

A GENERALIZATION OF BESSEL'S INTEGRAL FOR THE BESSEL COEFFICIENTS

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Abstract. We derive an integral over the m -dimensional unit hypercube that generalizes Bessel's integral for $J_n(x)$. The integrand is $G(x\psi(\mathbf{t})) \exp(-2\pi i \mathbf{n} \cdot \mathbf{t})$, where G is analytic, and $\psi(\mathbf{t}) = e^{2\pi i t_1} + \dots + e^{2\pi i t_m} + e^{-2\pi i(t_1 + \dots + t_m)}$, while \mathbf{n} is a set of non-negative integers. In particular, we consider the case when G is a hypergeometric function ${}_pF_q$.

1. INTRODUCTION

The series definition of the Bessel function

$$(1) \quad J_\nu(z) = \frac{\left(\frac{1}{2}z\right)^\nu}{\Gamma(\nu+1)} {}_0F_1 \left[\begin{matrix} \nu+1 \\ -\frac{1}{4}z^2 \end{matrix} \right], \quad -\nu \notin \mathbb{N},$$

and Bessel's integral representation

$$(2) \quad 2\pi J_n(z) = \int_0^{2\pi} \exp(i(z \sin \varphi - n\varphi)) d\varphi, \quad n \in \mathbb{Z},$$

are well known and may be found in many textbooks; see, for instance, Ch. 7 in [1] or Ch. 6 in [2].

We are interested in establishing a multidimensional generalization of (2). However, it is more convenient to work within the framework of hypergeometric functions. Accordingly, we set $z = x \exp(-\frac{1}{2}\pi i)$ and $\varphi = \frac{1}{2}\pi + 2\pi t$ to obtain the equivalent representation

$$(3) \quad \frac{\left(\frac{1}{2}x\right)^n}{n!} {}_0F_1 \left[\begin{matrix} n+1 \\ \frac{1}{4}x^2 \end{matrix} \right] = \int_0^1 \exp(x \cos(2\pi t) - 2\pi i n t) dt, \quad n \in \mathbb{N}_0.$$

In the sequel we shall establish a generalization of (3) in terms of an integral over the m -dimensional unit hypercube.

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2. THE GENERALIZED INTEGRAL

Let boldface letters denote m -dimensional vectors with the customary dot product. The analogue of the factor $\exp(-2\pi i n t)$ may reasonably be expected to be $\exp(-2\pi i \mathbf{n} \cdot \mathbf{t})$, where $n_1, \dots, n_m \in \mathbb{N}_0$. It is less evident what should take the place of $\exp(x \cos(2\pi t))$. Some preliminary considerations indicated that we should consider $G(x\psi(\mathbf{t}))$, where

$$(4) \quad \psi(\mathbf{t}) = \exp(2\pi i t_1) + \dots + \exp(2\pi i t_m) + \exp(-2\pi i (t_1 + \dots + t_m)),$$

while G is an analytic function. Introduce its Maclaurin expansion

$$(5) \quad G(\xi) = \sum_{k=0}^{\infty} \frac{g^{(k)}}{k!} \xi^k, \quad |\xi| < R,$$

where for brevity $g^{(k)}$ is written instead of the derivative $G^{(k)}(0)$. The integral to be investigated thus reads,

$$(6) \quad I = \int_0^1 \dots \int_0^1 G(x\psi(\mathbf{t})) \exp(-2\pi i \mathbf{n} \cdot \mathbf{t}) \, dt_1 \dots dt_m.$$

This may, on account of (5), be written

$$(7) \quad I = \sum_{k=0}^{\infty} g^{(k)} x^k L(k),$$

where

$$(8) \quad L(k) = \int_0^1 \dots \int_0^1 \frac{[\psi(\mathbf{t})]^k}{k!} \exp(-2\pi i \mathbf{n} \cdot \mathbf{t}) \, dt_1 \dots dt_m.$$

Next, by the multinomial theorem,

$$\begin{aligned} & \frac{[\psi(\mathbf{t})]^k}{k!} \exp(-2\pi i \mathbf{n} \cdot \mathbf{t}) \\ &= \sum_{\mathcal{J}_k} \frac{\exp[2\pi i (\mu_1 t_1 + \dots + \mu_m t_m - \mu_0 (t_1 + \dots + t_m) - (n_1 t_1 + \dots + n_m t_m))]}{\mu_0! \mu_1! \dots \mu_m!} \\ &= \sum_{\mathcal{J}_k} \frac{\exp[2\pi i (\mu_1 - \mu_0 - n_1) t_1] \dots \exp[2\pi i (\mu_m - \mu_0 - n_m) t_m]}{\mu_0! \mu_1! \dots \mu_m!}, \end{aligned}$$

where the index set \mathcal{J}_k is given by the inequalities

$$(9) \quad \mu_0 \geq 0, \mu_1 \geq 0, \dots, \mu_m \geq 0, \mu_0 + \mu_1 + \dots + \mu_m = k.$$

Hence,

$$\begin{aligned}
 L(k) &= \sum_{\mathcal{J}_k} \frac{1}{\mu_0! \mu_1! \cdots \mu_m!} \int_0^1 \exp [2\pi i (\mu_1 - \mu_0 - n_1) t_1] dt_1 \times \\
 &\quad \cdots \times \int_0^1 \exp [2\pi i (\mu_m - \mu_0 - n_m) t_m] dt_m \\
 &= \sum_{\mathcal{J}_k} \frac{1}{\mu_0! \mu_1! \cdots \mu_m!} \delta(\mu_1, \mu_0 + n_1) \cdots \delta(\mu_m, \mu_0 + n_m) \\
 &= \sum_{k=0}^{\infty} \frac{1}{\mu_0! (\mu_0 + n_1)! \cdots (\mu_0 + n_m)!},
 \end{aligned}$$

where $\delta(\kappa, \lambda)$ is Kronecker's delta. The condition $k = \mu_0 + \mu_1 + \dots + \mu_m$ implies that the last sum is empty unless we have

$$(10) \quad k = (m + 1) \mu_0 + n_1 + \dots + n_m$$

for some integer μ_0 . Introducing for brevity

$$(11) \quad N = n_1 + \dots + n_m$$

we may now state the result,

$$(12) \quad L(k) = \begin{cases} \frac{1}{\mu! (\mu + n_1)! \cdots (\mu + n_m)!}, & k = (m + 1) \mu + N, \quad \mu \in \mathbb{N}, \\ 0, & \text{otherwise.} \end{cases}$$

Inserting this into (7) we obtain

$$\begin{aligned}
 I &= \sum_{k=0}^{\infty} g(k) x^k L(k) = \sum_{\mu=0}^{\infty} \frac{g((m + 1) \mu + N) x^{(m+1)\mu + N}}{\mu! (\mu + n_1)! \cdots (\mu + n_m)!} \\
 &= \frac{x^N}{n_1! \cdots n_m!} \sum_{\mu=0}^{\infty} \frac{g((m + 1) \mu + N) (x^{m+1})^\mu}{\mu! (n_1 + 1)_\mu \cdots (n_m + 1)_\mu}.
 \end{aligned}$$

Thus, the final result is,

$$(13) \quad \begin{aligned} &\int_0^1 \cdots \int_0^1 G(x\psi(\mathbf{t})) \exp(-2\pi i \mathbf{n} \cdot \mathbf{t}) dt_1 \cdots dt_m \\ &= \frac{x^N}{n_1! \cdots n_m!} \sum_{\mu=0}^{\infty} \frac{g((m + 1) \mu + N) (x^{m+1})^\mu}{\mu! (n_1 + 1)_\mu \cdots (n_m + 1)_\mu}, \end{aligned}$$

for $|x|$ sufficiently small.

3. THE HYPERGEOMETRIC CASE

Assume now that G is a hypergeometric function,

$$(14) \quad G(\xi) = {}_pF_q \left[\begin{matrix} a_1, \dots, a_p \\ c_1, \dots, c_q \end{matrix} \middle| \xi \right];$$

we then have

$$(15) \quad g(k) = \frac{(a_1)_k \cdots (a_p)_k}{(c_1)_k \cdots (c_q)_k}.$$

Furthermore, by the multiplication formula for the Pochhammer symbol we obtain

$$\begin{aligned} (\alpha)_{N+(m+1)\mu} &= (\alpha)_N (\alpha + N)_{(m+1)\mu} \\ &= (\alpha)_N (m+1)^{(m+1)\mu} \left(\frac{\alpha+N}{m+1} \right)_\mu \left(\frac{\alpha+N+1}{m+1} \right)_\mu \cdots \left(\frac{\alpha+N+m}{m+1} \right)_\mu, \end{aligned}$$

and, by insertion, we arrive at the desired integral formula:

$$\begin{aligned} (16) \quad & \int_0^1 \cdots \int_0^1 {}_pF_q \left[\begin{matrix} a_1, \dots, a_p \\ c_1, \dots, c_q \end{matrix} \middle| x\psi(\mathbf{t}) \right] \exp(-2\pi i \mathbf{n} \cdot \mathbf{t}) \, dt_1 \cdots dt_m \\ &= \frac{(a_1)_N \cdots (a_p)_N x^N}{(c_1)_N \cdots (c_q)_N n_1! \cdots n_m!} \\ & \quad \times {}_{(m+1)p}F_{(m+1)q+m} \times \left[\begin{matrix} \mathcal{P}_N \\ \mathcal{P}_D \end{matrix} \middle| [x(m+1)^{p-q}]^{m+1} \right], \end{aligned}$$

where the parameter sets are given as follows

$$(17) \quad \begin{aligned} \mathcal{P}_N &= \{\Delta(m+1, a_1 + N), \dots, \Delta(m+1, a_p + N)\}, \\ \mathcal{P}_D &= \{\Delta(m+1, c_1 + N), \dots, \Delta(m+1, c_q + N), n_1 + 1, \dots, n_m + 1\} \end{aligned}$$

with, as usual,

$$(18) \quad \Delta(\nu, \alpha) = \left\{ \frac{\alpha}{\nu}, \frac{\alpha+1}{\nu}, \dots, \frac{\alpha+\nu-1}{\nu} \right\}.$$

As to the hypergeometric functions in (16) we must, in general, require $p \leq q + 1$. Moreover, in the case $p = q + 1$ they are hypergeometric *series* for $|x|(m+1) < 1$; otherwise, analytic continuations have to be considered.

4. PARTICULAR CASES

We note some results obtained by further specialization.

4.1. Assume that one of the numerator parameters a_1, \dots, a_p equals a negative integer $-M$. If $M < N$, the right-hand member of (16) vanishes. If $N \leq M \leq N + m$, the hypergeometric function on the right-hand side of (16) reduces to unity and we are left with the prefactor.

4.2. For $m = 1$, we obtain $\psi(t) = 2 \cos(2\pi t)$, and the formula (16) yields,

$$\begin{aligned}
 & \int_0^1 {}_pF_q \left[\begin{matrix} a_1, \dots, a_p \\ c_1, \dots, c_q \end{matrix} \middle| 2x \cos(2\pi t) \right] \exp(-2\pi i n t) dt \\
 (19) \quad &= \frac{(a_1)_n \cdots (a_p)_n x^n}{(c_1)_n \cdots (c_q)_n n!} \times \\
 & \times {}_{2p}F_{2q+1} \left[\begin{matrix} \frac{1}{2}(a_1+n), \frac{1}{2}(a_1+n+1), \dots, \frac{1}{2}(a_p+n), \frac{1}{2}(a_p+n+1) \\ \frac{1}{2}(c_1+n), \frac{1}{2}(c_1+n+1), \dots, \frac{1}{2}(c_q+n), \frac{1}{2}(c_q+n+1), n+1 \end{matrix} \middle| 4^{p-q} x^2 \right].
 \end{aligned}$$

We may, furthermore, take $p = 0 = q$, and replace x with $\frac{1}{2}x$. This leads to (3).

4.3. Let $m = 2, p = 1, q = 0, a_1 = \frac{1}{2}, \mathbf{n} = (n, 2n)$. Moreover, let $x \rightarrow \frac{1}{3}$; then on the right-hand side of (16) a ${}_3F_2[1]$ appears to which Watson's theorem applies. After a few steps involving elementary properties of the Pochhammer symbol, and the duplication formula for the Gamma function, we arrive at the formula

$$\begin{aligned}
 & \int_0^1 \int_0^1 \frac{\exp(-2\pi i n (t_1 + 2t_2))}{\sqrt{1 - \frac{1}{3} [\exp(2\pi i t_1) + \exp(2\pi i t_2) + \exp(-2\pi i (t_1 + t_2))]} dt_1 dt_2 \\
 (20) \quad &= \frac{\pi \left(\frac{1}{6}\right)_n \left(\frac{5}{6}\right)_n}{4^n [\Gamma(\frac{1}{2}n + \frac{7}{12}) \Gamma(\frac{1}{2}n + \frac{11}{12})]^2} = \frac{1}{4\pi} \Gamma \left[\begin{matrix} \frac{1}{2}n + \frac{1}{12}, \frac{1}{2}n + \frac{5}{12} \\ \frac{1}{2}n + \frac{7}{12}, \frac{1}{2}n + \frac{11}{12} \end{matrix} \right].
 \end{aligned}$$

4.4. The case $m = 3, p = 1, q = 0, a_1 = 1, \mathbf{n} = (n, n, 2n)$, and $x \rightarrow \frac{1}{4}$, is reminiscent of the preceding one. A parameter cancellation takes place, and we obtain a ${}_3F_2[1]$ to which we can, again, apply Watson's theorem. The formula obtained reads,

$$\begin{aligned}
 & \int_0^1 \int_0^1 \int_0^1 \frac{\exp(-2\pi i n (t_1 + t_2 + 2t_3)) dt_1 dt_2 dt_3}{1 - \frac{1}{4} [\exp(2\pi i t_1) + \exp(2\pi i t_2) + \exp(2\pi i t_3) + \exp(-2\pi i (t_1 + t_2 + t_3))]} \\
 (21) \quad &= \frac{\pi \left(\frac{1}{4}\right)_n \left(\frac{3}{4}\right)_n}{4^n [\Gamma(\frac{1}{2}n + \frac{5}{8}) \Gamma(\frac{1}{2}n + \frac{7}{8})]^2} = \frac{1}{2\sqrt{2}\pi} \Gamma \left[\begin{matrix} \frac{1}{2}n + \frac{1}{8}, \frac{1}{2}n + \frac{3}{8} \\ \frac{1}{2}n + \frac{5}{8}, \frac{1}{2}n + \frac{7}{8} \end{matrix} \right].
 \end{aligned}$$

5. FURTHER GENERALIZATION

One might consider a function G of several variables (see, e.g., [3]) in such a way that the integrand would involve (for example) $G(x_1\psi(\mathbf{t}), \dots, x_r\psi(\mathbf{t}))$. Although the corresponding investigation would proceed along similar lines, and the function L would again be useful, the resulting expressions would be rather bulky; we shall, therefore, leave this approach aside.

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