

ON THE INNER GEOMETRY OF THE SECOND FUNDAMENTAL FORM

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N. Hicks [2, p. 395, Theorem 7] proved the following result.

THEOREM A. *If the connexion induced on a complete, connected surface (in Euclidean space R^3) by its second fundamental form is the usual Riemannian connexion, then the surface is a sphere.*

The aim of this note is to prove a local version of Theorem A. In addition, we show that the conclusion of the theorem also holds for hypersurfaces in spaces of constant curvature, under weaker conditions for the connexion.

For a hypersurface in a space of constant curvature with definite second fundamental form, let β be the connexion induced by that form. We shall define the auto-parallel curves belonging to β as II-geodesics, and we shall prove the following local result.

THEOREM B. *Let F be a hypersurface in a space of constant curvature with a definite second fundamental form; each II-geodesic is an (ordinary) geodesic if and only if F is totally umbilic.*

The corollary to Theorem D will generalize Theorem B slightly.

LEMMA 1. *Every II-geodesic is a curve of constant normal curvature.*

The converse is not true, as can be seen from the following example. On a rotation surface in R^3 , the circles of latitude are curves of constant normal curvature but generally not II-geodesics. Thus, on an arbitrary hypersurface, the class of curves with constant normal curvature generally contains the class of II-geodesics as a proper subset. The natural question, whether Theorem B can be generalized to curves of constant normal curvature, is answered in Theorem D.

Proofs of the theorems. Let M_n be an n -dimensional manifold with local parameters (u^i) , and suppose that $M_n \in C^r$ ($r \geq 3$); let N_{n+1} be a Riemannian manifold of constant curvature K_0 , and let

$$(1.1) \quad x: M_n \rightarrow N_{n+1}$$

be an isometric C^r -immersion. As usual, we have on $x(M_n)$ a first and a second fundamental form; we shall assume that the second fundamental form is definite at each point of $x(M_n)$. The two forms induce symmetric connexions Γ and β on $x(M_n)$, and covariant differentiations ∇^I and ∇^{II} .

In a local coordinate system, we define g_{ij} and b_{ij} to be the tensor components of the first and second fundamental forms, Γ_{ij}^k and β_{ij}^k to be the components of the connexions Γ and β , and $g^{(ij)}$ and $b^{(ij)}$ to be the components of the inverse tensors of g_{jk} and b_{jk} .

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The Codazzi-equations are

$$(1.2) \quad \nabla_k^I b_{ij} = \nabla_j^I b_{ik}.$$

For the tensor components A_{ij}^k , defined by the equation

$$(1.3) \quad A_{ij}^k = \Gamma_{ij}^k - \beta_{ij}^k,$$

we shall prove the following result.

LEMMA 2. For $A_{ijk} = b_{rk} A_{ij}^r$, we have the relation

$$(1.4) \quad 2A_{ijk} = -\nabla_k^I b_{ij};$$

and A_{ijk} is symmetric in all indices.

Proof (compare [1], [6]). Application of the covariant derivations on b_{ij} gives the equations

$$(1.5) \quad \nabla_k^I b_{ij} = b_{ij|k} - \Gamma_{ik}^s b_{sj} - \Gamma_{kj}^s b_{si},$$

$$(1.6) \quad 0 = b_{ij|k} - \beta_{ik}^s b_{sj} - \beta_{kj}^s b_{si},$$

where $b_{ij|k} = \frac{\partial b_{ij}}{\partial u^k}$; thus it follows that

$$(1.7) \quad \nabla_k^I b_{ij} = -A_{ki}^s b_{sj} - A_{kj}^s b_{si}.$$

The symmetry of $\nabla_k^I b_{ij}$ in (k, j) implies that

$$(1.8) \quad 0 = A_{ji}^s b_{sk} - A_{ki}^s b_{sj},$$

so that A_{ijk} is symmetric in all indices; the assertion (1.4) follows from (1.7) and (1.8).

Proof of Lemma 1. We consider a curve $\gamma \in C^2$ on $x(M)$ with parameter $t \in \mathbb{R}$. If we put $\dot{u}^i = \frac{du^i}{dt}$, the normal curvature of γ is $b(t) = b_{ij} \dot{u}^i \dot{u}^j$. Using covariant differentiation D^{II}/dt with respect to β along γ , we find that

$$\frac{D^{II}}{dt} b(t) = 2b_{ij} \dot{u}^i \frac{D^{II} \dot{u}^j}{dt}.$$

If γ is Π -geodesic, then $\frac{D^{II}}{dt} \dot{u}^j = 0$ for a suitable parameter t . Thus the function $b(t)$ is constant.

THEOREM D. *If the second fundamental form is definite on $x(M)$, then the following statements are equivalent:*

- (a) *the Π -geodesics are geodesics;*
- (b) $\Gamma = \beta$;
- (c) $\nabla_k^I b_{ij} = 0$ for each point of $x(M_n)$;
- (d) *each geodesic has constant normal curvature.*

Proof. First, we prove that (a) \Rightarrow (b). For two connexions with the same auto-
parallels, there exists a vectorfield q_i such that

$$(1.9) \quad A_{ij}^k = \Gamma_{ij}^k - \beta_{ij}^k = q_i \delta_j^k + q_j \delta_i^k$$

(compare for example [3, p. 156]). From the symmetry of A_{ijk} in (j, k) it follows
that

$$(1.10) \quad 0 = q_k b_{ij} - q_j b_{jk}.$$

Multiplication with $b^{(ik)}$ shows that $q_j = 0$; (1.9) and (1.3) imply (b). The implication
(b) \Rightarrow (a) is trivial. Lemma 2 implies that (b) \Leftrightarrow (c). Lemma 1 implies that
(a) \Rightarrow (d). Finally, we prove that (d) \Rightarrow (c). For a geodesic with natural parameter
 t and constant normal curvature we have the relation (see (1.3))

$$\begin{aligned} 0 &= b_{ij} \dot{u}^i \frac{D^{II} \dot{u}^j}{dt} = b_{ij} \dot{u}^i (\ddot{u}^j + \beta_{rs}^j \dot{u}^r \dot{u}^s) \\ &= b_{ij} \dot{u}^i [(\ddot{u}^j + \Gamma_{rs}^j \dot{u}^r \dot{u}^s) - A_{rs}^j \dot{u}^r \dot{u}^s] = -A_{rsi} \dot{u}^r \dot{u}^s \dot{u}^i. \end{aligned}$$

If $p \in x(M)$, then $A_{rsi} \dot{u}^r \dot{u}^s \dot{u}^i = 0$ for every tangent direction at p ; hence the sym-
metry of A_{rsi} implies that $A_{rsi} = 0$, and therefore (c) follows from Lemma 2.

We say that a hypersurface $x(M_n) \subset N_{n+1}$ is of type (α) if each of its points is
umbilic, that is, if at each of its points all the principal curvatures k_1, k_2, \dots, k_n
have the same value. We say that $x(M_n)$ is of type (β) if there exists an integer p
($1 \leq p \leq n$) such that, for a suitable numbering of the principal curvatures,

$$k_1 = k_2 = \dots = k_p = \lambda_1 \neq 0 \quad \text{and} \quad k_{p+1} = k_{p+2} = \dots = k_n = \lambda_2,$$

where the constants λ_1 and λ_2 satisfy the condition $\lambda_1 \lambda_2 + K_0 = 0$. In [5], it was
proved that a hypersurface $x(M_n)$ in N_{n+1} satisfies the condition $\nabla_k^I b_{ij} = 0$ at each
point if and only if it is of type (α) or of type (β) .

Together with Theorem D, this criterion gives the following generalization of
Theorems A and B.

COROLLARY. *If $x(M_n)$ has a definite second fundamental form, then each of
the conditions (a), (b), and (c) is equivalent to the condition that $x(M_n)$ be of
type (α) or (β) .*

Remark. If $N_{n+1} = R^{n+1}$, then $K_0 = 0$. The assumption $\det(b_{ij}) \neq 0$ excludes
both surfaces of type (β) and the case $k_1 = k_2 = \dots = k_n = 0$. Thus Theorem B is
proved.

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