

4. Sampling from $F(x) = \int_0^x H e^{-Ht} dt$, ($0 \leq x < \infty$; $H > 0$). If $F(x) = \int_0^x H e^{-Ht} dt$, the probability function of S can be determined but is very cumbersome in the form in which it is known to the writer. The characteristic function, say $g(\theta)$, of the probability function of S will be given instead. By use of (2.1) it can be shown that:

$$(4.1) \quad g(\theta) = e^{iD\theta} \prod_{\lambda=1}^{n-1} \left\{ \frac{i\theta e^{D(i\theta - \lambda H)} - \lambda H}{i\theta - \lambda H} \right\},$$

where $i = \sqrt{-1}$.

The expected value, $E(S)$, and variance, σ_s^2 , of S are:

$$(4.2) \quad E(S) = D + \frac{1}{H} \sum_{\lambda=1}^{n-1} \frac{(1 - e^{-DH\lambda})}{\lambda},$$

$$\sigma_s^2 = \frac{1}{H^2} \sum_{\lambda=1}^{n-1} \frac{(1 - e^{-2DH\lambda})}{\lambda^2} - \frac{2D}{H} \sum_{\lambda=1}^{n-1} \frac{e^{-DH\lambda}}{\lambda}.$$

REFERENCES

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 [2] PHILIP HALL, "The distribution of means for samples of size n drawn from a population in which the variate takes values between 0 and 1, all such values being equally probable," *Biometrika*, Vol. 19 (1927), pp. 240-245.
 [3] H. E. ROBBINS, "On the measure of a random set," *Annals of Math. Stat.*, Vol. 15 (1944), p. 72.

INFORMATION GIVEN BY ODD MOMENTS

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The widespread use of the third moment about the mean as a measure of skewness and the belief engendered by this use that a distribution is symmetric if its third moment is zero prompt the question of how much information about a distribution can be deduced from a knowledge of its odd moments. An answer to this question is: Let $F(x)$, a cumulative distribution function; $\{\mu_{2n-1}\}$, ($n = 1, 2, \dots$), a sequence of real numbers; and $\epsilon > 0$ be arbitrary. There exists a c.d.f., $F^*(x)$, having as odd moments the terms of the given sequence and such that

$$(1) \quad |F(x) - F^*(x)| \leq \epsilon, \text{ all } x.$$

If the mean of $F(x)$ is equal to μ_1 and the variance of $F(x)$ is not zero, it can be shown that $F^*(x)$ may be chosen so that in addition the variance of $F^*(x)$ is equal to that of $F(x)$.

An immediate consequence of our statement is that a distribution need not be



lute odd moments of all orders are uniformly bounded, a bound for the absolute moments of order $2k - 1$ being one greater than the absolute moment of this order of H_k . This in turn insures that the odd moments of $H^*(x)$ exist and that they have the desired values. By adding a jump of $1 - H^*(\infty)$ at the origin we obtain $H(x)$, a c.d.f. with the given odd moments.

The main statement of this note is an immediate consequence of the lemma. Let the k th odd moment of $F(x)$ be M_{2k-1} , which we assume to be finite, and let the sequence $\{m_{2k-1}\}$ be defined by the relationships:

$$\mu_{2k-1} = (1 - \epsilon)M_{2k-1} + \epsilon m_{2k-1}, \quad (k = 1, 2, \dots).$$

Let $H(x)$ have the m 's as odd moments. The c.d.f. $F^*(x)$ defined by

$$F^*(x) = (1 - \epsilon)F(x) + \epsilon H(x)$$

clearly has the properties stated above, and our statement is proved. If the moments of $F(x)$ are not all finite, the proof will need only minor modifications.

If one asks in addition that F^* have a finite range, F^* will, in general, not exist. If, for example, the range of F is finite and its odd moments are zero, then F must be symmetric about the origin, for F^* defined by $dF^*(x) = dF(-x)$ would have the same moments as F . But a c.d.f. with finite range is determined by its moments; hence $F(x) = F^*(x)$.

SOME ORDER STATISTIC DISTRIBUTIONS FOR SAMPLES OF SIZE FOUR

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1. Summary. Let x_1, x_2, x_3, x_4 represent the values of a sample of size four drawn from a normal population. There is no loss of generality in assuming that the distribution function of this population has zero mean and unit variance. Denote it by $N(0, 1)$. Let $x_{(i)}$ be the i th largest of x_1, x_2, x_3, x_4 . The purpose of this note is to determine the joint distribution of

$x_{(4)} + x_{(3)} - x_{(2)} - x_{(1)}$, $x_{(4)} - x_{(3)} + x_{(2)} - x_{(1)}$, and $x_{(4)} - x_{(3)} - x_{(2)} + x_{(1)}$, and derive from this joint distribution the joint distributions of these statistics taken in pairs, also the distribution of each statistic itself.

2. Analysis. Consider the joint distribution of

$$r_1 = \frac{1}{2}(x_4 + x_3 - x_2 - x_1)$$

$$r_2 = \frac{1}{2}(x_4 - x_3 + x_2 - x_1)$$

$$r_3 = \frac{1}{2}(x_4 - x_3 - x_2 + x_1).$$