

## CONVEXITY OF THE GEODESIC DISTANCE ON SPACES OF POSITIVE OPERATORS

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Let  $A$  be a  $C^*$ -algebra with 1 and denote by  $A^+$  the set of positive invertible elements of  $A$ . The set  $A^+$  being open in  $A^s = \{a \in A; a^* = a\}$  it has a  $C^\infty$  structure and we can identify  $TA_a^+$  with  $A^s$  for each  $a \in A^+$ . We use  $G$  to denote the group of invertible elements of  $A$ . Notice that  $G$  operates on the left on  $A^+$  by the rule

$$L_g a = (g^*)^{-1} a g^{-1} \quad (g \in G, a \in A^+).$$

This action allows us to introduce a natural reductive homogeneous space structure in the sense of [8] (for details see [2], [3], [4]).

The corresponding connection—which is preserved by the group action—has covariant derivative

$$\frac{DX}{dt} = \frac{dX}{dt} - \frac{1}{2}(\dot{\gamma}\gamma^{-1}X + X\gamma^{-1}\dot{\gamma})$$

where  $X$  is a tangent field on  $A^+$  along the curve  $\gamma$  and exponential

$$\exp_a X = e^{Xa^{-1/2}} a e^{a^{-1}X/2}, \quad a \in A^+, X \in TA_a^+.$$

The curvature tensor has the formula

$$R(X, Y)Z = -\frac{1}{4}a[[a^{-1}X, a^{-1}Y], a^{-1}Z]$$

for  $X, Y, Z \in TA_a^+$ . The manifold  $A^+$  has also a natural Finsler structure given by

$$\|X\|_a = \|a^{-1/2}Xa^{-1/2}\| \text{ for } X \in TA_a^+$$

and the group  $G$  operates by isometries for this Finsler metric.

**THEOREM 1.** *If  $J(t)$  is a Jacobi field along the geodesic  $\gamma(t)$  in  $A^+$  then  $\|J(t)\|_{\gamma(t)}$  is a convex function of  $t \in \mathbf{R}$ .*

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*Proof.* The method of proof is based on a similar strategy used in [4]. By definition  $J(t)$  satisfies the equation

$$\frac{D^2 J}{dt^2} + R(J, V)V = 0 \quad (1)$$

where  $V(t) = \dot{\gamma}(t)$ .

Notice that by the invariance of the connection and the metric under the action of  $G$  we may assume that  $\gamma(t) = e^{tX}$  is a geodesic starting at  $\gamma(0) = 1 \in A$ , where  $X \in \mathfrak{A}^s$ . Then for the field  $K(t) = e^{-tX/2}J(t)e^{-tX/2}$  the differential equation (1) changes into

$$4\ddot{K} = KX^2 + X^2K - 2XKX, \quad (2)$$

(where the dots indicate ordinary derivative with respect to  $t$ ). Since the group  $G$  acts by isometries, we have  $\|J(t)\|_{\gamma(t)} = \|\gamma(t)^{-1/2}J(t)\gamma(t)^{-1/2}\| = \|K(t)\|$ . Thus the proof reduces to showing that for any solution  $K(t)$  of (2) the function  $t \rightarrow \|K(t)\|$  is convex in  $t \in \mathbf{R}$ , where the norm is the *ordinary norm* in the  $C^*$  algebra  $A$ . So fix  $u < v \in \mathbf{R}$  and let  $t$  satisfy  $u \leq t \leq v$ . We will prove that

$$\|K(t)\| \leq \frac{v-t}{v-u}\|K(u)\| + \frac{t-u}{v-u}\|K(v)\|. \quad (3)$$

Consider first the case where the selfadjoint element  $X \in A$  has the form

$$X = \sum_{i=1}^n \lambda_i p_i \quad (4)$$

with  $\lambda_1, \lambda_2, \dots, \lambda_n$  real numbers and  $p_1, p_2, \dots, p_n$  selfadjoint elements of  $A$  satisfying  $p_i p_j = 0$  for  $i \neq j$  and  $p_1 + p_2 + \dots + p_n = 1$ .

Suppose that  $A$  is faithfully represented in a Hilbert space  $\mathcal{H}$ . For fixed  $x \in A$  decompose  $x \in \mathcal{H}$  as  $x = \sum_{i=1}^n \xi_i x_i$  where  $x_i$  is a unit vector in the range of  $p_i$  and the  $\xi_i$  are appropriate scalars. Define next the matrix  $k(t) = (k_{ij}(t))$  by  $k_{ij}(t) = \langle K(t)x_i, x_j \rangle$  for all  $t$ . The differential equation (2) is equivalent to the equations

$$\ddot{k}_{ij}(t) = \delta_{ij}^2 k_{ij}(t) \quad (2ij)$$

where  $\delta_{ij} = (\lambda_i - \lambda_j)/2$ .

A simple verification (or Bernoulli's formula) shows that all solutions of  $\ddot{f}(t) = c^2 f(t)$  satisfy

$$f(t) = \phi(u, v, c; t)f(u) + \psi(u, v, c; t)f(v)$$

where

$$\phi(u, v, c; t) = \begin{cases} \frac{\text{Sinh } c(v - t)}{\text{Sinh } c(v - u)} & \text{for } c \neq 0, \\ \frac{(v - t)}{(v - u)} & \text{for } c = 0, \end{cases}$$

$$\psi(u, v, c; t) = \begin{cases} \frac{\text{Sinh } c(t - u)}{\text{Sinh } c(v - u)} & \text{for } c \neq 0, \\ \frac{(t - u)}{(v - u)} & \text{for } c = 0. \end{cases}$$

Then each  $k_{ij}(t)$  satisfies

$$k_{ij}(t) = \phi_{ij}(t)k_{ij}(u) + \psi_{ij}(t)k_{ij}(v)$$

where  $\phi_{ij}(t) = \phi(u, v, \delta_{ij}; t)$  and  $\psi_{ij}(t) = \psi(u, v, \delta_{ij}; t)$ . This can be written in matrix form as

$$k(t) = \Phi(t) \circ k(u) + \Psi(t) \circ k(v)$$

where  $\Phi(t) = \{\phi_{ij}(t)\}$  and  $\Psi(t) = \{\psi_{ij}(t)\}$ , and the symbol  $\circ$  denotes the Schur product  $\{a_{ij}\} \circ \{b_{ij}\} = \{a_{ij}b_{ij}\}$  of matrices. It follows that

$$\|k(t)\| \leq \|\Phi(t) \circ k(u)\| + \|\Psi(t) \circ k(v)\|. \tag{5}$$

The final step is to prove the inequalities

$$\|\Phi(t) \circ k(u)\| \leq \frac{v - t}{v - u} \|k(u)\|,$$

$$\|\Psi(t) \circ k(v)\| \leq \frac{t - u}{v - u} \|k(v)\|. \tag{6}$$

Notice that both  $\Phi(t)$  and  $\Psi(t)$  are positive semidefinite. This follows from Bochner's theorem [1] applied to  $\phi(u, v, c; t)$  and  $\psi(u, v, c; t)$  considered as functions of  $c$ . In both cases the matrix is of the form  $\{F(\lambda_i - \lambda_j)\}$  where  $F(c)$  is the Fourier transform of a positive function (see [7], formula 1.9.14, page 31).

Next we apply a theorem of Davis (see [6] and the generalization in [9]) according to which for  $n \times n$ -matrices  $A$  and  $P$  with  $P$  positive semidefinite we have

$$\|P \circ A\| \leq \left( \max_{1 \leq i \leq n} P_{ii} \right) \|A\|.$$

Taking  $P = \Phi(t)$  and  $P = \Psi(t)$  we get inequalities (6). Using now (5) and (6) we also get

$$\|k(t)\| \leq \frac{v-t}{v-u} \|k(u)\| + \frac{t-u}{v-u} \|k(v)\|. \quad (7)$$

Since the element  $x$  and the representation space  $\mathcal{H}$  were not specified, we may assume without loss of generality that for a given  $t$  between  $u$  and  $v$  we have  $\|K(t)x\| = |\langle K(t)x, x \rangle|$ . Then writing  $\xi = (\xi_1, \xi_2, \dots, \xi_n)$  we conclude that

$$\begin{aligned} |\langle k(t)\xi, \xi \rangle| &= |\langle K(t)x, x \rangle| = \|K(t)\| \\ |\langle k(u)\xi, \xi \rangle| &= |\langle K(u)x, x \rangle| \leq \|K(t)\| \\ |\langle k(v)\xi, \xi \rangle| &= |\langle K(v)x, x \rangle| \leq \|K(t)\| \end{aligned}$$

and then (3) follows from (7) for  $X$  of the special form (4).

Let us go then to the general case—when  $X$  is an arbitrary selfadjoint element of  $A$ . The spectral theorem allows us to approximate  $X$  (in operator norm) by elements of the form (4). From the well-posedness of problem (2) we conclude that  $(t, X) \rightarrow K(t)$  is norm continuous, and the inequality (3) for arbitrary  $X$  follows from the same inequality for  $X$  of the form (4). This completes the proof of Theorem 1.

For  $a, b \in A^+$  let  $\text{dist}(a, b)$  denote the geodesic distance from  $a$  to  $b$  in the Finsler metric  $\|X\|_a$  of  $A$ . It is not hard to prove (using the invariance of the metric) that

$$\text{dist}(a, b) = \|\ln(a^{-1/2}ba^{-1/2})\|. \quad (8)$$

**THEOREM 2.** *If  $\gamma(t)$  and  $\delta(t)$  are geodesics in  $A^+$  then  $t \rightarrow \text{dist}(\gamma(t), \delta(t))$  is a convex function of  $t \in \mathbf{R}$ .*

*Proof.* Suppose the geodesics  $\gamma(t)$  and  $\delta(t)$  are defined for  $u \leq t \leq v$ . Define  $h(s, t)$  by the properties:

(a) the function  $s \rightarrow h(s, u)$ ,  $0 \leq s \leq 1$  is the geodesic joining  $\gamma(u)$  and  $\delta(u)$ ;

(b) the function  $s \rightarrow h(s, v)$ ,  $0 \leq s \leq 1$  is the geodesic joining  $\gamma(v)$  and  $\delta(v)$ ;

(c) for each  $s$ , the function  $t \rightarrow h(s, t)$ ,  $u \leq s \leq v$  is the geodesic joining  $h(s, u)$  and  $h(s, v)$ .

In particular  $h(0, t) = \gamma(t)$  and  $h(1, t) = \delta(t)$ . Define also  $J(s, t) = \partial h(s, t) / \partial s$ . Then, for each  $s$ ,  $t \rightarrow J(s, t)$  is a Jacobi field along the geodesic

$t \rightarrow h(s, t)$ . Finally define

$$f(t) = \int_0^1 \|J(s, t)\|_{h(s, t)} ds.$$

From Theorem 1,  $t \rightarrow \|J(s, t)\|$  is convex for each  $s$ . Hence  $t \rightarrow f(t)$  is also convex for  $u \leq t \leq v$ . But  $f(u) = \int_0^1 \|J(s, u)\|_{h(s, u)} ds$  is the length of the geodesic  $s \rightarrow h(s, u)$  and therefore  $f(u) = \text{dist}(\gamma(u), \delta(u))$ . Similarly,  $f(v) = \text{dist}(\gamma(v), \delta(v))$ . Now for  $u \leq t \leq v$ , the value  $f(t) = \int_0^1 \|J(s, t)\|_{h(s, t)} ds$  is the length of the curve  $s \rightarrow h(s, t)$  joining  $\gamma(t)$  and  $\delta(t)$  and then we have  $\text{dist}(\gamma(v), \delta(v)) \leq f(t)$ . Convexity of  $\text{dist}(\gamma(v), \delta(v))$  follows and Theorem 2 is proved.

**COROLLARY 2.1.** *For any fixed  $y \in A^+$  the function  $f: A^+ \rightarrow \mathbf{R}$ ,  $f(x) = \text{dist}(x, y)$  is "convex in the geometric sense", that is, each geodesic  $\gamma(t)$  satisfies*

$$f(\gamma(t)) \leq (1 - t)f(\gamma(0)) + tf(\gamma(1)).$$

*In particular geodesic spheres are convex sets.*

*Proof.* Take  $\delta(t) = y$  for all  $t$  and apply Theorem 2.

**COROLLARY 2.2.** *For any  $a_0, a_1, b_0,$  and  $b_1$  in  $A^+$  we have*

$$\begin{aligned} & \left\| \left( a_0^{1/2} (a_0^{-1/2} a_1 a_0^{-1/2})^t a_0^{1/2} \right)^{1/2} \left( b_0^{1/2} (b_0^{-1/2} b_1 b_0^{-1/2})^t b_0^{1/2} \right)^{1/2} \right\| \\ & \leq \|a_0^{1/2} b_0^{1/2}\|^{1-t} \|a_1^{1/2} b_1^{1/2}\|^t. \end{aligned} \quad (9)$$

*Proof.* Take two geodesics  $\gamma(t)$  and  $\delta(t)$  and write them as

$$\begin{aligned} \gamma(t) &= a_0^{1/2} (a_0^{-1/2} a_1 a_0^{-1/2})^t a_0^{1/2}, \\ \delta(t) &= b_0^{1/2} (b_0^{-1/2} b_1 b_0^{-1/2})^t b_0^{1/2} \end{aligned}$$

where  $a_0 = \gamma(0)$ ,  $a_1 = \gamma(1)$ ,  $b_0 = \delta(0)$ ,  $b_1 = \delta(1)$ . Then for each  $0 \leq t \leq 1$  we have, by convexity,

$$\text{dist}(\gamma(t), \delta(t)) \leq (1 - t)\text{dist}(a_0, b_0) + t \text{dist}(a_1, b_1)$$

or

$$\begin{aligned} & \left\| \ln(\gamma(t)^{-1/2} \delta(t) \gamma(t)^{-1/2}) \right\| \\ & \leq (1 - t) \left\| \ln(a_0^{-1/2} b_0 a_0^{-1/2}) \right\| + t \left\| \ln(a_1^{-1/2} b_1 a_1^{-1/2}) \right\|. \end{aligned}$$

Next we apply this formula to the geodesics  $\gamma(t)$  and  $k\delta(t)$  where  $k > 0$ . By choosing  $k$  large enough we can assume that

$$\begin{aligned}\gamma(t)^{-1/2}(k\delta(t))\gamma(t)^{-1/2} &> 1 \\ a_0^{-1/2}(kb_0)a_0^{-1/2} &> 1 \\ a_1^{-1/2}(kb_1)a_1^{-1/2} &> 1\end{aligned}$$

and therefore using  $\|\ln x\| = \ln\|x\|$  for  $x > 1$  and canceling out  $k$ , the last inequality for norms becomes

$$\|\gamma(t)^{-1/2}\delta(t)\gamma(t)^{-1/2}\| \leq \|a_0^{-1/2}b_0a_0^{-1/2}\|^{1-t}\|a_1^{-1/2}b_1a_1^{-1/2}\|^t.$$

Notice that  $\gamma(t)^{-1}$  is also a geodesic so that the last formula gives also:

$$\|\gamma(t)^{1/2}\delta(t)\gamma(t)^{1/2}\| \leq \|a_0^{1/2}b_0a_0^{1/2}\|^{1-t}\|a_1^{1/2}b_1a_1^{1/2}\|^t$$

or equivalently

$$\|\gamma(t)^{1/2}\delta(t)^{1/2}\| \leq \|a_0^{1/2}b_0^{1/2}\|^{1-t}\|a_1^{1/2}b_1^{1/2}\|^t.$$

which is another way to write (9).

This inequality has many variations. For example, replacing  $a_i$  by  $a_i^2$  and  $b_i$  by  $b_i^2$  and using the definition of the geodesics, we get

$$\left\| \left( a_0(a_0^{-1}a_1^2a_0^{-1})^t a_0 \right)^{-1/2} \left( b_0(b_0^{-1}b_1^2b_0^{-1})^t b_0 \right)^{-1/2} \right\| \leq \|a_0b_0\|^{1-t}\|a_1b_1\|^t$$

or using  $|z| = (zz^*)^{1/2}$ :

$$\left\| \left| a_0(a_0^{-1}a_1^2a_0^{-1})^{t/2} \right| \left| b_0(b_0^{-1}b_1^2b_0^{-1})^{1/2} \right| \right\| \leq \|a_0b_0\|^{1-t}\|a_1b_1\|^t.$$

As special cases of (9) we can also get  $\|ab^t a\| \leq \|aba\|^t$  and  $\|a^t b^t\| \leq \|ab\|^t$  for any  $a, b \in A^+$  and  $0 \leq t \leq 1$ .

**THEOREM 3** (see [3]). *The exponential function in  $A^+$  increases distances.*

*Proof.* By invariance it suffices to show that the exponential function increases distances at the identity  $1 \in A^+$ . Consider two geodesics of the form  $\gamma(t) = e^{tX}$  and  $\delta(t) = e^{tY}$ . Then according to Theorem 2 the function

$$f(t) = \text{dist}(\gamma(t), \delta(t)) = \|\ln(e^{-tX/2}e^{tY}e^{-tX/2})\|$$

is convex. Since  $f(0) = 0$  this implies that  $f(t)/t \leq f(1)$  for each  $0 < t \leq 1$ . Taking limits we have  $\lim_{t \rightarrow 0} f(t)/t \leq f(1)$ .

Observe next that  $\ln x$  can be approximated on any interval  $[x_0, x_1]$  with  $0 < x_0 < x_1$  uniformly in the  $C^1$  sense by polynomials  $p_n(x)$ . In particular  $\lim_{n \rightarrow \infty} p_n(x) = \ln x$  and  $\lim_{n \rightarrow \infty} p'_n(x) = 1/x$ . Then

$$\begin{aligned} & \lim_{t \rightarrow 0} \frac{1}{t} \ln(e^{-tX/2} e^{tY} e^{-tX/2}) \\ &= \lim_{n \rightarrow \infty} \lim_{t \rightarrow 0} \frac{1}{t} p_n(e^{-tX/2} e^{tY} e^{-tX/2}) \\ &= \lim_{n \rightarrow \infty} \left. \frac{d}{dt} p_n(e^{-tX/2} e^{tY} e^{-tX/2}) \right|_{t=0} = Y - X \end{aligned}$$

(the last inequality is justified below). Now from this equality and convexity we conclude that  $f(t) \geq t\|Y - X\|$  and this means that

$$\text{dist}(\exp_a(tX), \exp_a(tY)) \geq t\|Y - X\| \quad \text{for all } a \in A^+ \quad \text{and all } X, Y \in TA_a^+.$$

To finish the proof write the polynomials  $p_n$  explicitly as  $p_n(x) = \sum r_{n,k} x^k$ . Then

$$\begin{aligned} & \left. \frac{d}{dt} \ln(e^{-tX/2} e^{tY} e^{-tX/2}) \right|_{t=0} \\ &= \lim_{n \rightarrow \infty} \left. \frac{d}{dt} p_n(e^{-tX/2} e^{tY} e^{-tX/2}) \right|_{t=0} \\ &= \lim_{n \rightarrow \infty} \sum r_{n,k} \left. \frac{d}{dt} (e^{-tX/2} e^{tY} e^{-tX/2})^k \right|_{t=0} \\ &= \lim_{n \rightarrow \infty} \sum r_{n,k} (Y - X)^k = \lim_{n \rightarrow \infty} p'_n(1)(Y - X) = (Y - X). \end{aligned}$$

As observed in [3] this property of the exponential is equivalent to Segal's inequality ( $\|e^{X+Y}\| \leq \|e^X e^Y\|$  for  $X, Y$  selfadjoint) which is therefore another consequence of the convexity of the distance function in  $A^+$ .

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