambda \Lambda^{\mu'} - \frac{3}{2} i \hat{\epsilon}_{\tau\omega\nu\rho\sigma} \Lambda^{\tau\omega\nu} \Lambda^{\lambda\rho\sigma} &= 0. \quad (\lambda \neq \mu)\end{aligned}$$

In the equation above Λ , $i\Lambda^{\lambda'}$, $\Lambda^{\lambda''}$, $i\Lambda^{\lambda''}$, or Λ^λ , $i\Lambda^{\lambda'}$, $\Lambda^{\lambda''}$, are real except for a common factor. The elements S of \mathfrak{S}_1 reserves the orientation of E_λ of R_8 , and S of \mathfrak{S}_2 changes the orientation of E_λ of R_8 .

As in 4-4 matrix, if we consider the space \tilde{R}_8 constituted by $E_\alpha (= \tilde{h}_\alpha^\beta \tilde{E}_\beta)$ where \tilde{E}_α are fixed and $\tilde{h}_\alpha^\gamma \tilde{h}_\beta^\delta g_{\gamma\delta} = g_{\alpha\beta}$, the same result is obtained, Λ , Λ^λ , ... and $\hat{\epsilon}_{\lambda\mu\nu\rho\sigma}$ being replaced by $\tilde{\Lambda}$, $\tilde{\Lambda}^\lambda$, ...: and $\tilde{\epsilon}_{\lambda\mu\nu\rho\sigma} = \pm \sqrt{\det |g_{\alpha\beta}|} \cdot \hat{\epsilon}_{\lambda\mu\nu\rho\sigma}$ respectively, where $\tilde{\Lambda}$, $\tilde{\Lambda}^\lambda$, ... are the coefficients of expansion of S with respect to \tilde{E}_λ . The only difference is that

$$\tilde{h}_\alpha^\gamma \tilde{h}_\mu^\beta \left(\tilde{\Lambda}^\lambda \tilde{\Lambda}^{\mu\eta} - \frac{3}{2} i \tilde{\epsilon}_{\tau\omega\nu\rho\sigma} \tilde{\Lambda}^{\tau\omega\nu} \tilde{\Lambda}^{\lambda\rho\sigma} \right) = 0 \quad (\alpha \neq \beta)$$

instead of $\Lambda^\lambda \Lambda^{\mu'} - \frac{3}{2} i \hat{\epsilon}_{\tau\omega\nu\rho\sigma} \Lambda^{\tau\omega\nu} \Lambda^{\lambda\rho\sigma} = 0$ ($\lambda \neq \mu$) where

$$\tilde{E}_\alpha = h_\alpha^\beta \hat{E}_\beta, \quad \sum_{\lambda=1}^6 h_\alpha^\lambda h_\beta^\lambda = g_{\alpha\beta}, \quad \text{and} \quad \hat{E}_{(\alpha} \hat{E}_{\beta)} = \delta_{\alpha\beta} I.$$

These theorems can be extended to $2^n \cdot 2^n$ matrix or to corresponding operator (n : positive integer) when the metric $g_{\lambda\mu}$ of $2n$ -dimensional Riemannian space is given.⁽¹⁾ If the metric $g_{\lambda\mu}$ of $(2n+1)$ -dimensional Riemannian space is given, $\gamma_1, \gamma_2, \dots, \gamma_{2n}$ and $i^n \gamma_1 \gamma_2 \dots \gamma_{2n} = \gamma_{2n+1}$ play the rôles of $\gamma_1, \gamma_2, \gamma_3$, and γ_4 in 4-4 matrix, and consequently the problem is reduced to the case when the metric of even-number-dimensional Riemannian space is given.⁽²⁾

Case (2) is treated in the next section.

§ 10. Classification of 8-8 matrix S by the orientations of 4-dimensional vector space.

In § 9 we have seen that any 8-8 matrices E_i satisfying $E_{(i} E_{j)} = g_{ij} I$ are given by

(1) The general question for $2^n \cdot 2^n$ matrix is treated directly in the last section.

(2) Brauer and Weyl, loc. cit.

$$E_c = S^{-1} h_i^j \hat{E}_j S \quad (i, j = 1, 2, \dots, 4), \quad (10.1)$$

where $\sum_{r=1}^4 h_i^r h_j^r = g_{ij}$ and $\hat{E}_i \hat{E}_j = \delta_{ij} I$. In the following section we use the letters of indices as follows:

$$\begin{aligned} i, j, \dots, r, s, \dots &= 1, 2, 3, 4, \\ x, y, \dots &= 5, 6, \\ \alpha, \beta, \dots, \lambda, \mu, \dots &= 1, 2, \dots, 6. \end{aligned}$$

As in the case of 4-4 matrices, we consider the space Γ'_4 constituted by all $E_i (= h_i^r \hat{E}_r)$ where \hat{E}_i are fixed and h_j^i may take all the values satisfying the relations $\sum_{r=1}^4 h_i^r h_j^r = g_{ij}$, and we investigate, the properties of S such that $'E_i = S^{-1} E_i S$ for any given E_i and $'E_i$ where $E_i = h_i^j \hat{E}_j$ and $'E_i = k_i^j \hat{E}_j$. If we put $H \equiv \|h_j^i\|$ and $K \equiv \|k_j^i\|$, then $H^* H = K^* K = G (= \|g_{ij}\|)$, and $HK^{-1} \equiv A (= \|a_{ij}\|)$ becomes an orthogonal matrix. Here we assume that A is real, i. e. as in the case of 4-4 matrices we consider any one sub-space, say R'_4 . We say that E_i and $'E_i$ have the same, or opposite, orientations according as A is proper or improper. From $'E_i = k_i^j \hat{E}_j = S^{-1} E_i S = S^{-1} h_i^j \hat{E}_j S$, we have

$$\hat{E}_i = S^{-1} a_i^j \hat{E}_j S \quad (10.2)$$

If we take \hat{E}_λ ($\lambda = 1, 2, \dots, 6$) and $i\hat{E}_7 = \hat{E}_1 \hat{E}_2 \dots \hat{E}_6$, and expand S as follows:

$$S = \Lambda I + \Lambda^\lambda \hat{E}_\lambda + \Lambda^\tau \hat{E}_7 + \Lambda^{\mu\lambda} \hat{E}_\mu \hat{E}_\nu + \Lambda^{\lambda\tau} \hat{E}_\lambda \hat{E}_7 + \Lambda^{\lambda\mu\nu} \hat{E}_\lambda \hat{E}_\mu \hat{E}_\nu + \Lambda^{\lambda\mu\tau} \hat{E}_\lambda \hat{E}_\mu \hat{E}_7, \quad (10.3)$$

where $\Lambda^{\lambda\mu} = -\Lambda^{\mu\lambda}$, $\Lambda^{\lambda\mu\tau} = -\Lambda^{\mu\lambda\tau}$ and $\Lambda^{\lambda\mu\nu} = \Lambda^{[\lambda\mu\nu]}$; then, substituting (10.3) into (10.2), and making use of the identities:

$$\hat{E}_\lambda \hat{E}_\mu \hat{E}_\nu \hat{E}_\omega = -\frac{i}{2} \epsilon_{\lambda\mu\nu\omega}^{\dots\rho\sigma} \hat{E}_\rho \hat{E}_\sigma \hat{E}_7, \quad (\lambda, \mu, \nu, \omega \neq 7)$$

$$\hat{E}_\lambda \hat{E}_\mu \hat{E}_\nu \hat{E}_7 = \frac{i}{6} \epsilon_{\lambda\mu\nu}^{\dots\rho\sigma\tau} \hat{E}_\rho \hat{E}_\sigma \hat{E}_\tau, \quad (\lambda, \mu, \nu \neq 7)$$

we have:

$$\left. \begin{aligned} \text{(i)} \quad & (a_i^k - \delta_i^k) \Lambda_k = 0, \\ \text{(ii)} \quad & (a_i^\lambda - \delta_i^\lambda) \Lambda + 2(a_i^k + \delta_i^k) \Lambda_k{}^\lambda = 0, \\ \text{(iii)} \quad & (a_i^k + \delta_i^k) \Lambda_k{}^7 = 0, \\ \text{(iv)} \quad & (a_i^{[\lambda} + \delta_i^{[\lambda} \Lambda^{\mu\lambda]} + 3(a_i^k - \delta_i^k) \Lambda_k{}^{\lambda\mu} = 0, \\ \text{(v)} \quad & (a_i^\lambda + \delta_i^\lambda) \Lambda^\tau + 2(a_i^k - \delta_i^k) \Lambda_k{}^{\lambda\tau} = 0, \\ \text{(vi)} \quad & (a_i^{[\lambda} - \delta_i^{[\lambda} \Lambda^{\mu\nu]} + \frac{i}{6} (a_i^k + \delta_i^k) \Lambda^{\epsilon\rho\tau} \epsilon_{k\epsilon\rho}^{\dots\lambda\mu\nu} = 0, \\ \text{(vii)} \quad & (a_i^{[\lambda} - \delta_i^{[\lambda} \Lambda^{\mu\tau]} - \frac{i}{2} (a_i^k + \delta_i^k) \Lambda^{\epsilon\rho\sigma} \epsilon_{k\epsilon\rho\sigma}^{\dots\lambda\mu} = 0, \end{aligned} \right\} \quad (10.4)$$

where $a_i^x = 0$.

When $A = \|a_j^i\|$ is proper, since A is a real matrix, by Lemma 2 there exists a real orthogonal matrix $T = \|t_j^i\|$ such that

$$T^{-1}AT = \tilde{A} \equiv \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} + \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix}.$$

Put $\tilde{A} = \|\tilde{a}_j^i\|$ and $t_j^i \hat{E}_j = {}' \hat{E}_{ij}$; then ${}' \hat{E}_i \hat{E}_j = \delta_{ij} I$. Substituting this into (10.2), we have

$${}' \hat{E}_i = S^{-1} \tilde{a}_i^j {}' \hat{E}_j S. \quad (10.5)$$

If we put $i {}' \hat{E}_7 = {}' \hat{E}_1 {}' \hat{E}_2 \dots {}' \hat{E}_6$ then ${}' \hat{E}_7 = \epsilon {}' \hat{E}_7$ where $\epsilon = \det. |T|$. Therefore ${}' \hat{E}_a$ and ${}' \hat{E}_7$ can be regarded as the basis, and S can be expanded in ${}' \hat{E}_i$'s. We shall use the letters of indices as follows:

$$\begin{aligned} i, j, \dots, r, s, \dots &= 1, 2, 3, 4, \\ a, b, &= 1, 2, \\ p, q, &= 3, 4, \\ x, y, &= 5, 6. \end{aligned}$$

In what follows for simplicity dropping ripples and dashes, we write a_j^i and $\Lambda, \Lambda^1, \dots$ instead of \tilde{a}_j^i and ${}' \Lambda, {}' \Lambda^1, \dots$ etc. ($\Lambda, \Lambda^1, \dots$ are the coefficients of expansion of S with respect to ${}' \hat{E}_i$'s). Then, as with 4-4 matrices, as the general solutions of (10.5) we have:

Λ : arbitrary,

$\Lambda^i = 0$; Λ^x, Λ^7 : arbitrary,

$$\Lambda^{ix} = \Lambda^{i7} = 0; \quad \Lambda^{xp} = 0, \quad \Lambda^{12} = \frac{1}{2} \tan \frac{\theta}{2} \Lambda, \quad \Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda,$$

$$\Lambda^{56} = -\frac{i}{2} \cot \frac{\theta}{2} \cot \frac{\varphi}{2} \Lambda^7, \quad \Lambda^{57} = i \cot \frac{\theta}{2} \cot \frac{\varphi}{2} \Lambda^6, \quad \Lambda^{67} = -i \cot \frac{\theta}{2} \cot \frac{\varphi}{2} \Lambda^5,$$

$$\Lambda^{ijk} = \Lambda^{ixy} = \Lambda^{ix7} = 0; \quad \Lambda^{xpx} = \Lambda^{x77} = 0,$$

$$\Lambda^{125} = -\frac{1}{6} \cot \frac{\theta}{2} \Lambda^5; \quad \Lambda^{345} = -\frac{1}{6} \cot \frac{\varphi}{2} \Lambda^5,$$

$$\Lambda^{126} = -\frac{1}{6} \cot \frac{\theta}{2} \Lambda^6; \quad \Lambda^{346} = -\frac{1}{6} \cot \frac{\varphi}{2} \Lambda^6,$$

$$\Lambda^{127} = -\frac{1}{2} \cot \frac{\theta}{2} \Lambda^7; \quad \Lambda^{347} = -\frac{1}{2} \cot \frac{\varphi}{2} \Lambda^7,$$

$$\Lambda^{457} = -\frac{i}{2} \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \Lambda.$$

(10.6)

(Calculations are found in Note.)

So that S is given as follows:

$$S = S_0 \left(I + \tan \frac{\theta}{2} \hat{E}_1 \hat{E}_2 + \tan \frac{\varphi}{2} \hat{E}_3 \hat{E}_4 - i \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \hat{E}_5 \hat{E}_6 \hat{E}_7 \right) \quad (10.7)$$

where

$$S_0 = \Lambda I + 2\Lambda^{56} \hat{E}_5 \hat{E}_6 + \Lambda^{57} \hat{E}_5 \hat{E}_7 + \Lambda^{67} \hat{E}_6 \hat{E}_7. \quad (10.8)$$

Here $S_0^{-1} \hat{E}_i S_0 = \hat{E}_i$, provided that there exists S_0^{-1} , and conversely, by putting $\theta = \varphi = 0$ in (10.6),⁽¹⁾ S_0 such as $S_0^{-1} \hat{E}_i S_0 = \hat{E}_i$ is obtained in the form (10.8). But, to avoid the indefiniteness of

$$I + \tan \frac{\theta}{2} \hat{E}_1 \hat{E}_2 + \tan \frac{\varphi}{2} \hat{E}_3 \hat{E}_4 - i \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \hat{E}_5 \hat{E}_6 \hat{E}_7$$

when θ or $\varphi \equiv \pi \pmod{2\pi}$, we rewrite (10.7) as follows:

$$\begin{aligned} S &= S_0 \cdot \alpha \left(I + \tan \frac{\theta}{2} \hat{E}_1 \hat{E}_2 + \tan \frac{\varphi}{2} \hat{E}_3 \hat{E}_4 - i \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \hat{E}_5 \hat{E}_6 \hat{E}_7 \right) \\ &= S_0 (\lambda I + 2\lambda^{12} \hat{E}_1 \hat{E}_2 + 2\lambda^{34} \hat{E}_3 \hat{E}_4 + \lambda^{567} \hat{E}_5 \hat{E}_6 \hat{E}_7) \end{aligned} \quad (10.9)$$

where $\lambda = \alpha$, $\lambda^{12} = \frac{\alpha}{2} \tan \frac{\theta}{2}$, $\lambda^{34} = \frac{\alpha}{2} \tan \frac{\varphi}{2}$, $\lambda^{567} = -i\alpha \tan \frac{\theta}{2} \tan \frac{\varphi}{2}$. Thus for any given E_i and E_j of R_4 , S such as $E_i = S^{-1} E_j S$ is determined uniquely except for an element S_0 . But $\Lambda, \Lambda^\lambda, \dots, \lambda, \lambda^{12}, \dots$ etc. here evaluated are in the dash-system; therefore, returning to the undashed system, we have:

$$S = S_0 (\lambda I + \lambda^{ij} \hat{E}_i \hat{E}_j + \lambda^{567} \hat{E}_5 \hat{E}_6 \hat{E}_7) \quad (10.10)$$

where $S_0 = \Lambda I + 2\Lambda^{56} \hat{E}_5 \hat{E}_6 + \Lambda^{57} \hat{E}_5 \hat{E}_7 + \Lambda^{67} \hat{E}_6 \hat{E}_7$, and $\lambda, \lambda^{ij}, \lambda^{567}$ are real except for a common factor. In the dash-system, eliminating θ, φ , we have $\lambda' \lambda^{567} + 4i \lambda^{12} \lambda^{34} = 0$; therefore in the undashed system we have

$$\lambda \lambda^{567} + \frac{i}{2} \epsilon_{ijkl} \lambda^{ij} \lambda^{kl} = 0. \quad (10.11)$$

As with 4-4 matrices, any S which transforms E_i to E'_i ($\in R'_4$) of the opposite orientation is expressed as a product a special S which interchanges the orientations, and general S which preserves the orientations; thus, for example, S is expressed as $S = S' \hat{E}_4$ where S' mediates E_i 's of the same orientations. Thus any S which changes the orientations has the following form:

$$S = S_0 (\Lambda^i \hat{E}_i + \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k). \quad (10.12)$$

and Λ^i, Λ^{ijk} are real except for a common factor. Now,

$$\Lambda^i \hat{E}_i + \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k = (\Lambda^4 + \Lambda^a \hat{E}_a \hat{E}_4 + 3\Lambda^{4ab} \hat{E}_a \hat{E}_b - 6i\Lambda^{123} \hat{E}_5 \hat{E}_6 \hat{E}_7) \hat{E}_4.$$

(1) Cf. Note (N. 4).

(2) The fact that (10.6) is a general solution is destroyed when S is factorized as (10.7); but if we factorize S as (10.9), the generality of solution (10.6) is not destroyed. Cf. § 3.

Therefore, the condition⁽¹⁾ for S of the form $S_2 = \Lambda^i \hat{E}_i + \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k$ to mediate E_i 's of R_4 is obtained by substituting the equation above into (10.11) as follows:

$$\hat{\epsilon}_{ijkl} \Lambda^i \Lambda^{jkl} = 0. \quad (10.13)$$

Next, to find the condition for the existence of the inverse of S of the form (10.10) or (10.12), put

$$S_0 \equiv \Lambda I + \Lambda^{xy} \hat{E}_x \hat{E}_y, \quad (x, y = 5, 6, 7)$$

$$S_1 \equiv \lambda I + \lambda^{ij} \hat{E}_i \hat{E}_j + \lambda^{567} \hat{E}_5 \hat{E}_6 \hat{E}_7,$$

$$S_2 \equiv \Lambda^i \hat{E}_i + \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k;$$

then

$$S_0(\Lambda I - \Lambda^{xy} \hat{E}_x \hat{E}_y) = \{(\Lambda)^2 + 2\Lambda^{xy}\} I, \quad (10.14)$$

$$S_1(\lambda I - \lambda^{ij} \hat{E}_i \hat{E}_j + \lambda^{567} \hat{E}_5 \hat{E}_6 \hat{E}_7) = \{(\lambda)^2 - (\lambda^{567})^2 + 2\lambda^{ij} \lambda_{ij} \Lambda_{xy}\} I \\ + \{2\lambda \lambda^{567} + i \hat{\epsilon}_{ijkl} \lambda^{ij} \lambda^{kl}\} \hat{E}_5 \hat{E}_6 \hat{E}_7 \quad (10.15)$$

$$S_2(\Lambda^i \hat{E}_i - \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k) = \{\Lambda^i \Lambda_i + 6\Lambda^{ijk} \Lambda_{ijk}\} I + 2i \hat{\epsilon}_{ijkl} \Lambda^i \Lambda^{kl} \hat{E}_5 \hat{E}_6 \hat{E}_7. \quad (10.16)$$

From (10.14) for S_0 such that $(\Lambda)^2 + 2\Lambda^{xy} \Lambda_{xy} = 0$, we have $S_0^{-1} = \frac{1}{(\Lambda)^2 + 2\Lambda^{xy} \Lambda_{xy}} \times (\Lambda I - \Lambda^{xy} \hat{E}_x \hat{E}_y)$. The inverse of S_1 which satisfies relation

(10.11) and whose coefficients $\lambda, \lambda^{ij}, i\lambda^{567}$ are real except for a common factor, from (10.15) is obtained as $S_1^{-1} = \frac{1}{\lambda^2 - (\lambda^{567})^2 + 2\lambda^{ij} \lambda_{ij}} [\lambda I + \lambda^{567} \hat{E}_5 \hat{E}_6 \hat{E}_7 - \lambda^{ij} \hat{E}_i \hat{E}_j]$,

$S=0$ being excluded. Next, for S_2 which satisfies the relation (10.12), and whose coefficients Λ^i, Λ^{ijk} are real except for a common factor, from (10.15)

we have $S_2^{-1} = \frac{1}{\Lambda^i \Lambda_i + 6\Lambda^{ijk} \Lambda_{ijk}} (\Lambda^i \hat{E}_i - \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k)$, $S=0$ being excluded.

And $(S_0 S_1)^{-1}$ or $(S_0 S_2)^{-1}$ is equal to $S_1^{-1} S_0^{-1}$ or $S_2^{-1} S_0^{-1}$ respectively, i. e. the condition that there exists the inverse of $S_0 S_1$ or $S_0 S_2$ is that there exist the inverses of both S_0 and S_1 or both S_0 and S_2 .

Thus we have the following theorem.

Theorem 3. *The set \mathfrak{S} of operators S which leave the space R_4 invariant consists of two parts \mathfrak{S}_1 and \mathfrak{S}_2 . \mathfrak{S}_1 consists of operators S which have the form $S_0 S_1$ and consists of operators S which have the form $S_0 S_2$, where*

$$S_0 = \Lambda I + \Lambda^{xy} \hat{E}_x \hat{E}_y \quad (x, y = 5, 6, 7), \quad (\Lambda)^2 + 2\Lambda^{xy} \Lambda_{xy} \neq 0;$$

$$S_1 = \lambda I + \lambda^{ij} \hat{E}_i \hat{E}_j + \lambda^{567} \hat{E}_5 \hat{E}_6 \hat{E}_7, \quad \lambda, \lambda^{ij}, \lambda^{567} \text{ are real except for a common factor};$$

$$S_2 = \Lambda^i \hat{E}_i + \Lambda^{ijk} \hat{E}_i \hat{E}_j \hat{E}_k, \quad \Lambda^i, \Lambda^{ijk} \text{ are real except for a common factor};$$

and their coefficients satisfy the following relations:

(1) Not the sufficient condition, but the necessary condition. Provided that the inverse of S exists, it is the necessary and sufficient condition.

$$\lambda\lambda^{567} + \frac{i}{2}\epsilon_{ijkl}\lambda^{ij}\lambda^{kl} = 0, \quad (S_1 = 0 \text{ is excluded})$$

$$\epsilon_{ijkl}A^iA^{jkl} = 0. \quad (S_2 = 0 \text{ is excluded})$$

Here $\hat{E}_{(i}\hat{E}_{x)} = 0$, $\hat{E}_{(x}\hat{E}_{y)}I$, and $i\hat{E}_7 = \hat{E}_1\hat{E}_2\dots\hat{E}_6$. S_0 is an identical transformation in I'_4 . The operator S of \mathfrak{S}_1 reserves the orientation of an element of R'_4 , and S of \mathfrak{S}_2 changes the orientation of an element of R'_4 . For any two given elements E_i and $'E_i$ of R'_4 , S such that $S^{-1}E_iS = 'E_i$ is determined uniquely except for S_0 .

With respect to \hat{E}_λ given by (9.8) in which, as $\hat{\gamma}_\lambda$ ($\lambda=1, 2, \dots, 5$), we take Dirac's matrices, the forms of S_0, S_1, S_2 are given as follows:

$$\left. \begin{aligned} S_0 &= \left(\begin{array}{c|c} aI & \begin{array}{c} 0 \\ \times \\ \times \\ 0 \end{array} \\ \hline \begin{array}{c} 0 \\ \times \\ \times \\ 0 \end{array} & bI \end{array} \right), \text{ where } a \text{ and } b \text{ are arbitrary numbers,} \\ S_1 &= \left(\begin{array}{c|c} \begin{array}{c} \times \\ 0 \\ 0 \\ 0 \end{array} & \begin{array}{c} 0 \\ \times \\ \times \\ 0 \end{array} \\ \hline \begin{array}{c} 0 \\ \times \\ \times \\ 0 \end{array} & \begin{array}{c} 0 \\ 0 \\ 0 \\ \times \end{array} \end{array} \right), \quad S_2 = \left(\begin{array}{c|c} \begin{array}{c} 0 \\ \times \\ \times \\ 0 \end{array} & \begin{array}{c} 0 \\ 0 \\ 0 \\ \times \end{array} \\ \hline \begin{array}{c} 0 \\ \times \\ \times \\ 0 \end{array} & \begin{array}{c} 0 \\ 0 \\ 0 \\ \times \end{array} \end{array} \right). \end{aligned} \right\} (10.17)$$

Here $E_i = h_i^k \hat{E}_k = \begin{pmatrix} \gamma_i \\ \bar{\gamma}_i \end{pmatrix}$, where $\gamma_i = h_i^k \hat{\gamma}_k$, $\bar{\gamma}_i = k_i^k \hat{\gamma}_k$ and

$$h_i^a = h_i^a, \quad k_i^4 = -h_i^4 \quad a=1, 2, 3 \quad \text{and} \quad i=1, 2, 3, 4.$$

Provided that the factor S_0 is excluded, the relation between Cayley's parametrization of an orthogonal matrix and the spin-operator S ,⁽¹⁾ and the meaning of condition (10.11) are quite the same as for 4-4 matrices. The set \mathfrak{S} of S 's obviously forms a group, and \mathfrak{S} is homomorphic to the real orthogonal group \mathfrak{O} as seen from (10.2). Then the quotient group $\mathfrak{S}' = \mathfrak{S}/\mathfrak{S}_0$ is isomorphic to \mathfrak{O} , where \mathfrak{S}_0 is the set of S_0 's corresponding to the unit element of \mathfrak{O} . Now \mathfrak{O} decomposes as $\mathfrak{O} = \mathfrak{H} + \tau\mathfrak{H}$, where \mathfrak{H} is a proper orthogonal group; consequently its faithful representation \mathfrak{S}' also decomposes as $\mathfrak{S}' = \mathfrak{X} + U\mathfrak{X}$. Comparing this with the result of Theorem 2, we see that \mathfrak{X} consists of S of the form S_1 , and $U\mathfrak{X}$ consists of S of the form S_2 .⁽²⁾

(1) This is easily seen from (ii) and (vi) of (10.4).

(2) In the case of 4-4 matrices, \mathfrak{S}_0 consists of unit matrix with numerical multiple, and the representation \mathfrak{S}' is irreducible. (Brauer and Weyl, loc. cit.) Then as Weyl shows (Weyl, The Classical Groups, p. 161), \mathfrak{X} the representation of \mathfrak{H} , is irreducible, or breaks up into two irreducible parts of equal degree. When \mathfrak{X} breaks up into two parts, by taking

a suitable co-ordinate system \mathfrak{X} can be written as $\mathfrak{X} = \left(\begin{array}{c|c} \times & 0 \\ \hline 0 & \times \end{array} \right)$, and then U has the form

$U = \left(\begin{array}{c|c} 0 & \times \\ \hline \times & 0 \end{array} \right)$. Then, by Theorem 1, we see that \mathfrak{X} is reducible, and the form of \mathfrak{X} and U

is obtained by taking Dirac's matrices as $\hat{\gamma}_i$.

If we consider the space \tilde{R}'_4 constituted by $E_i (= \tilde{h}_i^j \tilde{E}_j)$, where E_i are fixed and $\tilde{h}_i^j \tilde{h}_j^s g_{rs} = g_{ij}$, we see that exactly the same theorem as in R'_4 holds good, \tilde{E}_λ and $\tilde{\epsilon}_{ijkl}$ being replaced by \tilde{E}_λ and $\tilde{\epsilon}_{ijkl} = \det. | \tilde{H} | \cdot \epsilon_{ijkl}$ respectively.⁽¹⁾

§ 11. Physical Meaning of (10.17).

In this section we shall consider the physical meaning of (10.17). Let us consider a physical system P composed of two particles A and B , each of which induces its field, and as a whole the system P also induces a field in the form of one particle. Now, according to the idea of wave geometry, if we regard the field induced by A, B , and P as being represented by matrix fields, i. e. $\gamma_i, \bar{\gamma}_i$, and E_i ; then from the fundamental principle of wave geometry, these fields $\gamma_i, \bar{\gamma}_i$ and E_i determine the metrics of 4-dimensional space-time g_{ij}, \bar{g}_{ij} , and g'_{ij} , such that $\gamma_{(i} \gamma_{j)} = g_{ij} I$, $\bar{\gamma}_{(i} \bar{\gamma}_{j)} = \bar{g}_{ij} I$, and $E_{(i} E_{j)} = g'_{ij} I$. From the construction of the system P , it is natural to consider that, in the form of g'_{ij} 's, the fields induced by A and B are the same and also coincide with the field g_{ij} induced by P , while they differ in the form of matrix.

Mathematically we might set down the statements above as follows:

$$\begin{aligned} \gamma_{(i} \gamma_{j)} &= \bar{\gamma}_{(i} \bar{\gamma}_{j)} = g_{ij} I && \text{for each particle, } A \text{ and } B \\ E_i &= \begin{pmatrix} \gamma_i \\ \bar{\gamma}_i \end{pmatrix} && \text{for the system } P. \end{aligned}$$

Then it follows that $E_{(i} E_{j)} = g_{ij} I$. Here if we express E_i in the form $E_i = h_i^r \hat{E}_r$, where $\hat{E}_{(i} \hat{E}_{j)} = \delta_{ij} I$, it must follow that $\hat{E}_i = \begin{pmatrix} \hat{\gamma}_i \\ \hat{\gamma}'_i \end{pmatrix}$ and $\hat{\gamma}_i = h_i^r \gamma^r$, $\hat{\gamma}'_i = h_i^r \gamma'^r$, where $\hat{\gamma}_i, \hat{\gamma}'_i$ satisfy the relations $\hat{\gamma}_{(i} \hat{\gamma}_{j)} = \delta_{ij} I$ and have opposite orientations.⁽²⁾ So that γ_i and $\bar{\gamma}_i$ have opposite orientations. Then A and B can be regarded as particles that induce fields of opposite orientations; in other words A and B are in the states of opposite signs such that the field induced by particles with positive or negative charge.

Now, the general solution \hat{E}_λ satisfying $\hat{E}_{(\lambda} \hat{E}_{\mu)} = \delta_{\lambda\mu} I$ is given by (9.7), but, for simplicity, we take the form (9.8), i. e.

$$\hat{E}_\alpha = \begin{pmatrix} \hat{\gamma}_\alpha \\ \hat{\gamma}'_\alpha \end{pmatrix}, \quad E_4 = \begin{pmatrix} \hat{\gamma}_4 \\ -\hat{\gamma}'_4 \end{pmatrix}, \quad \hat{E}_5 = \begin{pmatrix} \hat{\gamma}_5 \\ \hat{\gamma}'_5 \end{pmatrix}, \quad E_6 = \begin{pmatrix} \hat{\gamma}_4 \\ \hat{\gamma}'_4 \end{pmatrix}, \quad E_7 = \begin{pmatrix} -\hat{\gamma}'_4 \\ i\hat{\gamma}_4 \end{pmatrix}. \quad (11.1)$$

Next we shall consider the problem: What changes of inner construction or inner states of P can be allowed, provided that the field by P is unchanged?

(1) $\tilde{E}_i = \tilde{h}_i^j \tilde{E}_j$, $\tilde{E}_{(i} \tilde{E}_{j)} = \delta_{ij} I$ and $\tilde{H} = \| h_j^i \|$.

(2) Here we assume that $E_5 = \begin{pmatrix} \hat{\gamma}_5 \\ \hat{\gamma}'_5 \end{pmatrix}$. Then from the discussion in §9, $\hat{\gamma}_i$ and $\hat{\gamma}'_i$ must be of opposite orientations.

Now, there are two kinds of transformations of E'_i , one being the coordinate transformation, the other the spin transformation. But so far as we are concerned with the orthogonal coordinate transformations with respect to g_{ij} , the coordinate transformations are reducible to spin transformations.⁽¹⁾ Therefore the action by which the inner construction of P is changed must be regarded as representable by a spin transformation of E_i . Thus we may set down the condition answering our problem in the following equation:

$$S^{-1}E_iS = E_i.$$

By (10.17), S satisfying (11.2) can be obtained as follows:

$$S = S_0 = \left(\begin{array}{c|c} aI & \begin{array}{|c|} \times \\ \hline \end{array} \\ \hline \begin{array}{|c|} \times \\ \hline \end{array} & bI \end{array} \right) = U + V,$$

where $U = \begin{pmatrix} aI & \\ & bI \end{pmatrix}$ and $V = \begin{pmatrix} & \begin{array}{|c|} \times \\ \hline \end{array} \\ \hline \begin{array}{|c|} \times \\ \hline \end{array} & \end{pmatrix}$. By U , the positions as well as the

orientations of A and B remain unchangeable, but by V the positions and the orientations of A and B interchanged.

Next, by means of the spin transformation of E_i , we can also consider the transformation of orientation of P as a whole. That is to say, if we solve the equation $S^{-1}E_iS = E'_i$, we have, excluding S_0 which satisfies $S_0^{-1}E_iS_0 = E_i$,

$$S = \left(\begin{array}{c|c} \begin{array}{|c|} \times \\ \hline \end{array} & \begin{array}{|c|} \times \\ \hline \end{array} \\ \hline \begin{array}{|c|} \times \\ \hline \end{array} & \begin{array}{|c|} \times \\ \hline \end{array} \end{array} \right) \equiv S_1 \quad \text{or} \quad S = \left(\begin{array}{c|c} \begin{array}{|c|} \times \\ \hline \end{array} & \begin{array}{|c|} \times \\ \hline \end{array} \\ \hline \begin{array}{|c|} \times \\ \hline \end{array} & \begin{array}{|c|} \times \\ \hline \end{array} \end{array} \right) \equiv S_2.$$

The transformation S_1 leaves the orientation of P , the position and orientations of A and B , unchanged; and S_2 changes the orientations of P , while it leaves the positions of A and B but changes their orientations.

As the actual model represented by such P as stated above we might mention a deuteron consisting of one proton and one neutron.

§ 12. Remarks.

The discussion above concerning the transformation: $\gamma_i = S^{-1}\gamma_iS$ can be extended to the case of matrix of degree 2^n by the analogous method.

(1) Cf. § 9.

But in the calculation of S for given γ_i and γ'_i , i. e. for given orthogonal matrix $\|a_j^i\|$, the properties of spinors have not been used explicitly. If we avail ourselves of the properties of spinors, the calculation for S becomes very simple; moreover, the general case of matrix of degree 2^n can be easily treated. We explain them in the following paragraphs.

We consider the operators $\hat{\gamma}_i$ ($i=1, 2, \dots, n$) satisfying

$$\hat{\gamma}_i \hat{\gamma}_j = \delta_{ij} I \quad (12.1)$$

where I denotes the unit operator. The problem, in general form, becomes to determine S such that

$$a_{pq}^{\alpha} \hat{\gamma}_q = S \hat{\gamma}_p S^{-1} \quad (p, q=1, 2, \dots, r, r: \text{even}) \quad (12.2)$$

for any real proper orthogonal matrices transformation (a_p^α). We consider such a set of S as an algebra Π consisting of all linear combinations of the 2^n units

$$l_{a_1 a_2 \dots a_n} = \hat{\gamma}_1^{a_1} \hat{\gamma}_2^{a_2} \dots \hat{\gamma}_n^{a_n} \quad (a_1, a_2, \dots, a_n \text{ integers mod. } 2).$$

If we take any orthogonal matrix $T = \|t_j^i\|$, then

$$\gamma'_i = t_j^i \hat{\gamma}_j \quad (i, j=1, 2, \dots, n)$$

also satisfy the same relation (12.1), and belong to the algebra Π ; also, the units of Π can be constructed from γ'_i . Therefore we can make the reduction as in § 10.

First we shall find an element S of Π such that

$$\hat{\gamma}_x = S \hat{\gamma}_x S^{-1} \quad (x=s+1, s+2, \dots, n); \quad (12.3)$$

s is arbitrary integer such that $0 \leq s < n$. Then $\hat{\gamma}_x S \hat{\gamma}_x = S$. Expanding S in the bases: $S = \lambda I + \lambda^{i_1} \hat{\gamma}_{i_1} + \lambda^{i_1 i_2} \hat{\gamma}_{i_1} \hat{\gamma}_{i_2} + \dots + \lambda^{i_1 i_2 \dots i_n} \hat{\gamma}_{i_1} \hat{\gamma}_{i_2} \dots \hat{\gamma}_{i_n}$ where $\lambda^{i_1 i_2} = \lambda^{[i_1 i_2]}, \dots, \lambda^{i_1 \dots i_n} = \lambda^{[i_1 i_2 \dots i_n]}$, and making use of the relations: if p is even and $i_1, i_2, \dots, i_p \neq x$,

$$\begin{aligned} \hat{\gamma}_x \hat{\gamma}_{i_1} \hat{\gamma}_{i_2} \dots \hat{\gamma}_{i_p} \hat{\gamma}_x &= \hat{\gamma}_{i_1} \hat{\gamma}_{i_2} \dots \hat{\gamma}_{i_p} && \text{when } \hat{\gamma}_{i_1} \dots \hat{\gamma}_{i_p} \text{ does not contain} \\ & && \hat{\gamma}_x \text{ as factor,} \\ &= -\hat{\gamma}_{i_1} \hat{\gamma}_{i_2} \dots \hat{\gamma}_{i_p} && \text{when } \hat{\gamma}_{i_1} \dots \hat{\gamma}_{i_p} \text{ contains } \hat{\gamma}_x \text{ as} \\ & && \text{factor;} \end{aligned}$$

if p is odd, the result is the reverse, we see that S contains only the terms of the product of even number of $\hat{\gamma}_i$ not containing $\hat{\gamma}_x$, and the terms of the product of odd number of $\hat{\gamma}_i$ containing all $\hat{\gamma}_x$. And conversely, if S is so, it satisfies the relations (12.3) provided that the inverse of S exists.

Next, to solve equation (12.2), we make the reduction as in § 10, by which $A = \|a_p^\alpha\|$ can be set in the form;

$$A = \left(\begin{array}{cc} \cos \theta_1 \sin \theta_1 & \\ -\sin \theta_1 \cos \theta_1 & \end{array} \right) \dot{+} \left(\begin{array}{cc} \cos \theta_2 \sin \theta_2 & \\ -\sin \theta_2 \cos \theta_2 & \end{array} \right) \dot{+} \dots \quad (12.4)$$

Here if we put

$$A_1 \equiv \left(\begin{array}{cc} \cos \theta_1 \sin \theta_1 & \\ -\sin \theta_1 \cos \theta_1 & \end{array} \right) \dot{+} \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right) \dot{+} \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right) \dot{+} \dots \equiv \| \hat{a}_q^1 \|$$

$$A_2 \equiv \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right) \dot{+} \left(\begin{array}{cc} \cos \theta_2 \sin \theta_2 & \\ -\sin \theta_2 \cos \theta_2 & \end{array} \right) \dot{+} \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right) \dot{+} \dots \equiv \| \hat{a}_q^2 \|,$$

.....

then $A = A_1 A_2 \dots$. Now a special solution of (12.2) for $\| a_q^x \|$ given by (12.4) is given by $S = S_1 S_2 \dots$, where S_λ are the solutions of

$$\hat{a}_p^q \hat{\gamma}_q = S_\lambda \hat{\gamma}_p S_\lambda^{-1} \quad \left((\lambda = 1, 2, \dots, \frac{r}{2}) \right). \quad (12.5)$$

In actual the equation (12.5) becomes as follows:

- (i) $\hat{a}_p^q \hat{\gamma}_q = S_\lambda \hat{\gamma}_p S_\lambda^{-1}, \quad (p, q = 2\lambda - 1, 2\lambda)$
- (ii) $\hat{\gamma}_x = S_\lambda \hat{\gamma}_x S_\lambda^{-1}. \quad (x = 1, 2, \dots, 2\lambda - 2, 2\lambda + 1, \dots, r).$ (12.6)

But, since S_λ satisfying (ii) of (12.6) can be put in the form $S = aI + b\hat{\gamma}_{2\lambda-1}\hat{\gamma}_{2\lambda}$, (not the necessary form), by substituting this into (i) of (12.6) we have

$$S_\lambda = a_\lambda \left(I + \tan \frac{\theta_\lambda}{2} \hat{\gamma}_{2\lambda-1} \hat{\gamma}_{2\lambda} \right); \quad (12.7)$$

so that (12.7) is a special solution of (12.5). Therefore, as a special solution of (12.2), we have

$$U = a \left(I + \tan \frac{\theta_1}{2} \hat{\gamma}_1 \hat{\gamma}_2 \right) \left(I + \tan \frac{\theta_2}{2} \hat{\gamma}_3 \hat{\gamma}_4 \right) (\dots) \dots (\dots). \quad (12.8)$$

Next, to find the general solution S of (12.2), from $a_p^q \hat{\gamma}_q = S \hat{\gamma}_p S^{-1} = U \hat{\gamma}_p U^{-1}$, if we put $S_0 \equiv U^{-1} S$, we have $S_0 \hat{\gamma}_p S_0^{-1} = \hat{\gamma}_p$. Therefore the general form of S_0 is obtained as the sum of the terms of the product of even number of $\hat{\gamma}_i$ not containing $\hat{\gamma}_p$, and the terms of the product of odd number of $\hat{\gamma}_i$ containing all $\hat{\gamma}_p$. Thus the general solution S of (12.2) is given by

$$S = S_0 \left(I + \tan \frac{\theta_1}{1} \hat{\gamma}_1 \hat{\gamma}_2 \right) \left(I + \tan \frac{\theta_2}{2} \hat{\gamma}_3 \hat{\gamma}_4 \right) \dots, \quad (12.9)$$

using the commutativity of S_0 and U .

If $r = n$, $S_0 = aI$. Therefore, when $n = r = 4$, we obtain the result of § 3, and when $n = r = 6$, we obtain the result of § 9. When $n = 6$, and $r = 4$.

$$S_0 = \alpha I + \beta \dot{\gamma}_5 \dot{\gamma}_6 + \gamma \dot{\gamma}_1 \dots \dot{\gamma}_4 \dot{\gamma}_5 + \delta \dot{\gamma}_1 \dots \dot{\gamma}_4 \dot{\gamma}_6$$

which can be written in the form :

$$S_0 = \alpha I + \beta^{xy} \dot{\gamma}_x \dot{\gamma}_y \quad (x, y = 5, 6, 7),$$

where $\dot{\gamma}_7 = \pm i \dot{\gamma}_1 \dot{\gamma}_2 \dots \dot{\gamma}_6$. That is to say, we obtain the result of § 10.

This method of finding S for given $A = \|a_{ij}^x\|$ is a finite formulation of the infinitesimal method used by Cartan, etc.⁽¹⁾ In other word, if we take

$\theta_1, \theta_2, \dots$ as infinitesimal, we have $A = I + \tau$, where $\tau = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \theta_1 + \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \theta_2 + \dots$; and corresponding to this, from (12.9) we have: $S = S_0(I + \lambda^{ij} \dot{\gamma}_i \dot{\gamma}_j)$, where $\sigma \equiv \|\lambda^{ij}\| = \begin{pmatrix} 0 & \frac{1}{4} \\ -\frac{1}{4} & 0 \end{pmatrix} \theta_1 + \begin{pmatrix} 0 & \frac{1}{4} \\ -\frac{1}{4} & 0 \end{pmatrix} \theta_2 + \dots = \frac{1}{4} \tau$, which is

the form of infinitesimal spin-transformation corresponding to an infinitesimal rotation obtained by Cartan and others. If we take into account that the finite formulation of $A = I + \tau$ may be regarded as Cayley's parametrization of the form $A = (I - T)(I + T)^{-1}$, the relation between S expressed by (12.9) and Cayley's parametrization T corresponding to the relation $\sigma = \frac{1}{4} \tau$ in the infinitesimal case is obtainable. In actuality since

$$A = \begin{pmatrix} \cos \theta_1 & \sin \theta_1 \\ -\sin \theta_1 & \cos \theta_1 \end{pmatrix} + \begin{pmatrix} \cos \theta_2 & \sin \theta_2 \\ -\sin \theta_2 & \cos \theta_2 \end{pmatrix} + \dots,$$

$T = \begin{pmatrix} 0 & -\tan \frac{\theta_1}{2} \\ \tan \frac{\theta_1}{2} & 0 \end{pmatrix} + \begin{pmatrix} 0 & -\tan \frac{\theta_2}{2} \\ \tan \frac{\theta_2}{2} & 0 \end{pmatrix} + \dots$ is obtained from $A = (I - T)(I + T)^{-1}$; and if we compare this T with $S = S_0(I + \lambda^{ij} \dot{\gamma}_i \dot{\gamma}_j + \dots)$ expressed by (12.9), we have the relation: $R = \|\lambda^{ij}\| = -\frac{1}{2} T$. This is no other than

the finite formulation of the relation $\sigma = \frac{1}{4} \tau$.⁽²⁾ Furthermore, we can see that the relation $R = -\frac{1}{2} T$ holds good in general coordinates, though it has been obtained in a special coordinate.⁽³⁾

(1) Cartan, Bull. Soc. Math. d. France, **41** (1913); Pauli, *ibid.*; Brauer & Weyl, *loc. cit.*

(2) If we choose Cayley's parametrization such that it coincides with τ when A is infinitesimal rotation, A is written as $A = \left(1 + \frac{T}{2}\right) \left(1 - \frac{T}{2}\right)^{-1}$, so that the relation $R = -\frac{1}{2} T$ is replaced by $R = \|\lambda^{ij}\| = \frac{1}{4} T$.

(3) Reversing the reduction of A into the form expressed by (12.4), we can prove that the relation $R = -\frac{1}{2} T$ holds good in special coordinates.

Note.

We consider the problem in the following cases :

Case I. $|A+I| \neq 0$, and $|A-I| \neq 0$,

Case II. $|A+I| = 0$, and $|A-I| \neq 0$,

Case III. $|A+I| \neq 0$, and $|A-I| = 0$,

Case IV. $|A+I| = 0$, and $|A-I| = 0$,

Case I. $|A+I| \neq 0$, $|A-I| \neq 0$, i. e. $\theta, \varphi \neq 0$, $\pi \pmod{2\pi}$.

From (i) $\Lambda_k = 0$; from (iii) $\Lambda_k^7 = 0$.

In (ii), by putting $\lambda = x$, $\Lambda_k^{xx} = 0$, and by putting $i = a$, $\lambda = p$, $\Lambda_a^{pp} = 0$, and by putting $i = a$, $\lambda = b$, $\Lambda^{12} = \frac{1}{2} \tan \frac{\theta}{2} \Lambda$. Likewise, $\Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda$.

In (iv) by putting $\lambda = x$, $\mu = y$, $\Lambda_k^{xy} = 0$, and by putting $\lambda = j$, $\mu = k$, $\Lambda_i^{jk} = 0$, (iv) can be written as follows :

$$(\alpha_i^j + \delta_i^j) V^x + 6(\alpha_i^x - \delta_i^x) \Lambda_k^{jx} = 0,$$

By putting $i = a$, $j = p$, $\Lambda_a^{px} = 0$, and by putting $i = a$, $j = b$, $\Lambda^{12x} = -\frac{1}{6} \cot \frac{\theta}{2} \Lambda^x$.

In like manner, $\Lambda^{34x} = -\frac{1}{6} \cot \frac{\varphi}{2} \Lambda^x$.

In (v), by putting $\lambda = x$, $\Lambda^{ix7} = 0$, and by putting $i = a$, $\lambda = p$, $\Lambda^{ap7} = 0$, and by putting $i = a$, $\lambda = b$, $\Lambda^{127} = -\frac{1}{2} \cot \frac{\theta}{2} \Lambda^7$. Similarly $\Lambda^{347} = -\frac{1}{2} \cot \frac{\varphi}{2} \Lambda^7$.

In (vi), by putting $i = a$, $\lambda = b$, $\mu = x$, $\nu = y$, we have $\Lambda^{56} = i \cot \frac{\theta}{2} \Lambda^{347} = -\frac{i}{2} \cot \frac{\theta}{2} \cot \frac{\varphi}{2} \Lambda^7$; and by putting $i = a$, $\lambda = b$, $\mu = p$, $\nu = q$, $\Lambda^{567} = -\frac{i}{2} \tan \frac{\theta}{2} \tan \frac{\varphi}{2} \Lambda$.

In (vii), by putting $i = a$, $\lambda = b$, $\mu = x$, we have $\Lambda^{57} = i \cot \frac{\theta}{2} \cot \frac{\varphi}{2} \Lambda^6$, and $\Lambda^{67} = -i \cot \frac{\theta}{2} \cot \frac{\varphi}{2} \Lambda^5$. In the other cases we have identities. Thus we have established (10.6).

Case II. $|A+I| = 0$, $|A-I| \neq 0$.

Here $\theta \equiv \pi$ or $\varphi \equiv \pi \pmod{2\pi}$. First we assume $\theta \equiv \pi \pmod{2\pi}$ and $\varphi \neq \pi \pmod{2\pi}$. Then, from $|A-I| \neq 0$, $\varphi \neq 0 \pmod{2\pi}$. Therefore $\alpha_a^b = -\delta_a^b$, and $|\alpha_a^p \pm \delta_a^p| \neq 0$. From (i) $\Lambda_k = 0$; therefore from (iv) $\Lambda^{ixy} = 0$, $\Lambda^{ijk} = 0$, $\Lambda_a^{px} = 0$, $\Lambda^{12x} = 0$, and $\Lambda^{34x} = -\frac{1}{6} \cot \frac{\varphi}{2} \Lambda^x$. In (ii), by putting $i = a$, $\Lambda = 0$, and therefore $\Lambda_p^\lambda = 0$, i. e. $\Lambda^{ap} = \Lambda^{pq} = \Lambda^{px} = 0$. From (iii). $\Lambda_p^7 = 0$.

In (v), by putting $i=a$, $\Lambda_a^{\lambda\gamma}=0$, i. e. $\Lambda^{a\beta\gamma}=\Lambda^{a\beta\gamma}=\Lambda^{a\alpha\gamma}=0$, and by putting $\lambda=x$, $\Lambda^{ix\gamma}=0$, and by putting $i=p$, $\Lambda^{34\gamma}=-\frac{1}{2}\cot\frac{\varphi}{2}\Lambda^\gamma$. In (vi), by putting $i=a$, $\delta_a^{\lambda\mu\nu}\Lambda^{\lambda\mu\nu}=0$, i. e. $\Lambda^{x\lambda}=0$, i. e. $\Lambda^{ix}=\Lambda^{xy}=0$, and by putting $i=p$, $\Lambda^{567}=-i\tan\frac{\varphi}{2}\Lambda^{12}$. In (vii), by putting $i=a$, $\Lambda^{i\lambda\gamma}=0$, and therefore $\Lambda^{\lambda\mu\nu}$ except Λ^{pqr} are zero. In the other cases we have identities. Thus we have:

$$\left. \begin{aligned} \Lambda &= 0 \\ \Lambda^i &= 0; \quad \Lambda^x, \Lambda^\gamma \text{ are arbitrary,} \\ \Lambda^{x\lambda} &= \Lambda^{p\lambda} = 0; \quad \Lambda^{i\lambda\gamma} = 0; \quad \Lambda^{12} \text{ is arbitrary,} \\ \Lambda^{ijk} &= \Lambda^{ixy} = \Lambda^{ix\gamma} = 0; \quad \Lambda^{\alpha\beta\gamma} = \Lambda^{a\lambda\gamma} = 0; \quad \Lambda^{12\alpha} = 0, \\ \Lambda^{34\alpha} &= -\frac{1}{6}\cot\frac{\varphi}{2}\Lambda^\alpha, \quad \Lambda^{34\gamma} = -\frac{1}{2}\cot\frac{\varphi}{2}\Lambda^\gamma, \\ \Lambda^{567} &= -i\tan\frac{\varphi}{2}\Lambda^{12}. \end{aligned} \right\} \quad (\text{N. 1})$$

This is the same as (10.6) in which $\theta = \pi \pmod{2\pi}$ in the same sense as in § 3.

If φ is also congruent $\pi \pmod{\pi 2}$, i. e. $\alpha_i^j = -\delta_i^j$, then we have:

$$\left. \begin{aligned} \Lambda &= 0 \\ \Lambda^i &= 0; \quad \Lambda^x, \Lambda^\gamma \text{ are arbitrary,} \\ \Lambda^{\lambda\mu} &= 0; \quad \Lambda^{i\lambda\gamma} = 0, \\ \Lambda^{\lambda\mu\nu} &= \Lambda^{i\lambda\gamma} = 0, \quad \Lambda^{567} \text{ is arbitrary.} \end{aligned} \right\} \quad (\text{N. 2})$$

This is the same as (N. 1) in which $\varphi \equiv \pi \pmod{2\pi}$, i. e. the same as (10.6) in which $\theta, \varphi \equiv \pi \pmod{2\pi}$.

Case III. $|A+I| \neq 0$, $|A-I|=0$.

Here $\theta \equiv 0$ or $\varphi \equiv 0 \pmod{2\pi}$. First we assume that $\theta \equiv 0 \pmod{2\pi}$ and $\varphi \neq 0 \pmod{2\pi}$. Therefore $\alpha_a^b = \delta_a^b$, $|\alpha_p^q \pm \delta_p^q| \neq 0$. From (i) $\Lambda_p = 0$, and from (ii) $\Lambda^{a\lambda} = 0$, $\Lambda^{p\alpha} = 0$, and $\Lambda^{34} = \frac{1}{2}\tan\frac{\varphi}{2}\Lambda$. From (iii) $\Lambda^{i\gamma} = 0$. In (iv), by putting $i=a$, $\Lambda^{\lambda} = 0$, and by putting $i=p$, $\Lambda^{p\lambda\mu} = 0$. In (v), by putting $i=a$, $\Lambda^\gamma = 0$; therefore $\Lambda^{p\lambda\gamma} = 0$. In (vi), by putting $i=a$, $\Lambda^{\varepsilon\rho\gamma}\varepsilon_{\alpha\varepsilon\rho}^{\lambda\mu\nu} = 0$, so that $\Lambda^{\varepsilon\rho\gamma}$ except $\Lambda^{12\gamma}$ are zero; and by putting $i=p$, $\lambda=x$, $\mu=y$, $\nu=q$, we have $\Lambda^{12\gamma} = -i\tan\frac{\varphi}{2}\Lambda^{56}$. In (vii), by putting $i=a$, $\Lambda^{\varepsilon\rho\sigma}\varepsilon_{\alpha\varepsilon\rho\sigma}^{\lambda\mu} = 0$, therefore $\Lambda^{\varepsilon\rho\sigma}$ except $\Lambda^{ab\sigma}$ are zero, because $\Lambda^{\rho\lambda\mu} = 0$. Putting $i=p$, $\lambda=q$, $\mu=x$, we have $\Lambda^{12\sigma} = \frac{i}{6}\tan\frac{\varphi}{2}\Lambda^{57}$, $\Lambda^{12\sigma} = -\frac{i}{6}\tan\frac{\varphi}{2}\Lambda^{67}$. In the other cases we have identities. Thus we have:

$$\left. \begin{aligned}
 & \Lambda \text{ is arbitrary,} \\
 & \Lambda^\lambda = 0; \quad \Lambda^7 = 0, \\
 & \Lambda^{\alpha\lambda} = \Lambda^{p\alpha} = 0; \quad \Lambda^{i7} = 0; \quad \Lambda^{34} = \frac{1}{2} \tan \frac{\varphi}{2} \Lambda, \quad \Lambda^{56}, \Lambda^{57}, \Lambda^{67} \text{ arbitrary,} \\
 & \Lambda^{p\lambda\mu} = \Lambda^{\alpha\beta\gamma} = 0; \quad \Lambda^{p\lambda 7} = \Lambda^{\alpha\beta 7} = \Lambda^{\alpha\gamma 7} = 0; \quad \Lambda^{125} = -\frac{i}{6} \tan \frac{\varphi}{2} \Lambda^{67}, \\
 & \Lambda^{126} = \frac{i}{6} \tan \frac{\varphi}{2} \Lambda^{57}, \\
 & \Lambda^{127} = -i \tan \frac{\varphi}{2} \Lambda^{56},
 \end{aligned} \right\} \quad (\text{N. 3})$$

This result is the same as (10.6) in which $\theta \equiv 0 \pmod{2\pi}$. If φ is also congruent 0 mod. 2π , i. e. $\alpha_j^i = \delta_j^i$, we have:

$$\left. \begin{aligned}
 & \Lambda: \text{ arbitrary,} \\
 & \Lambda^\lambda = \Lambda^7 = 0, \\
 & \Lambda^{i\lambda} = \Lambda^{i7} = 0; \quad \Lambda^{56}, \Lambda^{57}, \Lambda^{67}: \text{ arbitrary,} \\
 & \Lambda^{\xi\rho\sigma} = \Lambda^{\xi\rho 7} = 0.
 \end{aligned} \right\} \quad (\text{N. 4})$$

This result is the same as (N. 3) in which $\varphi \equiv 0 \pmod{2\pi}$, i. e. (10.6) in which $\theta, \varphi \equiv 0 \pmod{2\pi}$.

Case IV. $|A+I|=0, |A-I|=0$.

Here we can assume, without loss of generality, that $\theta \equiv 0 \pmod{2\pi}$ and $\varphi \equiv \pi \pmod{2\pi}$, i. e. $\alpha_a^\lambda = \delta_a^\lambda$ and $\alpha_p^\lambda = -\delta_p^\lambda$. Then we have:

$$\left. \begin{aligned}
 & \Lambda = 0 \\
 & \Lambda^\lambda = 0; \quad \Lambda^7 = 0, \\
 & \Lambda^{\alpha\lambda} = \Lambda^{p\alpha} = \Lambda^{\alpha\beta} = 0; \quad \Lambda^{i7} = 0, \quad \Lambda^{34}: \text{ arbitrary,} \\
 & \Lambda^{p\lambda\mu} = \Lambda^{\alpha\beta\gamma} = 0; \quad \Lambda^{p\lambda 7} = \Lambda^{\alpha\beta 7} = \Lambda^{\alpha\gamma 7} = 0; \quad \Lambda^{125}, \Lambda^{126}, \Lambda^{127}: \text{ arbitrary.}
 \end{aligned} \right\} \quad (\text{N. 5})$$

This result is the same as (N. 3) in which $\varphi \equiv \pi$, i. e. the same as (10.6) in which $\theta \equiv 0, \varphi \equiv \pi \pmod{2\pi}$.

This problem was discussed at a special Seminar of Geometry and Theoretical Physics in the Hiroshima University, and research into it has been carried on under the Scientific-Research Expenditure of the Department of Education.

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