

Central limit theorems for martingales-I: Continuous limits*

Bruno Rémillard[†]  Jean Vaillancourt[‡] 

Abstract

When the limiting compensator of a sequence of martingales is continuous, we obtain a weak convergence theorem for the martingales; the limiting process can be written as a Brownian motion evaluated at the compensator and we find sufficient conditions for both processes to be independent. As examples of applications, we revisit some known results for the occupation times of Brownian motion and symmetric random walks. In the latter case, our proof is much simpler than the construction of strong approximations. Furthermore, we extend finite dimensional convergence of statistical estimators of financial volatility measures to convergence as stochastic processes.

Keywords: Brownian motion; stochastic processes; weak convergence; martingales; mixtures.

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1 Introduction

Many central limit theorems involving a sequence of martingales are about weak convergence to a Brownian motion, and often they are obtained by requesting that the associated sequence of compensators converge in probability to a deterministic function. There are also some results where the sequence of compensators converge in probability to a stochastic process, and then the limit can be written as a mixture of a Brownian motion independent of the limiting compensator. Such results appear naturally for occupation times of symmetric random walks [9, 10] through complicated constructions of related strong approximations. Our goal here is to gather, under the umbrella of a single martingale central limit theorem (CLT), a number of weak convergence results for sequences of real-valued stochastic processes to mixtures of Brownian motions and independent increasing processes, without relying to special properties of the

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[†]HEC Montréal, Canada. E-mail: bruno.remillard@hec.ca

[‡]HEC Montréal, Canada. E-mail: jean.vaillancourt@hec.ca

processes, nor involving complicated constructions. In fact, under weak conditions involving sequence of martingale compensators, we will show that the CLTs holds for general martingales, and that the limiting process is a mixture of a Brownian motion with the limiting compensator of the sequence of martingales, and both processes are independent. These conditions are easy to verify and are general enough to be applicable to a wide range of situations.

The main results are stated in Section 2, while some examples involving either independent and identically distributed (iid) sequences or Markov processes, are found in Section 3. A longer application regarding volatility modeling in mathematical finance is in Section 4, extending previous results of [4, 5].

2 Main results

Let $D = D[0, \infty)$ be the Polish space of \mathbb{R}^d -valued càdlàg trajectories (right continuous with left limits everywhere), equipped with the Skorohod's \mathcal{J}_1 -topology on D — consult either Ethier and Kurtz [14] or Jacod and Shiryaev [19] for additional insight, as well as any unexplained terminology. All processes considered here have their trajectories in D and are adapted to a filtration $\mathbb{F} = (\mathcal{F}_t)_{t \geq 0}$ on a probability space (Ω, \mathcal{F}, P) satisfying the usual conditions (notably, right continuity of the filtration and completeness). Trajectories in D are usually noted $x(t)$ but occasionally x_t . Weak convergence of a sequence of D -valued processes X_n to another such process X , this last with continuous trajectories, will be denoted by $X_n \xrightarrow{\mathcal{C}} X$, while the weaker convergence of finite dimensional distributions will be denoted by $X_n \xrightarrow{f.d.d.} X$. In this paper the limit X always has continuous trajectories (even though the sequence of processes X_n may well not) so weak convergence in the \mathcal{J}_1 -topology coincides with that in the \mathcal{C} -topology, induced by the supremum norm over compact time sets. We will refer to \mathcal{C} -tightness etc. without further ado. All processes are written in coordinatewise fashion such as $X_n = (X_n^i)_{1 \leq i \leq d}$. Writing $|\cdot|$ for the Euclidean norm, square integrable processes X are those satisfying $E\{|X(t)|^2\} < \infty$ for every $t \geq 0$, while L_2 -bounded ones also satisfy $\sup_{t \geq 0} E\{|X(t)|^2\} < \infty$.

Suppose that M_n is a sequence of D -valued square integrable \mathbb{F} -martingales started at $M_n(0) = 0$. Because of the discontinuity of trajectories, the (matrix-valued or cross) quadratic variation $[M_n] := ([M_n^i, M_n^j])_{1 \leq i, j \leq d}$ is distinct from its matrix-valued (predictable) compensator $A_n := \langle M_n \rangle$ — another writing economy which stands for $(A_n^{ij})_{1 \leq i, j \leq d} := (\langle M_n^i, M_n^j \rangle)_{1 \leq i, j \leq d}$ — and it is the latter that is of interest from a practical point of view. Coordinatewise, we use $[M_n^i] = [M_n^i, M_n^i]$ and $\langle M_n^i \rangle = \langle M_n^i, M_n^i \rangle$ as well. The largest jump of $X \in D$ over $[0, t]$ is denoted by $J_t(X) := \sup_{s \in [0, t]} |X(s) - X(s-)|$. The following assumption will be used repeatedly.

Hypothesis 2.1. All of the following hold:

- (a) $A_n^{ii}(t) = \langle M_n^i \rangle_t \rightarrow \infty$ as $t \rightarrow \infty$ almost surely, for each fixed $n \geq 1$ and $i \in \{1, 2, \dots, d\}$;
- (b) There is a D -valued process A such that
 - (i) $A_n \xrightarrow{f.d.d.} A$ and $A^{ij} = 0$ for all $i \neq j$;
 - (ii) for all $t \geq 0$ and i , $\lim_n E\{A_n^{ii}(t)\} = E\{A^{ii}(t)\} < \infty$;
 - (iii) for all i , $A^{ii}(t) \rightarrow \infty$ as $t \rightarrow \infty$ almost surely.

Writing the inverse process for A_n^{ii} as $\tau_n^i(s) = \inf\{t \geq 0; A_n^{ii}(t) > s\}$, one defines the rescaled $\mathbb{F}_{\tau_n^i}$ -martingale $W_n^i = M_n^i \circ \tau_n^i$, with compensator $A_n^{ii} \circ \tau_n^i$. Note that by definition and using the right-continuity of A_n^{ii} , $A_n^{ii} \circ \tau_n^i(t) \geq t$. Actually, W_n^i is an $\mathbb{F}_{\tau_n^i}$ -Brownian

motion with respect to the filtration $\mathbb{F}_{\tau_n^i} = \{\mathcal{F}_{\tau_n^i(t)}\}_{t \geq 0}$, whenever Hypothesis 2.1.a holds and M_n^i is continuous everywhere, by Dambis [11] or Dubins and Schwarz [13]. In the latter case, the continuity of M_n^i implies the continuity of both $[M_n^i]$ and $\langle M_n^i \rangle$, as well as their equality $[M_n^i] = \langle M_n^i \rangle$. In this special case, the sequence M_n therefore comprises a naturally associated sequence of Brownian motions W_n^i coordinatewise. This is no longer the case as soon as at least one of the M_n^i 's has a discontinuity anywhere. Obtaining a CLT therefore requires building such a Brownian motion, possibly on an enlargement of the stochastic basis $(\Omega, \mathcal{F}, \mathbb{F}, P)$ with $\mathbb{F} = (\mathcal{F}_t)_{t \geq 0}$. Such enlargements will be used systematically in this paper and are understood to affect some statements implicitly, without further ado, for instance in some of the proofs. Equality in law is denoted by $\stackrel{Law}{=}$; convergence in probability is denoted by \xrightarrow{P} , in law by \xrightarrow{Law} , and almost sure convergence by $\xrightarrow{a.s.}$.

Theorem 2.1. Assume that Hypothesis 2.1 holds with A continuous everywhere; that $J_t(M_n) \xrightarrow{Law} 0$ for any $t > 0$; that there exists an \mathbb{F} -adapted sequence of D -valued square integrable martingales B_n started at $B_n(0) = 0$ so that

1. $(A_n, B_n) \overset{\mathcal{C}}{\rightsquigarrow} (A, B)$ holds, where B is a Brownian motion with respect to its natural filtration $\mathbb{F}_B = \{\mathcal{F}_{B,t} : t \geq 0\}$ and A is \mathbb{F}_B -measurable;
2. $\langle M_n^i, B_n^j \rangle_t \xrightarrow{Law} 0$, for any $i, j \in \{1, \dots, d\}$ and $t \geq 0$.

Then $(M_n, A_n, B_n) \overset{\mathcal{C}}{\rightsquigarrow} (M, A, B)$ holds, where M is a continuous square integrable \mathcal{F}_t -martingale with respect to (enlarged) filtration with predictable quadratic variation process A . Moreover, $M^i = W^i \circ A^{ii}$, $i \in \{1, \dots, d\}$ holds, with W a standard Brownian motion which is independent of B and A .

No need for A_n to converge in probability, nor for the nested filtrations required for stable convergence [19, Section VIII.5c], the usual way to characterize the law of M uniquely.

Proof. The idea of the proof is to use the convergence in law of A_n to a continuous A to get the tightness of M_n . Then, on another probability space, there is a subsequence converging almost surely. It remains to show that any possible limit of any subsequence has the desired properties. First, by Proposition A.4, the continuity of A implies that $A_n^{ii} \overset{\mathcal{C}}{\rightsquigarrow} A^{ii}$ holds for every i . By Jacod and Shiryaev [19, Theorem I.4.2], one concludes $(A_n^{ij}(t) - A_n^{ij}(s))^2 \leq (A_n^{ii}(t) - A_n^{ii}(s))(A_n^{jj}(t) - A_n^{jj}(s))$ almost surely, for every choice of i and j , so each A_n^{ij} is \mathcal{C} -tight and hence $A_n \overset{\mathcal{C}}{\rightsquigarrow} A$ as well. Next, set $X_n^i(t) = [M_n^i]_{\tau_n+t} - [M_n^i]_{\tau_n}$ and $Y_n^i(t) = A_n^{ii}(\tau_n+t) - A_n^{ii}(\tau_n)$, where τ_n is a sequence of bounded stopping times. The filtration of interest here is $\{\mathcal{F}_{\tau_n+t}\}_{t \geq 0}$. For any $\epsilon > 0$, $\eta > 0$ and sequence $\delta_n \in (0, 1) \rightarrow 0$, $EX_n^i(\delta_n) = EY_n^i(\delta_n)$ implies

$$P\left([M_n^i]_{\tau_n+\delta_n} - [M_n^i]_{\tau_n} \geq \epsilon\right) \leq \frac{1}{\epsilon} [\eta + E\{J_{\delta_n}(Y_n^i)\}] + P(Y_n^i(\delta_n) \geq \eta), \tag{2.1}$$

using (A.2) of Lemma A.1, with $J_{\delta_n}(Y_n^i) \leq Y_n^i(\delta_n) \leq \omega_{\mathcal{C}}(A_n^{ii}, \delta_n, T)$, since A_n^{ii} is nondecreasing. Therefore, the continuity of the limit A^{ii} implies $Y_n^i(\delta_n) \xrightarrow{Law} 0$ while $E\{Y_n^i(\delta_n)\} \rightarrow 0$ follows from Hypothesis 2.1.b(ii) by the dominated convergence theorem [14, Proposition App1.2]. By Theorem A.3, $[M_n^i]$ is \mathcal{J}_1 -tight. Since $J_t([M_n^i]) \xrightarrow{Law} 0$ is assumed, $[M_n^i]$ is actually \mathcal{C} -tight and hence so are M_n^i and $(M_n^i, A_n^{ii}, [M_n^i])$ successively. For every choice of i and j , inequality $([M_n^i, M_n^j]_t - [M_n^i, M_n^j]_s)^2 \leq ([M_n^i]_t - [M_n^i]_s)([M_n^j]_t - [M_n^j]_s)$ ensures the individual \mathcal{C} -tightness of each $[M_n^i, M_n^j]$. The \mathcal{C} -tightness of matrix $[M_n]$ follows, implying that of M_n and $(M_n, A_n, [M_n])$. By Skorohod's theorem, e.g., Ethier and Kurtz [14, Theorem 3.1.8], there exists a subsequence $\{n_k\}$, a probability space $(\Omega', \mathcal{F}', P')$, and

D -valued processes $Z'_{n_k} := (M'_{n_k}, B'_{n_k}, A'_{n_k})$ and $Z' := (M', B', A')$ defined on $(\Omega', \mathcal{F}', P')$ which are such that Z'_{n_k} and $Z_{n_k} := (M_{n_k}, B_{n_k}, \langle M_{n_k} \rangle)$ are identical in law for all $k \geq 1$, and Z'_{n_k} converges almost surely to Z' uniformly on compact time sets. We next prove that, for any such limit point $Z' = (M', B', A')$, M' and B' are both martingales with respect to the natural filtration $\mathcal{F}'_t = \sigma\{M'(s), B'(s), A'(s); s \leq t\}$, such that $\langle M' \rangle_t = A'_t$, $\langle B' \rangle_t = t$, and $\langle M', B' \rangle_t \equiv 0$.

For a given $\ell \geq 1$ and $0 \leq s_1 \leq \dots \leq s_\ell \leq s \leq t$, set $Y_{n_k} = (Z_{n_k}(s_1), \dots, Z_{n_k}(s_\ell))$, $Y'_{n_k} = (Z'_{n_k}(s_1), \dots, Z'_{n_k}(s_\ell))$ and $Y' = (Z'(s_1), \dots, Z'(s_\ell))$. Then, for any continuous and bounded function f of $\ell \times \{(1+d)^2 - 1\}$ variables, $(M'_{n_k}(t) - M'_{n_k}(s)) f(Y'_{n_k})$ converges almost surely to $(M'(t) - M'(s)) f(Y')$ and it is uniformly integrable since $E \left\{ (M'_{n_k}(t))^2 \right\} = EA'_{n_k}(t) = EA_{n_k}(t) \rightarrow EA(t)$. For M' to be a \mathcal{F}' -martingale, it suffices to prove $E \{(M'(t) - M'(s)) f(Y')\} = 0$ for any bounded (by 1) and continuous f , because the cylinder sets $\{Y' \in O\}$, O open, generate the σ -algebra $\mathcal{F}'(s)$, and because \mathbb{I}_O can be approximated by a sequence of bounded and continuous functions. Without loss of generality, we do so coordinatewise (hence $d = 1$) and drop the superscript i for the rest of the proof, in order to keep notation to a minimum. Since $A_{n_k}(u)$ is $\mathcal{F}_{n_k}(s)$ -measurable for all $0 \leq u \leq s$, $f(Y_{n_k})$ is $\mathcal{F}_{n_k}(s)$ -measurable and

$$0 = E \{(M_{n_k}(t) - M_{n_k}(s)) f(Y_{n_k})\} = E \{(M'_{n_k}(t) - M'_{n_k}(s)) f(Y'_{n_k})\} \xrightarrow{k \rightarrow \infty} E \{(M'(t) - M'(s)) f(Y')\}.$$

Moreover, using Ethier and Kurtz [14, Proposition App2.3] and Hypothesis 2.1.b, $\{M'_{n_k}(t)\}^2$ is uniformly integrable for each $t \geq 0$. Next, for all $0 \leq s \leq t$,

$$E \left\{ \{M'(t) - M'(s)\}^2 \right\} = \lim_{k \rightarrow \infty} E \left\{ \{M'_{n_k}(t) - M'_{n_k}(s)\}^2 \right\} = \lim_{k \rightarrow \infty} E \{A'_{n_k}(t) - A'_{n_k}(s)\} = E \{A(t) - A(s)\}. \quad (2.2)$$

Therefore M' is a square integrable martingale with respect to filtration $\{\mathcal{F}'(t)\}_{t \geq 0}$. The same argument also applies to B' . Next, $\left\{ (M'_{n_k}(t) - M'_{n_k}(s))^2 - A'_{n_k}(t) + A'_{n_k}(s) \right\} f(Y'_{n_k})$ converges almost surely to $\left\{ (M'(t) - M'(s))^2 - A'(t) + A'(s) \right\} f(Y')$ and its absolute value is bounded by $(M'_{n_k}(t) - M'_{n_k}(s))^2 + A'_{n_k}(t)$, which converges almost surely to $(M'(t) - M'(s))^2 + A'(t)$. Using (2.2), as $k \rightarrow \infty$, we have

$$E \left\{ (M'_{n_k}(t) - M'_{n_k}(s))^2 + A'_{n_k}(t) \right\} = 2EA'_{n_k}(t) - EA'_{n_k}(s) \rightarrow E \left\{ (M'(t) - M'(s))^2 + A'(t) \right\}.$$

By dominated convergence, for instance using Ethier and Kurtz [14, Proposition App1.2], one can conclude that

$$0 = E \left\{ \left\{ (M'_{n_k}(t) - M'_{n_k}(s))^2 - A'_{n_k}(t) + A'_{n_k}(s) \right\} f(Y'_{n_k}) \right\} \rightarrow E \left\{ \left\{ (M'(t) - M'(s))^2 - A'(t) + A'(s) \right\} f(Y') \right\}.$$

It follows that A' is the quadratic variation process of the martingale M' since, by construction, $A'(t)$ is $\mathcal{F}'(t)$ -measurable. Again, the same argument holds true for B' , with quadratic variation $\langle B' \rangle_t = t$, $t \geq 0$. Finally, both the within and cross off-diagonal terms in $\langle \tilde{M}_{n_k}, B_{n_k} \rangle$, are taken care of coordinatewise, as in the preceding argumentation, setting $d = 1$. For instance, the copy of the cross term

$$\left\{ M'_{n_k}(t)B'_{n_k}(t) - M'_{n_k}(s)B'_{n_k}(s) - \langle \tilde{M}'_{n_k}, B'_{n_k} \rangle_t + \langle \tilde{M}'_{n_k}, B'_{n_k} \rangle_s \right\} f(Y'_{n_k})$$

converges almost surely to $\{M'(t)B'(t) - M'(s)B'(s)\} f(Y')$, and its absolute value, using Kunita-Watanabe's inequality, is bounded by

$$g_{n_k} = \frac{1}{2} (M'_{n_k}(t))^2 + \frac{1}{2} (M'_{n_k}(s))^2 + \frac{1}{2} (B'_{n_k}(t))^2 + \frac{1}{2} (B'_{n_k}(s))^2 + \frac{1}{2} A'_{n_k}(t) + \frac{1}{2} \langle B'_{n_k} \rangle_t,$$

which converges almost surely to

$$g = \frac{1}{2} (M'(t))^2 + \frac{1}{2} (M'(s))^2 + \frac{1}{2} (B'(t))^2 + \frac{1}{2} (B'(s))^2 + \frac{1}{2} t + \frac{1}{2} A'(t).$$

Hypothesis (b) implies $E(g_{n_k}) \rightarrow E(g)$, so

$$E \left\{ \left\{ M'_{n_k}(t)B'_{n_k}(t) - M'_{n_k}(s)B'_{n_k}(s) - \langle \tilde{M}'_{n_k}, B'_{n_k} \rangle_t + \langle \tilde{M}'_{n_k}, B'_{n_k} \rangle_s \right\} f(Y'_{n_k}) \right\} \equiv 0$$

converges to $E \{ \{ M'(t)B'(t) - M'(s)B'(s) \} f(Y') \}$ and hence $\langle M', B' \rangle = 0$. Thus any limit point $Z' = (M', B', A')$ has the property that M', B' , and $M'B'$ are martingales with respect to the natural filtration \mathcal{F}'_t , with $\langle M' \rangle = A'$, B' is a Brownian motion, and most importantly, $\langle M', B' \rangle_t \equiv 0$. Since we already know that the trajectories of M' and B' are continuous, it follows from Ikeda and Watanabe [16, Theorem II.7.3] that $M' = W' \circ A'$ with independent Brownian motions W' and B' on probability space $(\Omega', \mathcal{F}', P')$. Since, A' is $\mathbb{F}_{B'}$ -measurable by hypothesis, W' is also independent of A' . Therefore all limit points (M', B', A') have the same law since the law of A' is the same as the one of A . \square

Remark 2.1. An historically important prototype of Theorem 2.1 is Rebolledo's landmark CLT for local martingales, when restricted to sequences of square integrable martingales [26] satisfying an asymptotic rarefaction of jumps condition. Functional CLTs involving limiting mixtures with non deterministic A go back to Rebolledo [25, p. 92-93] for processes converging to a diffusion in \mathbb{R}^d and Johansson [20], for point process martingales. Additional references on the early successes in the discrete case can be found in Hall and Heyde [15] and in the continuous case in Jacod and Shiryaev [19, Section VIII.5]. More recently, Merlevède et al. [22] display the current state of the art of the functional CLT for rescaled non-stationary sequences and arrays of dependent random variables when the limit is continuous — either a Brownian motion or the stochastic integral of a continuous function with respect to a Brownian motion.

The proof of the following useful proposition relies on the tightness induced by the convergence of the quadratic variation process.

Proposition 2.2. Suppose $(\xi_j)_{j \geq 1}$ is a sequence of iid random variables with mean 0 and variance 1, independent of a continuous stochastic process σ defined on $[0, \infty)$.

Set $M_n(t) = n^{-\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \sigma \left(\frac{j-1}{n} \right) \xi_j$, $V_n(t) = n^{-1} \sum_{j=1}^{\lfloor nt \rfloor} \sigma^2 \left(\frac{j-1}{n} \right)$, and define $V(t) =$

$\int_0^t \sigma^2(s) ds$. Finally, set $B_n(t) = n^{-\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \xi_j$. Then $(M_n, V_n, B_n) \xrightarrow{\mathcal{C}} (M, V, B)$, where

B is a Brownian motion independent of σ and M can also be written as a stochastic integral with respect to B viz. $M(t) = \int_0^t \sigma(s) dB_s$, $M = W \circ V$, and W is a Brownian motion independent of V .

Proof. Let $\mathcal{F}_{n,t} = \sigma \left\{ \xi_j, a \left(\frac{j}{n} \right); j \leq \lfloor nt \rfloor \right\}$. Then M_n is a $\mathcal{F}_{n,t}$ -martingale with $\langle M_n \rangle(t) = n^{-1} \sum_{j=1}^{\lfloor nt \rfloor} \sigma^2 \left(\frac{j-1}{n} \right) = V_n(t)$. From the continuity of σ , one gets that $V_n \rightarrow V$ and V is

continuous. Also, if $B_n(t) = n^{-\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \xi_j$, then $(B_n, V_n) \xrightarrow{\mathcal{C}} (B, V)$, where B is a Brownian

motion independent of σ and V . Since $J_t(M_n) \xrightarrow{Law} 0$ holds, Theorem A.3 shows that (M_n, V_n, B_n) is \mathcal{C} -tight. To complete the proof, let W be a Brownian motion independent of V . It is sufficient to show that for any $0 = t_0 < t_1 < \dots < t_m$, $M_n(t_1), \dots, M_n(t_m)$, $V_n(t_1), \dots, V_n(t_m)$, and $B_n(t_1), \dots, B_n(t_m)$ converge jointly in law to $W \circ V(t_1), \dots, B(t_m)$. To this end, take $\theta_1, \eta_1, \lambda_1, \dots, \theta_m, \eta_m, \lambda_m \in \mathbb{R}$, and set $\varphi(s) = E(e^{is\xi_j})$. Next, setting $G_n = e^{i \sum_{j=1}^m \eta_j \{V_n(t_j) - V_n(t_{j-1})\}}$, and using the standard proof of the CLT, one gets

$$\begin{aligned} & E \left[e^{i \sum_{k=1}^m [\lambda_k \{M_n(t_k) - M_n(t_{k-1})\} + \theta_k \{B_n(t_k) - B_n(t_{k-1})\} + \eta_k \{V_n(t_k) - V_n(t_{k-1})\}]} \right] \\ &= E \left[G_n \prod_{k=1}^m \prod_{j=\lfloor nt_{k-1} \rfloor + 1}^{\lfloor nt_k \rfloor} \varphi \left\{ n^{-\frac{1}{2}} \theta_k + n^{-\frac{1}{2}} \lambda_k \sigma \left(\frac{j-1}{n} \right) \right\} \right] \\ &= E \left[G_n e^{-\frac{1}{2} \sum_{k=1}^m \lambda_k^2 \{V_n(t_k) - V_n(t_{k-1})\} - \frac{1}{2} \sum_{k=1}^m \theta_k^2 (t_k - t_{k-1})} \right] + o(1) \\ &\rightarrow E \left[e^{-\frac{1}{2} \sum_{k=1}^m \lambda_k^2 \{V(t_k) - V(t_{k-1})\} - \frac{1}{2} \sum_{k=1}^m \theta_k^2 (t_k - t_{k-1}) + i \sum_{j=1}^m \eta_k \{V(t_k) - V(t_{k-1})\}} \right] \\ &= E \left[e^{i \sum_{k=1}^m [\lambda_k \int_{t_{k-1}}^{t_k} \sigma(s) dB_s + \eta_k \{V(t_k) - V(t_{k-1})\} + \theta_k \{B(t_k) - B(t_{k-1})\}]} \right]. \end{aligned}$$

Taking $\theta_1 = \dots = \theta_m = 0$, one gets that M has also the same distribution as $W \circ V$, for a Brownian motion W independent of V . □

3 Examples of application to occupation times

3.1 Occupation times for Brownian motion

Let B denote a Brownian motion, V continuous with compact support, and $\mu_V = \int_{-\infty}^{\infty} V(y)dy = 0$ but V is not identically 0. Set $F(x) = -2 \int_{-\infty}^x V(y)dy$ and $G(x) = \int_{-\infty}^x F(y)dy$ and consider the martingale $M_1(t) = G(B_t) + \int_0^t V(B_s)ds$ and the occupation time $\int_0^t V(B_s)ds$. Setting $B_n(t) = n^{-\frac{1}{2}} B_{nt}$, then the continuous martingale $M_n(t) = n^{-\frac{1}{4}} \int_0^{nt} F(B_s)dB_s = n^{\frac{1}{4}} \int_0^t F(n^{\frac{1}{2}} B_n(s)) dB_n(s)$ has the same asymptotic behavior as $n^{-\frac{1}{4}} \int_0^{nt} V(B_s)ds$ since G is bounded. Using the scaling property of Brownian motion, it follows that $(M_n, [M_n], B_n)_{t \geq 0} \xrightarrow{Law} (\tilde{M}_n, [\tilde{M}_n], \tilde{B})_{t \geq 0}$, where \tilde{B} is another Brownian motion, $\tilde{M}_n(t) = n^{\frac{1}{4}} \int_0^t F(\sqrt{n} \tilde{B}_u) d\tilde{B}_u$, and $[\tilde{M}_n]_t = n^{\frac{1}{2}} \int_0^t F^2(\sqrt{n} \tilde{B}_u) du$. Hence, as $n \rightarrow \infty$, $A_n(t) = [\tilde{M}_n]_t = \sqrt{n} \int_{\mathbb{R}} F^2(\sqrt{n}x) \ell_t(x) dx \xrightarrow{a.s.} \|F\|^2 \ell_t(0) = A(t)$, uniformly over compact time sets, where ℓ is the local time of Brownian motion \tilde{B} , and $\|F\|^2 = \int_{\mathbb{R}} F^2(x)dx = -2 \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |y - z| V(y) V(z) dz dy$. As a result, $(A_n, \tilde{B}) \xrightarrow{\mathcal{C}} (A, \tilde{B})$, and A is clearly $\mathbb{F}_{\tilde{B}}$ -measurable. Using Theorem 2.1, both M_n and $n^{-\frac{1}{4}} \int_0^{nt} V(B_s)ds$ converge weakly to $W \circ A$, where W is a Brownian motion independent of A and \tilde{B} . In fact, the full consequence of Theorem 2.1 states that $(M_n, A_n, \tilde{B}) \xrightarrow{\mathcal{C}} (M, A, \tilde{B})$ holds. The result for M_n was first proven in Papanicolaou et al. [23]. The proof given here is much easier and is similar to the one in [16]. The argument above for handling A_n under $\mu_V = 0$, carries through to yield $n^{-\frac{1}{2}} \int_0^{nt} V(B_s)ds \xrightarrow{\mathcal{C}} \mu_V \ell_t(0)$ when $\mu_V \neq 0$.

Remark 3.1. Recall that $\ell_t(0)/\sqrt{t} \stackrel{Law}{=} |B_1|$ which has Mittag-Leffler distribution with parameter $\frac{1}{2}$. Next, the inverse local time τ is known to be a Lévy process with density $ty^{-\frac{3}{2}}e^{-\frac{t^2}{2y}}$, $y > 0$, and Laplace transform $E[e^{-\lambda\tau}] = e^{-t\sqrt{2\lambda}}$, $\lambda \geq 0$ [7]. Hence τ_t has a positive stable distribution with index $\frac{1}{2}$.

3.2 Occupation times for random walks

Let S_n be the symmetric simple random walk on the integers \mathbb{Z} , $N_n(x) = \sum_{k=1}^n \mathbb{I}(S_k = x)$ the number of its visits to $x \in \mathbb{Z}$ up to time n and V a real-valued function on \mathbb{Z} with compact support but $V \not\equiv 0$. Setting $\mu_V := \sum_{x \in \mathbb{Z}} V(x)$, [12] proved that if $\mu_V \neq 0$, then $n^{-\frac{1}{2}} \sum_{k=1}^n V(S_k) \xrightarrow{Law} \mu_V \mathcal{V}$, where $\mathcal{V} \stackrel{Law}{=} |Z|$, where $Z \sim N(0, 1)$; while if $\mu_V = 0$, then $n^{-\frac{1}{4}} \sum_{k=1}^n V(S_k) \xrightarrow{Law} \mu_v \sqrt{\mathcal{V}} Z$, where $Z \sim N(0, 1)$ is independent of \mathcal{V} , and $\mu_v = 2c_V^2 - \sum_{x \in \mathbb{Z}} V^2(x)$, where $c_V^2 = - \sum_{y, z \in \mathbb{Z}} |y - z| V(y)V(z) = 2 \sum_{z \in \mathbb{Z}} \left\{ \sum_{y < z} V(y) \right\}^2$. Note that μ_v corresponds to expression $\|V\|^2$ in [21].

Just as in Section 3.1, we prove that $(V_n, B_n) \xrightarrow{C} (M, B)$ ensues when $\mu_V = 0$, where $V_n(t) := n^{-\frac{1}{4}} \sum_{k=1}^{\lfloor nt \rfloor} V(S_k)$, $B_n(t) := n^{-\frac{1}{2}} S_{\lfloor nt \rfloor}$, B is a Brownian motion, $A(t) = c_V^2 \ell_t(0)$ with ℓ the local time for B , and $M = W \circ A$, where W is a Brownian motion independent of A and B . We first build the pair (M_n, A_n) . To this end, set $G(x) = - \sum_{y \in \mathbb{Z}} |x - y| V(y)$.

Then

$$\begin{aligned} TG(x) &= \frac{G(x+1) + G(x-1)}{2} = - \sum_y V(y) \left\{ \frac{|y-x-1| + |y-x+1|}{2} \right\} \\ &= -V(x) - \sum_{y>x} V(y)(y-x) - \sum_{y<x} V(y)(x-y) = -V(x) + G(x), \end{aligned}$$

with G is constant outside the support of V : in fact, if $V \equiv 0$ on $[a, b]^c$, then $G(x) = \sum_{y \in [a, b]} yV(y) = c$ if $x > b$, while if $x < a$, then $G(x) = -c$. Consequently, $M_n(t) := n^{-\frac{1}{4}} \sum_{k=1}^{\lfloor nt \rfloor} \{G(S_k) - TG(S_{k-1})\} = n^{-\frac{1}{4}} \{G(S_{\lfloor nt \rfloor}) - G(0)\} + n^{-\frac{1}{4}} \sum_{k=1}^{\lfloor nt \rfloor} V(S_{k-1})$ is a martingale with

$$\begin{aligned} A_n(t) = \langle M_n \rangle_t &= n^{-\frac{1}{2}} \sum_{k=1}^{\lfloor nt \rfloor} E \left[\{G(S_k) - TG(S_{k-1})\}^2 \mid \mathcal{F}_{k-1} \right] \\ &= n^{-\frac{1}{2}} \sum_{k=1}^{\lfloor nt \rfloor} [TG^2(S_{k-1}) - \{TG(S_{k-1})\}^2] = n^{-\frac{1}{2}} \sum_{k=1}^{\lfloor nt \rfloor} v(S_{k-1}). \end{aligned}$$

Now, since $TG = G - V$, it follows that $v = TG^2 - (TG)^2 = 2VG - V^2 + TG^2 - G^2$ which has compact support since G^2 is constant outside $[a, b]$. As a result,

$$\begin{aligned} A_n(t) &= n^{-\frac{1}{2}} \sum_{k=1}^{\lfloor nt \rfloor} v(S_{k-1}) = n^{-\frac{1}{2}} \sum_{x \in \mathbb{Z}} v(x) N_{\lfloor nt \rfloor - 1}(x) \\ &= n^{-\frac{1}{2}} \sum_{x \in \mathbb{Z}} v(x) \{N_{\lfloor nt \rfloor - 1}(x) - N_{\lfloor nt \rfloor - 1}(0)\} + \mu_v n^{-\frac{1}{2}} N_{\lfloor nt \rfloor - 1}(0) \\ &= n^{-\frac{1}{4}} O_P(1) + \mu_v n^{-\frac{1}{2}} N_{\lfloor nt \rfloor}(0), \end{aligned}$$

using Dobrushin’s results and the fact that v has compact support, where

$$\mu_v = \sum_{x \in \mathbb{Z}} v(x) = -2 \sum_{y, x \in \mathbb{Z}} |y - x|V(y)V(x) - \sum_{x \in \mathbb{Z}} V^2(x) = \sum_{x \in \mathbb{Z}} \{V(x) + 2H(x)\}^2,$$

and $H(x) = \sum_{y < x} V(y)$. These expressions are proven in Appendix A. In particular, if $V(a) = 1$, $a \neq 0$, and $V(0) = -1$, then $\mu_v = 4|a| - 2$. It then follows that $(A_n, B_n) \xrightarrow{\mathcal{C}} (A, B)$, where B is a Brownian motion and $A(t) = \mu_v \ell_t(0)$ is the local time of the Brownian motion at 0. Next, setting $f(x) = x$, one gets that

$$\langle M_n, B_n \rangle_t = n^{-\frac{3}{4}} \sum_{k=1}^{\lfloor nt \rfloor} \{T(fG)(S_{k-1}) - Tf(S_{k-1})TG(S_{k-1})\} = n^{-\frac{3}{4}} \sum_{k=1}^{\lfloor nt \rfloor} g(S_{k-1}),$$

where $g = T(fG) - TfTG$. Since $Tf = f$, $G(x) = c$, $x > b$ and $G(x) = -c$, $x < a$, it follows that g also has compact support and, from the previous calculations and Dobrushin’s result, that for any $t \geq 0$, $\langle M_n, B_n \rangle_t = O\left(n^{-\frac{1}{4}}\right)$. Therefore, using Theorem 2.1, $(M_n, A_n, B_n) \xrightarrow{\mathcal{C}} (W \circ A, A, B)$, where W is a Brownian motion independent of A and B ; hence $(V_n, A_n, B_n) \xrightarrow{\mathcal{C}} (W \circ A, A, B)$ as well, since the above calculations yield also $\sup_{t \in [0, T]} |V_n(t) - M_n(t)| = O\left(n^{-\frac{1}{4}}\right)$ for any $T > 0$. The corresponding result $n^{-\frac{1}{4}}V_n \xrightarrow{\mathcal{C}} \mu_V \ell$ when $\mu_V \neq 0$ ensues from the definition of the local time for Brownian motion, as in the proof of $A_n \xrightarrow{\mathcal{C}} A$ in the case $\mu_V = 0$.

3.3 Scaling limit for the random comb

Let (ξ_n, ζ_n) and $(0, \psi_n)$ be two iid sequences independent of each other, with $P(\psi_n = \pm 1) = \frac{1}{2}$, and $P\{(\xi_n, \zeta_n) = (\pm 1, 0)\} = P\{(\xi_n, \zeta_n) = (0, \pm 1)\} = \frac{1}{4}$. The comb process (C_1, C_2) [6, 8] is a martingale with values on the integer lattice \mathbb{Z}^2 , as well as a Markov chain, started at $(0, 0)$ and defined by

$$\begin{aligned} C_1(n+1) &= C_1(n) + \xi_{n+1} \mathbb{I}_{\{C_2(n)=0\}}, \\ C_2(n+1) &= C_2(n) + \psi_{n+1} \mathbb{I}_{\{C_2(n) \neq 0\}} + \zeta_{n+1} \mathbb{I}_{\{C_2(n)=0\}}. \end{aligned}$$

Note that C_2 is also a Markov chain on its own, while C_1 is not. For all $n \geq 0$,

$$\begin{aligned} E[\{C_1(n+1) - C_1(n)\}^2 | \mathcal{F}_n] &= \frac{1}{2} \mathbb{I}_{\{C_2(n)=0\}}, \\ E[\{C_2(n+1) - C_2(n)\}^2 | \mathcal{F}_n] &= 1 - \frac{1}{2} \mathbb{I}_{\{C_2(n)=0\}}, \\ E[\{C_1(n+1) - C_1(n)\}\{C_2(n+1) - C_2(n)\} | \mathcal{F}_n] &= 0. \end{aligned}$$

Set $A_1(n) = \sum_{k=1}^n \mathbb{I}_{\{C_2(k)=0\}}$ and $\tau_k = \inf\{n \geq 1; A_1(n) \geq k\}$, the time of the k -th visit to 0 by C_2 after the initial departure, with defaults $A_1(0) = 0$ and $\tau_0 = 0$. Since the increments $\sigma_n = \tau_n - \tau_{n-1}$ are iid and $n^{-\frac{1}{2}}C_2([n \cdot]) \xrightarrow{\mathcal{C}} W_2$, a Brownian motion, there ensues $n^{-\frac{1}{2}}2^{-1}A_1([n \cdot]) \xrightarrow{\mathcal{C}} \eta_2$, the local time at 0 of W_2 . Build the \mathbb{R}^2 -valued martingale $\Xi_n(t) := \left\{n^{-\frac{1}{4}}C_1(\lfloor nt \rfloor), n^{-\frac{1}{2}}C_2(\lfloor nt \rfloor)\right\}$ with predictable quadratic variations $n^{-\frac{1}{2}}2^{-1}A_1(\lfloor nt \rfloor)$ and $n^{-1}\lfloor nt \rfloor - (2n)^{-1}A_1(\lfloor nt \rfloor)$ componentwise. Since $J_T(\Xi_n)n^{-\frac{1}{4}} \rightarrow 0$ as $n \rightarrow \infty$ almost surely, the only possible weak limits of Ξ_n have continuous trajectories. Further, $\left\{n^{-\frac{1}{2}}2^{-1}A_1([n \cdot]), n^{-1}[n \cdot] - (2n)^{-1}A_1([n \cdot])\right\} \xrightarrow{\mathcal{C}} \{t \mapsto (\eta_2(t), t)\}$, a process with continuous trajectories. Since Ξ_n has uncorrelated components, all the conditions of Theorem 2.1 are met and $\Xi_n \xrightarrow{\mathcal{C}} (W_1 \circ \eta_2, W_2)$. Notice that if we write $X_n = C_1(\tau_n) - C_1(\tau_{n-1})$, then $(X_n, \sigma_n)_{n \geq 1}$ are iid.

4 Volatility modeling and estimation

The financial return $R(t)$ at time t for some investment under consideration is modelled as $R(t) = Z \circ \tau(t)$, with $Z(s) := \gamma B(s) + \beta s$, where τ is a strictly increasing process, independent of the Brownian motion B . This model was first proposed by Ané and Geman [2]. Time scale τ is meant to reflect business cycles and other features known collectively in economics as business time; Z is thus the financial return adjusted accordingly. Constant γ is a scaling parameter and constant β the trend after the correction for business time. Note that a different model with the same distributional features is $R(t) = \int_0^t \sigma(s) dW(s) + \beta \tau(t)$, where σ is a continuous process independent of the Brownian motion W and $\tau(t) = \int_0^t \sigma^2(s) ds$. The latter was considered by [4].

Rigorous treatment of these models requires some technical results concerning D -valued square integrable \mathbb{F} -martingales M and their compensator $A = \langle M \rangle$. We gather these next. In what follows, we consider the partitions $s_{k,\delta} = k\delta$ independent of t , where $K(t, \delta) = \lfloor \frac{t}{\delta} \rfloor$. For each $\delta > 0$, construct

$$V_{p,\delta}(t) := \delta^{1-\frac{p}{2}} \sum_{1 \leq k \leq K(t,\delta)} |M(s_{k,\delta}) - M(s_{k-1,\delta})|^p$$

and

$$U_{p,\delta}(t) := \delta^{1-\frac{p}{2}} \sum_{1 \leq k \leq K(t,\delta)} \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^{\frac{p}{2}}.$$

Before stating the next result, set $\mu_p = E(|Z|^p) = 2^{\frac{p}{2}} \frac{\Gamma(\frac{p+1}{2})}{\Gamma(\frac{1}{2})}$, where $Z \sim N(0, 1)$. So

$\mu_{2n} = \prod_{k=1}^n (2k - 1)$ and $\mu_{2n+1} = \sqrt{\frac{2}{\pi}} \cdot \prod_{k=1}^n (2k)$. Typically useful values are $\mu_2 = 1$, $\mu_4 = 3$ and $\mu_8 = 105$.

Lemma 4.1. Given is a real-valued martingale M started at $M_0 = 0$ with finite p^{th} moment for some integer $p \geq 2$ and compensator A , where $A_t = \int_0^t a_s ds$, for some non-negative and continuous stochastic process a . Assume the existence of a Brownian motion B such that $M = B \circ A$, with A independent of B . Then, for $0 \leq s \leq t < \infty$, we have

$$E\{|M_t - M_s|^p | \mathcal{F}_s\} = \mu_p E\left\{(A_t - A_s)^{\frac{p}{2}} | \mathcal{F}_s\right\}. \tag{4.1}$$

In addition, $\lim_{\delta \downarrow 0} U_{p,\delta} = \mathcal{U}_p$ a.s., where $\mathcal{U}_p(t) = \int_0^t a_s^{\frac{p}{2}} ds$. Furthermore, under the additional assumption that M has finite $(2p)^{th}$ moment, $V_{p,\delta} \xrightarrow{Pr} \mathcal{V}_p = \mu_p \mathcal{U}_p$ as $\delta \downarrow 0$. In particular, if $M_t = \int_0^t \sigma_s dW_s$, for some Brownian motion W and continuous non-negative process σ independent of W , then $\mathcal{V}_p(t) = \mu_p \int_0^t \sigma_s^p ds$.

Proof. Equation (4.1) proceeds from $E\{|B \circ A_t - B \circ A_s|^p | \sigma\{A\}\} = \mu_p (A_t - A_s)^{\frac{p}{2}}$ which itself ensues from the independence of A and B , plus the moments of a standard normal distribution. When $p \geq 2$, note that $\mathcal{U}_p(t) = \int_0^t a_s^{\frac{p}{2}} ds \geq U_{p,\delta}(t)$ and $\delta^{1-\frac{p}{2}} \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^{\frac{p}{2}} = \delta \{a(w_{k,\delta})\}^{\frac{p}{2}} \leq \int_{s_{k-1,\delta}}^{s_{k,\delta}} a_s^{\frac{p}{2}} ds$, for some $w_{k,\delta} \in [s_{k-1,\delta}, s_{k,\delta}]$. As a result,

$\lim_{\delta \downarrow 0} U_{p,\delta} = \mathcal{U}_p$ since a is continuous and $\lim_{\delta \downarrow 0} \sum_{k=1}^{K(t,\delta)} \int_{s_{k-1,\delta}}^{s_{k,\delta}} [a_u^{\frac{p}{2}} - \{a(w_{k,\delta})\}^{\frac{p}{2}}] du = 0$. It remains to show that the filter of martingales $Z_\delta := V_{p,\delta} - \mu_p U_{p,\delta}$ converges in probability to 0, uniformly on compact time sets — the martingale property proceeds at once, just as

in the proof of Equation (4.1). Assuming $E\{|M_t|^{2p}\} < \infty$ for any $t \geq 0$, the representation $M = B \circ A$ yields

$$\begin{aligned} E \left\{ |M(s_{k,\delta}) - M(s_{k-1,\delta})|^p \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^{\frac{p}{2}} \middle| \mathcal{F}_{s_{k-1,\delta}} \right\} \\ = \mu_p E \left\{ \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^p \middle| \mathcal{F}_{s_{k-1,\delta}} \right\}. \end{aligned}$$

Expanding the square in

$$\begin{aligned} E \left\{ \left(|M(s_{k,\delta}) - M(s_{k-1,\delta})|^p - \mu_p \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^{\frac{p}{2}} \right)^2 \middle| \mathcal{F}_{s_{k-1,\delta}} \right\} \\ = (\mu_{2p} - \mu_p^2) E \left\{ \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^p \middle| \mathcal{F}_{s_{k-1,\delta}} \right\} \end{aligned}$$

implies that Z_δ is square integrable with compensator $\langle Z_\delta \rangle$ given by

$$\langle Z_\delta \rangle_t = \delta^{2-p} (\mu_{2p} - \mu_p^2) \sum_{1 \leq k \leq K(t,\delta)} E \left\{ \{A(s_{k,\delta}) - A(s_{k-1,\delta})\}^p \middle| \mathcal{F}_{s_{k-1,\delta}} \right\},$$

so there ensues $E\{\langle Z_\delta \rangle_t\} = \delta(\mu_{2p} - \mu_p^2)E\{U_{2p,\delta}(t)\}$ which goes to 0 with δ . By Lemma A.1, $\sup_{0 \leq s \leq t} |Z_\delta(s)|$ converges in probability to 0 with δ as well. \square

Remark 4.1. This result is an extension of [5]. They only prove their result for a fixed t with convergence in probability but claimed it could also be true as a process. The case $p = 2$ is just the definition of quadratic variation $[M]$ — see the proof of Ethier and Kurtz [14, Proposition 2.3.4], where the existence of $\mathcal{V}_2 := \lim_{\delta \downarrow 0} V_{2,\delta}$ is shown to hold for any right continuous local martingale and without any additional restriction, neither on A nor on the filter. Note that, when $p > 2$, the limit \mathcal{V}_p does not exist if M is not continuous everywhere. The asymptotics for $V_{p,\delta}$ under $p \in (0, 2)$ are covered extensively by [17] and [18], for a large class of processes with jumps, based on equally spaced observations. The cases $p \geq 3$ are also examined in Jacod [18, Theorems 2.11(i)] — the presence of jumps in the limit yields a CLT with $\delta^{-\frac{1}{2}}$ instead of $\delta^{1-\frac{p}{2}}$. For our continuous limits, the larger fluctuations observed there disappear. See his comments in Remarks 2.14, 2.15 and 2.16.

We can now state a first consistency result for an estimator of the realized volatility error in investment returns, when data is collected at regular intervals. This is an extension of the results presented in [4], where convergence was limited to a fixed t , while here we obtain the convergence of the whole process. Before stating the first theorem, define

$$\begin{aligned} X_n(t) &:= n^{\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \left[\left\{ \Delta_n M \left(\frac{j}{n} \right) \right\}^2 - \Delta_n A \left(\frac{j}{n} \right) \right], \\ \langle X_n \rangle_t &:= 2n \sum_{j=1}^{\lfloor nt \rfloor} E \left[\left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 \middle| \mathcal{F}_{\frac{j-1}{n}} \right], \\ V_n(t) &:= n \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n M \left(\frac{j}{n} \right) \right\}^4, \end{aligned}$$

where $\Delta_n f(s) = f(s) - f(s - 1/n)$.

Theorem 4.2 (Numerical scheme). Assume that both $A(t) \rightarrow \infty$ and $\mathcal{V}_4(t) \rightarrow \infty$ as $t \rightarrow \infty$. Under all the conditions of Lemma 4.1 with $p = 4$, including the finiteness of $E\{|M_t|^8\} < \infty$ for any $t \geq 0$, there is a standard Brownian motion W independent of \mathcal{V}_4 such that $(X_n, \langle X_n \rangle, V_n) \xrightarrow{\mathcal{L}} (W \circ A, A, \mathcal{V}_4)$, where $A = 2\mathcal{U}_4 = \frac{2}{3}\mathcal{V}_4$. Furthermore, for any adapted D -valued process N such that $n^{\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n N \left(\frac{j}{n} \right) \right\}^2 \xrightarrow{Pr} 0$ and $n \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n N \left(\frac{j}{n} \right) \right\}^2 \Delta_n A \left(\frac{j}{n} \right) \xrightarrow{Pr} 0$ both hold for all $t > 0$, there also comes $Y_n \xrightarrow{\mathcal{L}} W \circ A$, where $Y_n(t) := n^{\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \left[\left\{ \Delta_n (M + N) \left(\frac{j-1}{n} \right) \right\}^2 - \Delta_n A \left(\frac{j-1}{n} \right) \right]$.

Proof. By Lemma 4.1, V_n converges to \mathcal{V}_4 in probability and hence $V_n \xrightarrow{\mathcal{L}} \mathcal{V}_4$ holds, by Proposition A.4. The expression for $\langle X_n \rangle$ is a direct consequence of Lemma 4.1, which entails $E \left[\left\{ \Delta_n M \left(\frac{j}{n} \right) \right\}^4 | \mathcal{F}_{\frac{j-1}{n}} \right] = 3E \left[\left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 | \mathcal{F}_{\frac{j-1}{n}} \right]$, while the representation $M = B \circ A$ yields

$$E \left[\left\{ \Delta_n M \left(\frac{j}{n} \right) \right\}^2 \Delta_n A \left(\frac{j}{n} \right) | \mathcal{F}_{\frac{j-1}{n}} \right] = E \left[\left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 | \mathcal{F}_{\frac{j-1}{n}} \right].$$

Also, $V_n = \frac{3}{2}\langle X_n \rangle + \mathcal{Z}_n$, where

$$\mathcal{Z}_n(t) = n \sum_{j=1}^{\lfloor nt \rfloor} \left[\left\{ \Delta_n M \left(\frac{j}{n} \right) \right\}^4 - E \left[\left\{ \Delta_n M \left(\frac{j}{n} \right) \right\}^4 | \mathcal{F}_{\frac{j-1}{n}} \right] \right]$$

is a martingale with

$$\langle \mathcal{Z}_n \rangle_t = \mu_8 n^2 \sum_{k=1}^{\lfloor nt \rfloor} E \left[\left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^4 | \mathcal{F}_{\frac{j-1}{n}} \right] - \mu_4^2 n^2 \sum_{k=1}^{\lfloor nt \rfloor} E^2 \left[\left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 | \mathcal{F}_{\frac{j-1}{n}} \right].$$

By Lemma 4.1 with $p = 8$, $nE\{\langle \mathcal{Z}_n \rangle_t\}$ is bounded above by sequence $E\{\mathcal{U}_{8,1/n}(t)\}$ which converges to $E\{\mathcal{U}_8(t)\}$ and hence $\langle \mathcal{Z}_n \rangle \xrightarrow{\mathcal{L}} 0$ holds, by Proposition A.4. By Lemma A.1, $\sup_{0 \leq t \leq T} |\mathcal{Z}_n(t)|$ converges in probability to 0. This implies $\langle X_n \rangle \xrightarrow{\mathcal{L}} 2\mathcal{U}_4 = \frac{2}{3}\mathcal{V}_4$. Next, let Z_j

be iid standard Gaussian random variables independent of A , set $\mathbb{B}_n(t) = (2n)^{-\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} (Z_j^2 - 1)$;

further set $a_{n,j} = A \left(\frac{j}{n} \right) - A \left(\frac{j-1}{n} \right)$. It is then clear that $(A_n, \mathbb{B}_n) \xrightarrow{\mathcal{L}} (A, \mathbb{B})$, where \mathbb{B} is a Brownian motion independent of a . For any $0 = t_0 < t_1 < \dots < t_m$, and $\lambda_1, \dots, \lambda_m \in \mathbb{R}$, since $M = B \circ A$, where B is a Brownian motion independent of A , one has

$$\begin{aligned} & E \left[\exp \left[i \sum_{k=1}^m \lambda_k \{ X_n(t_k) - X_n(t_{k-1}) \} \right] \right] \\ &= E \left[\exp \left[i n^{\frac{1}{2}} \sum_{k=1}^m \lambda_k \sum_{j=\lfloor nt_{k-1} \rfloor + 1}^{\lfloor nt_k \rfloor} a_{n,j} (Z_j^2 - 1) \right] \right] \\ &= E \left[\exp \left[i 2^{\frac{1}{2}} n^{-\frac{1}{2}} \sum_{k=1}^m \lambda_k \sum_{j=\lfloor nt_{k-1} \rfloor + 1}^{\lfloor nt_k \rfloor} a \left(\frac{j-1}{n} \right) \left(\frac{Z_j^2 - 1}{2^{\frac{1}{2}}} \right) \right] \right] + o(1). \end{aligned}$$

One can then use Proposition 2.2 to conclude that $(X_n, \langle X_n \rangle, V_n, \mathbb{B}_n) \xrightarrow{\mathcal{L}} (X, \mathcal{A}, \mathcal{V}_4, \mathbb{B})$, where \mathbb{B} is a Brownian motion independent of $\mathcal{A} = \mathcal{U}_4$ and $X_t = \int_0^t a(s) d\mathbb{B}(s)$. Furthermore, X can be written as $X = W \circ \mathcal{A}$, where W is a Brownian motion independent of \mathcal{A} . Finally, writing $Z_n(t) := n^{\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \Delta_n N \left(\frac{j-1}{n} \right)$ yields square integrable martingale

$$\int_0^t Z_n(s) dM(s) = n^{\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \Delta_n M \left(\frac{j}{n} \right) \Delta_n N \left(\frac{j-1}{n} \right) \text{ with quadratic variation}$$

$$\left\langle \int_0^t Z_n(s) dM(s) \right\rangle = \int_0^t Z_n^2(s) d\langle M \rangle_t = n \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n N \left(\frac{j-1}{n} \right) \right\}^2 \Delta_n A \left(\frac{j-1}{n} \right).$$

Note also that $\int_0^t Z_n^2(s) ds = \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n N \left(\frac{j-1}{n} \right) \right\}^2$.

Therefore $Y_n(t) - X_n(t) = n^{\frac{1}{2}} \int_0^t Z_n^2(s) ds + 2 \int_0^t Z_n(s) dM(s) \xrightarrow{Pr} 0$ holds for every $t > 0$, since $\int_0^t Z_n^2(s) d\langle M \rangle_t \xrightarrow{Pr} 0$. Hence $Y_n - X_n \xrightarrow{\mathcal{L}} 0$ holds as well, yielding the last statement for Y_n via Lemma A.1, Theorem A.3 and Proposition A.4. \square

A frequent choice for perturbation process N is a linear function of the volatility. Recall the modulus of continuity of A , defined by

$$\omega_{\mathcal{C}}(A, \delta, T) = \sup_{0 \leq t_1 < t_2 \leq T, t_2 - t_1 < \delta} \|A(t_2) - A(t_1)\|.$$

Corollary 4.3. Suppose that $N(t) = \mu t + \beta A(t)$, for some constants $\mu \in \mathbb{R}$ and $\beta \geq 0$, and that the modulus of continuity of A satisfies $\delta^{-\alpha} \omega_{\mathcal{C}}(A, \delta, t) \xrightarrow{Pr} 0$ as $\delta \rightarrow 0$, for some $\alpha > \frac{3}{4}$ and all $t > 0$. The conclusions of Theorem 4.2 hold.

Proof. For the terms in A , the two conditions on N are a consequence of

$$n^{\frac{1}{2}} \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 + n \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^3 \leq tn^{3/2} \omega_{\mathcal{C}}^2(A, 1/n, t) + tn^2 \omega_{\mathcal{C}}^3(A, 1/n, t).$$

The terms in μ are treated similarly. \square

This numerical scheme extends readily to higher powers $p > 4$, where the case $p = 4$ is Theorem 4.2. We state it without proof, leaving the details to the reader. First, define

$$\begin{aligned} X_{n,p}(t) &:= n^{\frac{p-2}{4}} \sum_{j=1}^{\lfloor nt \rfloor} \left[\left| \Delta_n M \left(\frac{j}{n} \right) \right|^{\frac{p}{2}} - \mu_{\frac{p}{2}} \left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^{p/4} \right], \\ \langle X_{n,p} \rangle_t &:= \left(\mu_p - \mu_{\frac{p}{2}}^2 \right) n^{\frac{p}{2}-1} \sum_{j=1}^{\lfloor nt \rfloor} E \left[\left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^{\frac{p}{2}} \mid \mathcal{F}_{\frac{j-1}{n}} \right], \\ V_{n,p}(t) &:= n^{\frac{p}{2}-1} \sum_{j=1}^{\lfloor nt \rfloor} \left| \Delta_n M \left(\frac{j}{n} \right) \right|^p. \end{aligned}$$

Theorem 4.4 (New numerical scheme). Assume that $A(t) \rightarrow \infty$ and $\mathcal{V}_p(t) \rightarrow \infty$ as $t \rightarrow \infty$, with \mathcal{V}_p continuous, for some $p \geq 4$. Under all the conditions of Lemma 4.1, including the finiteness of the $(2p)^{th}$ moment of M , there is a standard Brownian motion

W independent of \mathcal{V}_p such that $(X_{n,p}, \langle X_{n,p} \rangle, V_{n,p}) \overset{\mathcal{C}}{\rightsquigarrow} (W \circ \mathcal{A}_p, \mathcal{A}_p, \mathcal{V}_p)$, where $\mathcal{A}_p = \frac{(\mu_p - \mu_{\frac{p}{2}})}{\mu_p} \mathcal{V}_p$.

Remark 4.2. In their analysis of the asymptotic properties of realized volatility error in investment returns, [4] assumed that $M_t = \int_0^t \sigma_u dW_u$, with square integrable σ independent of Brownian motion W — σ_u^2 is known as the spot volatility or instantaneous volatility at time u . Since $A_t = \int_0^t \sigma_u^2 du$ is continuous, it follows from the proof of Proposition 2.2 that M can also be written as $M = B \circ A$, where B is a Brownian motion independent of A . They also said that one could consider $N(t) = \mu t + \beta A(t)$ but mentioned that it could be difficult to obtain p -variation convergence, specially if $\beta \neq 0$. From our Corollary 4.3, we see that having this extra term does not influence the value of the limit $W \left(\frac{2}{3} \mathcal{V}_4 \right)$ for Y_n , confirming that they can be ignored when estimating realized volatility,

at least below the order of third moments. Note that their setting is a modification of the models introduced in Ané and Geman [2] by adding the drift term μ , while setting business time to $\tau = A$ and scaling parameter to $\gamma = 1$. Note also that from Theorem 4.2, Barndorff-Nielsen and Shephard [4, Theorem 1] can be restated as follows: as $n \rightarrow \infty$,

$$\frac{X_n(1)}{\left\{ 2n \sum_{j=1}^n \left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 \right\}^{\frac{1}{2}}} \xrightarrow{Law} N(0, 1) \text{ and } n \sum_{j=1}^n \left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 \xrightarrow{a.s.} \int_0^1 \sigma^4(s) ds := \mathcal{U}_4(1).$$

Furthermore, $2n \sum_{j=1}^{\lfloor nt \rfloor} \left\{ \Delta_n A \left(\frac{j}{n} \right) \right\}^2 - \langle X_n \rangle_t$ is a martingale that converges to 0, due to the continuity of A and the fact that σ^4 is locally integrable. As a result, $\mathcal{V}_4 = 3\mathcal{U}_4$. Their result is therefore an upshot of Theorem 4.2. More generally, Barndorff-Nielsen et al. [3] prove a CLT for sequences of continuous \mathbb{R}^d -valued semimartingales Y of the following general form — we stick to the case $d = 1$ here for the sake of simplicity:

$$Y(t) = Y(0) + \int_0^t a_s ds + \int_0^t \sigma_s dW(s),$$

with W a standard Brownian motion, a bounded predictable and σ D -valued. For any pair G and H of continuous real-valued functions with at most polynomial growth, the sequence of approximations

$$X_n(G, H)_t = n^{-1} \sum_{j=1}^{\lfloor nt \rfloor} G \left\{ \frac{1}{2} \Delta_n Y \left(\frac{j}{n} \right) \right\} \cdot H \left\{ \frac{1}{2} \Delta_n Y \left(\frac{j+1}{n} \right) \right\}$$

are first shown to obey a Law of Large Numbers:

$$X_n(G, H)_t \xrightarrow{Pr} X(G, H)_t := \int_0^t \rho_{\sigma_s}(G) \rho_{\sigma_s}(H) ds$$

where $\rho_{\sigma_s}(G) := E\{G(Z)\}$ where $Z \sim N(0, \sigma_s)$. Under some additional restrictions on both the stochastic structure of σ_s and the smoothness of G and H , a CLT also ensues — actually in the sense of stable convergence:

$$\frac{1}{2} \{ X_n(G, H)_t - X(G, H)_t \} \xrightarrow{Law} U(G, H)_t$$

where $U(G, H)_t$ is a stochastic integral with respect to another Brownian motion independent of the ambient filtration. A functional version of this result should ensue from our Theorem 4.4 through the same type of arguments, when G and H have at most polynomial growth. We do not pursue this here.

5 Conclusion

We have shown that under weak conditions involving compensators, one can get a CLT for general martingales, and the limiting process is a mixture of a Brownian motion with the limiting compensator of the sequence of martingales. These conditions are easy to verify and are general enough to be applicable to a wide range of situations.

A Auxiliary results

A.1 Some useful results

Lemma A.1 (Lenglart's inequality). Let X be an \mathbb{F} -adapted D -valued process. Suppose that Y is optional, non-decreasing, and that, for any bounded stopping time τ , $E|X(\tau)| \leq E\{Y(\tau)\}$. Then for any stopping time τ and all $\varepsilon, \eta > 0$,

a) if Y is predictable,

$$P(\sup_{s \leq \tau} |X(s)| \geq \varepsilon) \leq \frac{\eta}{\varepsilon} + P(Y(\tau) \geq \eta). \tag{A.1}$$

b) if Y is adapted,

$$P(\sup_{s \leq \tau} |X(s)| \geq \varepsilon) \leq \frac{1}{\varepsilon} [\eta + E\{J_\tau(Y)\}] + P(Y(\tau) \geq \eta). \tag{A.2}$$

Proof. See Jacod and Shiryaev [19, Lemma I.3.30]. □

Proving \mathcal{J}_1 -tightness generally involves the following lemma.

Lemma A.2 (Aldous's criterion). Let $\{X_n\}_{n \geq 1}$ be a sequence of D -valued processes. Suppose that for any sequence of bounded discrete stopping times $\{\tau_n\}_{n \geq 1}$ and for any sequence $\{\delta_n\}_{n \geq 1}$ in $[0, 1]$ converging to 0, the following condition holds, for every $T > 0$: (A) $X_n((\tau_n + \delta_n) \wedge T) - X_n(\tau_n) \xrightarrow{Law} 0$. Then, $\{X_n\}_{n \geq 1}$ is \mathcal{J}_1 -tight, if either of the two following conditions holds:

1. $\{X_n(0)\}_{n \geq 1}$ and $(J_T(X_n))_{n \geq 1}$ are tight;
2. $\{X_n(t)\}_{n \geq 1}$ is tight for any $t \in [0, T]$.

Proof. See Aldous [1], Jacod and Shiryaev [19, Theorem VI.4.5] or for several variants see Ethier and Kurtz [14, Theorem 3.8.6]. Note that condition (1) or condition (2) are necessary for \mathcal{J}_1 -tightness, but not condition (A). □

Now comes the main result about tightness, stated for real-valued processes. Before stating it, set $J(x_1, x_2, x_3) = |x_2 - x_1| \wedge |x_2 - x_3|$, where $x \wedge y = \min(x, y)$. For $x \in D$, set

$$w_{\mathcal{J}_1}(x, \delta, T) = \sup_{0 \leq t_1 < t_2 < t_3 \leq T, t_3 - t_1 < \delta} J\{x(t_1), x(t_2), x(t_3)\}.$$

It follows from [25, Remarques:I.6] and [24, VII, Lemma 6.4] that, for any $T > 0$ and $\delta > 0$,

$$J_T(x) \leq \omega_{\mathcal{C}}(x, \delta, T) \leq J_T(x) + 2\omega_{\mathcal{J}_1}(x, \delta, T). \tag{A.3}$$

Remark A.1. It follows from (A.3) that X_n is \mathcal{C} -tight iff X_n is \mathcal{J}_1 -tight and $J_T(X_n) \xrightarrow{Law} 0$. For if $\epsilon > 0$ is given, then, for any $\delta > 0$,

$$P(\omega_{\mathcal{C}}(X_n, \delta, T) > \epsilon) \leq P(J_T(X_n) > \epsilon/2) + P(\omega_{\mathcal{J}_1}(X_n, \delta, T) > \epsilon/4) \xrightarrow{n \rightarrow \infty} 0.$$

Theorem A.3. Let M_n be a sequence of D -valued square integrable \mathbb{F} -martingales with $M_n(0) = 0$, with quadratic variation $[M_n]$ and compensator $A_n = \langle M_n \rangle$.

- a) Assume that for any $t > 0$, $\limsup_{n \rightarrow \infty} E\{J_t^2(M_n)\} = 0$ holds. Then M_n is \mathcal{C} -tight if and only if $[M_n]$ is \mathcal{C} -tight.
- b) Assume that for any $t > 0$, $\limsup_{n \rightarrow \infty} E\{J_t^2(M_n)\} = 0$ and $J_t(A_n) \xrightarrow{Law} 0$ hold. Then the \mathcal{C} -tightness of $[M_n]$ implies that of A_n .
- c) Assume that for any $t > 0$, $J_t(M_n) \xrightarrow{Law} 0$ hold. Then the \mathcal{C} -tightness of A_n implies that of both M_n and $[M_n]$.

Remark A.2. If every M_n is continuous, then M_n is \mathcal{C} -tight if and only if A_n is \mathcal{C} -tight, by statement a), since both $J_t(M_n) = 0$ and $[M_n] = A_n$ then hold — this goes back to Rebolledo [25]. Without the continuity assumption on M_n , this equivalence no longer holds. Note also that c) follows from [19, Theorem 4.13].

Proof. The idea of the proof is to show \mathcal{J}_1 -tightness, and then use Remark A.1. For statement a), suppose first that M_n is \mathcal{C} -tight. Set $X_n(t) = [M_n]_{t+\tau_n} - [M_n]_{\tau_n}$ and $Y_n(t) = \sup_{0 \leq s \leq t} \{M_n(s + \tau_n) - M_n(\tau_n)\}^2$, where τ_n is a stopping time uniformly bounded by T for any n . Then, for any bounded stopping time τ , $E\{X_n(\tau)\} \leq E\{Y_n(\tau)\}$. Let δ be a bounded stopping time. By (A.2) of Lemma A.1, we have, for any $\varepsilon, \eta > 0$,

$$\begin{aligned} P([M_n]_{\tau_n+\delta_n} - [M_n]_{\tau_n} \geq \varepsilon) &\leq \frac{\eta}{\varepsilon} + \frac{1}{\varepsilon} E\{J_{\delta_n}(Y_n)\} + P(Y_n(\delta_n) \geq \eta) \\ &\leq \frac{\eta}{\varepsilon} + \frac{1}{\varepsilon} E\{J_{T+1}^2(M_n)\} + P\{\omega_{\mathcal{C}}(M_n, \delta_n, T+1) > \sqrt{\eta}\}. \end{aligned} \tag{A.4}$$

Since M_n is \mathcal{C} -tight, it follows that $P\{\omega_{\mathcal{C}}(M_n, \delta_n, T+1) > \sqrt{\eta}\} \rightarrow 0$ as $n \rightarrow \infty$. Set $\eta = \varepsilon^2$. Then $\limsup_{n \rightarrow \infty} P\{[M_n]_{\tau_n+\delta_n} - [M_n]_{\tau_n} \geq \varepsilon\} \leq \varepsilon$, showing that $[M_n]$ meets both conditions (A) and (1) of Lemma A.2, since $J_T([M_n]) = J_T^2(M_n)$. Hence $[M_n]$ is \mathcal{J}_1 -tight. The fact that $[M_n]$ is \mathcal{C} -tight follows from Remark A.1 and $J_T([M_n]) \xrightarrow{Law} 0$. To complete the proof of a), assume now that $[M_n]$ is \mathcal{C} -tight. Using Lemma A.1 yields

$$\begin{aligned} P\{|M_n(\tau_n + \delta_n) - M_n(\tau_n)| \geq \varepsilon\} &\leq \frac{\eta}{\varepsilon^2} + \frac{1}{\varepsilon^2} E\{J_{\delta_n}([M_n]_{\tau_n+\cdot} - [M_n]_{\tau_n})\} + P\{[M_n]_{\tau_n+\delta_n} - [M_n]_{\tau_n} > \eta\} \\ &\leq \frac{\eta}{\varepsilon^2} + \frac{1}{\varepsilon^2} E\{J_{T+1}([M_n])\} + P\{\omega_{\mathcal{C}}([M_n], \delta_n, T+1) > \eta\}. \end{aligned}$$

Choosing $\eta = \varepsilon^3$, both conditions (A) and (1) of Lemma A.2 are met and M_n is \mathcal{J}_1 -tight. Since $J_T(M_n) \xrightarrow{Law} 0$, it follows from Remark A.1 that M_n is \mathcal{C} -tight. For statement b), (A.4) becomes

$$P(A_n(\tau_n + \delta_n) - A_n(\tau_n) \geq \varepsilon) \leq \frac{\eta}{\varepsilon} + \frac{1}{\varepsilon} E\{J_{T+1}^2(M_n)\} + P\{\omega_{\mathcal{C}}([M_n], \delta_n, T+1) > \eta\},$$

showing that A_n meets both conditions (A) and (1) of Lemma A.2. As a result, A_n is \mathcal{J}_1 -tight. Since $J_T(A_n) \xrightarrow{Law} 0$, A_n is also \mathcal{C} -tight, using Remark A.1. Finally, for statement c), use (A.1) of Lemma A.1 instead to prove that each of M_n and $[M_n]$ meets both conditions (A) and (1) of Lemma A.2. As a result, both M_n and $[M_n]$ are \mathcal{J}_1 -tight. Since $J_T(M_n) \xrightarrow{Law} 0$, M_n is \mathcal{C} -tight by Remark A.1, and so is $[M_n]$ by a). \square

Proposition A.4. Let D -valued non-decreasing processes A_n and some continuous process A be such that $A_n \xrightarrow{f.d.d.} A$. Then A_n is \mathcal{C} -tight and $A_n \xrightarrow{\mathcal{C}} A$.

Proof. For any fixed $T > 0$ and $\delta > 0$ there holds, with i running only through the non-negative integers,

$$\begin{aligned} \limsup_{n \rightarrow \infty} P(\omega_{\mathcal{C}}(A_n, \delta, T) \geq \epsilon) &\leq \limsup_{n \rightarrow \infty} P\left(3 \max_{0 \leq i \leq T/\delta} \sup_{i\delta \leq s \leq T \wedge (i+1)\delta} |A_n(s) - A_n(i\delta)| \geq \epsilon\right) \\ &\leq \limsup_{n \rightarrow \infty} P\left(\bigcup_{0 \leq i \leq T/\delta} \{|A_n(T \wedge (i+1)\delta) - A_n(i\delta)| \geq \epsilon/3\}\right) \\ &\leq P\left(\bigcup_{0 \leq i \leq T/\delta} \{|A(T \wedge (i+1)\delta) - A(i\delta)| \geq \epsilon/3\}\right) \leq P(\omega_{\mathcal{C}}(A, \delta, T) \geq \epsilon/3), \end{aligned}$$

using convergence in law. Hence A_n is \mathcal{C} -tight since A is continuous. \square

A.2 Expression for μ_v

Since $\sum_{a \leq x \leq b} \{TG^2(x) - G^2(x)\} = 0$, $\mu_v = \sum_{x \in \mathbb{Z}} v(x) = \sum_{x \in \mathbb{Z}} \{2V(x)G(x) - V^2(x)\}$ follows.

One can check that $\sum_y \sum_z |z - y|V(y)V(z) = 4 \sum_y yV(y)H(y) + 2 \sum_y yV^2(y)$, where $H(x) = \sum_{y < x} V(y)$. Note that $H \equiv 0$ outside $[a, b]$. Now, $G(x) = -2xH(x) + 2 \sum_{y < x} yV(y) - c$. As a result,

$$\begin{aligned} \mu_v &= -4 \sum_x xV(x)H(x) + 4 \sum_x \sum_{y < x} yV(y)V(x) - \sum_x V^2(x) \\ &= -8 \sum_x xV(x)H(x) - 4 \sum_x xV^2(x) - \sum_x V^2(x), \end{aligned}$$

which is the expression of Equation 10 in [12]. Furthermore, since $0 = \sum_x V^2(x) +$

$2 \sum_x \sum_{y < x} V(y)V(x) = \sum_x V^2(x) + 2 \sum_x V(x)H(x)$, one also gets

$$\begin{aligned} 2 \sum_x H^2(x) &= 2 \sum_{a \leq x \leq b} \sum_{a \leq y < x} \sum_{a \leq z < x} V(y)V(z) = 2 \sum_{a \leq y \leq b} \sum_{a \leq z \leq b} V(y)V(z) \sum_{b \geq x > \max(y,z)} 1 \\ &= 2 \sum_{a \leq y \leq b} \sum_{a \leq z \leq b} V(y)V(z) \{b - \max(y, z)\} \\ &= 4 \sum_z \sum_{y < z} V(y)V(z)(b - z) + 2 \sum_y V^2(y)(b - y) \\ &= -4 \sum_z zH(z)V(z) - 2 \sum_y yV^2(y), \end{aligned}$$

proving the expressions $c_V^2 = 2 \sum_x H^2(x)$ and $2c_V^2 = \mu_v + \sum_x V^2(x)$. Note that $\mu_v = 2B_V$,

where $B_V = \frac{1}{2} \sum_{x \in \mathbb{Z}} \{2H(x) + V(x)\}^2$, as defined in [27].

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