

On Integral Invariants and Betti Numbers of Symmetric Riemannian Manifolds, I.

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(Received Nov. 15, 1947)

In his classical paper E. Cartan proved the important theorem that the p -th Betti-number of a compact symmetric Riemannian manifold M is equal to the number of linearly independent invariant differentials of rank p defined on M . Now there exist two kinds of compact symmetric Riemannian manifolds. The first class consists of the group-manifolds of simple compact Lie groups. The fundamental groups of these manifolds are semi-simple. The Poincaré-polynomials of compact simple Lie groups of four classes were first determined by R. Brauer. Pontrjagin investigated the homological properties of these manifolds and determined their homology basis. The second class of symmetric Riemannian manifolds are those whose fundamental groups are simple. Among the manifolds of these kinds there exist those which are at the same time algebraic varieties. The Betti numbers and the correspondingly homology basis of these manifolds were determined by C. Ehresmann. (The manifolds $S(n)$, $C(n)$, $A(n, k)$)¹⁾. In this paper I will give the complete table of Betti numbers of compact symmetric Riemannian manifolds by the method of E. Cartan.

Notations.

R_n : n -dimensional real vector space.

P_n : n -dimensional complex vector space.

k : The field of all real numbers, K : That of all complex numbers.

E or E_n : n -dimensional identity matrix, $\delta(ij)$ or δ_{ij} : $E = \delta(ij)$.

I or I_n : The skew matrix $\begin{vmatrix} & E_{n/2} \\ -E_{n/2} & \end{vmatrix}$, $\epsilon(ij)$ or ϵ_{ij} : $I = \epsilon(ij)$.

$US(n)$, $U(n)$, $USp(n)$, $O(n)$: unitary unimodular group, unitary group, unitary-symplectic group and real proper orthogonal group respectively.

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(1) These are manifolds in which the Betti numbers of odd dimensions are all zero, see E. Cartan, *Selecta*, p. 103; Ehresmann, [3].

- $R(n, k)$: The set of all k -dimensional linear subspaces of R_n .
- $A(n, k)$: The set of all k -dimensional linear subspaces of P_n .
- $S(n, k)$: The set of all k -dimensional linear subspaces of P_n invariant with respect to the operation $x \rightarrow \hat{x} = I\bar{x}$, ($n=2m, k=2k'$).
- $S(n)$: The set of all zero systems $x \rightarrow y = Sx$ such that the skew matrix S is at the same time orthogonal, $S^2 = -1$, ($n=2 \cdot m$).
- $C(n)$: The set of all m -dimensional linear subspaces of P_n such that $\mathfrak{M} \wedge \hat{\mathfrak{M}} = 0$, where $\hat{\mathfrak{M}}$ is the transform of \mathfrak{M} by $x \rightarrow \hat{x}$, ($n=2 \cdot m$).

Part I.

Representations; Linear invariants.

Chapter I.

The harmonics of the manifold $A^+(n)$.

1. We denote by $A^+(n)$ the set of all unimodular unitary matrices of n dimensions which are at the same time symmetric: $A^* = A$. $A^+(n)$ is then a symmetric Riemannian manifold whose group of displacements is $A \rightarrow T^*AT$, where $T \in US(n)$. The identity matrix E_n itself is contained in $A(n)$. The group of rotations associated with this point is nothing but the real orthogonal group. The automorphism of the group $US(n)$ associated with E is thus $T \rightarrow \bar{T}$, \bar{T} being the complex conjugate of T .

2. The generic matrix A of the manifold $A^+(n)$ satisfy the relation $\bar{A} = A^{-1}$, A is thus a transvection in the sense of E. Cartan. Let us see that any $A \in A^+(n)$ can be written in the form

$$A = R^{-1}\theta R, \quad R \in O(n).$$

where $\theta = \varepsilon_1 + \dots + \varepsilon_n$, $\varepsilon_i = \exp(2\pi\sqrt{-1}\theta_i)$. We say that a linear subspace $\mathfrak{M} \subset P_n$ is a real linear subspace or simply real if it is invariant by the operation $x \rightarrow \bar{x}$ (=the complex conjugate of x) which is invariant under the group $O(n)$. Any real linear subspace can be generated by a number of mutually orthogonal real vectors (the vectors whose components are real). Now let ε_i be an eigenvalue of A , x_i its corresponding eigenvector:

$$Ax_i = \varepsilon_i x_i.$$

By the relation $A^{-1} = \bar{A}$ we obtain $A\bar{x}_i = \bar{\varepsilon}_i \bar{x}_i$. The eigenspace of ε_i is thus real. We can thus then n real vectors x_1, \dots, x_n such that $x_i x_j = \delta_{ij}$ and

$$A \| x_1, \dots, x_n \| = \| x_1, \dots, x_n \| \begin{pmatrix} \varepsilon_1 & & \circ \\ & \ddots & \\ & & \varepsilon_n \end{pmatrix}, \quad \varepsilon_1 \dots \varepsilon_n = 1$$

We have thus $A = R^{-1}\theta R$, where $R = \| x_1, \dots, x_n \|$, $R \in O(n)$.

3. It may be seen that for any $A \in A^+(n)$ there exists a transvection $\theta^{\frac{1}{2}}$ such that A is the transform of E by $\theta^{\frac{1}{2}}$. Indeed, if $A = R^{-1}\theta R$, then by putting $\theta^{\frac{1}{2}} = R^{-1}\theta^{\frac{1}{2}}R$ ($\theta^{\frac{1}{2}} = e^{\pi\sqrt{-1}\theta_1} + \dots + e^{\pi\sqrt{-1}\theta_n}$) we obtain $A = \theta^{\frac{1}{2}}E(\theta^{\frac{1}{2}})^*$, and, moreover, $\theta^{\frac{1}{2}}$ is a transvection: $\bar{\theta}^{\frac{1}{2}} = (\theta^{\frac{1}{2}})^{-1}$.

Let $A + dA$ be a point near A . We transform the differential dA back to the point E by the transformation $\theta^{\frac{1}{2}}$: $\delta\theta = \theta^{-\frac{1}{2}}dA\theta^{-\frac{1}{2}}$. A simple calculation shows that $\delta\theta$ can be written as

$$\delta\theta = R^{-1} \left[\theta^{-1}d\theta + (\theta^{\frac{1}{2}}\delta R\theta^{-\frac{1}{2}} - \theta^{-\frac{1}{2}}\delta R\theta^{\frac{1}{2}}) \right] R, \quad \delta R = (dR)R^{-1}$$

So that it can easily be seen that $\delta\theta$ is an infinitesimal transvection: $\bar{\delta\theta} = -\delta\theta$. The (i, j) -elements of this matrix is

$$\begin{aligned} 2\pi\sqrt{-1}\delta\theta_i, & \quad i=j; \quad \sum_i \delta\theta_i = 0 \\ 2\sqrt{-1}\sin\frac{\theta_i - \theta_j}{2}\delta u_{ij}, & \quad i \neq j \end{aligned}$$

The representation of A in the form $R^{-1}\theta R$ is unique in some neighbourhood and we find as the volume-element of the manifold $A^+(n)$ the following expression:

$$\omega = \Delta[\omega]d\theta_1 \dots d\theta_{n-1}, \quad \Delta = \prod_{i < j} \sin \frac{\theta_i - \theta_j}{2}$$

4. Let $a(ij)$ be the elements of the generic matrix $A \in A^+(n)$, $a(ij) = a(ji)$. We construct the quantities

$$a(i_1, \dots, i_f; j_1, \dots, j_f) = \sum \varepsilon(P) a(i_1 j_{1'}) \dots a(i_f j_{f'}), \quad (1 \leq f \leq n-1)$$

where $\varepsilon(P)$ is the sign of the permutation $P: 12\dots f \rightarrow 1'2'\dots f'$ and the summation is extended over all P . By means of the generic element of the group $US(n)$, $a(\dots; \dots)$ are transformed according to the irreducible representation of the group $US(n)$ of signature $(2, \dots, 2, 0, \dots, 0)$, where 2 appears f times. The quantity

$$a_f = \sum_{i_1 < \dots < i_f} a(i_1, \dots, i_f; i_1, \dots, i_f)$$

stays invariant under the group $O(n)$ and we have

$$a_f = \sum_{i_1 < \dots < i_f} \varepsilon_{i_1} \dots \varepsilon_{i_f}$$

where $\varepsilon_1, \dots, \varepsilon_n$ are the roots of A .

5. We call "zonal" a function defined on $A^+(n)$ which is invariant under the group g . We see that for any A the roots $\varepsilon_1, \dots, \varepsilon_n$ are determined uniquely except their order and the $n-1$ quantities $\zeta_1, \dots, \zeta_{n-1}$ with

$$\zeta_f = \sum_{i_1 < \dots < i_f} \varepsilon_{i_1} \dots \varepsilon_{i_f} \quad (1 \leq f \leq n-1)$$

constitute a table of basic invariants of the group g . Any zonal can thus be expanded in the form

$$\zeta \sim \sum \Lambda_{a_1, \dots, a_p} \zeta_{a_1, \dots, a_p}$$

where the right side is a linear combination of the monomials

$$\zeta^*(f_1, \dots, f_{n-1}) = (\zeta_{n-1})^{a_1} (\zeta_{n-2})^{a_2} \dots (\zeta_1)^{a_{n-1}}$$

We write this monomial as $\zeta^*(f_1, \dots, f_{n-1})$, where (f_1, \dots, f_{n-1}) is the

conjugate diagram of $(\overbrace{n-1, \dots, n-1}^{2a_1}, \overbrace{1, \dots, 1}^{2a_{n-1}})$. We say that the monomial $\zeta^*(f_1, \dots, f_{n-1})$ is higher than $\zeta^*(f'_1, \dots, f'_{n-1})$ if and only if (f_1, \dots, f_{n-1}) is higher than (f'_1, \dots, f'_{n-1}) in the usual sense.

The angles $(\theta_1, \dots, \theta_{n-1})$ and $(\theta'_1, \dots, \theta'_{n-1})$ are said to be homologous if the $(\varepsilon_1, \dots, \varepsilon_n)$ and $(\varepsilon'_1, \dots, \varepsilon'_n)$ constructed from θ and θ' differ only by their order. There exists a polygon P in $(n-1)$ -space of $(\theta_1, \dots, \theta_{n-1})$ such that no two points of P are homologous and that for any $(\theta_1, \dots, \theta_{n-1})$ there exists a point of P which is homologous with (θ) ; this P may be defined by

$$\theta_1 \leq \theta_2 \leq \dots \leq \theta_n; \quad \theta_n - \theta_1 \leq 1; \quad \theta_1 + \dots + \theta_n = 0$$

Two zonals ζ, ζ' are said to be orthogonal if

$$\int_P \zeta \bar{\zeta}' \Delta d\theta_1 \dots d\theta_{n-1} = 0$$

Let $\zeta(f_1, \dots, f_{n-1})$ be zonals obtained from $\zeta^*(f_1, \dots, f_{n-1})$ by means of orthogonalization. Then

$$\zeta(f_1, \dots, f_{n-1}) = \zeta^*(f_1, \dots, f_{n-1}) + (\text{terms lower than } \zeta^*(f_1, \dots, f_{n-1}))$$

6. We have already seen that $n-1$ quantities $a(\dots, \dots)$ constitute harmonic sets. We \times -multiply these quantities and construct the following representation which is also a harmonic set:

$$Z^*(f_1, \dots, f_{n-1}) : Z_{n-1}^{a_1}, \dots, Z_1^{a_{n-1}}.$$

This representation contains only one irreducible representation of type (f_1, \dots, f_{n-1}) . This is the irreducible representation of the highest weight contained in Z^* . The components of Z may be written in the form

$$A(i_1, \dots, i_{f_1}; j_1, \dots, j_{f_2}; \dots; k_1, \dots, k_{f_{n-1}})$$

where A is skew symmetric with respect to the indices $i_1, j_1, \dots, k_1; i_2, \dots; \dots$ respectively. A are polynomials of $a(i_1, \dots, i_f; j_2, \dots, j_f)$ and the components A of the irreducible representation Z may be obtained from A by means of a definite process containing only symmetrization and alternation corresponding to the operator of Young operating on $(i_1, \dots, i_{f_1}; \dots)$ in this natural order. It can readily be seen that Z admits a linear invariant with respect to the subgroup g . Indeed, by using the fact that f_1, \dots, f_{n-1} are all even we see that

$$\delta(i_1 i_2) \dots \delta(j_1 j_2) \dots A(i_1 i_2 \dots; j_1 j_2 \dots; \dots)$$

is invariant. This is a linear combination of the monomials $\zeta^*(f'_1, \dots, f'_{n-1})$. The highest term may be obtained from $A(11\dots; 22\dots; \dots)$ which is equal to $\zeta^*(f_1, \dots, f_{n-1})$. Thus this invariant is of the form

$$\zeta'(f_1, \dots, f_{n-1}) = \zeta^*(f_1, \dots, f_{n-1}) + (\text{terms lower than } \zeta^*(f_1, \dots, f_{n-1}).)$$

Because $\zeta'(f_1, \dots, f_{n-1})$ are mutually orthogonal, we see easily that this coincides with $\zeta(f_1, \dots, f_{n-1})$ except a constant factor.

7. By the theory of E. Cartan we readily conclude that for any monomial $\zeta^*(f_1, \dots, f_{n-1})$ there exists an uniquely determined irreducible harmonic set admitting a linear invariant with respect to the subgroup g which is a polynomial in $\zeta_1, \dots, \zeta_{n-1}$ such that its highest terms is $\zeta^*(f_1, \dots, f_{n-1})$ and that any harmonic of the manifold $A^+(n)$ can be obtained in this manner. We thus have the following

Theorem 1. The quantities $Z(f_1, \dots, f_{n-1})$ constitute a complete harmonic set of the manifold $A^+(n)$. An irreducible representation of the group

$US(n)$ of signature $\zeta(f_1, \dots, f_{n-1})$ is contained in a harmonic set of the manifold $A^+(n)$ if and only if $f_1 \equiv f_2 \equiv \dots \equiv 0 \pmod{2}$.

Chapter II.

The harmonics of the manifold $A^-(n)$.

1. The manifold $A^-(n)$ is the set of all skew symmetric unitary unimodular matrices: $A^* + A = 0$. The group of displacements is $A \rightarrow T^*AT$, $T \in US(n)$. The skew matrix I is contained in $A^-(n)$ and the group of rotation g with center the point I is the group $USp(n)$ consisting of all the elements of the group $US(n)$ which are invariant under the involutive automorphism $\bar{T} \rightarrow I^{-1}\bar{T}I$. A transvection is an element of $US(n)$ such that $\theta^{-1} = I^{-1}\bar{\theta}I$. There exists a one to one correspondence between the points of $A^-(n)$ and the set of transvections described by

$$A = \theta I, \quad \theta = -AI$$

Let θ be a transvection. By the same argument as in the case of the manifold $A^+(n)$ it is possible to show that if ϵ is an eigenvalue of θ , then the corresponding eigenspace is invariant with respect to the operation $x \rightarrow \bar{I}x (= \hat{x})$ which is invariant under the group $USp(n)$ and that θ can be written as

$$\theta = R^{-1}\theta R, \quad R \in USp(n); \quad \theta = \theta_0 + \theta_0$$

where $\theta_0 = \epsilon_1 + \dots + \epsilon_m$, $\epsilon_i = \exp(2\pi\sqrt{-1}\theta_i)$. We call $\epsilon_1, \dots, \epsilon_m$ the roots of A . For given A , $\epsilon_1, \dots, \epsilon_m$ are determined uniquely except their order and we see that the quantities $\zeta_1, \dots, \zeta_{m-1}$ with $\zeta_f = \sum_{i_1 < \dots < i_f} \epsilon_{i_1} \dots \epsilon_{i_f}$ are fundamental-invariants of A with respect to the group g .

2. We now construct the harmonic set of $A^-(n)$ corresponding to the invariant ζ_f . Instead of $a(i_1 i_2 \dots; j_1 j_2 \dots)$ of $A^+(n)$ we define

$$Z_f: A(i_1 \dots i_{2f}) = \sum_P \epsilon(P) P a(i_1 i_2) \dots a(i_{s-1} i_s), \quad (s=2f)$$

where $a(ij)$ are the elements of the matrix A , P is the permutation $12 \dots (2f) \rightarrow 1'2' \dots (2f)'$ and the summation is extended over all P . The quantities Z_f constitute a harmonic set and give an irreducible representation of signature $(1, 1, \dots, 1, 0, \dots, 0)$, where 1 appears $2f$ times. We \times -multiply these quantities and construct:

$$Z: Z_{m-1}^{a_1} \times \dots \times Z_1^{a_{m-1}}$$

Z contains only one irreducible representation of the highest weight. This is of signature (f_1, \dots, f_{n-2}) , where (f_1, \dots, f_{n-2}) is the conjugate of $(\overbrace{2(m-1), \dots, 2(m-1)}^{a_1}, \dots, \overbrace{2, \dots, 2}^{a_{m-1}})$. We denote this by $Z(f_1, \dots, f_{n-2})$. The components of Z are uniquely determined and can be written as $A(i_1 i_2, \dots; j_1 j_2, \dots; \dots)$, A' are skew symmetric with respect to $i_1, i_2, \dots; j_1, j_2, \dots; \dots$ respectively. The zonale of $A^-(n)$ corresponding to Z is

$$\varepsilon(i_1 i_2) \varepsilon(i_3 i_4) \dots \varepsilon(j_1 j_2) \varepsilon(j_3 j_4) \dots Z(i_1 i_2 \dots; j_1 j_2 \dots; \dots)$$

which is a linear combination of the monomials $\zeta_{m-1}^{a_1'} \dots \zeta_1^{a_{m-1}'}$, the highest term being obtained from $A(12 \dots; 12 \dots; \dots)$. We denote this by $\zeta(f_1 f_2 \dots)$.

3. We write θ in the form $\theta = R^{-1} \theta R$. If we put $\theta^{\frac{1}{2}} = R^{-1} \theta^{\frac{1}{2}} R$, where the angles of $\theta^{\frac{1}{2}}$ are just the halves of those of θ , then it can readily be seen that the point $A = \theta I$ corresponding to θ is just the transform of I by $\theta^{\frac{1}{2}}$. Let $\theta + d\theta$ be a transvection corresponding to the point $A + dA$ near A . We transform $d\theta$ back to the point I by the transformation $\theta^{\frac{1}{2}}$: $\delta\theta = \theta^{-\frac{1}{2}} \cdot d\theta \cdot \theta^{-\frac{1}{2}}$. Then

$$\delta\theta = R^{-1} \left[\theta^{-1} d\theta + (\theta^{\frac{1}{2}} \delta R \theta^{-\frac{1}{2}} - \theta^{-\frac{1}{2}} \delta R \theta^{\frac{1}{2}}) \right], \quad \delta R = (dR) R^{-1}.$$

Now the representation of θ in the form $R^{-1} \theta R$ is not unique. Different R' give the same θ if they are of the form ρR . For generic θ ρ must be of the form $\rho = A_1 + \dots + A_m$, where A_i are matrices of the form

$$\left\| \begin{array}{cc} a & b \\ -\bar{b} & \bar{a} \end{array} \right\|, \quad a\bar{a} + b\bar{b} = 1$$

(We arrange the indices in the order $1, m+1, 2, m+2, \dots, m, m+m = n$). By means of this uncertainty we can normalize $\delta\theta$ such that $\delta u_{ii} = \delta u_{m+i, m+i} = 0$, ($i=1, 2, \dots, m$), $\delta u_{i, m+i} = \delta u_{m+i, i} = 0$, ($i=1, 2, \dots, m$). R has then a definite sense. The (ij) -elements of the matrix $\delta\theta$ are

$$\delta u_{ii} = \delta u_{m+i, m+i} = 2\pi \sqrt{-1} \delta\theta_i; \quad \sum_i \delta\theta_i = 0$$

$$\delta u_{im+j} = -\delta u_{m+ij} = \sqrt{-1} \sin(\theta_i - \theta_j/2) \tilde{\omega}_{ii} \quad (i \neq j)$$

$$\delta u_{ij} = \delta u_{m+i, m+j} = \sqrt{-1} \sin(\theta_i - \theta_j/2) \omega_{ij} \quad (i \neq j)$$

The volume element of the manifold $A^-(n)$ is thus

$$\omega = \Delta[\omega_j] d\theta_1 \dots d\theta_{m-1}$$

where

$$\Delta = \prod_{i < j} \sin^4 \frac{\theta_i - \theta_j}{2}$$

Theorem 1. 2. The quantities $Z(f_1, \dots, f_{n-2})$ constitute a complete harmonic set of the manifold $A^-(n)$. The irreducible representation of the group $US(n)$ of signature (f_1, \dots, f_{n-1}) is contained in a harmonic set of the manifold $A^-(n)$ if and only if the columns of the diagram (f_1, \dots, f_{n-1}) are all even. In particular, $f_{n-1} = 0$.

Chapter III.

The harmonics of the manifold $A(n, k)$; $k \leq h(=n-k)$.

1. The manifold $A(n, k)$ is the set of all k -dimensional linear subspaces of P_n . Let \mathfrak{M} be a linear subspace of P_n which is contained in $A(n, k)$. A unitary coordinate system e_1, \dots, e_n is said to be associated with \mathfrak{M} if $e_1, \dots, e_k \in \mathfrak{M}$. With respect to this coordinate system the group of rotations consist of all transformations of the form $T_k + T_h$. The involution of the group $US(n)$ associated with \mathfrak{M} is $A \rightarrow JAJ$, where $J = E_k + -E_h$.

Let \mathfrak{M}_1 be two linear subspaces of P , where $\dim \mathfrak{M}_1 = m_1$, $\dim \mathfrak{M}_2 = m_2$, $m_1 \leq m_2$. Then we can take unitary frames x_1, \dots, x_{m_1} ; y_1, \dots, y_{m_2} of \mathfrak{M}_1 and \mathfrak{M}_2 such that $(x_i, y_i) = \cos \theta_i$, ($i=1, 2, \dots, m_1$), and that all other (xy) vanish. In fact, let $\mathfrak{M}_1^0, \mathfrak{M}_2^0$ be linear subspaces of \mathfrak{M}_1 and \mathfrak{M}_2 whose vectors are all perpendicular with \mathfrak{M}_2 and \mathfrak{M}_1 respectively. Then the subspaces $\overline{\mathfrak{M}}_1 = \mathfrak{M}_1 - \mathfrak{M}_1^0$, $\overline{\mathfrak{M}}_2 = \mathfrak{M}_2 - \mathfrak{M}_2^0$ are of the same dimension, say m . Let $P_{\overline{\mathfrak{M}}_1}, P_{\overline{\mathfrak{M}}_2}$ be orthogonal projections on $\overline{\mathfrak{M}}_1$ and $\overline{\mathfrak{M}}_2$ respectively. The operator $P_{\overline{\mathfrak{M}}_1}, P_{\overline{\mathfrak{M}}_2}$ leaves invariant the subspace $\overline{\mathfrak{M}}_1$, and is hermitian in $\overline{\mathfrak{M}}_1$. Let x_1, \dots, x_m be eigenvectors of $P_{\overline{\mathfrak{M}}_1} P_{\overline{\mathfrak{M}}_2}$ in $\overline{\mathfrak{M}}_1$. The projections of x_i into \mathfrak{M}_2 are not zero, and if we denote by θ_i the angle between x_i and $P_{\overline{\mathfrak{M}}_2} x_i = y_i$, then $\cos^2 \theta_i$ are eigenvalues of $P_{\overline{\mathfrak{M}}_1} P_{\overline{\mathfrak{M}}_2}$ in \mathfrak{M}_1 . The vectors

$y_i = (\cos \theta_i)^{-1} \bar{y}_i$ constitute a certain frame of $\bar{\mathcal{M}}_2$ and moreover, a system of eigenvectors of $P_{\bar{\mathcal{M}}_2} P_{\bar{\mathcal{M}}_1}$ in $\bar{\mathcal{M}}_2$. The corresponding eigenvalues are again $\cos^2 \theta_1, \dots, \cos^2 \theta_m$. If we take in \mathcal{M}_1^0 and \mathcal{M}_2^0 orthogonal frames $x_{1+m_1}, \dots, x_{m_1}$ and $y_{1+m_2}, \dots, y_{m_2}$ arbitrarily, then it can readily be seen that these vectors satisfy the conditions of the assertion. This can be carried out by purely elemental geometric device.

2. A transvection is a transformation θ of $US(n)$ satisfying $J\theta J = \theta^{-1}$. There exists an one to one correspondence between the set of transvections and the linear subspaces of arbitrary dimensions of the space P_n described by

$$S = \theta J, \quad \theta = SJ$$

where S denotes the reflexion with respect to the subspace \mathcal{M} . The correspondence between S and \mathcal{M} may be described as:

$$\mathcal{M} = (x; 2x = (S+1)x); \quad S = 2P_{\mathcal{M}} - 1.$$

Let $\mathcal{M}_0, \mathcal{N}$ be two linear subspaces of P and let $\dim \mathcal{M}_0 = k, \dim \mathcal{N} = m$. Then there exists a coordinate system e_1, \dots, e_n associated with \mathcal{M}_0 ($\{e_1, \dots, e_k\} = \mathcal{M}$) such that the transvection associated with \mathcal{N} take the form

$$D(\theta_1) \dot{+} \dots \dot{+} D(\theta_k) \dot{+} \left\| \begin{array}{c} E_p \\ -E_p \end{array} \right\|$$

Suppose first that $k \leq m \leq n/2$, then there exists a system of vectors $x_1, \dots, x_k \in \mathcal{M}_0, x_i x_j = \delta_{ij}; y_1, \dots, y_m \in \mathcal{N}, y_i y_j = \delta_{ij}$ such that $x_i y_i = \cos \theta_i$ and that all other x, y vanish. We take cartesian frame associated with \mathcal{M}_0 such that:

$$e_i = x_i \quad (i=1, 2, \dots, k), \quad y_i = \cos \theta_i e_i + \sin \theta_i \cdot e_{k+i}, \\ e_{2k+1}, \dots, e_m \in \mathcal{N},$$

Then the subspace \mathcal{N} is generated by m vectors which are two rows of the matrix

$$B: \left\| \begin{array}{cccc} \cos \theta_1 & \sin \theta_1 & & \\ & & \cos \theta_2 & \sin \theta_2 & \dots \\ & & & & & E_{m-k} & 0 \end{array} \right\|$$

where the index is arranged in the order $1, k+1, 2, k+2, \dots, k, 2k, 2k+1, \dots, n$. The reflexion with respect to \mathcal{N} is $S = 2B^* B - 1$, and the

corresponding transvection is $\theta = SJ$. The explicit calculation gives the desired result. The case $k > m$ can be treated in analogous manner.

8. Let \mathfrak{M} be a k -dimensional linear subspace of P , θ be the corresponding transvection. The reflexion with respect to \mathfrak{M} is then θJ . Now we have seen that any θ associated with \mathfrak{M} , $\dim \mathfrak{M} = k$ can be written as

$$\theta = R^{-1}\theta R, \quad \theta = D(\theta_1) + \dots + D(\theta_k) + E_{n-2k}$$

where $R = T_k + T_h(g)$. Consider the transvection $\theta^{\frac{1}{2}}$ defined by

$$\theta^{\frac{1}{2}} = R^{-1}\theta^{\frac{1}{2}}R, \quad \theta^{\frac{1}{2}} = D(\theta_1/2) + \dots + D(\theta_k/2) + E_{n-2k}$$

Then the subspace \mathfrak{M} is the transform of $\mathfrak{M}_0 = \{e_1, \dots, e_k\}$ by $\theta^{\frac{1}{2}}$. Indeed, the reflection with respect to the transform of \mathfrak{M}_0 by $\theta^{\frac{1}{2}}$ is

$$\theta^{\frac{1}{2}}J(\theta^{\frac{1}{2}})^* = \theta^{\frac{1}{2}}J(\theta^{\frac{1}{2}})^*J, \quad J = \theta^{\frac{1}{2}} \cdot \theta^{\frac{1}{2}}J = \theta J = S.$$

Now let $\theta + d\theta$ be a transvection associated with $\mathfrak{M} + d\mathfrak{M} \in A(n, k)$ near \mathfrak{M} . We transform $d\theta$ back to \mathfrak{M}_0 by the transformation $\theta^{\frac{1}{2}}$:

$$\delta\theta = \theta^{-\frac{1}{2}}d\theta \cdot \theta^{-\frac{1}{2}}.$$

This shows that $\delta\theta$ is an infinitesimal transvection: $J\delta\theta J = -\delta\theta$. We have, in the same manner as in A^+ and A^- , as the volume-element between two zones $(\theta_1, \dots, \theta_k)$ and $(\theta_1 + d\theta_1, \dots, \theta_k + d\theta_k)$ the following expression;

$$\Delta d\theta_1 \dots d\theta_k; \quad \Delta = \Pi(\cos \theta_i - \cos \theta_j)^2 \Pi \sin \theta_i \Pi \sin^{2(n-2k)}(\theta_i/2)$$

4. The *zonales* are functions depending on k arguments $\cos^2 \theta_1/2, \dots, \cos^2 \theta_k/2$ invariant with respect to any permutation among them and thus are expressible by means of k quantities

$$\zeta_f = \sum_{i_1 < \dots < i_f} \cos^2(\theta_{i_1}/2) \dots \cos^2(\theta_{i_f}/2), \quad (1 \leq f \leq k)$$

Let $p(i_1, \dots, i_k)$ be Plücker coordinates of $A(n, k)$. Consider k quantities Z_1, \dots, Z_k .

$$Z_f: \sum_j p(i_1 \dots i_f j_1 \dots j_g) \bar{p}(k_1 \dots k_f j_1 \dots j_g).$$

These quantities constitute harmonic sets of the manifold $A(n, k)$. The zonale of Z_f is just ζ_f . Any harmonic set of the manifold $A(n, k)$ may thus be obtained from Z_1, \dots, Z_k by means of \times -multiplication. Let $Z(f_1, \dots, f_k)$ be the representation of the highest weight contained in

$$Z_k^{a_1} \dots Z_1^{a_k}$$

where (f_1, \dots, f_k) is the conjugate of $(\underbrace{k, \dots, k}_{a_1}, \dots, \underbrace{1, \dots, 1}_{a_k})$. The zonale of $Z(f_1, \dots, f_k)$ is

$$\zeta(f_1, \dots, f_k) = (\zeta_k)^{a_1} \dots (\zeta_1)^{a_k} + (\text{terms lower than } \zeta_k^{a_1} \dots \zeta_1^{a_k}).$$

The representation given by $Z(f_1, \dots, f_k)$ is of signature (h_1, \dots, h_{n-1}) :

$$h_i = f_i + f_1, \quad (i = 1, 2, \dots, k), \quad h_{i+1} = \dots = h_{n-2k} = f_1 \\ h_i + h_{n-i+1} = 2f_1$$

and we obtain the following.

Theorem 1. 3. The quantities

$$Z(f_1, \dots, f_k) \quad f_1 \geq f_2 \geq \dots \geq f_k \geq 0$$

with any f_1, f_2, \dots, f_k constitute a complete harmonic set of the manifold $A(n, k)$. The irreducible representation of the group $US(n)$ of signature (h_1, \dots, h_{n-1}) is contained in a harmonic set of the manifold $A(n, k)$ if and only if

$$h_1 = h_2 + h_{n-1} = \dots = h_k + h_{n-k+1} = 2h_{k+1} = \dots = 2h_{n-k}.$$

Chapter IV.

Some lemmas on linear invariants.

1. Let M be a compact homogenous manifold with fundamental group G , and suppose that G is a Lie group. Let $\Gamma(G)$ be an irreducible representation of G , $\Gamma(g)$ be the representation of the group of rotations $g (\subset G)$ derived from $\Gamma(G)$. E. Cartan established the following theorem:

$\Gamma(G)$ is contained in a harmonic set of the manifold M if and only if $\Gamma(g)$ contains a linear invariant. If there exist h linear invariants of $\Gamma(g)$, then there exists h different harmonic sets belonging to the representation $\Gamma(G)$. (see E. Cartan, [2]).

Now we have constructed in the preceding chapters the harmonic sets of the manifolds A^+, A^- by the explicit computation of the zonales. Thus the problems of finding the irreducible representations of the group $US(n)$ admitting a linear invariant with respect to its proper subgroups $O(n)$ or $US(n)$ are completely solved. (This method may afford a most natural

approach to this problem.) We have the following :

Theorem 1. 4. The representation of the group $US(n)$ of signature (f_1, \dots, f_{n-1}) admits a linear invariant with respect to the proper subgroups $O(n)$ and $USp(n)$ if and only if $f_1 \equiv f_2 \equiv \dots \equiv 0 \pmod{2}$ for $O(n)$, and $g_1 \equiv g_2 \equiv \dots \equiv 0 \pmod{2}$ for $USp(n)$ respectively, where g_1, g_2, \dots is the conjugate of f_1, f_2, \dots . In each cases there exists only one linear invariant.

In this chapter I will give a direct verification of this fact.

Lemma. Let $P(f_1, \dots, f_{n-1})$ be an irreducible representation of the real unimodular group $SL(n)$ of signature (f_1, f_2, \dots) . $P(f_1, \dots)$ admits a linear invariant with respect to its proper subgroup $O(n)$ if and only if all f_i are even. *Proof.* Let (g_1, g_2, \dots) be the conjugate of (f_1, f_2, \dots) . We take $g=g_1$ vectors x_1, x_2, \dots in R_n . The components of x_i may be denoted by $(x_i(1), \dots, x_i(n))$. The tensors

$$x_\lambda : x(i_1, \dots, i_\lambda) = \sum \varepsilon(P) P x(i_1) \dots x(i_\lambda)$$

are skew symmetric with respect to i_1, \dots, i_λ and the tensors defined by

$$X_{g_1} \times X_{g_2} \times \dots \times X_{g_f} \quad (f=f_1)$$

or

$$x(i_1, \dots, i_N) = x(i_1, \dots, i_{g_1}) \dots x(k_1, \dots, k_{g_f})$$

constitute a basis of the invariant subspace $P(f_1, \dots, f_{n-1})$. Now the quantities X_λ does not change if we replace the vectors x_1, \dots, x_g by

$$y_1 = x_1, y_2 = x_2 + \lambda_{21} x_1, \dots, y_g = x_g + \lambda_{g1} x_1 + \dots + \lambda_{gg} x_g$$

So that we can replace x_1, \dots, x_g by mutually orthogonal vectors without changing X . Any tensor of signature (f_1, \dots, f_{n-1}) is then a linear combination of the form $X = \sum \wedge_\alpha E_\alpha$, where E_α are basic vectors of $P(f_1, \dots)$ which are of the form

$$E_\alpha = [x_1, \dots, x_{g_1}] [x_2, \dots, x_{g_2}] \dots [x_1, \dots, x_{g_f}]$$

The vectors x_1, \dots, x_g are mutually orthogonal. The only way of constructing orthogonal invariants is the contraction with respect to $\delta(ij)$. We thus obtain as a necessary condition $N = \text{even}$. Any orthogonal invariant is thus a linear combination of the terms

$$\wedge = \delta(i_1 i_2) \dots \delta(i_{N-1} i_N) x(i_1, \dots, i_N)$$

If we use the relation $x_i x_j = 0$, ($i \neq j$), then :

$$\Lambda = \nu \sum \wedge_{\sigma} (x_1 x_1)^{s_1} (x_2 x_2)^{s_2} \dots (x_g x_g)^{s_g}, \quad 2s_1 = f_1, \dots, 2s_g = f_g$$

where $\nu(1'2' \dots N')$ is a number depending only on the permutation $12, \dots, N \rightarrow 1'2' \dots N'$. From which we conclude at once $f_i = 2s_i, \dots$. That is, f_1, \dots, f_{n-1} are all even. We also see that only one linear invariant can exist. Under this condition the required linear invariant is

$$\delta(i_1 i_2) \delta(i_3 i_4) \dots \delta(j_1 j_2) \dots X(i_1 j_1 \dots ; i_2 j_2 \dots ; \dots).$$

This is certainly not identically zero. (Consider the tensor whose components are all zero except $X(12 \dots g ; 12 \dots g ; \dots)$ and its homolog).

Lemma. The irreducible representation of the group $US(n)$ of signature (f_1, \dots, f_{n-1}) admits a linear invariant with respect to the subgroup $USp(n)$ if and only if all f_i are even.

We take a generic tensor X of $P(f_1, \dots, f_{n-1})$ in the form

$$X = \sum [x_1 \dots x_{g_1}] [x_1 \dots x_{g_2}] \dots$$

Any invariant may be obtained by contraction with respect to $\epsilon(ij)$. If the term $[x, \dots x] [x, \dots x] \dots$ does not vanish by this contraction, then it is possible to show that $x, \dots x$ can be taken such that :

$$x_{1+i} = y_{1+i}, \quad x_{2+i} = y_{2+i} + z_{2+i}, \quad z_{2+i} \perp \{y_2, y_1, \dots, y_{2+i}, y_{1+i}\}, \quad y_{2+i} = 1 \bar{y}_{1+i} \\ (i=0, 2, \dots).$$

From this follows at once the required result.

From these lemmas we conclude not only the theorem 1.4, but also the following.

Theorem 1.5. The irreducible representation of the group $GL(n, K)$ of signature (f_1, \dots, f_n) admits a linear invariant with respect to its proper subgroups $O^+(n)$ or $Sp(n)$ if and only if $f_i - f_n \equiv 0 \pmod{2}$ for $O(n)$ and $g_1 \equiv g_2 \equiv \dots \equiv 0 \pmod{2}$ for $Sp(n)$.

Part II.

The Betti-numbers.

Chapter I.

Formal preparation.

1. We consider a set (Q) of all (h, k) matrices in k or K :

$$\mathcal{Q} : (\omega_{i\lambda}), \quad (1 \leq i \leq h, 1 \leq \lambda \leq k).$$

In \mathcal{Q} we consider a group Γ isomorphic with $GL(k) \times GL(h)$:

$$\mathcal{Q} \rightarrow A\mathcal{Q}B^*, \quad A \in GL(k), \quad B \in GL(h)$$

The outer products of p elements of \mathcal{Q} :

$$\Gamma_p \cdot \omega_{i_1\lambda_1} \dots \omega_{i_p\lambda_p}$$

give a representation of the group Γ . Concerning the decomposition of $\Gamma(p)$ the following fact is known (Ehresmann, [3]) :

$\Gamma(p)$ decomposes into the irreducible representations according to the following scheme :

$$\Gamma(p) \sim \sum P(f_1, \dots, f_k) \times P(g_1, \dots, g_h).$$

where $P(f_1, \dots, f_k)$ is the irreducible representation of the group $GL(k)$ of signature f_1, \dots, f_k ($h \geq f_1 \geq f_2 \geq \dots \geq f_k \geq 0$), $P(g_1, \dots, g_h)$ is the irreducible representation of the group $GL(h)$ of signature (g_1, \dots, g_h) , ($k \geq g_1 \geq g_2 \geq \dots \geq g_h \geq 0$). Moreover, (f_1, \dots, f_k) and (g_1, \dots, g_h) are mutually conjugate. The term of the highest weight in $P(f_1, \dots, f_k) \times P(g_1, \dots, g_h)$ is

$$F_0 \quad \omega_{11} \times \omega_{21} \times \dots \times \omega_{f_1 1} \times \omega_{12} \dots \times \omega_{f_2 2} \times \dots \times \omega_{1g_1} \times \omega_{2g_1} \dots \times \omega_{f_1 g_1}.$$

The components of $P(\dots) \times P(\dots)$ may be obtained from $\omega_{i_1\lambda_1} \dots \omega_{i_p\lambda_p}$ by operating the operator of Young according to the definite manner indicated by the leading term F_0 . By the aid of theorem 1.5. we obtain the following.

Lemma 1. By descending from $GL(k) \times GL(h)$ to its subgroups $O(k) \times O(h)$ or $Sp(k) \times Sp(h)$ the representation $P(f_1, \dots, f_k) \times P(g_1, \dots, g_h)$ admits a linear invariant if and only if $f_1 - f_k \equiv f_2 - f_k \equiv \dots \equiv 0 \pmod{2}$, $g_1 - g_h \equiv g_2 - g_h \equiv \dots \equiv 0 \pmod{2}$ for $O(k) \times O(h)$ and $f_1 \equiv f_2 \equiv \dots \equiv 0 \pmod{2}$, $g_1 \equiv g_2 \equiv \dots \equiv 0 \pmod{2}$ for $Sp(k) \times Sp(h)$ respectively.

2. We denote by (\mathcal{Q}) the set of all skew symmetric matrices \mathcal{Q} in K :

$$\mathcal{Q} = (\omega_{ij}), \quad \omega_{ij} + \omega_{ji} = 0, \quad (i, j, \dots = 1, 2, \dots, n).$$

Consider in (\mathcal{Q}) the group Γ isomorphic with $GL(n)$: $\mathcal{Q} \rightarrow A^* \mathcal{Q} A$, $A \in GL(n)$. Concerning the representation given by the outer products $\Gamma(p) : \omega_{i_1 j_1} \times \dots$

... $\omega_{i_p j_p}$ the following fact is known ([3]):

$\Gamma(\rho)$ decomposes into the irreducible representations according to

$$\Gamma(\rho) \sim \sum \Gamma(f_1, \dots, f_l)$$

where $n > f_1 > f_2 > \dots > f_l > 0$. $\rho = f_1 + \dots + f_l$. The representation $\Gamma(f_1, \dots, f_l)$ is of signature $(f_1, f_2 + 1, \dots, f_l + l - 1, h_1, h_2, \dots)$, (h_1, \dots) is the conjugate of $(f_1 - l + 1, f_2 - l + 2, \dots, f_l)$. The highest term in (f_1, \dots, f_l) is

$$F_0: \omega_{12} \times \omega_{13} \times \dots \times \omega_{1, f_1+1} \times \omega_{23} \times \dots \times \omega_{2, f_2+2} \times \dots \times \omega_{l, l+1} \times \dots \times \omega_{l, l+f_l}$$

The components of $\Gamma(f_1, \dots, f_l)$ may be obtained from $\Gamma(\rho)$ by means of the definite process indicated by the leading term F_0 . By descending from $GL(n)$ to its subgroup $Sp(n)$ this representation admits a linear invariant if and only if the columns of the diagram $(f_1, f_2 + 1, \dots, h_1, h_2, \dots)$ are all even. Under this condition the numbers

$$k_1 = f_1 + f_2, k_2 = f_3 + f_4, \dots, k_p = f_{2p-1} + f_{2p}, \quad (l = 2p)$$

$$k_1 = f_1 + f_2, k_2 = f_3 + f_4, \dots, k_p = f_{2p-1} + f_{2p}, k_{p+1} = f_{2p+1} \quad (l = 2p + 1)$$

are all odd numbers satisfying the condition

$$k_1 \equiv k_2 \equiv \dots \equiv 1 \pmod{4}, \text{ and } k_{p+1} = f_{2p+1} = 1, 1 \leq k_i \leq 2n.$$

By this fact we readily see the following.

Lemma II. By descending from $GL(n)$ to its subgroup $Sp(n)$ the representation $\Gamma(f_1, \dots, f_l)$ admits B_p linear invariants. B_p is the coefficients of the Polynomial

$$P(z) \equiv (1+z)(1+z^5) \dots (1+z^{4\nu+3}) \quad n=2\nu$$

Let $(\mathcal{Q})_0$ be the set of all skew symmetric matrices in K satisfying the relation $\sum \varepsilon_{ij} \omega_{ij} = 0$. This relation is invariant with respect to the group $Sp(n)$ and we have the

Lemma II'. By descending from $GL(n)$ to its subgroup $Sp(n)$ the number of linear invariants contained in the product $\Gamma(\rho): \omega_{i_1 j_1} \times \dots \times \omega_{i_p j_p}$ is the coefficient of z^p in the polynomial

$$P_0(z) \equiv (1+z^5)(1+z^9) \dots (1+z^{4\nu-3}). \quad n=2\nu$$

Proof. Consider the invariant decomposition of ω_{ij} , where ω_{ij} are the elements of the generic matrix of (\mathcal{Q}) :

$$\omega_{ij} = \omega_{ij}^0 + \omega'_{ij}, \quad \omega'_{ij} = \varepsilon_{ij}\omega, \quad \omega = \frac{1}{n} \sum \varepsilon_{ab}\omega_{ab}.$$

The product $I(\rho)$ is

$$\omega_{i_1 j_1} \dots \omega_{i_p j_p} = \omega_{i_1 j_1}^0 \dots \omega_{i_p j_p}^0 + \rho [\omega_{i_1 j_1}^1; \omega_{i_2 j_2}^0 \dots \omega_{i_p j_p}^0]$$

The two terms in the right side of this equation are unitary orthogonal, so that if we denote by P, P^0, P^1 the vector spaces spanned by $\omega_{i_1 j_1} \dots \omega_{i_p j_p}, \omega_{i_1 j_1}^0 \dots \omega_{i_p j_p}^0$ and $[\omega_{i_1 j_1}^1; \omega_{i_2 j_2}^0 \dots \omega_{i_p j_p}^0]$ respectively, then $P = P^0 + P^1$. Let χ, χ^0, χ^1 be the characters of the group $Sp(n)$ induced in P, P^0, P^1 . Then $\chi = \chi^0 + \chi^1$. By integrating over the unitary restricted group $Sp(n)$ we have

$$\int \chi = \int \chi^0 + \int \chi^1.$$

The left side of this equation indicates the number of linear invariants contained in $I(\rho)$, say B_p . The first term of the right side indicates the required number, say B_p^0 . It is easy to see that the second term of the right side is just B_{p-1}^0 . Thus we see $B_p = B_p^0 + B_{p-1}^0$. B_p is thus the coefficient of the Polynomial $P(z)/(1+z)$.

The adjoint group of the group $OL(n)$ is just $\mathcal{Q} \rightarrow A^* \mathcal{Q} A$, where $A \in OL(n)$. The representation $I(f_1, \dots, f_l)$ admits a linear invariant with respect to this group if and only if the numbers $f_1, f_2 + 1, \dots, f_l + l - 1; l_1, l_2, \dots$ are all congruent with each other. We have thus as in the case of lemma II the

Theorem II. The Poincaré Polynomial of the group $OL(n)$ is

$$P(z) \equiv (1+z^3)(1+z^7) \dots (1+z^{4\nu-1}) \quad n = 2\nu + 1.$$

$$P(z) \equiv (1+z^3)(1+z^7) \dots (1+z^{4\nu-5})(1+z^{2\nu-1}) \quad n = 2\nu.$$

3. In this paragraph (\mathcal{Q}) is the set of all symmetric matrices in K .

$$\mathcal{Q} : (\omega_{ij}); i, j, \dots = 1, 2, \dots, n, \quad \omega_{ij} = \omega_{ji}$$

The outer product

$$I(\rho) : \omega_{i_1 j_1} \dots \omega_{i_p j_p}$$

decomposes according to the following scheme :

$$I(\rho) \sim \sum I(f_1, \dots, f_l) \quad n+1 > f_1 > f_2 > \dots > f_l > 0.$$

$\Gamma(f_1, \dots, f_l)$ is the irreducible representation of the group $GL(n)$ of signature $(f_1+1, \dots, f_l+1, h_1, \dots, h_{n-l})$, where h_1, \dots, h_{n-l} is the conjugate of $(f_1-l, f_2-l-1, \dots, f_l-1)$. The highest term in (f_1, \dots, f_l) is

$$\omega_{11} \times \dots \times \omega_{1f_1} \times \omega_{22} \times \dots \times \omega_{2, f_2+1} \times \dots \times \omega_{ll} \times \dots \times \omega_{lf_l+1}$$

By theorem 1.5 we have the following

Lemma III. By descending from $GL(n)$ to its subgroup $O(n)$ the representation $\Gamma(p)$ admits B_p linear invariants, where B_p is the coefficient of

$$P(z) \equiv (1+z)(1+z^5) \dots (1+z^{4\nu-3})(1+z^{2\nu}) \quad \text{for } n=2\nu.$$

$$P(z) \equiv (1+z)(1+z^5) \dots (1+z^{4\nu+1}) \quad \text{for } n=2\nu+1.$$

Let $(Q)_0$ be the set of all symmetric matrices in K satisfying the relation $\sum \omega_{ij} = 0$ which is invariant under the group $OL(n)$. By using the invariant decomposition $\omega_{ij} = \omega_{ij}^0 + \omega'_{ij}$, where $n\omega'_{ij} = \delta_{ij} \sum \omega_{aa}$, we have in the same way as in Lemma II' the following

Lemma III'. The Polynomial $P_0(Z)$ corresponding to ω_{ij}^0 is given by $P_0(z) \equiv P(z)/(1+z)$, where $P(z)$ is the Polynomial of Lemma III.

The adjoint group of the group $USp(n)$ can be reduced to the form $\Omega \rightarrow A^* \Omega A$, $A \in USp(n)$. The representation $\Gamma(f_1, \dots, f_l)$ admits a linear invariant with respect to this subgroup if and only if the columns of the diagram $(f_1+1, f_2+2, \dots, f_l+l, h_1, \dots, h_{n-l})$ are even. We thus see that the numbers $k_1=f_1+f_2, k_2=f_2+f_3, \dots$ are all odd numbers such that $k_1 \equiv k_2 \equiv \dots \equiv -1 \pmod{4}$; $2n > k_i \geq 3$, and we have the following

Theorem III. The Poincaré Polynomial of the group $Sp(n)$ is

$$P(z) \equiv (1+z^3)(1+z^7) \dots (1+z^{4\nu-1}).$$

Chapter II.

The determination of Betti-numbers.

1. $R(n, k)$ Infinitesimal transvection is

$$\delta\theta: \begin{pmatrix} & S \\ -S^* & \end{pmatrix}, \quad S = (\omega_{i\lambda}), \quad 1 \leq i \leq h, \quad 1 \leq \lambda \leq k.$$

The adjoint transformation is $S \rightarrow T_k^* S T_h$, where $T_k \in O(k)$, $T_h \in O(h)$.

(The case of lemma I.)

$S(n, k)$. Infinitesimal transvection is of the same form as $R(n, k)$ but

$$S = \left(-\frac{A}{B} \frac{B}{A} \right), \quad A = (\omega_{i\lambda}), \quad B = (\tilde{\omega}_{i\lambda}), \quad 1 \leq i \leq k/2, \quad 1 \leq \lambda \leq k/2.$$

This is also reduced to the case of lemma I, because the adjoint transformations are defined by $S \rightarrow T_k^* S T_h$, where T_k, T_h are unitary symplectic.

$A(n, k)$. The adjoint transformations are $S \rightarrow T_k^* S T_h$, where T_k, T_h are unitary. This case was treated by Ehresmann.

By lemma I we obtain the following

Theorem IV. The p -th Betti-number of the manifolds $R(n, k)$, $S(n, k)$, $A(n, k)$ are

$R(n, k)$: The number of partitions $p = f_1 + \dots + f_k$ such that $f_i - f_k, g_i - g_k$ are all even, where (g_1, g_2, \dots, g_k) is the conjugate of (f_1, f_2, \dots, f_k) .

$S(n, k)$: $B_p = 0$ if $p \neq 4s$. For $p = 4s$ B_p is equal to the number of partitions of s in $k/2$ non negative integers less than or equal to $h/2$: $S = f_1 + \dots + f_{k/2}, h/2 \geq f_1 \geq f_2 \geq \dots \geq f_{k/2} \geq 0$.

$A(n, k)$: $B_p = 0$ if $p \neq 2s$. For $p = 2s$ B_p is equal to the number of partitions of s in k non negative integers less than $h+1$.

2. The adjoint transformations of the manifolds A^+, A^-, S, C are

$A^+(n)$: $\Omega \rightarrow T^* \Omega T, T \in O(n)$, where $\Omega = (\omega_{ij}), \omega_{ij} = \omega_{ji}, \sum \omega_{ii} = 0$.

$A^-(n)$: $\Omega \rightarrow T^* \Omega T, T \in USp(n)$, where $\Omega = (\omega_{ij}), \omega_{ij} + \omega_{ji} = 0$, and $\sum \epsilon_{ij} \omega_{ij} = 0$ (The cases of lemma III' and lemma II' respectively.)

$S(n)$: $\Omega \rightarrow U \Omega U^*, \Omega + \Omega^* = 0; U \in U(n/2)$,

$C(n)$: $\Omega \rightarrow U \Omega U^*, \Omega = \Omega^*; U \in U(n/2)$,

(The cases treated by Ehresmann).

By lemma II and III we obtain the following

Theorem V. The Poincaré Polynomials of the manifolds A^+, A^-, S, C are

$$A^+(n): (1+z^5)(1+z^9)\dots(1+z^{4\nu+1}), \quad n=2\nu+1$$

$$(1+z^5)(1+z^9)\dots(1+z^{4\nu-3})(1+z^{2\nu}), \quad n=2\nu.$$

$$A^-(n): (1+z^5)(1+z^9)\dots(1+z^{4\nu-3})$$

$$S(n): (1+z^2)(1+z^4)\dots(1+z^{2(\nu-1)}).$$

$$C(n): (1+z^2)(1+z^4)\dots(1+z^{2\nu}).$$

3. We denote by $\tilde{A}^+(n), \tilde{A}^-(n)$ the set of all symmetric or skew symmetric unitary matrices. These are also symmetric Riemannian mani-

folds and the Betti numbers of these manifolds can be determined in the same manner as above by the aid of lemmas II and III:

Theorem VI. The Poincaré polynomials of the manifolds $\tilde{A}^+(n)$, $\tilde{A}^-(n)$ can be represented as $P(z) = P_0(z)/(1+z)$, where $P_0(z)$ are the Poincaré polynomials of $A^+(n)$ and $A^-(n)$ respectively.

4. The adjoint transformations of the group $GL(n)$ are

$$\Omega \rightarrow A^{-1}\Omega A, \quad \Omega = (\omega_i^j)$$

consider the outer product $\Gamma(p) : \omega_{i_1}^{j_1} \dots \omega_{i_p}^{j_p}$. We operate the operator of Young corresponding to the partition (f_1, \dots, f_n) to the indices i_1, i_2, \dots, i_p . The result is not zero if and only if $n \geq f_1$. With respect to the indices j_1, \dots, j_p this quantity gives the irreducible representation of signature $(-g_n, \dots, -g_1)$. Thus $\Gamma(p) \sim \sum_{n \geq f_1 \geq \dots \geq f_n \geq 0} P(f_1 \dots f_n) \times P(-g_n, \dots, -g_1)$. By the lemma stated in Ehresmann, 3 we see that $P(f_1, \dots, f_n) \times P(-g_n, \dots, -g_1)$ admits a linear invariant if and only if the diagram (f_1, f_2, \dots, f_n) is self-conjugate. By examining the property of the self-conjugate diagram we readily see the following

Theorem I. The Poincaré polynomials of the groups $GL(n)$ and $SL(n)$ are

$$(1+z)(1+z^3)\dots(1+z^{2n-1})$$

and

$$(1+z^3)(1+z^5)\dots(1+z^{2n-1}).$$

Remark. After all the discussions given above it remains finally to show that the invariants given above does not vanish identically. But this can easily be carried out by means of the leading term F . Consider, for example the case of the group $GL(n)$. The leading term of the representation $P(f_1, \dots, f_n) \times P(-f_n, \dots, -f_1)$ is

$$F_0 : \omega_1^1 \omega_1^2 \dots \omega_1^{f_1} \\ \times \omega_2^1 \omega_2^2 \dots \omega_2^{f_2} \quad (f_1 = g_1, \dots) \\ \times \omega_{g_1}^1 \omega_{g_2}^2 \dots$$

Consider the infinitesimal matrix Ω in which all ω_i^j are zero except those appearing in F_0 . The only non vanishing term is F_0 and this gives at the same time the value of the corresponding invariant.

Reference.

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