



## DETERMINANTAL REPRESENTATION OF TRIGONOMETRIC POLYNOMIAL CURVES VIA SYLVESTER METHOD

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ABSTRACT. For any trigonometric polynomial  $\phi(\theta)$ , we give a constructive algorithm by Sylvester elimination which produces matrices  $C_1, C_2, C_3$  such that  $\det(C_1 + \Re(\phi(\theta))C_2 + \Im(\phi(\theta))C_3) = 0$ . For a typical trigonometric polynomial, we assert that  $C_1$  is positive definite, and thus the typical polynomial curve admits a determinantal representation.

### 1. INTRODUCTION AND PRELIMINARIES

Let  $A$  be an  $n \times n$  matrix. The real ternary form  $F_A(t, x, y)$  associated to  $A$  is defined as

$$F_A(t, x, y) = \det(tI_n + x\Re(A) + y\Im(A)),$$

where  $\Re(A) = (A + A^*)/2$  and  $\Im(A) = (A - A^*)/(2i)$ . Kippenhahn [8] characterized the numerical range of  $A$ ,  $W(A) = \{\xi^* A \xi : \xi \in \mathbb{C}^n, \xi^* \xi = 1\}$ , as the convex hull of the real affine part of the dual curve of the curve  $F_A(t, x, y) = 0$ . The form  $F_A(t, x, y)$  is hyperbolic with respect to  $(1, 0, 0)$ , i.e.,  $F_A(1, 0, 0) \neq 0$ , and for any real pair  $x, y$ ,  $F_A(t, x, y)$  has only real roots in  $t$ . The converse part was conjectured by Fiedler [5] and Lax [9], namely, for any real ternary hyperbolic form  $f(t, x, y)$ , there exist Hermitian (or real symmetric) matrices  $S_1$  and  $S_2$  such that

$$f(t, x, y) = \det(tI_n + xS_1 + yS_2) = F_S(t, x, y),$$

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where  $S = S_1 + iS_2$ . Helton and Vinnikov [6] gave an affirmative answer to the conjecture (see also [10, 12]). In this case, we call that the form  $f(t, x, y)$  admits a determinantal representation by the matrix  $S$ .

In [2], the authors of this paper study a typical roulette curve given by

$$\phi(\theta) = \exp(in\theta) + a \exp(-i(n-1)\theta), \quad (1.1)$$

$0 \leq \theta \leq 2\pi$ ,  $n = 2, 3, \dots$ , and  $0 < a < 1$ . In particular, they obtain that there exists a  $2n \times 2n$  matrix  $A$  so that the roulette (1.1) is exactly the algebraic curve defined by  $F_A(t, x, y)$ . In other words,

$$F_A(1, \Re(\phi(\theta)), \Im(\phi(\theta))) = 0, \quad 0 \leq \theta \leq 2\pi. \quad (1.2)$$

A more general form of the roulette curve (1.1) is a class of trigonometric polynomials given by

$$\phi(\theta) = \sum_{j=-n}^n c_j \exp(ij\theta). \quad (1.3)$$

The curve  $C_\phi$  in the Gaussian plane associated to the trigonometric polynomial  $\phi$  is defined as

$$C_\phi = \{(\Re(\phi(\theta)), \Im(\phi(\theta))) : 0 \leq \theta \leq 2\pi\}.$$

By using Henrion method [7] based on Bezoutian resultant, it is shown in [3] that there exist  $2n \times 2n$  real symmetric matrices  $A_1, A_2, A_3$  so that the curve  $C_\phi$  lies in the curve

$$\det(A_1 + xA_2 + yA_3) = 0.$$

Sufficient conditions are given in [3] that guarantee the matrix  $A_1$  being positive definite. In this case, the curve  $C_\phi$  admits a determinantal representation by the matrix

$$A_0 = A_1^{-1/2}(A_2 + iA_3)A_1^{-1/2},$$

that is  $F_{A_0}(1, \Re(\phi(\theta)), \Im(\phi(\theta))) = 0$ .

We continue our study to construct another algorithm, based on Sylvester matrix, that produces matrices  $C_1, C_2, C_3$  for trigonometric polynomial  $\phi(\theta)$  in (1.3) satisfying

$$\det(C_1 + \Re(\phi(\theta))C_2 + \Im(\phi(\theta))C_3) = 0. \quad (1.4)$$

For a typical trigonometric polynomial  $\phi(\theta)$ , we assert that  $C_1$  is positive definite, and thus the corresponding curve  $C_\phi$  admits a determinantal representation.

## 2. SYLVESTER METHOD

Consider a complex trigonometric polynomial  $\phi(\theta)$  as in (1.3). The conjugate of  $\phi(\theta)$  is denoted by

$$\psi(\theta) = \sum_{j=-n}^n \bar{c}_j \exp(-ij\theta) = \sum_{j=-n}^n \bar{c}_{-j} \exp(ij\theta). \quad (2.1)$$

We substitute the variable  $u = \exp(i\theta)$ . Then (1.3) and (2.1) respectively become

$$\sum_{j=-n}^n c_j u^{n+j} - \phi(\theta)u^n = 0, \quad (2.2)$$

$$\sum_{j=-n}^n \overline{c_{-j}} u^{n+j} - \psi(\theta) u^n = 0. \tag{2.3}$$

Recall that the  $2\ell \times 2\ell$  Sylvester matrix  $H$  of two polynomials

$$p(u) = \sum_{j=0}^{\ell} \gamma_{\ell-j} u^j \text{ and } q(u) = \sum_{j=0}^{\ell} \delta_{\ell-j} u^j$$

is defined as

$$H = H_{p,q} = \begin{pmatrix} \gamma_0 & \gamma_1 & \dots & \gamma_{\ell} & 0 & 0 & \dots & 0 \\ 0 & \gamma_0 & \gamma_1 & \dots & \gamma_{\ell} & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & \dots & \gamma_0 & \gamma_1 & \dots & \dots & \gamma_{\ell} \\ \delta_0 & \delta_1 & \dots & \dots & \delta_{\ell} & 0 & \dots & 0 \\ 0 & \delta_0 & \delta_1 & \dots & \dots & \delta_{\ell} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & \dots & \delta_0 & \delta_1 & \dots & \dots & \delta_{\ell} \end{pmatrix}.$$

The determinant of the matrix  $H$  is called the *resultant* of  $p(u)$  and  $q(u)$  with respect to  $u$ . It is well known that  $p(u)$  and  $q(u)$  have a common non-constant factor if and only if  $\det(H) = 0$  (cf. [4, 13]).

To construct matrices  $C_1, C_2, C_3$  satisfying (1.4), we introduce a new parameter  $t$  in (2.2) and (2.3), and write

$$t \sum_{j=-n}^n c_j u^{n+j} - \phi(\theta) u^n = \sum_{j=0}^{2n} \gamma_{2n-j}(t, z) u^j,$$

$$t \sum_{j=-n}^n \overline{c_{-j}} u^{n+j} - \psi(\theta) u^n = \sum_{j=0}^{2n} \delta_{2n-j}(t, w) u^j.$$

Now, let  $H$  be the  $4n \times 4n$  Sylvester matrix of polynomials

$$p(u : t, z) = \sum_{j=0}^{2n} \gamma_{2n-j}(t, z) u^j \text{ and } q(u : t, z) = \sum_{j=0}^{2n} \delta_{2n-j}(t, z) u^j.$$

Denote the matrix  $H$  with rows  $r_1, r_2, \dots, r_{4n}$  as

$$H = H(r_1, r_2, \dots, r_{4n}). \tag{2.4}$$

More precisely, the  $j$ -th row of the matrix  $H$  is

$$r_j = (0_{j-1}, c_n t, c_{n-1} t, \dots, c_0 t - \phi, \dots, c_{-n} t, 0_{2n-j})$$

for  $1 \leq j \leq 2n$ , and

$$r_j = (0_{j-2n-1}, \overline{c_{-n} t}, \overline{c_{-n+1} t}, \dots, \overline{c_0 t} - \psi, \dots, \overline{c_n t}, 0_{4n-j})$$

for  $2n + 1 \leq j \leq 4n$ , where  $0_k$  stands for  $k$ -dimensional zero vector. We will produce a  $2n \times 2n$  matrix associated to  $\phi(\theta)$  by modifying the matrix  $H$ . At first, we define the matrix

$$\tilde{H} = \tilde{H}(r_1, \dots, r_n, \tilde{r}_{n+1}, \dots, \tilde{r}_{3n}, r_{3n+1}, \dots, r_{4n}) \tag{2.5}$$

which is obtained from  $H$  (2.4) by replacing the  $n + 1, n + 2, \dots, 3n$  rows with the following new rows

$$\begin{aligned} \tilde{r}_{n+1} &= r_{n+1} - c_{-n}/\overline{c_n} r_{3n+1}, \\ \tilde{r}_{n+2} &= r_{n+2} - c_{-n}/\overline{c_n} r_{3n+2} - (c_{-n+1}\overline{c_n} - c_{-n}\overline{c_{n-1}})/\overline{c_n}^2 r_{3n+1} \\ \tilde{r}_{n+3} &= r_{n+3} - c_{-n}/\overline{c_n} r_{3n+3} - (c_{-n+1}\overline{c_n} - c_{-n}\overline{c_{n-1}})/\overline{c_n}^2 r_{3n+2} \\ &\quad - [c_{-n+2}\overline{c_n}^2 - c_{-n+1}\overline{c_{n-1}}\overline{c_n} + c_{-n}(\overline{c_{n-1}}^2 - \overline{c_{n-2}}\overline{c_n})]/\overline{c_n}^3 r_{3n+1}, \\ &\quad \dots, \end{aligned}$$

and

$$\begin{aligned} \tilde{r}_{3n} &= r_{3n} - \overline{c_n}/c_n r_n, \\ \tilde{r}_{3n-1} &= r_{3n-1} - \overline{c_n}/c_n r_{n-1} - (c_n\overline{c_{-n+1}} - c_{n-1}\overline{c_{-n}})/c_n^2 r_n, \\ \tilde{r}_{3n-2} &= r_{3n-2} - \overline{c_n}/c_n r_{n-2} - (c_n\overline{c_{-n+1}} - c_{n-1}\overline{c_{-n}})/c_n^2 r_{n-1} \\ &\quad - [(c_n^2\overline{c_{-n+2}} - c_n c_{n-1}\overline{c_{-n+1}}) + \overline{c_{-n}}(c_{n-1}^2 - c_{n-2}c_n)]/c_n^3 r_n, \\ &\quad \dots \end{aligned}$$

The general rows  $\tilde{r}_{n+k}, k = 1, 2, \dots, n$ , are formulated by

$$\tilde{r}_{n+k} = r_{n+k} + \sum_{j=1}^k \alpha_j r_{3n+k+1-j},$$

where the coefficients  $\alpha_1, \alpha_2, \dots, \alpha_k$  are uniquely determined so that the  $(3n + 1)$ -th,  $(3n + 2)$ -th,  $\dots$ ,  $(3n + k)$ -th entries of the row  $\tilde{r}_{n+k}$  all equal 0, while the coefficients  $\beta_1, \beta_2, \dots, \beta_k$  of the general rows

$$\tilde{r}_{3n+1-k} = r_{3n+1-k} + \sum_{j=1}^k \beta_j r_{n+j-k}, \quad k = 1, \dots, n$$

are uniquely determined so that the  $n$ -th,  $(n - 1)$ -th,  $\dots$ ,  $(n - k + 1)$ -th entries of the row  $\tilde{r}_{3n+1-k}$  equal 0.

The following result is a key observation for the properties of the matrix  $\tilde{H}$  in (2.5).

**Theorem 2.1.** *Let  $\tilde{H}$  be the matrix defined in (2.5) corresponding to the trigonometric polynomial  $\phi(\theta)$  in (1.3). Then the following hold:*

- (i) *The upper left  $n \times n$  principal submatrix of  $\tilde{H}$  is an upper triangular matrix with diagonals  $(c_n t, c_n t, \dots, c_n t)$ .*
- (ii) *The lower right  $n \times n$  principal submatrix of  $\tilde{H}$  is a lower triangular matrix with diagonals  $(\overline{c_n} t, \overline{c_n} t, \dots, \overline{c_n} t)$ .*
- (iii) *The first  $n$  entries and the last  $n$  entries of the new rows  $r_{n+1}, \dots, r_{2n}, r_{2n+1}, \dots, r_{3n}$  are all 0.*
- (iv) *The form associated to  $\phi(\theta)$  in (1.3) is given by*

$$R(t, x, y) \equiv \det(H) = \det(\tilde{H}) = |c_n|^{2n} t^{2n} \times \det(H_0), \tag{2.6}$$

where  $H_0$  is the  $2n \times 2n$  principal submatrix of  $\tilde{H}$  by deleting the first  $n$  and last  $n$  rows and columns.

(v) If we denote the matrix  $H_0$  by

$$H_0 = H_0(t, \phi, \psi) = H_0(t, x + iy, x - iy) = tC_1 + xC_2 + yC_3, \tag{2.7}$$

then we have

$$\det(C_1 + \Re(\phi(\theta))C_2 + \Im(\phi(\theta))C_3) = 0.$$

The matrix  $C_1$  obtained in Theorem 2.1 is not necessarily Hermitian and is therefore not positive definite; see, for example, the remark at the end of this section. It is shown in [2] that a special trigonometric polynomial (1.1) admits a determinantal representation. We apply Theorem 2.1 to more general typical trigonometric polynomials of the form  $\phi(\theta) = \exp(in\theta) + a \exp(-im\theta)$  which guarantee the positive definiteness of  $C_1$ .

**Theorem 2.2.** *Let  $\phi(\theta)$  be a trigonometric polynomial defined by*

$$\phi(\theta) = \exp(in\theta) + a \exp(-im\theta),$$

$0 \leq \theta \leq 2\pi$ , where  $0 < m < n$  are positive integers and  $0 < a < 1$  is a positive real number. Then the matrix  $H_0 = tC_1 + xC_2 + yC_3$  in (2.7) satisfies the following conditions:

- (i) The  $2n \times 2n$  matrices  $C_1, C_2, C_3$  are Hermitian and  $C_1$  is positive definite.
- (ii) The matrix  $C_0 = C_1^{-1/2}(C_2 + iC_3)C_1^{-1/2}$  satisfies

$$F_{C_0}(t, x, y)\det(C_1) = \det(H_0).$$

- (iii) For  $0 \leq \theta \leq 2\pi$ ,

$$F_{C_0}(1, \cos(n\theta) + a \cos(m\theta), \sin(n\theta) - a \sin(m\theta)) = 0.$$

*Proof.* From (2.7), the matrix  $H_0(0, x, y) = xC_2 + yC_3$  is the following form

$$\begin{pmatrix} 0 & P(x, y) \\ Q(x, y) & 0 \end{pmatrix},$$

where  $P(x, y)$  is a lower triangular Toeplitz matrix

$$P(x, y) = \begin{pmatrix} p_1(x, y) & 0 & 0 & \dots \\ rp_2(x, y) & p_1(x, y) & 0 & \dots \\ rp_3(x, y) & p_2(x, y) & p_1(x, y) & \dots \\ r \dots & \dots & \dots & \dots \end{pmatrix} \in M_n$$

with

$$\begin{aligned} p_1(x, y) &= [(-\bar{c}_n + c_{-n})x + i(-\bar{c}_n - c_{-n})y]/\bar{c}_n, \\ p_2(x, y) &= (c_{-n+1}\bar{c}_n - c_{-n}\bar{c}_{n-1})(x - iy)/\bar{c}_n^2, \\ p_3(x, y) &= \{c_{-n+2}\bar{c}_n^2 - c_{-n+1}\bar{c}_{n-1}\bar{c}_n + c_{-n}(\bar{c}_{n-1}^2 - \bar{c}_{n-2}\bar{c}_n)\}(x - iy)/\bar{c}_n^3, \\ &\dots, \end{aligned}$$

and  $Q(x, y)$  is an upper triangular Toeplitz matrix

$$Q(x, y) = \begin{pmatrix} q_1(x, y) & q_2(x, y) & q_3(x, y) & \dots \\ 0 & q_1(x, y) & q_2(x, y) & \dots \\ 0 & 0 & q_1(x, y) & \dots \\ \dots & \dots & \dots & \dots \end{pmatrix} \in M_n$$

with

$$\begin{aligned} q_1(x, y) &= [(-c_n + \overline{c_{-n}})x + i(c_n + \overline{c_{-n}})y]/c_n, \\ q_2(x, y) &= [(c_n\overline{c_{-n+1}} - c_{n-1}\overline{c_{-n}})(x + iy)]/c_n^2, \\ q_3(x, y) &= [\{c_n^2\overline{c_{-n+2}} - c_{n-1}c_n\overline{c_{-n+1}}\} + \overline{c_{-n}}(c_{n-1}^2 - c_{n-2}c_n)](x + iy)/c_n^3, \\ &\dots \end{aligned}$$

Hence the matrices  $C_2, C_3$  are Hermitian, and

$$\begin{aligned} \det(H_0(0, x, y)) &= \det(xC_2 + yC_3) \\ &= (-1)^n p_1(x, y)^n q_1(x, y)^n \\ &= (-1)^n \{-\overline{c_n}(x + iy) + c_n(x - iy)\}^n \\ &\quad \times \{\overline{c_{-n}}(x + iy) - c_n(x - iy)\}^n / |c_n|^{2n}, \end{aligned}$$

Let  $\ell = n - m$ . Then the matrix  $C_1$  is given by

$$\begin{pmatrix} I_\ell & 0_{\ell, 2n-2\ell} & aI_\ell \\ 0_{2n-2\ell, \ell} & (1 - a^2)I_{2n-2\ell} & 0_{2n-2\ell, \ell} \\ aI_\ell & 0_{\ell, 2n-2\ell} & I_\ell \end{pmatrix},$$

which is a real symmetric positive definite matrix. The matrix

$$C_0 = C_1^{-1/2}(C_2 + iC_3)C_1^{-1/2}$$

gives a homogeneous polynomial

$$F_{C_0}(t, x, y) = \det(tI_n + xC_1^{-1/2}C_2C_1^{-1/2} + yC_1^{-1/2}C_3C_1^{-1/2})$$

satisfying

$$F_{C_0}(t, x, y)\det(C_1) = \det(H_0) = \det(tC_1 + xC_2 + yC_3).$$

The assertion (iii) follows from the Sylvester construction (2.6) and (2.7) for the trigonometric polynomial  $\phi(\theta)$ , i.e.,

$$F_{C_0}(1, \Re(\phi(\theta)), \Im(\phi(\theta))) = 0, \quad 0 \leq \theta \leq 2\pi.$$

□

*Remark 2.3.* Although the matrix  $C_1$  in Theorem 2.2 is positive definite for  $\phi(\theta) = \exp(in\theta) + a \exp(-im\theta)$ , in general,  $C_1$  is not Hermitian for an arbitrary trigonometric polynomial  $\phi(\theta)$  given in (1.3). For example, let  $n = 2$  and

$$\phi(\theta) = \exp(2i\theta) - \frac{1}{4} \exp(i\theta) - \frac{17}{72} + \frac{1}{36} \exp(-i\theta) + \frac{1}{72} \exp(-2i\theta).$$

Then

$$\phi(\theta) \exp(2i\theta) = \left(\exp(i\theta) + \frac{1}{3}\right)\left(\exp(i\theta) + \frac{1}{4}\right)\left(\exp(i\theta) - \frac{1}{3}\right)\left(\exp(i\theta) - \frac{1}{2}\right).$$

The matrices constructed by Theorem 2.2 are

$$C_1 = \begin{pmatrix} 20732 & -5192 & -4828 & 648 \\ -9 & 20714 & -5039 & -4666 \\ -4666 & -5039 & 20714 & -9 \\ r648 & -4828 & -5192 & 20732 \end{pmatrix},$$

and

$$xC_2 + yC_3 = \begin{pmatrix} 0 & 0 & \alpha & 0 \\ 0 & 0 & \beta & \alpha \\ \bar{\alpha} & \bar{\beta} & 0 & 0 \\ 0 & \bar{\alpha} & 0 & 0 \end{pmatrix},$$

where  $\alpha = -20448x - 21024yi$ ,  $\beta = 648x - 648yi$ . The matrix  $C_1$  is not Hermitian.

### 3. DISCUSSION

Let  $0 < m < n$  be two positive integers and  $0 < a < 1$  be a real number. Consider a trigonometric polynomial  $\phi(\theta) = \exp(in\theta) + a \exp(-im\theta)$ ,  $0 \leq \theta \leq 2\pi$  which defines a real affine curve by the relation

$$x = x(\theta) = \Re(\phi(\theta)), y = y(\theta) = \Im(\phi(\theta)),$$

$0 \leq \theta \leq 2\pi$ . Based on Bezoutian, the authors of this paper [3] gave a constructive proof by providing real symmetric matrices  $A_1, A_2, A_3$  so that the curve  $(x(\theta), y(\theta))$  lies on  $\det(A_1 + xA_2 + yA_3) = 0$ .

We compare the two construction matrices obtained in [3] and Theorem 2.2 by investigating the following example. The relation between Bezoutian and Sylvester resultants can be found in [11]. Let  $n = 2, m = 1, a = 4/5$ ,

$$\phi(\theta) = \exp(2i\theta) + \frac{4}{5} \exp(-i\theta),$$

Then the matrix  $H_0(t, x, y) = tC_1 + xC_2 + yC_3$  in (2.7) is computed by

$$C_1 = \begin{pmatrix} 1 & 0 & 0 & 4/5 \\ 0 & 9/25 & 0 & 0 \\ 0 & 0 & 9/25 & 0 \\ 4/5 & 0 & 0 & 1 \end{pmatrix},$$

$$C_2 = \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 4/5 & -1 \\ -1 & 4/5 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}, \quad C_3 = \begin{pmatrix} 0 & 0 & -i & 0 \\ 0 & 0 & -4i/5 & -i \\ i & 4i/5 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix}.$$

We have that

$$(C_1)^{-1/2} C_2 (C_1)^{-1/2} = \frac{5}{9} \begin{pmatrix} 0 & \sqrt{5} & -2\sqrt{5} & 0 \\ \sqrt{5} & 0 & 4 & -2\sqrt{5} \\ -2\sqrt{5} & 4 & 0 & \sqrt{5} \\ 0 & -2\sqrt{5} & \sqrt{5} & 0 \end{pmatrix}$$

and

$$(C_1)^{-1/2}C_3(C_1)^{-1/2} = \frac{5}{9} \begin{pmatrix} 0 & -i\sqrt{5} & -2i\sqrt{5} & 0 \\ i\sqrt{5} & 0 & -4i & -2i\sqrt{5} \\ 2i\sqrt{5} & 4i & 0 & -i\sqrt{5} \\ 0 & 2i\sqrt{5} & i\sqrt{5} & 0 \end{pmatrix}.$$

Thus the matrix  $C_0 = C_1^{-1/2}(C_2 + iC_3)C_1^{-1/2}$  in Theorem 2.2 is given by

$$C_0 = \frac{10}{9} \begin{pmatrix} 0 & \sqrt{5} & 0 & 0 \\ 0 & 0 & 4 & 0 \\ -2\sqrt{5} & 0 & 0 & \sqrt{5} \\ 0 & -2\sqrt{5} & 0 & 0 \end{pmatrix}. \quad (3.1)$$

On the other hand, the matrices constructed by Bezoutian in [3] satisfying

$$6250000 \det(tC_1 + xC_2 + yC_3) = \det(tA_1 + xA_2 + yA_3)$$

are given by

$$A_1 = \begin{pmatrix} 27 & 0 & -63 & 0 \\ 0 & 27 & 0 & -3 \\ -63 & 0 & 207 & 0 \\ 0 & -3 & 0 & 7 \end{pmatrix},$$

and

$$A_2 = \begin{pmatrix} -15 & 0 & 35 & 0 \\ 0 & 65 & 0 & 15 \\ 35 & 0 & 85 & 0 \\ 0 & 15 & 0 & -35 \end{pmatrix}, \quad A_3 = \begin{pmatrix} 0 & -60 & 0 & -10 \\ -60 & 0 & -10 & 0 \\ 0 & -10 & 0 & 40 \\ -10 & 0 & 40 & 0 \end{pmatrix},$$

The matrix  $A_1^{-1/2}$  is a scalar multiple of the matrix

$$S = \begin{pmatrix} p & 0 & q & 0 \\ 0 & u & 0 & v \\ q & 0 & r & 0 \\ 0 & v & 0 & w \end{pmatrix},$$

where

$$p = \sqrt{218(6217 + 98\sqrt{5})}, \quad q = 7\sqrt{218(13 - 2\sqrt{5})}, \quad r = \sqrt{218(257 + 98\sqrt{5})}, \\ u = \sqrt{298(1373 + 54\sqrt{5})}, \quad v = 3\sqrt{298(17 - 6\sqrt{5})}, \quad w = 3\sqrt{298(637 + 6\sqrt{5})}.$$

More precisely  $S = 2\sqrt{108}\sqrt{149}A_1^{-1/2}$ .

The matrices  $A_1^{-1/2}A_2A_1^{-1/2}$  and  $A_1^{-1/2}A_3A_1^{-1/2}$  are respectively real symmetric matrices of the form

$$\begin{pmatrix} a_{11} & 0 & a_{13} & 0 \\ 0 & a_{22} & 0 & a_{24} \\ a_{13} & 0 & a_{33} & 0 \\ 0 & a_{24} & 0 & a_{44} \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 0 & a_{12} & 0 & a_{14} \\ a_{12} & 0 & a_{23} & 0 \\ 0 & a_{23} & 0 & a_{34} \\ a_{14} & 0 & a_{34} & 0 \end{pmatrix},$$

where  $a_{ij}$ 's are distinct non-zero real numbers. Therefore none of entries of the matrix  $A_0 = A_1^{-1/2}(A_2 + iA_3)A_1^{-1/2}$  is 0, while the matrix  $C_0$  in (3.1) obtained by



Theorem 2.2 is rather sparse. The sparsity of  $A_0$  and  $C_0$ , obtained by the two methods, is an interesting subject for further study.

We have proposed two constructive algorithms for determinantal representations of the trigonometric polynomial  $\phi(\theta) = \exp(in\theta) + a \exp(-im\theta)$  by matrices  $A_0 = A_1^{-1/2}(A_2 + iA_3)A_1^{-1/2}$  and  $C_0 = C_1^{-1/2}(C_2 + iC_3)C_1^{-1/2}$  satisfying (1.2). It is interesting to ask whether the two matrices  $A_0$  and  $C_0$  are unitarily similar. At this time, we cannot answer this question. Nevertheless, we give a positive answer for the case when

$$\phi(\theta) = \exp(2i\theta) + 4/5 \exp(-i\theta).$$

According to [2], there constructs a matrix

$$B = \frac{10}{9} \begin{pmatrix} 0 & -4 & 0 & 0 \\ 0 & 0 & -4 & -3 \\ -5 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

satisfying

$$729\det(tI_4 + x\Re(B) + y\Im(B)) = 15625\det(tC_1 + xC_2 + yC_3).$$

At first, we show that the matrices  $A_0$  and  $B$  are unitarily similar by a unitary intertwining matrix  $W$ :

$$WA_1^{-1/2}(A_2 + iA_3)A_1^{-1/2} = BW.$$

Setting  $WA_1^{1/2} = V$ , the matrix  $V$  satisfies

$$VA_1^{-1}(A_2 + iA_3) = WA_1^{1/2}A_1^{-1}(A_2 + iA_3) = WA_1^{-1/2}(A_2 + iA_3) = BWA_1^{1/2} = BV, \tag{3.2}$$

and

$$VA_1^{-1}V^* = WA_1^{1/2}A_1^{-1}A_1^{1/2}W^* = WW^* = I_4. \tag{3.3}$$

Conversely, if  $V$  satisfies (3.2) and (3.3) then the unitary matrix  $W = VA_1^{-1/2}$  satisfies  $WA_1^{-1/2}(A_2 + iA_3)A_1^{-1/2}W^* = B$ . Such a matrix  $V$  is given by

$$V = \begin{pmatrix} -3i/2 & 3/2 & -3i/2 & 3/2 \\ 3i/2 & 3/2 & 3i/2 & 3/2 \\ -3i/2 & -9/2 & 9i/2 & 3/2 \\ 9i/2 & -3/2 & -27i/2 & 1/2 \end{pmatrix}.$$

This shows that  $A_0$  and  $B$  are unitarily similar.

On the other hand, the matrix  $C_0$  is unitarily similar to  $B$ , and  $UC_0U^* = B$  for the unitary matrix

$$U = \begin{pmatrix} 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1/\sqrt{5} & 0 & 0 & -2/\sqrt{5} \\ 2/\sqrt{5} & 0 & 0 & 1/\sqrt{5} \end{pmatrix}.$$

Thus, both  $A_0$  and  $C_0$  are unitarily similar to  $B$ .

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