

**A NEW HYBRID-EXTRAGRADIENT METHOD FOR GENERALIZED
MIXED EQUILIBRIUM PROBLEMS, FIXED POINT PROBLEMS
AND VARIATIONAL INEQUALITY PROBLEMS**

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Dedicated to Professor Wataru Takahashi on the occasion of his 65th birthday

Abstract. In this paper, we introduce a new iterative scheme based on the hybrid method and the extragradient method for finding a common element of the set of solutions of a generalized mixed equilibrium problem and the set of fixed points of a nonexpansive mapping and the set of the variational inequality for a monotone, Lipschitz-continuous mapping. We obtain a strong convergence theorem for the sequences generated by these processes in Hilbert spaces. Based on this result, we also get some new and interesting results. The results in this paper generalize, extend and unify some well-known strong convergence theorems in the literature.

1. INTRODUCTION

Let H be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and induced norm $\|\cdot\|$ and let C be a nonempty closed convex subset of H . let $B : C \rightarrow H$ be a nonlinear mapping and let $\varphi : C \rightarrow R$ be a function and F be a bifunction from $C \times C$ to R , where R is the set of real numbers. Then, we consider the following generalized mixed equilibrium problem: Finding $x \in C$ such that

$$(1.1) \quad F(x, y) + \varphi(y) - \varphi(x) + \langle Bx, y - x \rangle \geq 0, \forall y \in C.$$

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The set of solutions of (1.1) is denoted by $GMEP(F, \varphi, B)$.

If $B = 0$, then the generalized mixed equilibrium problem (1.1) becomes the following mixed equilibrium problem :

$$(1.2) \quad \text{Finding } x \in C \text{ such that } F(x, y) + \varphi(y) - \varphi(x) \geq 0, \forall y \in C.$$

Problem (1.2) was studied by Ceng and Yao [1]. The set of solutions of (1.2) is denoted by $MEP(F, \varphi)$.

If $\varphi = 0$, then the generalized mixed equilibrium problem (1.1) becomes the following generalized equilibrium problem:

$$(1.3) \quad \text{Finding } x \in C \text{ such that } F(x, y) + \langle Bx, y - x \rangle \geq 0, \forall y \in C.$$

Problem (1.2) was studied by Takahashi and Takahashi [2]. The set of solutions of (1.3) is denoted by $GEP(F, B)$.

If $\varphi = 0$ and $B = 0$, then the generalized mixed equilibrium problem (1.1) becomes the following equilibrium problem:

$$(1.4) \quad \text{Finding } x \in C \text{ such that } F(x, y) \geq 0, \forall y \in C.$$

The set of solutions of (1.4) is denoted by $EP(F)$.

If $F(x, y) = 0$ for all $x, y \in C$, the generalized mixed equilibrium problem (1.1) becomes the following generalized variational inequality problem:

$$(1.5) \quad \text{Finding } x \in C \text{ such that } \varphi(y) - \varphi(x) + \langle Bx, y - x \rangle \geq 0, \forall y \in C.$$

The set of solutions of (1.5) is denoted by $GVI(C, B, \varphi)$.

If $\varphi = 0$ and $F(x, y) = 0$ for all $x, y \in C$, the generalized mixed equilibrium problem (1.1) becomes the following variational inequality problem:

$$(1.6) \quad \text{Finding } x \in C \text{ such that } \langle Bx, y - x \rangle \geq 0, \forall y \in C.$$

The set of solutions of (1.6) is denoted by $VI(C, B)$.

If $B = 0$ and $F(x, y) = 0$ for all $x, y \in C$, the generalized mixed equilibrium problem (1.1) becomes the following minimize problem:

$$(1.7) \quad \text{Finding } x \in C \text{ such that } \varphi(y) - \varphi(x) \geq 0, \forall y \in C.$$

The set of solutions of (1.7) is denoted by $Argmin(\varphi)$.

The problem (1.1) is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, minimax problems, Nash equilibrium problem in noncooperative games and others; see for instance, [1-4].

Recall that a mapping S of a closed convex subset C of H is nonexpansive [5] if there holds that

$$\|Sx - Sy\| \leq \|x - y\| \text{ for all } x, y \in C.$$

We denote the set of fixed points of S by $Fix(S)$. Ceng and Yao [1] introduced an iterative scheme for finding a common element of the set of solution of problem (1.2) and the set of common fixed points of a family of infinitely nonexpansive mappings in a Hilbert space and obtained a strong convergence theorem. Takahashi and Takahashi [2] introduced an iterative scheme for finding a common element of the set of solution of problem (1.3) and the set of fixed points of a nonexpansive mapping in a Hilbert space and proved a strong convergence theorem.

Some methods have been proposed to solve the problem (1.4); see, for instance, [3, 4, 6-9, 26 and the references therein]. Recently, Combettes and Hirstoaga [6] introduced an iterative scheme of finding the best approximation to the initial data when $EP(F)$ is nonempty and proved a strong convergence theorem. Takahashi and Takahashi [7] introduced an iterative scheme by the viscosity approximation method for finding a common element of the set of solutions of problem (1.4) and the set of fixed points of a nonexpansive mapping in a Hilbert space proved a strong convergence theorem. Su, Shang and Qin [8] introduced the following iterative scheme by the viscosity approximation method for finding a common element of the set of solutions of problem (1.4) and the set of fixed points of a nonexpansive mapping and the set of solutions of the variational inequality problem for an α -inverse strongly monotone mapping in a Hilbert space. Starting with an arbitrary $x_1 \in H$, define sequences $\{x_n\}$ and $\{u_n\}$ by

$$(1.8) \quad \begin{cases} F(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) SP_C(u_n - \lambda_n A u_n), \forall n \in N. \end{cases}$$

They proved that under certain appropriate conditions imposed on $\{\alpha_n\}$, $\{r_n\}$ and $\{\lambda_n\}$, the sequences $\{x_n\}$ and $\{u_n\}$ generated by (1.8) converge strongly to $z \in Fix(S) \cap EP(F) \cap VI(C, A)$, where $z = P_{Fix(S) \cap EP(F) \cap VI(C, A)} f(z)$. Tada and Takahashi [9] introduced the following iterative scheme by the hybrid method for finding a common element of the set of solutions of problem (1.4) and the set of fixed points of a nonexpansive mapping in a Hilbert space. Starting with an arbitrary $x_1 \in H$, define sequences $\{x_n\}$ and $\{u_n\}$ by

$$(1.9) \quad \begin{cases} u_n \in C, F(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ w_n = (1 - \alpha_n)x_n + \alpha_n S u_n, \\ C_n = \{z \in H : \|w_n - z\| \leq \|x_n - z\|\}, \\ Q_n = \{z \in H : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{cases}$$

They proved that under certain appropriate conditions imposed on $\{\alpha_n\}$ and $\{r_n\}$, the sequences $\{x_n\}$ and $\{u_n\}$ generated by (1.9) converge strongly to $P_{\text{Fix}(S) \cap EP(F)}x$. Generally speaking, the algorithm suggested by Tada and Takahashi is based on the well-known type of method, namely, on the so-called hybrid or "outer-approximation" for solving fixed point problem. The idea of "hybrid" or "outer-approximation" types of methods was originally introduced by Haugazeau in 1968 and was successfully generalized and extended in recent papers of Bauschke and Combettes [10], [11], Burachik, Lopes and Svaiter [12], Combettes [13], Nakajo and Takahashi [14], and Solodov and Svaiter [15], Kikkawa and Takahashi [16], Iiduka and Takahashi [17].

On the other hand, for solving the variational inequality problem in the finite-dimensional Euclidean R^n , Korpelevich [18] introduced the following so-called extragradient method:

$$(1.10) \quad \begin{cases} x_1 = x \in C \\ y_n = P_C(x_n - \lambda Ax_n), \\ x_{n+1} = P_C(x_n - \lambda Ay_n), \end{cases}$$

for every $n = 0, 1, 2, \dots$, where $\lambda \in (0, \frac{1}{k})$. He showed that if $VI(C, A)$ is nonempty, then the sequences $\{x_n\}$ and $\{y_n\}$, generated by (1.10), converge to the same point $z \in VI(C, A)$. The idea of the extragradient iterative process introduced by Korpelevich was successfully generalized and extended not only in Euclidean but also in Hilbert and Banach spaces; see, e. g., the recent papers of He, Yang and Yuan [19], Garciga Otero and Iuzem [20], Solodov and Svaiter [21], Solodov [22]. Moreover, Zeng and Yao [23] and Nadezhkina and Takahashi [24] introduced an iterative process based on the extragradient method for finding the common element of the set of fixed points of nonexpansive mappings and the set of solutions of variational inequality problem for a monotone, Lipschitz-continuous mapping. Yao and Yao [25] introduced an iterative process based on the extragradient method for finding the common element of the set of fixed points of nonexpansive mappings and the set of solutions of variational inequality problem for an α -inverse strongly monotone mapping. Plubtieng and Punpaeng [26] introduced an iterative process based on the extragradient method for finding the common element of the set of fixed points of nonexpansive mappings, the set of an equilibrium problem and the set of solutions of variational inequality problem for α -inverse strongly monotone mappings.

Very recently, by combine a hybrid method with an extragradient method, Nadezhkina and Takahashi [27] introduced an iterative process as follows:

$$(1.11) \quad \begin{cases} x_1 = x \in C, \\ y_n = P_C(x_n - \lambda_n Ax_n), \\ z_n = \beta_n x_n + (1 - \beta_n)SP_C(x_n - \lambda_n Ay_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{cases}$$

for every $n = 1, 2, \dots$. They proved that under certain appropriate conditions imposed on $\{\beta_n\}$ and $\{\lambda_n\}$, the sequences $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ generated by (1.11) converge strongly to $z \in \text{Fix}(S) \cap VI(C, A)$. Ceng, Hadjisavvas and Yao [28] introduced the following iterative process by combining hybrid -extragradient method for finding a common element of the set of fixed points of a nonexpansive mapping and the set of solutions of the variational inequality problem for a monotone, Lipschitz-continuous mapping.

$$(1.12) \quad \begin{cases} x_1 = x \in C, \\ y_n = (1 - \gamma_n)x_n + \gamma_n P_C(x_n - \lambda_n Ax_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n SP_C(x_n - \lambda_n Ay_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|Ax_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{cases}$$

for every $n = 1, 2, \dots$. They proved that under certain appropriate conditions imposed on $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$ and $\{\lambda_n\}$, the sequences $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ generated by (1.12) converge strongly to $z \in \text{Fix}(S) \cap VI(C, A)$. If $\gamma_n = 1$ and $\alpha_n = 0$ for every $n = 1, 2, \dots$, then (1.12) becomes (1.11). Ceng, Hadjisavvas and Yao pointed up taking more general sequences $\{\alpha_n\}$, $\{\beta_n\}$ and $\{\gamma_n\}$ might improve the rate of convergence to a solution.

In the present paper, by using the well-known KKM technique we derive an important lemma which is a foundation for studying the generalized mixed equilibrium problem. Then, we introduce a new iterative scheme based on the extragradient method and the hybrid method for finding a common element of the set of solutions of a generalized mixed equilibrium problem, the set of fixed points of a nonexpansive mapping and the set of the variational inequality for a monotone, Lipschitz-continuous mapping. We obtain a strong convergence theorem for the sequences generated by these processes. Based on this result, we also get some new and interesting results. The results in this paper generalize, extend and unify some well-known strong convergence theorems in the literature.

2. PRELIMINARIES

Let H be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$. Let C be a nonempty closed convex subset of H . Let symbols \rightarrow and \rightharpoonup denote strong and weak convergence, respectively. In a real Hilbert space H , it is well known that

$$\| \lambda x + (1 - \lambda)y \|^2 = \lambda \|x\|^2 + (1 - \lambda) \|y\|^2 - \lambda(1 - \lambda) \|x - y\|^2$$

for all $x, y \in H$ and $\lambda \in [0, 1]$.

For any $x \in H$, there exists a unique nearest point in C , denoted by $P_C(x)$, such that $\|x - P_C(x)\| \leq \|x - y\|$ for all $y \in C$. The mapping P_C is called the metric projection of H onto C . We know that P_C is a nonexpansive mapping from H onto C . It is also known that $P_C x \in C$ and

$$(2.1) \quad \langle x - P_C(x), P_C(x) - y \rangle \geq 0$$

for all $x \in H$ and $y \in C$.

It is easy to see that (2.1) is equivalent to

$$(2.2) \quad \|x - y\|^2 \geq \|x - P_C(x)\|^2 + \|y - P_C(x)\|^2$$

for all $x \in H$ and $y \in C$.

A mapping A of C into H is called monotone if

$$\langle Ax - Ay, x - y \rangle \geq 0$$

for all $x, y \in C$. A mapping A of C into H is called α -inverse-strongly monotone if there exists a positive real number α such that

$$\langle x - y, Ax - Ay \rangle \geq \alpha \|Ax - Ay\|^2$$

for all $x, y \in C$. A mapping $A : C \rightarrow H$ is called k -Lipschitz-continuous if there exists a positive real number k such that

$$\|Ax - Ay\| \leq k \|x - y\|$$

for all $x, y \in C$. It is easy to see that if A is an α -inverse-strongly-monotone mapping, then A is monotone and Lipschitz-continuous. The converse is not true in general. The class of α -inverse-strongly-monotone mappings does not contain some important classes of mappings even in a finite-dimensional case. For example, if the matrix in the corresponding linear complementarity problem is positively semidefinite, but not positively definite, then the mapping A will be monotone and Lipschitz-continuous, but not α -inverse-strongly-monotone (see [27]).

Let A be a monotone mapping of C into H . In the context of the variational inequality problem the characterization of projection (2.1) implies the following:

$$u \in VI(C, A) \Rightarrow u = P_C(u - \lambda Au), \lambda > 0,$$

and

$$u = P_C(u - \lambda Au) \text{ for some } \lambda > 0 \Rightarrow u \in VI(C, A).$$

It is also known that H satisfies the Opial's condition [29], i.e., for any sequence $\{x_n\} \subset H$ with $x_n \rightharpoonup x$, the inequality

$$\liminf_{n \rightarrow \infty} \|x_n - x\| < \liminf_{n \rightarrow \infty} \|x_n - y\|$$

holds for every $y \in H$ with $x \neq y$.

A set-valued mapping $T : H \rightarrow 2^H$ is called monotone if for all $x, y \in H$, $f \in Tx$ and $g \in Ty$ imply $\langle x - y, f - g \rangle \geq 0$. A monotone mapping $T : H \rightarrow 2^H$ is maximal if its graph $G(T)$ of T is not properly contained in the graph of any other monotone mapping. It is known that a monotone mapping T is maximal if and only if for $(x, f) \in H \times H$, $\langle x - y, f - g \rangle \geq 0$ for every $(y, g) \in G(T)$ implies $f \in Tx$. Let A be a monotone, k -Lipschitz-continuous mapping of C into H and let $N_C v$ be normal cone to C at $v \in C$, i.e, $N_C v = \{w \in H : \langle v - u, w \rangle \geq 0, \forall u \in C\}$. Define

$$Tv = \begin{cases} Av + N_C v & \text{if } v \in C, \\ \emptyset & \text{if } v \notin C. \end{cases}$$

Then T is maximal monotone and $0 \in Tv$ if and only if $v \in VI(C, A)$ (see [30]).

For each $B \subseteq H$, we denote by $conv(B)$ the convex hull of B . A multivalued mapping $G : B \rightarrow 2^H$ is said to be a KKM map if, for every finite subset $\{x_1, x_2, \dots, x_n\} \subseteq B$,

$$conv(x_1, x_2, \dots, x_n) \subseteq \bigcup_{i=1}^n G(x_i).$$

We shall use the following results in the sequel.

Lemma 2.1. ([31]). *Let B be a nonempty subset of a Hausdorff topological vector space X and let $G : B \rightarrow 2^X$ be a KKM map. If $G(x)$ is closed for all $x \in B$ and is compact for at least one $x \in B$, then $\bigcap_{x \in B} G(x) \neq \emptyset$.*

Lemma 2.2. (see Proposition 5.3 in [32]). *Let C be a nonempty closed convex subset of a strictly convex Banach space X and $S : C \rightarrow C$ a nonexpansive mapping with $Fix(S) \neq \emptyset$. Then $Fix(S)$ is closed and convex.*

For solving the generalized mixed equilibrium problem and the mixed equilibrium problem, let us give the following assumptions for the bifunction F , φ and the set C :

- (A1) $F(x, x) = 0$ for all $x \in C$;
- (A2) F is monotone, i.e. $F(x, y) + F(y, x) \leq 0$ for any $x, y \in C$;
- (A3) for each $y \in C$, $x \mapsto F(x, y)$ is weakly upper semicontinuous;
- (A4) for each $x \in C$, $y \mapsto F(x, y)$ is convex;

(A5) for each $x \in C$, $y \mapsto F(x, y)$ is lower semicontinuous;

(B1) For each $x \in H$ and $r > 0$, there exist a bounded subset $D_x \subseteq C$ and $y_x \in C$ such that for any $z \in C \setminus D_x$,

$$F(z, y_x) + \varphi(y_x) - \varphi(z) + \frac{1}{r} \langle y_x - z, z - x \rangle < 0;$$

(B2) C is a bounded set;

(B3) For each $x \in H$ and $r > 0$, there exist a bounded subset $D_x \subseteq C$ and $y_x \in C$ such that for any $z \in C \setminus D_x$,

$$\varphi(y_x) - \varphi(z) + \frac{1}{r} \langle y_x - z, z - x \rangle < 0;$$

(B4) For each $x \in H$ and $r > 0$, there exist a bounded subset $D_x \subseteq C$ and $y_x \in C$ such that for any $z \in C \setminus D_x$,

$$F(z, y_x) + \frac{1}{r} \langle y_x - z, z - x \rangle < 0.$$

Lemma 2.3. *Let C be a nonempty closed convex subset of H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A4) and let $\varphi : C \rightarrow R$ be a proper lower semicontinuous and convex function. For $r > 0$ and $x \in H$, define a mapping $T_r : H \rightarrow C$ as follows.*

$$T_r(x) = \{z \in C : F(z, y) + \varphi(y) - \varphi(z) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \forall y \in C\}$$

for all $x \in H$. Assume that either (B1) or (B2) holds. Then, the following results hold:

- (1) For each $x \in H$, $T_r(x) \neq \emptyset$;
- (2) T_r is single-valued;
- (3) T_r is firmly nonexpansive, i.e, for any $x, y \in H$,

$$\|T_r(x) - T_r(y)\|^2 \leq \langle T_r(x) - T_r(y), x - y \rangle;$$

- (4) $Fix(T_r) = MEF(F, \varphi)$;
- (5) $MEF(F, \varphi)$ is closed and convex.

Proof. Let x_0 be any given point in H . For each $y \in C$, we define

$$G(y) = \{z \in C : F(z, y) + \varphi(y) - \varphi(z) + \frac{1}{r} \langle y - z, z - x_0 \rangle \geq 0\}.$$

Note that for each $y \in C$, $G(y)$ is nonempty since $y \in G(y)$. We shall prove that G is a KKM map. Suppose that there exist a finite subset $\{y_1, y_2, \dots, y_n\}$ of C and

$\mu_i \geq 0$ for all $i = 1, 2, \dots, n$ with $\sum_{i=1}^n \mu_i = 1$ such that $\hat{z} = \sum_{i=1}^n \mu_i y_i \notin G(y_i)$ for each $i = 1, 2, \dots, n$. Then we have

$$F(\hat{z}, y_i) + \varphi(y_i) - \varphi(\hat{z}) + \frac{1}{r} \langle y_i - \hat{z}, \hat{z} - x_0 \rangle < 0$$

for each $i = 1, 2, \dots, n$. By (A4) and the convexity of φ , we have

$$\begin{aligned} 0 &= F(\hat{z}, \hat{z}) + \varphi(\hat{z}) - \varphi(\hat{z}) + \frac{1}{r} \langle \hat{z} - \hat{z}, \hat{z} - x_0 \rangle \\ &\leq \sum_{i=1}^n \mu_i [F(\hat{z}, y_i) + \varphi(y_i) - \varphi(\hat{z})] + \frac{1}{r} \left[\sum_{i=1}^n \mu_i \langle y_i - \hat{z}, \hat{z} - x_0 \rangle \right] < 0 \end{aligned}$$

which is a contradiction. Hence, G is a KKM map. Note that $\overline{G(y)}^w$ (the weak closure of $G(y)$) is a weakly closed subset of C for each $y \in C$. Moreover, if (B2) holds, then $\overline{G(y)}^w$ is also weakly compact for each $y \in C$. If (B1) holds, then for $x_0 \in H$, there exist a bounded subset $D_{x_0} \subseteq C$ and $y_{x_0} \in C$ such that for any $y \in C \setminus D_{x_0}$,

$$F(z, y_{x_0}) + \varphi(y_{x_0}) - \varphi(z) + \frac{1}{r} \langle y_{x_0} - z, z - x_0 \rangle < 0.$$

This shows that

$$G(y_{x_0}) = \{z \in C : F(z, y_{x_0}) + \varphi(y_{x_0}) - \varphi(z) + \frac{1}{r} \langle y_{x_0} - z, z - x_0 \rangle \geq 0\} \subseteq D_{x_0}.$$

And hence $\overline{G(y_{x_0})}^w$ is weakly compact. Thus, in both cases, we can use Lemma 2.1 and have $\bigcap_{y \in C} \overline{G(y)}^w \neq \emptyset$.

Next we shall prove that $\overline{G(y)}^w = G(y)$ for each $y \in C$; i.e., $G(y)$ is weakly closed. Let $z \in \overline{G(y)}^w$ and z_m be a sequence in $G(y)$ such that $z_m \rightharpoonup z$. Then,

$$F(z_m, y) + \varphi(y) - \varphi(z_m) + \frac{1}{r} \langle y - z_m, z_m - x_0 \rangle \geq 0$$

Since $\|\cdot\|^2$ is weakly lower semicontinuous, we have

$$\begin{aligned} &\limsup_{m \rightarrow \infty} \langle y - z_m, z_m - x_0 \rangle \\ &= \limsup_{m \rightarrow \infty} [\langle y - z_m, -x_0 \rangle + \langle y, z_m \rangle - \|z_m\|^2] \\ &= \lim_{m \rightarrow \infty} \langle z_m - y, x_0 \rangle + \lim_{m \rightarrow \infty} \langle y, z_m \rangle - \liminf_{m \rightarrow \infty} \|z_m\|^2 \\ &\leq \langle z - y, x_0 \rangle + \langle y, z \rangle - \|z\|^2 \\ &= \langle z - y, x_0 - z \rangle. \end{aligned}$$

It follows from (A3) and the weak lower semicontinuity of φ that

$$\begin{aligned} 0 &\leq \limsup_{m \rightarrow \infty} [F(z_m, y) + \varphi(y) - \varphi(z_m) + \frac{1}{r} \langle y - z_m, z_m - x_0 \rangle] \\ &\leq \limsup_{m \rightarrow \infty} [F(z_m, y) + \varphi(y)] - \liminf_{m \rightarrow \infty} \varphi(z_m) + \frac{1}{r} \limsup_{m \rightarrow \infty} \langle y - z_m, z_m - x_0 \rangle \\ &\leq F(z, y) + \varphi(y) - \varphi(z) + \frac{1}{r} \langle z - y, x_0 - z \rangle. \end{aligned}$$

This implies that $z \in G(y)$. Hence, $G(y)$ is weakly closed. Hence, $T_r(x_0) = \bigcap_{y \in C} G(y) = \bigcap_{y \in C} \overline{G(y)}^w \neq \emptyset$. Hence, from the arbitrariness of x_0 , we know that $T_r(x) \neq \emptyset$, $\forall x \in H$. We claim that T_r is single-valued. Indeed, for $x \in H$ and $r > 0$, let $z_1, z_2 \in T_r(x)$. Then,

$$F(z_1, z_2) + \varphi(z_2) - \varphi(z_1) + \frac{1}{r} \langle z_2 - z_1, z_1 - x \rangle \geq 0$$

and

$$F(z_2, z_1) + \varphi(z_1) - \varphi(z_2) + \frac{1}{r} \langle z_1 - z_2, z_2 - x \rangle \geq 0.$$

Adding the two inequalities, we have

$$F(z_1, z_2) + F(z_2, z_1) + \frac{1}{r} \langle z_2 - z_1, z_1 - z_2 \rangle \geq 0.$$

From (A2) and $r > 0$, we have

$$\langle z_2 - z_1, z_1 - z_2 \rangle \geq 0.$$

So, we have $z_1 = z_2$.

Now we claim that T_r is a firmly nonexpansive-type map. Indeed, for $x, y \in H$, we have

$$F(T_r(x), T_r(y)) + \varphi(T_r(y)) - \varphi(T_r(x)) + \frac{1}{r} \langle T_r(y) - T_r(x), T_r(x) - x \rangle \geq 0$$

and

$$F(T_r(y), T_r(x)) + \varphi(T_r(x)) - \varphi(T_r(y)) + \frac{1}{r} \langle T_r(x) - T_r(y), T_r(y) - y \rangle \geq 0.$$

Adding the two inequalities, we have

$$F(T_r(x), T_r(y)) + F(T_r(y), T_r(x)) + \frac{1}{r} \langle T_r(y) - T_r(x), T_r(x) - T_r(y) - x + y \rangle \geq 0.$$

From (A2) and $r > 0$, we have

$$\langle T_r(y) - T_r(x), T_r(x) - T_r(y) - (x - y) \rangle \geq 0.$$

Therefore, we have

$$\|T_r(x) - T_r(y)\|^2 \leq \langle T_r(x) - T_r(y), x - y \rangle.$$

Next we claim that $Fix(T_r) = MEF(F, \varphi)$. Indeed, we have the following:

$$\begin{aligned} u \in Fix(T_r) &\Leftrightarrow u = T_r(u) \\ &\Leftrightarrow F(u, y) + \varphi(y) - \varphi(u) + \frac{1}{r} \langle y - u, u - u \rangle \geq 0, \forall y \in C \\ &\Leftrightarrow F(u, y) \geq 0, \forall y \in C \\ &\Leftrightarrow u \in MEF(F, \varphi). \end{aligned}$$

At last, we claim that $MEF(F, \varphi)$ is closed convex. Indeed, Since T_r is firmly non-expansive, T_r is also nonexpansive. By Lemma 2.2, we know that $MEF(F, \varphi) = Fix(T_r)$ is closed and convex.

Remark 2.1.

- (i) Lemma 2.3 generalizes and extends Corollary 5 in [4] and Lemma 2.12 in [6], Lemma 2.1 and 2.2 in [7] which are the foundations for the algorithms of equilibrium problems. And hence Lemma 2.3 plays a key role in the research of algorithms for problems (1.1) and (1.2).
- (ii) We observed that in Lemma 3.1 in [1], the condition of the sequentially continuity from the weak topology to the strong topology for the derivative K' of the function $K : C \rightarrow R$ is a very strong condition. Even if $K(x) = \frac{\|x\|^2}{2}$ and $\eta(x, y) = x - y$, then $K'(x) = x$ is not sequentially continuous from the weak topology to the strong topology.

3. STRONG CONVERGENCE THEOREMS

In this section, we show a strong convergence of an iterative algorithm based on extragradient method and hybrid method which solves the problem of finding a common element of the set of solutions of a generalized mixed equilibrium problem, the set of fixed points of a nonexpansive mapping and the set of the variational inequality for a monotone, Lipschitz-continuous mapping in a Hilbert space.

Theorem 3.1. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let A be a monotone and k -Lipschitz-continuous mapping of C into H and B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\Omega = Fix(S) \cap VI(C, A) \cap GMEP(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
- (iii) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_\Omega(x)$.

Proof. It is obvious that C_n is closed and Q_n is closed and convex for every $n = 1, 2, \dots$. Since

$$C_n = \{z \in H : \|z_n - x_n\|^2 + 2\langle z_n - x_n, x_n - z \rangle \leq (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\},$$

we also have that C_n is convex for every $n = 1, 2, \dots$. It is easy to see that $\langle x_n - z, x - x_n \rangle \geq 0$ for all $z \in Q_n$ and by (2.1), $x_n = P_{Q_n} x$. Put $t_n = P_C(u_n - \lambda_n A y_n)$ for every $n = 1, 2, \dots$. Let $u \in \Omega$ and let $\{T_{r_n}\}$ be a sequence of mappings defined as in Lemma 2.3. Then $u = P_C(u - \lambda_n A u) = T_{r_n}(u - r_n B u)$. From $u_n = T_{r_n}(x_n - r_n B x_n) \in C$ and the α -inverse-strongly monotonicity of B , we have

$$\begin{aligned} \|u_n - u\|^2 &= \|T_{r_n}(x_n - r_n B x_n) - T_{r_n}(u - r_n B u)\|^2 \\ &\leq \|x_n - r_n B x_n - (u - r_n B u)\|^2 \\ &\leq \|x_n - u\|^2 - 2r_n \langle x_n - u, B x_n - B u \rangle + r_n^2 \|B x_n - B u\|^2 \\ (3.1) \quad &\leq \|x_n - u\|^2 - 2r_n \alpha \|B x_n - B u\|^2 + r_n^2 \|B x_n - B u\|^2 \\ &= \|x_n - u\|^2 + r_n(r_n - 2\alpha) \|B x_n - B u\|^2 \\ &\leq \|x_n - u\|. \end{aligned}$$

From (2.2), the monotonicity of A , and $u \in VI(C, A)$, we have

$$\begin{aligned} & \|t_n - u\|^2 \leq \|u_n - \lambda_n Ay_n - u\|^2 - \|u_n - \lambda_n Ay_n - t_n\|^2 \\ &= \|u_n - u\|^2 - \|u_n - t_n\|^2 + 2\lambda_n \langle Ay_n, u - t_n \rangle \\ &= \|u_n - u\|^2 - \|u_n - t_n\|^2 + 2\lambda_n (\langle Ay_n - Au, u - y_n \rangle \\ &\quad + \langle Au, u - y_n \rangle + \langle Ay_n, y_n - t_n \rangle) \\ &\leq \|u_n - u\|^2 - \|u_n - t_n\|^2 + 2\lambda_n \langle Ay_n, y_n - t_n \rangle \\ &\leq \|u_n - u\|^2 - \|u_n - y_n\|^2 - 2\langle u_n - y_n, y_n - t_n \rangle \\ &\quad - \|y_n - t_n\|^2 + 2\lambda_n \langle Ay_n, y_n - t_n \rangle \\ &= \|u_n - u\|^2 - \|u_n - y_n\|^2 - \|y_n - t_n\|^2 + 2\langle u_n - \lambda_n Ay_n - y_n, t_n - y_n \rangle. \end{aligned}$$

Further, Since $y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n Au_n)$ and A is k -Lipschitz-continuous, we have

$$\begin{aligned} & \langle u_n - \lambda_n Ay_n - y_n, t_n - y_n \rangle \\ &= \langle u_n - \lambda_n Au_n - y_n, t_n - y_n \rangle + \langle \lambda_n Au_n - \lambda_n Ay_n, t_n - y_n \rangle \\ &\leq \langle u_n - \lambda_n Au_n - (1 - \gamma_n)u_n - \gamma_n P_C(u_n - \lambda_n Au_n), t_n - y_n \rangle \\ &\quad + \lambda_n \|Au_n - Ay_n\| \|t_n - y_n\| \\ &\leq \gamma_n \langle u_n - \lambda_n Au_n - P_C(u_n - \lambda_n Au_n), t_n - y_n \rangle \\ &\quad - (1 - \gamma_n)\lambda_n \langle Au_n, t_n - y_n \rangle + \lambda_n k \|u_n - y_n\| \|t_n - y_n\|. \end{aligned}$$

In addition, from the definition of P_C , we have

$$\begin{aligned} & \langle u_n - \lambda_n Au_n - P_C(u_n - \lambda_n Au_n), t_n - y_n \rangle \\ &= \langle u_n - \lambda_n Au_n - P_C(u_n - \lambda_n Au_n), t_n - (1 - \gamma_n)u_n - \gamma_n P_C(u_n - \lambda_n Au_n) \rangle \\ &= (1 - \gamma_n) \langle u_n - \lambda_n Au_n - P_C(u_n - \lambda_n Au_n), t_n - u_n \rangle \\ &\quad + \gamma_n \langle u_n - \lambda_n Au_n - P_C(u_n - \lambda_n Au_n), t_n - P_C(u_n - \lambda_n Au_n) \rangle \\ &\leq (1 - \gamma_n) \|u_n - \lambda_n Au_n - P_C(u_n - \lambda_n Au_n)\| \|t_n - u_n\| \\ &\leq (1 - \gamma_n)\lambda_n \|u_n - Au_n - u_n\| (\|t_n - y_n\| + \|y_n - u_n\|) \\ &\leq (1 - \gamma_n)\lambda_n \|Au_n\| (\|t_n - y_n\| + \|y_n - u_n\|). \end{aligned}$$

So, from the assumptions $b < \frac{1}{4k}$, $\gamma_n > \frac{3}{4}$ and (3.1), we have

$$\begin{aligned}
& \|t_n - u\|^2 \leq \|u_n - u\|^2 - \|u_n - y_n\|^2 - \|y_n - t_n\|^2 \\
& + 2\gamma_n(1 - \gamma_n)b\|Au_n\|(\|t_n - y_n\| + \|y_n - u_n\|) \\
& + 2(1 - \gamma_n)b\|Au_n\|\|t_n - y_n\| + 2bk\|u_n - y_n\|\|t_n - y_n\| \\
(3.2) \quad & \leq \|u_n - u\|^2 - \|u_n - y_n\|^2 - \|y_n - t_n\|^2 + (1 - \gamma_n)(2b^2\|Au_n\|^2 \\
& + \|t_n - y_n\|^2 + \|y_n - u_n\|^2) + (1 - \gamma_n)(b^2\|Au_n\|^2 \\
& + \|t_n - y_n\|^2) + bk(\|u_n - y_n\|^2 + \|t_n - y_n\|^2) \\
& = \|u_n - u\|^2 - (\gamma_n - bk)\|u_n - y_n\|^2 \\
& + (1 - 2\gamma_n + bk)\|t_n - y_n\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2 \\
& \leq \|u_n - u\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2 \\
& \leq \|x_n - u\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2.
\end{aligned}$$

In addition, from $u \in VI(C, A)$ and (3.1), we have

$$\begin{aligned}
& \|y_n - u\|^2 = \|(1 - \gamma_n)(u_n - u) + \gamma_n(PC(u_n - \lambda_n Au_n) - u)\|^2 \\
& \leq (1 - \gamma_n)\|u_n - u\|^2 + \gamma_n\|PC(u_n - \lambda_n Au_n) - PC(u)\|^2 \\
(3.3) \quad & \leq (1 - \gamma_n)\|u_n - u\|^2 + \gamma_n\|u_n - \lambda_n Au_n - u\|^2 \\
& \leq (1 - \gamma_n)\|u_n - u\|^2 + \gamma_n[\|u_n - u\|^2 - 2\lambda_n\langle Au_n, u_n - u \rangle + \lambda_n^2\|Au_n\|^2] \\
& \leq \|u_n - u\|^2 + b^2\|Au_n\|^2 \\
& \leq \|x_n - u\|^2 + b^2\|Au_n\|^2.
\end{aligned}$$

Therefore from (3.1)- (3.3), $z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n St_n$ and $u = Su$, we have

$$\begin{aligned}
& \|z_n - u\|^2 = \|(1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n St_n - u\|^2 \\
& \leq (1 - \alpha_n - \beta_n)\|x_n - u\|^2 + \alpha_n\|y_n - u\|^2 + \beta_n\|St_n - u\|^2 \\
(3.4) \quad & \leq (1 - \alpha_n - \beta_n)\|x_n - u\|^2 + \alpha_n\|y_n - u\|^2 + \beta_n\|t_n - u\|^2 \\
& \leq (1 - \alpha_n - \beta_n)\|x_n - u\|^2 + \alpha_n[\|u_n - u\|^2 + b^2\|Au_n\|^2] \\
& \quad + \beta_n[\|u_n - u\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2] \\
& \leq \|x_n - u\|^2 + (3 - 3\gamma_n + \alpha_n)b^2\|Au_n\|^2,
\end{aligned}$$

for every $n = 1, 2, \dots$ and hence $u \in C_n$. So, $\Omega \subset C_n$ for every $n = 1, 2, \dots$. Next, let us show by mathematical induction that $\{x_n\}$ is well defined and $\Omega \subset C_n \cap Q_n$ for every $n = 1, 2, \dots$. For $n = 1$ we have $x_1 = x \in C$ and $Q_1 = C$. Hence we obtain $\Omega \subset C_1 \cap Q_1$. Suppose that x_k is given and $\Omega \subset C_k \cap Q_k$ for some

$k \in N$. Since Ω is nonempty, $C_k \cap Q_k$ is a nonempty closed convex subset of H . So, there exists a unique element $x_{k+1} \in C_k \cap Q_k$ such that $x_{k+1} = P_{C_k \cap Q_k} x$. It is also obvious that there holds $\langle x_{k+1} - z, x - x_{k+1} \rangle \geq 0$ for every $z \in C_k \cap Q_k$. Since $\Omega \subset C_k \cap Q_k$, we have $\langle x_{k+1} - z, x - x_{k+1} \rangle \geq 0$ for every $z \in \Omega$ and hence $\Omega \subset Q_{k+1}$. Therefore, we obtain $\Omega \subset C_{k+1} \cap Q_{k+1}$.

Let $l_0 = P_\Omega x$. From $x_{n+1} = P_{C_n \cap Q_n} x$ and $l_0 \in \Omega \subset C_n \cap Q_n$, we have

$$(3.5) \quad \|x_{n+1} - x\| \leq \|l_0 - x\|$$

for every $n = 1, 2, \dots$. Therefore, $\{x_n\}$ is bounded. From (3.1)-(3.4) and the Lipschitz continuity of A , we also obtain that $\{u_n\}$, $\{Au_n\}$, $\{t_n\}$ and $\{z_n\}$ are bounded. Since $x_{n+1} \in C_n \cap Q_n \subset C_n$ and $x_n = P_{Q_n} x$, we have

$$\|x_n - x\| \leq \|x_{n+1} - x\|$$

for every $n = 1, 2, \dots$. It follows from (3.5) that $\lim_{n \rightarrow \infty} \|x_n - x\|$ exists.

Since $x_n = P_{Q_n} x$ and $x_{n+1} \in Q_n$, using (2.2), we have

$$\|x_{n+1} - x_n\|^2 \leq \|x_{n+1} - x\|^2 - \|x_n - x\|^2$$

for every $n = 1, 2, \dots$. This implies that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0.$$

Since $x_{n+1} \in C_n$, we have $\|z_n - x_{n+1}\|^2 \leq \|x_n - x_{n+1}\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|Au_n\|^2$ and hence it follows from $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\lim_{n \rightarrow \infty} \alpha_n = 0$ that $\lim_{n \rightarrow \infty} \|z_n - x_{n+1}\| = 0$. Since

$$\|x_n - z_n\| \leq \|x_n - x_{n+1}\| + \|x_{n+1} - z_n\|$$

for every $n = 1, 2, \dots$, we have $\|x_n - z_n\| \rightarrow 0$.

For $u \in \Omega$, from (3.4) we obtain

$$\begin{aligned} & \|z_n - u\|^2 - \|x_n - u\|^2 \\ & \leq (-\alpha_n - \beta_n)\|x_n - u\|^2 + \alpha_n\|y_n - u\|^2 + \beta_n\|St_n - u\|^2 \\ & \leq (3 - 3\gamma_n + \alpha_n)b^2\|Au_n\|^2. \end{aligned}$$

Since $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\{u_n\}$, $\{Au_n\}$ and $\{z_n\}$ are bounded, we have

$$\lim_{n \rightarrow \infty} \beta_n(\|St_n - u\|^2 - \|x_n - u\|^2) = 0.$$

By $\liminf_{n \rightarrow \infty} \beta_n > 0$, we get

$$\lim_{n \rightarrow \infty} \|St_n - u\|^2 - \|x_n - u\|^2 = 0.$$

From (3.2) and $u = Su$, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} \|St_n - u\|^2 - \|x_n - u\|^2 &\leq \lim_{n \rightarrow \infty} \|t_n - u\|^2 - \|x_n - u\|^2 \\ &\leq \lim_{n \rightarrow \infty} 3(1 - \gamma_n)b^2\|Au_n\|^2 = 0. \end{aligned}$$

Thus, $\lim_{n \rightarrow \infty} \|t_n - u\|^2 - \|x_n - u\|^2 = 0$.

From (3.2) and (3.1), we have

$$\begin{aligned} &(\gamma_n - bk)\|u_n - y_n\|^2 + (2\gamma_n - 1 - bk)\|t_n - y_n\|^2 \\ &\leq \|x_n - u\|^2 - \|t_n - u\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2. \end{aligned}$$

It follows that

$$\lim_{n \rightarrow \infty} (\gamma_n - bk)\|u_n - y_n\|^2 + (2\gamma_n - 1 - bk)\|t_n - y_n\|^2 = 0.$$

The assumptions on γ_n and λ_n imply that $\gamma_n - bk > \frac{1}{2}$ and $2\gamma_n - 1 - bk > \frac{1}{4}$. Consequently, $\lim_{n \rightarrow \infty} \|u_n - y_n\| = \lim_{n \rightarrow \infty} \|t_n - y_n\| = 0$. Since A is Lipschitz continuous, we have $\lim_{n \rightarrow \infty} \|At_n - Ay_n\| = 0$. It follows from $\|u_n - t_n\| \leq \|u_n - y_n\| + \|t_n - y_n\|$ that $\lim_{n \rightarrow \infty} \|u_n - t_n\| = 0$.

We rewrite the definition of z_n as

$$z_n - x_n = \alpha_n(y_n - x_n) + \beta_n(St_n - x_n).$$

From $\lim_{n \rightarrow \infty} \|z_n - x_n\| = 0$, $\lim_{n \rightarrow \infty} \alpha_n = 0$, the boundedness of $\{x_n\}$, $\{y_n\}$ and $\liminf_{n \rightarrow \infty} \beta_n > 0$ we infer that $\lim_{n \rightarrow \infty} \|St_n - x_n\| = 0$.

By (3.4) and (3.1), we have

$$\begin{aligned} &\|z_n - u\|^2 \leq (1 - \alpha_n - \beta_n)\|x_n - u\|^2 + \alpha_n[\|u_n - u\|^2 \\ &\quad + b^2\|Au_n\|^2] + \beta_n[\|u_n - u\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2] \\ (3.6) \quad &\leq (1 - \alpha_n - \beta_n)\|x_n - u\|^2 + \alpha_n[\|x_n - u\|^2 \\ &\quad + r_n(r_n - 2\alpha)\|Bx_n - Bu\|^2 + b^2\|Au_n\|^2] \\ &\quad + \beta_n[\|x_n - u\|^2 + r_n(r_n - 2\alpha)\|Bx_n - Bu\|^2 + 3(1 - \gamma_n)b^2\|Au_n\|^2] \\ &\leq \|x_n - u\|^2 + (\alpha_n + \beta_n)r_n(r_n - 2\alpha)\|Bx_n - Bu\|^2 \\ &\quad + (3 - 3\gamma_n + \alpha_n)b^2\|Au_n\|^2. \end{aligned}$$

Hence, we have

$$\begin{aligned} &(\alpha_n + \beta_n)d(2\alpha - e)\|Bx_n - Bu\|^2 \\ &\leq (\alpha_n + \beta_n)r_n(2\alpha - r_n)\|Bx_n - Bu\|^2 \\ &\leq \|x_n - u\|^2 - \|z_n - u\|^2 + (3 - 3\gamma_n + \alpha_n)b^2\|Au_n\|^2 \\ &\leq (\|x_n - u\| + \|z_n - u\|)\|x_n - z_n\| + (3 - 3\gamma_n + \alpha_n)b^2\|Au_n\|^2. \end{aligned}$$

Since $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\liminf_{n \rightarrow \infty} \beta_n > 0$, $\lim_{n \rightarrow \infty} \gamma_n = 1$, $\|x_n - z_n\| \rightarrow 0$ and the sequences $\{x_n\}$ and $\{z_n\}$ are bounded, we obtain $\|Bx_n - Bu\| \rightarrow 0$.

For $u \in \Omega$, we have, from Lemma 2.3,

$$\begin{aligned} \|u_n - u\|^2 &= \|T_{r_n}(x_n - r_n Bx_n) - T_{r_n}(u - r_n Bu)\|^2 \\ &\leq \langle T_{r_n}(x_n - r_n Bx_n) - T_{r_n}(u - r_n Bu), x_n - r_n Bx_n - (u - r_n Bu) \rangle \\ &= \frac{1}{2} \{ \|u_n - u\|^2 + \|x_n - r_n Bx_n - (u - r_n Bu)\|^2 \\ &\quad - \|x_n - r_n Bx_n - (u - r_n Bu) - (u_n - u)\|^2 \} \\ &\leq \frac{1}{2} \{ \|u_n - u\|^2 + \|x_n - u\|^2 - \|x_n - r_n Bx_n - (u - r_n Bu) - (u_n - u)\|^2 \} \\ &= \frac{1}{2} \{ \|u_n - u\|^2 + \|x_n - u\|^2 - \|x_n - u_n\|^2 \\ &\quad + 2r_n \langle Bx_n - Bu, x_n - u_n \rangle - r_n^2 \|Bx_n - Bu\|^2 \}. \end{aligned}$$

Hence,

$$\begin{aligned} \|u_n - u\|^2 &\leq \|x_n - u\|^2 - \|x_n - u_n\|^2 + 2r_n \langle Bx_n - Bu, x_n - u_n \rangle \\ -r_n^2 \|Bx_n - Bu\|^2 &\leq \|x_n - u\|^2 - \|x_n - u_n\|^2 + 2r_n \langle Bx_n - Bu, x_n - u_n \rangle. \end{aligned}$$

Then, by (3.4), we have

$$\begin{aligned} \|z_n - u\|^2 &\leq (1 - \alpha_n - \beta_n) \|x_n - u\|^2 + \alpha_n [\|u_n - u\|^2 + b^2 \|Au_n\|^2] \\ &\quad + \beta_n [\|u_n - u\|^2 + 3(1 - \gamma_n) b^2 \|Au_n\|^2] \\ &\leq (1 - \alpha_n - \beta_n) \|x_n - u\|^2 + \alpha_n [(\|x_n - u\|^2 - \|x_n - u_n\|^2 \\ &\quad + 2r_n \langle Bx_n - Bu, x_n - u_n \rangle) + b^2 \|Au_n\|^2] + \beta_n [(\|x_n - u\|^2 \\ &\quad - \|x_n - u_n\|^2 + 2r_n \langle Bx_n - Bu, x_n - u_n \rangle) + 3(1 - \gamma_n) b^2 \|Au_n\|^2] \\ &\leq \|x_n - u\|^2 + (-\alpha_n - \beta_n) \|x_n - u_n\|^2 + 2r_n \|Bx_n - Bu\| \|x_n - u_n\| \\ &\quad + (3 - 3\gamma_n + \alpha_n) b^2 \|Au_n\|^2 \end{aligned}$$

Hence,

$$\begin{aligned} (\alpha_n + \beta_n) \|x_n - u_n\|^2 &\leq \|x_n - u\|^2 - \|z_n - u\|^2 \\ &\quad + 2r_n \|Bx_n - Bu\| \|x_n - u_n\| + (3 - 3\gamma_n + \alpha_n) b^2 \|Au_n\|^2 \\ &\leq (\|x_n - u\| + \|z_n - u\|) \|x_n - z_n\| \\ &\quad + 2r_n \|Bx_n - Bu\| \|x_n - u_n\| + (3 - 3\gamma_n + \alpha_n) b^2 \|Au_n\|^2. \end{aligned}$$

Since $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\liminf_{n \rightarrow \infty} \beta_n > 0$, $\lim_{n \rightarrow \infty} \gamma_n = 1$, $\|x_n - z_n\| \rightarrow 0$, $\|Bx_n - Bu\| \rightarrow 0$ and the sequences $\{x_n\}$ and $\{z_n\}$ are bounded, we obtain

$\|x_n - u_n\| \rightarrow 0$. From $\|z_n - t_n\| \leq \|z_n - x_n\| + \|x_n - u_n\| + \|u_n - t_n\|$ we have $\|z_n - t_n\| \rightarrow 0$. From $\|t_n - x_n\| \leq \|t_n - u_n\| + \|x_n - u_n\|$ we also have $\|t_n - x_n\| \rightarrow 0$.

Since $z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S t_n$, we have $\beta_n(S t_n - t_n) = (1 - \alpha_n - \beta_n)(t_n - x_n) + \alpha_n(t_n - y_n) + (z_n - t_n)$. Then

$$\beta_n \|S t_n - t_n\| \leq (1 - \alpha_n - \beta_n) \|t_n - x_n\| + \alpha_n \|t_n - y_n\| + \|z_n - t_n\|$$

and hence $\|S t_n - t_n\| \rightarrow 0$.

As $\{x_n\}$ is bounded, there exists a subsequence $\{x_{n_i}\}$ of $\{x_n\}$ such that $x_{n_i} \rightharpoonup w$. From $\|x_n - u_n\| \rightarrow 0$, we obtain that $u_{n_i} \rightharpoonup w$. From $\|u_n - t_n\| \rightarrow 0$, we also obtain that $t_{n_i} \rightharpoonup w$. Since $\{u_{n_i}\} \subset C$ and C is closed and convex, we obtain $w \in C$.

First, we show $w \in GMEP(F, \varphi, B)$. By $u_n = T_{r_n}(x_n - r_n B x_n)$, we know that

$$F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle B x_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \forall y \in C.$$

It follows from (A2) that

$$\varphi(y) - \varphi(u_n) + \langle B x_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq F(y, u_n), \forall y \in C.$$

Hence,

$$(3.7) \quad \varphi(y) - \varphi(u_{n_i}) + \langle B x_{n_i}, y - u_{n_i} \rangle + \langle y - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r_{n_i}} \rangle \geq F(y, u_{n_i}), \forall y \in C.$$

For t with $0 < t \leq 1$ and $y \in C$, let $y_t = t y + (1 - t)w$. Since $y \in C$ and $w \in C$, we obtain $y_t \in C$. So, from (3.7) we have

$$\begin{aligned} \langle y_t - u_{n_i}, B y_t \rangle &\geq \langle y_t - u_{n_i}, B y_t \rangle - \varphi(y_t) + \varphi(u_{n_i}) - \langle y_t - u_{n_i}, B x_{n_i} \rangle \\ &\quad - \langle y_t - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r_{n_i}} \rangle + F(y_t, u_{n_i}) \\ &= \langle y_t - u_{n_i}, B y_t - B u_{n_i} \rangle + \langle y_t - u_{n_i}, B u_{n_i} - B x_{n_i} \rangle - \varphi(y_t) + \varphi(u_{n_i}) \\ &\quad - \langle y_t - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r_{n_i}} \rangle + F(y_t, u_{n_i}). \end{aligned}$$

Since $\|u_{n_i} - x_{n_i}\| \rightarrow 0$, we have $\|B u_{n_i} - B x_{n_i}\| \rightarrow 0$. Further, from the inverse-strongly monotonicity of B , we have $\langle y_t - u_{n_i}, B y_t - B u_{n_i} \rangle \geq 0$. So, from (A4), (A5), and the weakly lower semicontinuity of φ , $\frac{u_{n_i} - x_{n_i}}{r_{n_i}} \rightarrow 0$ and $u_{n_i} \rightharpoonup w$, we have

$$(3.8) \quad \langle y_t - w, B y_t \rangle \geq -\varphi(y_t) + \varphi(w) + F(y_t, w),$$

as $i \rightarrow \infty$. From (A1), (A4) and (3.8), we also have

$$\begin{aligned} 0 &= F(y_t, y_t) + \varphi(y_t) - \varphi(y_t) \\ &\leq tF(y_t, y) + (1 - t)F(y_t, w) + t\varphi(y) + (1 - t)\varphi(w) - \varphi(y_t) \\ &= t[F(y_t, y) + \varphi(y) - \varphi(y_t)] + (1 - t)[F(y_t, w) + \varphi(w) - \varphi(y_t)] \\ &\leq t[F(y_t, y) + \varphi(y) - \varphi(y_t)] + (1 - t)\langle y_t - w, By_t \rangle \\ &= t[F(y_t, y) + \varphi(y) - \varphi(y_t)] + (1 - t)t\langle y - w, By_t \rangle \end{aligned}$$

and hence

$$0 \leq F(y_t, y) + \varphi(y) - \varphi(y_t) + (1 - t)\langle y - w, By_t \rangle.$$

Letting $t \rightarrow 0$, we have, for each $y \in C$,

$$F(w, y) + \varphi(y) - \varphi(w) + \langle y - w, Bw \rangle \geq 0.$$

This implies that $w \in GMEP(F, \varphi, B)$.

We next show that $w \in Fix(S)$. Assume $w \notin Fix(S)$. Since $t_{n_i} \rightarrow w$ and $w \neq Sw$, from the Opial theorem [29] we have

$$\begin{aligned} \liminf_{i \rightarrow \infty} \|t_{n_i} - w\| &< \liminf_{i \rightarrow \infty} \|t_{n_i} - Sw\| \\ &\leq \liminf_{i \rightarrow \infty} \{\|t_{n_i} - St_{n_i}\| + \|St_{n_i} - Sw\|\} \\ &\leq \liminf_{i \rightarrow \infty} \|t_{n_i} - w\| \end{aligned}$$

This is a contradiction. So, we get $w \in Fix(S)$.

Finally we show $w \in VI(C, A)$. Let

$$Tv = \begin{cases} Av + N_C v & \text{if } v \in C, \\ \emptyset & \text{if } v \notin C. \end{cases}$$

where $N_C v$ is the normal cone to C at $v \in C$. We have already mentioned that in this case the mapping T is maximal monotone, and $0 \in Tv$ if and only if $v \in VI(C, A)$. Let $(v, g) \in G(T)$. Then $Tv = Av + N_C v$ and hence $g - Av \in N_C v$. So, we have $\langle v - t, g - Av \rangle \geq 0$ for all $t \in C$. On the other hand, from $t_n = P_C(u_n - \lambda_n Ay_n)$ and $v \in C$ we have

$$\langle u_n - \lambda_n Ay_n - t_n, t_n - v \rangle \geq 0$$

and hence

$$\langle v - t_n, \frac{t_n - u_n}{\lambda_n} + Ay_n \rangle \geq 0.$$

Therefore, we have

$$\begin{aligned}
\langle v - t_{n_i}, g \rangle &\geq \langle v - t_{n_i}, Av \rangle \\
&\geq \langle v - t_{n_i}, Av \rangle - \langle v - t_{n_i}, \frac{t_{n_i} - u_{n_i}}{\lambda_{n_i}} + Ay_{n_i} \rangle \\
&= \langle v - t_{n_i}, Av - Ay_{n_i} - \frac{t_{n_i} - u_{n_i}}{\lambda_{n_i}} \rangle \\
&= \langle v - t_{n_i}, Av - At_{n_i} + At_{n_i} - Ay_{n_i} - \frac{t_{n_i} - u_{n_i}}{\lambda_{n_i}} \rangle \\
&= \langle v - t_{n_i}, Av - At_{n_i} \rangle + \langle v - t_{n_i}, At_{n_i} - Ay_{n_i} \rangle - \langle v - t_{n_i}, \frac{t_{n_i} - u_{n_i}}{\lambda_{n_i}} \rangle \\
&\geq \langle v - t_{n_i}, At_{n_i} - Ay_{n_i} \rangle - \langle v - t_{n_i}, \frac{t_{n_i} - u_{n_i}}{\lambda_{n_i}} \rangle
\end{aligned}$$

Hence we obtain $\langle v - w, g \rangle \geq 0$ as $i \rightarrow \infty$. Since T is maximal monotone, we have $w \in T^{-1}0$ and hence $w \in VI(C, A)$. This implies $w \in \Omega$.

From $l_0 = P_\Omega x$, $w \in \Omega$ and (3.5), we have

$$\|l_0 - x\| \leq \|w - x\| \leq \liminf_{i \rightarrow \infty} \|x_{n_i} - x\| \leq \limsup_{i \rightarrow \infty} \|x_{n_i} - x\| \leq \|l_0 - x\|.$$

So, we obtain

$$\lim_{i \rightarrow \infty} \|x_{n_i} - x\| = \|w - x\|.$$

From $x_{n_i} - x \rightharpoonup w - x$ we have $x_{n_i} - x \rightarrow w - x$ and hence $x_{n_i} \rightarrow w$. Since $x_n = P_{Q_n}x$ and $l_0 \in \Omega \subset C_n \cap Q_n \subset Q_n$, we have

$$-\|l_0 - x_{n_i}\|^2 = \langle l_0 - x_{n_i}, x_{n_i} - x \rangle + \langle l_0 - x_{n_i}, x - l_0 \rangle \geq \langle l_0 - x_{n_i}, x - l_0 \rangle.$$

As $i \rightarrow \infty$, we obtain $-\|l_0 - w\|^2 \geq \langle l_0 - w, x - l_0 \rangle \geq 0$ by $l_0 = P_\Omega x$ and $w \in \Omega$. Hence we have $w = l_0$. This implies that $x_n \rightarrow l_0$. It is easy to see $u_n \rightarrow l_0$, $y_n \rightarrow l_0$ and $z_n \rightarrow l_0$. The proof is now complete.

By Theorem 3.1, we can obtain some new and interesting strong convergence theorems for some algorithms of finding the solution of generalized mixed equilibrium problem as follows.

Theorem 3.2. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1) – (A5) and $\varphi : C \rightarrow \mathbb{R}$ be a lower semicontinuous and convex function. Let B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\text{Fix}(S) \cap \text{GMEP}(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n u_n + \beta_n S u_n, \\ C_n = \{z \in C : \|z_n - z\| \leq \|x_n - z\|\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\alpha_n\}, \{\beta_n\}$ are two sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$.

Then, $\{x_n\}, \{u_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap GMEP(F, \varphi, B)}(x)$.

Proof. Putting $A = 0$, by Theorem 3.1 we obtain the desired result.

Theorem 3.3. Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1)-(A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap GMEP(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}, \{u_n\}$ and $\{z_n\}$ be sequences generated by

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ z_n = (1 - \beta_n)x_n + \beta_n S u_n, \\ C_n = \{z \in C : \|z_n - z\| \leq \|x_n - z\|\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\beta_n\}$ is a sequence in $[0, 1]$ satisfying the condition $\liminf_{n \rightarrow \infty} \beta_n > 0$. Then, $\{x_n\}, \{u_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap GMEP(F, \varphi, B)}(x)$.

Proof. Putting $A = 0$ and $\alpha_n = 0$ for every $n = 1, 2, \dots$, by Theorem 3.1 we obtain the desired result.

A mapping T of a closed convex subset C into itself is pseudocontractive if there holds that

$$\langle Tx - Ty, x - y \rangle \leq \|x - y\|^2$$

for all $x, y \in C$; see [33]. Obviously, the class of pseudocontractive mappings is more general than the class of nonexpansive mappings. Now we prove a strong convergence theorem of a new iterative process for finding a common element of the set of solutions of a generalized mixed equilibrium problem, the set of fixed points of a nonexpansive mapping and the set of fixed points of a Lipschitz pseudocontractive mapping.

Theorem 3.4. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let T be a pseudocontractive and m -Lipschitz-continuous mapping of C into itself and B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap Fix(T) \cap GMEP(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n[u_n - \lambda_n(u_n - Tu_n)], \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n SP_C(u_n - \lambda_n(y_n - Ty_n)), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2\|u_n - Tu_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4(m+1)})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
- (iv) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap Fix(T) \cap GMEP(F, \varphi, B)}(x)$.

Proof. Let $A = I - T$. From the proof of Theorem 4.5 in [27], we know that the mapping A is monotone and $(m+1)$ -Lipschitz-continuous and $Fix(T) = VI(C, A)$. By Theorem 3.1 we obtain the desired result.

Theorem 3.5. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let B be an α -inverse-strongly monotone mapping of C into H and A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\Omega = \text{Fix}(S) \cap \text{VI}(C, A) \cap \text{GMEP}(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \beta_n)x_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\beta_n\}$ is a sequence in $[0, 1]$ satisfying $\liminf_{n \rightarrow \infty} \beta_n > 0$. Then, $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_\Omega(x)$.

Proof. Putting $\gamma_n = 1$ and $\alpha_n = 0$, by Theorem 3.1 we obtain the desired result.

It is easy to see that Theorem 3.1-3.5 generalize and extend Theorem 3.1 in [9].

Theorem 3.6. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let B be an α -inverse-strongly monotone mapping of C into H and A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\Omega = \text{Fix}(S) \cap \text{VI}(C, A) \cap \text{GMEP}(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = P_C(u_n - \lambda_n A u_n), \\ z_n = P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$. Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_\Omega(x)$.

Proof. Putting $S = I$, $\gamma_n = \beta_n = 1$ and $\alpha_n = 0$ for every $n = 1, 2, \dots$, by Theorem 3.1 we obtain the desired result.

Theorem 3.7 Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1)-(A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let A be a monotone and k -Lipschitz-continuous mapping of C into H and B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\Omega = \text{Fix}(S) \cap \text{VI}(C, A) \cap \text{GMEP}(F, \varphi, B) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\gamma_n\}$ is a sequence in $[0, 1]$ such that $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$. Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_\Omega(x)$.

Proof. Putting $S = I$, $\alpha_n = 0$ and $\beta_n = 1$ for every $n = 1, 2, \dots$, by Theorem 3.1 we obtain the desired result.

4. APPLICATIONS

By the above results, we can obtain many new and interesting strong convergence theorems for some algorithms of finding the solution of the problems (1.2)-(1.7). Now we give some examples as follows:

Let $B = 0$, by Theorem 3.1 and 3.5, we obtain the following two strong convergence theorems for the algorithms of finding solutions of problem (1.2):

Theorem 4.1. Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5) and

$\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap VI(C, A) \cap MEP(F, \varphi) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ be sequences generated by

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n} \cap Q_n x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, +\infty)$ for some $d > 0$, and $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
- (iv) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap VI(C, A) \cap MEP(F, \varphi)}(x)$.

Theorem 4.2. Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5) and $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap VI(C, A) \cap MEP(F, \varphi) \neq \emptyset$. Assume that either (B1) or (B2) holds. Let $\{x_n\}, \{u_n\}, \{y_n\}$ and $\{z_n\}$ be sequences generated by

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \beta_n)x_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n} \cap Q_n x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, +\infty)$ for some $d > 0$, and $\{\beta_n\}$ is a sequence in $[0, 1]$ satisfying $\liminf_{n \rightarrow \infty} \beta_n > 0$.

Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap VI(C,A) \cap MEP(F,\varphi)}(x)$.

Let $\varphi = 0$, by Theorem 3.1 and 3.5, we obtain the following two strong convergence theorems for the algorithms of finding solutions of problem (1.3):

Theorem 4.3. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5). Let A be a monotone and k -Lipschitz-continuous mapping of C into H and B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap VI(C, A) \cap GEP(F, B) \neq \emptyset$. Assume that either (B4) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
- (iii) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap VI(C,A) \cap GEP(F,B)}(x)$.

Theorem 4.4. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5). Let A be a monotone and k -Lipschitz-continuous mapping of C into H and B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping*

of C into H such that $Fix(S) \cap VI(C, A) \cap GEP(F, B) \neq \emptyset$. Assume that either (B4) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by

$$\begin{cases} x_1 = x \in C, \\ F(u_n, y) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ y_n = P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \beta_n)x_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{cases}$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\beta_n\}$ is a sequence in $[0, 1]$ satisfying $\liminf_{n \rightarrow \infty} \beta_n > 0$.

Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap VI(C, A) \cap GEP(F, B)}(x)$.

Let $F(x, y) = 0$ for $x, y \in C$, by Theorem 3.1 we obtain the following strong convergence theorem for an algorithm of finding solutions of problem (1.5):

Theorem 4.5. Let C be a nonempty closed convex subset of a real Hilbert space H . Let $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let A be a monotone and k -Lipschitz-continuous mapping of C into H and B be an α -inverse-strongly monotone mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap VI(C, A) \cap GVI(C, \varphi, B) \neq \emptyset$. Assume that either (B3) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by

$$\begin{cases} x_1 = x \in C, \\ \varphi(y) - \varphi(u_n) + \langle Bx_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{cases}$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, e]$ for some $d, e \in (0, 2\alpha)$, and $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;

- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
 (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
 (iv) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{\text{Fix}(S) \cap \text{VI}(C, A) \cap \text{GVI}(C, \varphi, B)}(x)$.

Let $B = 0$ and $F(x, y) = 0$ for $x, y \in C$, by Theorem 3.1 we obtain the following strong convergence theorem for an algorithm of finding solutions of problem (1.7):

Theorem 4.6. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let $\varphi : C \rightarrow R$ be a lower semicontinuous and convex function. Let A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\text{Fix}(S) \cap \text{VI}(C, A) \cap \text{Argmin}(\varphi) \neq \emptyset$. Assume that either (B3) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, +\infty)$ for some $d > 0$, and $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
 (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
 (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
 (iv) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{\text{Fix}(S) \cap \text{VI}(C, A) \cap \text{Argmin}(\varphi)}(x)$.

Let $B = 0$ and $\varphi = 0$, by Theorem 3.1, we obtain the following strong convergence theorem for an algorithm of finding solutions of problem (1.4):

Theorem 4.7. *Let C be a nonempty closed convex subset of a real Hilbert space H . Let F be a bifunction from $C \times C$ to R satisfying (A1) – (A5). Let A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap VI(C, A) \cap MEP(F, \varphi) \neq \emptyset$. Assume that either (B4) or (B2) holds. Let $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by*

$$\left\{ \begin{array}{l} x_1 = x \in C, \\ F(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \\ y_n = (1 - \gamma_n)u_n + \gamma_n P_C(u_n - \lambda_n A u_n), \\ z_n = (1 - \alpha_n - \beta_n)x_n + \alpha_n y_n + \beta_n S P_C(u_n - \lambda_n A y_n), \\ C_n = \{z \in C : \|z_n - z\|^2 \leq \|x_n - z\|^2 + (3 - 3\gamma_n + \alpha_n)b^2 \|A u_n\|^2\}, \\ Q_n = \{z \in C : \langle x_n - z, x - x_n \rangle \geq 0\}, \\ x_{n+1} = P_{C_n \cap Q_n} x \end{array} \right.$$

for every $n = 1, 2, \dots$ where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$, $\{r_n\} \subset [d, +\infty)$ for some $d > 0$, and $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
- (iv) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}$, $\{u_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{Fix(S) \cap VI(C, A) \cap EP(F)}(x)$.

Theorem 4.8. (see Theorem 5 in [28]). *Let C be a nonempty closed convex subset of a real Hilbert space H . Let A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $Fix(S) \cap VI(C, A) \neq \emptyset$. Let $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by (1.12), where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$ and $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$ are three sequences in $[0, 1]$ satisfying the conditions:*

- (i) $\alpha_n + \beta_n \leq 1$ for all $n \in N$;
- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0$;
- (iii) $\liminf_{n \rightarrow \infty} \beta_n > 0$;
- (iv) $\lim_{n \rightarrow \infty} \gamma_n = 1$ and $\gamma_n > \frac{3}{4}$ for all $n \in N$;

Then, $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{\text{Fix}(S) \cap VI(C,A)}(x)$.

Proof. Putting $\varphi = 0$, $B = 0$ and $F(x, y) = 0$ for $x, y \in C$ in Theorem 3.1, then $u_n = P_C x_n = x_n$ for every $n = 1, 2, \dots$. By Theorem 3.1 we obtain the desired result.

Theorem 4.9. (see Theorem 3.1 in [27]). *Let C be a nonempty closed convex subset of a real Hilbert space H . Let A be a monotone and k -Lipschitz-continuous mapping of C into H . Let S be a nonexpansive mapping of C into H such that $\text{Fix}(S) \cap VI(C, A) \neq \emptyset$. Let $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences generated by (1.11), where $\{\lambda_n\} \subset [a, b]$ for some $[a, b] \subset (0, \frac{1}{4k})$ and $\{\beta_n\}$ is a sequence in $[0, 1]$ satisfying $\liminf_{n \rightarrow \infty} \beta_n > 0$. Then, $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ converge strongly to $w = P_{\text{Fix}(S) \cap VI(C,A)}(x)$.*

Proof. Putting $\varphi = 0$, $B = 0$ and $F(x, y) = 0$ for $x, y \in C$, $\alpha_n = 0$ and $\gamma_n = 1$ for every $n = 1, 2, \dots$ in Theorem 3.1, then $u_n = P_C x_n = x_n$ for every $n = 1, 2, \dots$. By Theorem 3.1 we obtain the desired result.

Theorem 4.8 and 4.9 generalize and extend Theorem 3.4 in [14].

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