

POSTULATES FOR THE SUBSTITUTIVE ALGEBRA OF THE  
2-PLACE FUNCTORS IN THE 2-VALUED CALCULUS  
OF PROPOSITIONS

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In recent papers ([1], [2] in the Bibliography at the end of this note), the algebra of functions [3] has been applied to the 2-valued calculus of propositions.

Eight of the sixteen 2-place functors have been denoted by  $A, B, C, D, E, I, J$ , and  $I$ , according to the truth tables

	$A$	$B$	$C$	$D$	$E$	$I$	$J$	$I$
(0,0)	1	0	1	1	1	0	0	1
(0,1)	1	1	1	0	0	0	1	1
(1,0)	1	1	0	1	0	1	0	1
(1,1)	0	1	1	1	1	1	1	1

Moreover,  $F'$  is the functor such that  $F'(x,y) \neq F(x,y)$  for every  $(x,y)$ , where  $F$  stands for any of the aforementioned eight functors.

$A$  is incompatibility;  $A'$  is conjunction;  $B$  is nonexclusive disjunction;  $C$  is implication;  $E$  is equivalence.  $I$  and  $J$  will be called (2-place) *selectors* and  $I$  is the *constant* 2-place functor of value 1. Instead of  $I'$ , one may also write  $0$ . (In contrast to the truth-values, symbolized by 1 and 0, the constant functors are designated by *italic*  $I$  and  $0$ .)

The principal operation in the algebra of functors is substitution. The result of substituting the ordered pair of functors  $(G,H)$  into the functor  $F$  is defined\* as the functor

$F(G,H)$  such that  $F(G,H)(x,y) = F(G(x,y), H(x,y))$  for every  $(x,y)$ . This operation is what in [1]-[3] has been called *superassociative*; that is to say, (1)  $F(G_1, G_2)(H_1, H_2) = F(G_1(H_1, H_2), G_2(H_1, H_2))$  for any five functors.

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\*Besides this "*parenthesis substitution*", there is a superassociative "*bracket substitution*" of the ordered pair  $G, H$  into  $F$  resulting in a 4-place functor  $F[G, H]$  (cf. [1], [2], [3]).

There are  $16^3$  different expressions  $F(G,H)$ . If each of the 4096 functors thus designated can be identified with one of the 16 functors  $A, B, \dots, I'$ , then every functor resulting from the substitution of a functor pair into a functor can be so identified. In other words, every formula of the substitutive algebra of 2-place functors can be derived from 4096 *basic* formulae,  $F(G,H) = K$ . In [2], these basic formulae, in turn, have been reduced to a small number of formulae in terms of  $A, I$ , and  $J$ , from which the other 13 functors can be defined.

In the present paper we give a more transparent derivation of the 4096 basic formulae from 48 of them, which then will be further reduced. For this purpose we consider the set of the  $16^2$  ordered pairs  $(M,N)$  of 2-place functors. We call each such pair a *transformation* and define the substitution of any transformation  $(N_1,N_2)$  into any transformation  $(M_1,M_2)$  by

$$(M_1,M_2)(N_1,N_2) = (M_1(N_1,N_2),M_2(N_1,N_2)).$$

This binary operation is *associative* because of (1), that is, because of the superassociativity of the substitution in the realm of 2-place functors. Hence the 256 transformations constitute a semigroup, which will be denoted by  $\mathfrak{S}$  :

$\mathfrak{S}$  has a maximal subgroup  $\mathfrak{g}$ , which is isomorphic with the octahedral group or the (“symmetric”) group of all permutations of four objects (cf. [2]).  $\mathfrak{g}$  consists of the 24 transformations  $(G,H)$  such that

$$G, H = I, J, E, I', J', E \text{ and } G \neq H \neq G'.$$

$\mathfrak{g}$  can be generated by two transformations, e.g., by  $(J',I')$  and  $(I',E)$ , which we shall denote by  $h$  and  $e$ , respectively; that is to say, for each transformation  $(G,H)$  in  $\mathfrak{g}$  there exist an integer  $m$  (which can always be chosen  $\leq 6$ ) and a sequence of  $m$  transformations  $g_1, g_2, \dots, g_m$  such that  $g_i = h$  or  $e$  for  $i = 1, 2, \dots, m$  and

$$(G, H) = g_1 g_2 \dots g_m.$$

E.g.,  $(I, J) = hh = eeee$  and  $(J, I) = eehee$ .

Obviously,  $\mathfrak{g}$  cannot be generated by less than two transformations. Moreover, if  $s$  is any transformation not belonging to  $\mathfrak{g}$ , and  $t$  is any transformation, then  $st$  and  $ts$  do not belong to  $\mathfrak{g}$ . Hence  $\mathfrak{S}$  cannot be generated by less than three transformations. But  $\mathfrak{S}$  can be generated by  $h, e$ , and  $a = (A,I')$  (see Appendix); that is to say, for each transformation  $(G,H)$  in  $\mathfrak{S}$  there exists an integer  $n$  and a sequence of  $n$  transformations  $t_1, t_2, \dots, t_n$  such that  $t_i = h$  or  $e$  or  $a$  (for  $i = 1, 2, \dots, n$ ) and

$$(G, H) = t_1 t_2 \dots t_n.$$

It follows that, for any functor  $F$ ,

$$F(G,H) = F(t_1 t_2 \dots t_n) = (Ft_1)(t_1 t_2 \dots t_n) = ((Ft_1)t_2)(t_3 \dots t_n) = \dots ((Ft_1)t_2) \dots t_{n-1} t_n.$$

Hence, if for every functor  $M$ , one can identify  $Mh, Me$ , and  $Ma$  with one of the 16 functors, then one can identify  $F(G,H)$  with one of them. For example from

$$(I,A) = eeha \text{ and } Ae = B, Be = C, Ch = C, Ca = C$$

one can conclude

$$A(I,A) = A(e e h a) = (A e)(e h a) = B(e h a) = (B e)(h a) = C(h a) = (C h)a = C a = C.$$

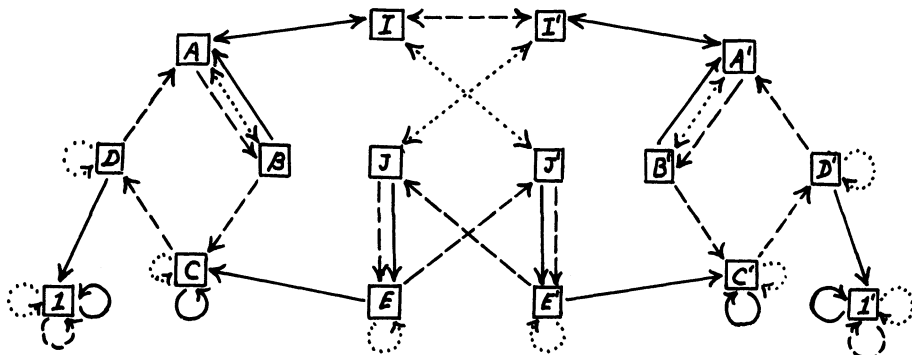
In this way one can derive the 4096 formulae  $F(G,H) = K$  from the 48 formulae tabulated below, which list the results of substituting  $h = (J',I')$ ,  $e = (I',E)$ ,  $a = (A,I')$  into the sixteen functions.

	<i>h</i>	<i>e</i>	<i>a</i>
<i>A</i>	<i>B</i>	<i>B</i>	<i>I</i>
<i>B</i>	<i>A</i>	<i>C</i>	<i>A</i>
<i>C</i>	<i>C</i>	<i>D</i>	<i>C</i>
(2) <i>D</i>	<i>D</i>	<i>A</i>	<i>I</i>
<i>E</i>	<i>E</i>	<i>J'</i>	<i>C</i>
<i>I</i>	<i>J'</i>	<i>I'</i>	<i>A</i>
<i>J</i>	<i>I'</i>	<i>E</i>	<i>I'</i>
<i>I</i>	<i>I</i>	<i>I</i>	<i>I</i>

	<i>h</i>	<i>e</i>	<i>a</i>
<i>A'</i>	<i>B'</i>	<i>B'</i>	<i>I'</i>
<i>B'</i>	<i>A'</i>	<i>C'</i>	<i>A'</i>
<i>C'</i>	<i>C'</i>	<i>D'</i>	<i>C'</i>
(2') <i>D'</i>	<i>D'</i>	<i>A'</i>	<i>I'</i>
<i>E'</i>	<i>E'</i>	<i>J</i>	<i>C'</i>
<i>I'</i>	<i>J</i>	<i>I</i>	<i>A'</i>
<i>J'</i>	<i>I</i>	<i>E'</i>	<i>I</i>
<i>I'</i>	<i>I'</i>	<i>I'</i>	<i>I'</i>

For example,  $Ba = A$ ,  $Ae = B$ ,  $Ah = B$ ,  $Bh = A$ , and  $Dh = D$ .

The table may be replaced by the following graph in which solid, dashed, and dotted arrows indicate the substitution of  $a$ ,  $e$ , and  $h$ , respectively. The aforementioned examples are expressed by the solid arrow from  $B$  to  $A$ , the dashed arrow from  $A$  to  $B$ , the dotted double arrow between  $A$  and  $B$ , and the dotted loop at  $D$ .



Starting from any of the 14 nonconstant functors in the graph, one can reach every other functor by a chain of arrows. Hence, *in terms of every nonconstant functor, every functor can be obtained by a sequence of transformations  $h, e, a$ .* For example, starting from  $A$  one obtains

$$\begin{array}{llll}
 Ah = B & & & Aa = I \\
 Ahe = C & & Aah = J' & & Aae = I' \\
 & & & & & & Aaea = A' \\
 Ahee = D & & Aahe = E' & & & & Aaeae = B' \\
 Aheea = I & & Aahee = J & = & Aaeh & & \\
 & & & & & & Aaeaeae = C' \\
 & & Aaheea = E & & & & Aaeaeaeae = D' \\
 & & & & & & Aaeaeaeaea = I'
 \end{array}$$

Starting, say, from  $E$ , one would obtain  $Ea = C$ ,  $Eae = D$ ,  $Eaeae = A$  and thus could reach all the other functors.

Thus for any nonconstant functor  $M$  and any functor  $N$  there is at least one transformation transforming  $M$  into  $N$ . We will select one of these transformations and denote it by  $t_{MN}$ . Then

$$Mt_{MN} = N \text{ for every } M \neq I, 0 \text{ and every } N.$$

The 24 formulae (2') can be derived from the corresponding formulae (2) provided that one introduces a unitary functor (which we shall denote by  $\sim$ ) satisfying the following assumptions

- a)  $\sim P = P'$  for  $P = A, B, \dots, I$ ;
- b)  $(\sim \sim)P_0 = P_0$  for at least one of the seven nonconstant functors  $A, B, \dots, J$ ; for example,  $(\sim \sim)A = A$ .

Moreover, substitution of functors into  $\sim$  is assumed to be associative; that is to say,

$$\sim(Fg) = (\sim F)g \text{ and } \sim(\sim F) = (\sim \sim)F \text{ for every functor } F \text{ and every transformation } g.$$

It follows that, if  $P$  stands for any of the eight unprimed functors, then (3)  $\sim(Pg) = (\sim P)g = P'g$ .

In a formula (2), the functor on the right side is either primed or unprimed. In the first case, in view of (3) and a), from  $Pg = Q$  it follows that  $P'g = Q'$ . In the second case,  $P'g = \sim Q'$ . Then, from  $Q = A t_{AQ}$  in view of b) it follows that

$$\sim Q' = \sim(\sim(A t_{AQ})) = \sim((\sim A)t_{AQ}) = (\sim(\sim A))t_{AQ} = ((\sim \sim)A)t_{AQ} = A t_{AQ} = Q.$$

In both cases, the formula (2) implies the corresponding formula (2').

Summarizing one can say that the substitutive algebra of the 2-place functors can be derived from the 48 formulae (2) and (2') or from the 24 formulae (2) in conjunction with a) and b).

#### APPENDIX ON THE SEMIGROUP $\mathfrak{S}$ .

That the transformations  $h, e,$  and  $a$  generate the semigroup  $\mathfrak{S}$  was first verified by Miss Eva L. Menger and Mr. H. Ian Whitlock, who expressed each of the 256 transformations  $(G, H)$  in terms of  $h, e,$  and  $a$ . Then

the possibility of generating  $\mathfrak{S}$  was shown by Mr. Richard Peters at Illinois Institute of Technology as follows. Each of the four pairs  $(x,y) = (0,0), (0,1), (1,0), (1,1)$  may be represented by the number  $2x + y$ , which is 0, 1, 2, 3, respectively; and similarly, one may represent the value of the transformation  $(G,H)$  for  $(x,y)$ , that is, the pair  $(G(x,y), H(x,y))$ , by the number  $2G(x,y) + H(x,y)$ . Accordingly, one may represent each transformation  $(G,H)$  by the ordered quadruple  $[i_0, i_1, i_2, i_3]$  of the values that  $(G,H)$  assumes for 0, 1, 2, 3, respectively. (For this representation, cf. also [2].) For example,  $h = (J', I')$ ,  $e = (I', E)$  and  $a = (A, I')$  are represented by

$$[3, 1, 2, 0], \quad [3, 2, 0, 1], \quad \text{and} \quad [3, 3, 2, 0],$$

respectively. Each of the 24 transformations belonging to the maximal subgroup  $\mathcal{g}$  of  $\mathfrak{S}$  is represented by a permutation. Each of the 144 transformation that assume exactly three different values, as does  $a$ , is represented by  $g_1 a g_2$  for some transformations  $g_1$  and  $g_2$  in  $\mathcal{g}$ . The 48 transformations assuming one value exactly three times can be obtained in the form  $g_1 a e a g_2$ . The 36 transformations assuming two values twice can be obtained in the form  $g_1 a e h a g_2$ . The four constant transformations  $(0,0), \dots, (1,1)$  can be obtained in the form  $g a e a h e e a$  for some  $g$  in  $\mathcal{g}$ . Thus all 256 transformations in  $\mathfrak{S}$  are accounted for.

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