

## ADMISSIBILITY OF THE LIKELIHOOD RATIO TEST WHEN A NUISANCE PARAMETER IS PRESENT ONLY UNDER THE ALTERNATIVE

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This paper establishes the asymptotic admissibility of the likelihood ratio (LR) test for a general class of testing problems in which a nuisance parameter is present only under the alternative hypothesis. The paper also establishes the finite sample admissibility of the LR test for testing problems of this sort that arise in Gaussian linear regression models with known variance.

**1. Introduction.** This paper considers hypothesis tests when a nuisance parameter is present only under the alternative hypothesis. Such tests are nonstandard and the classical likelihood ratio (LR) test does not possess its usual chi-square asymptotic null distribution in this context. It also does not possess its usual asymptotic optimality properties [of the sort considered by Wald (1943)].

Davies (1977, 1987) first provided a general asymptotic analysis of the testing problems considered here. He established the asymptotic null distribution of the LR test under a set of high-level assumptions. He also provided approximations to the asymptotic critical values of the LR test.

Andrews and Ploberger (1994) (denoted AP) developed a class of tests, called average exponential LR tests, that exhibit explicit asymptotic optimality properties in terms of weighted average power when a nuisance parameter is present only under the alternative. The weight functions they consider are particular multivariate normal densities. The class of tests that are optimal with respect to these weight functions does not include the LR test. These results, Davies' adoption of the LR test and the omnibus use of the LR test make the question of the asymptotic admissibility of the LR test one of considerable interest (to some at least). It is this question that is addressed in the present paper.

We show that the LR test and two asymptotically equivalent tests, namely, the sup Wald and sup Lagrange multiplier (LM) tests, are asymptotically admissible. In fact, we show that these tests are best tests, in a certain sense, against alternatives that are sufficiently distant from the null hypothesis. We establish these results first under a set of high-level assumptions. Then we

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provide primitive sufficient conditions for a number of examples. The examples considered include tests of (i) cross-sectional constancy in nonlinear models, (ii) threshold effects in autoregressive models and (iii) variable relevance in nonlinear models, such as Box–Cox transformed regressor models. Primitive sufficient conditions for tests of changepoints are given in AP. Two examples that are covered by the high-level results, but for which primitive conditions are not provided, are tests of (i) white noise versus first-order autoregressive moving average structure and (ii) white noise versus first-order generalized autoregressive conditional heteroskedasticity.

Next, we consider finite sample admissibility of the LR test for the Gaussian linear regression model with known variance. Minor modifications to the proof of the asymptotic admissibility result yield finite sample admissibility. The types of hypotheses covered by this result include tests of (i) single and multiple changepoints, (ii) variable relevance for Box–Cox transformed regressors and (iii) cross-sectional constancy, among others. The admissibility result for a single changepoint in the case of an iid univariate Gaussian location model replicates a recent result of Chang and Hartigan (1993).

The remainder of this paper is organized as follows. Section 2 presents the main asymptotic admissibility result under a set of high-level assumptions. Section 3 presents examples and provides primitive sufficient conditions for the high-level assumptions. Section 4 states the finite sample admissibility results for tests concerning a Gaussian linear regression model. Section 5 gives proofs of the results stated in earlier sections.

**2. Asymptotic admissibility.** This section introduces notation and assumptions and states the asymptotic admissibility result of the paper. The notation and assumptions are very similar to those of AP.

*2.1. Notation and definitions.* Let  $\underline{Y}_T$  denote the data matrix when the sample size is  $T$  for  $T = 1, 2, \dots$ . Consider a parametric family  $\{f_T(y_T, \theta, \pi): \theta \in \Theta, \pi \in \Pi\}$  of densities of  $\underline{Y}_T$  with respect to some  $\sigma$ -finite measure  $\mu_T$ , where  $\Theta \subset R^s$  and  $\Pi$  is some metric space (usually a subset of Euclidean space). The likelihood function of the data is given by  $f_T(\theta, \pi) = f_T(\underline{Y}_T, \theta, \pi)$ .

The parameter  $\theta$  is taken to be of the form  $\theta = (\beta', \delta')$ , where  $\beta \in R^p$ ,  $\delta \in R^q$  and  $s = p + q$ . For example, in one-time changepoint problems, the parameter  $\pi \in (0, 1)$  indicates the point of change as a fraction of the sample size,  $\delta$  is of the form  $(\delta'_1, \delta'_2)'$ ,  $\delta_1$  is a prechange parameter vector,  $\delta_1 + \beta$  is a postchange parameter vector and  $\delta_2$  is a parameter vector that is constant across regimes.

The null hypothesis of interest is

$$(2.1) \quad H_0: \beta = \underline{0}.$$

In the changepoint problem, this is the hypothesis of no change. The alternative hypothesis is

$$(2.2) \quad H_1: \beta \neq \underline{0}$$

and the likelihood function depends on the parameter  $\pi$ .

We let  $\theta_0$  denote the true value of  $\theta$  under the null hypothesis. Under the null hypothesis, the likelihood function  $f_T(\theta_0, \pi)$  does not depend on the parameter  $\pi$  and is denoted  $f_T(\theta_0)$ . Let  $l_T(\theta, \pi) = \log f_T(\theta, \pi)$ . Let  $Dl_T(\theta, \pi)$  denote the  $s$ -vector of partial derivatives of  $l_T(\theta, \pi)$  with respect to  $\theta$ . Let  $D^2l_T(\theta, \pi)$  denote the  $s \times s$  matrix of second partial derivatives of  $l_T(\theta, \pi)$  with respect to  $\theta$ . [Note that  $Dl_T(\theta_0, \pi)$  and  $D^2l_T(\theta_0, \pi)$  depend on  $\pi$  in general even though  $f_T(\theta_0, \pi)$  and  $l_T(\theta_0, \pi)$  do not.]

We consider the case where the appropriate norming factors for  $Dl_T(\theta, \pi)$  and  $D^2l_T(\theta, \pi)$  [so that each is  $O_p(1)$ , but not  $o_p(1)$ ] are nonrandom diagonal  $s \times s$  matrices  $B_T^{-1}$  and  $B_T^{-1} \times B_T^{-1}$ , respectively, where  $[B_T^{-1}]_{jj} \rightarrow 0$  as  $T \rightarrow \infty \forall j \leq s$ . For nontrending data, the matrix  $B_T$  is just  $\sqrt{T}I_s$ . For data with deterministic time trends,  $B_T$  is more complicated; see AP. The local alternatives to  $H_0$  that we consider are of the form  $f_T(\theta_0 + B_T^{-1}h, \pi)$  for  $h \in R^s$  and  $\pi \in \Pi$ .

All limits below are taken “as  $T \rightarrow \infty$ ” unless stated otherwise. We say that a statement holds “under  $\theta_0$ ” (i.e., under the null hypothesis) if it holds when the true density of  $\underline{Y}_T$  is  $f_T(\theta_0)$  for  $T = 1, 2, \dots$ . Let  $\lambda_{\min}(A)$  denote the smallest eigenvalue of a matrix  $A$ . Let  $\|\cdot\|$  denote the Euclidean norm. Let  $wp \rightarrow 1$  abbreviate “with probability that goes to 1 as  $T \rightarrow \infty$ .”

2.2. *Assumptions.* The likelihood function/parametric model is assumed to satisfy the following assumption.

ASSUMPTION 1. (a)  $f_T(\theta, \pi)$  does not depend on  $\pi$  for all  $\theta$  in the null hypothesis.

(b)  $\theta_0$  is an interior point of  $\Theta$ .

(c)  $f_T(\theta, \pi)$  is twice continuously partially differentiable in  $\theta$  for all  $\theta \in \Theta_0$  and  $\pi \in \Pi$  with probability 1 under  $\theta_0$ , where  $\Theta_0$  is some neighborhood of  $\theta_0$ .

(d)  $\sup_{\pi \in \Pi, \theta \in \Theta_0} | -B_T^{-1}D^2l_T(\theta, \pi)B_T^{-1} - \mathbf{I}(\theta, \pi) | \rightarrow_p 0$  under  $\theta_0$  for some nonrandom  $s \times s$  matrix function  $\mathbf{I}(\theta, \pi)$  and some sequence of nonrandom diagonal  $s \times s$  matrices  $\{B_T: T \geq 1\}$  that satisfies  $[B_T]_{jj} \rightarrow \infty$  as  $T \rightarrow \infty \forall j \leq s$ .

(e)  $\mathbf{I}(\theta, \pi)$  is continuous in  $(\theta, \pi)$  on  $\Theta_0 \times \Pi$ .

(f)  $\mathbf{I}(\theta_0, \pi)$  is positive definite for all  $\pi \in \Pi$ .

The matrix function  $\mathbf{I}(\theta, \pi)$  introduced in Assumption 1 is the asymptotic information matrix for  $\theta$  for given  $\pi$ , which depends on both  $\theta$  and  $\pi$ . See AP for comments on Assumption 1.

Let  $\hat{\theta}(\pi) [= \hat{\theta}_T(\pi)]$  be the (*unrestricted*) maximum likelihood (ML) estimator of  $\theta$  for fixed  $\pi \in \Pi$ . That is,  $\hat{\theta}(\pi)$  satisfies

$$(2.3) \quad l_T(\hat{\theta}(\pi), \pi) = \sup_{\theta \in \Theta} l_T(\theta, \pi) \quad \forall \pi \in \Pi \text{ wp } \rightarrow 1 \text{ under } \theta_0.$$

Let  $\tilde{\theta}$  be the *restricted maximum likelihood estimator* of  $\theta$ . That is,  $\tilde{\theta}$  satisfies

$$(2.4) \quad \begin{aligned} \tilde{\theta} \in \tilde{\Theta} &= \{\theta \in \Theta: \theta = (0', \delta')' \text{ for some } \delta \in R^q\}, \\ l_T(\tilde{\theta}, \pi) &= \sup_{\theta \in \tilde{\Theta}} l_T(\theta, \pi) \quad \text{wp} \rightarrow 1 \text{ under } \theta_0. \end{aligned}$$

Note that  $\tilde{\theta}$  does not depend on  $\pi$  by Assumption 1(a).

We assume that the parametric model is sufficiently regular that the ML estimators  $\hat{\theta}(\pi)$  and  $\tilde{\theta}$  are consistent for  $\theta_0$  under the null hypothesis uniformly over  $\pi \in \Pi$ .

ASSUMPTION 2.  $\sup_{\pi \in \Pi} \|\hat{\theta}(\pi) - \theta_0\| \rightarrow_p 0$  under  $\theta_0$ .

ASSUMPTION 3.  $\tilde{\theta} - \theta_0 \rightarrow_p 0$  under  $\theta_0$ .

The parameter space  $\Pi$  is assumed to satisfy the next assumption.

ASSUMPTION 4.  $\Pi$  is a compact metric space with metric  $\rho$ .

We now specify high-level conditions under which the asymptotic null distribution of the sup LR, Wald and LM test statistics (defined below) can be determined. Let  $\rightarrow_d$  denote convergence in distribution. Let  $\Rightarrow$  denote weak convergence of stochastic processes indexed by  $\pi \in \Pi$ . Below we consider weak convergence of the process  $B_T^{-1} D l_T(\theta_0, \pi)$  ( $\in R^s$ ) indexed by  $\pi \in \Pi$  to a process  $G(\theta_0, \pi)$ . Note that the definition of weak convergence requires the specification of a metric  $d$  on the space  $\mathbf{E}$  of  $R^s$ -valued functions on  $\Pi$ . We assume  $d$  is chosen such that (i) the function

$$(2.5) \quad G(\cdot) \rightarrow \sup_{\pi \in \Pi} (HG(\pi))' [H\mathbf{I}^{-1}(\theta_0, \pi)H']^{-1} HG(\pi)$$

is continuous at each function  $G \in \mathbf{E}$  that is continuous on  $\Pi$ , where  $H = [I_p; 0] \in R^{p \times s}$  and (ii) if  $g_n \in \mathbf{E} \forall n \geq 0$ ,  $g_0$  is continuous on  $\Pi$  and  $d(g_n, g_0) \rightarrow 0$  as  $n \rightarrow \infty$ , then

$$(2.6) \quad \sup_{\pi \in \Pi} \|g_n(\pi) - g_0(\pi)\| \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

These conditions hold, for example, if the uniform metric is used, as in Pollard (1984), or if the Skorohod metric is used in the case when  $\Pi \subset [0, 1]$  or  $\Pi \subset [0, 1]^r$ , as in Billingsley (1968).

We assume that the normalized score function satisfies the following assumption.

ASSUMPTION 5.  $B_T^{-1} D l_T(\theta_0, \cdot) \Rightarrow G(\theta_0, \cdot)$  under  $\theta_0$  (as processes indexed by  $\pi \in \Pi$ ) for some mean zero  $R^s$ -valued Gaussian stochastic process  $\{G(\theta_0, \pi): \pi \in \Pi\}$  that has  $EG(\theta_0, \pi)G(\theta_0, \pi)' = \mathbf{I}(\theta_0, \pi) \forall \pi \in \Pi$  and has continuous sample paths (as functions of  $\pi$  for fixed  $\theta_0$ ) with probability 1.

In applications, Assumption 5 is verified by applying a functional CLT. Assumptions 1-3 and 5 above are the same as in AP.

2.3. *Specification of weight functions.* The admissibility result given below is stated in terms of *weighted average power*. That is, we show that for certain weight functions the sup LR, Wald and LM tests have greater weighted average power than any other *asymptotically distinct* test. To achieve this, a weight function  $J(\cdot)$  needs to be specified for the parameter  $\pi \in \Pi$ . Given  $\pi$ , a weight function  $Q_{r,\pi}(\cdot)$  needs to be specified for the perturbation vector  $h$  that appears in the local alternative density  $f_T(\theta_0 + B_T^{-1}h, \pi)$ .

Let  $S(\pi, \varepsilon)$  denote the open sphere in  $\Pi$  centered at  $\pi$  with radius  $\varepsilon > 0$ . Of the weight function  $J(\cdot)$ , we only assume the following statement.

ASSUMPTION 6.  $J(\cdot)$  is a probability measure on  $\Pi$  for which  $\inf_{\pi \in \Pi} J(S(\pi, \varepsilon)) > 0 \forall \varepsilon > 0$ .

If  $\Pi$  is separable (and satisfies Assumption 4), then Assumption 6 holds provided the support of  $J$  is  $\Pi$ .

The weight functions  $\{Q_{r,\pi}: \pi \in \Pi\}$  for  $r > 0$  are taken to be ellipses of radius proportional to  $r$ . The ellipses are the same as those considered by Wald (1943) for a single fixed  $\pi$ .

ASSUMPTION 7.  $Q_{r,\pi}$  is the distribution of  $rA_\pi(A'_\pi \mathbf{I}_\pi A_\pi)^{-1/2}X$ , where  $X \sim U_p$ ,  $U_p$  is the uniform distribution on the unit sphere in  $R^p$ ,  $\mathbf{I}_\pi = \mathbf{I}(\theta_0, \pi) = \begin{bmatrix} \mathbf{I}_{1\pi} & \mathbf{I}_{2\pi} \\ \mathbf{I}'_{2\pi} & \mathbf{I}_{3\pi} \end{bmatrix}$  and  $A_\pi = \begin{bmatrix} I_p \\ -\mathbf{I}'_{3\pi} \mathbf{I}_{2\pi} \end{bmatrix}$ .

2.4. *Definition of the sup LR, Wald and LM test statistics.* For known  $\pi \in \Pi$ , the standard LR, Wald and LM test statistics for testing  $H_0$  against  $H_1$  [as defined in (2.1) and (2.2)] are given by

$$\begin{aligned} \text{LR}_T(\pi) &= -2(l_T(\tilde{\theta}, \pi) - l_T(\hat{\theta}(\pi), \pi)), \\ (2.7) \quad W_T(\pi) &= (HB_T \hat{\theta}(\pi))' [H \mathbf{I}_T^{-1}(\hat{\theta}(\pi), \pi) H']^{-1} HB_T \hat{\theta}(\pi), \\ \text{LM}_T(\pi) &= [B_T^{-1} D l_T(\tilde{\theta}, \pi)]' \mathbf{I}_T^{-1}(\tilde{\theta}, \pi) B_T^{-1} D l_T(\tilde{\theta}, \pi), \end{aligned}$$

where

$$H = [I_p; 0] \subset R^{p \times s} \quad \text{and} \quad \mathbf{I}_T(\theta, \pi) = -B_T^{-1} D^2 l_T(\theta, \pi) B_T^{-1}.$$

Alternatively, one can define  $\mathbf{I}_T(\theta, \pi)$  to be of outer product, rather than Hessian, form.

The sup LR, Wald and LM test statistics are now defined as

$$(2.8) \quad \sup_{\pi \in \Pi} \text{LR}_T(\pi), \quad \sup_{\pi \in \Pi} W_T(\pi) \quad \text{and} \quad \sup_{\pi \in \Pi} \text{LM}_T(\pi).$$

Note that the sup LR test statistic is the standard LR test statistic for the case of unknown  $\pi$ .

Let  $\{k_{T\alpha}: T \geq 1\}$  be a sequence of critical values (possibly random, but with nonrandom probability limit in this case) such that the sup LR, Wald or LM tests  $\{\xi_T: T \geq 1\}$  have asymptotic significance level  $\alpha$ . That is,  $\int \xi_T f_T(\theta_0) d\mu_T \rightarrow \alpha$  for all  $\theta_0$  that satisfy the null hypothesis, where

$$(2.9) \quad \xi_T = 1 \left( \sup_{\pi \in \Pi} \text{LR}_T(\pi) > k_{T\alpha} \right)$$

or where  $\xi_T$  is defined analogously with  $\text{LR}_T(\pi)$  replaced by  $W_T(\pi)$  or  $\text{LM}_T(\pi)$ .

Under Assumptions 1–5, the asymptotic null distribution of

$$\sup_{\pi \in \Pi} \text{LR}_T(\pi), \quad \sup_{\pi \in \Pi} W_T(\pi) \quad \text{and} \quad \sup_{\pi \in \Pi} \text{LM}_T(\pi)$$

is that of

$$(2.10) \quad \sup_{\pi \in \Pi} (HG(\theta_0, \pi))' (H\mathbf{I}^{-1}(\theta_0, \pi)H')^{-1} HG(\theta_0, \pi).$$

This is proved by an argument analogous to that used to prove Theorem 1 of AP.

2.5. *Asymptotic admissibility.* Let  $\varphi_T$  denote a test of  $H_0$ . That is,  $\varphi_T$  is a  $[0, 1]$ -valued function that is determined by  $\underline{Y}_T$  (and perhaps some randomization scheme) that rejects  $H_0$  with probability  $\gamma$  when  $\varphi_T = \gamma$ . The power of  $\varphi_T$  against the local alternative  $f_T(\theta_0 + B_T^{-1}h, \pi)$  is denoted  $\int \varphi_T f_T(\theta_0 + B_T^{-1}h, \pi) d\mu_T$ .

DEFINITION. A sequence of tests  $\{\varphi_T: T \geq 1\}$  is *asymptotically distinct* from the sup LR, Wald or LM tests  $\{\xi_T: T \geq 1\}$  if

$$(2.11) \quad \delta = \liminf_{T \rightarrow \infty} \int (1 - \varphi_T) \xi_T f_T(\theta_0) d\mu_T > 0.$$

Note that  $\int (1 - \varphi_T) \xi_T f_T(\theta_0) d\mu_T$  is just the null probability that the test  $\varphi_T$  accepts  $H_0$  and the sup test  $\xi_T$  rejects  $H_0$ . If two tests are not equal almost surely (under  $\theta_0$ ) and are not nested, then this probability is positive. Inequality (2.11) requires that this distinction between  $\varphi_T$  and  $\xi_T$  does not disappear as  $T \rightarrow \infty$ .

The sup LR, Wald and LM tests are asymptotically equivalent under the null and local alternatives under Assumptions 1–5; see AP. In consequence, if a sequence of tests is asymptotically distinct from any one of the three, it is asymptotically distinct from all three.

The main result of this paper is the following admissibility result.

THEOREM 1. *Suppose Assumptions 1–7 hold and  $\{\varphi_T: T \geq 1\}$  is a sequence of tests that is asymptotically distinct from a sequence of asymptotically level*

$\alpha$  supremum LR, Wald, or LM tests  $\{\xi_T: T \geq 1\}$ . Then there exists an  $r_0 < \infty$  such that, for all  $r \geq r_0$ ,

$$\begin{aligned} & \limsup_{T \rightarrow \infty} \int \left[ \int \varphi_T f_T(\theta_0 + B_T^{-1}h, \pi) d\mu_T \right] dQ_{r, \pi}(h) dJ(\pi) \\ & < \liminf_{T \rightarrow \infty} \int \left[ \int \xi_T f_T(\theta_0 + B_T^{-1}h, \pi) d\mu_T \right] dQ_{r, \pi}(h) dJ(\pi). \end{aligned}$$

(In addition, the  $\liminf_{T \rightarrow \infty}$  on the right-hand side equals  $\lim_{T \rightarrow \infty}$ .)

REMARKS.

1. The proof of Theorem 1 shows that the ratio of the asymptotic (as  $T \rightarrow \infty$ ) weighted average type II error of  $\varphi_T$  [with respect to  $(Q_{r, \pi}, J)$ ] over that of  $\xi_T$  diverges to infinity as  $r \rightarrow \infty$ .
2. Theorem 1 holds for any weight functions  $J$  that satisfy Assumption 6.
3. Theorem 1 holds for any sequence of asymptotically distinct tests  $\{\varphi_T: T \geq 1\}$ —it need not be a sequence of tests of asymptotic significance level  $\alpha$ . Thus, for certain alternatives the only way to increase the asymptotic power of a sequence of sup tests is to enlarge its critical regions.
4. Assumption 3 is not required in Theorem 1 for the case of the sup Wald test.

3. Examples.

3.1. Empirical process examples. This section provides primitive sufficient conditions for Assumptions 1–5 for empirical process examples.

EXAMPLE 1 (Cross-sectional constancy). In this example, the observations are iid and the unknown parameter  $\pi$  partitions the sample space of some observed variable(s) into  $m + 1$  regions. In one region the model is indexed by the parameter  $(\delta'_1, \delta'_2)'$  and in other regions it is indexed by  $(\delta'_1 + \beta'_j, \delta'_2)'$  for  $j \leq m$ . In this case,  $\theta = (\beta', \delta)'$  for  $\beta = (\beta'_1, \dots, \beta'_m)'$  and  $\delta = (\delta'_1, \delta'_2)'$ . In this model, a test of cross-sectional constancy of the parameters corresponds to a test of the null hypothesis  $H_0: \beta = 0$ .

To be concrete, consider the special case given by a linear regression model with two regions:

$$(3.1) \quad Y_t = \begin{cases} X'_t \delta_1 + U_t, & \text{for } Z_t \leq \pi, \\ X'_t (\delta_1 + \beta) + U_t, & \text{for } Z_t > \pi, \end{cases} \quad \text{for } t = 1, \dots, T,$$

where  $\{(Y_t, X_t, Z_t, U_t): t = 1, \dots, T\}$  are iid,  $(X_t, Z_t)$  and  $U_t$  are independent;  $U_t$  is an unobserved  $N(0, \delta_2)$  error,  $Y_t$  is an observed scalar random variable;  $X_t$  is an observed random  $p$ -vector with  $EX'_t X_t < \infty$ ;  $Z_t$  is an observed scalar random variable that may be an element of  $X_t$ ;  $Z_t$  has bounded density with respect to Lebesgue measure on the intersection of its support and  $\Pi$ ;

$$\inf_{\pi \in \Pi} \lambda_{\min} \left( E \begin{pmatrix} X_t 1(Z_t > \pi) \\ X_t \end{pmatrix} \begin{pmatrix} X_t 1(Z_t > \pi) \\ X_t \end{pmatrix}' \right) > 0;$$

the parameter  $\theta = (\beta', \delta_1', \delta_2)'$  lies in a compact set  $\Theta \subset R^{2p+1}$  that excludes  $\delta_2$  values less than or equal to 0; the parameter  $\pi$  lies in a compact set  $\Pi \subset R$ ; and the true parameter  $\theta_0$  lies in the interior of  $\Theta$  under  $H_0$ .

**EXAMPLE 2 (Threshold autoregression).** This example generalizes Example 1 to time series contexts in which the variable (or vector)  $Z_t$  is often given by a lagged value(s) of a dependent variable. In particular, consider the simple threshold autoregressive model defined by (3.1) with  $X_t = (1, Y_{t-1})'$ ,  $Z_t = Y_{t-d}$  for some integer  $d > 0$ ,  $\{U_t: t = 1, \dots, T\}$  are iid,  $(Y_0, Y_{1-d})$  have distributions that correspond to a stationary startup of the AR model when  $\beta = 0$  and  $\Theta$  and  $\Pi$  are as defined above with  $p = 2$  and  $|\delta_1| < 1$ . Models of this sort have been applied in the physical and biological sciences [e.g., see Tong (1990)], as well as in economics [e.g., see Potter (1995)]. Typically, it is of interest with these models to test for the existence of a threshold effect, which corresponds to testing the null  $H_0: \beta = 0$ .

**EXAMPLE 3 (Variable relevance).** This example considers tests of variable relevance in nonlinear models. For specificity, consider a nonlinear regression model

$$(3.2) \quad Y_t = g(X_t, \delta_1) + \beta h(Z_t, \pi) + U_t \quad \text{for } t = 1, \dots, T,$$

where  $\{(Y_t, X_t, Z_t, U_t): t = 1, \dots, T\}$  are iid;  $(X_t, Z_t)$  and  $U_t$  are independent;  $U_t$  is an unobserved  $N(0, \delta_2)$  error;  $Y_t$  is an observed scalar random variable;  $X_t$  and  $Z_t$  are observed random vectors;  $g$  and  $h$  are known functions;  $\beta$  is a scalar parameter;  $\pi$  is an  $R^b$ -valued parameter;  $\theta = (\beta, \delta_1', \delta_2)'$  and  $\pi$  lie in compact sets  $\Theta$  and  $\Pi$ , respectively;  $\Theta$  excludes  $\delta_2$  values less than or equal to 0; the true parameter  $\theta_0$  lies in the interior of  $\Theta$  under  $H_0$ ;  $g(X_t, \delta_1)$  is two times continuously differentiable in  $\delta_1 \forall \theta \in \Theta_0$  with probability 1 under  $\theta_0$ , where  $\Theta_0$  is some neighborhood of  $\theta_0$ ;  $h(Z_t, \pi)$  is differentiable in  $\pi$  with probability 1 under  $\theta_0 \forall \pi \in \Pi$ ;  $E \sup_{\theta \in \Theta} g^2(X_t, \delta_1) < \infty$ ;  $E \sup_{\pi \in \Pi} h^2(Z_t, \pi) \log^+(|h(Z_t, \pi)|) < \infty$ , where  $\log^+(x) = \max\{\log(x), 0\}$  for  $x \geq 0$ ;

$$E \sup_{\theta \in \Theta_0} \left\| \frac{\partial}{\partial \delta_1} g(X_t, \delta_1) \right\|^2 < \infty;$$

$$E \sup_{\theta \in \Theta_0} \left\| \frac{\partial^2}{\partial \delta_1 \partial \delta_1'} g(X_t, \delta_1) \right\|^2 < \infty;$$

$$E \sup_{\pi \in \Pi} \left\| \frac{\partial}{\partial \pi} h(Z_t, \pi) \right\|^r \leq \infty \quad \text{for some } r > 2;$$

$$\inf_{\pi \in \Pi} \lambda_{\min} \left( E \begin{pmatrix} h(Z_t, \pi) \\ (\partial/\partial \delta_1) g(X_t, \delta_{10}) \end{pmatrix} \begin{pmatrix} h(Z_t, \pi) \\ (\partial/\partial \delta_1) g(X_t, \delta_{10}) \end{pmatrix}' \right) > 0$$

and  $E(g(X_t, \delta_1) - g(X_t, \delta_{10}) + \beta h(Z_t, \pi))^2 > 0 \forall \theta \in \Theta$  with  $\theta \neq \theta_0$ .



For example,  $h(Z_t, \pi)$  might be of the Box-Cox form  $(Z_t^\pi - 1)/\pi$ . A test for the relevance of the regressors  $Z_t$  is a test of the null hypothesis  $H_0: \beta = 0$ .

EXAMPLE 4 (Functional form). Example 3 covers tests of functional form. For example, in (3.2), if  $Z_t$  is taken to be a subvector of  $X_t$ , a test of  $H_0: \beta = 0$  is a test of functional form of the regression function. Neural network tests of functional form and some consistent tests of model specification are of this type.

We now introduce the requisite definitions and assumptions used for the empirical process examples. The data are given by  $\{(Y_t, X_t): t = 1, \dots, T\}$  which are part of a strictly stationary, absolutely regular process  $\{(Y_t, X_t): t = \dots, 0, 1, \dots\}$ , where  $\{Y_t\}$  is an  $m$ th order Markov sequence of random variables and  $\{X_t\}$  is a sequence of weakly exogeneous variables. By definition,  $\{Y_t: t = \dots, 0, 1, \dots\}$  is  $m$ th order Markov if the conditional distribution of  $Y_t$  given  $\mathbf{F}_{t-1} = \sigma(\dots, Y_{t-2}, Y_{t-1}; \dots, X_{t-1}, X_t)$  equals the conditional distribution of  $Y_t$  given  $Y_{t,m} = (Y_{t-m}, \dots, Y_{t-1})$  and  $X_{t,m} = (X_{t-m}, \dots, X_t)$  for all  $t$ . By definition,  $\{X_t\}$  is *weakly exogeneous* if the conditional distribution of  $X_t$  given  $Y_1, \dots, Y_{t-1}, X_1, \dots, X_{t-1}$  does not depend on the unknown parameters  $\theta$  and  $\pi \forall t \geq 1$ .

By definition, a sequence  $\{W_t: t = \dots, 0, 1, \dots\}$  is *absolutely regular* ( $\beta$ -mixing) if  $\beta(s) \rightarrow 0$  as  $s \rightarrow \infty$ , where  $\beta(s)$  is defined as follows. For any two  $\sigma$ -fields  $\mathbf{A}$  and  $\mathbf{B}$ , define

$$(3.3) \quad \beta(\mathbf{A}, \mathbf{B}) = \frac{1}{2} \sup \sum_{(i,j) \in I \times J} |P(A_i \cap B_j) - P(A_i)P(B_j)|,$$

where the supremum is taken over all finite partitions of the sample space  $\{A_i: i \in I\}$  and  $\{B_j: j \in J\}$  that are  $\mathbf{A}$  and  $\mathbf{B}$  measurable, respectively. Let  $\mathbf{F}_t = \sigma(\dots, W_{t-1}, W_t)$  and  $\mathbf{F}^t = \sigma(W_t, W_{t+1}, \dots)$ , where  $\sigma(\cdot)$  denotes a  $\sigma$ -field. Then

$$(3.4) \quad \beta(s) = \sup_t \beta(\mathbf{F}_t, \mathbf{F}^{t+s}).$$

Absolute regularity is stronger than strong mixing ( $\alpha$ -mixing), but weaker than  $\varphi$ -mixing. Examples of absolutely regular processes are given by Davydov (1973), Mokkadem (1986, 1990) and Doukhan (1994). They include, under suitable conditions, finite state space Harris recurrent Markov chains, vector autoregressive moving average processes, bilinear processes and nonlinear autoregressive processes, among others. In particular, the AR process of Example 2 under  $H_0$  is absolutely regular with  $\beta(s) = O(\rho^s)$  for  $0 < \rho < 1$  by Mokkadem (1986).

Let  $W_t = (Y'_{t-m}, \dots, Y'_t, X'_{t-m}, \dots, X'_t)'$ . Let

$$(3.5) \quad g(W_t, \theta, \pi) = g(Y_t | Y_{t-m}, \dots, Y_{t-1}, X_{t-m}, \dots, X_t; \theta, \pi),$$

for  $\theta \in \Theta$  and  $\pi \in \Pi$  denote a parametric family of conditional densities (with respect to some measure) of  $Y_t$  given  $Y_1, \dots, Y_{t-1}, X_1, \dots, X_t$  evaluated at the random variables  $Y_1, \dots, Y_t, X_1, \dots, X_t$ . The parameter space  $\Theta$  is a subset of

$R^s$  and  $\Pi$  also is a subset of Euclidean space. Let

$$(3.6) \quad h_t = h(X_t|Y_1, \dots, Y_{t-1}, X_1, \dots, X_{t-1})$$

denote the conditional density (with respect to some measure) of  $X_t$  given  $Y_1, \dots, Y_{t-1}, X_1, \dots, X_{t-1}$  evaluated at the random variables  $Y_1, \dots, Y_{t-1}, X_1, \dots, X_t$ .

The likelihood and log-likelihood functions of the sample are

$$(3.7) \quad \begin{aligned} f_T(\theta, \pi) &= \prod_{t=1}^T g(W_t, \theta, \pi) \prod_{t=1}^T h_t \quad \text{and} \\ l_T(\theta, \pi) &= \sum_{t=1}^T \log g(W_t, \theta, \pi) + \sum_{t=1}^T h_t. \end{aligned}$$

The information matrix for  $\theta$  given  $\pi$  is defined to be

$$(3.8) \quad \mathbf{I}(\theta, \pi) = -E \frac{\partial^2}{\partial \theta \partial \theta'} \log g(W_t, \theta, \pi).$$

Below, we use the concept of  $L^r$ -continuity. Let  $f(W_t, \tau)$  be a vector-valued function of a vector  $\tau \in \mathbf{T}$ . We say that  $f$  is  $L^r$ -continuous at  $\tau_0$  if

$$(3.9) \quad E \sup_{\tau \in \mathbf{T}: \|\tau - \tau_0\| < \delta} \|f(W_t, \tau) - f(W_t, \tau_0)\|^r \rightarrow 0 \quad \text{as } \delta \rightarrow 0,$$

where  $\|\cdot\|$  is the Euclidean norm. We say that  $f$  is  $L^r$ -continuous at  $\tau_0$  with modulus of continuity  $c(\delta)$  if the left-hand side of (3.9) is less than or equal to  $c(\delta) \forall \delta$  small and  $c(\delta) \rightarrow 0$  as  $\delta \rightarrow 0$ . Of course,  $L^r$ -continuity is implied by almost sure pointwise continuity [viz.,  $f(W_t, \tau) \rightarrow f(W_t, \tau_0)$  as  $\tau \rightarrow \tau_0$  a.s.] plus a moment condition [viz.,  $E \sup_{\tau \in \mathbf{T}: \|\tau - \tau_0\| < \delta} \|f(W_t, \tau) - f(W_t, \tau_0)\|^r < \infty$  for some  $\delta > 0$ ] by the dominated convergence theorem.

To obtain the weak convergence property of Assumption 5, we use a bracketing empirical process central limit theorem (CLT) of Doukhan, Mas-sart and Rio (1995). The latter is a generalization to strictly stationary absolutely regular processes of an empirical process CLT of Ossiander (1987) for iid processes.

Throughout this section, we assume  $g(\cdot, \theta, \pi), (\partial/\partial \theta) \log g(\cdot, \theta, \pi)$  and  $(\partial^2/\partial \theta \partial \theta') \log g(\cdot, \theta, \pi)$  are Borel measurable functions  $\forall \theta \in \Theta, \forall \pi \in \Pi$ , as are their element by element suprema and infima over all balls in  $\Theta \times \Pi$  of small radius. All expectations  $E$  below are taken under  $\theta_0$ .

The following Assumptions EP1-EP4' are sufficient for Assumptions 1-5 of Section 2.

ASSUMPTION EP1. (a) Under  $\theta_0$ ,  $\{(Y_t, X_t): t = \dots, 0, 1, \dots\}$  is a strictly stationary absolutely regular sequence of random variables with  $\sum_{s=1}^\infty s^{2/(r-2)} \beta(s) < \infty$  for some constant  $r > 2$ ,  $\{Y_t: t = \dots, 0, 1, \dots\}$  is  $m$ th order Markov and  $\{X_t: t = \dots, 0, 1, \dots\}$  is weakly exogeneous.

(b)  $g(W_t, \theta, \pi)$  does not depend on  $\pi$  for  $\theta$  in the null hypothesis.

(c) The true parameter  $\theta_0$  is in the interior of  $\Theta$ .

(d)  $g(W_t, \theta, \pi)$  is twice continuously partially differentiable in  $\theta$  for all  $\theta \in \Theta_0$  and  $\pi \in \Pi$  with probability 1 under  $\theta_0$ , where  $\Theta_0$  is some neighborhood of  $\theta_0$ .

(e)  $E \sup_{\theta \in \Theta, \pi \in \Pi} |\log g(W_t, \theta, \pi)| < \infty$ ,  $E \sup_{\pi \in \Pi} \|(\partial/\partial\theta)\log g(W_t, \theta_0, \pi)\|^r < \infty$ , for  $r$  as in part (a), and  $E \sup_{\theta \in \Theta_0, \pi \in \Pi} \|(\partial^2/\partial\theta\partial\theta')\log g(W_t, \theta, \pi)\| < \infty$ . (If  $\{(Y_t, X_t): t = \dots, 0, 1, \dots\}$  is a sequence of independent or  $m$ -dependent random variables for some  $m < \infty$ , then  $r$  can be taken to equal 2 here and in Assumption EP4 below. If  $\{(Y_t, X_t): t = \dots, 0, 1, \dots\}$  has geometrically declining  $\beta$ -mixing numbers [i.e.,  $\beta(s) = O(\rho^s)$  for some  $0 < \rho < 1$ ], then  $E \sup_{\pi \in \Pi} \|(\partial/\partial\theta)\log g(W_t, \theta_0, \pi)\|^r < \infty$  can be replaced by

$$E \sup_{\pi \in \Pi} \left\| \frac{\partial}{\partial\theta} \log g(W_t, \theta, \pi) \right\|^2 \log^+ \left( \left\| \frac{\partial}{\partial\theta} \log g(W_t, \theta_0, \pi) \right\| \right) < \infty$$

and  $r$  can be taken to be any number greater than 2 in Assumption EP4 below.)

(f)  $I(\theta, \pi)$  is continuous in  $(\theta, \pi)$  on  $\Theta_0 \times \Pi$ .

(g)  $I(\theta_0, \pi)$  is positive definite for all  $\pi \in \Pi$ .

ASSUMPTION EP2. (a)  $\Theta$  is compact.

(b)  $\log g(W_t, \theta, \pi)$  is  $L^1$ -continuous in  $(\theta, \pi)$  on  $\Theta \times \Pi$  under  $\theta_0$ .

(c)  $(\partial^2/\partial\theta\partial\theta')\log g(W_t, \theta, \pi)$  is  $L^1$ -continuous in  $(\theta, \pi)$  on  $\Theta_0 \times \Pi$  under  $\theta_0$ .

ASSUMPTION EP3.  $g(W_t, \theta, \pi) \neq g(W_t, \theta_0, \pi)$  with positive probability under  $\theta_0 \forall \theta \in \Theta$  with  $\theta \neq \theta_0$  and  $\forall \pi \in \Pi$ .

ASSUMPTION EP4. (a)  $\Pi$  is compact.

(b)  $(\partial/\partial\theta)\log g(W_t, \theta_0, \pi)$  is  $L^r$ -continuous in  $\pi$  on  $\Pi$  with modulus of continuity  $C\delta^\psi$  for some positive constants  $C$  and  $\psi$ , where  $r$  is as in Assumption EP1(a) and (e).

We note that Assumptions EP1–EP4 are satisfied in Examples 1–4 above. Assumption EP3 can be verified in the examples by showing that  $E(\log g(W_t, \theta_0, \pi) - \log g(W_t, \theta, \pi)) > 0 \forall \theta \in \Theta$  with  $\theta \neq \theta_0 \forall \pi \in \Pi$ . In Example 1, the assumption that  $Z_t$  has a bounded Lebesgue density is used to verify Assumption EP4 with  $\psi = 1$ . In Example 3, the assumptions that  $h(Z_t, \pi)$  is differentiable in  $\pi$  and its derivative satisfies a moment condition are used to verify Assumption EP4 with  $\psi = 1$ .

The result referred to above is summarized as follows:

THEOREM 2. Assumptions EP1–EP4 imply Assumptions 1–5.

Note that under assumptions EP1–EP4, Assumption 5 holds with the Gaussian process  $G(\theta_0, \cdot)$  having covariance function given by  $EG(\theta_0, \pi_1)G(\theta_0, \pi_2)' = E(\partial/\partial\theta)\log g(W_t, \theta_0, \pi_1)(\partial/\partial\theta')\log g(W_t, \theta_0, \pi_2)$  for  $\pi_1, \pi_2 \in \Pi$ . Continuity (in  $\pi$ ) of the sample path of  $G(\theta_0, \pi)$  is with respect to the  $L^r$ -pseudometric, where  $r$  is as in Assumptions EP1(a), EP1(e) and EP4.

3.2. *Changepoint example.* Sufficient conditions for Assumptions 1–3 and 5 for changepoint tests in stationary dynamic nonlinear models are given in AP (Assumption SC). These assumptions are quite similar to standard assumptions in the literature for the consistency and asymptotic normality of ML estimators in stationary contexts. For brevity, these conditions are not restated here.

**4. Finite sample admissibility.** In this section we show that the LR test is finite sample admissible for a class of testing problems that arise in a Gaussian linear model.

ASSUMPTION 8. The model is given by

$$Y_t = X_t(\pi)' \beta + Z_t' \delta + U_t \quad \text{for } t = 1, \dots, T,$$

where  $U_t \sim \text{iid } N(0, \sigma^2)$ ,  $\sigma^2$  is known,  $X_t(\pi) \in R^p$ ,  $\beta \in R^p$ ,  $Z_t \in R^q$ ,  $\delta \in R^q$ ,  $\{(X_t(\pi), Z_t): t = 1, \dots, T\}$  are nonrandom,  $\pi \in \Pi$ ,  $\sum_{t=1}^T \begin{pmatrix} X_t(\pi) \\ Z_t \end{pmatrix} \begin{pmatrix} X_t(\pi) \\ Z_t \end{pmatrix}'$  is nonsingular for all  $\pi \in \Pi$  and  $X_t(\pi)$  is continuous on  $\Pi$  for all  $t = 1, \dots, T$ .

Below, the parameter space  $\Pi$  is assumed to satisfy Assumption 4 and the weight functions  $J(\cdot)$  and  $Q_{r, \pi}(\cdot)$  are assumed to satisfy Assumptions 6 and 7, respectively, with  $\mathbf{I}_\pi$  equal to

$$\sum_{t=1}^T \begin{pmatrix} X_t(\pi) \\ Z_t \end{pmatrix} \begin{pmatrix} X_t(\pi) \\ Z_t \end{pmatrix}'$$

in Assumption 7.

The hypotheses of interest are the same as in Section 2 and are specified by (2.1) and (2.2). By varying the definition of  $X_t(\pi)$ , we obtain hypotheses of different types. For example, if

$$(4.1) \quad \begin{aligned} X_t(\pi) &= X_t 1(t \leq T\pi), \\ Z_t &= \begin{pmatrix} X_t \\ X_t^* \end{pmatrix} \quad \text{and} \quad \Pi \subset \{1/T, 2/T, \dots, (T-1)/T\}, \end{aligned}$$

then a test of  $H_0: \beta = 0$  is a test for a single changepoint in a subvector of the regressor vector. This example can be extended straightforwardly to allow for arbitrarily many changepoints.

Another example is a test of relevance of Box–Cox transformed regressors. In this case,

$$(4.2) \quad X_t(\pi) = ((X_{1t}^\pi - 1)/\pi, \dots, (X_{pt}^\pi - 1)/\pi)' \quad \text{and} \quad \Pi \subset [0, \infty).$$

Under the null  $H_0: \beta = 0$ , the Box–Cox transformed regressors do not belong in the regression model. This example can be extended to allow the Box–Cox parameter to differ across regressors.

A third example is a test of cross-sectional constancy. In this case,

$$(4.3) \quad X_t(\pi) = X_t 1(X_{1t} \leq \pi), \quad Z_t = \begin{pmatrix} X_t \\ X_t^* \end{pmatrix} \quad \text{and} \quad \Pi \subset R,$$

where  $X_{1t}$  is an element of the regressor  $X_t$ . In this example, one is testing

for constancy of the parameters across two (unknown) regions. Multiple regions could be considered.

For known  $\pi$ , the standard LR, Wald and LM test statistics for testing  $H_0$  against  $H_1$  are given by (2.7) with  $B_T = I_s$ ,  $\hat{\theta}(\pi)$  equal to the unrestricted least square (LS) estimator of  $\theta = (\beta', \delta')$ ,

$$\mathbf{I}_T(\theta, \pi) = \frac{1}{\sigma^2} \sum_{t=1}^T \begin{pmatrix} X_t(\pi) \\ Z_t \end{pmatrix} \begin{pmatrix} X_t(\pi) \\ Z_t \end{pmatrix}' \quad \forall \theta \in \Theta = R^{p+q},$$

$\tilde{\theta}$  equal to the restricted LS estimator of  $\theta$  and  $l_T(\theta, \pi)$  and  $Dl_T(\theta, \pi)$  equal to the Gaussian regression log-likelihood and its vector of derivatives with respect to  $\theta$ , respectively. As is well known,  $LR_T(\pi)$ ,  $W_T(\pi)$  and  $LM_T(\pi)$  are monotone transformations of each other. In consequence, the test statistics  $\sup_{\pi \in \Pi} W_T(\pi)$ ,  $\sup_{\pi \in \Pi} LM_T(\pi)$  and  $\sup_{\pi \in \Pi} LR_T(\pi)$  yield equivalent tests.

We say that a test  $\varphi_T$  is *distinct* from the significance level  $\alpha$  LR test  $\xi_T = 1(\sup_{\pi \in \Pi} W_T(\pi) > k_\alpha)$ , where  $k_\alpha$  is a positive constant, if

$$(4.4) \quad \delta = \int (1 - \varphi_T) \xi_T f_T(\theta_0) d\mu_T > 0,$$

where  $f_T(\theta_0)$  is the null Gaussian density and  $\mu_T$  is Lebesgue measure on  $R^T$ . That is,  $\varphi_T$  is distinct from  $\xi_T$  if there is positive probability under  $H_0$  that  $\varphi_T$  accepts when  $\xi_T$  rejects.

Minor alterations of the proof of asymptotic admissibility of the LR test in Theorem 1 yield finite sample admissibility of the LR test for the Gaussian linear regression model.

**THEOREM 3.** *Suppose Assumptions 4 and 6–8 hold with  $\mathbf{I}_\pi = (1/\sigma^2)\sum_{t=1}^T(X_t(\pi), Z_t)(X_t(\pi), Z_t)'$  in Assumption 7. Let  $\varphi_T$  be a test that is distinct from the level  $\alpha$  LR test  $\xi_T$ . Then there exists an  $r_0 < \infty$  such that, for all  $r \geq r_0$ ,*

$$\int \left[ \int \varphi_T f_T(\theta_0 + h, \pi) d\mu_T \right] dQ_{r, \pi}(h) dJ(\pi) < \int \left[ \int \xi_T f_T(\theta_0 + h, \pi) d\mu_T \right] dQ_{r, \pi}(h) dJ(\pi).$$

**REMARKS.**

1. Remarks 1–3 following Theorem 1 all apply to Theorem 3 (with the references to asymptotics deleted).
2. See Andrews, Lee and Ploberger (1996) for an alternative set of finite sample optimality properties for some changepoint tests.

**5. Proofs.** First we prove Theorem 1. Let  $F_T(\pi)$  denote  $LR_T(\pi)$ ,  $W_T(\pi)$  or  $LM_T(\pi)$ . For notational simplicity, let sup denote “ $\sup_{\pi \in \Pi}$ .” For  $r \geq 0$ , let  $P_r$  and  $E_r$  denote probabilities and expectations with respect to the density  $\int f_T(\theta_0 + B_T^{-1}h, \pi) dQ_{r, \pi}(h) dJ(\pi)$ . The case  $r = 0$  corresponds to the null density  $f_T(\theta_0)$ . The likelihood ratio of  $P_r$  to  $P_0$  is denoted

$$(5.1) \quad LR_{T,r} = \int f_T(\theta_0 + B_T^{-1}h, \pi) dQ_{r, \pi}(h) dJ(\pi) / f_T(\theta_0).$$

For  $\lambda \geq 0$  and arbitrary  $\mu \in R^p$  with  $\|\mu\| = 1$ , let

$$(5.2) \quad \psi_p(\lambda) = \int \exp(\lambda x' \mu) dU_p(x),$$

where  $U_p(\cdot)$  denotes the uniform distribution on the unit sphere in  $R^p$ .

Define  $\bar{\theta}(\pi)$  and an approximate Wald statistic  $\bar{W}_T(\pi)$  by

$$(5.3) \quad \begin{aligned} \bar{\theta}(\pi) &= \mathbf{I}^{-1}(\theta_0, \pi) B_T^{-1} D l_T(\theta_0, \pi), \\ \bar{W}_T(\pi) &= (H \bar{\theta}(\pi))' [H \mathbf{I}^{-1}(\theta_0, \pi) H']^{-1} H \bar{\theta}(\pi). \end{aligned}$$

The proof of Theorem 1 uses the following lemmas.

LEMMA 1. *Under Assumptions 1, 2, 5 and 7,*

$$\exp(-r^2/2) \int \psi_p(r \bar{W}_T^{1/2}(\pi)) dJ(\pi) / LR_{T,r} \rightarrow_p 1$$

under  $P_0$ .

LEMMA 2. *For some constants  $C_1, C_2$  and  $C_3$  in  $(0, \infty)$ :*

- (a)  $\psi_p(\lambda) \leq C_1 + C_2 \exp(\lambda) \forall \lambda \geq 0$ .
- (b)  $\psi_p(\lambda) \geq C_3 \exp(\lambda) \lambda^{-(p-1)/2} \forall \lambda \geq 1$ .

LEMMA 3. *Under Assumptions 1-5,  $\sup |\bar{W}_T(\pi) - F_T(\pi)| \rightarrow_p 0$  and  $\sup F_T(\pi) \rightarrow_d \sup F(\pi) = \sup (HG(\theta_0, \pi))' [H \mathbf{I}^{-1}(\theta_0, \pi) H']^{-1} HG(\theta_0, \pi)$  under  $P_0$  and  $\sup F(\pi)$  has absolutely continuous distribution.*

LEMMA 4. *Under Assumptions 1, 2, 5 and 7,  $\{P_r: T \geq 1\}$  are contiguous to  $P_0$  for all  $r > 0$ .*

PROOF OF THEOREM 1. For simplicity we consider the case where  $k_{T\alpha}$  equals a constant  $k_\alpha \forall T \geq 1$ . For the case of random  $k_{T\alpha}$ , we must have  $k_{T\alpha} \rightarrow_p k_\alpha$  for some constant  $k_\alpha$  by Lemma 3 and the corresponding adjustments to the proof are minor.

To prove Theorem 1, it suffices to show that

$$(5.4) \quad \liminf_{T \rightarrow \infty} E_r(1 - \varphi_T) / \limsup_{T \rightarrow \infty} P_r(\sup F_T(\pi) \leq k_\alpha) \rightarrow \infty \text{ as } r \rightarrow \infty.$$

Below we show that

$$(5.5) \quad \begin{aligned} \limsup_{T \rightarrow \infty} P_r(\sup F_T(\pi) \leq k_\alpha) \\ \leq 2 \exp(-r^2/2) [C_1 + C_2 \exp(rk_\alpha^{1/2})] \quad \forall r > 0. \end{aligned}$$

We also show that, for some  $\gamma > 0$  and  $0 < C_4 < \infty$ ,

$$(5.6) \quad \begin{aligned} \liminf_{T \rightarrow \infty} E_r(1 - \varphi_T) \\ \geq C_4 \exp(-r^2/2) \exp(r(k_\alpha + \gamma)^{1/2}) [r(k_\alpha + \gamma)^{1/2}]^{-(p-1)/2} \end{aligned}$$

for  $r$  sufficiently large. Equation (5.4) follows immediately from (5.5) and (5.6).

We now establish (5.5). Define the event  $D_{T,r}^*$  by

$$(5.7) \quad D_{T,r}^* = \left\{ \exp(-r^2/2) \int \psi_p(r\bar{W}_T^{1/2}(\pi)) dJ(\pi) / LR_{T,r} \in [1/2, 2] \right\}.$$

By Lemmas 1 and 4,  $\lim_{T \rightarrow \infty} P_r(D_{T,r}^*) = 1 \forall r \geq 0$ . In addition,  $\sup F_T(\pi) - \sup \bar{W}_T(\pi) \rightarrow_p 0$  under  $P_r$  by Lemmas 3 and 4.

Using these results, we obtain,  $\forall r > 0$ ,

$$(5.8) \quad \begin{aligned} & \limsup_{T \rightarrow \infty} P_r(\sup F_T(\pi) \leq k_\alpha) \\ &= \limsup_{T \rightarrow \infty} P_r(\sup \bar{W}_T(\pi) \leq k_\alpha, D_{T,r}^*) \\ &= \limsup_{T \rightarrow \infty} E_0 LR_{T,r} \cdot 1(\sup \bar{W}_T(\pi) \leq k_\alpha, D_{T,r}^*) \\ &\leq 2 \exp(-r^2/2) \\ &\quad \times \limsup_{T \rightarrow \infty} E_0 \int \psi_p(r\bar{W}_T^{1/2}(\pi)) dJ(\pi) \cdot 1(\sup \bar{W}_T(\pi) \leq k_\alpha) \\ &\leq 2 \exp(-r^2/2) \limsup_{T \rightarrow \infty} E_0 \int [C_1 + C_2 \exp(r\bar{W}_T^{1/2}(\pi))] dJ(\pi) \\ &\quad \times 1(\sup \bar{W}_T(\pi) \leq k_\alpha) \\ &\leq 2 \exp(-r^2/2) [C_1 + C_2 \exp(rk_\alpha^{1/2})], \end{aligned}$$

where the second inequality uses Lemma 2. Note that the first equality of (5.8) actually relies on the results above plus the convergence in distribution, absolute continuity and contiguity results of Lemmas 3 and 4.

Next, we establish (5.6). The fact that  $\varphi_T$  and  $\xi_T$  are asymptotically distinct implies that  $\exists \gamma > 0$  such that

$$(5.9) \quad \liminf_{T \rightarrow \infty} E_0(1 - \varphi_T)1(\sup F_T(\pi) > k_\alpha + 2\gamma) \geq \delta/2,$$

where  $\delta$  is as in the definition of asymptotically distinct. This follows because

$$(5.10) \quad \begin{aligned} & \limsup_{T \rightarrow \infty} P_0(\sup F_T(\pi) \in (k_\alpha, k_\alpha + 2\gamma]) \\ &= P_0(\sup F(\pi) \in (k_\alpha, k_\alpha + 2\gamma]) \leq \delta/2, \end{aligned}$$

where the inequality holds for some small  $\gamma > 0$  by Lemma 3.

Let  $K$  be a compact subset (under the metric  $d$ ) of the space of continuous  $R^s$ -valued functions on  $\Pi$ . For  $\delta$  as above,  $K$  can be chosen such that

$$(5.11) \quad P_0(\mathbf{I}^{-1}(\theta_0, \cdot)G(\theta_0, \cdot) \in K) \geq 1 - \delta/4$$

using Assumptions 1 and 5. For  $\varepsilon > 0$ , Let  $K(\varepsilon) = \{g \in \mathbf{E}: \sup_{\pi \in \Pi} \|g(\pi) - l(\pi)\| < \varepsilon \text{ for some } l \in K\}$ . Note that  $K(\varepsilon)$  is a neighborhood of  $K$  in  $(\mathbf{E}, d)$  by the condition (2.6) on the metric  $d$ . By Assumption 5,  $\bar{\theta}(\cdot) \Rightarrow \mathbf{I}^{-1}(\theta_0, \cdot)G(\theta_0, \cdot)$ .

In consequence,

$$(5.12) \quad \liminf_{T \rightarrow \infty} P_0(\bar{\theta}(\cdot) \in K(\varepsilon)) \geq 1 - \delta/4 \quad \forall \varepsilon > 0.$$

Under the assumptions, given  $\gamma > 0$ ,  $\exists \varepsilon_1 > 0$  and  $\xi > 0$  such that

$$(5.13) \quad \sup_{\rho(\pi, \pi') < \xi} |\bar{W}_T(\pi) - \bar{W}_T(\pi')| < \gamma \quad \forall \bar{\theta} \in K(\varepsilon_1).$$

For  $\varepsilon_1$  as in (5.13), define the event  $D_{T,r}$  by

$$(5.14) \quad D_{T,r} = \{1 - \varphi_T > \delta/8, \sup \bar{W}_T(\pi) > k_\alpha + 2\gamma, \bar{\theta} \in K(\varepsilon_1), D_{T,r}^*\}.$$

Let  $\hat{\pi}$  be a random element of  $\Pi$  that satisfies  $\sup_{\pi \in S(\hat{\pi}, \xi)} \bar{W}_T(\pi) = \sup_{\pi \in \Pi} \bar{W}_T(\pi)$ .

Using Lemma 1, we now have

$$(5.15) \quad \begin{aligned} E_r(1 - \varphi_T) &\geq \frac{\delta}{8} P_r\left(1 - \varphi_T > \frac{\delta}{8}\right) \\ &\geq \frac{\delta}{8} P_r(D_{T,r}) = \frac{\delta}{8} E_0 \text{LR}_{T,r} \cdot 1(D_{T,r}) \\ &\geq \frac{\delta}{16} \exp\left(\frac{-r^2}{2}\right) E_0 1(D_{T,r}) \int \psi_p(r\bar{W}_T^{1/2}(\pi)) dJ(\pi) \\ &\geq \frac{\delta}{16} \exp\left(\frac{-r^2}{2}\right) E_0 1(D_{T,r}) \int 1(\pi \in S(\hat{\pi}, \xi)) \psi_p(r\bar{W}_T^{1/2}(\pi)) dJ(\pi) \\ &\geq \frac{\delta}{16} \exp\left(\frac{-r^2}{2}\right) E_0 1(D_{T,r}) \inf_{\pi \in S(\hat{\pi}, \xi)} \psi_p(r\bar{W}_T^{1/2}(\pi)) \inf_{\pi \in \Pi} J(S(\pi, \xi)). \end{aligned}$$

Note that  $D_{T,r}$  has been defined such that, for  $\omega \in D_{T,r}$  and  $\pi \in S(\hat{\pi}, \xi)$ , we have

$$(5.16) \quad r\bar{W}_T^{1/2}(\pi)_\omega \geq r\left(\sup_{\pi \in \Pi} \bar{W}_T(\pi)_\omega - \gamma\right)^{1/2} \geq r(k_\alpha + \gamma)^{1/2}.$$

Let  $b = \inf_{\pi \in \Pi} J(S(\pi, \xi))$ . By Assumption 6,  $b > 0$ .

For  $r$  such that  $r(k_\alpha + \gamma)^{1/2} > 1$ , Lemma 2, (5.15) and (5.16) combine to yield

$$(5.17) \quad \begin{aligned} E_r(1 - \varphi_T) &\geq \frac{b\delta}{16} \exp\left(\frac{-r^2}{2}\right) E_0 1(D_{T,r}) \\ &\quad \times \inf_{\pi \in S(\hat{\pi}, \xi)} \left[ C_3 \exp(r\bar{W}_T^{1/2}(\pi)) (r\bar{W}_T^{1/2}(\pi))^{-(p-1)/2} \right] \\ &\geq C_3 \frac{b\delta}{16} \exp\left(\frac{-r^2}{2}\right) P_0(D_{T,r}) \\ &\quad \times \exp(r(k_\alpha + \gamma)^{1/2}) [r(k_\alpha + \gamma)^{1/2}]^{-(p-1)/2}. \end{aligned}$$



The desired result follows if  $\liminf_{T \rightarrow \infty} P_0(D_{T,r}) \geq \delta/8 \forall r \geq 0$ . Inequalities (5.9) and (5.12) yield

$$(5.18) \quad \begin{aligned} & \liminf_{T \rightarrow \infty} E_0(1 - \varphi_T) \mathbf{1}(\sup F_T(\pi) > k_\alpha + 2\gamma, \bar{\theta} \in K(\varepsilon_1)) \\ & \geq \frac{\delta}{2} - \limsup_{T \rightarrow \infty} P_0(\bar{\theta} \notin K(\varepsilon_1)) \geq \frac{\delta}{4}. \end{aligned}$$

This result, Lemma 1, and Lemma 3 give

$$(5.19) \quad \begin{aligned} \delta/4 & \leq \liminf_{T \rightarrow \infty} E_0(1 - \varphi_T) \mathbf{1}(\sup \bar{W}_T(\pi) > k_\alpha + 2\gamma, \bar{\theta} \in K(\varepsilon_1)) \\ & \leq \liminf_{T \rightarrow \infty} P_0(1 - \varphi_T > \delta/8, \sup \bar{W}_T(\pi) > k_\alpha + 2\gamma, \bar{\theta} \in K(\varepsilon_1)) \\ & \quad + \limsup_{T \rightarrow \infty} E_0(1 - \varphi_T) \mathbf{1}(1 - \varphi_T \leq \delta/8) \\ & \leq \liminf_{T \rightarrow \infty} P_0(D_{T,r}) + \delta/8. \end{aligned} \quad \square$$

PROOF OF LEMMA 1. Let  $G_T = B_T^{-1} D l_T(\theta_0, \pi)$ ,  $\mathbf{I}_T = \mathbf{I}_T(\theta_0, \pi)$  and  $\mathbf{I} = \mathbf{I}(\theta_0, \pi)$ . Define

$$(5.20) \quad \omega_T(r) = \sup_{\substack{\pi \in \Pi, h: h' \mathbf{I} h \leq r^2, \\ 0 < \lambda < 1}} \|\mathbf{I}_T(\theta_0 + \lambda B_T^{-1} h, \pi) - \mathbf{I}_T(\theta_0, \pi)\|.$$

Then, for  $h$  such that  $h' \mathbf{I} h \leq r^2$ , a two-term Taylor expansion yields

$$(5.21) \quad \begin{aligned} & l_T(\theta_0 + B_T^{-1} h, \pi) - l_T(\theta_0) = h' G_T - h' \mathbf{I}_T h / 2 + R_T, \\ & \text{where } |R_T| \leq \omega_T(r) \|h\|^2 \\ & \leq \omega_T(r) r^2 / \inf_{\pi \in \Pi} \lambda_{\min}(\mathbf{I}(\theta_0, \pi)) = C_r \omega_T(r) \end{aligned}$$

for some constant  $C_r < \infty$ .

By Assumption 1(d) and (e),  $\omega_T(r) \rightarrow_p 0 \forall r > 0$  [by adding in and subtracting out both  $\mathbf{I}(\theta_0 + \lambda B_T^{-1} h, \pi)$  and  $\mathbf{I}(\theta_0, \pi)$  and then applying the triangle inequality]. Hence,  $\forall \pi \in \Pi$  and  $\forall h$  with  $h' \mathbf{I} h \leq r^2$ , we have

$$(5.22) \quad \begin{aligned} K_{1T} & = \exp(-C_r \omega_T(r)) \\ & \leq \exp(h' G_T - h' \mathbf{I}_T h / 2) / [f_T(\theta_0 + B_T^{-1} h, \pi) / f_T(\theta_0)] \\ & \leq \exp(C_r \omega_T(r)) = K_{2T}, \end{aligned}$$

where  $K_{1T} \rightarrow_p 1$  and  $K_{2T} \rightarrow_p 1$ . In turn, this yields

$$(5.23) \quad K_{1T} \leq \int \exp(h' G_T - h' \mathbf{I}_T h / 2) dQ_{r,\pi}(h) dJ(\pi) / LR_{T,r} \leq K_{2T}.$$

By Assumption 1(d),  $\exp(h'\mathbf{I}_T h/2)\exp(-h'\mathbf{I}h/2) \rightarrow_p 1$  uniformly over  $h$  with  $h'\mathbf{I}h \leq r^2$  and over  $\pi \in \Pi$ . In consequence, there exist sequences of constants  $K_{3Tr}$  and  $K_{4Tr}$  such that  $K_{3Tr} \rightarrow_p 1$ ,  $K_{4Tr} \rightarrow_p 1$  and

$$(5.24) \quad K_{3Tr} \leq \int \exp(h'G_T - h'\mathbf{I}h/2) dQ_{r,\pi}(h) dJ(\pi) / LR_{T,r} \leq K_{4Tr}.$$

For  $h$  in the support of  $Q_{r,\pi}$ , we have  $h'\mathbf{I}h = r^2$  and  $h = A_\pi \lambda$  for some  $\lambda \in R^p$ . For such  $h$ ,  $h'\mathbf{I}(I_s - A_\pi H) = 0$ , since straightforward algebra shows that  $A'_\pi \mathbf{I}(I_s - A_\pi H) = 0$ . Thus,

$$\begin{aligned} & \int \exp(h'G_T - h'\mathbf{I}h/2) dQ_{r,\pi}(h) dJ(\pi) \\ &= \exp(-r^2/2) \int \exp(h'\mathbf{I}A_\pi H\bar{\theta}(\pi) \\ & \quad + h'\mathbf{I}(I_s - A_\pi H)\bar{\theta}(\pi)) dQ_{r,\pi}(h) dJ(\pi) \\ (5.25) \quad &= \exp(-r^2/2) \int \exp(h'\mathbf{I}A_\pi H\bar{\theta}(\pi)) dQ_{r,\pi}(h) dJ(\pi) \\ &= \exp(-r^2/2) \int \exp(rx'(A'_\pi \mathbf{I}A_\pi)^{1/2} H\bar{\theta}(\pi)) dU_p(x) dJ(\pi) \\ &= \exp(-r^2/2) \int \exp(r\bar{W}_T^{1/2}(\pi) x'\mu) dU_p(x) dJ(\pi) \\ &= \exp(-r^2/2) \int \psi_p(r\bar{W}_T^{1/2}(\pi)) dJ(\pi), \end{aligned}$$

where the third equality uses Assumption 7,

$$\mu = (A'_\pi \mathbf{I}A_\pi)^{1/2} H\bar{\theta}(\pi) / \|(A'_\pi \mathbf{I}A_\pi)^{1/2} H\bar{\theta}(\pi)\|$$

and

$$\bar{W}_T(\pi) = \|(A'_\pi \mathbf{I}A_\pi)^{1/2} H\bar{\theta}(\pi)\|^2$$

since  $A'_\pi \mathbf{I}A_\pi = (H\mathbf{I}^{-1}H')^{-1}$  by straightforward algebra.

Equations (5.24) and (5.25) combine to give the desired result.  $\square$

**PROOF OF LEMMA 2.** This lemma follows straightforwardly from results in the literature. For example, it follows from (15.3.7), (15.3.9), and the last equation on page 431 of Mardia, Kent and Bibby (1979). Note that their equation (15.3.7) contains a typo. The expression  $(p - 1)/2$  should be  $(p/2) - 1$  in the two places it appears.  $\square$

PROOF OF LEMMA 3. Under Assumptions 1, 2, 4 and 5,

$$(5.26) \quad \sup\|\bar{W}_T(\pi) - F_T(\pi)\| \rightarrow_p 0 \quad \text{under } P_0$$

by the proof of Theorem A-1 parts (c)–(e) of AP. By Assumptions 1, 4 and 5, the continuous mapping theorem [e.g., see Pollard (1984), page 70], (2.5) and (5.26), the second result of the lemma holds. Absolute continuity of  $\sup F(\pi)$  follows from a result of Lifshits (1982).  $\square$

PROOF OF LEMMA 4. We make use of the following result, which follows, for example, from Theorems 16.8 and 18.11 of Strasser (1985): If (i)  $LR_{T,r} \rightarrow_d X_r^*$  under  $P_0$  and (ii)  $E_0 X_r^* = 1$ , then  $\{P_r: T \geq 1\}$  are contiguous to  $P_0$ . Condition (i) holds with  $X_r^* = \exp(-r^2/2) \int \psi_p(rF^{1/2}(\pi)) dJ(\pi)$ , where  $F(\pi)$  is as in Lemma 3, by Lemma 1, Assumptions 1 and 5 and the continuous mapping theorem.

Condition (ii) is obtained as follows. Let  $Z(\pi) \sim N(0, I_p)$ . Then  $F(\pi)$  and  $Z(\pi)'Z(\pi)$  have the same distribution by Assumption 5. We now obtain

$$\begin{aligned} E_0 X_r^* &= \exp(-r^2/2) E_0 \int \left[ \int \exp(rF^{1/2}(\pi) x' \mu) dU_p(x) \right] dJ(\pi) \\ (5.27) \quad &= \exp(-r^2/2) \int \left[ \int E_0 \exp(rx'Z(\pi)) dU_p(x) \right] dJ(\pi) \\ &= \exp(-r^2/2) \int \left[ \int \exp(r^2 x' x) dU_p(x) \right] dJ(\pi) = 1, \end{aligned}$$

where the second equality holds by taking the arbitrary unit vector  $\mu$  to be  $Z(\pi)/\|Z(\pi)\|$  and applying Fubini's theorem and the third equality uses the standard formula for the moment generating function of a standard normal random vector.  $\square$

PROOF OF THEOREM 2. Assumptions 1(a), (b), (c), (e) and (f) follow immediately from EP1(b), (c), (d), (f) and (g), respectively; 1(d) follows with  $B_T = \sqrt{T}I_s$  from EP1(a), EP1(e), EP2(a), EP2(c) and EP4(a) using the uniform weak law of large numbers (WLLN) given in the theorem in Andrews (1987). In particular, pointwise WLLN's hold for the infs and sups of  $g(W_t, \theta, \pi)$  over small balls in  $\Theta_0 \times \Pi$  by the ergodic theorem, because such random variables are strictly stationary and absolutely regular and, hence, ergodic.

Assumptions 2 and 3 can be verified using Lemma A-1 of Andrews (1993). We verify its conditions (a) and (b) for  $Q_T(\theta, \pi) = -(1/T)\sum_1^T \log g(W_t, \theta, \pi)$  and  $Q(\theta, \pi) = -E \log g(W_t, \theta, \pi)$ . For Assumption 2, the parameter space for  $\theta$  is  $\Theta$ ; for 3, the parameter space for  $\theta$  is  $\hat{\Theta} = \Theta \cap V$ , the null hypothesis

parameter space. Condition (a) of Lemma A-1 requires that  $Q_T(\theta, \pi)$  satisfies a uniform WLLN over  $\Theta \times \Pi$ . This follows by the same uniform WLLN as used above by EP1(a), EP1(e), EP2(a), EP2(b) and EP4(a). Condition (b) of Lemma A-1 holds for Assumptions 2 (with parameter space  $\Theta$ ) and 3 (with parameter space  $\Theta$ ) by EP2(a), EP3 and EP4(a).

Assumption 5 holds with  $B_T = \sqrt{T}I_s$  by Theorem 1 of Doukhan, Massart and Rio (1995) using EP1(a), EP1(e) and EP4. More specifically, the key condition (2.10) of Theorem 1 of Doukhan, Massart and Rio is implied by their equation (S.1) and (2.11) by their Lemma 2. Equations (S.1) and (2.11) hold with  $\phi(x) = x^{r/2}$  by EP1(a) and EP4, respectively, since  $\|\cdot\|_{\phi,2}$  equals the  $L^r$ -norm  $\|\cdot\|_r$  in this case, using Theorem 5 of Andrews (1994). The latter follows because  $\mathbf{M}$  is a type IV class of functions, as defined in Andrews (1994), and by Theorem 5 satisfies Ossiander's  $L^r$  entropy condition, which is equivalent to equation (2.11) of Doukhan, Massart and Rio.  $\square$

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