

Closed hypersurfaces with constant mean curvature in a Riemannian manifold

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It has been proved by H. Liebmann [3] and W. Süss [4] that the only convex closed hypersurface with constant mean curvature is a sphere. To prove this theorem we need integral formulas of Minkowski.

Prof. Y. Katsurada [1], [2] derived integral formulas of Minkowski type which are valid in an Einstein space and proved the following generalisation of the theorem of Liebmann-Süss.

THEOREM. *Let M be an $(m+1)$ -dimensional orientable Einstein space and S a closed orientable hypersurface in M whose first mean curvature is constant. We suppose that M admits a one-parameter group of conformal transformations such that the inner product α of the generating vector v^h and the normal C^h to the hypersurface does not change the sign (and $\neq 0$) on S . Then every point of S is umbilical.*

The main purpose of the present paper is to derive three integral formulas which are valid in a general Riemannian manifold and to generalise Katsurada's theorem to the case of general Riemannian manifolds admitting a one-parameter group of homothetic transformations.

§ 0. Preliminaries.

We consider an orientable $(m+1)$ -dimensional Riemannian manifold M with positive definite metric and denote by g_{ji} , ∇_j , K_{kji}^h , $K_{ji} = K_{kji}^k$, the fundamental metric tensor, the covariant differentiation with respect to the Riemannian connection, the curvature tensor, and the Ricci tensor of M respectively, where and in the sequel the indices h, i, j, k, \dots run over the range $1, 2, \dots, m, m+1$.

We assume that there is given an orientable hypersurface S whose local expression is

$$(0.1) \quad \xi^h = \xi^h(\eta^a),$$

where ξ^h are local coordinates in M and η^a are local parameters on the hypersurface S , where and in the sequel the indices a, b, c, d, \dots run over the range $\dot{1}, \dot{2}, \dots, \dot{m}$.

If we put

$$(0.2) \quad B_b^h = \partial_b \xi^h, \quad \partial_b = \partial/\eta^b,$$

then the first fundamental tensor of S is given by

$$(0.3) \quad g_{cb} = g_{ji} B_c^j B_b^i.$$

We assume that B_b^h ($b = \dot{1}, \dot{2}, \dots, \dot{m}$) give the positive direction in S and choose the unit normal C^h to S in such a way that B_b^h, C^h give the positive direction in M .

Denoting by ∇_c the van der Waerden-Bortolotti covariant differentiation along the S , we can write equations of Gauss and Weingarten in the form

$$(0.4) \quad \nabla_c B_b^h = h_{cb} C^h,$$

$$(0.5) \quad \nabla_c C^h = -h_c^a B_a^h$$

respectively, where h_{cb} is the second fundamental tensor of S and $h_c^a = h_{cb} g^{ba}$.

If we denote by k_1, k_2, \dots, k_m the principal curvatures of S , that is, the roots of the characteristic equation

$$(0.6) \quad |h_{cb} - k g_{cb}| = 0,$$

then the first mean curvature H_1 and the second mean curvature H_2 of S are respectively given by

$$(0.7) \quad mH_1 = \sum_a k_a = h_c^c$$

and

$$(0.8) \quad \binom{m}{2} H_2 = \sum_{c < b} k_c k_b = \frac{1}{2} (h_c^b h_b^c - h_c^c h_b^b).$$

Now, the equations of Gauss and those of Codazzi are respectively written as

$$(0.9) \quad K_{kjih} B_a^k B_c^j B_b^i B_a^h = K_{acba} - (h_{da} h_{cb} - h_{ca} h_{db})$$

and

$$(0.10) \quad K_{kjih} B_a^k B_c^j B_b^i C^h = \nabla_a h_{cb} - \nabla_c h_{ab}.$$

Transvecting g^{cb} to the equations of Codazzi and remembering $g^{cb} B_c^j B_b^i = g^{ji} - C^j C^i$, we find

$$(0.11) \quad K_{kh} B_a^k C^h = \nabla_a h_c^c - \nabla_c h_a^c.$$

We now assume that there is given a global vector field $v^h(\xi)$ in M and denote by \mathcal{L} the Lie differentiation with respect to v^h . (See [5].) The vector field v^h is said to be conformal, homothetic or Killing when it satisfies

$$\mathcal{L} g_{ji} = \nabla_j v_i + \nabla_i v_j = 2\rho g_{ji},$$

$$\mathcal{L} g_{ji} = 2c g_{ji},$$

or

$$\mathcal{L} g_{ji} = 0$$

respectively, where ρ is a function and c is a constant. When v^h is conformal, it satisfies

$$(0.12) \quad \mathcal{L}\{^h_{ji}\} = \nabla_j \nabla_i v^h + K_{kji}{}^h v^k = \delta_j^h \rho_i + \delta_i^h \rho_j - \rho^h g_{ji},$$

where $\{^h_{ji}\}$ are Christoffel symbols and $\rho_i = \nabla_i \rho$, $\rho^h = \rho_i g^{ih}$. When v^h is homothetic, it satisfies

$$(0.13) \quad \mathcal{L}\{^h_{ji}\} = \nabla_j \nabla_i v^h + K_{kji}{}^h v^k = 0$$

and thus it defines an infinitesimal affine collineation.

On the hypersurface S we can put

$$(0.14) \quad v^h = B_a{}^h v^a + \alpha C^h.$$

Since we have

$$\begin{aligned} B_c{}^j B_b{}^i \mathcal{L} g_{ji} &= B_c{}^j B_b{}^i (\nabla_j v_i + \nabla_i v_j) \\ &= \nabla_c v_b + \nabla_b v_c - 2\alpha h_{cb}, \end{aligned}$$

denoting also by \mathcal{L} the Lie differentiation with respect to v^a in S , we have

$$(0.15) \quad B_c{}^j B_b{}^i (\mathcal{L} g_{ji}) = \mathcal{L} g_{cb} - 2\alpha h_{cb}.$$

Transvecting v^d to (0.11), we find

$$\begin{aligned} K_{kh} B_a{}^k v^d C^h &= v^d \nabla_a h_c{}^c - v^d (\nabla_c h_a{}^c), \\ K_{ji} (v^j - \alpha C^j) C^i &= v^d \nabla_a h_c{}^c - \nabla_c (h_a{}^c v^d) + h^{cb} \nabla_c v_b \end{aligned}$$

and consequently

$$(0.16) \quad K_{ji} v^j C^i - \alpha K_{ji} C^j C^i = v^d \nabla_a h_c{}^c - \nabla_c (h_a{}^c v^d) + \frac{1}{2} h^{cb} (\mathcal{L} g_{cb})$$

or

$$(0.17) \quad \begin{aligned} K_{ji} v^j C^i - \alpha K_{ji} C^j C^i &= v^d \nabla_a h_c{}^c - \nabla_c (h_a{}^c v^d) + \alpha h_c{}^b h_b{}^c \\ &\quad + \frac{1}{2} h^{cb} B_c{}^j B_b{}^i (\mathcal{L} g_{ji}) \end{aligned}$$

by virtue of (0.15).

§ 1. The first integral formula.

We have

$$v_b = B_b{}^i v_i$$

from which, by covariant differentiation along S ,

$$\nabla_c v_b = \alpha h_{cb} + B_c{}^j B_b{}^i (\nabla_j v_i).$$

Transvecting g^{cb} to this, we get

$$g^{cb} \nabla_c v_b = \alpha h_c{}^c + \frac{1}{2} g^{cb} B_c{}^j B_b{}^i (\mathcal{L} g_{ji})$$

or

$$g^{cb}\nabla_c v_b = m\alpha H_1 + \frac{1}{2}g^{cb}B_c^j B_b^i (\mathcal{L}g_{ji}).$$

Thus, assuming S to be compact, we get the integral formula

$$(1.1) \quad \int_S m\alpha H_1 dS + \frac{1}{2} \int_S g^{cb} B_c^j B_b^i (\mathcal{L}g_{ji}) dS = 0,$$

where dS denotes the surface element of S . (See [6].)

If the vector field v^b is conformal, that is, if $\mathcal{L}g_{ji} = 2\rho g_{ji}$, we have, from the formula above,

$$(1.2) \quad \int_S \alpha H_1 dS + \int_S \rho dS = 0.$$

§2. The second integral formula.

If we put

$$(2.1) \quad w_b = h_b^a v_a,$$

we have, by covariant differentiation along S ,

$$\nabla_c w_b = \nabla_c (h_{ab} v^d).$$

Transvecting g^{cb} to this, we get

$$g^{cb}\nabla_c w_b = \nabla_c (h_a^c v^d),$$

from which, taking account of (0.17)

$$(2.2) \quad g^{cb}\nabla_c w_b = v^d \nabla_d h_c^c + \alpha h_c^b h_b^c - K_{ji} v^j C^i + \alpha K_{ji} C^j C^i + \frac{1}{2} h^{cb} B_c^j B_b^i (\mathcal{L}g_{ji}).$$

On the other hand, we have, from (0.7) and (0.8),

$$h_c^c = mH_1, \quad h_c^b h_b^c = m^2 H_1^2 - m(m-1)H_2,$$

and consequently, we have, from (2.2),

$$\begin{aligned} g^{cb}\nabla_c w_b &= m v^d \nabla_d H_1 + m\alpha \{mH_1^2 - (m-1)H_2\} \\ &\quad - K_{ji} v^j C^i + \alpha K_{ji} C^j C^i + \frac{1}{2} h^{cb} B_c^j B_b^i (\mathcal{L}g_{ji}). \end{aligned}$$

Thus, assuming S to be compact, we get the second integral formula

$$(2.3) \quad \int_S [m v^d \nabla_d H_1 + m\alpha \{mH_1^2 - (m-1)H_2\} - K_{ji} v^j C^i + \alpha K_{ji} C^j C^i + \frac{1}{2} h^{cb} B_c^j B_b^i (\mathcal{L}g_{ji})] dS = 0.$$

If the vector field v^b is conformal, then we get from (2.3)

$$(2.4) \quad \int_S [mv^a \nabla_a H_1 + m\rho H_1 + m\alpha \{mH_1^2 - (m-1)H_2\} - K_{ji} v^j C^i + \alpha K_{ji} C^j C^i] dS = 0.$$

§ 3. The third integral formula.

We have

$$(3.1) \quad \alpha = v^h C_h,$$

from which, by covariant differentiation along S ,

$$\nabla_b \alpha = (B_b^i \nabla_i v^h) C_h - h_b^a v_a$$

and

$$\nabla_c \nabla_b \alpha = h_{cb} (\nabla_j v_i) C^j C^i + B_c^j B_b^i (\nabla_j \nabla_i v^h) C_h - h_c^a B_b^i (\nabla_i v^h) B_{ah} - \nabla_c (h_b^a v_a).$$

Transvecting g^{cb} to this, we get

$$g^{cb} \nabla_c \nabla_b \alpha = \frac{1}{2} h_c^c (\mathcal{L} g_{ji}) C^j C^i + g^{cb} B_c^j B_b^i (\mathcal{L} \{_{ji}^h\}) C_h - K_{ji} v^j C^i - \frac{1}{2} h^{cb} B_c^j B_b^i (\mathcal{L} g_{ji}) - g^{cb} \nabla_c (h_b^a v_a)$$

by virtue of

$$\nabla_j \nabla_i v^h = \mathcal{L} \{_{ji}^h\} - K_{kji}^h v^k.$$

Thus, assuming S to be compact, we get the third integral formula

$$(3.3) \quad \int_S \left[\frac{1}{2} h_c^c (\mathcal{L} g_{ji}) C^j C^i + g^{cb} B_c^j B_b^i (\mathcal{L} \{_{ji}^h\}) C_h - K_{ji} v^j C^i - \frac{1}{2} h^{cb} B_c^j B_b^i (\mathcal{L} g_{ji}) \right] dS = 0.$$

We now assume that the vector field v^h is conformal, then we have

$$\mathcal{L} g_{ji} = 2\rho g_{ji}, \quad \mathcal{L} \{_{ji}^h\} = \delta_j^h \rho_i + \delta_i^h \rho_j - g_{ji} \rho^h.$$

Thus we find from (3.3)

$$(3.4) \quad \int_S [m\rho_i C^i + K_{ji} v^j C^i] dS = 0.$$

Moreover if v^h is homothetic, we get

$$(3.5) \quad \int_S K_{ji} v^j C^i dS = 0.$$

§ 4. Integral formulas for the case $H_1 = \text{constant}$.

We assume in this section that the Riemannian manifold admits an infinitesimal conformal transformation v^h and the first mean curvature H_1 of the hypersurface S is constant. Then, the first integral formula (1.2) and the

second integral formula (2.4) become respectively

$$(4.1) \quad H_1 \int_S \alpha \, dS + \int_S \rho \, dS = 0$$

and

$$(4.2) \quad H_1 \int_S \rho \, dS + \int_S \alpha \{mH_1^2 - (m-1)H_2\} \, dS \\ - \frac{1}{m} \int_S (K_{ji}v^j C^i - \alpha K_{ji} C^j C^i) \, dS = 0.$$

Eliminating $\int_S \rho \, dS$ from these equations, we find

$$(4.3) \quad \int_S (m-1)\alpha(H_1^2 - H_2) \, dS - \frac{1}{m} \int_S (K_{ji}v^j C^i - \alpha K_{ji} C^j C^i) \, dS = 0.$$

If the Riemannian manifold M under consideration is an Einstein space, then

$$K_{ji} = \lambda g_{ji}$$

and consequently we have from (4.3)

$$(4.4) \quad \int_S \alpha(H_1^2 - H_2) \, dS = 0,$$

where

$$(4.5) \quad H_1^2 - H_2 = \frac{1}{m^2(m-1)} \sum_{a \neq b} (k_a - k_b)^2.$$

Using (4.4) and (4.5), Prof. Katsurada proved the theorem mentioned in the introduction of the present paper.

§ 5. Hypersurfaces with constant first mean curvature in a Riemannian manifold admitting an infinitesimal homothetic transformation.

We assume in this section that the Riemannian manifold admits an infinitesimal homothetic transformation v^h and the first mean curvature H_1 of the hypersurface is constant. Then the first, the second and the third integral formulas become respectively

$$(5.1) \quad H_1 \int_S \alpha \, dS + c \int_S dS = 0$$

$$(5.2) \quad cH_1 \int_S dS + \int_S \alpha \{mH_1^2 - (m-1)H_2\} \, dS + \frac{1}{m} \int_S \alpha K_{ji} C^j C^i \, dS = 0$$

$$(5.3) \quad \int_S K_{ji} v^j C^i \, dS = 0.$$

Eliminating $\int_S dS$ from (5.1) and (5.2), we find

$$(5.4) \quad \int_S \alpha \left[(m-1)(H_1^2 - H_2) + \frac{1}{m} K_{ji} C^j C^i \right] dS = 0.$$

From this we have

THEOREM 5.1. *Let M be an $(m+1)$ -dimensional orientable Riemannian manifold and S a closed orientable hypersurface in M whose first mean curvature is constant. We suppose that M admits a one-parameter group of homothetic transformations such that the inner product of the generating vector v^h and the normal C^h to the hypersurface does not change the sign (and $\neq 0$) on S and that the Ricci curvature K_{ji} with respect to the normal C^h is non-negative on S . Then every point of S is umbilical and $K_{ji} C^j C^i = 0$ on S .*

We assume next that the Riemannian manifold under consideration is an Einstein space: $K_{ji} = \lambda g_{ji}$. Then from (5.3) we have

$$(5.7) \quad \lambda \int_S \alpha dS = 0,$$

λ being a constant.

Thus if α does not change the sign and is not identically zero on S , we must have $\lambda = 0$ and consequently $K_{ji} = 0$. Thus we have

THEOREM 5.2. *Let M be an $(m+1)$ -dimensional orientable Einstein space and S a closed orientable hypersurface in M whose first mean curvature is constant. We suppose that M admits a one-parameter group of homothetic transformations such that the inner product of the generating vector v^h and the normal C^h to S does not change the sign and is not identically zero on S . Then the curvature scalar of the space vanishes and every point of the hypersurface is umbilical.*

If $\alpha = 0$, then (1.2) becomes

$$c \int_S dS = 0,$$

from which

$$c = 0.$$

Thus we have

THEOREM 5.3. *Let M be an $(m+1)$ -dimensional orientable Riemannian manifold and S a closed orientable hypersurface in M . If we suppose that M admits a one-parameter group of homothetic transformations such that the generating vector v^h is always tangent to M . Then the group is that of motions.*

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